





# **Tensorflow Lite Micro**

CS 249 TinyML

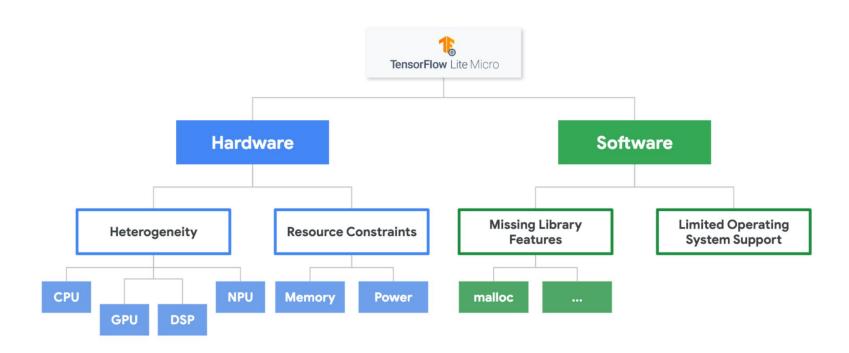
#### Roadmap

- High-Level Tensorflow Lite Micro Sales Pitch
- Review of Important Concepts
- Under the hood of Tensorflow Lite Micro
- Tensorflow Lite Micro Demo

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#### What is TFLite Micro?

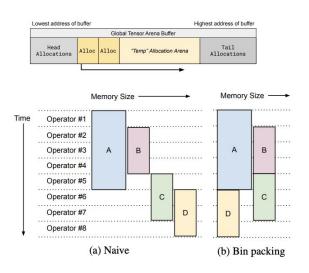


#### What is TFLite Micro?

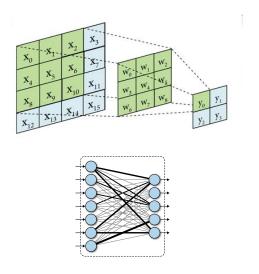
Hardware agnostic, with minimal external dependencies



**Minimal memory overhead** for trained models



Uses TFLite to cover a wide variety of model architectures



...and many more!

#### > TFLM in a Machine Learning Pipeline

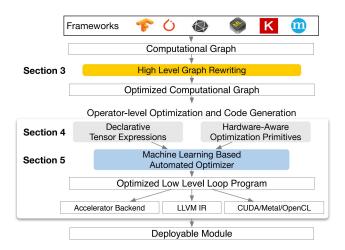




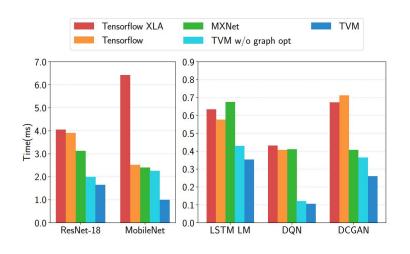
**uTensor** 







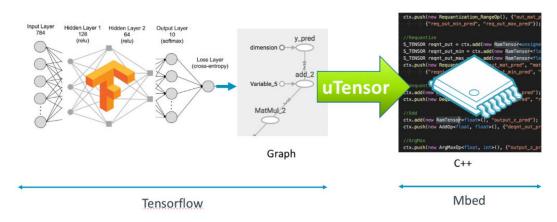
**SVM System Overview** 



TVM Time Comparison

Compiler that exposes **graph-level** and **operator-level optimizations** to provide performance portability to deep learning workloads across diverse hardware back-ends

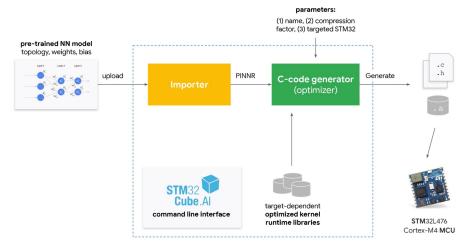




TVM Time Comparison

Framework that **converts ML models** to **C++ source files** to increase human-readability and ease of editing with a core runtime **size of 2KB** 





STM32Cube.Al Workflow

Generates an internal representation of a network, **generates optimized code** using a **compiler** and **optimized kernel libraries**, generates executable code runnable on a microcontroller

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#### Embedded System

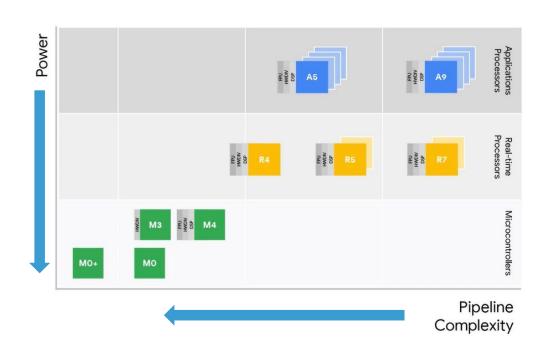
Computer hardware system with software that:

- is managed by **microcontrollers**, digital signal processors (DSP), application specific integrated circuit (ASIC), or field-programmable gate arrays (FPGA)
- is designed to perform a dedicated function under tight constraints, either as an independent system or as a part of a large system
- stores programming instructions in **read-only memory** or flash memory chips

# **Embedded Systems: Hardware**

Board	MCU / ASIC	Clock	Memory	Sensors	Radio
Himax WE-I Plus EVB	HX6537-A 32-bit EM9D DSP	400 MHz	2MB flash 2MB RAM	Accelerometer, Mic, Camera	None
Arduino Nano 33 BLE Sense	32-bit nRF52840	64 MHz	1MB flash 256kB RAM	Mic, IMU, Temp, Humidity, Gesture, Pressure, Proximity, Brightness, Color	BLE
SparkFun Edge 2	32-bit ArtemisV1	48 MHz	1MB flash 384kB RAM	Accelerometer, Mic, Camera	BLE
Espressif EYE	32-bit ESP32-DOWD	240 MHz	4MB flash 520kB RAM	Mic, Camera	WiFi, BLE

#### **Embedded Systems: Hardware**







## **Embedded Systems: Software**



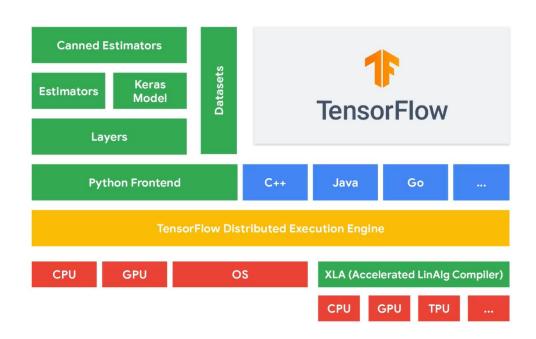
**Embedded Systems: Software** Software **TF Micro Application** Arduino mbed OS Embedded Sys. arm Nano 33 BLE Sense MBEDOS Hardware

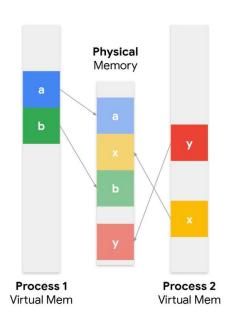
#### Microprocessor vs Microcontroller

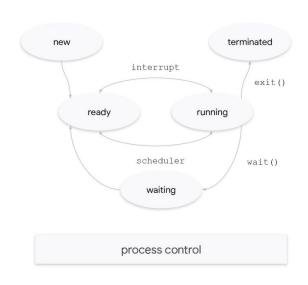
Microprocessor	Micro Controller			
Read-Only Microprocessor  Microprocessor  Serial	Microcontroller Read-Only Read-Write Memory Memory			
System Bus Interface Timer I/O Port	Timer I/O Port Serial Interface			
Microprocessor is heart of Computer system.	Micro Controller is a heart of embedded system.			
It is just a processor. Memory and I/O components have to be connected externally	Micro controller has external processor along with internal memory and i/O components			
Since memory and I/O has to be connected externally, the circuit becomes large.	Since memory and I/O are present internally, the circuit is small.			
Cannot be used in compact systems and hence inefficient	Can be used in compact systems and hence it is an efficient technique			
Cost of the entire system increases	Cost of the entire system is low			
Due to external components, the entire power consumption is high. Hence it is not suitable to used with devices running on stored power like batteries.	Since external components are low, total power consumption is less and can be used with devices running on stored power like batteries.			
Most of the microprocessors do not have power saving features.	Most of the micro controllers have power saving modes like idle mode and power saving mode. This helps to reduce power consumption even further.			
Since memory and I/O components are all external, each instruction will need external operation, hence it is relatively slower.	Since components are internal, most of the operations are internal instruction, hence speed is fast.			
Microprocessor have less number of registers, hence more operations are memory based.	Micro controller have more number of registers, hence the programs are easier to write.			
Microprocessors are based on von Neumann model/architecture where program and data are stored in same memory module	Micro controllers are based on Harvard architecture where program memory and Data memory are separate			
Mainly used in personal computers	Used mainly in washing machine, MP3 players			



Library = 400MB



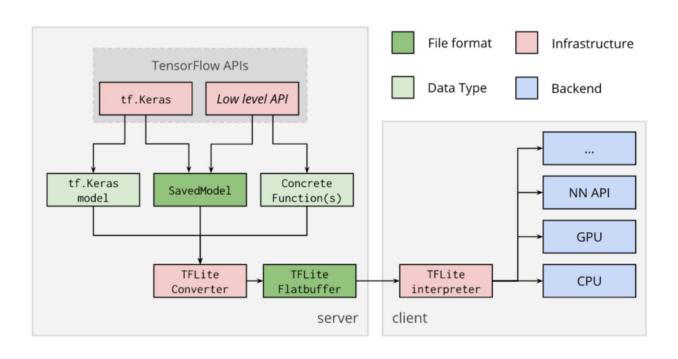




**Virtual Memory** 

**Multi-Threading** 

	Microprocessor	>	Microcontroller
Platform	edX		
Compute	1GHz-4GHz	~10X	1MHz-400MHz
Memory	512MB-64GB	~10000X	2KB-512KB
Storage	64GB-4TB	~100000X	32KB-2MB
Power	30W-300W	~1000X	150µW-23.5mW



**TFLite Conversion Process** 

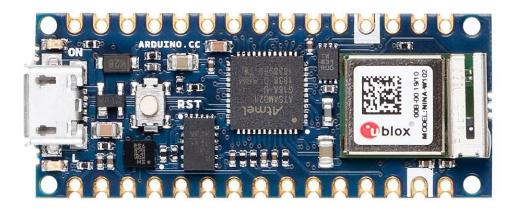


Library = 1MB



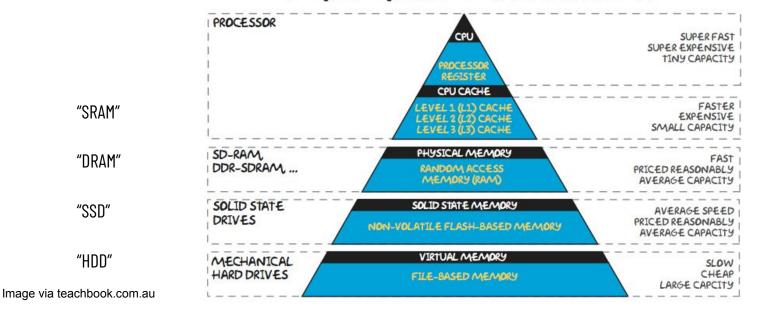


Library = 16KB

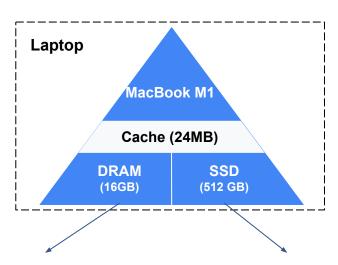


### Background: Memory Hierarchy

#### THE MEMORY HIERARCHY

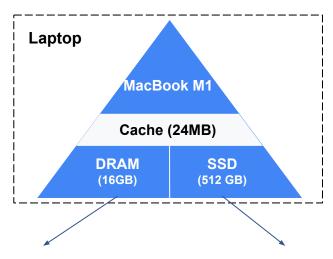


### Background: Memory in MCUs

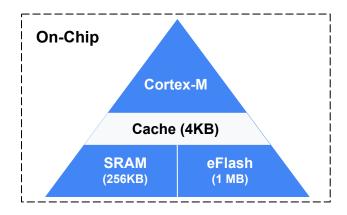


Volatile Memory: Data is lost when the computer is turned off Non-volatile Memory: Data persists even when the computer is turned off

## Background: Memory in MCUs

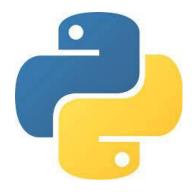


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### Interpreters vs Compilers

Python: Interpreted language



```
Python 3.8.5 Shell

File Edit Shell Debug Options Window Help

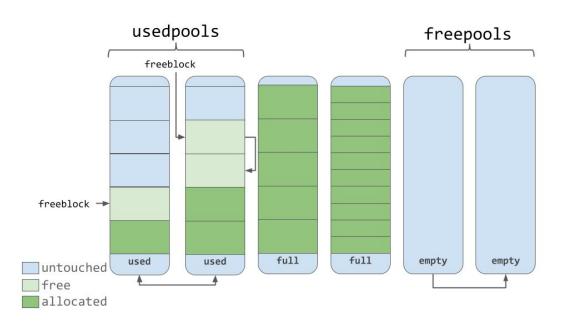
Type "help", "copyright", "credits" or "l

>>> print('Hello, World!')

Hello, World!

>>> |
```

# Interpreters vs Compilers



**Interpreter Memory Management** 

# Interpreters vs Compilers

#### Python: Interpreted language



```
Python 3.8.5 Shell

File Edit Shell Debug Options Window Help

Type "help", "copyright", "credits" or "l

>>> print('Hello, World!')

Hello, World!

>>>
```

#### C++: **Compiled** language



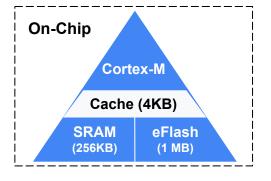
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Why care about Memory?

# Why care about Memory?

Memory Limits

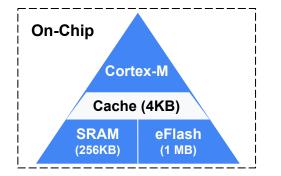


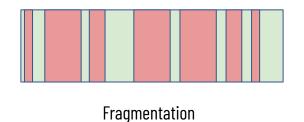
#### Why care about **Memory?** Memory Long-Running Limits **Applications** On-Chip Cortex-M Heap (Working Memory) Cache (4KB) **SRAM** eFlash Fragmentation (256KB) (1 MB)

# Why care about Memory?

Memory Limits

Long-Running Applications Lack of OS Support





malloc() Virtual Memory

#### How TFL Micro solves these challenges

1. Ask developers to supply a contiguous area of memory to the interpreter, and in return the framework avoids any other memory allocations

```
constexpr int kTensorArenaSize = 2000;
uint8_t tensor_arena[kTensorArenaSize];
...
static tflite::MicroInterpreter static_interpreter(model, resolver, tensor_arena, kTensorArenaSize, error_reporting);
```

#### How TFL Micro solves these challenges

- 1. Ask developers to **supply a contiguous area of memory** to the interpreter, and in return the framework avoids any other memory allocations
- 2. Framework guarantees that it won't allocate from this "arena" after initialization, so long-running applications won't fail due to fragmentation

#### How TFL Micro solves these challenges

- 1. Ask developers to **supply a contiguous area of memory** to the interpreter, and in return the framework avoids any other memory allocations
- 2. Framework guarantees that it won't allocate from this "arena" after initialization, so long-running applications won't fail due to fragmentation
- 3. Ensures clear budget for the memory used by ML, and that the **framework** has no dependency on OS facilities needed by malloc or new

#### uint8\_t tensor\_arena[kTensorArenaSize]

**Operator Variables** 

**Interpreter State** 

Operator Inputs and Outputs

## Loading the Model

```
model = tflite::GetModel(g_model);
```

**g\_model** variable is an array of bytes that we exported from TensorFlow

Holds all of the information about the model, its operators, their connections, and the trained weights

#### g\_model FlatBuffer Format

#### Metadata (version, quantization ranges, etc)

Name	Args	Input	Output	Weights
Conv2D	3x3	0	1	2
FC	-	1	3	4
Softmax	-	3	5	-

#### Weight Buffers

Index	Туре	Values
2	Float	0.01, 7.45, 9.23,
4	Int8	34, 19, 243,

## Loading the Model

```
model = tflite::GetModel(g_model);
```

**GetModel** call lets us access the model's data elements

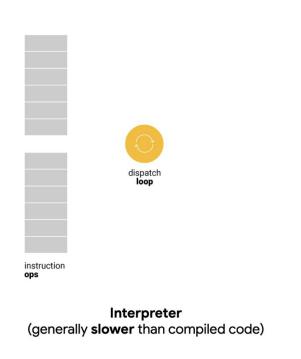
This call doesn't do any data movement or copying, so it's very memory efficient, it just creates a thin wrapper to read the information in-place.

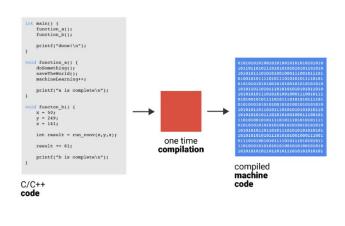
## Loading the Model

```
model = tflite::GetModel(g_model);
```

The resulting model is a class object that lets us access the model weights and operations.

#### Interpreter-based design for machine learning



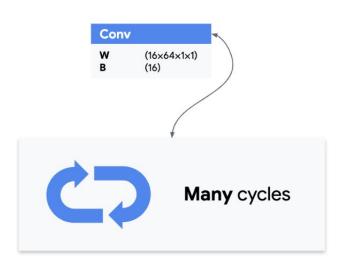


Compiler (generally faster than interpreted code)

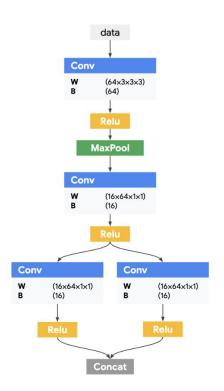
#### Interpreter-based design for machine learning

 A single line of ML code can take up to millions of operations

 The bottleneck is matrix multiplications and other operations, so an interpreter is used.



## ML models have low interpreter overhead

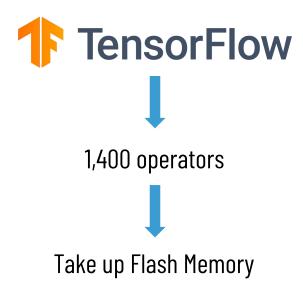


Model	Total Cycles	Calculation Cycles	Interpreter Overhead
Visual Wake Words (Ref)	18,990.8K	18,987.1K	< 0.1%
Google Hotword (Ref)	36.4K	34.9K	4.1%

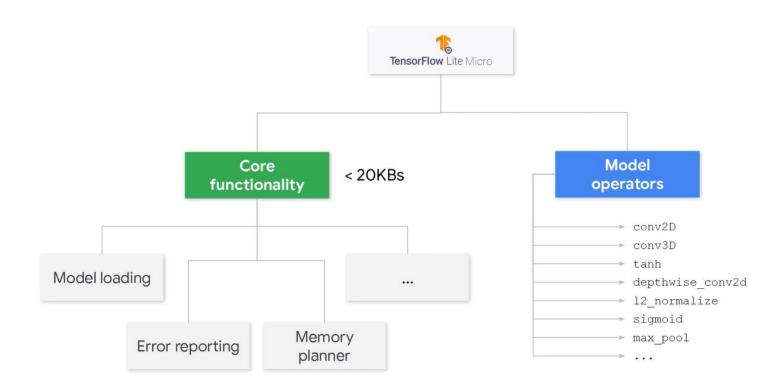
#### Example interpreter execution

```
if (op_type == CONV2D) {
   Convolution2d(conv_size, input, output, weights);
} else if (op_type == FULLY_CONNECTED) {
   FullyConnected(input, output, weights)
}
```

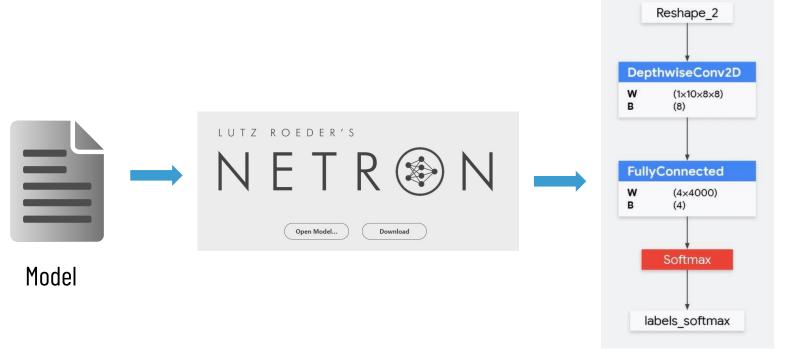
## NN Operator Support



## NN Operator Support

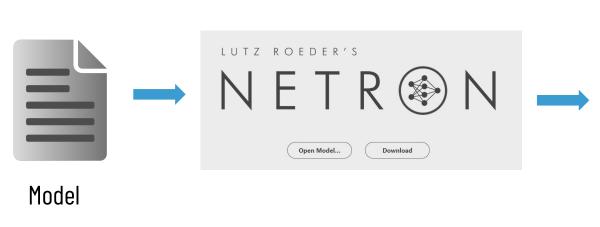


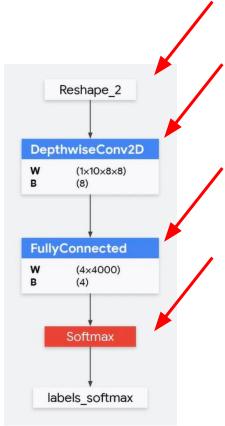
#### Choosing the Necessary Operators



Visible Operators

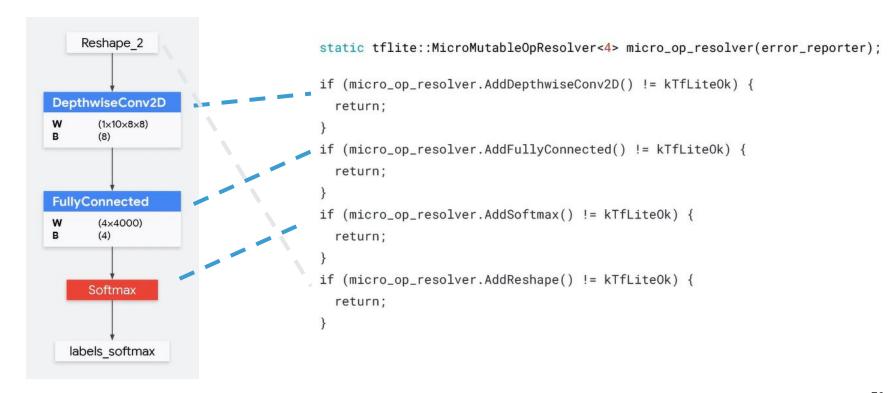
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Visible Operators

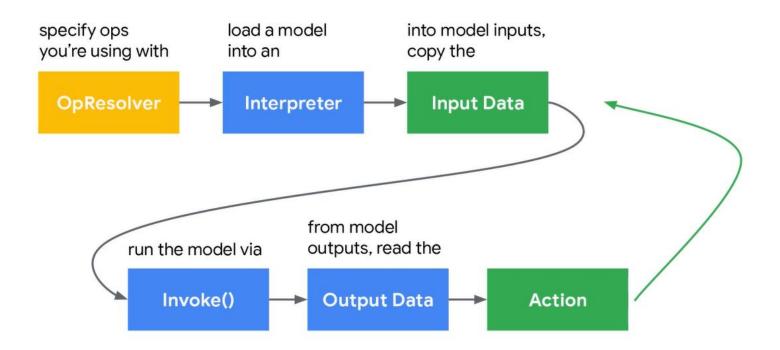
#### OpResolver

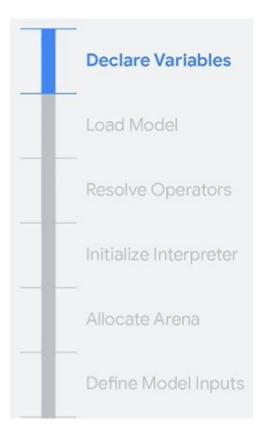


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#### > TFLM Workflow





```
// Globals, used for compatibility
// with Arduino-style sketches.
namespace {
    tflite::ErrorReporter* error_reporter = nullptr;
    const tflite::Model* model = nullptr;
    tflite::MicroInterpreter* interpreter = nullptr;
    TfLiteTensor* model_input = nullptr;
    FeatureProvider* feature_provider = nullptr;
    RecognizeCommands* recognizer = nullptr;
    int32_t previous_time = 0:
    // Create an area of memory to use for input,
    // output, and intermediate arrays.
    // The size of this will depend on the model
    // you're using, and may need to be
    // determined by experimentation.
    constexpr int kTensorArenaSize = 10 * 1024;
    uint8_t tensor_arena[kTensorArenaSize];
    int8_t feature_buffer[kFeatureElementCount];
    int8_t* model_input_buffer = nullptr;
```

## **Declare Variables** Load Model Resolve Operators Initialize Interpreter Allocate Arena Define Model Inputs

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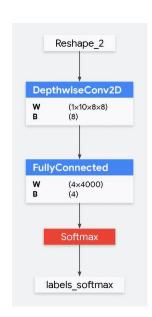


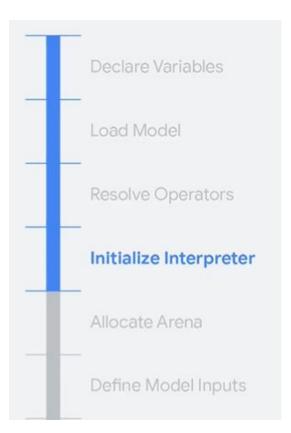
model =
tflite::GetModel(g\_model);

```
35=const unsigned char g_model[] DATA_ALIGN_ATTRIBUTE = {
       0x20, 0x00, 0x00, 0x00, 0x54, 0x46, 0x4c, 0x33, 0x00, 0x00, 0x00, 0x00,
       0x00, 0x00, x12, 0x00, 0x1c, 0x00, 0x04, 0x00, 0x08, 0x00, 0x0c, 0x00,
       0x10, 0x00, 0x14, 0x00, 0x00, 0x00, 0x18, 0x00, 0x12, 0x00, 0x00, 0x00
       0x03 0x00, 0x00, 0x00, 0x94, 0x48, 0x00, 0x00, 0x34, 0x42, 0x00, 0x00
       0x1c, 0x42, 0x00, 0x00, 0x3c, 0x00, 0x00, 0x00, 0x04, 0x00,
       0x01. 0x00. 0x00. 0x00, 0x0c, 0x00, 0x00, 0x00, 0x08, 0x00, 0x0c, 0x00
       0x04, 0x00, 0x08, 0x00, 0x08, 0x00, 0x00, 0x00, 0x08, 0x00, 0x00, 0x00
       0x0b, 0x00, 0x00, 0x00, 0x13, 0x00, 0x00, 0x00, 0x6d, 0x69, 0x6e, 0x5f,
       0x72, 0x75, 0x6e, 0x74, 0x69, 0x6d, 0x65, 0x5f, 0x76, 0x65, 0x72, 0x73,
       0x69, 0x6f, 0x6e, 0x00, 0x0c, 0x00, 0x00, 0x00, 0xd4, 0x41, 0x00, 0x00
       0xb4, 0x41, 0x00, 0x00, 0x24, 0x03, 0x00, 0x00, 0xf4, 0x02, 0x00, 0x00
       0xec, 0x02, 0x00, 0x00, 0xe4, 0x02, 0x00, 0x00, 0xc4, 0x02, 0x00, 0x00
       0xbc, 0x02, 0x00, 0x00, 0x2c, 0x00, 0x00, 0x00, 0x24, 0x00, 0x00, 0x00
       0x1c. 0x00. 0x00. 0x00. 0x04. 0x00. 0x00. 0x00. 0x16. 0xbd. 0xff. 0xff.
       0x04, 0x00, 0x00, 0x00, 0x05, 0x00, 0x00, 0x00, 0x31, 0x2e, 0x35, 0x2e,
       0x30, 0x00, 0x00, 0x00, 0x94, 0xba, 0xff, 0xff, 0x98, 0xba, 0xff, 0xff,
       0x32, 0xbd, 0xff, 0xff, 0x04, 0x00, 0x00, 0x00, 0x80, 0x02, 0x00, 0x00,
       0xfa, 0xee, 0x28, 0xc4, 0xee, 0xfe, 0xcf, 0x0f, 0xle, 0xf7, 0x1f, 0x06,
       0x0d, 0xed, 0xe9, 0x83, 0x5c, 0xc9, 0x18, 0xe3, 0xf9, 0x14, 0x28, 0x2a,
       0x09, 0xf2, 0x18, 0x34, 0x62, 0xea, 0xef, 0xd6, 0x36, 0xb7, 0x1e, 0xf7,
       0x3b, 0x22, 0x28, 0x39, 0xc2, 0x9d, 0xf1, 0x07, 0x5e, 0x0b, 0x1e, 0x2c,
57
       0x07, 0xdd, 0xfd, 0xc3, 0xd8, 0x4a, 0xf3, 0x28, 0xa7, 0x16, 0xd5, 0xf1,
       0xc3, 0x05, 0xfd, 0x27, 0xcc, 0xba, 0xle, 0xcb, 0xd7, 0x3d, 0xd4, 0x29
       0x00, 0xfd, 0x28, 0x44, 0xfb, 0xf2, 0xf3, 0xb6, 0x4f, 0xcf, 0x09, 0xf0,
       0xfa, 0x45, 0x41, 0x49, 0x05, 0xc5, 0x17, 0x5d, 0x64, 0x00, 0xf8, 0xee,
       0x48, 0x17, 0xf4, 0xe9, 0x2e, 0x4b, 0x2e, 0x3f, 0xdf, 0xee, 0xe4, 0x08
       0x38, 0xf1, 0x16, 0x13, 0x2f, 0x2d, 0xed, 0xc2, 0xbf, 0x36, 0xf4, 0x02,
       0xcf. 0xaa. 0xd2. 0xfa. 0xac. 0x13. 0xf6. 0xe8. 0xb5. 0x68. 0x12. 0xb6.
       0xce, 0x0e, 0xdf, 0x58, 0xe4, 0x49, 0x14, 0x15, 0x03, 0xed, 0xfa, 0xd4,
       0x40, 0xa7, 0xf6, 0xca, 0xfb, 0x00, 0x4d, 0x5e, 0xe4, 0x55, 0x1d, 0x30
       0x45, 0xe2, 0xfc, 0x01, 0x48, 0x81, 0xe9, 0xf1, 0x1e, 0xfc, 0x21, 0x32
       0xed, 0x4b, 0xed, 0xfa, 0x2f, 0xd2, 0xfa, 0xfb, 0x4d, 0xa7, 0xed, 0xc7,
       0x92, 0xdf, 0xe6, 0xdb, 0xf8, 0x1f, 0xd9, 0xfa, 0x91, 0xf5, 0xe5, 0xc5,
       0x8c, 0x17, 0x0f, 0xb9, 0xd2, 0xc7, 0xfe, 0x68, 0xd3, 0x51, 0x2e, 0x49,
       0x1f, 0xbd, 0x01, 0xeb, 0x31, 0x17, 0xf0, 0xef, 0xff, 0xb8, 0x5d, 0x62,
       0x02, 0x0f, 0x1f, 0x78, 0x6a, 0xb0, 0xf9, 0xfe, 0x4f, 0xcc, 0xd3, 0xff,
       0x0a, 0x96, 0x1e, 0x2c, 0xed, 0xbc, 0xf4, 0x0b, 0x42, 0xc8, 0xf1, 0xea,
       0x6e, 0x58, 0xec, 0xc4, 0x99, 0xae, 0xdc, 0xd7, 0x12, 0x87, 0xd8, 0x06,
       0xa2, 0xc2, 0xe6, 0xa2, 0x81, 0x24, 0xe9, 0xac, 0xce, 0xb6, 0x15, 0x6b
       0xba, 0x00, 0x19, 0x58, 0x29, 0xb6, 0xfe, 0x01, 0x25, 0x96, 0xd2, 0xec,
```



```
static tflite::MicroMutableOpResolver<4>
micro_op_resolver(error_reporter);
if (micro_op_resolver.AddBuiltin(
  tflite::BuiltinOperator_DEPTHWISE_CONV_2D,
  tflite::ops::micro::Register_DEPTHWISE_CONV_2D()) != kTfLiteOk)
  return:
if (micro_op_resolver.AddBuiltin(
 tflite::BuiltinOperator_FULLY_CONNECTED,
  tflite::ops::micro::Register_FULLY_CONNECTED()) != kTfLiteOk)
  return;
if (micro_op_resolver.AddBuiltin(
  tflite::BuiltinOperator_SOFTMAX,
  tflite::ops::micro::Register_SOFTMAX()) != kTfLiteOk)
  return:
if (micro_op_resolver.AddBuiltin(
    tflite::BuiltinOperator_RESHAPE,
    tflite::ops::micro::Register_RESHAPE()) != kTfLiteOk)
  return;
```



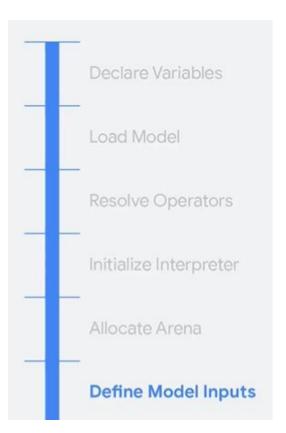


```
// Build an interpreter to run the model with.
static tflite::MicroInterpreter static_interpreter(
    model, micro_op_resolver, tensor_arena,
    kTensorArenaSize, error_reporter);
interpreter = &static_interpreter;
```



```
// Allocate memory from the tensor_arena for
// the model's tensors.

TfLiteStatus allocate_status =
interpreter->AllocateTensors();
```



```
model_input = interpreter->input(0);
model_input_buffer = model_input->data.int8;
```

#### TFLM Executive Summary

- TFLM is built to fit with embedded system constraints
- Very small binary footprint
- **No** dynamic memory allocation
- No dependencies on standard C/C++ Libraries
- **No** operating system dependencies

#### Roadmap

- High-Level Tensorflow Lite Micro Sales Pitch
- Review of Important Concepts
- Under the hood of Tensorflow Lite Micro
- Tensorflow Lite Micro Demo

# Extra Slides

#### References

- David, Robert, et al. "Tensorflow lite micro: Embedded machine learning for tinyml systems." Proceedings of Machine Learning and Systems 3 (2021): 800-811.
- Chen, Tianqi, et al. "{TVM}: An automated {End-to-End} optimizing compiler for deep learning." 13th USENIX Symposium on Operating Systems Design and Implementation (OSDI 18). 2018.
- UTensor (<u>https://github.com/uTensor/uTensor</u>)
- Microprocessor VS Microcontroller (<a href="https://www.linguip.com/blog/difference-between-microprocessor-and-microcontroller/">https://www.linguip.com/blog/difference-between-microprocessor-and-microcontroller/</a>)
- Embedded Systems (<a href="https://www.heavy.ai/technical-glossary/embedded-systems">https://www.heavy.ai/technical-glossary/embedded-systems</a>)
- TFLite Conversion (<a href="https://www.tensorflow.org/lite/models/convert">https://www.tensorflow.org/lite/models/convert</a>)
- Edx TinyML Course (<a href="https://www.edx.org/professional-certificate/harvardx-tiny-machine-learning">https://www.edx.org/professional-certificate/harvardx-tiny-machine-learning</a>)
- Edx TinyML Course Material (<a href="https://github.com/tinyMLx/courseware/tree/master/edX#chapter-44-tensorflow-lite-micro">https://github.com/tinyMLx/courseware/tree/master/edX#chapter-44-tensorflow-lite-micro</a>)

## Suggested Readings

- Banbury, C., Reddi, V. J., Torelli, P., Holleman, J., Jeffries, N., Kiraly, C., ... & Xuesong, X. (2021). Mlperf tiny benchmark. arXiv preprint arXiv:2106.07597. <a href="https://doi.org/10.07597.pdf">2106.07597.pdf</a> (arxiv.org)
- David, R., Duke, J., Jain, A., Janapa Reddi, V., Jeffries, N., Li, J., ... & Rhodes, R. (2021). Tensorflow lite micro: Embedded machine learning for tinyml systems. Proceedings of Machine Learning and Systems, 3, 800-811. <u>TensorFlow Lite Micro: Embedded Machine Learning on TinyML Systems (arxiv.org)</u>
- Chen, Tianqi, et al. "{TVM}: An automated {End-to-End} optimizing compiler for deep learning." 13th USENIX Symposium on Operating Systems Design and Implementation (OSDI 18). 2018. <a href="https://www.usenix.org/system/files/osdi18-chen.pdf">https://www.usenix.org/system/files/osdi18-chen.pdf</a>

#### **Additional Links:**

- Memory Management in Tensorflow Lite Micro
  - Source: tflite-micro/memory management.md at main tensorflow/tflite-micro (github.com)
- MLPerf Tiny Deep Learning Benchmarks for Embedded Devices
  - Source: mlcommons/tiny: MLPerf™ Tiny is an ML benchmark suite for extremely low-power systems such as microcontrollers (github.com)