Computer Vision and Deep Learning

Exam 1

2021.12.23

1.

1)

Ans:

$$\begin{bmatrix}
X \\
Y
\end{bmatrix} = \begin{bmatrix}
R_{11} & R_{12} & R_{13} & T_{1} \\
R_{21} & R_{22} & R_{23} & T_{2}
\end{bmatrix} \begin{bmatrix}
X \\
Y
\end{bmatrix} = \begin{bmatrix}
R_{31} & R_{32} & R_{33} & T_{3} \\
R_{31} & R_{32} & R_{33} & T_{3}
\end{bmatrix} \begin{bmatrix}
X \\
Y
\end{bmatrix}$$

2) **Ans:**

3) **Ans:**

$$\begin{cases} \lambda U = \alpha x + ry + U_0 Z \\ \lambda V = \beta y + V_0 Z \Rightarrow V = \frac{\beta y + V_0 Z}{Z} \end{cases}$$

4) **Ans:**

Matrix H is also called <u>Affine Transform</u> Matrix A is called <u>Projection Transform</u>

2. (20%, Camera Calibration)

1)

Ans:

Mahalanobis distance

2)

Ans:

Levenberg-Marquardt algorithm

3)

Ans:

$$(5) \rightarrow (1) \rightarrow (3)$$

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3.
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1)

Ans: (3), (6), (1), (4)

- 1. Scale-Space Extrema Detection
- 2. Keypoint localization
- 3. Orientation Assignment for each keypoint
- 4. Keypoint descriptor

2

Ans: (2), (1), (3), (2)

- (A) Edge feature
- (B) Flat feature
- (C) Corner feature
- (D) Edge feature (Won't occur??)

4.

Ans:

1)

- (1) Feature extraction
- (2) Classification

2)

- (1) Local feature
- (2) Medium feature
- (3) Global feature

3)

AlexNet, VGG16, ResNet

5.

1)

Ans:

$$[w_1, w_2, w_3, \dots, w_k, b] = Z$$

2) **Ans:**

- 1) Cascade
- 2) Non-linear discrimination
- 3) Feature extraction
- 4) Down-sampling
- 5) Non-linear discrimination
- 6. (6%) For this class so far, please write your suggestions for professor Lien, Jenn-Jier James 連震杰 to improve his lecture? (6%) (At least 30 words, written in either English or Chinese. 用中文寫就好)
 - 1) Positive site (Pros.):

2) Negative site (Cons.):