

Drivergene.net: A Cytoscape app for the identification of driver nodes of large-scale complex networks and case studies in discovery of drug target genes.

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Abstract

There are no tools to identify driver nodes of large-scale networks in approach of competition-based controllability. This study proposed a novel method for this computation of large-scale networks. It implemented the method in a new Cytoscape plug-in app called Drivergene.net. Experiments of the software on large-scale biomolecular networks have shown outstanding speed and computing power. Interestingly, 86.67% of the top 10 driver nodes found on these networks are anticancer drug target genes that reside mostly at the innermost K-cores of the networks. Finally, compared method with those of five other researchers and confirmed that the proposed method outperforms the other methods on identification of anticancer drug target genes. Taken together, Drivergene.net is a reliable tool that efficiently detects not only drug target genes from biomolecular networks but also driver nodes of large-scale complex networks. Drivergene.net with a user manual and example datasets are available <https://github.com/tinhpd/Drivergene.git>

Keywords:

Drug target genes, Competitive dynamics model, Complex network, Cytoscape plugin, Driver node identification

1. Introduction

The identification of driver nodes in complex networks has been a topic of significant research in the field of network science. Several scientific and applied achievements have contributed for understanding this important aspect of network control. First, Liu et al. investigated the concept of structural controllability in linear complex networks [1]. They demonstrated that the minimum

set of driver nodes, which can control the network, can be computed efficiently using a reduction to the maximum matching problem on bipartite graphs. This work laid the foundation for subsequent studies on driver node identification. Building upon Liu et al.'s findings, Ruths and Ruths explored the maximum matching approach in network controllability and classified control profiles based on different types of controls, such as source nodes, external dilations, and internal dilations [2]. Their work provided insights into the diversity of control mechanisms in complex networks. Besides, Nepusz and Vicsek focused on controlling edge dynamics in complex networks

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[3]. They proposed a method to identify the optimal set of driver nodes using the concept of the region of attraction. Their approach offered a new perspective on achieving control in complex networked systems. In a study by Wei et al., a practical problem called the target control problem with objectives-guided optimization (TCO) was addressed [4]. The goal was to control specific variables or targets in a network while minimizing the number of driver nodes and maximizing the quantity of constrained nodes. They developed an efficient algorithm called TCOA, which outperformed existing control-focused approaches in identifying precise driver nodes. These publications have significantly advanced the understanding of driver node identification in complex networks, but their methods were based on network structure, which may be ineffective with networks with similar structure but different in dynamics. Recently, Tran et al proposed a dynamics model to identify driver nodes based on the simulation of a competition between inside agents and an outside agent where driver nodes are the inside nodes with the highest total support score receiving from the other nodes [5]. The study applied the model to 17 different cancer signaling networks and found that driver nodes are often anticancer drug target genes. This result confirmed the precision of the dynamics model and shows the potential of driver nodes in the identification of therapeutic targets in drug discovery. The discovery of anticancer drug target genes is an important step in the development of drugs to treat cancer. Therefore, it is extremely important to develop tools that can accurately identify anticancer drug target genes. In recent years, several tools have been introduced to identify anticancer drug target genes. These tools can be categorized into three main approaches: machine learning-based methods, mutation similarity-based statistics methods, and network-based methods. Machine learning-based methods involve the use of supervised machine learning technology to identify anticancer drug target genes. Examples of such tools include DriverML, which quantifies the functional impacts of mutations on proteins to identify target genes [6], and EARN (Ensemble

of Artificial Neural Network, Random Forest, and non-linear Support Vector Machine), which uses machine learning to evaluate metastasis breast anticancer drug target genes [7]. Another tool called PCDG-Pred distinguishes the attributes of anticancer drug target genes from passenger attributes using genomic sequencing data and a machine learning model [8]. However, a limitation of this approach is the requirement for large sample sets and standardized anticancer drug target gene datasets, which may not be available for every cancer type [9].

Mutation similarity-based statistics methods focus on evaluating mutations and their similarity to identify anticancer drug target genes. DrGaP is a versatile tool that identifies anticancer drug target genes and controls signaling pathways in gene-based sequencers [10]. OncodriveCLUST is another method that identifies target genes by evaluating noncoding mutations from somatic mutations [11]. OncoVar utilizes known bioinformatics algorithms to identify target genes based on the oncogenic potential of somatic mutations and cancer genes [12]. A limitation of this approach arises when known and unknown disease genes have indirect relationships or similar functions, leading to incorrect function annotation and affecting prediction results [13, 14].

The network-based approach considers the observation that genes associated with the same or similar diseases tend to be located close together in biomolecular networks [15]. This approach can be divided into two groups: local methods and global methods [16]. Local methods focus on genes that are directly connected or have the shortest path to the identified causative genes [17, 18, 19, 20, 21, 22, 23, 24, 25]. Global methods utilize algorithms to propagate disease information from known disease genes through a network system and assign candidate gene weights based on similarity to known disease genes [26, 27, 28]. Network-based studies require less data but need improvement in accuracy.

Here, based on dynamic network model, namely outside competitive dynamics model, the study proved that driver nodes can identify anticancer drug target genes [5]. However, the algorithm

works inefficiently on large-scale networks, so it can not discover insights from these large networks. In other words, controllability characteristics of large-scale complex network is still in mystery because of no analysis tool for them. In this study, the study proposed a new version of parallel algorithm to effectively execute on large-scale molecular biological networks. In addition, a new software tool was developed for integration into Cytoscape, called Drivergene.net, which implements the outside competitive dynamic model with the parallel algorithm using the OpenCL library in Java to ensure that the algorithm is scalable on large-scale biomolecular networks. The library utilizes the full computing power of a multi-core central processing unit [29, 30], enabling more efficient in the computational performance of the software. The software is developed as a Cytoscape plug-in with a user-friendly graphical user interface (GUI) where network visualization functions, necessary data, and options are easily set through the GUI of Cytoscape. To test the computational performance of Drivergene.net for identifying driver nodes in large-scale biomolecular networks, the study performed an analysis of three large-scale biomolecular networks, including: human signaling network, human protein-protein interaction network, and human gene regulatory network. The results showed that parallel execution for multi-core CPUs provides a maximum acceleration factor that outperforms sequential computations on single core CPUs. In particular, 86.67% of the top 10 driver genes with the highest total support score computed by Drivergene.net were in fact anticancer drug target genes in cancer therapy. In addition, these genes were mostly within the innermost core of the networks. This finding is in agreement with the results of previous studies that important cancer biomarker genes are often located in the innermost core of the biological network [31, 32, 33, 34], and anticancer drug target genes often act as target genes for cancer drugs and cancer biomarker genes in the biological networks [23]. Finally, to evaluate the prediction results on anticancer drug target genes, the study made a comparison between the results of Drivergene.net with those of five other methods based

on earlier work in this area. As a result, Drivergene.net’s predictions for the three networks exhibited a better result than those of the previous methods because sharing the largest number of anticancer drug target genes crossing. This comparison result showed that the genes found from the networks share consensus with those found by other studies and that the method of Drivergene.net is better than other methods. Drivergene.net is a reliable tool that efficiently detects not only anticancer drug target genes from biomolecular networks but also driver nodes of large-scale complex networks.

2. Methods and Materials

2.1. Experimental Data

The study utilized data from three previously publications. The first network is a human signaling network [18], containing 1561 nodes and 5089 edges, including 2403 activating edges labeled as +1, 741 inhibiting edges labeled as -1, 1915 neutral edges labeled as 0, and 30 edges of unknown type, labeled as 0. This network was manually constructed and their interactions were derived from the comprehensive signaling pathway database BioCarta (<http://www.biocarta.com/>). Pathways in the database are illustrated as diagrams manually constructed. To ensure the accuracy of interactions, all data underwent four-fold cross-checking by different researchers. Subsequently, the network was further expanded by integrating interactions from the Cancer Cell Map (<http://cancer.cellmap.org/cellmap/>), a database containing 10 manually curated signaling pathways for cancer.

The second network is a large-scale human protein-protein interaction network downloaded from [19]. The network contains 7533 nodes and 22052 edges, generated through high-throughput techniques of protein - protein interactions at the genome scale, combining two-hybrid experiments to identify binary interactions.

The third network is a human gene regulatory network containing 943 genes and 3922 edges, introduced in [20]. The dataset was built from knowledge of gene regulatory networks by collecting and

integrating the regulatory interactions between transcription factors (TFs), microRNAs (miRNAs), and the target genes from 25 databases. The result is a dataset containing a comprehensive set of regulatory interactions. Furthermore, the study also describes statistical properties and structural characteristics of regulatory gene networks across the entire human genome, extracting and explaining important networks related to interactions between TF-miRNA and their targets.

Figure 1a, Network preprocessor module. The input data network is a complex network, and this module converts various network types into a single network. Figure 1b, Analysis module. The main module of Drivergene.net is developed using an outside competitive dynamics model that identifies driver nodes, with the highest total support, of the network. The parallel algorithm is used with the help of the OpenCL library to ensure the algorithm’s scalability on large-scale networks. Figure 1c, The presenting module. The output data is a list of nodes ranked by total support in descending order. With the help of evidence collected from PubMed, the driver nodes are often anticancer drug target genes in biomolecular networks.

2.2. Design and implementation

The study propose a software design for identifying driver nodes of a complex network, which often are anticancer drug target genes on large-scale molecular biological networks. This software exploited the outside competitive network dynamic model that was introduced in the previous study [5]. The software architecture includes three modules (Figure 1). First, the network preprocessor module (Figure 1a) is used to obtain input data and convert various network types into a single network, after extracting the maximum connected components of the network. Second, the analysis module (Figure 1b) with the outside competition dynamic model [5] integrated to determine the driver nodes of the disease network [23], with a parallel computing technique being applied and the help of the installed OpenCL library. This is a solution that fully exploits the computing resource of multi-core processors because it uses

the OpenCL library which is designed to run on any available multi-core CPU. Next, the application computes the total support of each node in the network. In turn, each thread loads and processes a selected amount of network data, in relation to the settings of the respective algorithm. The native source code supports connection and data processing and plays an intermediary role in converting the source code to OpenCL and processing on CPUs. It loads the data, converted into an array, into the kernel and then initializes the local area of the memory to load data into the CPU cores for processing. Third, the presenting module (Figure 1c) creates the output of the computation as a list of genes in the network and ranks nodes in descending order by total support. Finally, biomedical evidence is collected from the PubMed database for the top 10 highest-ranking genes used.

2.3. Parallel algorithms for the identification of driver nodes with OpenCL

Next, using the mathematical model of the outside competitive network dynamics model, the study designed a parallel version of the algorithm published previously and implemented this version with the help of the OpenCL library installed. The algorithm in Algorithm 1 has the main entry as *ParFindDriverNode* which parallelly calls *ToS* sub-function for computing total support of every node. The *OutsideCompetition* sub-function is called by *ToS* to calculate influence of vertices in the network with a specific vertex α as the driver when an outside agent β is present. This function includes initializing the initial state of the vertices, creating a connection with the outside agent, updating the state of the vertices in the network by *InsideCompetition* sub-function, and checking the stopped condition of the algorithm. The output of this sub-function is the supporting score of the other nodes to driver α . For each vertex α traversed, *ParFindDriverNode* calls the *ToS* to determine whether a vertex α is a driver or not by checking their total support score to reach the highest value. **Algorithm 1.** Parallelly finding driver nodes of a complex network $G(V, E)$. This algorithm is applied in the identification of

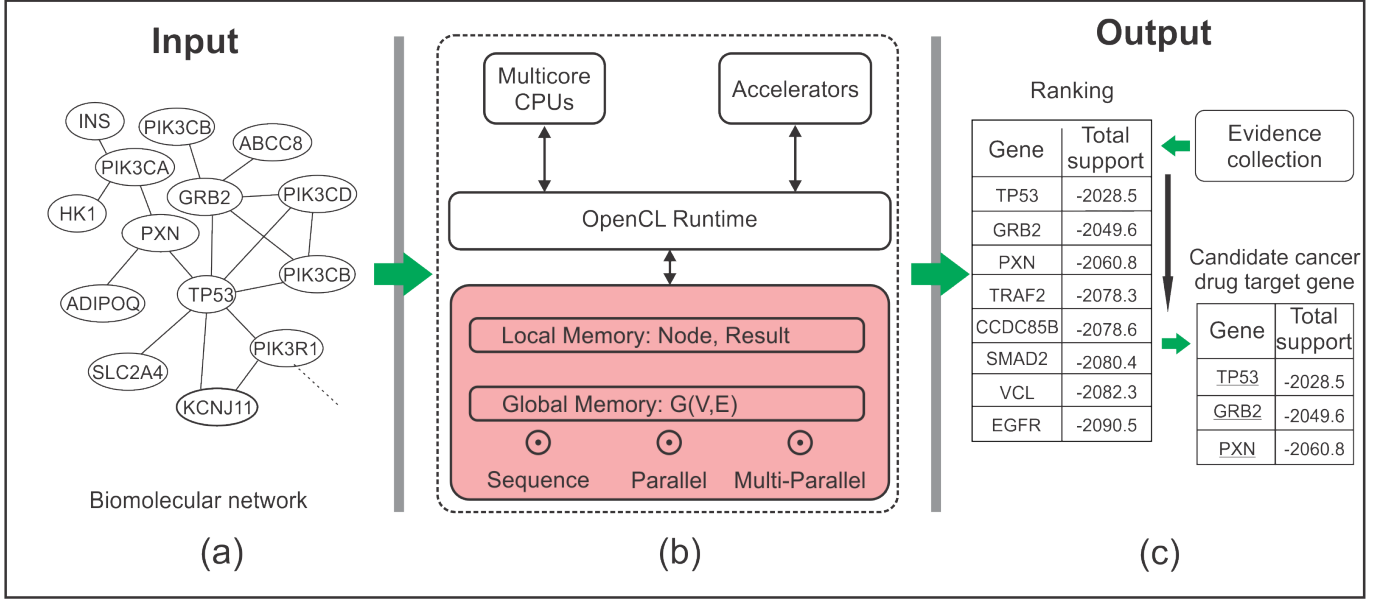


Figure 1: The design of Drivergene.net to identify driver nodes of a complex network.

anticancer drug target genes from biomolecular networks.

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function [ $X_t$ ] InsideCompetition( $G(V,E)$ ,  $Leaders \in V, AgainstLeaders \in V$ )
 $maxIterations \leftarrow V \times E$ ;  $Epsilon \leftarrow 4.94e-324$ ;
 $\varepsilon \leftarrow 1 / (Max(total\ weights\ of\ out-links\ of\ v, \forall v \in V) - Epsilon)$ ;
 $X_t \leftarrow \text{new Dictionary}(node, value)$ ;  $X_{t+1} \leftarrow \text{new Dictionary}(node, value)$ ;
for ( $Node$  in  $V$ ) do
 $X_t[Node] \leftarrow 0$ ; end for
for ( $Leader$  in  $Leaders$ ) do
 $X_t[Leader] \leftarrow 1$ ;  $X_{t+1}[Leader] \leftarrow 1$ ; end for
for ( $AgainstLeader$  in  $AgainstLeaders$ ) do
 $X_t[AgainstLeader] \leftarrow -1$ ;  $X_{t+1}[AgainstLeader] \leftarrow -1$ ; end for
 $Error \leftarrow 0$ ;  $t \leftarrow 0$ ;
Do
 $Error \leftarrow 0$ ;
for ( $u$  in  $V$ ) do
if ( $Leaders$  contain  $u$  or  $AgainstLeaders$  contain  $u$ ) continue; end if
 $r \leftarrow 0$ 
for ( $v$  in  $Neighbors\ of\ u$ ) do
 $r \leftarrow r + weight(u, v) \times (X_t[v] - X_t[u])$ ; end for
 $X_{t+1}[u] \leftarrow X_t[u] + \varepsilon \times r$ ;
 $Error \leftarrow Error + Math.Abs(X_t[u] - X_{t+1}[u])$ ;
end for;

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 $Temp \leftarrow X_t$ ;  $X_t \leftarrow X_{t+1}$ ;  $X_{t+1} \leftarrow Temp$ ;  $t \leftarrow t+1$ ;
while ( $Error > Epsilon \wedge t < maxIterations$ );
return  $X_t$ ; //Output as stable states of nodes as  $t \rightarrow \infty$ 
end
function [ $Support$ ] OutsideCompetition ( $G(V,E)$ ,  $\alpha \in V$ )
 $Support \leftarrow \text{new Dictionary}(node, value)$ ;
 $\beta \leftarrow \text{new Node}$ ;
 $NormalAgents \leftarrow V \setminus \{\beta, \alpha\}$ ;
for ( $\gamma$  in  $NormalAgents$ ) do
 $e \leftarrow \text{new Edge}(\beta, \gamma)$ ;  $E = E \cup e$ ;
 $\underline{X} \leftarrow \text{InsideCompetition}(G(V,E), \alpha, \beta)$ ;
 $Support[\gamma] \leftarrow \underline{X}[\gamma]$ ;  $E = E \setminus e$ ; end for
return  $Support$ ; //Support of nodes to  $\alpha$  when connecting to  $\beta$ 
end
procedure ToS( $G(V,E)$ ,  $\alpha \in V$ , out  $result$ )
 $Support \leftarrow \text{new Dictionary}(node, value)$ ;
 $Support \leftarrow \text{OutsideCompetition}(G(V,E), \alpha)$ ;
 $TotalSupport \leftarrow 0$ ;
for ( $\gamma$  in  $V \setminus \alpha$ ) do
 $TotalSupport \leftarrow TotalSupport + Support[\gamma]$ ;
end for
 $result[\alpha] = TotalSupport$ ; //Total support of nodes to  $\alpha$ 
end

```

function *[driver nodes]* *ParFindDriverNode*($G(V, E)$),
//G(V, E): Global variable; α : Local variable; *re-*
sult: Local variable;
result \leftarrow **new** *Dictionary*(*node, value*);
for(α in V) **in parallel do**
ToS($G(V, E), \alpha, result$);
Wait for all works done(); **end for**
return *result with the highest total support score*;
end.

3. Results

3.1. *Drivergene.net app in Cytoscape*

Drivergene.net is developed in a Java programming environment with using the availability of OpenCL library installed as a solution that fully exploits the computing power of multi-core CPUs. The software was compiled and packaged separately as a plug-in for Cytoscape, and can be run on any system where Java Virtual Machine is installed, including Windows, Ubuntu, and Mac OS. The user can choose the network data and execution among many options, such as executing in sequential on CPU, executing in parallel on CPUs, or executing in parallel on all computing devices. The user can flexibly provide input network data and get output computation results according to the data standards supported by Cytoscape. The software works with three main functions, including 1) Visualizing the network, 2) Identifying driver nodes in the network, and 3) Evaluating the approximate time it takes to compute a network. The analyzed networks are displayed in the execution window and can be exported as tables. Details of the features, installation steps, and instructions for use of Drivergene.net software are presented in the User Manual file.

3.2. *Computational performance analysis of the software*

To test the computational performance of Drivergene.net in large-scale biomolecular networks, the study conducted experiments on five networks with various node scales, including: Human gene regulatory network in Table S1 [35], Human PPI

network in Table S2 [36], Human signalling network in Table S3 [37], E. coli PPI networks in Table S4 [38], and Human cytomegalovirus infection in Table S5 [39, 40]. This process was tested on a Dell OptiPlex 5050 hardware system, Intel i7-7700 octa-core CPU clocked at 3.6 GHz that supports programming technology using OpenCL library, 32 GB DDR IV DDRAM memory. Table 1 shows the test results with the estimated computation time across the networks. The column labelled "Parallel on CPUs" shows the execution time of the software on multi-core CPUs. The results show that the parallel algorithm of multi-core CPUs outperforms the sequential algorithms of single core CPUs and suggest that implementation of the parallel algorithm is correct and effective. More details about computational effectiveness of the software is presented in Fig. S1 in User manual & Case studies. This is achieved through the efficient use of local memory with simple data, in addition to parallelization. To accelerate processing in Drivergene.net, the study made modifications to the implementation of the network data storage by switching from the 'String' class used in the old version to an integer-based data type. Additionally, the OpenCL library takes advantage of local cache memory, the fastest type of memory available, whereas a sequential algorithm on a single-core CPU would use regular memory for storage [41]. The parallel version is remarkably faster than the sequential version, and this allows the user to work effectively on large-scale networks.

The computational speed of Drivergene.net on various biomolecular networks. The computation is executed in two computation modes: sequential on the CPU and parallel on multi-core CPUs. The results show that the computational speed is improved significantly in the parallel algorithm.

3.3. *Case studies*

The study verified the ability of Drivergene.net to detect driver nodes on the three types of large-scale biomolecular networks: Human signaling network [37] Human PPI network [36], and Human gene regulatory network [35]. Interestingly, 86.67 %, i.e., 26 of 30, of the top 10 genes with the

Table 1: The computational speed of Drivergene.net

Biomolecular network	Properties		Computation time (minutes)		Acceleration (A/B)
	Node	Edge	Sequential (A)	Parallel (B)	
Human cytomegalovirus infection	213	1214	5.7	0.11	51.8
E. coli PPI networks	850	1193	341	5	68.2
Human gene regulatory network	943	3917	207	7	29.5
Human signaling network	1609	5079	5092	35	145.5
Human PPI network	7242	21909	373392	3888	96.0

highest total support score computed by Drivergene.net are driver nodes, also considered as candidate drug target genes in cancer therapy (see Table 2).

Assessing anticancer drug target genes identified from a directed biomolecular network.

First, employed Drivergene.net for Human gene regulatory network, with the data in Table S1, for identifying driver nodes as well as anticancer drug target genes from a directed network. After computing the total support of each node by the software, selected the gene with the highest total support score. As a result, the study found that the NFKB1 gene (p105/p50) with the highest total support score is one of five important subunits of NF- κ B, a factor involved in the pathogenesis of most human malignancies [42, 43]. For instance, deficiency or loss of NFKB1 promotes chronic liver disease associated with aging, an increase in the ratio of neutrophils to lymphocytes, the development of idiopathic chronic liver disease, and liver cancer characterized by dysplastic nodules, increased tumor incidence, features of steatohepatitis and fibrosis, hepatocellular telomere lesions, and hepatocellular carcinoma [44]. mRNA expression analysis of human cancers, including medulloblastoma, indicated that NFKB1 is down-regulated in many human hematologic malignancies, including T-cell and B-cell lymphoma and acute myeloid leukemia. NFKB1 mRNA expression was found to be downregulated relative to controls in many hematological malignancies. These data indicate that NFKB1 is a haploidentical tumor suppressor that suppresses the growth of hematological malignancies, in the context of alkylating injury [45]. A deficiency in NFKB1, even loss of a single allele, is also found to be responsible

for spontaneously invasive gastric cancer (GC), representing the histopathological progression of gastric adenocarcinoma intestines in humans [46]. Increased NFKB1 expression and NF- κ B activation in hormone independent human estrogen receptor have been implicated in the development of breast cancer [42, 47]. Human colorectal cancer research has found that NFKB1 (homodimer p50) can impair macrophage M1 polarization, promoting the growth of colorectal cancer [48, 49]. These investigations may help clarify the role of NFKB1 in cancer pathogenesis and support the development of strategies to manipulate NF- κ B as a potential cancer therapy [42]. This first case study confirmed that Drivergene.net can exactly identify the driver nodes of a directed network as well as the anticancer drug target genes of a human directed biomolecular network.

Assessing anticancer drug target genes identified from an undirected biomolecular network.

In addition, the study employed Drivergene.net for Human protein-protein interaction network, with the data in Table S2, for identifying driver nodes as well as anticancer drug target genes from an undirected network. After computing the total support of each node by the software, selected the gene with the highest total support score. As a result, the study found that mutation of TP53 or p53, with the highest total support score, is found in 50% of all human cancers, which sufficiently indicates the tumor suppressive action of p53. Cells are organized and protected by the p53 gene against melanoma transformation and progression. The potent transcriptional properties of activated p53 can control cell cycle processes, senescence, and apoptosis. Although p53 does not interact directly with cancer-specific

targeted therapies, its key role in controlling cell growth and apoptosis, as well as frequent mutations in tumors, make p53 a unique target for cancer therapy. A wise strategy in cancer therapy is thought to be the activation of the p53 inhibitory pathway in malignancies [50, 51, 52]. This second case study confirmed that Drivergene.net can exactly identify the driver nodes of an undirected network as well as the anticancer drug target genes of a human undirected biomolecular network.

Assessing anticancer drug target genes identified from a heterogeneous biomolecular network.

Finally, the study employed Drivergene.net for Human signaling network, with the data in Table S3, for identifying driver nodes as well as anticancer drug target genes from a heterogeneous network. After computing the total support of each node by the software, selected the gene with the highest total support score. As a result, the study found that gene SRC is strongly implicated in the development, maintenance, progression and metastasis of several human cancers, such as prostate, colorectal, breast, lung, head and neck, pancreatic, and brain. In prostate cancer, SRC has been found to be expressed at high levels in malignant tissues and primary cell cultures [53, 54]. In colorectal cancer, it was proved that the level of SRC expression in precancerous polyps is 5 to 8 times higher than in normal mucosa [54], and current treatment modalities studies for human colorectal cancer often combine EGFR targeting with control of SRC [56, 57]. In breast cancer, alterations in signaling pathways associated with SRC have been identified [58], and recent data in breast cancer suggest that drug of Dasatinib with inhibition of SRC is tolerable in patients with breast tumors [59]. In non-small cell lung cancer (NSCLC), the role of tyrosine kinase and SRC signaling as a prominent target in the treatment of lung cancer [60, 61]. In head and neck cancer (HNSCC), usage of SRC-targeted Dasatinib and AZD-0530 in preclinical models of HNSCC showed reduced cell proliferation and invasion of cancer cells [62, 63]. In pancreatic cancer, high levels of SRC were detected in tumor tissues and cell cultures de-

rived from pancreatic malignancies [64, 65], and SRC-targeted therapy was proposed. In brain cancer, preclinical data indicate that Dasatinib has the potential to suppress the viability and migration of glioblastoma cells in laboratory settings (in vitro) and impede tumor growth in living organisms (in vivo) by targeting the SRC signaling pathway [66]. This third case study confirmed that Drivergene.net can exactly identify the driver nodes of a heterogeneous network as well as the anticancer drug target genes of a heterogeneous biomolecular network. The study found genes with the highest total support of three large-scale biomolecular networks and proved that these driver genes are anticancer drug target genes. Especially, the other genes in the top 10 highest total support are also proven as being related to various cancer types. In addition, the top 10 genes in terms of highest total support as identified by Drivergene.net are located at the innermost core of these networks [24], respectively: 80% K-core of the human signaling network, 70% R-core of the human gene regulatory network, and 60% K-core of human PPI network, where K-core and R-core are the network central areas defined in [34]. This result agrees the consensus of previous studies that important cancer biomarker genes are often located in the innermost cores of biological networks [31, 32, 33, 34], and these genes often act as target genes for cancer drugs and as biomarker genes for cancer in the biological networks [23]. In the Table 2, the top 10 genes with the highest total support are denoted with NCBI gene symbols, where 86.67% of them, i.e., 26 out of 30 genes, were previously reported as candidate anticancer drug target genes.

3.4. Comparison with other methods

The study compared Drivergene.net's prediction results of anticancer drug target genes (driver nodes) with those of five previous methods: Tran's [5], Wang's [67], Emig's [68], Li's [69], and Liu's [70]. These predictions were obtained using network-based approaches to predict anticancer drug target genes. Tran et al used an outside competitive dynamics model and predicted over 17 cancer-signaling networks from KEGG for finding 34 can-

Table 2: Candidate anticancer drug target genes identified by Drivergene.net ranking

Biomolecular network	Properties		Candidate genes	PubMed ID of published evidence
	Node	Edge		
Human gene regulatory network (directed network)	943	3917	NFKB1	30205516,29562203, 32231206
			RELA	For further studies
			JUN	32917236,17672916
			FOS	34610301,32280695
			MYC	22464321,32651356, 33397405, 33051686
			STAT1	33608980,25267067, 33834023
			CCND1	29969496,27713153
			CREB1	30127997,26743006
			STAT3	24743777,32816914, 33435349
			HIF1A	28358664,35860430
Human PPI network (undirected network)	7242	21909	TP53	23115424,20966976, 15990917
			GRB2	29550383
			PXN	34135128
			TRAF2	30294322
			DIPA	For further studies
			SMAD2	20010874
			VCL	For further studies
			EGFR	28368335,28002810
			SRC	11114744,19581523
			SMAD3	20010874
Human signaling network (mixed network)	1609	5079	SRC	11114744,19581523
			AR	24425228
			AKT	27232857
			SHC	For further studies
			SMAD3	20010874
			RAC1	32460002
			GAB2	22858987
			PI3K	30782187
			PKA	24212646
			SMAD4	29602802

didate anticancer drug target genes [5]. Wang et al identified 25 candidate cancer drug targets by network score from genes sensitive with p53 mutation, which exists in more than half of all human cancer cases. The research utilized a method for structural analysis of regulatory network to locate potential synthetic lethal genes [67]. Emig et al found 17 candidate anticancer drug target genes through the combination of four network methods, namely Neighborhood Scoring, Interconnectivity, Network Propagation, and Random Walks, using a molecular interaction network associated with microarray experimental data [68]. Li proposed an algorithm called PersonalRank, a variant of Random Walk algorithm, for anti-cancer drug target prediction. The study found 16 candidate anticancer drug targets [69]. Liu developed a network distance-based method to identify specific anticancer drug targets due to the potential adverse effects of chemotherapy agents on both cancer and normal tissues. The study found 13 candidate anticancer drug genes from 35 pairs of SynLethDB genes in association with synthetic lethality data [70]. For comparison with the above methods, the study used the top 10 genes in Table 2, including a list of 24 candidate unique genes for three large-scale biological networks. Note that, the selection of the top 10 rather than the other top highest-ranking candidates of biomarker genes, for it makes sure that the number of genes in the study’s prediction is not significantly different from those in other predictions. Specifically, the number of anticancer drug target genes of Ours prediction, Tran’s prediction, Wang’s prediction, Emig’s prediction, Li’s prediction, Liu’s prediction are respectively 24, 34, 25, 17, 16, 13, whose proportions are not significantly different ($P\text{-value} > 0.05$). In other words, that our size of sample is statistically similar with the other’s makes sure that the comparison is not bias due to the difference in sample sizes. The Venn diagram in Fig. 2 shows that Drivergene.net’s prediction joins the consensus of all other methods with the largest number of intersected genes being 9, whereas other methods have only as highest as 5. This implies that the prediction results for Drivergene.net on large-scale biomolec-

ular networks are better than others’ results because they agree with almost other methods and provide the largest number of intersection genes when the number of elements was not significantly different. The shared genes included *EGFR*, *GRB2*, *GAB2*, *STAT3*, *HIF1A*, *TRAF2*, *TP53*, *MYC* and *JUN*. These genes encode proteins in the nucleus and cytoplasm involved in cancer pathways in the digestive system, such as colorectal cancer, GC, and hepatocellular carcinoma. All are genes that encode phosphoproteins, which are considered biomarkers of cancer therapy [71]. Note that although the prediction results of Drivergene.net are better than those of previous methods, this does not mean that the study reject the results of these methods, and using all these methods together will produce the best results.

Figure 2, the Venn diagram was drawn from the predictions of five research results on anti-cancer drug target genes. Drivergene.net’s prediction outperforms those of the other methods, as it agrees with all other methods and gives the largest number of intersected genes. The figure was drawn with the online tool www.bioinformatics.psb.ugent.be/webtools/Venn/

4. Discussion

In fact, driver genes and hub genes can be significantly overlap each other in undirected networks but significantly different in directed networks. Some driver genes may serve as hub genes in undirected networks. In other words, they not only regulate key biological processes but also interact with many other genes within the network. Similarly, some hub genes may exhibit characteristics of driver genes, which exert to significantly control over network dynamics and to influence various cellular processes. The convergence of driver genes and hub genes highlights their importance in network organization and function, it can help identify key regulatory elements and potential therapeutic targets for intervention. In contrary, in directed networks, driver genes are more likely to be input nodes rather than hub nodes. For example, an input node with only a directed link to the hub node of a network can be the exact

2) executing parallelly on CPUs; and 3) executing parallelly on all computing devices. Finally, the computational performance of the software tested with various sizes of large-scale biomolecular networks proved that the parallel algorithm was correctly implemented. Especially, the computation on three human large-scale biomolecular networks, including a human protein interaction network (undirected network), a human gene regulatory network (directed network), and a human signaling network (mixed network) showed that the parallel algorithm with the help of the OpenCL library provided the outstanding ability to identify driver nodes. Specifically, 86.67% of the top 10 driver genes with the highest total support were proved as candidate anticancer drug target genes from these networks. Interestingly, the study also found that these genes are located at the innermost core of these networks. This finding is consistent with earlier studies indicating that important cancer biomarker genes are often located in the innermost core of biological networks [31, 32, 33], and these genes often act as anticancer drug target genes and cancer biomarkers in biological networks [23]. The high consistency of these results was tested in comparison with five other prediction methods, and the predictions of Drivergene.net were better than those of competitors, as it agrees with almost other methods and provides the largest number of intersection genes. The intersection genes refer to genes encoding phosphoproteins, which are proven as biomarkers in cancer therapy. The model and software used in this study can effectively detect driver nodes from complex networks as well as anticancer drug target genes from biomolecular networks. In real life, a network system may be interacted by multiple outside agents by multiple links to the nodes inside the system. It's hard to simulate and find driver node by this method without any improvement. In the future, it is possible to further develop the model with more than one interaction to the system at the same time. For example, in cancer therapy, combination therapies may be used simultaneously chemistry or targeted drug to inhibit driver genes in anti-cancer therapy. It is

still necessary problem to solve in the future.

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Declaration of competing interest. None

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Supplementary data. Supplementary data to this article can be found online at <https://github.com/tinhpd/Drivergene.git>

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