

ETC3430/ETC5343

Financial Mathematics under Uncertainty

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

You need some (basic) knowledge about:

- ▶ maximum likelihood estimation methods
- ▶ law of large numbers
- ▶ asymptotic distribution and central limit theorem
- ▶ asymptotic properties of maximum likelihood estimator

Models and Model parameters

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Markov Process

Two-states MC

Three-states MC

Poisson Model

We use a model to describe the process that results in the data that are observed. For example, we may use a linear model to predict the revenue that will be generated for a company depending on how much they may spend on advertising (this would be an example of linear regression)

$$y_i = x_i\beta + \epsilon_i \quad \epsilon_i \sim N(0, \sigma^2)$$

Model Specification: Linear, Gaussian

Model Parameters: β, σ^2

Each model contains its own set of parameters that ultimately defines what the model looks like.

Maximum Likelihood Estimate

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MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Maximum likelihood estimation is a method that determines values for the parameters of a model. The parameter values are found such that they maximise the likelihood that the process described by the model produced the data that were actually observed.

Input:

- ▶ Data: **independent** random variables X_1, \dots, X_n with observed samples: x_1, \dots, x_n
- ▶ Model: the same probability density/mass function $f(x; \theta)$, i.e., the model we think best describes the process of generating the data that usually comes from having some domain expertise but we won't discuss this here.

Objective: Estimate $\theta = (\theta_1, \dots, \theta_p)$, some **unknown** parameters.

MLE utilise the likelihood function (fitness of the parameters to the sample)

$$\mathcal{L}(\theta; x_1, \dots, x_n) = f(x_1; \theta) \cdot f(x_2; \theta) \cdots f(x_n; \theta)$$

or simply $\mathcal{L}(\theta)$. maximum likelihood estimate

$$\hat{\theta} = \arg \max_{\theta} \mathcal{L}(\theta) = \arg \max_{\theta} \log \mathcal{L}(\theta)$$

$\hat{\theta} = \hat{\theta}(x_1, \dots, x_n)$ depends on the observations x_1, \dots, x_n

Observe Some data

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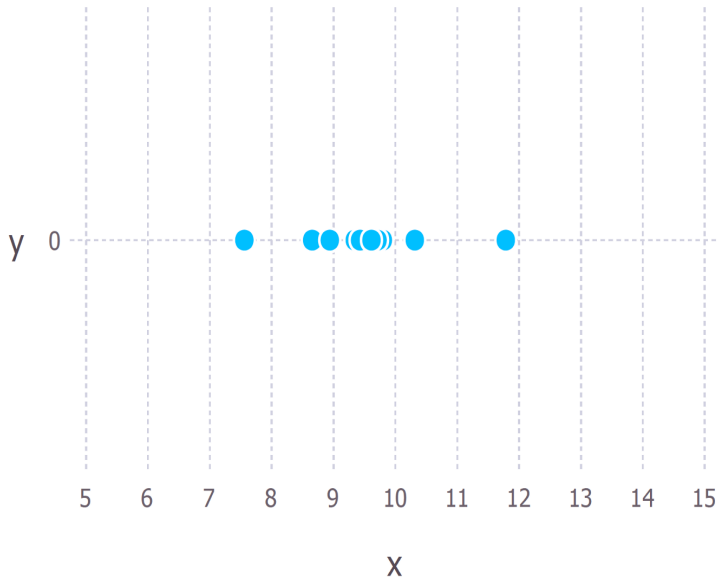
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Markov Process

Two-states MC

Three-states MC

Poisson Model



Which Gaussian

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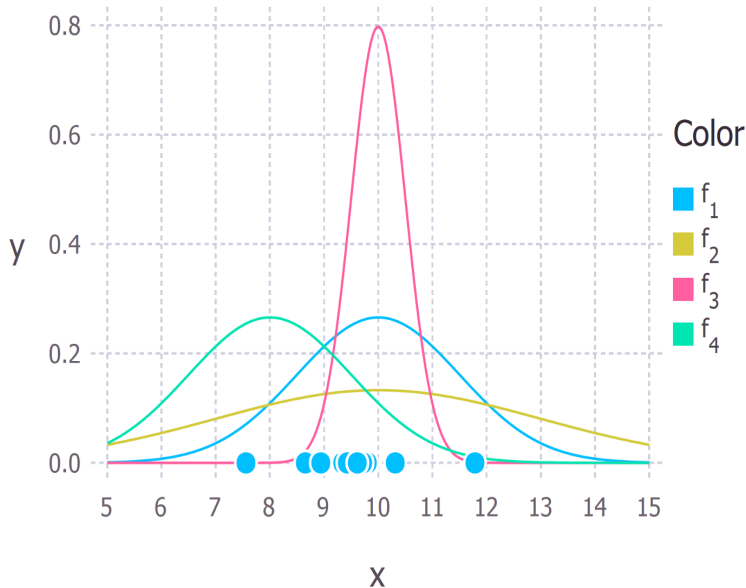
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Markov Process

Two-states MC

Three-states MC

Poisson Model



Asymptotic Distribution: ML Estimator

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The maximum likelihood **estimator**

$$\tilde{\theta} = \hat{\theta}(X_1, \dots, X_n)$$

is a random variable itself because it is a function of the X_1, \dots, X_n .

- ▶ exact distribution is hard to compute (simulation?)
- ▶ **asymptotic** distribution: limiting distribution as $n \rightarrow \infty$

$$N(\theta_0, \mathcal{I}^{-1})$$

where

$$\mathcal{I}_{ij} = -\mathbb{E} \left(\frac{\partial^2}{\partial \theta_i \partial \theta_j} \log \mathcal{L}(\theta; X_1, \dots, X_n) \right)$$

denote by $\tilde{\theta} \stackrel{a}{\sim} \mathcal{N}(\theta, \mathcal{I}^{-1})$

- ▶ Large n : exact distribution \approx asymptotic distribution

Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Theorem

If X_1, \dots, X_n is a sequence of independent and identically distributed random variables with finite mean μ , then

$$\frac{1}{n} \sum_{i=1}^n X_i \rightarrow \mu, \quad \text{as } n \rightarrow \infty$$

with probability 1.

- ▶ weak law of large numbers: $\frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{P} \mu$
- ▶ heuristic: $\frac{1}{n} \sum_{i=1}^n X_i \approx \mu$

Theorem

Univariate central limit theorem If X_1, \dots, X_n is a sequence of independent and identically distributed random variables with finite mean μ and variance σ^2 ,

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n X_i \stackrel{a}{\sim} \mathcal{N}(\mu, \sigma^2), \text{ as } n \rightarrow \infty.$$

Multivariate central limit theorem

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Theorem

If X_1, \dots, X_n is a sequence of independent and identically distributed random vectors with finite mean μ and covariance matrix Σ , as $n \rightarrow \infty$,

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n X_i \stackrel{a}{\sim} \mathcal{N}(\mu, \Sigma), \text{ as } n \rightarrow \infty.$$

An interesting thing about the CLT is that it does not matter what the distribution of the X_i 's is. It can be discrete, continuous, or mixed random variables.

Example

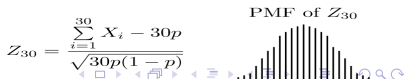
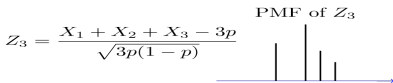
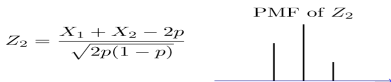
$X_i \sim \text{Bernoulli}(p)$, then

$$\mathbb{E}[X_i] = p, \text{ and } \text{var}(X_i) = p(1 - p).$$

Assumptions:

- X_1, X_2, \dots are iid Bernoulli(p).
- $Z_n = \frac{X_1 + X_2 + \dots + X_n - np}{\sqrt{np(1 - p)}}$.

We choose $p = \frac{1}{3}$.



Example

$X_i \sim \text{Uniform}(0, 1)$, then

$$\mathbb{E}[X_i] = 0.5, \text{ and } \text{var}(X_i) = \frac{1}{12}.$$

Assumptions:

- X_1, X_2, \dots are iid $\text{Uniform}(0,1)$.
- $Z_n = \frac{X_1 + X_2 + \dots + X_n - \frac{n}{2}}{\sqrt{\frac{n}{12}}}$.

$$Z_1 = \frac{X_1 - \frac{1}{2}}{\sqrt{\frac{1}{12}}}$$

PDF of Z_1



$$Z_2 = \frac{X_1 + X_2 - 1}{\sqrt{\frac{2}{12}}}$$

PDF of Z_2



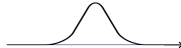
$$Z_3 = \frac{X_1 + X_2 + X_3 - \frac{3}{2}}{\sqrt{\frac{3}{12}}}$$

PDF of Z_3



$$Z_{30} = \frac{\sum_{i=1}^{30} X_i - \frac{30}{2}}{\sqrt{\frac{30}{12}}}$$

PDF of Z_{30}



Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Some asymptotic properties

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Slutsky's theorem

Let $\tilde{\theta}_1 \stackrel{a}{\sim} \mathcal{N}(\theta_1, \sigma_1^2)$ and $\tilde{\theta}_2 \approx c$.

- ▶ $\tilde{\theta} = \tilde{\theta}_1 - \tilde{\theta}_2 \stackrel{a}{\sim} \mathcal{N}(\theta_1 - c, \sigma_1^2)$
- ▶ $\tilde{\theta} = \tilde{\theta}_1 \cdot \tilde{\theta}_2 \stackrel{a}{\sim} \mathcal{N}(c\theta_1, c^2\sigma_1^2)$
- ▶ $\tilde{\theta} = \frac{\tilde{\theta}_1}{\tilde{\theta}_2} \stackrel{a}{\sim} \mathcal{N}\left(\frac{\theta_1}{c}, \frac{\sigma_1^2}{c^2}\right)$ if $c \neq 0$

Asymptotic Independence

$$\begin{pmatrix} \tilde{\theta}_1 \\ \tilde{\theta}_2 \end{pmatrix} \stackrel{a}{\sim} \mathcal{N}\left(\begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}, \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}\right)$$

then $\tilde{\theta}_1$ and $\tilde{\theta}_2$ are asymptotically independent.

An interval $(\tilde{\theta}_L(x_1, \dots, x_n), \tilde{\theta}_U(x_1, \dots, x_n))$ is

- ▶ a 95% confidence interval for θ if

$$\mathbb{P}(\tilde{\theta}_L(X_1, \dots, X_n) < \theta < \tilde{\theta}_U(X_1, \dots, X_n)) = 95\%$$

- ▶ a 95% **asymptotic** confidence interval for θ if

$$\mathbb{P}(\tilde{\theta}_L(X_1, \dots, X_n) < \theta < \tilde{\theta}_U(X_1, \dots, X_n)) \rightarrow 95\%, n \rightarrow \infty.$$

For large n ,

$$\mathbb{P}(\tilde{\theta}_L(X_1, \dots, X_n) < \theta < \tilde{\theta}_U(X_1, \dots, X_n)) \approx 95\%$$

Suppose $\tilde{\theta} = \tilde{\theta}(X_1, \dots, X_n) \stackrel{a}{\sim} \mathcal{N}(\theta, \sigma_n^2)$:

- ▶ estimate $\hat{\theta} = \tilde{\theta}(x_1, \dots, x_n)$
- ▶ an 95% asymptotic confidence interval is

$$\left(\hat{\theta} - 1.96\sigma_n, \hat{\theta} + 1.96\sigma_n \right), \text{ or } \hat{\theta} \pm 1.96\sigma_n$$

where 1.96 is rounded from 1.95996 . . .

- ▶ if σ_n is unknown but estimable by $\hat{\sigma}_n$, use the interval

$$\left(\hat{\theta} - 1.96\hat{\sigma}_n, \hat{\theta} + 1.96\hat{\sigma}_n \right), \text{ or } \hat{\theta} \pm 1.96\hat{\sigma}_n.$$

A Bernoulli Example

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MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

In fact, the Bernoulli distribution $B(p)$ is not a single distribution but rather a one-parameter family of distributions. Each value of p defines a different distribution in the family, with the pdf

$$f(x) = p^x(1 - p)^{1-x} \quad x \in \{0, 1\}.$$

There are many methods for estimating unknown parameters from data. We will first consider the maximum likelihood estimate (MLE), which answers the question:

For which parameter value does the observed data have the most significant probability?

Example Continue

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Markov Process

Two-states MC

Three-states MC

Poisson Model

A coin is flipped 100 times. Given that there were 55 heads find the maximum likelihood estimate for the probability p of heads on a single toss.

- ▶ Experiment: Flip the coin 100 times and count the number of heads.
- ▶ Data: The data is the result of the experiment. In this case, it is 55 heads
- ▶ Parameter of interest: We are interested in the value of the unknown parameter p .
- ▶ Likelihood, or likelihood function

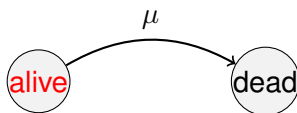
$$L_{100}(p) = \binom{100}{55} p^{55} (1-p)^{100-55}$$

$$\text{Optimal } \hat{p} = \frac{55}{100} = 0.55.$$

Two States Markov Chain

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For lives from age x to $x + 1$ obeying a Markov model with two states: alive and dead



Assumption

The mortality rate, i.e. transition rate, $\mu_{x+t} = \mu$ for all $t \in [0, 1)$

For $t \in [0, 1)$,

$$\begin{aligned} {}_t p_x &= P(\text{Alive at age } t + x | \text{Alive at age } x) \\ &= \exp \left(- \int_0^t \mu_{x+s} ds \right) = \exp(-\mu t) \end{aligned}$$

Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Estimating the Mortality rate

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

- ▶ the value of μ is often unknown in real life
- ▶ μ may be estimated from observations

Data of individuals

- ▶ observations of n lives indexed by $i \in \{1, \dots, n\}$
- ▶ starting from $x + a_i$ and ends **no later than** $x + b_i$
- ▶ censored (more in next week): $0 \leq a_i < b_i \leq 1$
- ▶ i -th life survives to $x + T_i$ in observation
- ▶ waiting time $V_i \equiv T_i - a_i \in (0, b_i - a_i]$
- ▶ $D_i = 1$ if i -th life ends during observation otherwise $D_i = 0$
- ▶ our dataset is $\{(v_i, d_i) : i = 1, \dots, n\}$

Assumption

The lives are identical and statistically independent, i.e., $\{(V_i, D_i) : i = 1, \dots, n\}$ are i.i.d. distributed.

- ▶ D_i fully depends on V_i : $D_i = 0 \Leftrightarrow V_i = b_i - a_i$
- ▶ V_i has a probability mass

$$\mathbb{P}(V_i = b_i - a_i) = p_x = \exp(-\mu(b_i - a_i))$$

- ▶ ... and density function on $(0, b_i - a_i)$

$$\begin{aligned} f(t; \mu) &= \frac{\partial}{\partial t} t q_x \\ &= \frac{\partial}{\partial t} (1 - \exp(-\mu t)) = \mu \exp(-\mu t), \quad t \in (0, b_i - a_i) \end{aligned}$$

- Likelihood for $i \in \mathcal{C} = \{i : d_i = 0\}$

$$\mathcal{L}_i(\mu) = \exp(-\mu(b_i - a_i)) = \exp(-\mu \mathbf{v}_i) = \mu^{d_i} \exp(-\mu \mathbf{v}_i)$$

- Likelihood for $i \in \mathcal{D} = \{i : d_i = 1\}$

$$\mathcal{L}_i(\mu) = f(\mathbf{v}_i; \mu) = \mu \exp(-\mu \mathbf{v}_i) = \mu^{d_i} \exp(-\mu \mathbf{v}_i)$$

Total likelihood

$$\mathcal{L}(\mu) = \prod_{i=1}^n \mathcal{L}_i(\mu) = \mu^d \exp(-\mu \mathbf{v})$$

where

$$d = \sum_{i=1}^n d_i, \quad \mathbf{v} = \sum_{i=1}^n \mathbf{v}_i$$

Maximum Likelihood Estimation

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Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

- ▶ $\log \mathcal{L}(\mu) = d \log \mu - \mu v$
- ▶ $(\log \mathcal{L}(\mu))' = \frac{d}{\mu} - v = 0$ gives $\hat{\mu}_x = \frac{d}{v}$
- ▶ $(\log \mathcal{L}(\mu))'' = -\frac{d}{\mu^2} < 0$

The maximum likelihood estimate is

$$\hat{\mu} = \frac{d}{v} = \frac{\sum_{i=1}^n d_i}{\sum_{i=1}^n v_i}$$

and the maximum likelihood estimator

$$\tilde{\mu} = \frac{D}{V} = \frac{\sum_{i=1}^n D_i}{\sum_{i=1}^n V_i}$$

- ▶ average number of deaths from the population for each time unit

Asymptotic Properties of $\tilde{\mu}$

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MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

$$\tilde{\mu} - \mu = \frac{\frac{1}{n} \sum_{i=1}^n (D_i - \mu V_i)}{\frac{1}{n} \sum_{i=1}^n V_i}$$

► Homeworks:

$$\mathbb{E}(D_i - \mu V_i) = 0, \text{Var}(D_i - \mu V_i) = \mathbb{E}(D_i - \mu V_i)^2 = \mu E(V_i)$$

► Central limit theorem:

$$\frac{1}{n} \sum_{i=1}^n (D_i - \mu V_i) \overset{a}{\sim} \mathcal{N}\left(0, \frac{1}{n} \mu E(V_i)\right)$$

► Law of large numbers: $\frac{1}{n} \sum_{i=1}^n V_i \approx E(V_i)$

► Slutsky theorem:

$$\tilde{\mu} - \mu \overset{a}{\sim} \mathcal{N}\left(0, \frac{1}{n} \frac{\mu E(V_i)}{(E(V_i))^2}\right)$$

From the last step:

$$\tilde{\mu} - \mu \stackrel{a}{\sim} \mathcal{N}\left(0, \frac{1}{n} \frac{\mu}{E(V_i)}\right)$$

or equivalently

$$\tilde{\mu} \stackrel{a}{\sim} \mathcal{N}\left(\mu, \frac{\mu}{E(V)}\right)$$

since $E(V) = \sum_{i=1}^n E(V_i) = nE(V_i)$

95% Confidence Interval

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Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

From the last step:

$$\hat{\mu} \pm 1.96 \sqrt{\frac{\mu}{E(V)}}$$

Estimating μ by $\hat{\mu}$ and $E(V)$ by v yields the asymptotic 95% confidence interval

$$\hat{\mu} \pm 1.96 \sqrt{\frac{\hat{\mu}}{v}}$$

HSD Model

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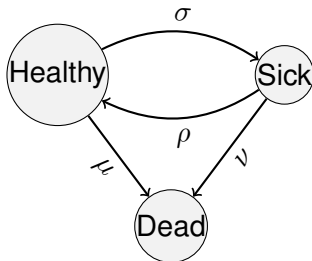
Markov Process

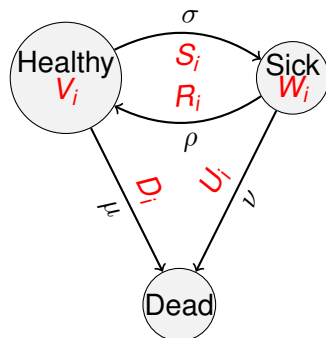
Two-states MC

Three-states MC

Poisson Model

For lives from obeying a Markov model with three states:
healthy (H), sick (S) and dead (D)





the i -th life:

V_i = **Total** waiting time in 'healthy'

W_i = **Total** waiting time in 'sick'

S_i = # transitions 'healthy' to 'sick'

R_i = # transitions 'sick' to 'healthy'

D_i = # transitions 'healthy' to 'dead'

U_i = # transitions 'sick' to 'dead'

Observed: v_i , w_i , s_i , r_i , d_i and u_i .

$$v_i = \sum_{j=1}^{d_i+s_i} v_{i,j} \text{ and } w_i = \sum_{j=1}^{r_i+u_i} w_{i,j}$$

Last week, Page 3

Given a jump has occurred, the time at which took place does affect the probability of the jump being to a particular state.

Two independent components:

1. waiting times

- ▶ at state 'Healthy':

$$\prod_{j=1}^{d_i+s_i} (\mu+\sigma) \exp(-(\mu+\sigma) v_{i,j}) = (\mu+\sigma)^{d_i+s_i} \exp(-(\mu+\sigma) v_i)$$

- ▶ at state 'Sick'

$$\prod_{j=1}^{r_i+u_i} (\rho+\nu) \exp(-(\rho+\nu) w_{i,j}) = (\rho+\nu)^{r_i+u_i} \exp(-(\rho+\nu) w_i)$$

2. transitions between states

Individual likelihood: continued

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Two independent components:

1. waiting times

- ▶ at state 'Healthy': $(\mu + \sigma)^{d_i + s_i} \exp(-(\mu + \sigma) v_i)$
- ▶ at state 'Sick': $(\rho + \nu)^{r_i + u_i} \exp(-(\rho + \nu) w_i)$

2. transitions between states

- ▶ $H \rightarrow S: \left(\frac{\sigma}{\mu + \sigma}\right)^{s_i}$
- ▶ $H \rightarrow D: \left(\frac{\mu}{\mu + \sigma}\right)^{d_i}$
- ▶ $S \rightarrow H: \left(\frac{\rho}{\rho + \nu}\right)^{r_i}$
- ▶ $S \rightarrow D: \left(\frac{\nu}{\rho + \nu}\right)^{u_i}$

Multiplying all components,

$$\mathcal{L}_i(\mu, \nu, \sigma, \rho) = \exp(-(\mu + \sigma) v_i) \exp(-(\rho + \nu) w_i) \mu^{d_i} \nu^{u_i} \sigma^{s_i} \rho^{r_i}$$

Total likelihood

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Recall from the last step:

$$\mathcal{L}_i(\mu, \nu, \sigma, \rho) = \exp(-(\mu + \sigma) v_i) \exp(-(\rho + \nu) w_i) \mu^{d_i} \nu^{u_i} \sigma^{s_i} \rho^{r_i}$$

The individuals are independent:

$$\begin{aligned}\mathcal{L}(\mu, \nu, \sigma, \rho) &= \prod_{i=1}^n \mathcal{L}_i(\mu, \nu, \sigma, \rho) \\ &= \exp(-(\mu + \sigma) v) \exp(-(\rho + \nu) w) \mu^d \nu^u \sigma^s \rho^r\end{aligned}$$

where

$$\begin{aligned}v &= \sum_{i=1}^n v_i, \quad w = \sum_{i=1}^n w_i, \quad s = \sum_{i=1}^n s_i, \\ r &= \sum_{i=1}^n r_i, \quad d = \sum_{i=1}^n d_i, \quad u = \sum_{i=1}^n u_i.\end{aligned}$$

Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Maximum Likelihood

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

$$\log \mathcal{L} = -(\mu + \sigma) v - (\rho + \nu) w + d \log \mu + u \log \nu + s \log \sigma + r \log \rho$$
$$\frac{\partial \mathcal{L}}{\partial \mu} = -v + \frac{d}{\mu}, \quad \frac{\partial \mathcal{L}}{\partial \nu} = -w + \frac{u}{\nu}, \quad \frac{\partial \mathcal{L}}{\partial \sigma} = -v + \frac{s}{\sigma}, \quad \frac{\partial \mathcal{L}}{\partial \rho} = -w + \frac{r}{\rho}$$

Setting all partial derivatives to be zero, yields the maximum likelihood estimates

$$\hat{\mu} = \frac{d}{v}, \quad \hat{\nu} = \frac{u}{w}, \quad \hat{\sigma} = \frac{s}{v}, \quad \hat{\rho} = \frac{r}{w}$$

They are maximum points because the log-likelihood function is concave: the Hessian matrix

$$\mathbf{H}(\mu, \nu, \sigma, \rho) = \text{diag} \left(-\frac{d}{v^2}, -\frac{u}{\nu^2}, -\frac{s}{\sigma^2}, -\frac{r}{\rho^2} \right)$$

is negative definite.

Maximum likelihood estimates in general

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

The maximum likelihood estimate of the transition rate μ_{km} from state k to state m , $k \neq m$, is

$$\begin{aligned}\hat{\mu}_{km} &= \frac{n_{km}}{t_k} \\ &= \frac{\# \text{ transitions from state } k \text{ to state } m}{\text{total waiting time in state } k}\end{aligned}$$

- ▶ This is a general formula for time-homogeneous Markov jump process with any finite number of states.
- ▶ Denote by the corresponding estimator to be $\tilde{\mu}_{km}$.

K-states time-homogeneous Markov jump process:

- ▶ estimators $\{\tilde{\mu}_{km} : k, m \in \{1, \dots, K\}, k \neq m\}$ are asymptotically multivariate normal
- ▶ ... and asymptotically independent
 - ▶ The Hessian matrix of log-likelihood function is diagonal, and so does the Fisher information;
 - ▶ HSD model: $D_i - \mu V_i$, $U_i - \mu V_i$, $S_i - \sigma V_i$, and $R_i - \rho W_i$ are uncorrelated

just like in the two-states model:



$$\tilde{\mu}_{km} - \mu_{km} \overset{a}{\sim} \mathcal{N}\left(0, \frac{\mu_{km}}{\mathbb{E}(T_k)}\right)$$

where T_k is the total waiting time in state k over all individuals.

- asymptotic 95% confidence intervals for μ_{km}

$$\hat{\mu}_{km} \pm 1.96 \sqrt{\frac{\hat{\mu}_{km}}{t_k}}$$

Expected number of deaths

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Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

- ▶ $D_i = 1$ is a Bernoulli variable

$$\mathbb{E}(D_i) = \mathbb{P}(D_i = 1) = 1 - e^{-\mu(b_i - a_i)} \approx \mu(b_i - a_i)$$

- ▶ The expected number of deaths

$$\mathbb{E}(D) = \sum_{i=1}^n \mathbb{E}(D_i) \approx \mu \sum_{i=1}^n (b_i - a_i) = \mu E_x^c$$

- ▶ ... where $E_x^c = \sum_{i=1}^n (b_i - a_i)$ is called central exposed to risk (more in Week 8)

Theorem

Poisson limit theorem: when D_i are independent and under some weak regularity conditions,

$$D = \sum_{i=1}^n D_i \stackrel{a}{\sim} \text{Poisson}(\lambda)$$

where $\lambda = \mu E_x^c$.

The Poisson approximation:

$$\mathbb{P}(D = d) \approx \frac{e^{-\mu E_x^c} (\mu E_x^c)^d}{d!}$$

the approximation allows the impossible event $D > n$ with a small probability

MLE in Poisson Model

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Now use the approximate Poisson likelihood

$$\mathcal{L}(\mu) = \frac{e^{-\mu E_x^c} (\mu E_x^c)^d}{d!}$$

Taking logarithms of both sides yields that

$$\log \mathcal{L}(\mu) = -\mu E_x^c + d (\log(\mu) + \log(E_x^c)) - \log(d!)$$

Solve the first order condition

$$(\log \mathcal{L}(\mu))' = -E_x^c + \frac{d}{\mu} = 0$$

and we obtain the maximum likelihood estimator

$$\hat{\mu} = \frac{d}{E_x^c}$$

► Second order condition: $(\log \mathcal{L}(\mu))'' = -\frac{d}{\mu^2} < 0$.

Introduction

Crash course to
MLE

Markov Process

Two-states MC

Three-states MC

Poisson Model

Maximum Likelihood Estimator in Poisson Model

The maximum likelihood estimator is therefore

$$\tilde{\mu} = \frac{D}{E_x^c}$$

and the maximum likelihood estimate is

$$\hat{\mu} = \frac{d}{E_x^c}$$

- ▶ Substituting E_x^c for V in the previous MLE $\tilde{\mu} = \frac{D}{V}$

Asymptotic Property of $\tilde{\mu}$

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- ▶ When $E(D) \approx \mu E_x^c$ is large, we can use the normal approximation

$$D \stackrel{a}{\sim} \mathcal{N}(\mu E_x^c, \mu E_x^c)$$

and thus

$$\tilde{\mu} = \frac{D}{E_x^c} \stackrel{a}{\sim} \mathcal{N}\left(\mu, \frac{\mu}{E_x^c}\right)$$

- ▶ 95% asymptotic confidence interval

$$\hat{\mu} \pm 1.96 \sqrt{\frac{\hat{\mu}}{E_x^c}}$$

- ▶ same formula as before except substituting E_x^c for v