

SciTinyML

Scientific Use of Machine Learning on Low Power Devices

Regional Workshop - Africa

Hands-on Lab with Edge Impulse
Motion Classification

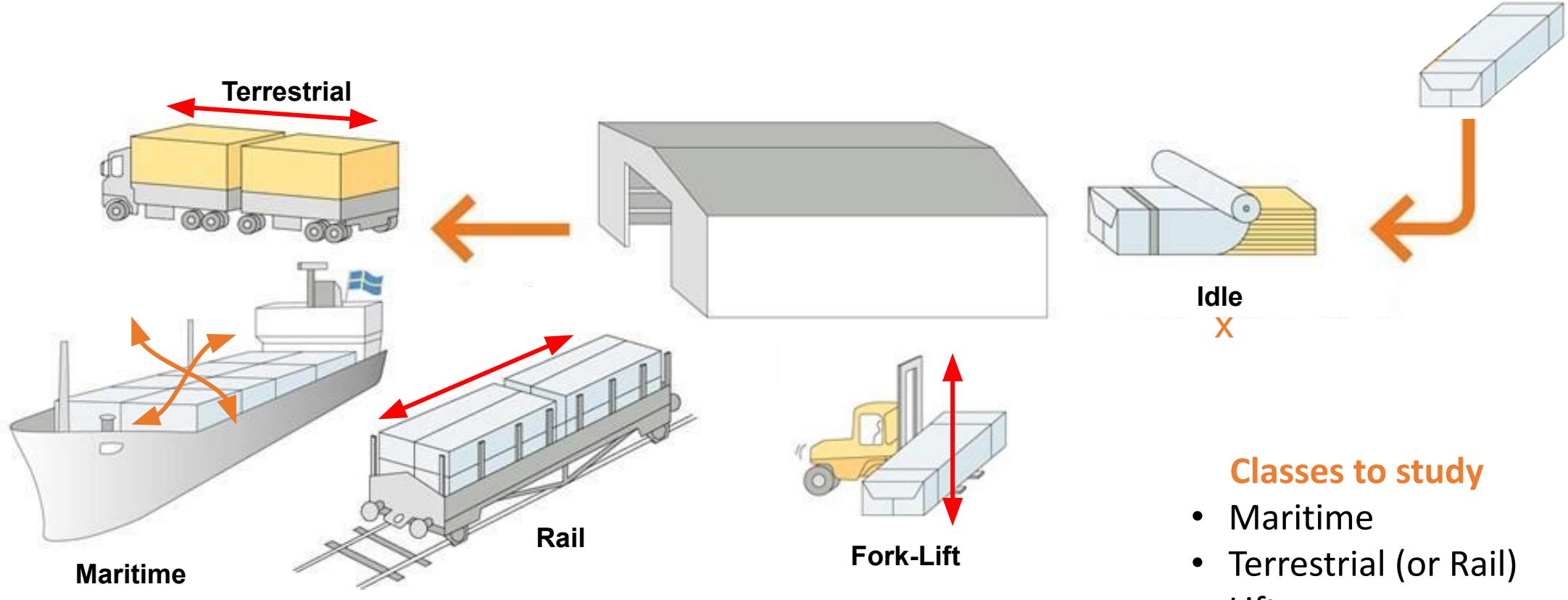
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Professor, UNIFEI - Brazil

Shawn Himel
Senior DevRel Engineer, Edge Impulse



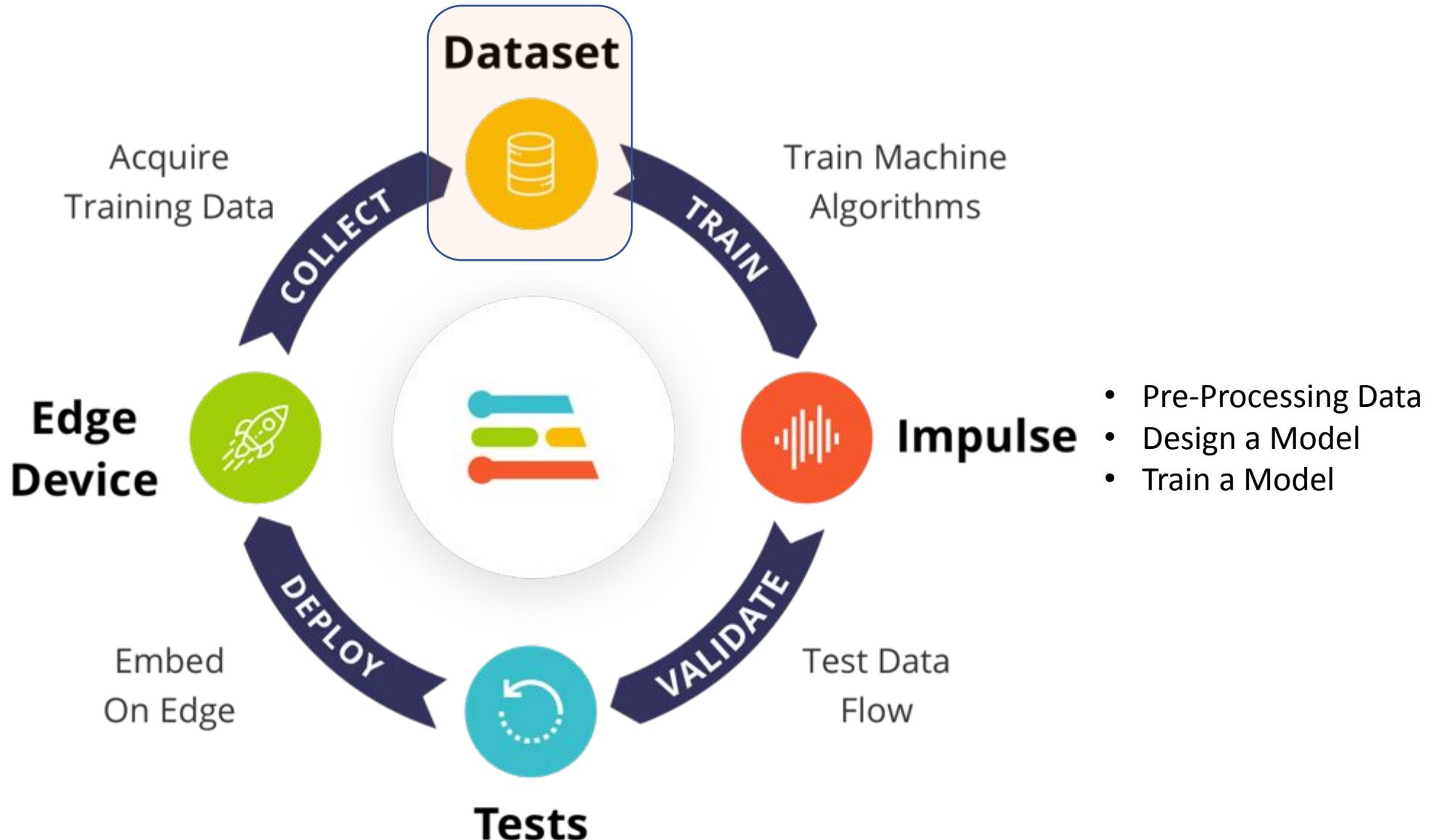
Hands-on lab for
motion classification

Case Study: Mechanical Stresses in Transport



Classes to study

- Maritime
- Terrestrial (or Rail)
- Lift
- Idle



The screenshot shows the Edge Impulse Studio interface for data acquisition. A modal window titled "studio.edgeimpulse.com wants to connect to a serial port" is open, listing available ports:

- cu.Bluetooth-Incoming-Port
- cu.MALS
- cu.RovaisAirPods-Wirelessi
- cu.SOC
- Nano 33 BLE (cu.usbmodem145101)**

A blue arrow labeled "2" points to the "Nano 33 BLE" entry. An orange box highlights the "cu.SOC" entry, and another orange box highlights the "Connect" button at the bottom of the modal. A large blue arrow labeled "3" points from the bottom of the modal towards the main studio interface.

The main studio interface has a purple header bar with the text "Acquisition mode or development board, or upload your existing datasets - Show options". On the right, there's a user profile for "MJRoBot (Marcelo Rovai)".

The main content area includes:

- A "Record new data" section with a message: "No devices connected to the remote management API."
- A "RAW DATA" section with the text "Click on a sample to load..."
- A "Connect using WebUSB" button with a small icon.

Blue arrows labeled "1" point to the "Connect using WebUSB" button and the "RAW DATA" section.

At the bottom left, the sidebar shows navigation links like Dashboard, Devices, Data acquisition, and Model testing. The "Data acquisition" link is highlighted with an orange box.

At the bottom right, there are links for Documentation and Forums.

WebUSB works fine with Chrome

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - [Show options](#)

DATA COLLECTED

Collected data

No data collected yet

Let's collect some data

Record new data

Device: 36:17:55:F9:70:F7

Label: terrestrial (highlighted with orange border)

Sample length (ms.): 10000

Sensor: Built-in accelerometer

Frequency: 100Hz

Start sampling

RAW DATA
Click on a sample to load...

The screenshot shows the Edge Impulse Data Acquisition interface. On the left sidebar, under the 'Data acquisition' section, there is a 'Label' field which is highlighted with an orange border. Two large blue arrows point from the bottom of the page towards the 'Start sampling' button at the bottom right of the 'Record new data' form. The 'Label' field contains the text 'terrestrial'. The 'Start sampling' button is located to the right of the 'Frequency' dropdown.

Devices - IESTI01 - Nano Motion Classification

studio.edgeimpulse.com/studio/61345/devices

EDGE IMPULSE

DEVICES (IESTI01 - NANO MOTION CLASSIFICATION)

MJRoBot (Marcelo Rovai)

Your devices

+ Connect a new device

These are devices that are connected to the Edge Impulse remote management API, or have posted data to the ingestion SDK.

NAME	ID	TYPE	SENSORS	REMOTE M...	LAST SEEN
 36:17:55:F9:70:F7	36:17:55:F9:70:F7	ARDUINO_NANO33BLE	Built-in accelerometer, Built-in microphone...	●	Today, 12:26:49

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Dashboard

Devices

Data acquisition

Impulse design

Create impulse

EON Tuner

Retrain model

Live classification

Model testing

Versioning

Deployment

GETTING STARTED

Documentation

Forums

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - [Show options](#)

DATA COLLECTED 10s TRAIN / TEST SPLIT 100% / 0% ⚠

Collected data

SAMPLE NAME	LABEL	ADDED	LENGTH
terrestrial.json.2jbimlk	terrestrial	Today, 13:01:46	10s

Record new data

Device Nano

Label terrestrial

Sample length (ms.) 10000

Sensor Sensor with 3 axes (accX, accY, accZ)

Frequency 100Hz

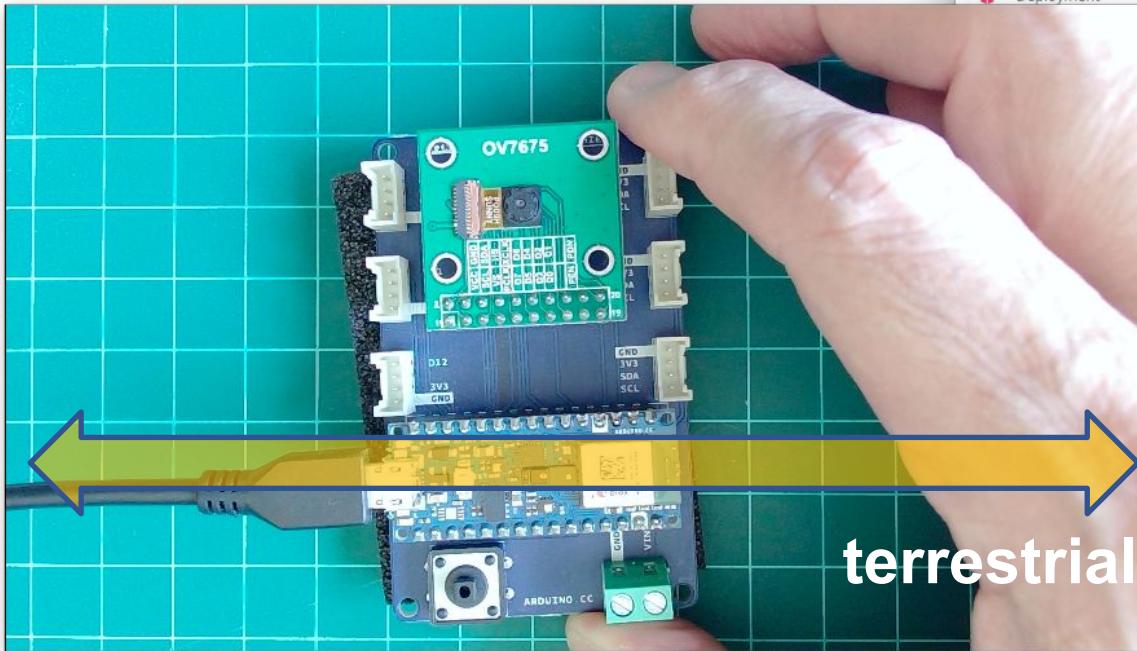
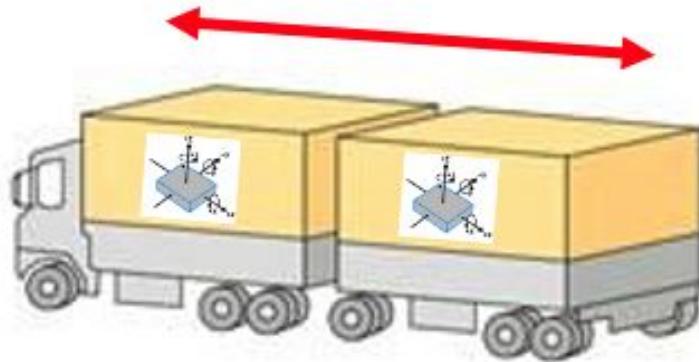
Start sampling

RAW DATA
terrestrial.json.2jbimlk

accX accY accZ

<https://studio.edgeimpulse.com/studio/61345/acquisition/training?page=1#>

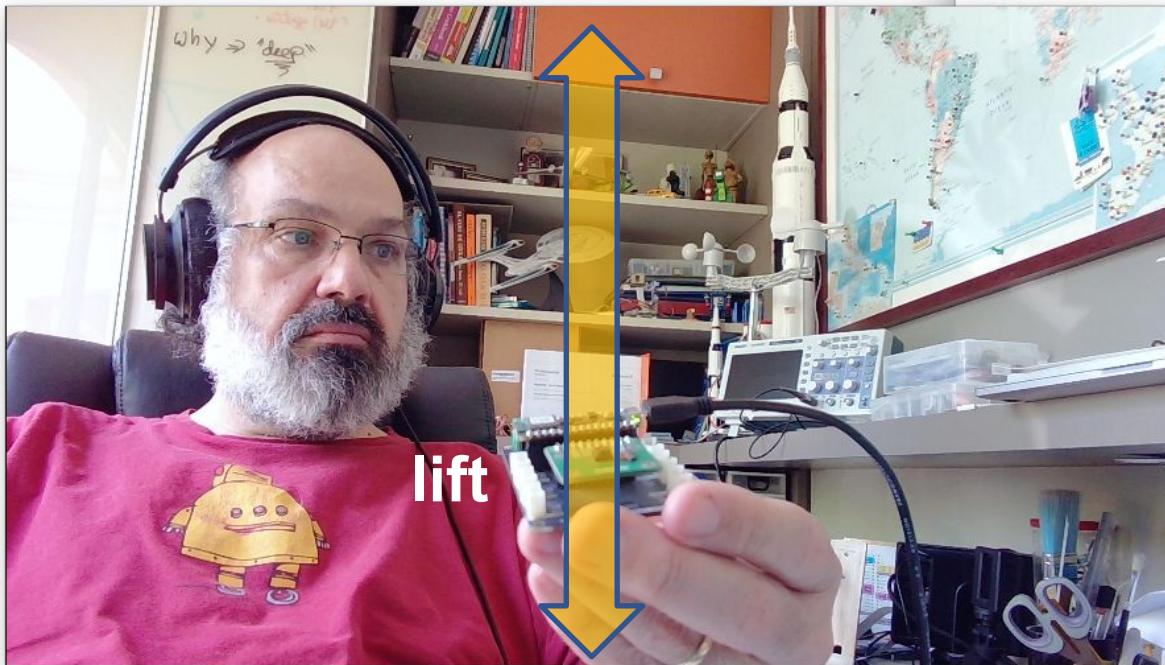
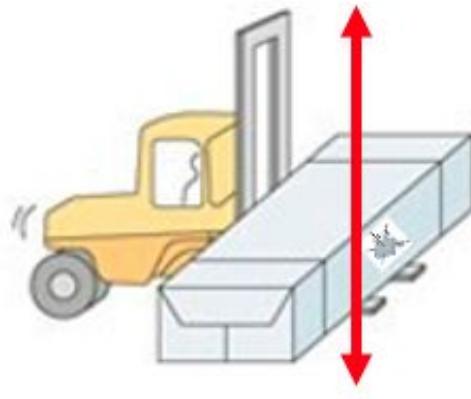
Label: terrestrial



The screenshot shows the Edge Impulse Data Acquisition interface. On the left, a sidebar lists options: Dashboard, Devices, Data acquisition (selected), Impulse design, Create impulse, EON Tuner, Retrain model, Live classification, Model testing, Versioning, and Deployment. The main area displays "DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)". It shows "Training data" and "Test data" tabs, with a note: "Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options". Below this, it says "DATA COLLECTED 1m 40s" and "TRAIN / TEST SPLIT 100% / 0%". A table titled "Collected data" lists ten entries, all labeled "terrestrial". The right side of the interface shows a "Record new data" section with fields for Device (Nano), Label (terrestrial), Sample length (ms.) (10000), Sensor (Sensor with 3 axes (accX, accY, accZ)), Frequency (100Hz), and a "Start sampling" button. At the bottom, a "RAW DATA" section titled "terrestrial.json.2jvgelce" shows a line graph of three axes (accX, accY, accZ) over time.

SAMPLE NAME	LABEL	ADDED	LENGTH
terrestrial.json.2jv...	terrestrial	Today, 14:26:56	10s
terrestrial.json.2jv...	terrestrial	Today, 14:26:29	10s
terrestrial.json.2jv...	terrestrial	Today, 14:26:06	10s
terrestrial.json.2jv...	terrestrial	Today, 14:25:48	10s
terrestrial.json.2jv...	terrestrial	Today, 14:25:29	10s
terrestrial.json.2jv...	terrestrial	Today, 14:25:04	10s
terrestrial.json.2jv...	terrestrial	Today, 14:24:45	10s
terrestrial.json.2jv...	terrestrial	Today, 14:24:21	10s
terrestrial.json.2jvf...	terrestrial	Today, 14:17:45	10s
terrestrial.json.2jv...	terrestrial	Today, 13:01:46	10s

Label: LIFT



studio.edgeimpulse.com/studio/61345/acquisition/training?page=1

EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

MJRoBot (Marcelo Rovai)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED 3m 20s TRAIN / TEST SPLIT 100% / 0%

SAMPLE NAME	LABEL	ADDED	LENGTH
lift.json.2jvhbt7	lift	Today, 14:42:04	10s
lift.json.2jvh9pe3	lift	Today, 14:41:45	10s
lift.json.2jvh96uh	lift	Today, 14:41:26	10s
lift.json.2jvh8j6q	lift	Today, 14:41:06	10s
lift.json.2jvh80rg	lift	Today, 14:40:47	10s
lift.json.2jvh7g2v	lift	Today, 14:40:30	10s
lift.json.2jvh6uqu	lift	Today, 14:40:12	10s
lift.json.2jvh6c6a	lift	Today, 14:39:53	10s
lift.json.2jvh5qbe	lift	Today, 14:39:35	10s
lift.json.2jvh55hs	lift	Today, 14:39:14	10s
terrestrial.json.2jv...	terrestrial	Today, 14:26:56	10s
terrestrial.json.2jv...	terrestrial	Today, 14:26:29	10s

Record new data

Device Nano

Label lift

Sample length (ms.) 10000

Sensor Sensor with 3 axes (accX, accY, accZ)

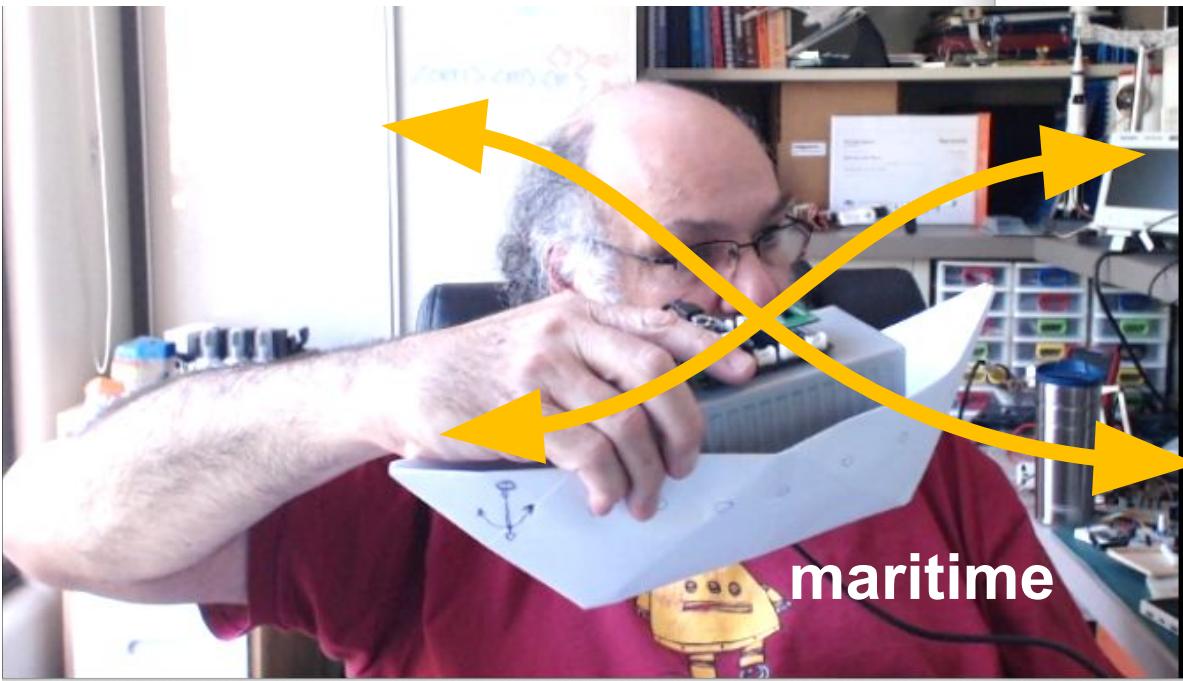
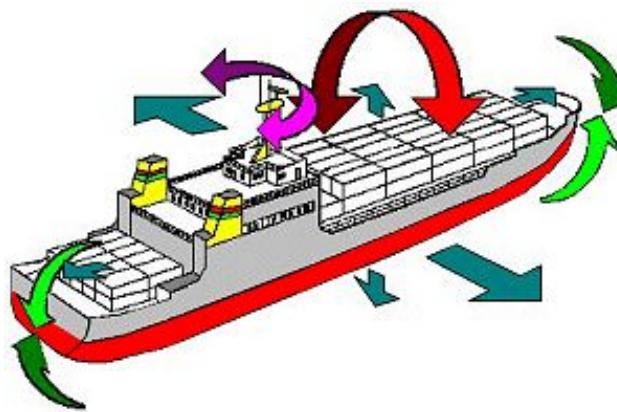
Frequency 100Hz

Start sampling

RAW DATA lift.json.2jvhbt7

The graph displays three data series: accX (red), accY (green), and accZ (blue). The x-axis represents time in milliseconds, ranging from 0 to 9360 with major ticks every 1040 units. The y-axis ranges from -20 to 20 with major ticks every 5 units. All three axes show a highly oscillatory pattern, with accX generally having the highest amplitude and accZ the lowest. The data points correspond to the samples listed in the table above.

Label: maritime



Data acquisition - IESTI01 - Na +

studio.edgeimpulse.com/studio/61345/acquisition/training?page=1

MJRoBot (Marcelo Rovai)

EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED 5m 0s TRAIN / TEST SPLIT 100% / 0% ▲

SAMPLE NAME	LABEL	ADDED	LENGTH
maritime.json.2jvi6...	maritime	Today, 14:57:35	10s
maritime.json.2jvi6...	maritime	Today, 14:57:13	10s
maritime.json.2jvi5...	maritime	Today, 14:56:48	10s
maritime.json.2jvi4...	maritime	Today, 14:56:31	10s
maritime.json.2jvi4...	maritime	Today, 14:56:13	10s
maritime.json.2jvi3...	maritime	Today, 14:55:55	10s
maritime.json.2jvi3...	maritime	Today, 14:55:36	10s
maritime.json.2jvi2...	maritime	Today, 14:55:19	10s
maritime.json.2jvi2...	maritime	Today, 14:55:00	10s
maritime.json.2jvi1...	maritime	Today, 14:54:42	10s
lift.json.2jhbt7	lift	Today, 14:42:04	10s
lift.json.2vh9pe3	lift	Today, 14:41:45	10s

Record new data

Device Nano

Label maritime

Sample length (ms.) 10000

Sensor Sensor with 3 axes (accX, accY, accZ)

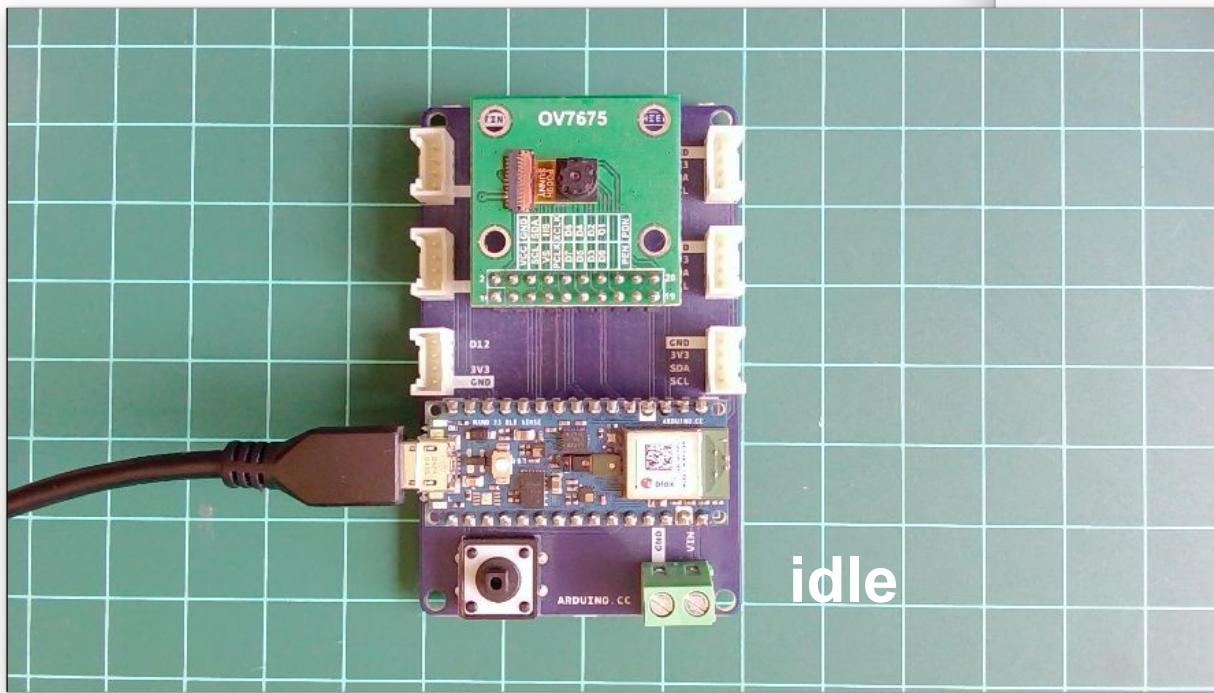
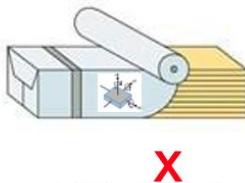
Frequency 100Hz

Start sampling

RAW DATA maritime.json.2jvi6p3r

accX accY accZ

Label: idle



Data acquisition - IESTI01 - Na +

studio.edgeimpulse.com/studio/61345/acquisition/training?page=1

MJRoBot (Marcelo Rovai)

EDGE IMPULSE

DATA ACQUISITION (IESTI01 - NANO MOTION CLASSIFICATION)

Training data Test data

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED 6m 40s TRAIN / TEST SPLIT 100% / 0% ▲

Record new data Connect using WebUSB

Device Nano

Label idle Sample length (ms.) 100000

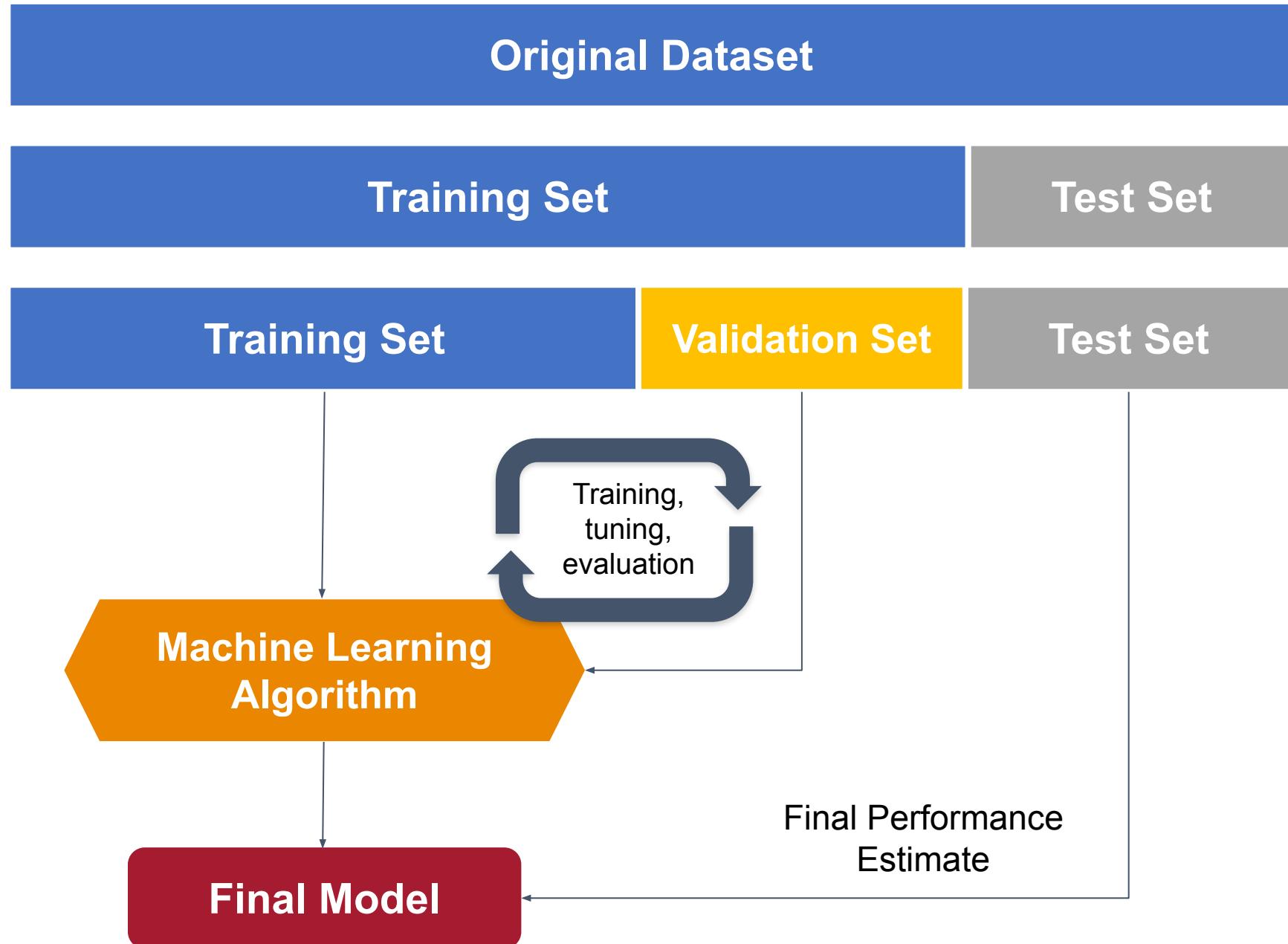
Sensor Sensor with 3 axes (accX, accY, accZ) Frequency 100Hz

Start sampling

RAW DATA idle.json.2jvif14

SAMPLE NAME	LABEL	ADDED	LENGTH
idle.json.2jvif14	idle	Today, 15:06:09	1m 40s
maritime.json.2jvi6...	maritime	Today, 14:57:35	10s
maritime.json.2jvi6...	maritime	Today, 14:57:13	10s
maritime.json.2jvi5...	maritime	Today, 14:56:48	10s
maritime.json.2jvi4...	maritime	Today, 14:56:31	10s
maritime.json.2jvi4...	maritime	Today, 14:56:13	10s
maritime.json.2jvi3...	maritime	Today, 14:55:55	10s
maritime.json.2jvi3...	maritime	Today, 14:55:36	10s
maritime.json.2jvi2...	maritime	Today, 14:55:19	10s
maritime.json.2jvi2...	maritime	Today, 14:55:00	10s
maritime.json.2jvi1...	maritime	Today, 14:54:42	10s
lift.json.2jhbt7	lift	Today, 14:42:04	10s

accX accY accZ



Dashboard - IESTI01 - Nano M

studio.edgeimpulse.com/studio/61345

EDGE IMPULSE

Dashboard

Devices

Data acquisition

Impulse design

- Create impulse

EON Tuner

Retrain model

Live classification

Model testing

Versioning

Deployment

GETTING STARTED

Documentation

Forums

Download block output

No downloads available yet

Performance settings

Use GPU for training

Parallel DSP jobs

Job limit in minutes

DSP file size limit (MB)

Administrative zone

Show Linux deploy options

Save experiments

Danger zone

Perform train / test split

Delete this project

Delete all data in this project

Project info

Project ID 61345

Labeling method One label per data

Latency calculations Cortex-M4F 80M

Dashboard - IESTI01 - Nano M

studio.edgeimpulse.com/studio/61345

EDGE IMPULSE

Download block output

No downloads available yet

Performance settings

Use GPU for training

Parallel DSP jobs

Job limit in minutes

DSP file size limit (MB)

Administrative zone

Show Linux deploy options

Save experiments

Danger zone

Performing split...

Delete this project

Delete all data in this project

?

Perform train / test split

Are you sure you want to rebalance your dataset? This splits all your data automatically between the training and testing set, and resets the categories for all data. This is irrevocable!

Cancel Yes, perform the train / test split

DATA ACQUISITION - TESTING (EINSTEIN CLASSIFICATION)

Training data **Test data**

Did you know? You can capture data from any device or development board, or upload your existing datasets - Show options

DATA COLLECTED 40s

TRAIN / TEST SPLIT 90% / 10%

Collected data

SAMPLE NAME	LABEL	ADDED	LENGTH
maritime.json.2jvi4...	maritime	Today, 14:56:13	10s
maritime.json.2jvi1...	maritime	Today, 14:54:42	10s
lift.json.2jvh6uqu	lift	Today, 14:40:12	10s
terrestrial.json.2jv...	terrestrial	Today, 13:01:46	10s

Device **Nano**

Label **idle**

Sample length (ms.) **100000**

Sensor **Sensor with 3 axes (accX, accY, accZ)**

Frequency **100Hz**

Start sampling

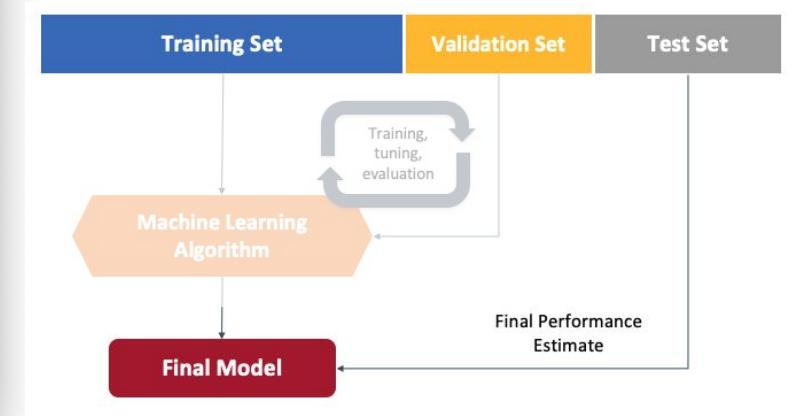
RAW DATA

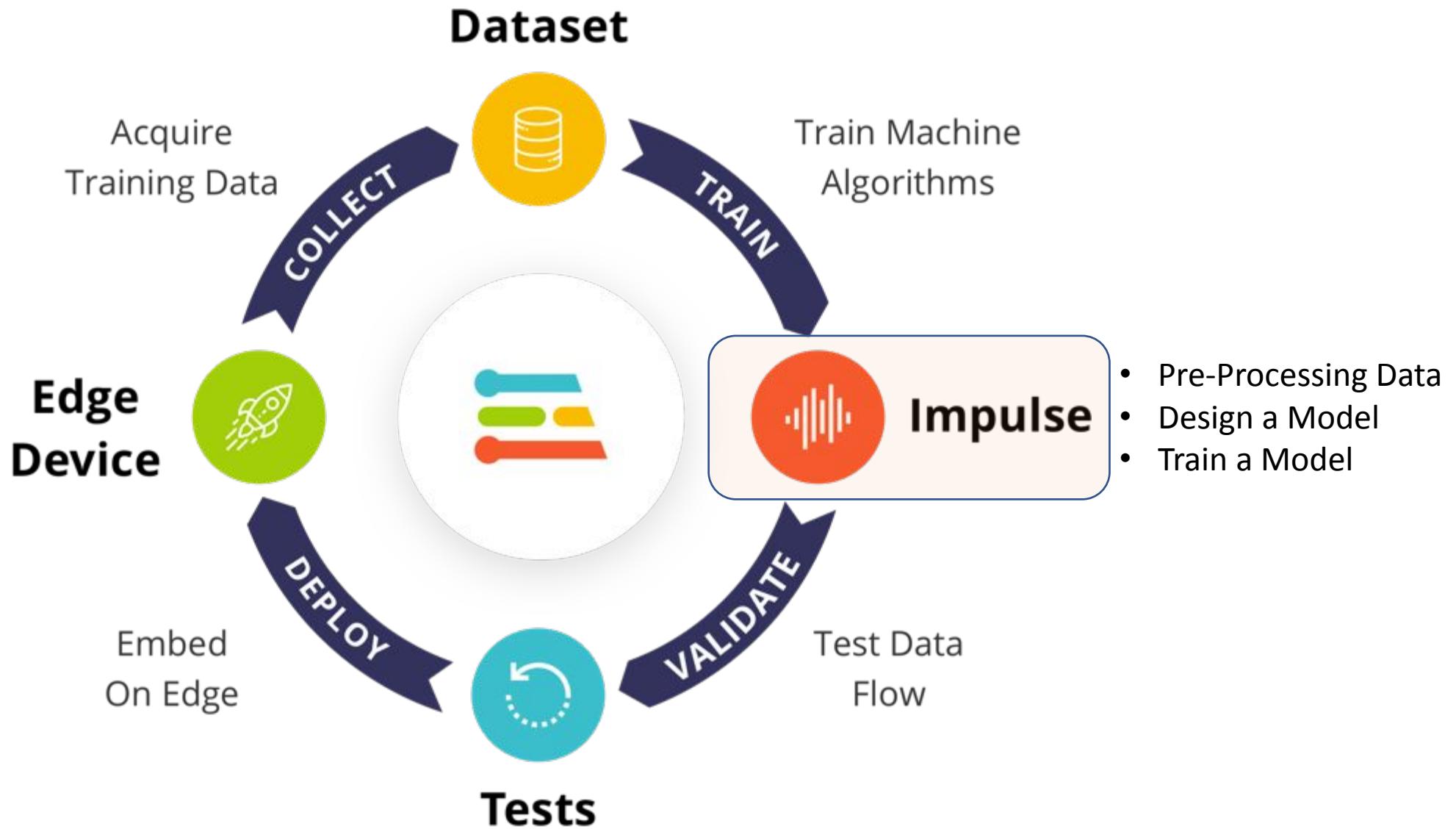
Click on a sample to load...

If automatic split is not good, proceed with manual split

The screenshot shows the Edge Impulse Studio interface. On the left, a sidebar menu includes options like Dashboard, Devices, Data acquisition (which is highlighted with an orange border), Create impulse, EON Tuner, Retrain model, Live classification, Model testing, Versioning, Deployment, Documentation, and Forums. The main area is titled "DATA ACQUISITION - TESTING (IE500 - ACTION CLASSIFICATION)". It displays "DATA COLLECTED 1m 20s" and a "TRAIN / TEST SPLIT 80% / 20%" button. Below this is a table titled "Collected data" with columns: SAMPLE NAME, LABEL, ADDED, LENGTH. The table lists several samples: "terrestrial.json.2jv...", "lift.json.2jhbt7", "idle.json.2jvjlon", "maritime.json.2ji4...", "maritime.json.2ji1...", "lift.json.2jh6uqu", and "terrestrial.json.2jv...". A large orange arrow points from the sidebar's "Data acquisition" option to the "Test data" tab in the top navigation bar.

Dataset is balanced (has representative samples from all classes) and split 80%/20%





Time series data

Axes
accX, accY, accZ

Window size
2000 ms.

Window increase
80 ms.

Frequency (Hz)
62.5

Zero-pad data

Spectral Analysis

Name
Spectral Analysis

Input axes
 accX
 accY
 accZ

Neural Network (Keras)

Name
Neural Network (Keras)

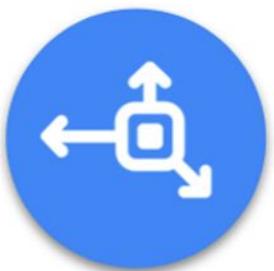
Input features
 Spectral Analysis

Output features
4 (idle, lift, maritime, terrestrial)

Output features

4 (idle, lift, maritime, terrestrial)

Save Impulse



Spectral Analysis



NN Classifier



Classes

- Lift
- Terrestrial
- Maritime
- Idle

Spectral features - IESTI01 - N

studio.edgeimpulse.com/studio/61345/dsp/spectral-analysis/3

Raw data

terrestrial.json.2jvgdqv9 (terrestrial)

accX accY accZ

Raw features

1.6400, -0.9700, 9.8000, 1.7100, -0.6400, 9.8100, 1.8500, -0.4200, 9.7900, 1.7800, -0.5200, 9.7500, 1.7100,...

Parameters

Scaling

Scale axes

Filter

Type Cut-off frequency Order

Spectral power

FFT length No. of peaks Peaks threshold Power edges

Save parameters

DSP result

After filter

Frequency domain

Spectral power

Processed features

1.9614, 0.7937, 2.6663, 0.0000, 0.0000, 0.0000, 0.0000, 0.4550, 0.0489, 0.0025, 0.2078, 2.3810, 0.1...

On-device performance

PROCESSING TIME 9 ms. PEAK RAM USAGE 5 KB

Spectral features - IESTI01 - N

studio.edgeimpulse.com/studio/61345/dsp/spectral-analysis/3/generate-features

EDGE IMPULSE

SPECTRAL FEATURES (IESTI01 - NANO MOTION CLASSIFICATION)

#1 ▾ Click to set a description for this version

Parameters **Generate features**

Training set

Data in training set 5m 20s

Classes 4 (idle, lift, maritime, terrestrial)

Window length 2000 ms.

Window increase 80 ms.

Training windows 3,400

Feature explorer (3,400 samples)

X Axis accX RMS Y Axis accY RMS Z Axis accZ RMS

idle (blue), lift (orange), maritime (green), terrestrial (red)

Feature generation output

Job started
Creating windows from 25 files...
[0/25] Creating windows from files...
[1/25] Creating windows from files...
[25/25] Creating windows from files...
Created 3400 windows: idle: 976, lift: 808, maritime: 808, terrestrial: 808

Creating features
[1/3400] Creating features...
[898/3400] Creating features...
[1798/3400] Creating features...
[2704/3400] Creating features...
[3400/3400] Creating features...
Created features

Job completed

On-device performance

PROCESSING TIME 9 ms. PEAK RAM USAGE 5 KB

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MJRoBot (Marcelo Rovai)

Neural Network settings

Training settings

Number of training cycles ?
30

Learning rate ?
0.0005

Neural network architecture

- Input layer (33 features)**
- Dense layer (20 neurons)
- Dense layer (10 neurons)
- Add an extra layer
- Output layer (4 classes)**

Start training

Model

Model version: ? Quantized (int8)

Last training performance (validation set)

%	ACCURACY 99.9%	graph	LOSS 0.01
--	---------------------------------	--	----------------------------

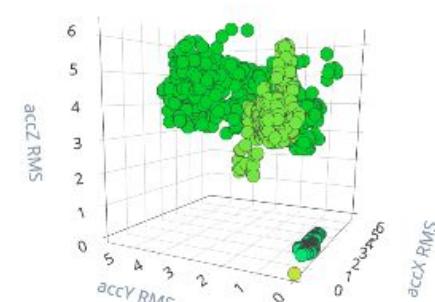
Confusion matrix (validation set)

	IDLE	LIFT	MARITIME	TERRESTRIAL
IDLE	100%	0%	0%	0%
LIFT	0%	99.4%	0.6%	0%
MARITIME	0%	0%	100%	0%
TERRESTRIAL	0%	0%	0%	100%
F1 SCORE	1.00	1.00	1.00	1.00

Feature explorer (full training set) ?

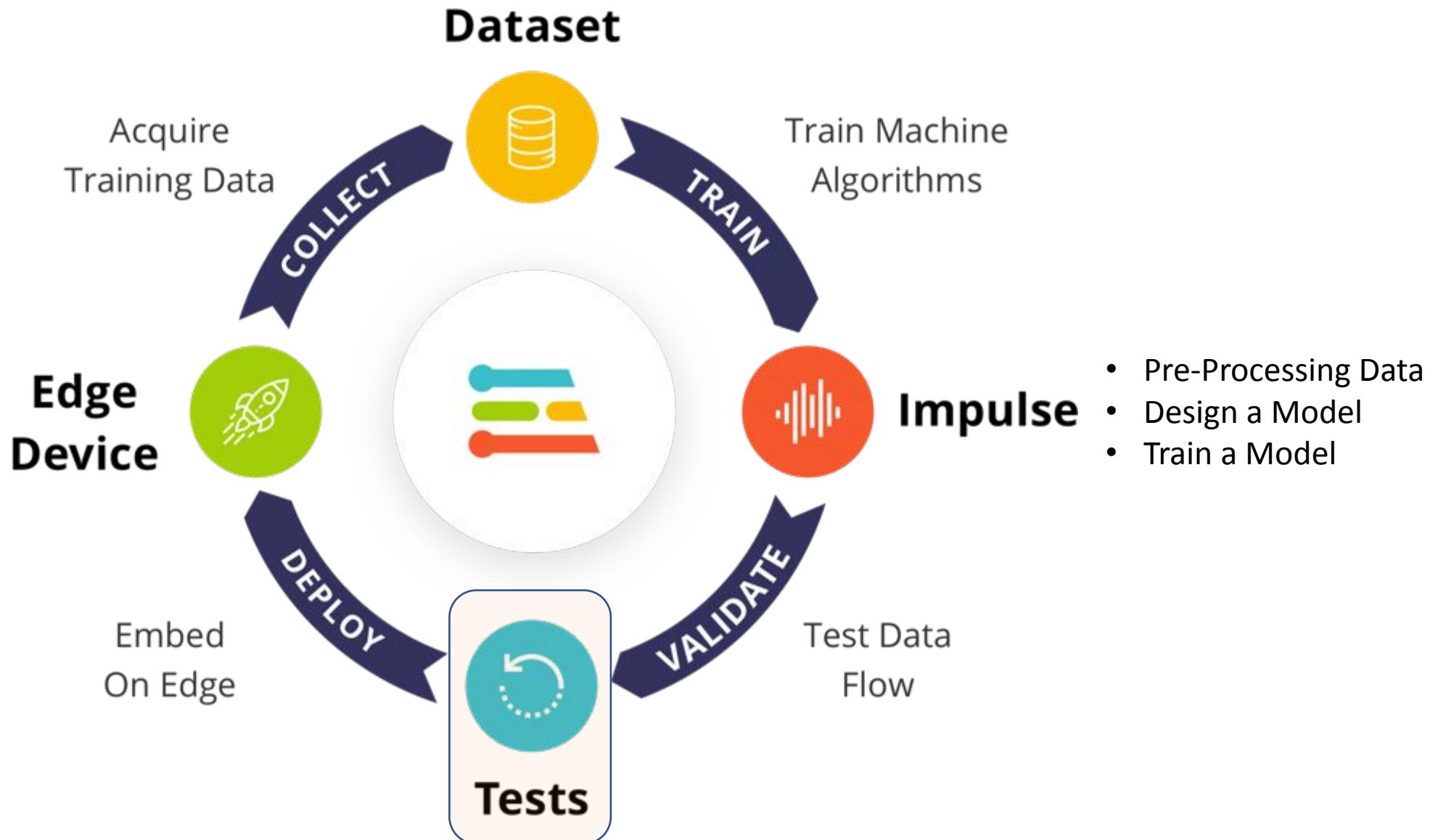
accX RMS ▼ accY RMS ▼ accZ RMS ▼

● idle - correct
● lift - correct
● maritime - correct
● terrestrial - correct
● lift - incorrect



On-device performance ?

⌚	RAM	FLASH
Inferencing time 1 ms.	Peak RAM usage 1.7K	Flash usage 19.0K



Model testing - IESTI01 - Nano

studio.edgeimpulse.com/studio/61345/validation

Test data

Set the 'expected outcome' for each sample to the desired outcome to automatically score the impulse.

SAMPLE NAME	EXPECTED OUTCOME	LENGTH	ACCURACY	RESULT	⋮
terrestrial.json.2...	terrestrial	10s	100%	101 terrestrial	⋮
lift.json.2jhbt7	lift	10s	100%	101 lift	⋮
idle.json.2jvjlvn	idle	20s	100%	226 idle	⋮
maritime.json.2j...	maritime	10s	100%	101 maritime	⋮
maritime.json.2j...	maritime	10s	100%	101 maritime	⋮
lift.json.2jh6uqu	lift	10s	100%	101 lift	⋮
terrestrial.json.2...	terrestrial	10s	100%	101 terrestrial	⋮

Model testing output

Classifying data for NN Classifier...
 Copying features from processing blocks...
 Copying features from DSP block...
 Copying features from DSP block OK
 Copying features from processing blocks OK

Classifying data for float32 model...
 Scheduling job in cluster...
 Job started
 Classifying data for NN Classifier OK

Job completed

Model testing results

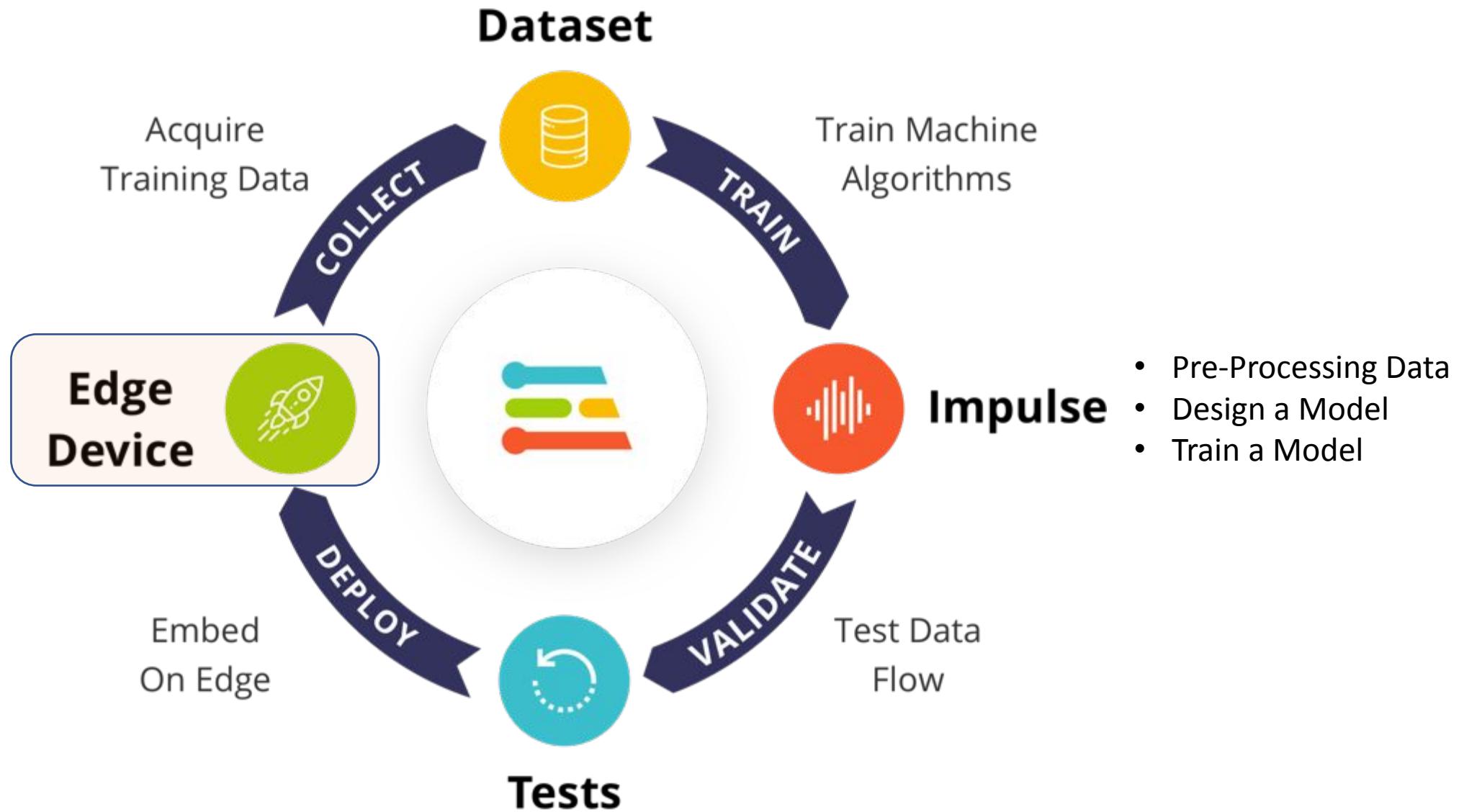
ACCURACY
100.00%

	IDLE	LIFT	MARITIME	TERRESTRIAL	UNCERTAIN
IDLE	100%	0%	0%	0%	0%
LIFT	0%	100%	0%	0%	0%
MARITIME	0%	0%	100%	0%	0%
TERRESTRIAL	0%	0%	0%	100%	0%
F1 SCORE	1.00	1.00	1.00	1.00	

Feature explorer

accX RMS accY RMS accZ RMS

- idle - correct
- lift - correct
- maritime - correct
- terrestrial - correct



Deployment - IESTI01 - Nano Motion Classification

studio.edgeimpulse.com/studio/61345/deployment

EDGE IMPULSE

DEPLOYMENT (IESTI01 - NANO MOTION CLASSIFICATION)

MJRoBot (Marcelo Rovai)

Deploy your impulse

You can deploy your impulse to any device. This makes the model run without an internet connection, minimizes latency, and runs with minimal power consumption. [Read more.](#)

Create library

Turn your impulse into optimized source code that you can run on any device.

C++ library Arduino library Cube.MX CMSIS-PACK

WebAssembly TensorRT library

Build firmware

Or get a ready-to-go binary for your development board that includes your impulse.

ST IoT Discovery Kit Arduino Nano 33 BLE Sense Eta Compute ECM3532 AI Sensor

SiLabs Thunderboard Sense 2 Himax WE-I Plus Nordic nRF52840 DK + IKS02A1

Nordic nRF5340 DK + IKS02A1 Nordic nRF9160 DK + IKS02A1 Nordic Thingy:91

ei-iesti01---nano....zip

Show All

Build output

```
Creating job... OK (ID: 1646786)
Writing templates...
Writing templates OK
Copying Edge Impulse SDK...
Copying Edge Impulse SDK OK
Compiling EON model...
Compiling EON model OK
Removing clutter and updating headers...
Removing clutter and updating headers OK
Creating archive...
Job started
Creating archive OK
Job completed
```

Deployment - IESTI01 - Nano Motion Classification

studio.edgeimpulse.com/studio/61345/deployment

EDGE IMPULSE

- Dashboard
- Devices
- Data acquisition
- Impulse design
 - Create impulse
 - Spectral features
 - NN Classifier
- EON Tuner
- Retrain model
- Live classification
- Model testing
- Versioning
- Deployment

GETTING STARTED

- Documentation
- Forums

SiLabs Thunderboard Sense 2

Himax WE-I Plus

Nordic nRF52840 DK + IKS02A1

Nordic nRF5340 DK + IKS02A1

Nordic nRF9160 DK + IKS02A1

Nordic Thingy:91

Sony's SpreSense

Select optimizations (optional)

Model optimizations can increase on-device performance. Choose from recommended choices for your target. Click [View all optimizations](#) to see more.

Enable EON™ Compiler

Same accuracy, up to 50% less RAM usage.

Available optimizations for NN Classifier

Optimization	RAM Usage	Latency	Confusion Matrix																				
Quantized (int8) ★	1.1K	1 ms	<table border="1"><tr><td>100</td><td>0</td><td>0</td><td>0</td><td>0</td></tr><tr><td>0</td><td>100</td><td>0</td><td>0</td><td>0</td></tr><tr><td>0</td><td>0</td><td>100</td><td>0</td><td>0</td></tr><tr><td>0</td><td>0</td><td>0</td><td>100</td><td>0</td></tr></table>	100	0	0	0	0	0	100	0	0	0	0	0	100	0	0	0	0	0	100	0
100	0	0	0	0																			
0	100	0	0	0																			
0	0	100	0	0																			
0	0	0	100	0																			
Unoptimized (float32)	19.0K	100%	<table border="1"><tr><td>100</td><td>0</td><td>0</td><td>0</td><td>0</td></tr><tr><td>0</td><td>100</td><td>0</td><td>0</td><td>0</td></tr><tr><td>0</td><td>0</td><td>100</td><td>0</td><td>0</td></tr><tr><td>0</td><td>0</td><td>0</td><td>100</td><td>0</td></tr></table>	100	0	0	0	0	0	100	0	0	0	0	0	100	0	0	0	0	0	100	0
100	0	0	0	0																			
0	100	0	0	0																			
0	0	100	0	0																			
0	0	0	100	0																			

Currently selected

This optimization is recommended for best performance.

Click to select

Estimate for Cortex-M4F 80MHz

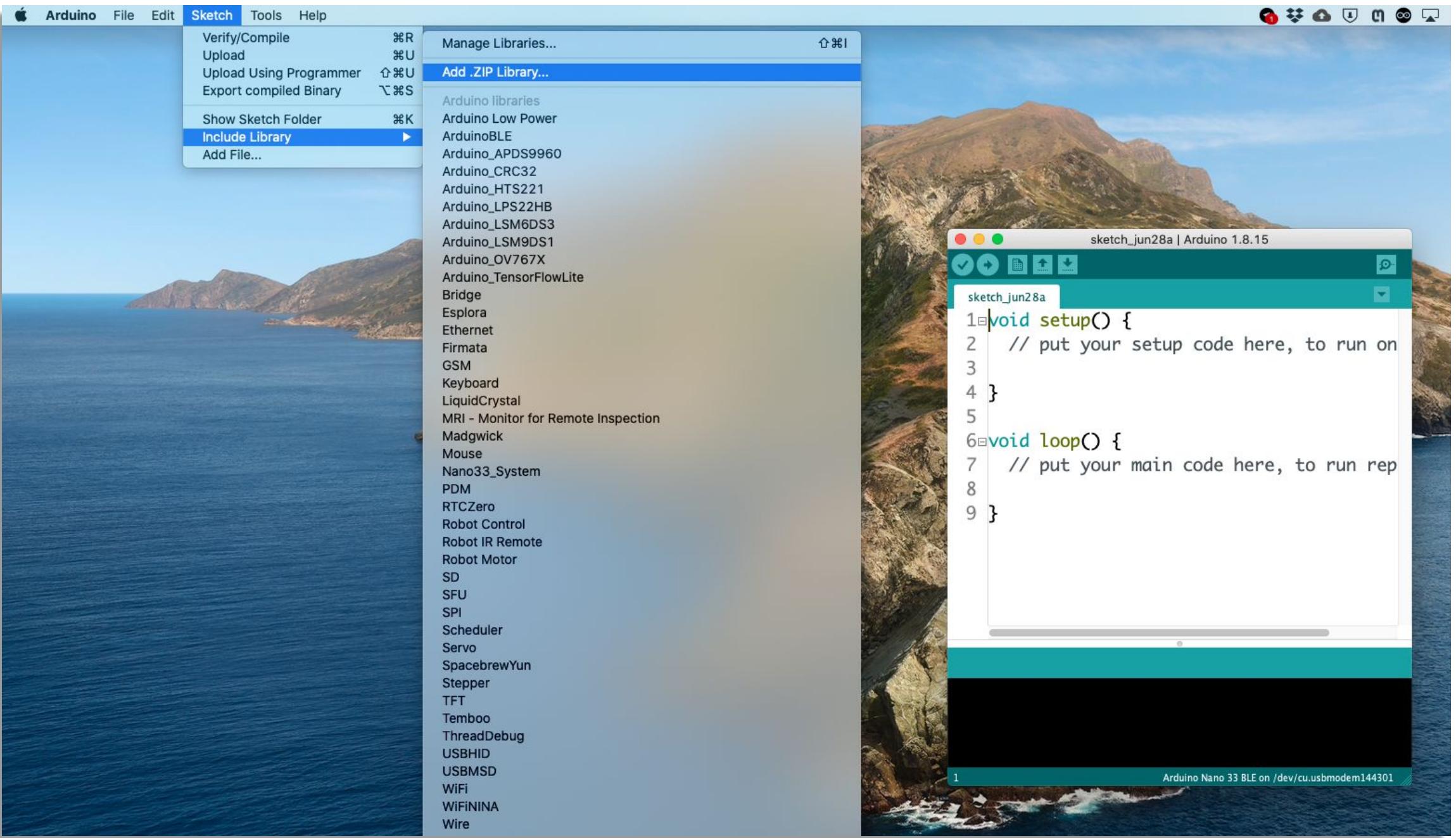
Build

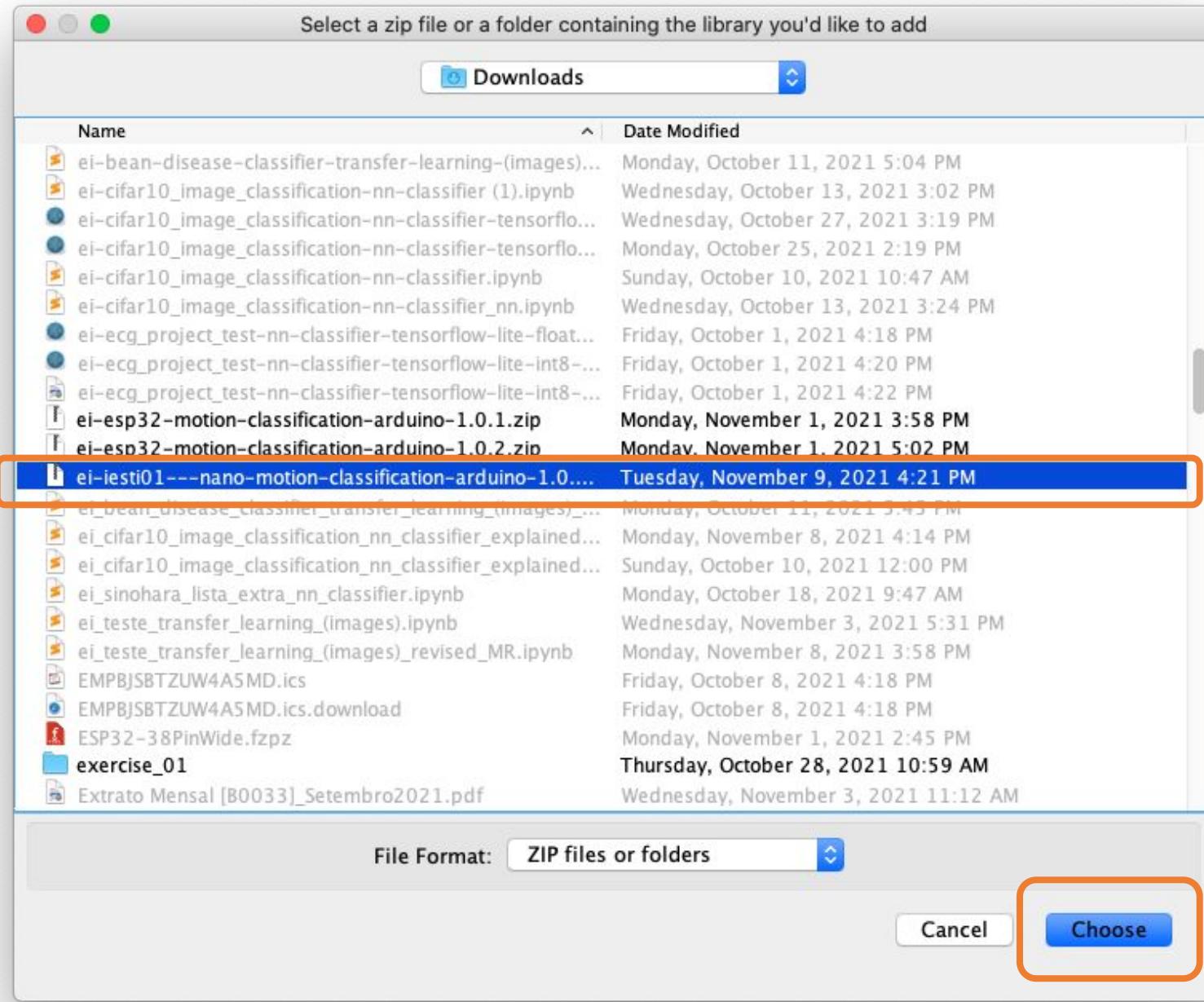
Build output

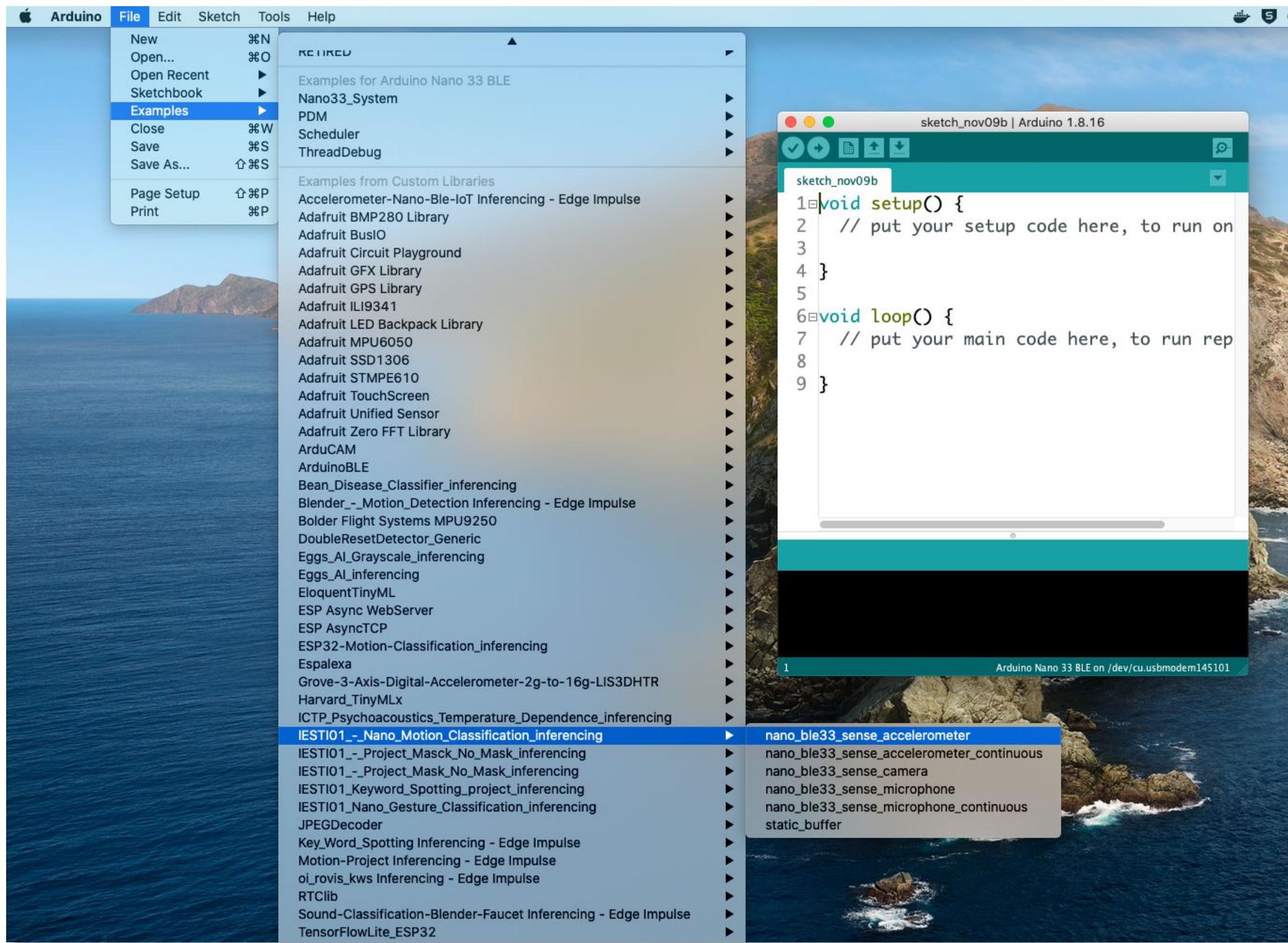
```
Creating job... OK (ID: 1646786)
Writing templates...
Writing templates OK
Copying Edge Impulse SDK...
Copying Edge Impulse SDK OK
Compiling EON model...
Compiling EON model OK
Removing clutter and updating headers...
Removing clutter and updating headers OK
Creating archive...
Archive OK
```

ei-iesti01---nano....zip

Show All







Model Inference

/dev/cu.usbmodem145101

Sampling...

Predictions (DSP: 20 ms., Classification: 0 ms., Anomaly: 0 ms.):

```
idle: 0.00000
lift: 0.00000
maritime: 0.00000
terrestrial: 0.99609
```

Starting inferencing in 2 seconds...

Sampling...

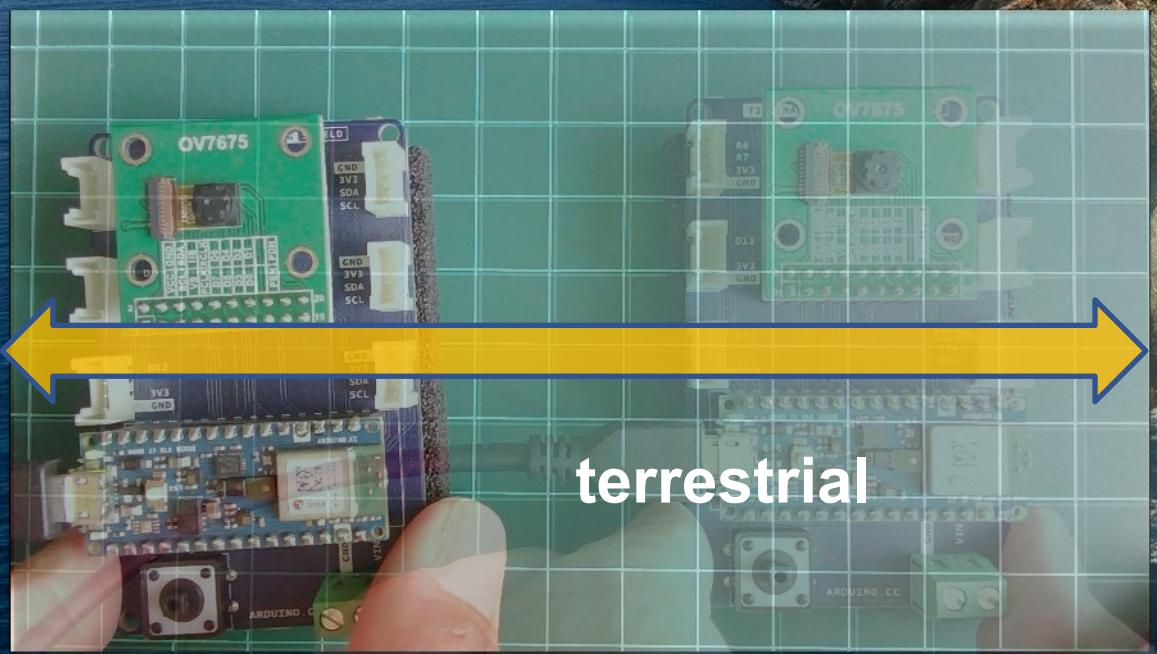
Predictions (DSP: 20 ms., Classification: 1 ms., Anomaly: 0 ms.):

```
idle: 0.00000
lift: 0.00000
maritime: 0.00000
terrestrial: 0.99609
```

Starting inferencing in 2 seconds...

Autoscroll Show timestamp

Both NL & CR 115200 baud Clear output



nano_ble33_sense_accelerometer | Arduino 1.8.16

nano_ble33_sense_accelerometer

```
1/* Edge Impulse Arduino examples
2 * Copyright (c) 2021 EdgeImpulse Inc.
3 *
4 * Permission is hereby granted, free of charge, to any person obtaining a copy
5 * of this software and associated documentation files (the "Software"), to
6 * in the Software without restriction, including without limitation the right
7 * to use, copy, modify, merge, publish, distribute, sublicense, and/or sell
8 * copies of the Software, and to permit persons to whom the Software is
9 * furnished to do so, subject to the following conditions:
10 *
11 * The above copyright notice and this permission notice shall be included in
12 * all copies or substantial portions of the Software.
13 *
14 * THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR
15 * IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
16 * FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE
17 * AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
18 * LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM
19 * OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN
20 * SOFTWARE.
21 */
22
23/* Includes -----
24#include <IESTI01_-_Nano_Motion_Classification_inferencing.h>
25#include <Arduino_LSM9DS1.h>
26
27/* Constant defines -----
28#define CONVERT_G_TO_MS2 9.80665f
29
30/* Private variables -----
31static bool debug_nn = false; // Set this to true to see e.g. features generated by the neural network.
```

Done in 6.027 seconds

reset()

15

Arduino Nano 33 BLE on /dev/cu.usbmodem145101

```
/dev/cu.usbmodem145101  
Send  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 27 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,  
Predictions (DSP: 29 ms., Classification: 0 ms., Anomaly: 0 ms.): terrestrial [ 0, 0, 0, 10, 0, 0,
```



```
nano_ble33_sense_accelerometer_continuous | Arduino 1.8.16  
nano_ble33_sense_accelerometer_continuous  
22  
23 /* Includes -----  
24 #include <IESTI01_-_Nano_Motion_Classification_inferencing.h>  
25 #include <Arduino_LSM9DS1.h>  
26  
27 /* Constant defines -----  
28 #define CONVERT_G_TO_MS2 9.80665f  
29  
30 /* Private variables -----  
31 static bool debug_nn = false; // Set this to true to see e.g. features  
32 static uint32_t run_inference_every_ms = 200;  
33 static rtos::Thread inference_thread(osPriorityLow);  
34 static float buffer[EI_CLASSIFIER_DSP_INPUT_FRAME_SIZE] = { 0 };  
35 static float inference_buffer[EI_CLASSIFIER_DSP_INPUT_FRAME_SIZE];  
36  
37 /* Forward declaration */  
38 void run_inference_background();  
39  
40 /**  
41 * @brief Arduino setup function  
42 */  
43 void setup()  
44{  
    // put your setup code here, to run once:  
    Serial.begin(115200);  
    Serial.println("Edge Impulse Inferencing Demo");  
      
    if (!IMU.begin()) {  
        ei_printf("Failed to initialize IMU!\r\n");  
    }  
    else {  
        ei_printf("IMU initialized\r\n");  
    }  
}  
  
Done uploading.  
Done in 6.034 seconds  
reset()
```

TinyML motion classification uses
on **Real Life**

Cow Monitoring

Using the Internet of Things for Agricultural Monitoring

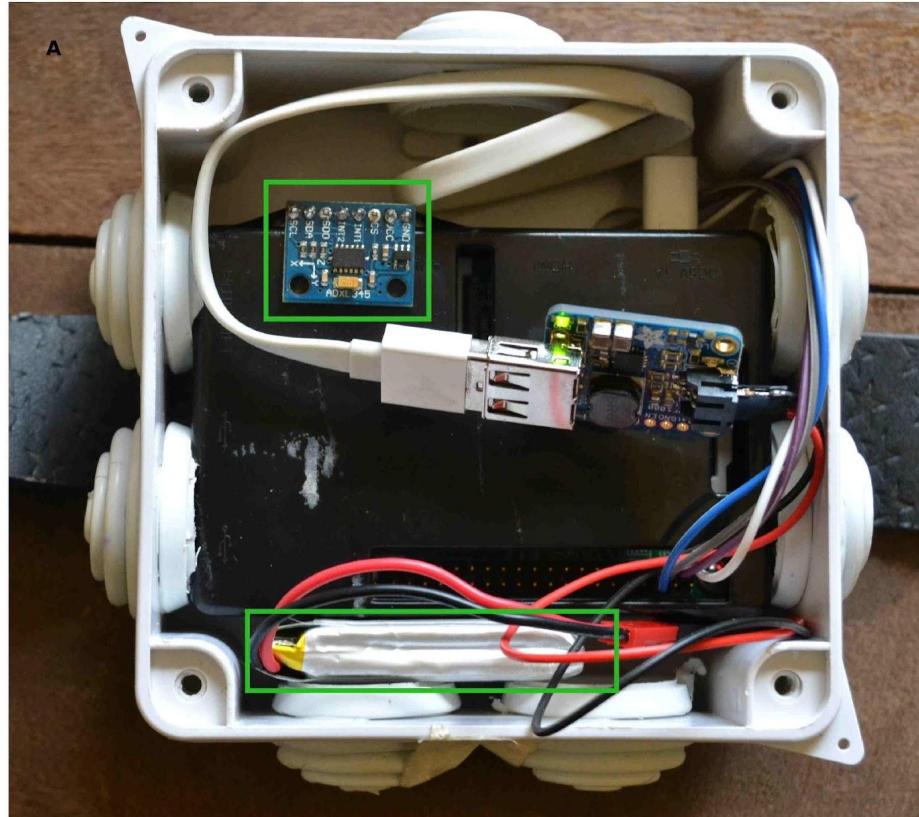
"We aim to deploy a variety of sensors for agricultural monitoring. One of the projects involves using **accelerometer sensors** to monitor activity levels in dairy cows with a view to determining when the cows are on heat or when they are sick."



Ciira wa Maina, Ph.D.

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Department of Electrical and Electronic Engineering
Dedan Kimathi University of Technology
Nyeri Kenya
Email: ciira.maina@dkut.ac.ke

Kenia



<https://sites.google.com/site/cwamainadekut/research>



Predict and classify common Elephant behavior



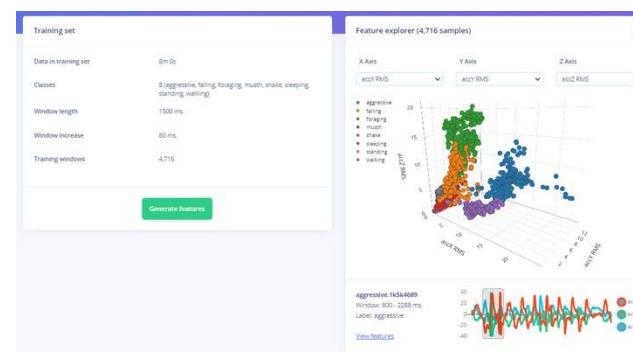
Aggressive



Standing



Sleeping



https://www.hackster.io/dhruvsheth_elect-tinyml-and-iot-based-smart-wildlife-tracker-c03e5a#toc-accelerometer-data-models-4

Thanks

