

Basics of Probability

Logic-based Systems: Assumptions

- ▶ Assertions are **completely accurate**
- ▶ Observations are **complete** and **error-free**
- ▶ Conclusions are **equally viable**
- ▶ Inference rules are **truth-preserving**

Each of these may be unrealistic when modelling complex systems

Logic-Based Systems: Assumptions I

- ▶ Assertions are **completely accurate**
 - ▶ Initial intuition: inaccuracy can be eliminated by increasing specificity

if car won't start **then** battery flat



if car won't start **and** lights OK **and** starter motor OK **and** ...

- ▶ Untenable for really complex systems (**Qualification** problem)
- ▶ Observations are **complete** and **error-free**

Logic-Based Systems: Assumptions II

- ▶ Random and systematic errors are common
- ▶ Some tests are impossible, too costly, or too dangerous
- ▶ Conclusions are **equally viable**
 - ▶ Alternative ligands may be indicated as binding well to a target protein
 - ▶ But, both may not be equally viable as new drugs (toxicity, ease of manufacture, ...)

Logic-Based Systems: Assumptions III

- ▶ Inference rules are **truth-preserving**
 - ▶ No role for uncertainty
 - ▶ Even if inference rules are sound, any errors (however small) in the assertions or observations can compound with chaining

Solution: Explicit Methods for Handling Uncertainty

- ▶ **Joint probability distributions**
- ▶ 'Certainty factors' attached to rules
- ▶ Dempster-Shafer Theory
- ▶ Non-monotonic reasoning
- ▶ Possibility Theory
- ▶ **Bayesian Networks**

Simple logic-based systems: Terminology

- ▶ **Variables** (features): usually boolean, discrete or continuous
- ▶ **Atomic Proposition**: assignment of a value to a variable

Cavity = true Weather = sunny X = 5.1

- ▶ **Compound Proposition**: atomic propositions combined with standard logical connectives \neg, \wedge, \vee
- ▶ **State** (interpretation): assignment of values to all variables
 - Mutually exclusive (at most one is actually the case)
 - Collectively exhaustive (at least one must be the case)

To Add Probability

- ▶ Variables → **Random Variables** (intuitively, a variable that takes one of several values, depending on some observed outcome)
- ▶ Probabilities are applied to propositions

$$P(\textit{Weather} = \textit{sunny}) = 0.70$$

- ▶ State: assignment of values to all the random variables (sometimes called an **atomic event**)

Probabilities I

- Toss a coin

$$P(H) = \frac{1}{2} \quad P(T) =$$

$$P(H) = \frac{1}{4} \quad P(T) =$$

- Toss a coin several times

$$P(H) = \frac{1}{2} \quad P(HHH) =$$

$$P(H) = \frac{1}{2} \quad P(\text{identical result 4 tosses}) =$$

$$P(H) = \frac{1}{2} \quad P(\text{at least 3 H on 4}) =$$

Axioms of Probability

- ▶ $0 \leq P(a) \leq 1$
- ▶ $P(\text{true}) = 1$
- ▶ The sum of probabilities = 1. So, $P(A) + P(\neg A) = 1$

Unconditional and **prior probability** of a proposition is the degree of belief accorded to it
in the absence of any other information

$P(\text{Cavity} = \text{true})$ or simply $P(\text{cavity})$

$P((\text{Cavity} = \text{false}) \wedge (\text{Weather} = \text{sunny}))$ or simply

$P(\neg \text{cavity}, (\text{Weather} = \text{sunny}))$

Probability Distribution

- ▶ For a discrete random variable a probability distribution tells us how the probability is distributed over the set of events for which the random variable takes a particular value:

$$P(\textit{Weather} = \textit{sunny}) = 0.70$$

$$P(\textit{Weather} = \textit{rain}) = 0.20$$

$$P(\textit{Weather} = \textit{cloudy}) = 0.08$$

$$P(\textit{Weather} = \textit{snow}) = 0.02$$

- ▶ For the continuous case, a probability density function (p.d.f.) often can be used. We will not be looking at this case.

Joint Probability Distribution

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	0.108	0.012	0.072	0.008
\neg <i>cavity</i>	0.016	0.064	0.144	0.576

where

toothache: I have a toothache

cavity: I have a cavity

catch: the dentist's probe catches in my tooth

Conditional (Posterior) Probability

$P(a|b)$: the probability of a given that all we know is b

$$P(a|b) = \frac{P(a \wedge b)}{P(b)}$$

Example

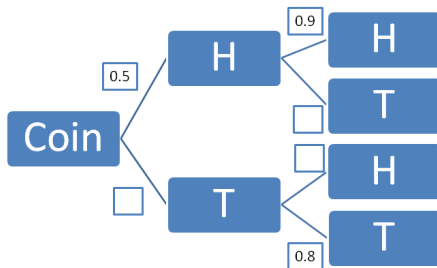
$$\begin{aligned}P(\textit{cavity}|\textit{toothache}) &= \frac{P(\textit{cavity} \wedge \textit{toothache})}{P(\textit{toothache})} \\&= \frac{0.108 + 0.012}{0.108 + 0.012 + 0.016 + 0.064} \\&= 0.60\end{aligned}$$

$$\begin{aligned}P(\neg\textit{cavity}|\textit{toothache}) &= \frac{P(\neg\textit{cavity} \wedge \textit{toothache})}{P(\textit{toothache})} \\&= 0.40\end{aligned}$$

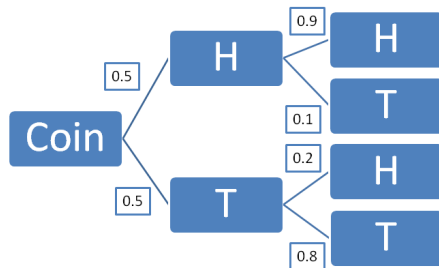
Probability Trees

In general, many (all?) probability questions are solvable by drawing out probability trees

Conditional Probabilities: Coins

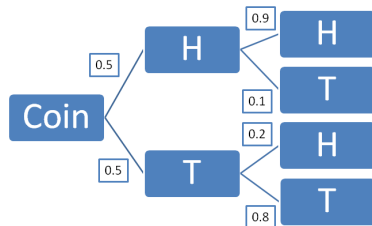


Conditional Probabilities: Coins



$$P(X_2 = H) = 0.9 \times 0.5 + 0.5 \times 0.2 = 0.55$$

Conditional Probabilities: Coins I



$$\begin{aligned} P(X_2 = H) &= P(X_2 = H|X_1 = H)P(X_1 = H) \\ &+ P(X_2 = H|X_1 = T)P(X_1 = T) \end{aligned}$$

Conditional Probabilities: Coins II

In general:

$$P(Y) = \sum_i P(Y|X = X_i)P(X = X_i)$$

Conditional Probabilities: Weather

$$P(D_1 = \textit{sunny}) = \text{Prob. Day1 is sunny} = 0.9$$

$$P(D_2 = \textit{sunny} | D_1 = \textit{sunny}) = 0.8. \text{ Then:}$$

$$P(D_2 = \textit{rainy} | D_1 = \textit{sunny}) = \dots$$

Dependent Events

$$P(D_1 = \textit{sunny}) = \text{Prob. Day1 is sunny} = 0.9$$

$$P(D_2 = \textit{sunny} | D_1 = \textit{sunny}) = 0.8. \text{ Then:}$$

$$P(D_2 = \textit{rainy} | D_1 = \textit{sunny}) = 0.2$$

Conditional Probabilities: Weather

$P(D_1 = \textit{sunny}) = \text{Prob. Day1 is sunny} = 0.9$

$P(D_2 = \textit{sunny} | D_1 = \textit{sunny}) = 0.8$. Then:

$P(D_2 = \textit{rainy} | D_1 = \textit{sunny}) = 0.2$

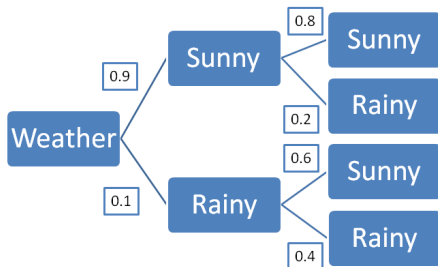
Now, if:

$P(D_2 = \textit{sunny} | D_1 = \textit{rainy}) = 0.6$. Then:

$P(D_2 = \textit{rainy} | D_1 = \textit{rainy}) = 0.4$

Now, what is $P(D_2 = \textit{sunny})$?

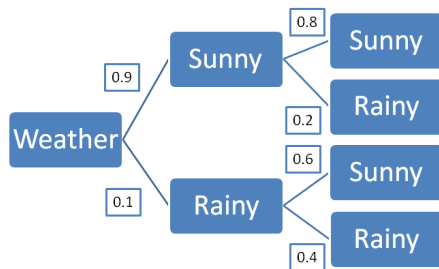
Conditional Probabilities: Weather I



$$P(D_2 = \text{sunny}) = 0.9 \times 0.8 + 0.1 \times 0.6 = 0.78$$

Now, what is $P(D_3 = \text{sunny})$?

Conditional Probabilities: Weather I

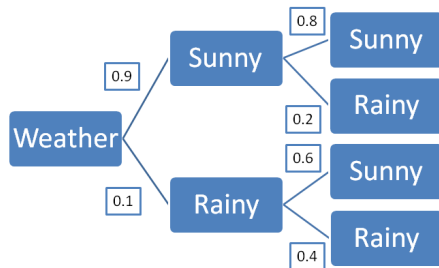


$$P(D_2 = \text{sunny}) = 0.9 \times 0.8 + 0.1 \times 0.6 = 0.78$$

Conditional Probabilities: Weather II

$$\begin{aligned}P(D_3 = \textit{sunny}) &= P(D_3 = \textit{sunny} | D_2 = \textit{sunny})P(D_2 = \textit{sunny}) \\&+ P(D_3 = \textit{sunny} | D_2 = \textit{rainy})P(D_2 = \textit{rainy}) \\&= 0.8 \times 0.78 + 0.6 \times 0.22 \\&= 0.756\end{aligned}$$

Conditional Probabilities: Weather I

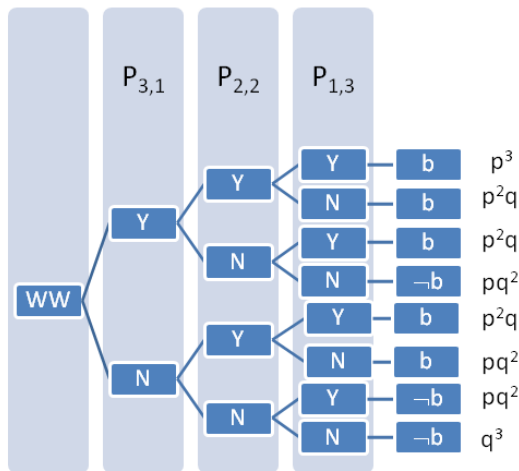


$$P(D_2 = \textit{sunny}) = 0.9 \times 0.8 + 0.1 \times 0.6 = 0.78$$

Conditional Probabilities: Weather II

$$\begin{aligned}P(D_3 = \textit{sunny}) &= P(D_3 = \textit{sunny} | D_2 = \textit{sunny})P(D_2 = \textit{sunny}) \\&+ P(D_3 = \textit{sunny} | D_2 = \textit{rainy})P(D_2 = \textit{rainy}) \\&= 0.8 \times 0.78 + 0.6 \times 0.22 \\&= 0.756\end{aligned}$$

Conditional Probabilities: Wumpus I



$$P(P_{1,3} = y|b) = \frac{P(P_{1,3} = y, b)}{P(b)} = \frac{p^3 + 2p^2q}{p^3 + 3p^2q + pq^2}$$

Conditional Probabilities: Wumpus II

That is:

$$P(P_{1,3} = y|b) = \frac{p^2 + 2pq}{p^2 + 3pq + q^2}$$

If $p = 0.2$, then $q = 0.8$ and:

$$P(P_{1,3} = y|b) = \frac{0.04 + 2(0.2)(0.8)}{(0.04) + 3(0.2)(0.8) + (0.8)(0.8)} = \frac{0.36}{0.04 + 0.48 + 0.64}$$

Conditional Probabilities: Cancer

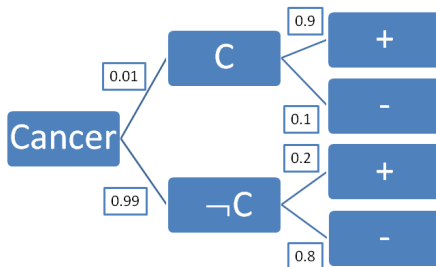
$P(C) = 0.01$. Then $P(\neg C) = 0.99$

Suppose there is a test for this, and $P(+|C) = 0.9$. Again,
 $P(-|C) = 0.1$.

Also, let $P(+|\neg C) = 0.2$. Then $P(-|\neg C) = 0.8$

Now, what can we say about $P(C|+)$

Conditional Probabilities: Cancer I



By definition of conditional probability:

$$P(C, +) = P(C|+) \times P(+).$$

Conditional Probabilities: Cancer II

So, we want:

$$P(C|+) = \frac{P(C,+)}{P(+)}$$

Now $P(C,+) = 0.01 \times 0.9$, and $P(+) = (0.01 \times 0.9 + 0.99 \times 0.2)$.

So $P(C|+) = 0.009/0.207 = 0.043$.

We have just done the calculations for a formula known as Bayes' Rule

Since $P(C,+) = P(+,C)$, we have:

$P(C,+) = P(+,C) = P(+|C) \times P(C)$. So, we have:

$P(C|+) \times P(+) = P(+|C) \times P(C)$. Or:

$$P(C|+) = \frac{P(+|C) \times P(C)}{P(+)}$$

This is Bayes' formula or Bayes' Rule.

Product Rule

Equivalent to the previous equation is the following, known as the **product rule**

$$P(a \wedge b) = P(a|b)P(b)$$

$$P(b \wedge a) = P(b|a)P(a)$$

Note on Boldface Notation

- ▶ X denotes a random variable but \mathbf{X} denotes a set of random variables
- ▶ $P(X = x)$ denotes the probability that random variable X takes the value x , but $\mathbf{P}(X)$ denotes a probability distribution over X
 - ▶ $\mathbf{P}(\textit{Weather}) = \langle 0.70, 0.20, 0.08, 0.02 \rangle$
 - ▶ $\mathbf{P}(X, Y) = \mathbf{P}(X|Y)\mathbf{P}(Y)$ stands for a set of equations (not matrix multiplication)

$$P(X = x_1 \wedge Y = y_1) = P(X = x_1|Y = y_1)P(Y = y_1)$$

$$P(X = x_1 \wedge Y = y_2) = P(X = x_1|Y = y_2)P(Y = y_2)$$

...

Marginalisation and Conditioning

- ▶ Marginalisation or **summing out** for any sets of variables \mathbf{Y}, \mathbf{Z}

$$\mathbf{P}(\mathbf{Y}) = \sum_{\mathbf{Z} \in \mathbf{Z}} \mathbf{P}(\mathbf{Y}, \mathbf{Z})$$

This follows from the Law of Total Probability.

- ▶ Conditioning (variant of marginalisation, using the product rule)

$$\mathbf{P}(\mathbf{Y}) = \sum_{\mathbf{Z} \in \mathbf{Z}} \mathbf{P}(\mathbf{Y}|\mathbf{Z})P(\mathbf{Z})$$

Some Important Relations

Total Probability:

$$P(Y) = \sum_x P(Y, X = x) = \sum_x P(Y|X = x)P(X = x)$$

Conditional form of this:

$$P(Y|e) = \sum_x P(Y, X = x|e) = \sum_x P(Y|X = x, e)P(X = x|e)$$

Also:

$$P(\neg A|B) = 1 - P(A|B)$$

But:

$$P(A|\neg B) \neq 1 - P(A|B)$$

$$P(\textit{cavity}|\textit{toothache}) = \frac{P(\textit{cavity} \wedge \textit{toothache})}{P(\textit{toothache})}$$

$$P(\neg\textit{cavity}|\textit{toothache}) = \frac{P(\neg\textit{cavity} \wedge \textit{toothache})}{P(\textit{toothache})}$$

- ▶ The denominator in both cases is the same
- ▶ It can be viewed as a normalisation constant α

$$\mathbf{P(X|Y)} = \alpha \mathbf{P(X, Y)}$$

General Inference Procedure

Let X be a random variable. We want to know its probabilities, given some values \mathbf{e} for observable evidence variables \mathbf{E} . Let \mathbf{Y} be the remaining unobserved variables. The query $\mathbf{P}(X|\mathbf{e})$ can be answered by:

$$\mathbf{P}(X|\mathbf{e}) = \alpha \mathbf{P}(X, \mathbf{e}) = \alpha \sum_{\mathbf{y}} \mathbf{P}(X, \mathbf{e}, \mathbf{y})$$

Toothache Again

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	0.108	0.012	0.072	0.008
\neg <i>cavity</i>	0.016	0.064	0.144	0.576

Inference: Example

$$\begin{aligned}\mathbf{P}(\textit{Cavity}|\textit{toothache}) &= \alpha \mathbf{P}(\textit{Cavity}, \textit{toothache}) \\ &= \alpha \sum \mathbf{P}(\textit{Cavity}, \textit{toothache}, \textit{Catch}) \\ &= \alpha [\mathbf{P}(\textit{Cavity}, \textit{toothache}, \textit{catch}) + \\ &\quad \mathbf{P}(\textit{Cavity}, \textit{toothache}, \neg \textit{catch})] \\ &= \alpha [\langle 0.108, 0.016 \rangle + \langle 0.012, 0.064 \rangle] \\ &= \alpha \langle 0.12, 0.08 \rangle \\ &= \langle 0.60, 0.40 \rangle\end{aligned}$$

Independence

- ▶ Propositions a and b are independent if and only if

$$P(a \wedge b) = P(a)P(b)$$

- ▶ Or, by the product rule

$$P(a|b) = P(a) \quad \text{and} \quad P(b|a) = P(b)$$

- ▶ Between variables, this is

$$\begin{aligned} \mathbf{P}(X, Y) &= \mathbf{P}(X)\mathbf{P}(Y) \quad \text{and} \\ \mathbf{P}(X|Y) &= \mathbf{P}(X) \quad \text{and} \quad \mathbf{P}(Y|X) = \mathbf{P}(Y) \end{aligned}$$

Illustration of Independence

Suppose we add a fourth variable: *Weather* with 4 values. We know (product rule) that:

$$\begin{aligned} &P(\textit{toothache}, \textit{catch}, \textit{cavity}, \textit{Weather} = \textit{cloudy}) \\ &= P(\textit{Weather} = \textit{cloudy} | \textit{toothache}, \textit{catch}, \textit{cavity}) \\ &= P(\textit{Weather} = \textit{cloudy})P(\textit{toothache}, \textit{catch}, \textit{cavity}) \end{aligned}$$

We can do the same for every value of the 4 variables. That is:

$$\begin{aligned} &\mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}, \textit{Weather}) \\ &= \mathbf{P}(\textit{Weather})\mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \end{aligned}$$

Bayes' Rule I

$$P(C|+) = \frac{P(+|C) \times P(C)}{P(+)}$$

In general:

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Here is some terminology:

$P(A)$ is called the prior probability of A

$P(A|B)$ is called the posterior probability of A given B

$P(B|A)$ is called the likelihood of B given A

$P(B)$ is called the marginal likelihood of B

$$P(B) = \sum_a P(B|A=a)P(A=a).$$

(This is the rule of total probability.)

Conditional form of Bayes' rule:

$$P(A|B, e) = \frac{P(B|A, e) \times P(A|e)}{P(B|e)} \quad (\text{Check!})$$

Bayes' Rule Calculations I

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$
$$P(\neg A|B) =$$

Bayes' Rule Calculations I

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

$$P(\neg A|B) = \frac{P(B|\neg A) \times P(\neg A)}{P(B)}$$

So, $P(A|B) = \alpha P(B|A)P(A)$ and $P(\neg A|B) = \alpha P(B|\neg A)P(\neg A)$.
Since $P(A|B) + P(\neg A|B) = 1$, we get α as:

$$\alpha = \frac{1}{P(B|A)P(A) + P(B|\neg A)P(\neg A)}$$

Although we knew this anyway, it still gives us a slightly different way of calculating with Bayes' rule, by postponing the calculation of the normalising factor α

Bayes' Rule with Multivalued Variables

$$\mathbf{P}(Y|X) = \frac{\mathbf{P}(X|Y)\mathbf{P}(Y)}{\mathbf{P}(X)}$$

Or, with normalisation:

$$\mathbf{P}(Y|X) = \alpha \mathbf{P}(X|Y)\mathbf{P}(Y)$$

Why Use Bayes' Rule?

- ▶ Causal knowledge such as $P(\text{effect}|\text{cause})$ is often more readily available, and reliable, than diagnostic knowledge such as $P(\text{cause}|\text{effect})$

$P(\text{stiff neck}|\text{meningitis})$ versus $P(\text{meningitis}|\text{stiff neck})$

- ▶ Bayes' rule lets us use causal knowledge to make diagnostic inferences

Use $P(\text{stiff neck}|\text{meningitis})$ to derive $P(\text{meningitis}|\text{stiff neck})$

Bayes' Rule with Several Variables

$$\mathbf{P}(Y_1, \dots, Y_m | X_1, \dots, X_n) = \\ \alpha \mathbf{P}(X_1, \dots, X_n | Y_1, \dots, Y_m) \mathbf{P}(Y_1, \dots, Y_m)$$

- ▶ We need to know the conditional probabilities for all possible combinations of the X_i, Y_j s
 - With just boolean variables, this is $2^n 2^m$
 - Just like using the full joint distribution
- ▶ Can we use the idea of independence to reduce these requirements?

Conditional Independence

- ▶ If X and Y are conditionally independent given Z then

$$\mathbf{P}(X, Y|Z) = \mathbf{P}(X|Z)\mathbf{P}(Y|Z) \quad \text{and} \\ \mathbf{P}(X|Y, Z) = \mathbf{P}(X|Z) \quad \text{and} \quad \mathbf{P}(Y|X, Z) = \mathbf{P}(Y|Z)$$

- ▶ X_1, \dots, X_n are conditionally independent, given Y_1, \dots, Y_m if and only if

$$\mathbf{P}(X_1, \dots, X_n|Y_1, \dots, Y_m) = \\ \alpha \mathbf{P}(X_1|Y_1, \dots, Y_m) \cdots \mathbf{P}(X_n|Y_1, \dots, Y_m)$$

- ▶ For boolean variables, this reduces the representation to $2n2^m$ combinations

Benefits of Conditional Independence

- ▶ Conditional independence allows probabilistic systems to scale up (tabular representations of full joint distributions become very large)

$$\begin{aligned}\mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \\ &= \mathbf{P}(\textit{Toothache}, \textit{Catch} | \textit{Cavity}) \mathbf{P}(\textit{Cavity}) \\ &= \mathbf{P}(\textit{Toothache} | \textit{Cavity}) \mathbf{P}(\textit{Catch} | \textit{Cavity}) \mathbf{P}(\textit{Cavity})\end{aligned}$$

- ▶ Conditional independence information is much more commonly available than absolute independence. For example, *Toothache* and *Catch* are not independent *per se*. But they are, given the knowledge about the presence or absence of a cavity.

Summary

- ▶ Basic probability statements include **prior** and **conditional** probabilities over simple and compound propositions.
- ▶ The **full joint distribution** specifies the probability of each complete assignment of values to random variables.
- ▶ **Absolute independence** between subsets of random variables may allow the full joint to be factored into smaller joint distributions.
- ▶ Bayes' rule performs computations using conditional distributions.
- ▶ **Conditional independence** may allow the full joint into smaller conditional distributions. It may allow more efficient computations using Bayes' rule.