

Previous lecture summary:

(1) CNN operators.

* convolution (cross-correlation)

* Pooling

↳ stride
↳ padding

Multiple channels

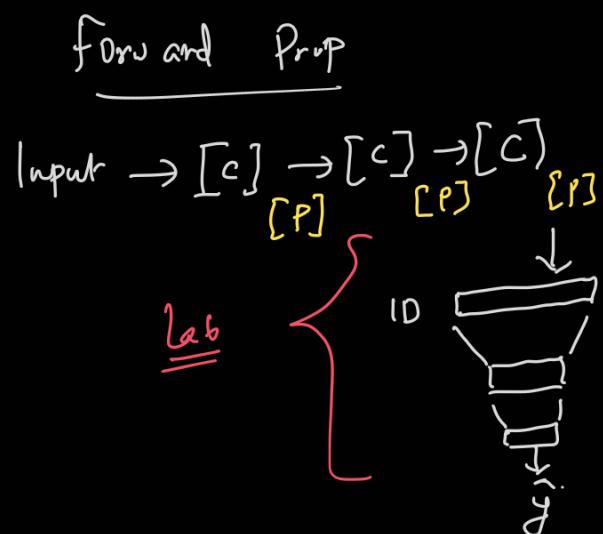
* Inputs
* output

1x1 convolution.

→ Nothing to do with spatial relations

→ Output channels.

256 channel → 1x1 → 64 channel output.



To day:

Backprop errors in CNN.

↓
Gradient of loss is computed.

(conv layer)

Notations

- (1) Inputs are \underline{X} : X_{ij}

- (2) Parameters in a filter (kernel) \underline{W} : w_{ij}
 $2D \rightarrow$

- (3) hidden layer activation: \underline{H} : H_{ij}

(4) outputs \underline{O} : O_{ij}

(5) '*' denote convolution (cross-correlation)

$$\begin{array}{ccc} \boxed{\text{X}} & * & \boxed{\text{W}} \\ \text{X} & & \text{W} \end{array} = \boxed{\text{O}}$$

inputs
(images)

$$\begin{array}{ccc} \boxed{\text{H}} & * & \boxed{\text{W}} \\ \text{H} & & \text{W} \end{array} = \boxed{\text{O}}$$

activations
(op of prev.
conv...)

$$\text{X} : 3 \times 3, \quad \text{W} : 2 \times 2, \quad \text{stride} = 1, \quad \text{padding} = \text{none}$$

$$\left[\begin{array}{ccc} x_{11}^{(l-1)} & x_{12}^{(l-1)} & x_{13}^{(l-1)} \\ x_{21} & x_{22} & x_{23}^{(l-1)} \\ x_{31} & x_{32} & x_{33}^{(l-1)} \end{array} \right] * \left[\begin{array}{cc} w_{11}^{(l)} & w_{12}^{(l)} \\ w_{21}^{(l)} & w_{22}^{(l)} \end{array} \right] = \left[\begin{array}{cc} o_{11} & o_{12} \\ o_{21} & o_{22} \end{array} \right]$$

$$\boxed{\text{H}}^{(l-1)} * \boxed{\text{W}}^{(l)} = \sigma \left(\boxed{\text{O}}^{(l)} \right)$$

non linear
activation
(ReLU).

Target outputs:

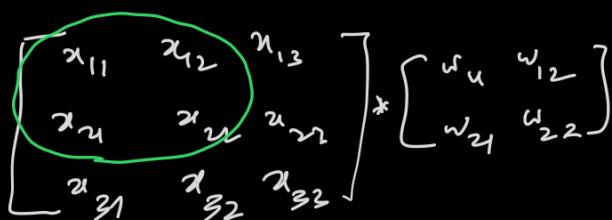
$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \leftarrow$$

Loss function:

$$L \left(\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix}, \begin{bmatrix} o_{11} & o_{12} \\ o_{21} & o_{22} \end{bmatrix} \right)$$

chain rule

$$\rightarrow O_{11} = \underline{\underline{w_{11}x_{11}}} + w_{12}x_{12} \\ + w_{21}x_{21} + w_{22}x_{22}$$



$$- O_{12} = \underline{w_{11}x_{12}} + \underline{w_{12}x_{13}}$$

$$+ w_{21}x_{22} + w_{22}x_{23}$$

$$- O_{21} = w_{11}x_{21} + \underline{w_{12}x_{22}}$$

$$+ w_{21}x_{31} + w_{22}x_{32}$$

$$- O_{22} = w_{11}x_{22} + w_{12}x_{23}$$

$$+ w_{21}x_{32} + w_{22}x_{33}$$

Gradients

=

$$(1) \begin{bmatrix} \frac{\partial L}{\partial \underline{w}} \\ \vdots \end{bmatrix}$$

$$(2) \frac{\partial L}{\partial \underline{x}} \text{ at any } (l)$$

$$\begin{bmatrix} \frac{\partial L}{\partial \underline{x}} \\ \vdots \end{bmatrix}$$

$$\frac{\partial L}{\partial \underline{w}}$$

Path 1

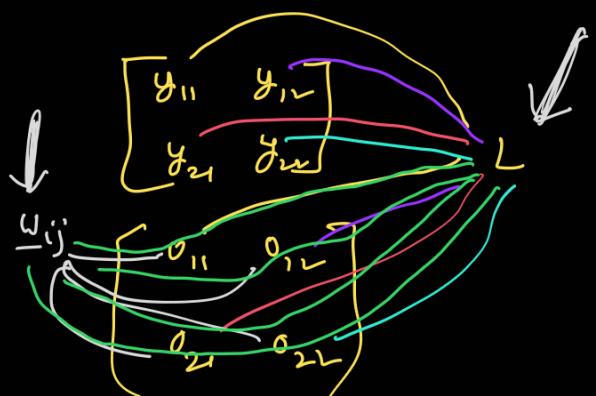
Path 2

$$\frac{\partial L}{\partial w_{11}} = \frac{\partial L}{\partial O_{11}} \frac{\partial O_{11}}{\partial w_{11}} + \frac{\partial L}{\partial O_{12}} \frac{\partial O_{12}}{\partial w_{11}} \\ + \frac{\partial L}{\partial O_{21}} \frac{\partial O_{21}}{\partial w_{11}} + \frac{\partial L}{\partial O_{22}} \frac{\partial O_{22}}{\partial w_{11}}$$

$$\frac{\partial L}{\partial w_{12}} = \frac{\partial L}{\partial O_{11}} \frac{\partial O_{11}}{\partial w_{12}} + \frac{\partial L}{\partial O_{12}} \frac{\partial O_{12}}{\partial w_{12}}$$

$$\frac{\partial L}{\partial w_{12}} = \frac{\partial L}{\partial O_{21}} \frac{\partial O_{21}}{\partial w_{12}} + \frac{\partial L}{\partial O_{22}} \frac{\partial O_{22}}{\partial w_{12}}$$

$$\underline{w} \leftarrow \underbrace{O_{11} \quad O_{12} \quad O_{21} \quad O_{22}}_{L} \quad L = \sum (y_{ij} - O_{ij})^2$$



$$\frac{\partial L}{\partial w_1}, \quad \frac{\partial L}{\partial w_{2+}}$$

$$\frac{\partial L}{\partial \omega_{11}} : \quad \frac{\partial L}{\partial \omega_{11}} u_{11} + \frac{\partial L}{\partial \omega_{12}} u_{12} + \frac{\partial L}{\partial \omega_{21}} u_{21} + \frac{\partial L}{\partial \omega_{22}} u_{22}$$

$$\frac{\partial L}{\partial \omega_{12}} : \quad \frac{\partial L}{\partial o_{11}} u_{12} + \frac{\partial L}{\partial o_{12}} x_{13} + \frac{\partial L}{\partial o_{21}} x_{21} + \frac{\partial L}{\partial o_{22}} x_{23}$$

$$\frac{\partial L}{\partial \omega_{21}} : \quad \frac{\partial L}{\partial \omega_{11}} u_{21} + \frac{\partial L}{\partial \omega_{12}} u_{22} + \frac{\partial L}{\partial \omega_{21}} u_{31} + \frac{\partial L}{\partial \omega_{22}} u_{32}$$

$$\frac{\partial L}{\partial \omega_{22}} : \quad \frac{\partial L}{\partial \omega_{11}} \omega_{22} + \frac{\partial L}{\partial \omega_{12}} \omega_{23} + \frac{\partial L}{\partial \omega_{21}} \omega_{32} + \frac{\partial L}{\partial \omega_{22}} \omega_{33}$$

$$\left[\begin{array}{cc} \frac{\partial L}{\partial w_{11}} & \frac{\partial L}{\partial w_{12}} \\ \frac{\partial L}{\partial w_{21}} & \frac{\partial L}{\partial w_{22}} \end{array} \right] = \left[\begin{array}{ccc} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{array} \right] * \left[\begin{array}{cc} \frac{\partial L}{\partial o_{11}} & \frac{\partial L}{\partial o_{12}} \\ \frac{\partial L}{\partial o_{21}} & \frac{\partial L}{\partial o_{22}} \end{array} \right]$$

$$\frac{\partial L}{\partial \underline{w}} = \left[\text{conv} \left(\underline{x}, \frac{\partial L}{\partial \underline{o}} \right) \right]_{\text{cross-correlation}}$$

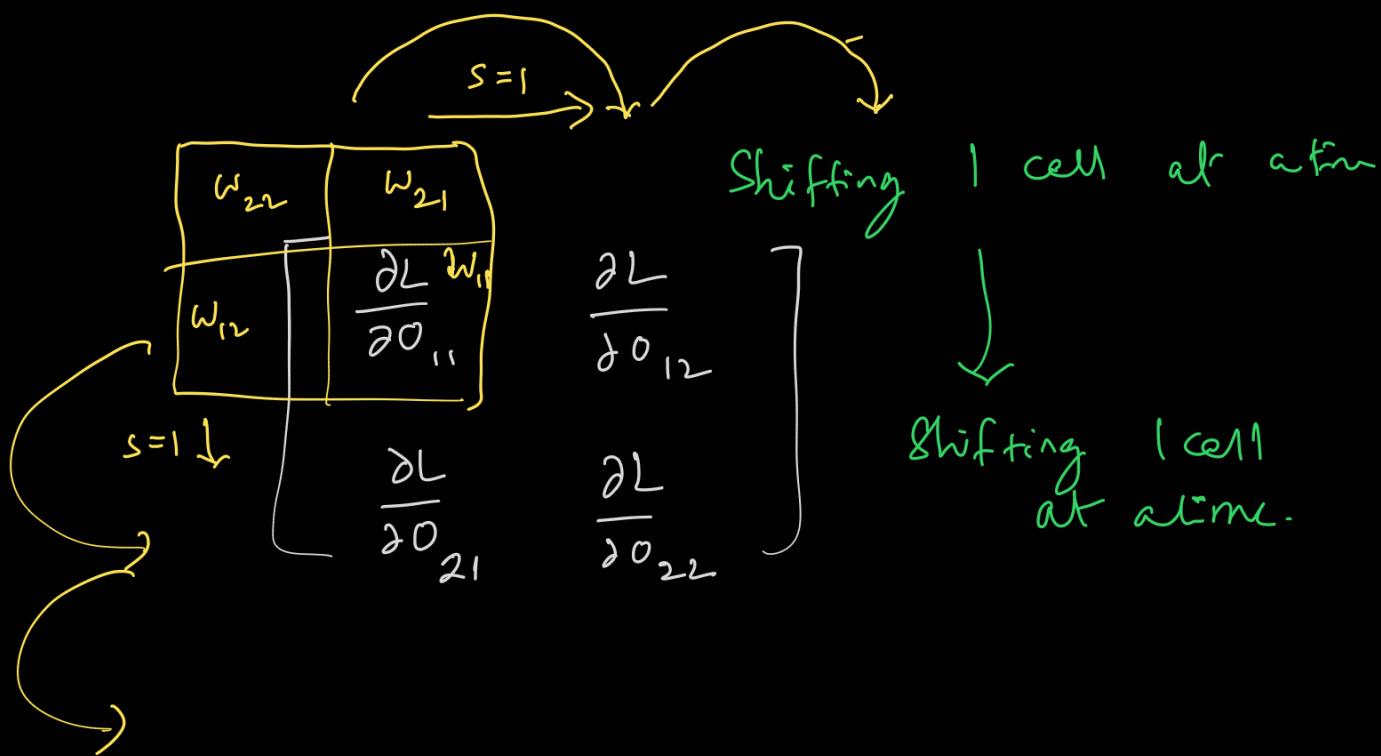
$$\left\{ \frac{\partial L}{\partial w^{(l)}} = \text{Conv} \left(\text{input}^{(l)}, \frac{\partial L}{\partial h^{(l)}} \right) \right.$$

$\frac{\partial L}{\partial x} :$
 $\boxed{w_{11}} x_{11} + w_{12} x_{12} + w_{21} x_{21} + w_{22} x_{22}$
 $\frac{\partial L}{\partial u_{11}} = \frac{\partial L}{\partial o_{11}} \overset{\frac{\partial o_{11}}{\partial x_{11}}}{w_{11}} + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} 0 + \frac{\partial L}{\partial o_{22}} 0$
 $\frac{\partial L}{\partial u_{12}} = \frac{\partial L}{\partial o_{11}} w_{12} + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} 0 + \frac{\partial L}{\partial o_{22}} 0$
 $\frac{\partial L}{\partial u_{13}} = \frac{\partial L}{\partial o_{11}} 0 + \frac{\partial L}{\partial o_{12}} w_{12} + \frac{\partial L}{\partial o_{21}} 0 + \frac{\partial L}{\partial o_{22}} 0$
 $\frac{\partial L}{\partial u_{21}} = \frac{\partial L}{\partial o_{11}} w_{21} + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} w_{11} + \frac{\partial L}{\partial o_{22}} 0$
 $\frac{\partial L}{\partial u_{22}} = \frac{\partial L}{\partial o_{11}} w_{22} + \frac{\partial L}{\partial o_{12}} w_{11} + \frac{\partial L}{\partial o_{21}} w_{12} + \frac{\partial L}{\partial o_{22}} w_{11}$
 $\frac{\partial L}{\partial u_{23}} = \frac{\partial L}{\partial o_{11}} 0 + \frac{\partial L}{\partial o_{12}} w_{12} + \frac{\partial L}{\partial o_{21}} 0 + \frac{\partial L}{\partial o_{22}} w_{11}$
 $\frac{\partial L}{\partial u_{31}} = \frac{\partial L}{\partial o_{11}} 0 + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} w_{21} + \frac{\partial L}{\partial o_{22}} 0$
 $\frac{\partial L}{\partial u_{32}} = \frac{\partial L}{\partial o_{11}} 0 + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} w_{22} + \frac{\partial L}{\partial o_{22}} w_{21}$
 $\frac{\partial L}{\partial u_{33}} = \frac{\partial L}{\partial o_{11}} 0 + \frac{\partial L}{\partial o_{12}} 0 + \frac{\partial L}{\partial o_{21}} 0 + \frac{\partial L}{\partial o_{22}} w_{22}$

Matrix form:

$$\left[\begin{array}{ccc} \frac{\partial L}{\partial u_{11}} & \frac{\partial L}{\partial u_{12}} & \frac{\partial L}{\partial u_{13}} \\ \frac{\partial L}{\partial u_{21}} & \frac{\partial L}{\partial u_{22}} & \frac{\partial L}{\partial u_{23}} \\ \frac{\partial L}{\partial u_{31}} & \frac{\partial L}{\partial u_{32}} & \frac{\partial L}{\partial u_{33}} \end{array} \right] = \left[\begin{array}{cc} \frac{\partial L}{\partial o_{11}} & \frac{\partial L}{\partial o_{12}} \\ \frac{\partial L}{\partial o_{21}} & \frac{\partial L}{\partial o_{22}} \end{array} \right] \otimes \begin{bmatrix} w_{22} & w_{21} \\ w_{12} & w_{11} \end{bmatrix}$$

90° 90°



$$\frac{\partial L}{\partial X} = \cancel{\text{Full Convolution}} = \text{Conv.} \left(\frac{\partial L}{\partial O}, \underbrace{\text{Rotate180}(w)}_{\cancel{=}} \right)$$

$$\boxed{\frac{\partial L}{\partial H^{(L-1)}} = \text{Full_Conv} \left(\frac{\partial L}{\partial H^{(L)}}, \text{Rotate180}(W^{(L)}) \right)}$$

