Bill of Material

| Sr. No. | Part Name | | Quantity |
|---------|------------------------------------|-------|----------|
| | | Price | |
| 1 | Plug-in board MB-102 | - | 1 |
| 2 | Moto Driver Adafruit DRV8833 | - | 1 |
| 3 | Development Board ESP32 NodeMCU | - | 1 |
| 4 | TT Motor Encoder | - | 2 |
| 5 | Servo Motor Miuzei 9G | - | 1 |
| 6 | Cable Motor Driver to ESP32 | 9 € | 1 |
| 7 | Cable Power Supply | - | 1 |
| 8 | Jumper Wire | - | 1 set |
| 9 | Motor Feetech DC-130D | - | 2 |
| 10 | Power supply unit MB102 | - | 1 |
| 11 | Base Plate 305x305x15 mm | - | 1 |
| 12 | Microswitch red XSS-5GL13 | - | 3 |
| 13 | Belt T2 2mm pitch 6mm wide | - | 1.6m |
| 14 | Linear ball bearing LMU-N6 | - | 8 |
| 15 | Push Button | - | 1 |
| 16 | Shafts d6 x 300mm | - | 7 |
| 17 | Storage box | - | 1 |
| 18 | Screws (M4, M5, M6) | - | 20 |
| 19 | Screws (M2, M3) Box | 10 | 13 |
| 20 | Led | | 1 |

Bill of Material – CAD

| Sr. No. | Diagram | Part Name | Short Description | Quantity |
|------------|---------|-------------------------------------|---|----------|
| 1 | | Base Plate 305x305x15 mm | A wooden base plate used for mounting other parts in the project. | 1 |
| 2 | | Move-Pulley | A 3D-printed pulley part used for mechanical movement in the system. | 2 |
| 3 | | Geared- Pulley | A 3D-printed pulley with teeth mechanism for precise movement. | 2 |
| 4 | | 3D-printed feet | Feet designed and printed to support the system structure. | 4 |
| 5 | | X-axis moving guide | The X-axis moving guide is a component that moves along the X-axis using a belt mechanism. The stationary part is where the servo motor is mounted to drive the movement. | 1 |
| 6 | | x axis rod support with motor | The X-axis rod support with motor is designed to securely fix a DC motor for X-axis movement. It also accommodates an encoder to monitor and control the motor's position and movement. | 1 |

| 7 | X-axis end support guide | The X-axis end support guide provides structural support for the X-axis, while also connecting the belt to the roller, ensuring smooth and efficient movement along the axis | 1 |
|----|-------------------------------------|--|---|
| 8 | X- axis_Motor_ Blocker | The X-axis motor blocker is designed to securely hold the DC motor in place, providing stability and support during operation. | 1 |
| 9 | y axis rod support with motor | The Y-axis rod support with motor and encoder is designed to mount a DC motor for Y-axis movement, while the encoder ensures precise position tracking and control. | 1 |
| 10 | y-axis parallel support | The Y-axis parallel support is built to connect the rods, facilitating smooth and accurate movement along the Y-axis. It ensures proper alignment and stability during operation. | 1 |
| 11 | y-axis parallel support back | The Y-axis parallel support back is built to connect the rods, facilitating smooth and accurate movement along the Y-axis. It ensures proper alignment and stability during operation. | 1 |
| 12 | Y-axis right support | The Y-axis right support is designed to provide stability for the Y-axis, connecting the belt to the roller and securing the rod for smooth and controlled movement along the Y-axis. | 1 |

| 13 | Y axis trolley | The Y-axis trolley is designed to hold the X-axis rod support with motor, allowing the rod to pass through it. It features bearings for smooth and frictionless movement during operation. | 1 |
|----|------------------------|--|---|
| 14 | Z axis movable part | The Z-axis movable part is designed to hold the pen and control its vertical movement, allowing the pen to lift up and down as needed during operation. | 1 |