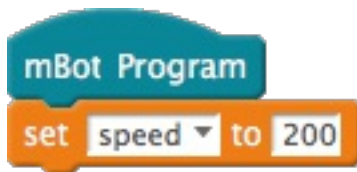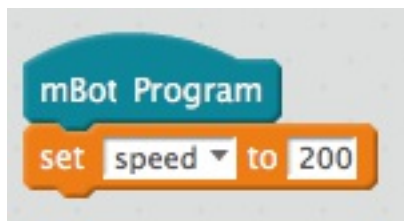# Line Follower

What are the sensors
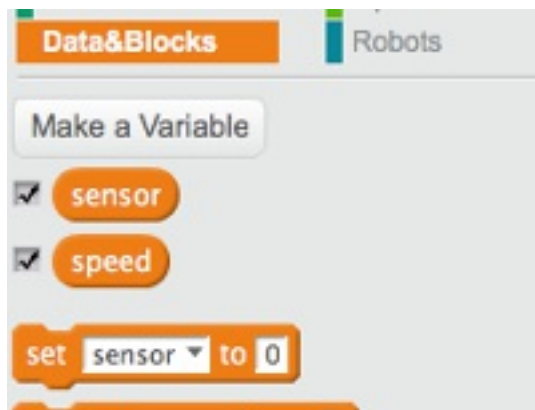
mBlock Code

Create a variable speed

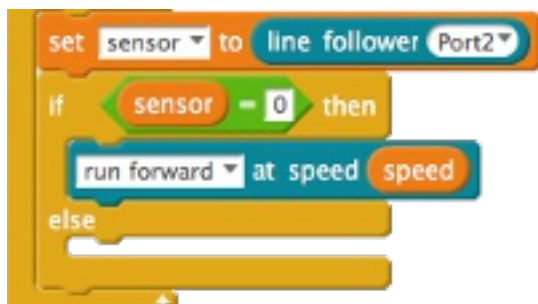**Set it to the speed you want**
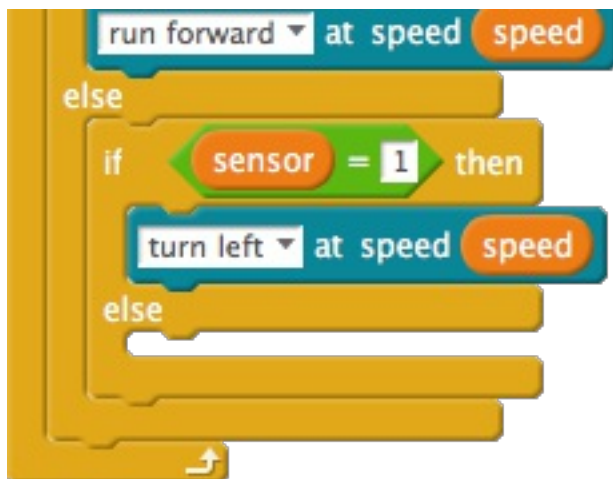

Create a variable sensor

Set it to the line follower

If the sensor is 0 then go forwards

If the sensor is 1 then turn left

If the sensor is 2 then turn right, and for all others go backwards