

# mpmfracture Manual

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## 1 Important Files

### 1.1 mpmfracture.tar.gz

This is an archive containing `mpmfracture.exe`. Extract the executable by typing:

```
tar -zxvf mpmfracture.tar.gz
```

This is to avoid problems with pushing executables into github repository.

### 1.2 mpmfracture.exe

As mentioned in section 1.1, `mpmfracture.exe` is archived in `mpmfracture.tar.gz`.

The executable solver, compiled C code from `mpmfracture.m` conversion via MATLAB coder. Reads the input file `input.txt` and produces output data at SimOutput folder.

If folder named "SimOutput" doesn't exist, `mpmfracture.exe` produces no output.

Expected use case: high performance run

### 1.3 mpmfracture.m

The "source code" of the executable solver `mpmfracture.exe`. Run in MATLAB, `mpmfracture.m` works the same way as its C-compiled executable counterpart.

`mpmfracture.m` is a parallelized MATLAB code, with known bug of having a small chance of big *parfors* loop going over the defined upper limit. A *try-catch* and rollback procedure which could easily work around the issue renders the MATLAB script non-CODER-compliant, therefore deprecated. When left running via MATLAB for a long time, expect the run to crash at random point.

Expected use case: debugging and test runs

### 1.4 mpmfractureplot.m

Plots the run results. To be run in MATLAB, not intended to go through coder. This `mpmfractureplot.m` is essentially

Editing `mpmfractureplot.m` is unrecommended, instead edit `mpmfracture.m` and generate `mpmfractureplot.m` by running `generateplotter.m` (see subsection 1.5).

### 1.5 generateplotter.m

`generateplotter.m` activates plotting features suppressed in `mpmfracture.m` for coder compliance. Run in MATLAB, `generateplotter.m` generates `mpmfractureplot.m`, which, run in MATLAB, reads simulation output files and generates plot.

### 1.6 Input file input.txt

An input file called `input.txt` is included in the repository. See section 2 on the rules to write this input file, and section 3 for the available parameters.

## 2 How to write input file input.txt

### 2.1 Regular input

Variable input must conform with the following format:

`<variable> = <value> | <type>`

Spaces and indentations at the start of the line, around the equal sign, around the | sign, or at the end of the line is ignored.

For example, inputting the elastic modulus **E** can be done as:

`E = 8000 | float`

Which means the variable to be input is called **E**, with the value of 8000, and with variable type **float**.

There are three variable types (**<type>**):

1. **long**: for long integer
2. **float**: for decimal number
3. **string**: for string input

Variable names need to match exactly with what the solver expects, and are **case sensitive**.

Variable types need to match exactly with what the solver expects. For example, elastic modulus **E** needs to be marked as **float**, even though the value is a round number, for example, 8000.

Same goes with **long**, which should serve quantities that involves counting of round numbers. For example, number of grids (**NN\_base\_1** and **NN\_base\_2**) and **refinementfactor**

### 2.2 Comment

The symbol **%** and any text after, up to the end of the line, is ignored.

### 2.3 New line

Both ASCII characters 10 and 13 (and 10 followed by 13 and vice versa) are accepted as new line marker in the input file.

## 3 Parameters

### 3.1 General

#### 3.1.1 **refinementfactor**

Determines the subdivision of cells for refinement purpose

#### 3.1.2 **E**

Set the elastic modulus

#### 3.1.3 **nu**

Set poisson's ratio

#### 3.1.4 **b\_1**

Constant body force in the x direction

#### 3.1.5 **b\_2**

Constant body force in the y direction

### **3.1.6 le\_base**

Determines the size of cell before refinement

### **3.1.7 NN\_base\_1**

Number of grids in x direction before refinement

### **3.1.8 NN\_base\_2**

Number of grids in y direction before refinement

### **3.1.9 NodexPosition\_PredXvel**

Determines the X position of where X displacement-controlled nodes are located. There's some tolerance to the number, so non-rounded decimals or irrational numbers won't be a problem

### **3.1.10 NodeyPosition\_PredYvel**

Determines the Y position of where Y displacement-controlled nodes are located. There's some tolerance to the number, so non-rounded decimals or irrational numbers won't be a problem

### **3.1.11 NodexPosition\_PredXvel\_rel**

Determines the X position of where X displacement-controlled nodes are located. There's some tolerance to the number, so non-rounded decimals or irrational numbers won't be a problem

### **3.1.12 NodeyPosition\_PredYvel\_rel**

Determines the Y position of where Y displacement-controlled nodes are located. There's some tolerance to the number, so non-rounded decimals or irrational numbers won't be a problem

### **3.1.13 endcostime**

Determines when the cosine ramp ends (see figure 1)

### **3.1.14 dispload**

Determines the displacement at when **endcostime** is reached (see figure 1)

### **3.1.15 ftime**

Determines the time when simulation is considered finished

### **3.1.16 NodexPosition\_pin**

Determines the x position of nodes with pin support

### **3.1.17 NodeyPosition\_pin**

Determines the y position of nodes with pin support

### **3.1.18 NodexPosition\_roller**

Determines the x position of nodes with roller support

### **3.1.19 NodeyPosition\_roller**

Determines the y position of nodes with roller support

### **3.1.20 x\_start**

Determines the start of particle placement in x direction

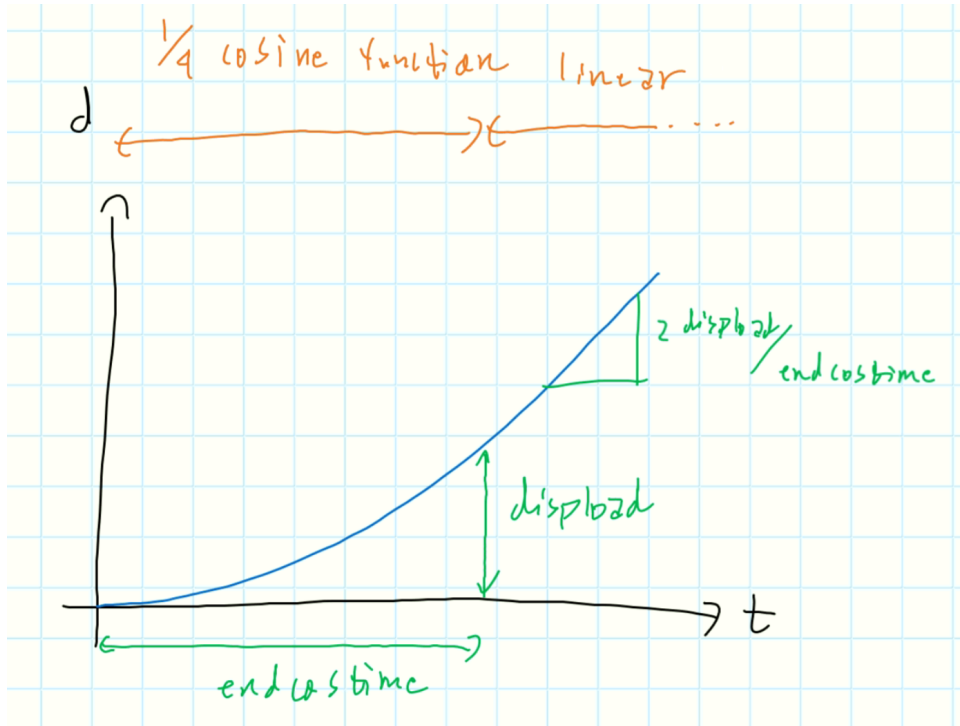


Figure 1: Definition of endcostime and dispload

### 3.1.21 x\_end

Determines the end of particle placement in x direction

### 3.1.22 y\_start

Determines the start of particle placement in y direction

### 3.1.23 y\_end

Determines the end of particle placement in y direction

### 3.1.24 denyinitiation

Prevents any crack initiation

### 3.1.25 denypropagation

Prevents any crack propagation

### 3.1.26 t\_halfife

Damping, how long does it take to half particle velocity (the smaller the number, the larger the damping). If not assigned, then no damping applies.

### 3.1.27 t0\_plane

Sets the thickness of the 2D plane. Thickness stays constant under plane strain, may change under plane stress.

## 3.2 Erase Boxes

Particles can be deleted (erased) to, for example, create a notch. This is achieved by defining several boxes where particles can be deleted from

### 3.2.1 n\_eraseboxes

Declare the number of boxes to be defined. This is important for memory preallocation.

### 3.2.2 x\_erase\_start(i)

Defines the left boundary of the box, where  $i = 1, 2, 3, \dots, \text{n\_eraseboxes}$

### 3.2.3 x\_erase\_end(i)

Same as `x_erase_start(i)` but for the right boundary of the box.

### 3.2.4 y\_erase\_start(i)

Same as `x_erase_start(i)` but for the bottom boundary of the box.

### 3.2.5 y\_erase\_end(i)

Same as `x_erase_start(i)` but for the top boundary of the box.

## 3.3 Initial Cracks

Initial cracks are defined by how many crack paths is desired, followed by the number of particles for each path.

### 3.3.1 n\_crackpaths

Declares the number of crack paths as initial crack.

### 3.3.2 n\_crackparticles( $i_{path}$ )

Declares the number of crack particles for path number  $i_{path}$

### 3.3.3 x\_crackparticle( $i_{particle}, i_{dim}, i_{path}$ )

Defines the position of crack particle number  $i_{particle}$  of path  $i_{path}$ , in either x ( $i_{dim} = 1$ ) or y ( $i_{dim} = 2$ ) direction

### 3.3.4 tip\_terminate( $i_{path}, i_{tip}$ )

`tip_terminate( $i_{path}, i_{tip}$ )=1` prevents tip number  $i_{tip}$  of path  $i_{path}$  from propagating.  $i_{tip} = 1$  designates the tip with the highest  $i_{particle}$  number, while  $i_{tip} = 2$  designates the tip with the lowest  $i_{particle}$ .

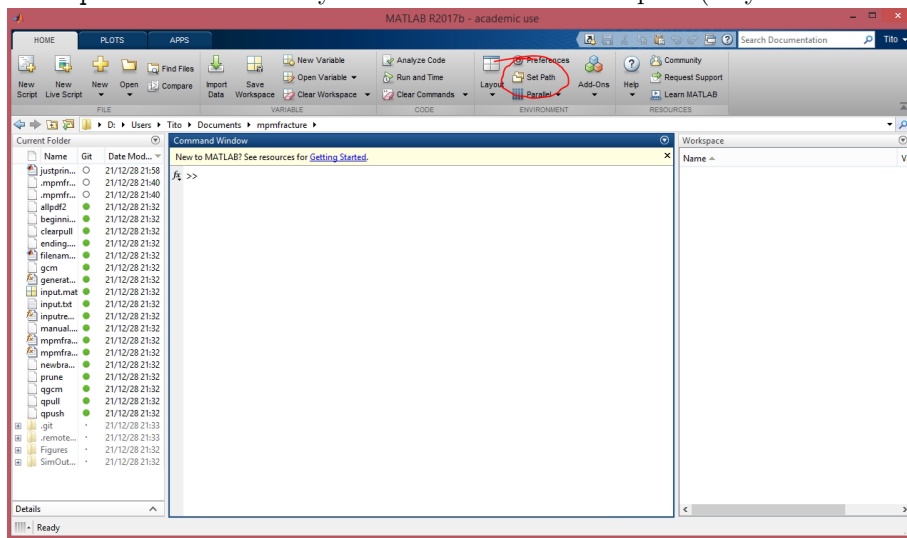
### 3.3.5 elasticstrength

Determines the strength of the elastic material, for the purpose of crack initiation and propagation.

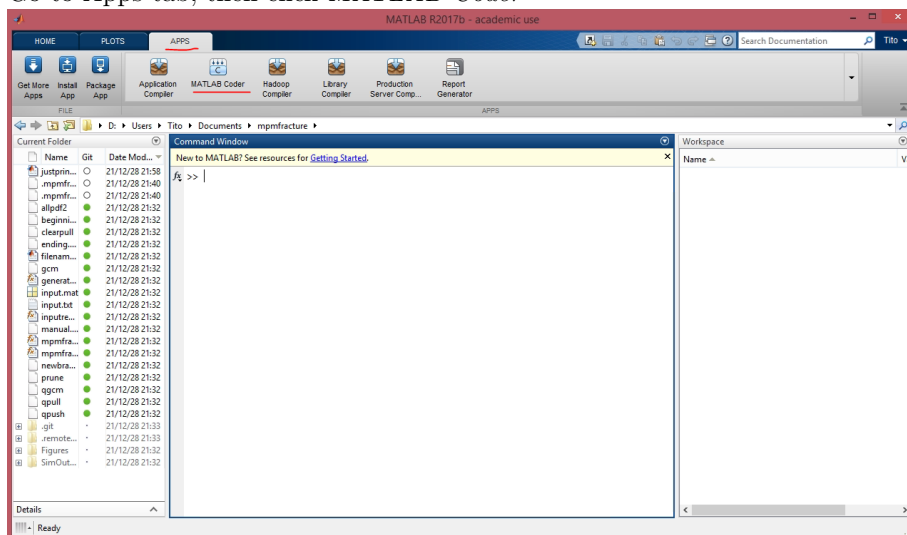
## 4 How to "compile" mpmfracture.m into an executable

### 4.1 MATLAB coder

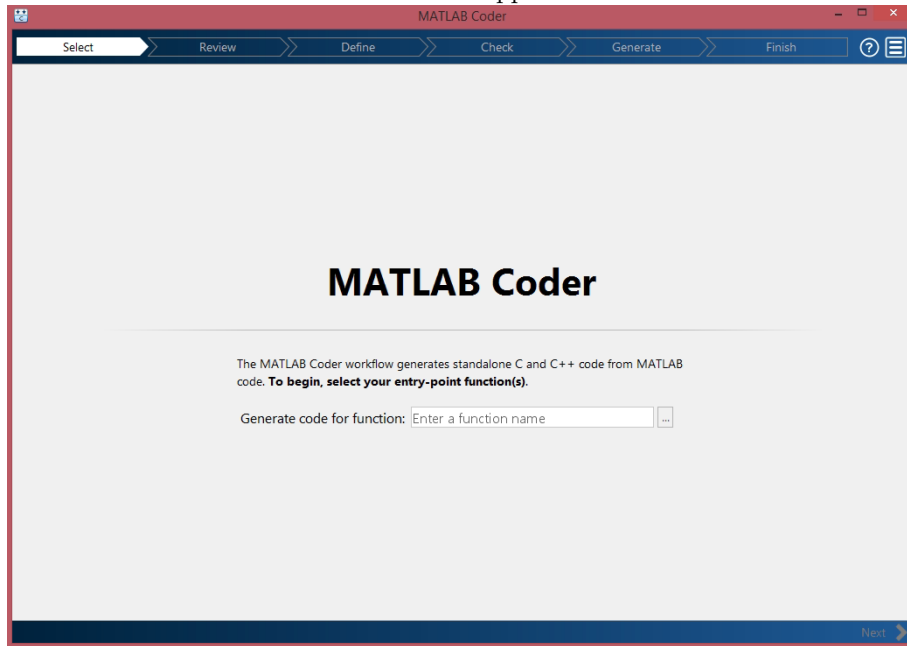
1. Add mpmfracture directory into MATLAB as known path (only need to do this once)



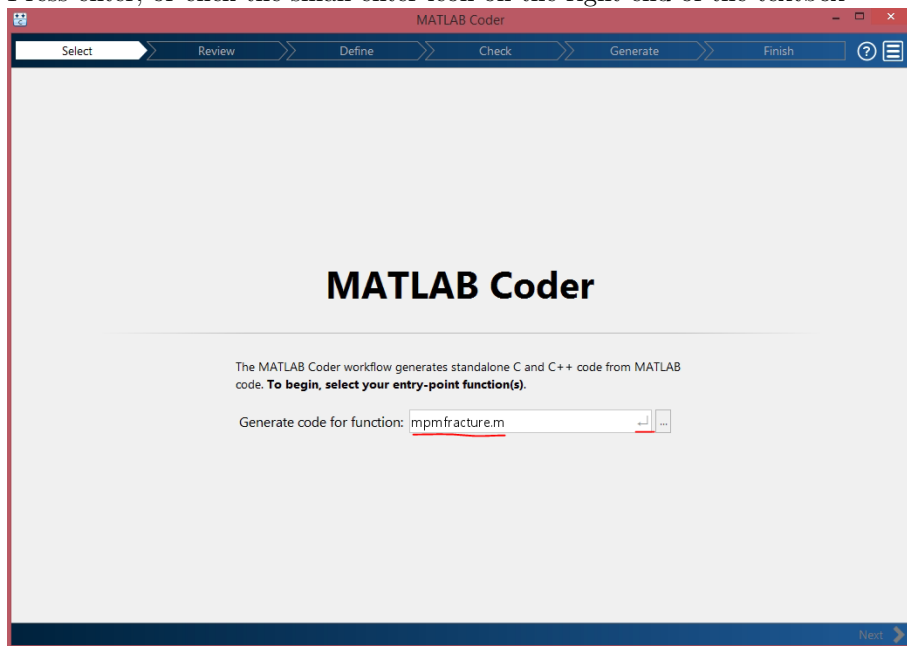
2. Go to Apps tab, then click *MATLAB Coder*



- Wait until the *MATLAB Coder* window appears

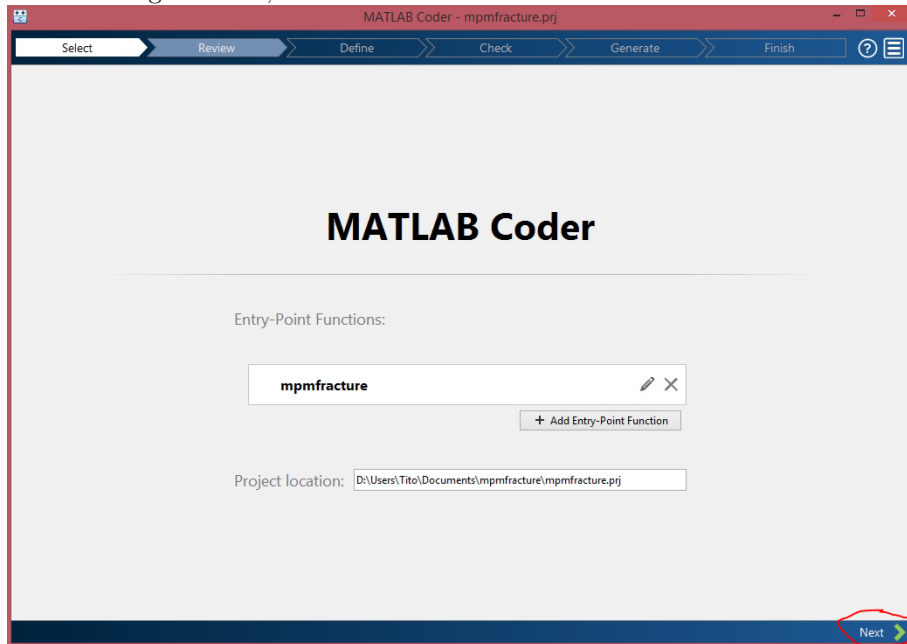


- write `mpmfracture.m` in the *Enter a function name* textbox
- Press enter, or click the small enter icon on the right end of the textbox

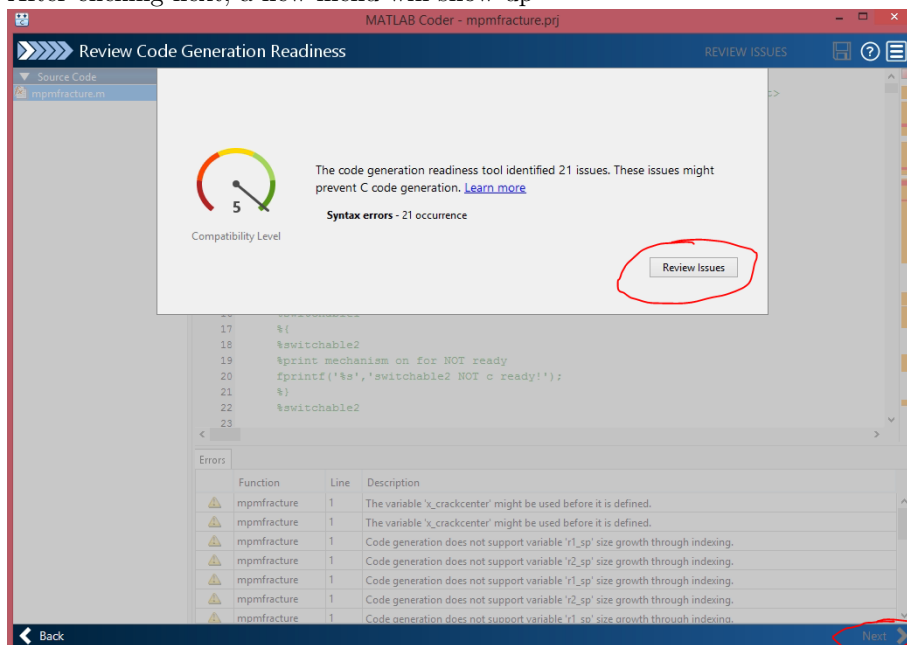


- If there is a warning about project already existing, click *overwrite*

7. After waiting for a bit, the next button can be clicked

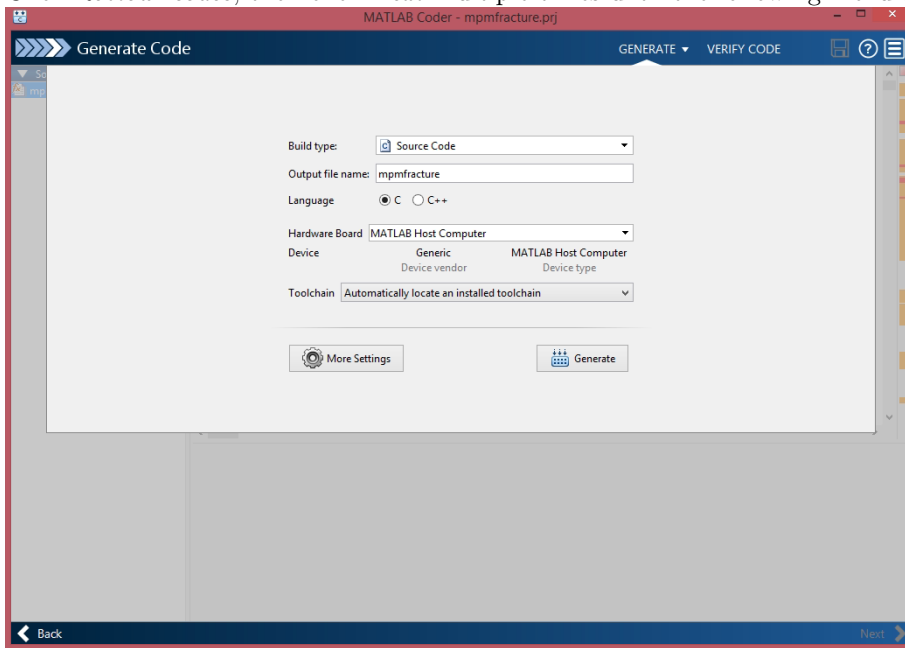


8. After clicking next, a new menu will show up

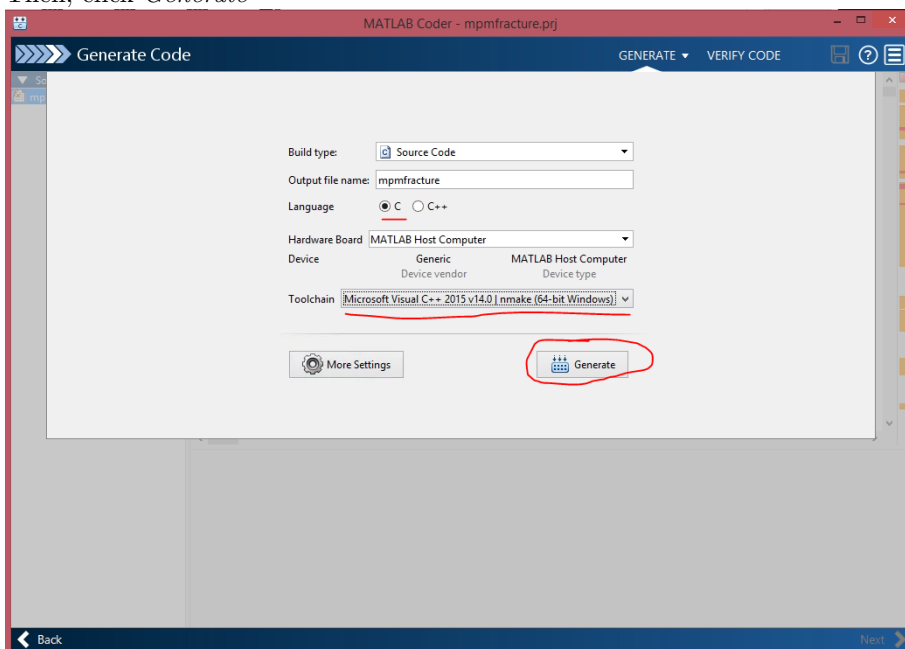




9. Click *Review Issues*, then click *Next* multiple times until the following menu appears:

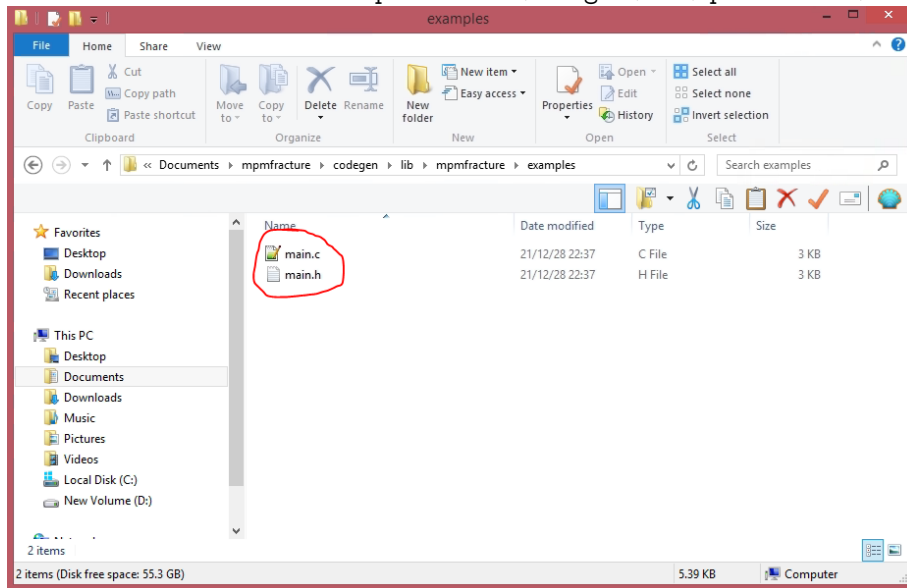


10. Make sure *C* is selected as the *Language*  
11. For *Toolchain*, choose *Microsoft Visual C++ 2015 v14.0*  
12. Then, click *Generate*



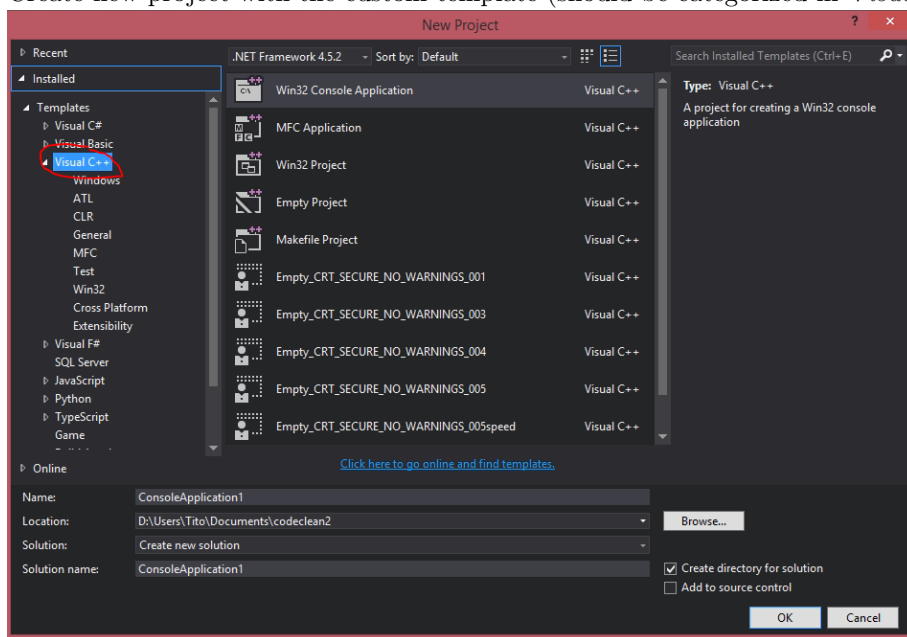
13. The process may take about 3 minutes until the C code is generated  
14. Once done, a bunch of .c and .h files should be available in `mpmfracture\codegen\lib\mpmfracture`

15. move `main.c` and `main.h` from `mpmfracture\codegen\lib\mpmfracture\examples` to `mpmfracture\codegen\lib`

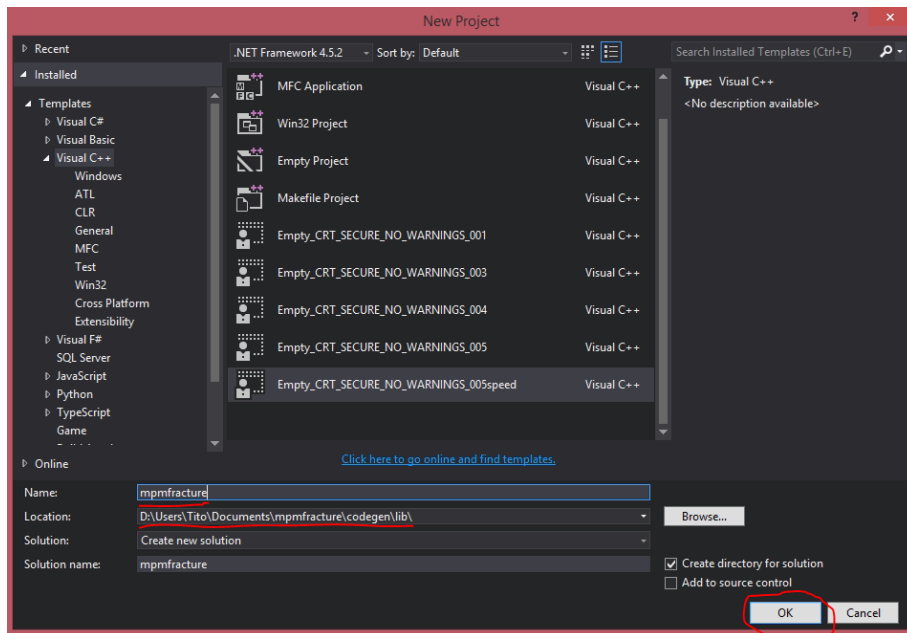


## 4.2 MS Visual Studio

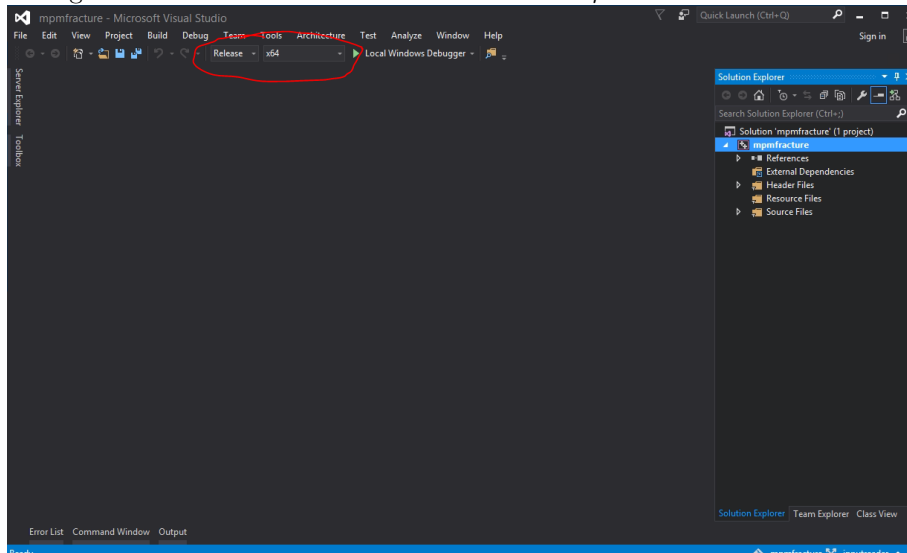
1. Open MS Visual Studio
2. Import the included template .zip file in `mpmfracture\MSVSTemplate`
3. Create new project with the custom template (should be categorized in *Visual C++*)



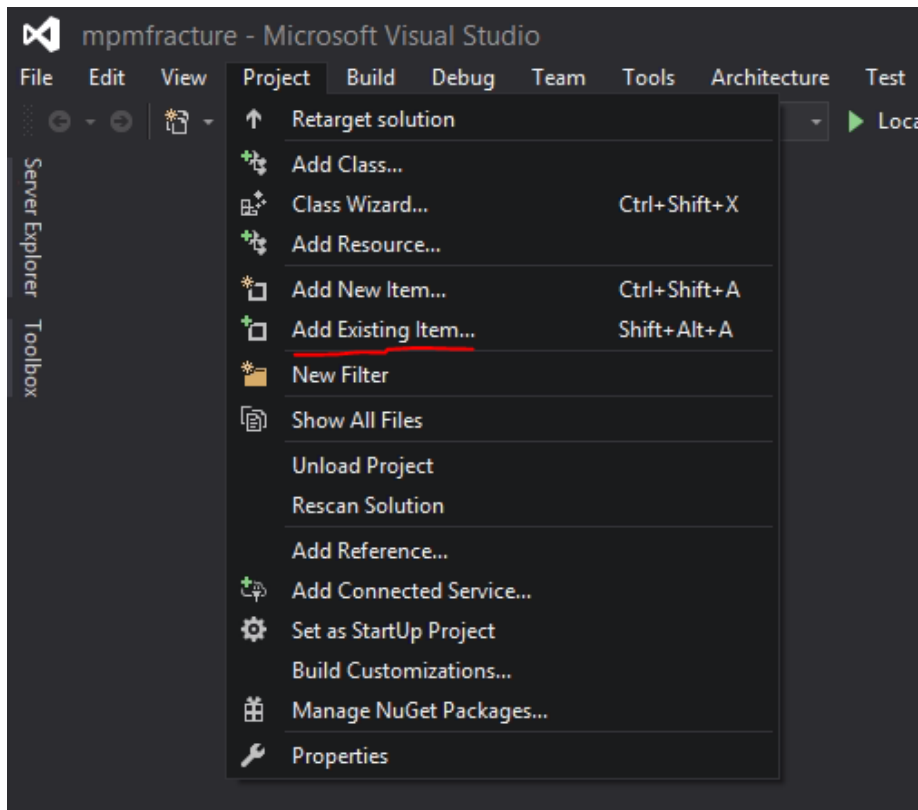
4. Put `mpmfracture` in the *Name* textbox, and the full directory of `mpmfracture\codegen\lib` in *Location* textbox, then click OK



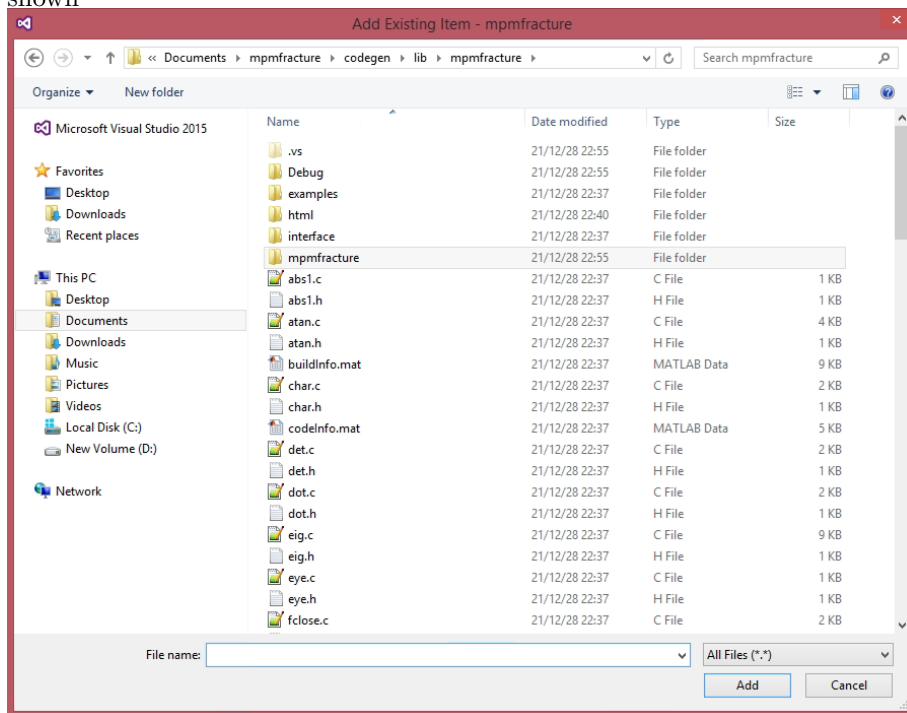
5. Change the two selectors above to *Release* and *x64*



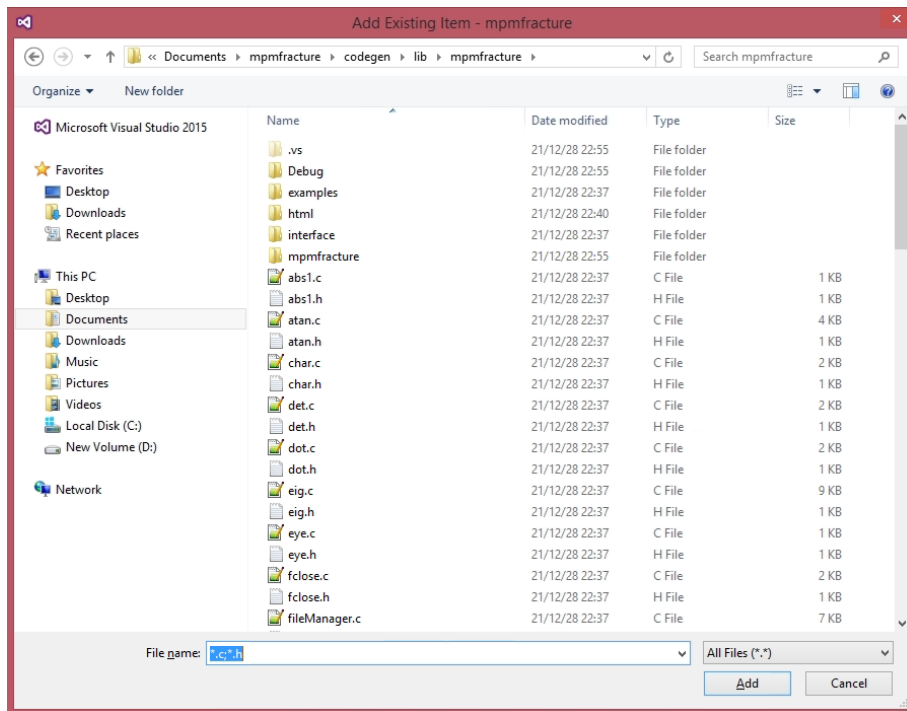
6. Go to *Project*, *Add Existing Item*



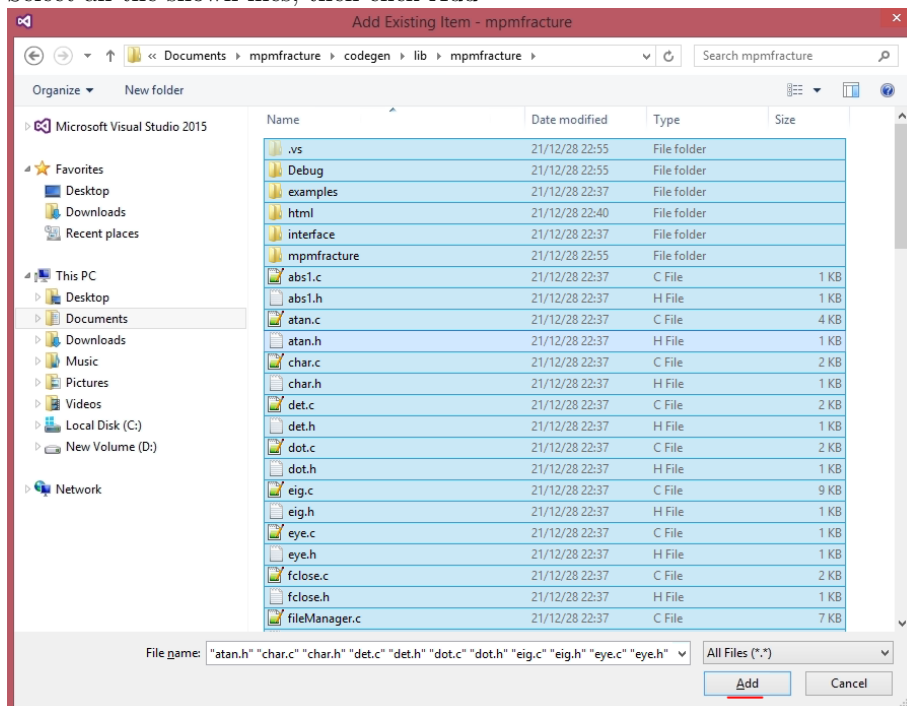
7. Go to the `mpmfracture\codegen\lib\mpmfracture` directory, a bunch of `.c` and `.h` files should be shown



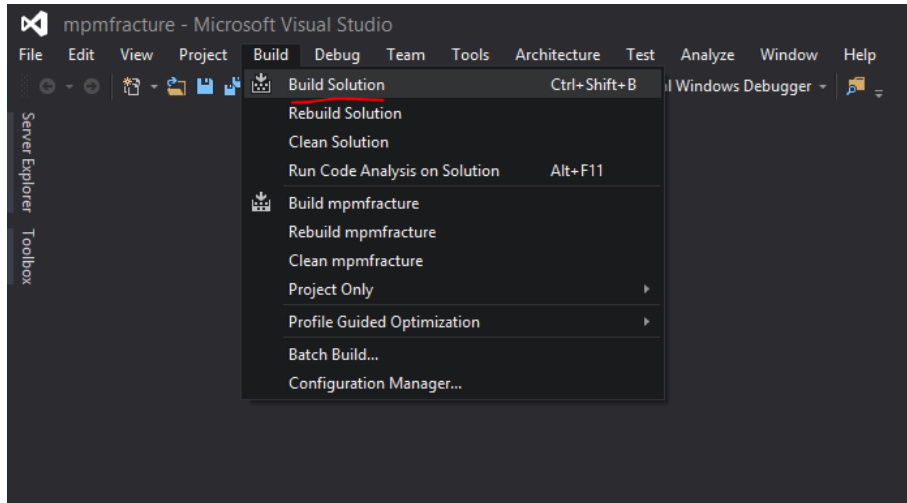
8. Type `*.c;*.h` in the file name, then press enter (to show only `.c` and `.h` files)



9. Select all the shown files, then click Add



10. Go to *Build, Build Solution*, then wait until the build process is finished



11. After the build is finished, the executable is located in `mpmfracture\codegen\lib\mpmfracture\x64\Release\mpmfracture.exe`. Copy the executable to the root directory (`mpmfracture` folder)
12. Make sure `SimOutput` folder exists in the root directory
13. Run `mpmfracture.txt`, the output should be many `.txt` files in `SimOutput` directory
14. At any point of the simulation, the result can be printed by running `mpmfractureplot.m` in MATLAB. A new folder will be created within `SimOutput` containing printed frames of some timesteps.

## 5 release Versions

### 5.1 Current

- cleaner source code, same functionality
- no more warnings from MATLAB Coder (R2017b)

### 5.2 Commit Hash fbda4ee2ac218c585358db592e3cd42e62494d67

- support crack initiation, propagation, merging in elastic medium
- cohesion is inaccessible
- ability to create notches via particle deletion

### 5.3 Commit Hash 89884f2e7cea72df665e06d68f8b5be2a8fcbbaf

- coder compliant
- no access to cracking features
- input file as `input.txt`

### 5.4 Commit Hash cddb217154dcc657114a0b9c2850942a2f57f80e

- not coder compliant
- parfor error handling via MATLAB run
- input file as `input.mat`

## Appendix: Interacting with the github repository

The github repository is:

`https://github.com/titoadibaskoro/mpmfracture`

Only clone from `release` branch. For pushing, please use `dev` branch.

To clone `release` branch of the repository, type:

```
git clone -b release https://github.com/titoadibaskoro/mpmfracture.git
```

To create new branch, type:

```
git branch <new branch name>
```

To pull remote branch that is currently active locally:

```
git pull origin <branch name>
```

Typing <branch name> different from the current active branch may result in unexpected merging.

To pull remote branch that doesn't exist locally:

```
git fetch origin <branch name>:<branch name>
```

To switch branch:

```
git checkout <branch name>
```

To go to any commit hash:

```
git checkout <commit hash>
```

To drop any uncommitted changes:

```
git checkout .
```