Udacity AIND, Foundations of AI: Project 3, Create a Domain-Independent Planner

| | Breadth-First-Search | | Depth-First-Graph- Search | | Uniform Cost Search | |
|--------------------------------|--|---|--|---|--|--|
| | Expansions | 43 | Expansions | 21 | Expansions | 55 |
| Air Cargo Problem 1 | Goal Tests | 56 | Goal Tests | 22 | Goal Tests | 57 |
| | New Nodes | 180 | New Nodes | 84 | New Nodes | 224 |
| | Plan Length | 6 | Plan Length | 20 | Plan Length | 6 |
| | Time | 0.032 | Time | 0.015 | Time | 0.038 |
| Air Cargo Problem 2 | Expansions | 3343 | Expansions | 624 | Expansions | 4852 |
| | Goal Tests | 4609 | Goal Tests | 625 | Goal Tests | 4854 |
| | New Nodes | 30509 | New Nodes | 5602 | New Nodes | 44030 |
| | Plan Length | 9 | Plan Length | 619 | Plan Length | 9 |
| | Time | 14.324 | Time | 3.501 | Time | 12.068 |
| Air Cargo Problem 3 | Expansions | 14663 | Expansions | 408 | Expansions | 18235 |
| | Goal Tests | 18098 | Goal Tests | 409 | Goal Tests | 18237 |
| | New Nodes | 129631 | New Nodes | 3364 | New Nodes | 159716 |
| | Plan Length | 12 | Plan Length | 392 | Plan Length | 12 |
| | Time | 105.178 | Time | 1.967 | Time | 53.048 |
| | A* h_1 | | A* h_ignore_preconditions | | A* h_pg_levelsum | |
| | Expansions | 55 | | | | |
| | LAPUIISIONS | 55 | Expansions | 55 | Expansions | 11 |
| | Goal Tests | 57 | Goal Tests | 55 57 | Expansions Goal Tests | 11 13 |
| Air Cargo | - | | - | | * | |
| Air Cargo Problem 1 | Goal Tests | 57 | Goal Tests | 57 | Goal Tests | 13 |
| _ | Goal Tests New Nodes | 57 224 | Goal Tests New Nodes | 57 224 | Goal Tests New Nodes | 13 50 |
| _ | Goal Tests New Nodes Plan Length | 57 224 6 | Goal Tests New Nodes Plan Length | 57 224 6 | Goal Tests New Nodes Plan Length | 13 50 6 |
| Problem 1 | Goal Tests New Nodes Plan Length Time | 57 224 6 0.037 | Goal Tests New Nodes Plan Length Time | 57 224 6 0.050 | Goal Tests New Nodes Plan Length Time | 13 50 6 0.593 |
| Problem 1 Air Cargo | Goal Tests New Nodes Plan Length Time Expansions | 57 224 6 0.037 4852 | Goal Tests New Nodes Plan Length Time Expansions | 57 224 6 0.050 4852 | Goal Tests New Nodes Plan Length Time Expansions | 13 50 6 0.593 86 |
| Problem 1 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 57 224 6 0.037 4852 4854 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 57 224 6 0.050 4852 4854 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 13 50 6 0.593 86 88 |
| Problem 1 Air Cargo | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes | 57 224 6 0.037 4852 4854 44030 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes | 57 224 6 0.050 4852 4854 44030 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes | 13 50 6 0.593 86 88 841 |
| Problem 1 Air Cargo | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length | 57 224 6 0.037 4852 4854 44030 9 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length | 57 224 6 0.050 4852 4854 44030 9 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length | 13 50 6 0.593 86 88 841 9 |
| Air Cargo Problem 2 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time | 57 224 6 0.037 4852 4854 44030 9 12.053 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time | 57 224 6 0.050 4852 4854 44030 9 13.292 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time | 13 50 6 0.593 86 88 841 9 52.880 |
| Air Cargo Problem 2 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions | 57 224 6 0.037 4852 4854 44030 9 12.053 18235 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions | 57 224 6 0.050 4852 4854 44030 9 13.292 18235 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions | 13 50 6 0.593 86 88 841 9 52.880 318 |
| Problem 1 Air Cargo Problem 2 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 57 224 6 0.037 4852 4854 44030 9 12.053 18235 18237 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 57 224 6 0.050 4852 4854 44030 9 13.292 18235 18237 | Goal Tests New Nodes Plan Length Time Expansions Goal Tests New Nodes Plan Length Time Expansions Goal Tests | 13 50 6 0.593 86 88 841 9 52.880 318 320 |

Depth first search consistently performs the most poorly, giving the largest plan length, though in the shortest amount of time. This is due to the fact that Depth first search must traverse the search tree all the way from top to bottom, reaching the goal state quickly but creating the least efficient plan. Uniform cost search, A* using h_1, and A* using h_ignore_preconditions return identical results, though ignore preconditions takes the longest to create a plan. Breadth first search performs marginally faster for Air Cargo Problem 1, but otherwise A* h 1 and Uniform cost search are clearly the most efficient algorithms, and therefore deemed as providing the optimal solution. This is because Breadth first search traverses nodes sequentially while uniform cost search uses nodes of similar cost, and h 1 uses heuristics to efficiently solve the problem. Even though A* using levelsum consistently has the least expansions, goal tests, and new nodes, it's performance is slower than A* h 1 and Uniform cost search since it has to iterate through multiple levels to find the levelsum, depeniding on where the goals are. Below are the resulting plans for each problem, using the most optimal solution based on the recorded times and shortest plans from the tables above. As stated in module 32 (A* Search 5) of Lesson 11: Search of the video lessons, A* finds the lowest cost path if the heuristic underestimates the true cost, making h optimistic and admissible, supporting the results and analysis above. Similarly, in module 26 (On Uniform Cost) of the same lesson, uniform cost search is shown to search in the direction of the goal rather than in all directions, significantly improving results and time to find the goal.

Optimal solution for problem 1 using A* h_1

Load(C1, P1, SFO)

Load(C2, P2, JFK)

Fly(P1, SFO, JFK)

Fly(P2, JFK, SFO)

Unload(C1, P1, JFK)

Unload(C2, P2, SFO)

Optimal solution for problem 2 using A* h 1

Load(C1, P1, SFO)

Load(C2, P2, JFK)

Load(C3, P3, ATL)

Fly(P1, SFO, JFK)

Fly(P2, JFK, SFO)

Flv(P3, ATL, SFO)

Unload(C3, P3, SFO)

Unload(C1, P1, JFK)

Unload(C2, P2, SFO)

Optimal solution for problem 3 using Uniform cost search

Load(C1, P1, SFO)

Load(C2, P2, JFK)

Fly(P1, SFO, ATL)

Load(C3, P1, ATL)

Fly(P2, JFK, ORD)

Load(C4, P2, ORD)

Fly(P2, ORD, SFO)

Fly(P1, ATL, JFK)

Unload(C4, P2, SFO)

Unload(C3, P1, JFK)

Unload(C1, P1, JFK) Unload(C2, P2, SFO)