

REPORT ON

DEVELOPMENT OF HIGHER ORDER FINITE  
ELEMENT.



PRESENTED BY

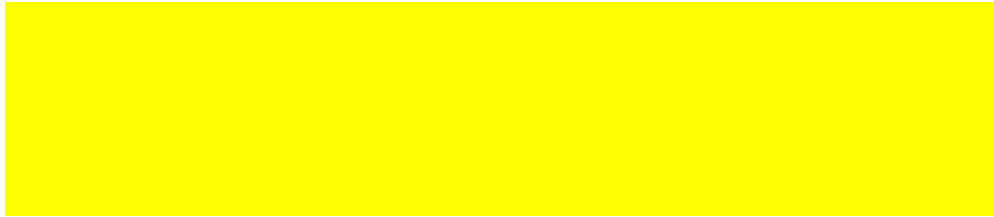
NAME-BARUN KUMAR

ROLL-23MT0095

M.TECH (DESIGN)

DEPT.-MECHANICAL ENGINEERING

IIT (ISM), DHANBAD

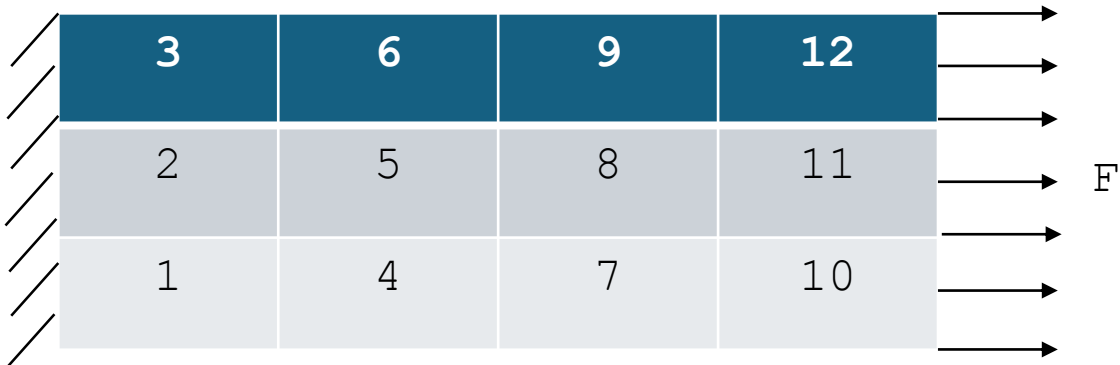


# INDEX

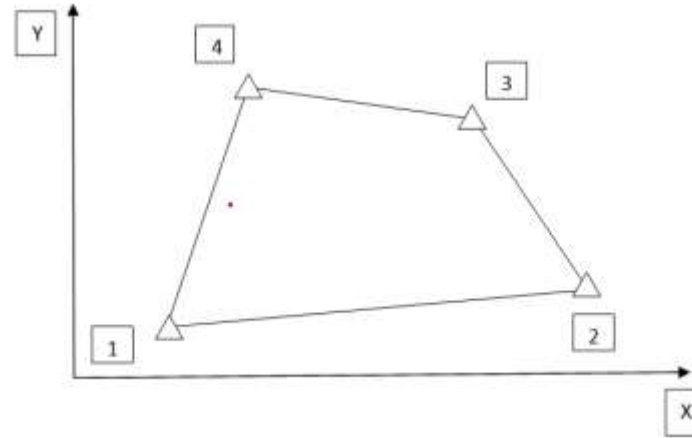
Serial no.	Topics
1	INTRODUCTION
2	LITERATURE REVIEW
3	GAPS/PROPOSED RESEARCH
4	EXPERIMENTAL DETAILS/METHODOLOGY/MATHEMATICAL FORMULATION
5	RESULTS/DISCUSSION
6	CONCLUSION/WORK TO BE CARRIED OUT
7	REFERENCES/PROPOSED TIME FRAME

# INTRODUCTION:

- The process of dividing the body into an equivalent number of finite elements associated with nodes is called as discretization of an element in finite element analysis.
- Discretization helps out to know the stress and displacement values at a particular point also.

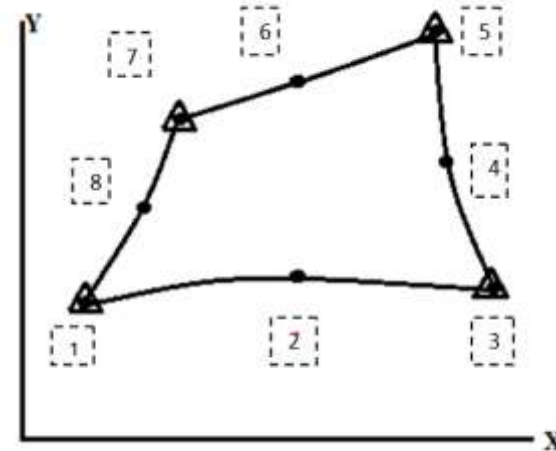


Discretization



Isoparametric element

Geometry Node = Displacement Node



Subparametric element

Geometry Node < Displacement Node

# INTRODUCTION:

- The finite element method (FEM) is a powerful numerical tool used across various fields, from structural engineering to fluid dynamics, for solving complex partial differential equations. While lower-order finite elements have been widely utilized for their simplicity and computational efficiency, higher-order finite elements (HOFE) offer significant advantages in terms of solution accuracy and convergence rates.

1					
$\xi$	$\eta$				
$\xi^2$	$\xi\eta$	$\eta^2$			
$\xi^3$	$\xi^2\eta$	$\xi\eta^2$	$\eta^3$		
$\xi^4$	$\xi^3\eta$	$\xi^2\eta^2$	$\xi\eta^3$	$\eta^4$	
$\xi^5$	$\xi^4\eta$	$\xi^3\eta^2$	$\xi^2\eta^3$	$\xi\eta^4$	$\eta^5$

→ linear

→ quadratic

→ cubic

→ quartic

→ quintic

Pascal's triangle

*k = order*

$p = 1 \quad \phi_i = a_0 + a_1\xi + a_2\eta,$

$p = 2 \quad \phi_i = a_0 + a_1\xi + a_2\eta + a_3\xi^2 + a_4\xi\eta + a_5\eta^2,$

$p = 3 \quad \phi_i = a_0 + a_1\xi + a_2\eta + a_3\xi^2 + a_4\xi\eta + a_5\eta^2 + a_6\xi^3 + a_7\xi^2\eta + a_8\xi\eta^2 + a_9\eta^3.$

The number of terms in ' $p$ ' degree polynomial:  $n_p = \frac{(p+1)(p+2)}{2}$

# STATE OF THE ART:

TITLE	AUTHOR	Program	Year	Element used	FINDINGS
Shear Lag Analysis due to Flexure of Prismatic Beams with Arbitrary Cross-Sections by FEM	Dang-Bao Tran	MATLAB Code	2021	9-Noded	In this study, shear lag effects resulting from flexure of beams with arbitrary cross sections of homogenous elastic materials is examined using the finite element method (FEM).
Finite Elements for Engineering Analysis: A Comparison of all elements with one problem.	R w lewis	FORTRAN	2011	CST, LST, 4-	

<div> <div>TITLE</div> </div>	<div> <div>AUTHOR</div> </div>	<div> <div>Program</div> </div>	<div> <div>Year</div> </div>	<div> <div>Element used</div> </div>	<div> <div>FINDING</div> </div>
<div> <div>A FIRST COURSE IN THE</div> <div>FINITE ELEMENT METHOD</div> </div>	<div> <div>Daryl L. Logan</div> </div>	<div> <div>fortran</div> </div>	<div> <div>1986</div> </div>	<div> <div>CST, LST,</div> <div>4-Noded</div> </div>	<div> <div>Systemic development theories,2 d elements</div> </div>
<div> <div>Finite Element Analysis:</div> <div>Theory and Programming</div> </div>	<div> <div>C. S. Krishnamoorthy</div> </div>	<div> <div>Fortran</div> </div>	<div> <div>1987</div> </div>	<div> <div>4-Noded</div> </div>	<div> <div>Emphasis on programming, ation to engg problems</div> </div>
<div> <div>Stiffness Matrices of</div> <div>Isoparametric Four-node</div> <div>Finite Elements by Exact</div> <div>Analytical Integration</div> </div>	<div> <div>Gautam Dasgupta</div> </div>	<div> <div>Mathemat</div> <div>ica</div> <div>programmi</div> <div>ng</div> <div>language</div> </div>	<div> <div>2006</div> </div>	<div> <div>4-Noded</div> </div>	<div> <div>Analyti</div> <div>l</div> <div>integra</div> <div>on met</div> <div>is used</div> </div>
<div> <div>Development of an</div> <div>Interactive Finite Element</div> <div>Solution Module for 2d</div> <div>Stress Problem Analysis</div> <div>Using Isoparametric</div> </div>	<div> <div>K.M. entwistle</div> </div>	<div> <div>MATLAB</div> <div>Code</div> </div>	<div> <div>2018</div> </div>	<div> <div>8-Noded</div> </div>	<div> <div>Variational and energy methods</div> </div>

# GAPS AND DOMAIN OF WORK

## **Automated Mesh Generation for Higher-Order Elements**

- Gap:** While mesh generation is well-developed for linear elements, creating high-quality meshes for higher-order elements, especially in 3D with curved boundaries, is still problematic.

## **Scalable and Efficient Solvers**

- Gap:** The computational cost of higher-order finite element methods is substantial, particularly for large-scale problems.

## **Adaptive Refinement Techniques**

- Gap:** Adaptive refinement for higher-order finite elements is less mature compared to its application in lower-order elements.

## **5. Robustness in Multi-Physics Simulations**

- Gap:** The application of HOFE in multi-physics and highly nonlinear problems.

## **6. Numerical Integration and Quadrature Rules**

- Gap:** Accurate numerical integration for high-order elements, especially for elements with curved boundaries or in 3D, is a challenging task.

## **Handling Complex Boundary Conditions**

- Gap:** Imposing complex boundary conditions such as mixed or non-standard conditions in HOFE is less straightforward than with lower-order elements.

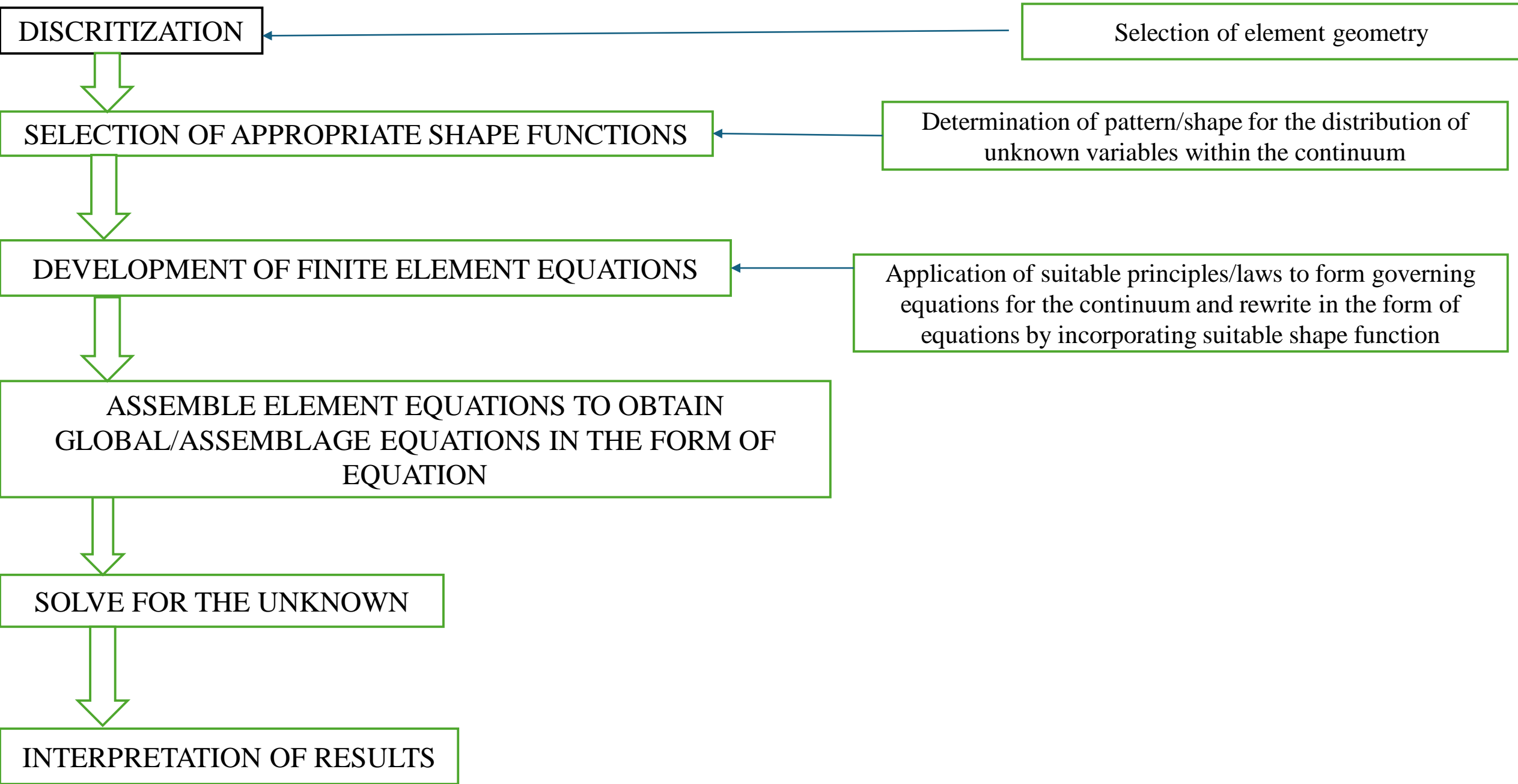
## **• Parallelization and High-Performance Computing (HPC)**

- Gap:** HOFE methods inherently involve more computational data, which can challenge existing parallel computing frameworks.

## **Application-Specific Methodologies**

- Gap:** There is limited research focused on optimizing HOFE for specific applications, such as turbulent flow simulation.

# METHODOLOGY





## 2. Strain-displacement relationships:

$$\varepsilon_x = \frac{\partial u}{\partial x}$$

$$\varepsilon_y = \frac{\partial v}{\partial y}$$

$$\varepsilon_z = \frac{\partial w}{\partial z}$$

$$\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$$

$$\gamma_{yz} = \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y}$$

$$\gamma_{zx} = \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}$$

**Displacement approximation** in terms of shape functions

$$\underline{u} = \underline{N} \underline{d}$$

**Strain approximation** in terms of strain-displacement matrix

$$\underline{\varepsilon} = \underline{B} \underline{d}$$

**Stress approximation**

$$\underline{\sigma} = \underline{D} \underline{B} \underline{d}$$

**Element stiffness matrix**

$$\underline{k} = \int_{V^e} \underline{B}^T \underline{D} \underline{B} dV$$

**Element nodal load vector**

$$\underline{f} = \underbrace{\int_{V^e} \underline{N}^T \underline{X} dV}_{\underline{f}_b} + \underbrace{\int_{S_r^e} \underline{N}^T \underline{T}_s dS}_{\underline{f}_s}$$

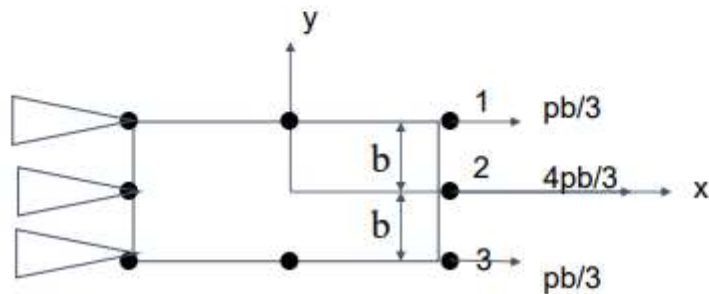
# MATHEMATICAL FORMULATIONS

The **consistent nodal loads** are

$$F_{1x} = \int_{-b}^b p N_1 dy = \int_{-b}^b p \frac{y(b+y)}{2b^2} dy = \frac{pb}{3}$$

$$F_{2x} = \int_{-b}^b p N_2 dy = \int_{-b}^b p \frac{b^2 - y^2}{b^2} dy = \frac{4pb}{3}$$

$$F_{3x} = \int_{-b}^b p N_3 dy = -\int_{-b}^b p \frac{y(b-y)}{2b^2} dy = \frac{pb}{3}$$

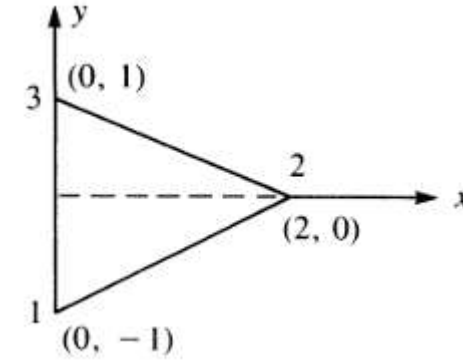


$$[k] = \frac{tE}{4A(1+\nu)(1-2\nu)} \begin{bmatrix} \beta_i & 0 & \gamma_i \\ 0 & \gamma_i & \beta_i \\ \beta_j & 0 & \gamma_j \\ 0 & \gamma_j & \beta_j \\ \beta_m & 0 & \gamma_m \\ 0 & \gamma_m & \beta_m \end{bmatrix}$$

$$\times \begin{bmatrix} 1-\nu & \nu & 0 \\ \nu & 1-\nu & 0 \\ 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix} \begin{bmatrix} \beta_i & 0 & \beta_j & 0 & \beta_m & 0 \\ 0 & \gamma_i & 0 & \gamma_j & 0 & \gamma_m \\ \gamma_i & \beta_i & \gamma_j & \beta_j & \gamma_m & \beta_m \end{bmatrix}$$

## MATHEMATICAL FORMULATIONS

Evaluating the stiffness matrix for the elements shown in Figure . The coordinates are in units of inches. Assume plane stress conditions. Let  $E = 30 \times 10^6$  psi,  $\nu = 0.25$ , and thickness  $t = 1$  in.



$$[k] = t A [B]^T [D] [B]$$

$$x_i = 0, y_i = -1, x_j = 2, y_j = 0, x_m = 0, y_m = 1$$

$$A = \frac{1}{2} b h = \frac{1}{2} (2)(2) = 2 \text{ in.}^2$$

$$\beta_i = y_j - y_m = 0 - 1 = -1$$

$$\beta_j = y_m - y_i = 1 - (-1) = 2$$

$$\beta_m = y_i - y_j = -1 - 0 = -1$$

$$\gamma_i = x_m - x_j = 0 - 2 = -2$$

$$\gamma_j = x_i - x_m = 0 - 0 = 0$$

$$\gamma_m = x_j - x_i = 2 - 0 = 2$$

$$[B] = \frac{1}{2A} \begin{bmatrix} \beta_i & 0 & \beta_j & 0 & \beta_m & 0 \\ 0 & \gamma_i & 0 & \gamma_j & 0 & \gamma_m \\ \gamma_i & \beta_i & \gamma_j & \beta_j & \gamma_m & \beta_m \end{bmatrix}$$

$$[B] = \frac{1}{2A} \begin{bmatrix} \beta_i & 0 & \beta_j & 0 & \beta_m & 0 \\ 0 & \gamma_i & 0 & \gamma_j & 0 & \gamma_m \\ \gamma_i & \beta_i & \gamma_j & \beta_j & \gamma_m & \beta_m \end{bmatrix}$$

Since it is plane stress  $[D] = \frac{E}{(1-\nu^2)} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix}$

$$\text{So } [B]^T [D] = \frac{30 \times 10^6}{4(0.9375)} \begin{bmatrix} -1 & 0 & -2 \\ 0 & -2 & -1 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \\ -1 & 0 & 2 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0.25 & 0 \\ 0.25 & 1 & 0 \\ 0 & 0 & 0.375 \end{bmatrix}$$

# MATHEMATICAL FORMULATIONS

$$\text{So } [B]^T [D] = \frac{30 \times 10^6}{4(0.9375)} \begin{bmatrix} -1 & 0 & -2 \\ 0 & -2 & -1 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \\ -1 & 0 & 2 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0.25 & 0 \\ 0.25 & 1 & 0 \\ 0 & 0 & 0.375 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & -0.25 & -0.75 \\ -0.5 & -2 & -0.375 \\ 2 & 0.5 & 0 \\ 0 & 0 & 0.75 \\ -1 & -0.25 & 0.75 \\ 0.5 & 2 & -0.375 \end{bmatrix} \frac{30 \times 10^6}{4(0.9375)}$$

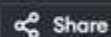
$$[k] = t A [B]^T [D] [B]$$

$$\Rightarrow [k] = (1 \text{ in.})(2) \frac{30 \times 10^6}{4(0.9375)} \begin{bmatrix} -1 & -0.25 & -0.75 \\ -0.5 & -2 & -0.375 \\ 2 & 0.5 & 0 \\ 0 & 0 & 0.75 \\ -1 & -0.25 & 0.75 \\ 0.5 & 2 & -0.375 \end{bmatrix}$$

$$\frac{1}{4} \begin{bmatrix} -1 & 0 & 2 & 0 & -1 & 0 \\ 0 & -2 & 0 & 0 & 0 & 2 \\ -2 & -1 & 0 & 2 & 2 & -1 \end{bmatrix}$$

$$[k] = 4.0 \times 10^6 \begin{matrix} & i=1 & j=2 & m=3 \\ \begin{bmatrix} 2.5 & 1.25 & -2 & -1.5 & -0.5 & 0.25 \\ 1.25 & 4.375 & -1 & -0.75 & -0.25 & -3.625 \\ -2 & -1 & 4 & 0 & -2 & 1 \\ -1.5 & -0.75 & 0 & 1.5 & 1.5 & -0.75 \\ -0.5 & -0.25 & -2 & 1.5 & 2.5 & -1.25 \\ 0.25 & -3.625 & 1 & -0.75 & -1.25 & 4.375 \end{bmatrix} \end{matrix}$$

main.cpp



Run

Output

Clear

```
191 // Compute D * B
192 std::vector<std::vector<double>> DB = multiplyMatrices(D, B);
193 if(DB.empty()) {
194     std::cerr << "Error in multiplying D and B matrices for Element "
195         << elem.id << ". Skipping.\n";
196     continue;
197 }
198 // Compute BT * (D * B)
199 std::vector<std::vector<double>> BTDB = multiplyMatrices(BT, DB);
200 if(BTDB.empty()) {
201     std::cerr << "Error in multiplying B^T and (D * B) matrices for
202         Element " << elem.id << ". Skipping.\n";
203     continue;
204 }
205 // Compute stiffness matrix K = t * A * BTDB
206 std::vector<std::vector<double>> K = BTDB;
207 for(auto& row : K) {
208     for(auto& val : row) {
209         val *= t * area;
210     }
211 }
212 // Display stiffness matrix
213 std::cout << "\nStiffness Matrix for Element " << elem.id << ":\n";
214 printMatrix(K);
215
```

Enter the number of nodes: 3

Enter node data (ID x y) for each node:

Format: ID x y

1 0 -1

2 2 0

3 0 1

Enter the number of elements: 1

Enter element data (ID node1 node2 node3) for each element:

Format: ID node1 node2 node3

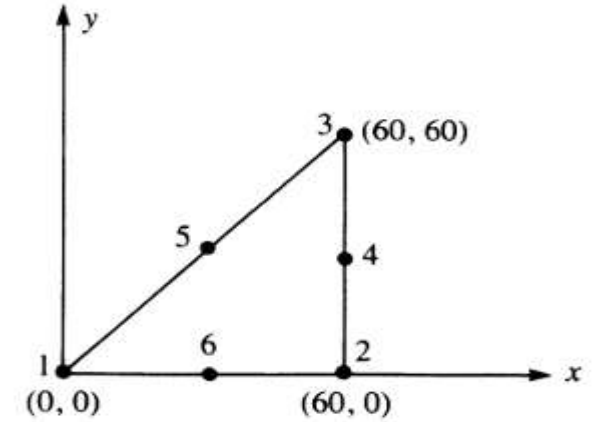
1 1 2 3

Stiffness Matrix for Element 1:

10000000.0000	5000000.0000	-8000000.0000	-6000000.0000	-2000000.0000
.0000	1000000.0000			
5000000.0000	17500000.0000	-4000000.0000	-3000000.0000	-1000000.0000
.0000	-14500000.0000			
-8000000.0000	-4000000.0000	16000000.0000	0.0000	-8000000.0000
.0000	4000000.0000			
-6000000.0000	-3000000.0000	0.0000	6000000.0000	6000000.0000
.0000	-3000000.0000			
-2000000.0000	-1000000.0000	-8000000.0000	6000000.0000	10000000.0000
.0000	-5000000.0000			
1000000.0000	-14500000.0000	4000000.0000	-3000000.0000	-5000000.0000
.0000	17500000.0000			

## DOMAIN DISCUSSIONS

Evaluating the shape functions for the linear-strain triangle shown. Then evaluate the B matrix. Units are millimeters



$$u_1 = u(0, 0) = a_1 \quad (1)$$

$$u_2 = u(60, 0) = a_1 + 60 a_2 + 3600 a_4 \quad (2)$$

$$u_3 = u(60, 60) = a_1 + 60 a_2 + 60 a_3 + 3600 a_4 + 3600 a_5 + 3600 a_6 \quad (3)$$

$$u_4 = u(60, 30) = a_1 + 60 a_2 + 30 a_3 + 3600 a_4 + 1800 a_5 + 800 a_6 \quad (4)$$

$$u_5 = u(30, 30) = a_1 + 30 a_2 + 30 a_3 + 900 a_4 + 900 a_5 + 900 a_6 \quad (5)$$

$$u_6 = u(30, 0) = a_1 + 30 a_2 + 900 a_4 \quad (6)$$

$$\text{By (1)} \Rightarrow a_1 = u_1$$

$$\text{By (2) - 2 (6)} \Rightarrow a_4 = \frac{u_2 - 2u_6 + u_1}{1800}$$

$$\text{By - (2) + 4 (6)} \Rightarrow a_2 = \frac{4u_6 - u_2 + 3u_1}{60}$$

$$\text{By 2(4) - (3)} \Rightarrow a_6 = \frac{u_2 + u_3 - 2u_4}{1800}$$

$$(4) - (5) \Rightarrow a_5 = \frac{-u_2 + u_4 - u_5 + u_6}{900}$$

$$(4) \Rightarrow a_3 = \frac{u_2 - u_3 + 4u_5 - 4u_6}{60}$$



## DOMAIN DISCUSSIONS

Can verify by substituting all  $a$ 's into Equation (3)

$$\begin{aligned}\therefore u = & u_1 + \left( \frac{4u_6 - u_2 + 3u_1}{60} \right) x + \left( \frac{u_2 - u_3 + 4u_5 - 4u_6}{60} \right) y \\ & + \left( \frac{u_2 - 2u_6 + u_1}{1800} \right) x^2 + \left( \frac{-u_2 + u_4 - u_5 + u_6}{900} \right) xy \\ & + \left( \frac{u_2 + u_3 - 2u_4}{1800} \right) y^2\end{aligned}$$

$\therefore$  Shape functions are

$$N_1 = 1 - \frac{3x}{60} + \frac{x^2}{1800} \quad (\text{From all } u_1 \text{ coefficient})$$

$$N_2 = \frac{-x}{60} + \frac{y}{60} + \frac{x^2}{1800} - \frac{xy}{900} + \frac{y^2}{1800}$$

$$N_3 = \frac{-y}{60} + \frac{y^2}{1800}$$

$$N_4 = \frac{xy}{900} - \frac{2y^2}{1800}$$

$$N_5 = \frac{4y}{60} - \frac{xy}{900}$$

$$N_6 = \frac{4x}{60} - \frac{4y}{60} - \frac{2x^2}{1800} + \frac{xy}{900}$$

$$2A = 2 \left( \frac{1}{2} \right) (60) (60) = 3600$$

$$\beta_1 = 2A \left( \frac{\partial N_1}{\partial x} \right) = 3600 \left( -\frac{3}{60} + \frac{2x}{1800} \right) = -180 + 4x$$

$$\beta_2 = 3600 \left[ -\frac{1}{60} + \frac{2x}{1800} - \frac{y}{900} \right] = -60 + 4x - 4y$$

$$\beta_3 = 0, \beta_4 = 3600 \left( \frac{y}{900} \right) = 4y$$

$$\beta_5 = 3600 \left( \frac{-y}{900} \right) = -4y$$

$$\beta_6 = 3600 \left[ \frac{4}{60} - \frac{4x}{1800} + \frac{y}{900} \right] = 240 - 8x + 4y$$

$$\gamma_1 = 2A \frac{\partial N_1}{\partial y} = 0, \gamma_5 = 3600 \left( \frac{4}{60} - \frac{x}{900} \right) = 240 - 4x$$

$$\gamma_2 = 3600 \left( \frac{1}{60} - \frac{x}{900} + \frac{2y}{1800} \right) = 60 - 4x + 4y$$

$$\gamma_3 = 3600 \left( -\frac{1}{60} + \frac{2y}{1800} \right) = -60 + 4y$$

$$\gamma_4 = 3600 \left( \frac{x}{900} - \frac{4y}{1800} \right) = 4x - 8y$$

$$\gamma_6 = 3600 \left( \frac{-4}{60} + \frac{x}{900} \right) = -240 + 4x$$

## DOMAIN DISCUSSIONS

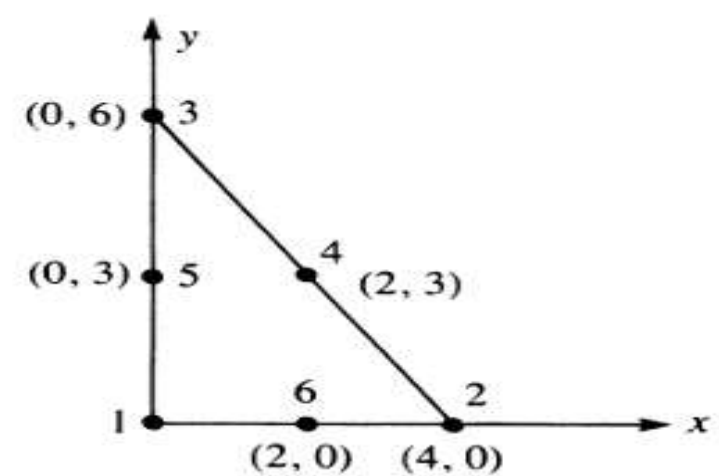
For the linear-strain elements shown in Figure P8-5, determine the strains  $\varepsilon_x$ ,  $\varepsilon_y$ , and  $\gamma_{xy}$ . Evaluate the stresses  $\sigma_x$ ,  $\sigma_y$ , and  $\tau_{xy}$  at the centroids. The coordinates of the nodes are shown in units of inches. Let  $E = 30 \times 10^6$  psi,  $\nu = 0.25$ , and  $t = 0.25$  in. for both elements. Assume plane stress conditions apply. The nodal displacements are given as

$$\begin{aligned} u_1 &= 0.0 & v_1 &= 0.0 \\ u_2 &= 0.001 \text{ in.} & v_2 &= 0.002 \text{ in.} \\ u_3 &= 0.0005 \text{ in.} & v_3 &= 0.0002 \text{ in.} \\ u_4 &= 0.0002 \text{ in.} & v_4 &= 0.0001 \text{ in.} \\ u_5 &= 0.0 & v_5 &= 0.0001 \text{ in.} \\ u_6 &= 0.0005 \text{ in.} & v_6 &= 0.001 \text{ in.} \end{aligned}$$

$$\begin{aligned} h &= 6 \text{ in.} \\ b &= 4 \text{ in.} \\ 2A &= 24 \text{ in.}^2 \\ \text{Centroid at } &\left(\frac{4}{3}, 2\right) \end{aligned}$$

$$\{\varepsilon\} = [B] \{d\}$$

$$[B] = \frac{1}{2A} \begin{bmatrix} \beta_1 & 0 & \beta_2 & 0 & \beta_3 & 0 & \beta_4 & 0 & \beta_5 & 0 & \beta_6 & 0 \\ 0 & \gamma_1 & 0 & \gamma_2 & 0 & \gamma_3 & 0 & \gamma_4 & 0 & \gamma_5 & 0 & \gamma_6 \\ \gamma_1 & \beta_1 & \gamma_2 & \beta_2 & \gamma_3 & \beta_3 & \gamma_4 & \beta_4 & \gamma_5 & \beta_5 & \gamma_6 & \beta_6 \end{bmatrix}$$



$$\beta_1 = -3h + \frac{4hx}{6} + 4y = 6x + 4y - 18$$

$$\beta_2 = -h + \frac{4hx}{6} = 6x - 6, \beta_3 = 0$$

$$\beta_4 = 4y, \beta_5 = -4y$$

$$\beta_6 = 4h - \frac{8hx}{6} - 4y = -12x - 4y + 24$$

$$\gamma_1 = -3b + 4x + \frac{4by}{h} = 4x + \frac{8}{3}y - 12$$

$$\gamma_2 = 0$$

$$\gamma_3 = -b + \frac{4by}{h} = \frac{8}{3}y - 4$$

$$\gamma_4 = 4x$$



## DOMAIN DISCUSSIONS

$$\gamma_5 = 4b - 4x - \frac{8by}{h} = -4x - \frac{16}{3}y + 16$$

$$\gamma_6 = -4x$$

$$\begin{aligned}\therefore 2A \varepsilon_x &= \beta_2 u_2 + \beta_4 u_4 + \beta_6 u_6 \\ &= 0.001 (6x - 6) + 0.0002 (4y) + 0.0005 (-12x - 4y + 24)\end{aligned}$$

$$2A \varepsilon_x = -0.0012y + 0.006$$

$$\therefore \varepsilon_x = -5 \times 10^{-5}y + 2.5 \times 10^{-4}$$

$$\begin{aligned}2A \varepsilon_y &= \gamma_3 v_3 + \gamma_4 v_4 + \gamma_5 v_5 + \gamma_6 v_6 \\ &= 0.0002 \left( \frac{8}{3}y - 4 \right) + 0.0001 (4x) + 0.0001 \left( -4x - \frac{16}{3}y + 16 \right) + 0.001 (-4x)\end{aligned}$$

$$2A \varepsilon_y = -0.004x + 0.0008$$

$$\therefore \varepsilon_y = -1.67 \times 10^{-4}x + 3.33 \times 10^{-5}$$

$$\begin{aligned}2A \gamma_{xy} &= 0.002 (6x - 6) + 0.0005 \left( \frac{8}{3}y - 4 \right) + 0.0002 (4x) + 0.0001 (4y) \\ &\quad + 0.0001 (-4y) + 0.0005 (-4x) + 0.001 (-12x - 4y + 24)\end{aligned}$$

$$2A \gamma_{xy} = -0.0012x - 0.00267y + 0.01$$

$$\therefore \gamma_{xy} = -5 \times 10^{-5}x - 1.11 \times 10^{-4}y + 4.167 \times 10^{-4}$$

Evaluate stresses at centroid

$$\{\sigma\} = [D] \{\varepsilon\}$$

$$\{\varepsilon\} \bigg|_{\left(\frac{4}{3}, 2\right)} = \begin{Bmatrix} 0.00015 \\ -1.89 \times 10^{-4} \\ 0.000128 \end{Bmatrix}$$

$$\{\sigma\} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} 1.5 \times 10^{-4} \\ -1.89 \times 10^{-4} \\ 1.28 \times 10^{-4} \end{Bmatrix}$$

$$\{\sigma\} = \begin{Bmatrix} 3288 \\ -4848 \\ 1536 \end{Bmatrix} \text{ psi}$$

$$I = \int_0^1 \int_0^1 f(s,t) ds dt \approx \sum_{i=1}^m w_i f(s_i, t_i)$$

□ where  $w_i$  = weight and  $(s_i, t_i)$  = coordinates at the integration point and  $m$  is the total number of points.

- $n$  = number of Gauss points in the  $t$  direction
- $w_i$  and  $w_j$  = Gauss weights in  $s$  and  $t$  directions
- $f(s_i, t_j)$  = value of the integrand at the point  $(s_i, t_j)$
- The total number of gauss points =  $m \times n$

Evaluate  $I = \int_{-1}^1 \int_{-1}^1 (8s^7 + 7t^6) ds dt$  using Gauss quadrature.

(i) Using 1 x 1 formula:

$$f(0,0) = 0 \quad I = 0$$

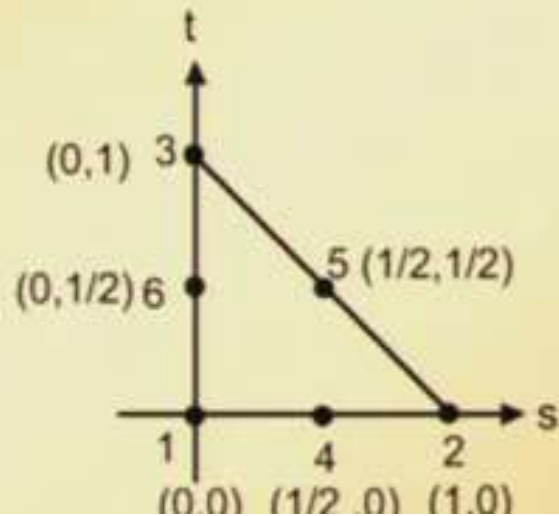
(ii) Using 2 x 2 formula

$$f(s,t) = 8s^7 + 7t^6$$

The calculations are summarized in the following table

Point	$s_i$	$t_j$	$f(s_i, t_j)$	$w_i$	$w_j$	$w_i w_j f(s_i, t_j)$
1	0.57735	-0.57735	0.43032	1	1	0.43032
2	0.57735	0.57735	0.43032	1	1	0.43032
3	-0.57735	0.57735	0.088192	1	1	0.088192
4	-0.57735	-0.57735	0.088192	1	1	0.088192
Sum						1.03703

Evaluate  $\iint_{\hat{A}} N_1^2 N_5 ds dt$  over of a quadratic triangular element shown in figure below.



One point integration:

$$I = 1/2 f(1/3, 1/3) = 0.002744$$

Three point integration:

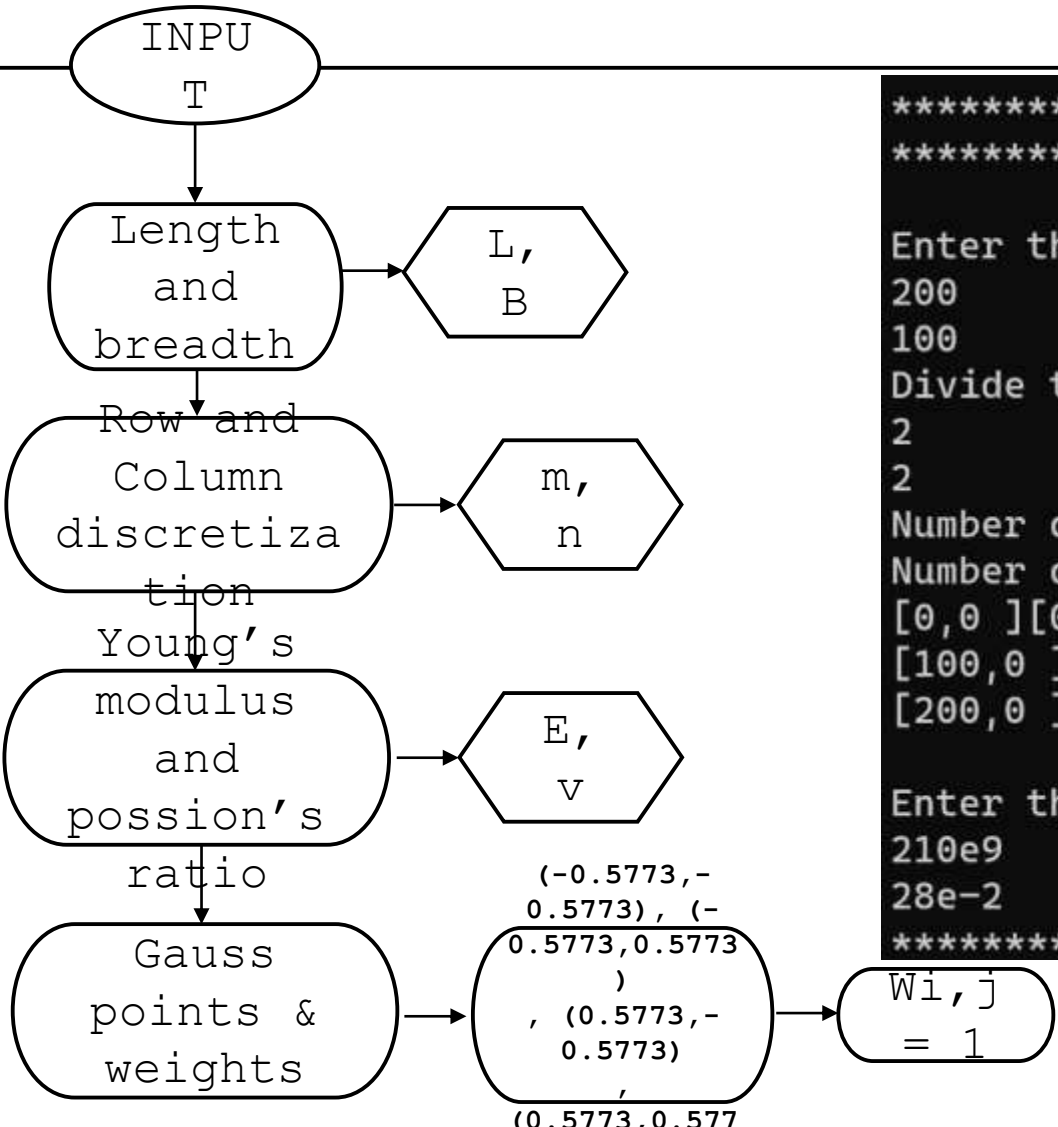
$$\begin{aligned} I &= 1/6 f(1/6, 1/6) + 1/6 f(2/3, 1/6) + 1/6 f(1/6, 2/3) \\ &= 0.0009145 + 0.0009145 + 0.0009145 = 0.002744 \end{aligned}$$

Four point integration:

$$\begin{aligned} I &= -9/32 f(1/3, 1/3) + 25/96 f(1/5, 1/5) + 25/96 f(3/5, 1/5) \\ &\quad + 25/96 f(1/5, 3/5) \\ &= -0.001543 + 0.0006 + 0.0018 + 0.0018 = 0.002657 \end{aligned}$$

It can easily be verified that the exact integral = 0.001587

# MAIN FLOW CHART ALGORITHM:

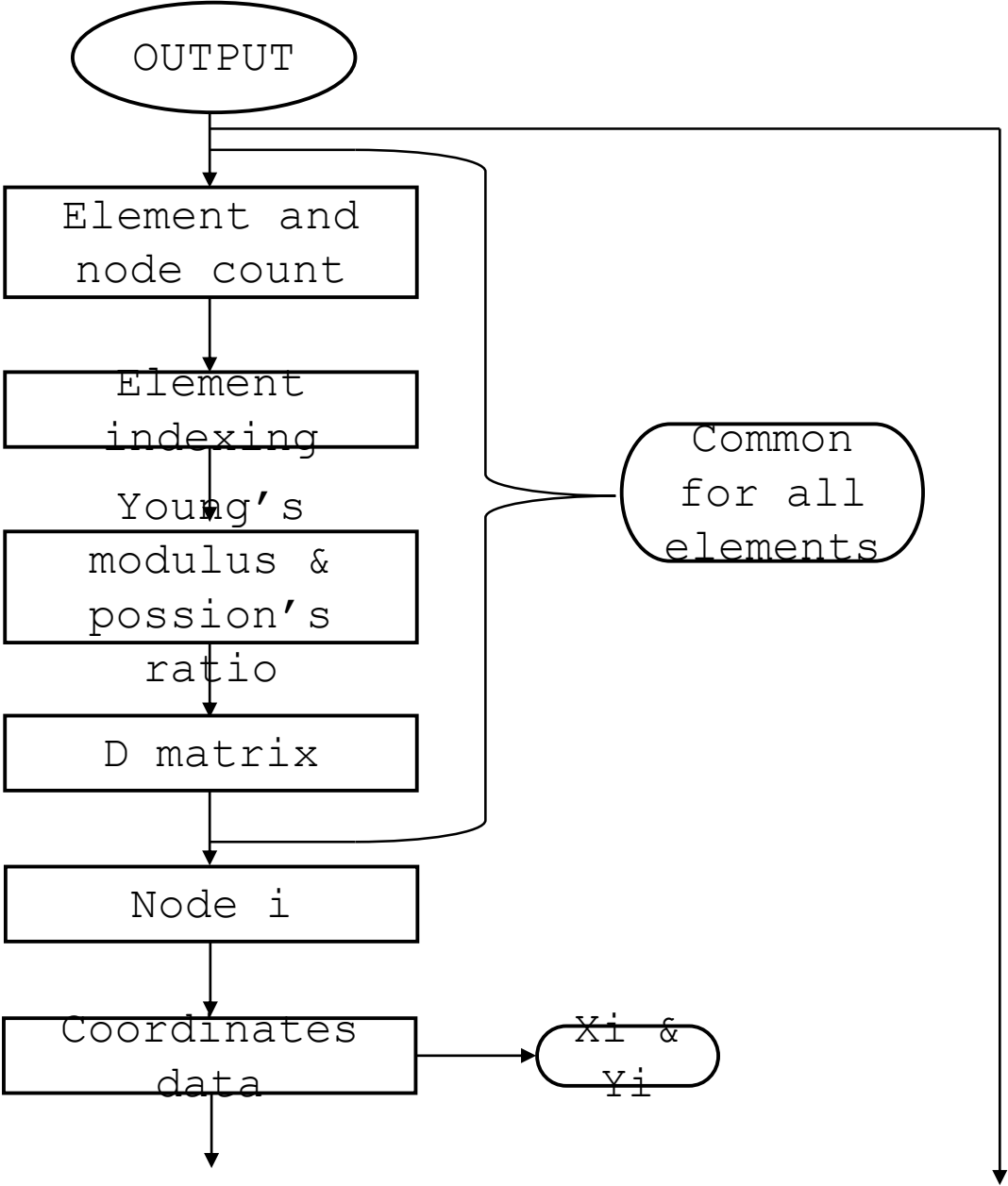


```
*****Hello Welcome to Meshing world!
*****

Enter the length and breadth of the plate.
200
100
Divide the length and breadth into column (p) and rows (m) pieces.
2
2
Number of elements present:4
Number of nodes present:9
[0,0 ][0,50 ][0,100 ]
[100,0 ][100,50 ][100,100 ]
[200,0 ][200,50 ][200,100 ]

Enter the values of E = Young's modulus and v = Poisson's ratio
210e9
28e-2
*****
```

RESULT DISCUSSION

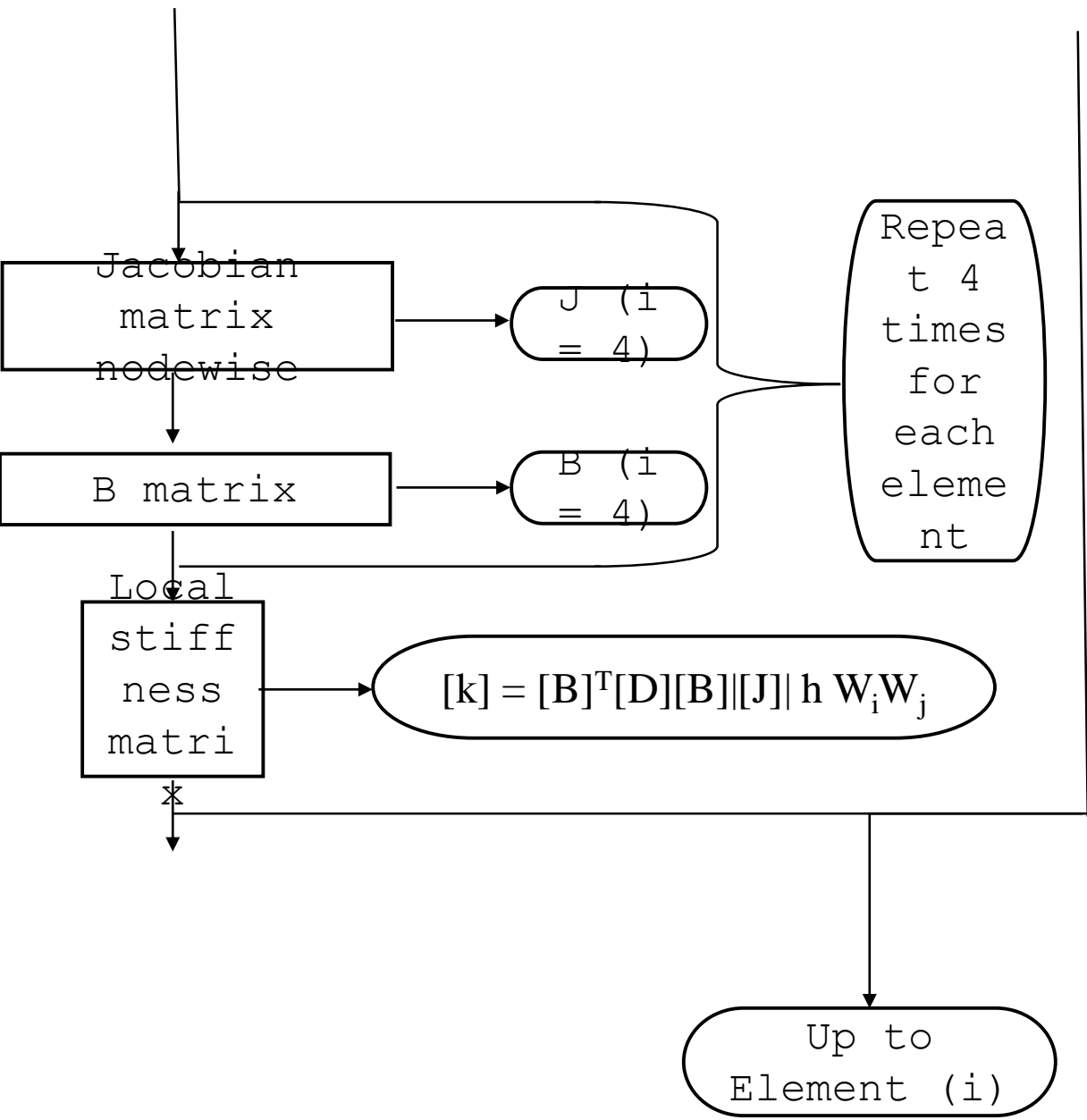


```
For Element: 1
00
10
11
01
Young's Modulus =2.1e+011
Poisson's ratio =0.28
D matrix is:
2.27865e+011    6.38021e+010    0
6.38021e+010    2.27865e+011    0
0      0      8.20312e+010
Nodes of element: 1
X Co-ordinates for 4 Nodes of element is:1
0
100
100
0

Transpose of X is Xt
0 100 100 0
Y Co-ordinate for 4 Nodes of element is:1
0
0
50
50
```



RESULT DISCUSSION



Jacobian Matrix of element:2

0	0.197163	0	-0.197163
-0.197163	0	0.0528375	0.144325
0	-0.0528375	0	0.0528375
0.197163	-0.144325	-0.0528375	0

1250

5.40325e+013	2.83449e+013	-1.35980e+013	-1.26207e+013	-1.44802e+013	-7.59615e+012	-2.59536e+013	-8.12807e+012
2.83449e+013	9.65499e+013	-8.12807e+012	1.57659e+013	-7.59615e+012	-2.58744e+013	-1.26207e+013	-8.64415e+013
-1.35980e+013	-8.12807e+012	2.44346e+013	-7.59615e+012	3.64434e+013	2.17824e+012	-1.44802e+013	1.3546e+013
-1.26207e+013	1.57659e+013	-7.59615e+012	1.43335e+013	3.38222e+012	-4.22511e+012	1.68346e+013	-2.58744e+013
-1.44802e+013	-7.59615e+012	3.64434e+013	3.38222e+012	3.88853e+012	2.83659e+012	6.95528e+012	2.17824e+012
-7.59615e+012	-2.58744e+013	2.17824e+012	-4.22511e+012	2.83659e+012	6.93406e+012	3.38222e+012	2.31654e+013
-2.59536e+013	-1.26207e+013	-1.44802e+013	1.68346e+013	6.95528e+012	3.38222e+012	3.34784e+013	-7.59615e+012
-8.12807e+012	-8.64415e+013	1.3546e+013	-2.58744e+013	2.17824e+012	2.31654e+013	-7.59615e+012	8.91504e+013

Jacobian Matrix of element:2

0	0.0528375	0.144325	-0.197163
-0.0528375	0	0.0528375	0
-0.144325	-0.0528375	0	0.197163
0.197163	0	-0.197163	0

Jacobian Matrix of element:2

1250							
3.34784e+013	7.59615e+012	6.95528e+012	-3.38222e+012	-1.44802e+013	-1.68346e+013	-2.59536e+013	1.26207e+013
7.59615e+012	8.91504e+013	-2.17824e+012	2.31654e+013	-1.3546e+013	-2.58744e+013	8.12807e+012	-8.64415e+013
6.95528e+012	-2.17824e+012	3.88853e+012	-2.83659e+012	3.64434e+013	-3.38222e+012	-1.44802e+013	7.59615e+012
-3.38222e+012	2.31654e+013	-2.83659e+012	6.93406e+012	-2.17824e+012	-4.22511e+012	7.59615e+012	-2.58744e+013
-1.44802e+013	-1.3546e+013	3.64434e+013	-2.17824e+012	2.44346e+013	7.59615e+012	-1.35980e+013	8.12807e+012
-1.68346e+013	-2.58744e+013	-3.38222e+012	-4.22511e+012	7.59615e+012	1.43335e+013	1.26207e+013	1.57659e+013
-2.59536e+013	8.12807e+012	-1.44802e+013	7.59615e+012	-1.35980e+013	1.26207e+013	5.40325e+013	-2.83449e+013
1.26207e+013	-8.64415e+013	7.59615e+012	-2.58744e+013	8.12807e+012	1.57659e+013	-2.59536e+013	9.65499e+013

Jacobian Matrix of element:2

0	0.197163	-0.144325	-0.0528375
-0.197163	0	0.197163	0
0.144325	-0.197163	0	0.0528375
0.0528375	0	-0.0528375	0

1250

2.44346e+013	7.59615e+012	-1.35980e+013	8.12807e+012	-1.44802e+013	-1.3546e+013	3.64434e+013	-2.17824e+012
7.59615e+012	1.43335e+013	1.26207e+013	1.57659e+013	-1.68346e+013	-2.58744e+013	-3.38222e+012	-4.22511e+012
-1.35980e+013	1.26207e+013	5.40325e+013	-2.83449e+013	-2.59536e+013	8.12807e+012	-1.44802e+013	7.59615e+012
8.12807e+012	1.57659e+013	-2.83449e+013	9.65499e+013	1.26207e+013	2.31654e+013	7.59615e+012	-2.58744e+013
-1.44802e+013	-1.68346e+013	-2.59536e+013	1.26207e+013	3.34784e+013	7.59615e+012	6.95528e+012	-3.38222e+012
-1.3546e+013	-2.58744e+013	8.12807e+012	-8.64415e+013	7.59615e+012	8.91504e+013	-2.17824e+012	2.31654e+013
3.64434e+013	-3.38222e+012	-1.44802e+013	7.59615e+012	6.95528e+012	-2.17824e+012	3.88853e+012	-2.83659e+012
-2.17824e+012	-4.22511e+012	7.59615e+012	-2.58744e+013	-3.38222e+012	2.31654e+013	-2.59536e+013	6.93406e+012

Jacobian Matrix of element:2

0	0.0528375	0	-0.0528375
-0.0528375	0	0.197163	-0.144325
0	-0.197163	0	0.197163
0.0528375	0.144325	-0.197163	0

1250

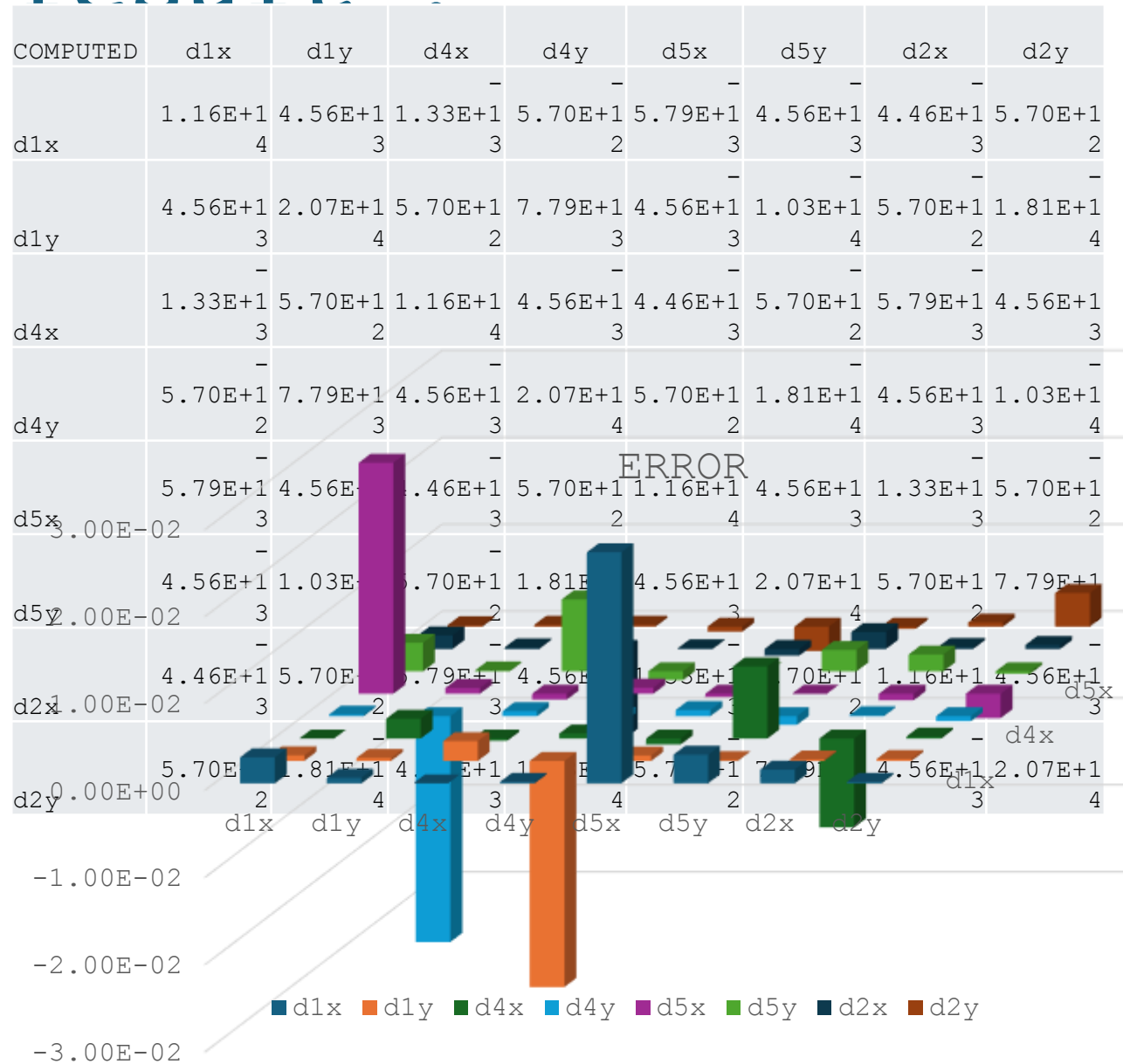
3.88853e+012	2.83659e+012	6.95528e+012	2.17824e+012	-1.44802e+013	-7.59615e+012	3.64434e+013	3.38222e+012
2.83659e+012	6.93406e+012	3.38222e+012	2.31654e+013	-7.59615e+012	-2.58744e+013	2.17824e+012	-4.22511e+012
6.95528e+012	3.38222e+012	3.34784e+013	-7.59615e+012	-1.68346e+013	-2.58744e+013	1.68346e+013	-2.58744e+013
2.17824e+012	2.31654e+013	-7.59615e+012	8.91504e+013	-8.12807e+012	-8.64415e+013	1.3546e+013	-2.58744e+013
-1.44802e+013	-7.59615e+012	-2.59536e+013	-8.12807e+012	5.40325e+013	2.83449e+013	-1.35980e+013	-1.26207e+013
-7.59615e+012	-2.58744e+013	1.26207e+013	8.64415e+013	9.65499e+013	3.38222e+012	1.57659e+013	1.57659e+013
3.64434e+013	2.17824e+012	-1.44802e+013	1.3546e+013	-1.35980e+013	-8.12807e+012	2.44346e+013	-7.59615e+012
3.38222e+012	-4.22511e+012	1.68346e+013	-2.58744e+013	-1.26207e+013	1.57659e+013	-7.59615e+012	1.43335e+013

Local stiffness matrix: 2 is

1.15826e+014	4.55729e+013	-1.32871e+013	-5.69661e+012	-5.79206e+013	-4.55729e+013	-4.46184e+013	5.69661e+012
4.55729e+013	2.86968e+014	5.69661e+012	7.78627e+013	-4.55729e+013	-1.83498e+014	-5.69661e+012	-1.81333e+014
-1.32871e+013	5.69661e+012	1.15826e+014	-4.55729e+013	-4.46184e+013	-5.69661e+012	-5.79206e+013	4.55729e+013
-5.69661e+012	7.78627e+013	-4.55729e+013	2.86968e+014	5.69661e+012	-1.81333e+014	4.55729e+013	-1.83498e+014
-5.79206e+013	-4.55729e+013	-4.46184e+013	5.69661e+012	1.15826e+014	4.55729e+013	-1.32871e+013	-5.69661e+012
-4.55729e+013	-1.83498e+014	-5.69661e+012	-1.81333e+014	4.55729e+013	2.86968e+014	5.69661e+012	7.78627e+013
-4.46184e+013	-5.69661e+012	-5.79206e+013	4.55729e+013	-1.32871e+013	5.69661e+012	1.15826e+014	-4.55729e+013
5.69661e+012	-1.81333e+014	4.55729e+013	-5.69661e+012	7.78627e+013	-4.55729e+013	2.86968e+014	5.69661e+012

Up to Element (i)

# Comparison of Computed and analytical result :



ANALYTIC	AL	d1x	d1y	d4x	d4y	d5x	d5y	d2x	d2y
d1x	1.16E+14	4.56E+13	1.33E+13	5.70E+12	5.79E+13	4.56E+13	4.46E+13	5.70E+13	5.70E+13
d1y	4.56E+13	2.07E+14	5.70E+13	7.79E+13	4.56E+13	1.03E+14	5.70E+13	1.81E+14	1.81E+14
d4x	1.33E+13	5.70E+12	1.16E+13	4.56E+12	4.46E+13	5.70E+12	5.79E+12	4.56E+12	4.56E+12
d4y	5.70E+12	7.79E+12	4.56E+12	2.07E+12	5.70E+12	1.81E+12	4.56E+12	1.03E+12	1.03E+12
d5x	5.79E+13	4.56E+13	4.46E+13	5.70E+13	1.16E+13	4.56E+13	1.33E+13	5.70E+13	5.70E+13
d5y	4.56E+13	1.03E+14	5.70E+13	1.81E+13	4.56E+13	2.07E+13	5.70E+13	7.79E+13	7.79E+13
d2x	4.46E+13	5.70E+12	5.79E+12	4.56E+12	1.33E+13	5.70E+12	1.16E+12	4.56E+12	4.56E+12
d2y	5.70E+12	1.81E+13	4.56E+12	1.03E+12	5.70E+12	7.79E+12	4.56E+12	2.07E+12	2.07E+12

- This are local stiffness matrix of element 1.
- Error =  $\frac{\text{computed result} - \text{analytical result}}{\text{analytical result}}$
- Maximum error = 2.66%
- Minimum error = 7.53e-10%
- Error might due to approximation made during the calculations.

# CONCLUSION

## Advantages over Linear Elements:

- Increased Accuracy:** Higher-order finite elements allow for better representation of the solution space, achieving the same level of accuracy as linear elements but with fewer overall elements.
- Smooth Transitions:** Utilizing higher-degree polynomial shape functions helps ensure smoother transitions across adjacent elements.
- Handling Complex Geometries:** These elements are better suited for intricate or curved boundaries and areas where changes in the material properties or forces are non-linear.

**Structural Analysis:** Higher-order finite elements are particularly valuable in structural analysis, where precision and the ability to model complex stress distributions are crucial.

**Electromagnetic Simulations:** In electromagnetic field simulations, higher-order finite elements provide significant advantages when dealing with wave propagation and field distribution problems.



CONCLUSION

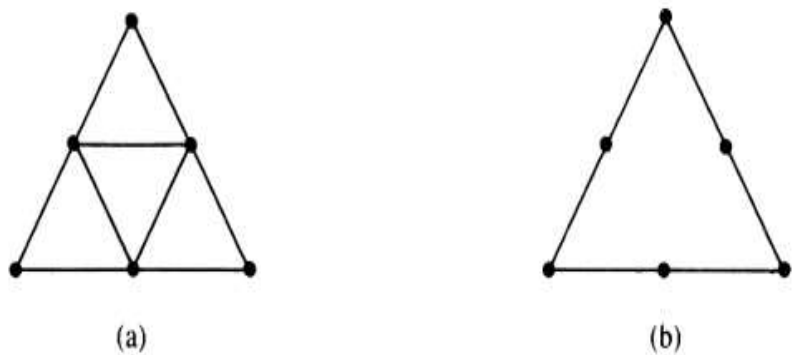


Figure 8-4 Basic triangular element: (a) four-CST and (b) one-LST

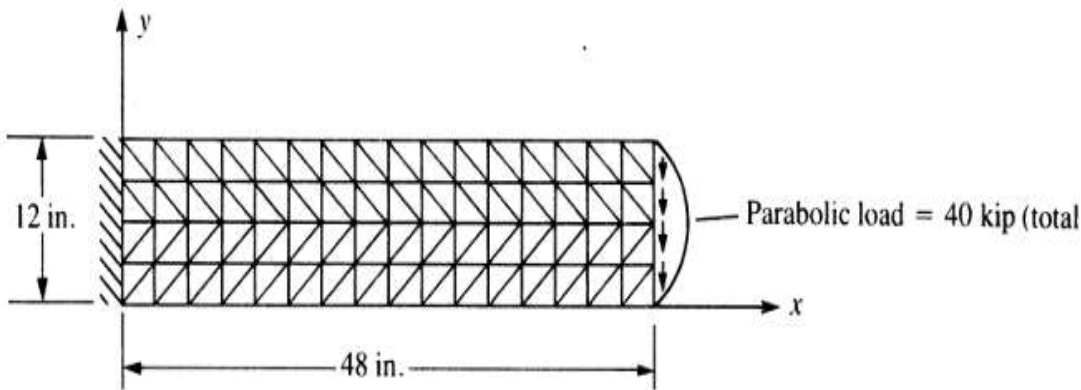
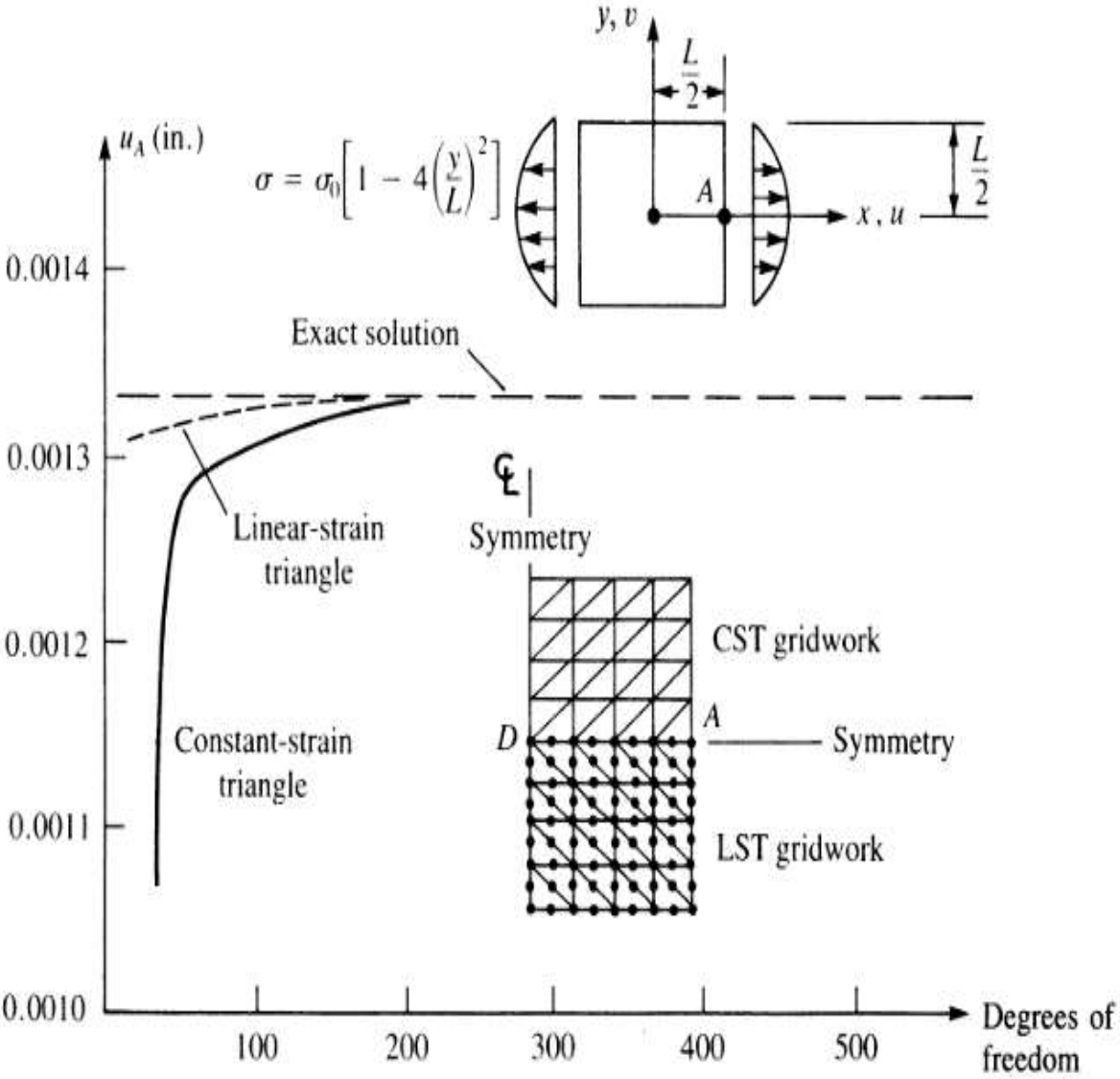


Figure 8-5 Cantilever beam used to compare the CST and LST elements with a 4 × 16 mesh



## conclusion

- HOFE incorporates polynomial basis functions of higher degrees, allowing for more precise approximations with fewer elements compared to linear or low-order methods. This results in more accurate simulations, especially in problems involving complex geometries, wave propagation, or high-gradient fields. Despite their potential, HOFE poses unique challenges such as increased computational costs, handling complex geometries, and ensuring numerical stability.

## **1. Optimization of Computational Algorithms:**

1. Development and implementation of more efficient solvers specifically designed for higher-order finite element systems to reduce computational costs.

## **2. Adaptive Mesh Refinement:**

1. Incorporating automatic mesh refinement based on error estimations to ensure that higher-order elements are selectively applied where they are most needed.

## **3. Numerical Integration Improvements**

- Investigation into more effective numerical integration schemes that can handle the increased complexity of higher-order elements without compromising accuracy.

## **4. Application to Multiphysics Problems:**

1. Extending the use of higher-order finite elements to multiphysics simulations, where interactions between different physical domains are present (e.g., fluid-structure interaction, thermal-electrical analysis).

## **5. Error Estimation and Control:**

1. Enhancement of error estimation techniques that are capable of quantifying the accuracy of higher-order finite element solution.

## **6. Software Development and Integration:**

1. Further development of user-friendly software packages that support higher-order finite elements and their integration into common finite element analysis frameworks.

# References:

- [1] Moore, J.L., Morgan, N.R. and Horstemeyer, M.F., 2019. ELEMENTS: A high-order finite element library in C++. *SoftwareX*, 10, p.100257.
- [2] Logan, D.L., 2016. *A first course in the finite element method*. Cengage Learning.
- [3] Krishnamoorthy, C.S., 1994. *Finite element analysis: theory and programming*. Tata McGraw-Hill Education.
- [4] Ergatoudis, I.R.O.N.S., Irons, B.M. and Zienkiewicz, O.C., 1968. Curved, isoparametric, “quadrilateral” elements for finite element analysis. *International journal of solids and structures*, 4(1), pp.31-42.
- [5] Dasgupta, G., 2008. Stiffness matrices of isoparametric four-node finite elements by exact analytical integration. *Journal of Aerospace Engineering*, 21(2), pp.45-50..
- [6] Tran, D.B. and Navrátil, J., 2022. Shear Lag Analysis due to Flexure of Prismatic Beams with Arbitrary Cross-Sections by FEM. *Periodica Polytechnica Civil Engineering*, 66(1), pp.244-255.
- [7] Odunfa, K.M. and Akinmolayan, O.P., Development of an Interactive Finite Element Solution Module for 2d Stress Problem Analysis Using Isoparametric Element.
- [8] Perumal, L. and Mon, D.T.T., 2011. Finite elements for engineering analysis: a brief review. In *Proceedings of the International Conference on Modeling, Simulation and Control, Singapore*.

# Project work with Tentative Experimental / Theoretical Framework:

Activities	Tentative workplan
<ul style="list-style-type: none"><li>• Study the finite elements and methods.</li></ul>	June – July
<ul style="list-style-type: none"><li>• Formulation of Higher order elements .</li><li>• Implementation of C++ for efficient solution of complex geometry.</li></ul>	August – December
<ul style="list-style-type: none"><li>• Using FEA software to analyse the complex geometry and effective,fast and correct solution.</li><li>• Validation of the both stress result coming from the FEA software and the developed C++ program.</li></ul>	January-February
<ul style="list-style-type: none"><li>• Initialization of thesis writing.</li></ul>	March - April

THANK

YOU

```

D for plane stress
(3x3)std::vector<std::vector<double>>
computeDMatrix(double E, double nu) {
double coeff = E / (1.0 - nu * nu);
std::vector<std::vector<double>> D(3,
std::vector<double>(3, 0.0));
D[0][0] = 1.0;      D[0][1] = nu;      D[1][0]
= nu;      D[1][1] = 1.0;      D[2][2] = (1.0 -
nu) / 2.0;      for(int i=0;i<3;i++) {
for(int j=0;j<3;j++) {      D[i][j]
*= coeff;      }      }      return D;}//
Function to transpose a
matrixstd::vector<std::vector<double>>
transposeMatrix(const
std::vector<std::vector<double>>& mat) {
if(mat.empty()) return {};      int rows =
mat.size();      int cols = mat[0].size();
std::vector<std::vector<double>>
trans(cols, std::vector<double>(rows,
0.0));      for(int i=0;i<rows;i++) {
for(int j=0;j<cols;j++) {
trans[j][i] = mat[i][j];      }      }
return trans;}// Function to multiply two
matricesstd::vector<std::vector<double>>
multiplyMatrices(const

```