

ECE291

Lecture 14

Protected mode

Lecture outline

- Real mode review
- Protected mode theory
- Differences
- Protected mode examples

Real Mode Addressing

- Up to 1Mb of addressable memory. Address is always computed by **<segment:displacement>** where each of the two can be 16-bits.
- Segment register is always extended with a 0H at the right end.
- Thus up to 20 bits of address => 1Mb of memory
- Segments are always 64Kb

16-bit Default Segment + Offset address combinations:

Segment	Offset	Special Purpose
CS	IP	Instruction address
SS	SP or BP	Stack address
DS	BX, DI, SI, an 8- or 16-bit number	Data address
ES	DI for string ops	String destination address

Real Mode

32-bit Default Segment + Offset address combinations:

Segment	Offset	Special Purpose
CS	EIP	Instruction address
SS	ESP or EBP	Stack address
DS	EBX, EDI, ESI, EAX, ECX, EDX, an 8- or 32-bit number	Data address
ES	DI for string ops	String destination address
FS	No default	General address (386+)
GS	No default	General address (386+)

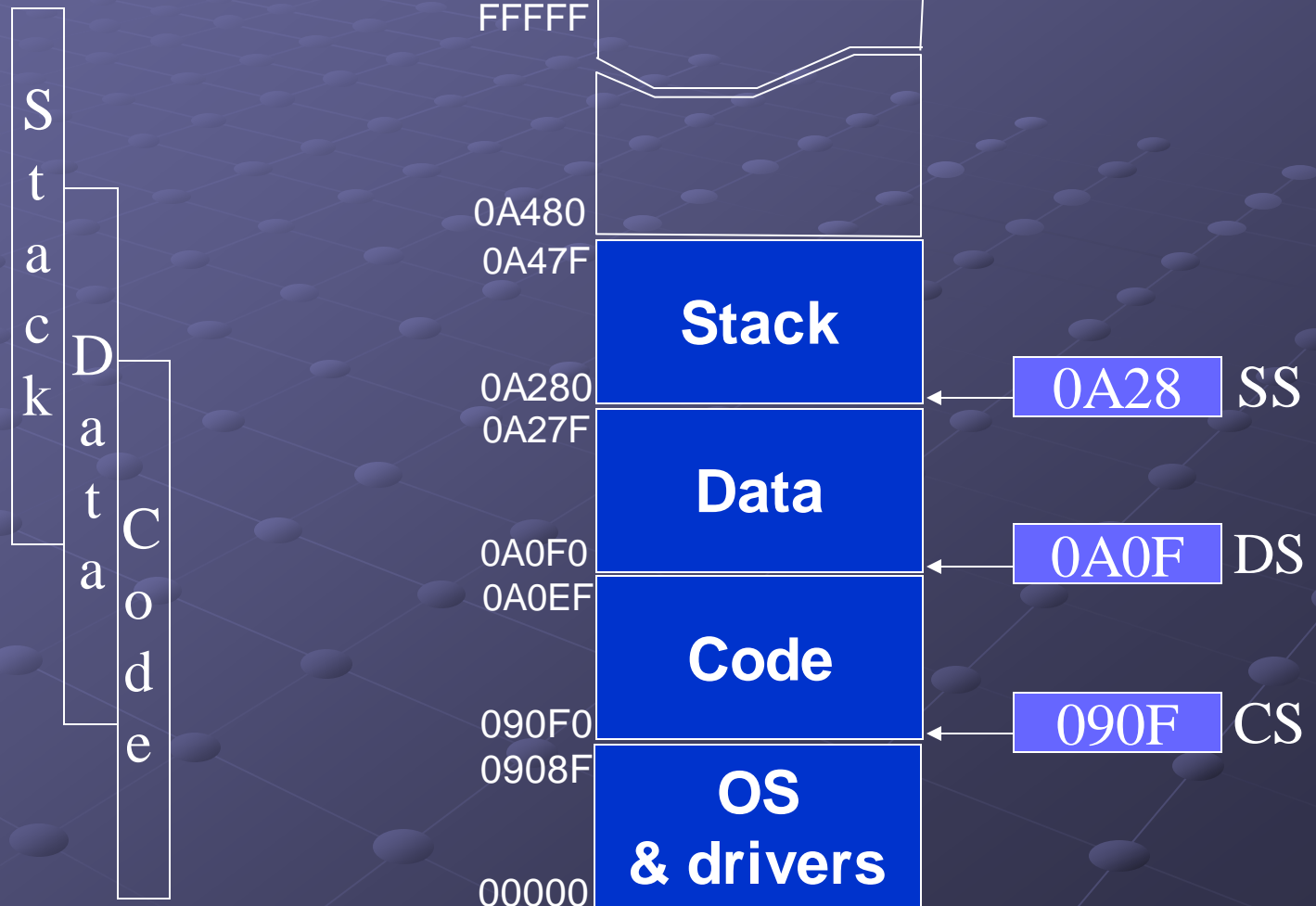
- In 386-Pentium III, never place a number $> \text{FFFFH}$ in an offset register when operating in real mode.
- This causes the system to halt and to indicate an addressing error

Real Mode (cont.)

- Up to four 64Kb-segments for $< \text{x286}$
- Up to six segments for $\geq \text{x386}$
- Program can use any arbitrary number of segments but only four/six can be addressed simultaneously at any given time
- If a user segment does not use all 64Kb of memory segment registers can be initialized so that segments can **overlap** - it's your responsibility to assure the overlap does not create unwanted side-effects!
- DOS or any other OS is responsible for linking and loading a user program, figuring out the code-data-stack segments, dynamic data area, and initializing the corresponding segment registers.

Overlapping Segments

Conceptual overlap



Real Mode (cont.)

- Segment registers allow programs to be written using only offset address and still be relocated anywhere in memory: all we need to do to move a code/data/stack segment is to change the corresponding segment register - all offset addresses remain same.
- Relocation of code and data is very important for:
 - up/downward compatibility
 - write programs without being concerned about the memory size of the particular machine they execute on
 - moving programs around in memory and allowing multiple programs to run simultaneously
- Segment registers are used to address memory in Real Mode only.
- The result is similar to Virtual Memory (in ECE 312)

Protected Mode

- In protected mode (where memory is much larger) we have yet another indirection
- Segment registers no longer point directly to memory - they point to descriptors which then point to the beginning of a segment in memory
- The **drawback** is a more expensive address translation mechanism
- But the **benefit** is that we can relocate any segment anywhere in 4Gb space, customize access rights to each segment, share segments with different programs/applications, etc.
- **NOTE:** Protected mode does NOT require any change in the application either (unless you customize protection rights) since the indirection is handled automatically by the linker/loader.

Protected Mode: General

- In PM, segment registers point to descriptor tables (DT) - which then give us the starting address of the segment
- Each DT contains 8K (8,192) descriptors where each descriptor is an 8-byte quantity that describes a memory segment. There are two DTs:
 - Global (or system) descriptor table
 - Local (or application) descriptor table
- Therefore we have up to 16K (2 x 8192) memory segments that can be addressed in PM by each application.
- Each DT resides in memory and takes up a maximum of 64Kb of memory (8B x 8K).

Format of Descriptors in PM

80286 Descriptor

00000000	00000000
Access rights	Base(B23-B16)
Base (B15-B0)	
Limit (L15-L0)	

386-Pentium III Descriptor

Base B31-B24	G	D	0	A V	Limit L19-L16
Access rights	Base(B23-B16)				
Base (B15-B0)					
Limit (L15-L0)					

- Base is the base address of segment in memory
 - in x286 it is 24-bits;
 - in x386+ it can be 32-bits. (Smallest memory granularity is 4Kb so in x386+, least significant 12 bits can be ignored in Base => 20+12=32 bit addresses)
- Limit is the last offset in a segment
 - i.e. variable size segments in PM. In x286 limit is 16-bits bit in x386+ it is 20bits.
- Examples:
 - x286: segment begins at F00000H and ends at F000FFH => it has base F00000H and has a limit of 00FFH (16 bits).
 - x386: same segment would begin at 00F00000H and will have a limit of 000FFH (20 bits)

PM: Descriptor Format

386-Pentium III Descriptor

G - granularity bit: Specifies the size of segment increments:

Base B31-B24	G	D	0	A V	Limit L19-L16
Access rights	Base(B23-B16)				
Base (B15-B0)					
Limit (L15-L0)					

- G=0 => Limit specifies a segment limit of 00000H to FFFFFH

- G=1 => Limit specifies a segment limit of 00000XXXH to FFFFFXXXH

(G=1 allows a segment length of 4Kb-4Gb in increments of 4Kb)

Example 1: Starting Address = 10000000h Segment Size = 1FFh
 G = 0, Base = 10000000h, Limit = 001FFh
 Ending Address = Base+Limit=10000000h + 001FFh = 100001FFh

Example 2: Starting Address = 10000000h Segment Size = 1FF000
 G = 1
 End = Base + Limit = 10000000h + 001FFXXXh = 101FFFFFFh

The extension XXX can take any value from 000 to FFF

PM: Descriptor Format (cont.)

386-Pentium III Descriptor

Base B31-B24	G	D	0	A V	Limit L19-L16
Access rights	Base(B23-B16)				
Base (B15-B0)					
Limit (L15-L0)					

AV-bit: Specifies whether the segment is available or not.

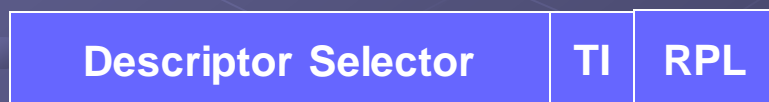
D-bit: Specifies how memory is accessed in RM or PM

- **D=0** => Default: 16-bit instructions, offsets and registers
- **D=1** => Default: 32-bit instructions, offsets and registers

NOTE: The default of register size and offset size can be overridden in both 16- and 32-bit instruction modes.

Access Rights byte: Specifies access rights, access violation actions, direction of growth (for data segments) - e.g., shared code segments

Segment Register in PM:



RPL=requested privilege level
(00-highest, 11-lowest)

TI=0 => Global descriptor table
TI=1 => Local descriptor table

Selects one of 8,192 descriptors in global or local description tables

DPMI

● The Dos Protected Mode Interface

- Windows 2000 runs in PMode and encapsulates your programs so they can't crash the computer (theoretically)
- This encapsulation prevents direct access to some of the processor's protected mode capabilities
- DPMI is a standard way to access these capabilities outside the box while still having Windows provide some protection

DPMI

- DPMI is accessed via INT 31h
- See the DPMI reference on the References Page for great detail
- For most things you will use our special Protected Mode Library
- One of the ints you'll use directly involves invoking DOS interrupts in PMode. This is function 300h.
- Function 300h is used to call any ISR which accesses memory

How to write PMode Programs

; Simple Real Mode Program

```
STKSEG SEGMENT STACK
RESB 512
STKTOP
```

```
SEGMENT CODE
    myvar1 db 45h
    myvar2 resb 1
..start
    mov ax, cs
    mov ds, ax

    ret
```

; Simple Protected Mode Program

```
SECTION .data
    myvar1 db 45h
```

```
SECTION .bss
    myvar2 resb 1
```

```
SECTION .text
GLOBAL _main
_main
    ret
```

Other differences – program structure

- SECTION is essentially the same as SEGMENT
- .data contains initialized variables
- .bss contains uninitialized variables that take up no space in your executable but get allocated and initialized to zero when your program executes
- .text is the same as CODE
- `_main` must be declared global and serves the same purpose as `..start`
- All offsets change from 16 bit to 32 bit

Other differences - addressing

- Memory addressing now uses extended registers EBX, EBP, ESI, EDI instead of the 16 bit equivalents
- You can *also* use **any** 32-bit register to address memory (including EAX, ECX, EDX, ESP)
- Add *any* two of these registers
- One may be multiplied by a scaling factor of 1, 2, 4, or 8.
 - `mov ax, [disp]`
 - `mov ax, [eax + disp]`
 - `mov ax, [eax + 4*ebp + disp]` ;defaults to DS
 - `mov ax, [ebp + 4*eax + disp]` ;defaults to SS

Example MMX Program

```
GLOBAL _main
```

```
SECTION .bss ;=====
```

```
; Uninitialized data
```

```
SECTION .data ;=====
```

```
Array_1 db 01h, 02h, 03h, 04h, 05h, 06h, 07h, 08h  
          db 01h, 01h, 01h, 01h, 01h, 01h, 01h, 01h  
          db 08h, 09h, 0Ah, 0Bh, 0Ch, 0Dh, 0Eh, 0Fh
```

```
Array_2 db 09h, 09h, 09h, 09h, 09h, 09h, 09h, 09h  
          db 00h, 01h, 02h, 03h, 04h, 05h, 06h, 07h  
          db 80h, 90h, 0A0h, 0B0h, 0C0h, 0D0h, 0E0h, 0F0h
```

```
ClearMMX dd 00h, 00h
```


Example MMX Program

```
SECTION .text ;=====
```

```
_main
```

```
mov ebx, Array_1
mov edx, Array_2
mov ecx, 3
```

```
call _MMX_Reset ;Reset MMX registers to zero
```

```
.Add_Array
```

```
movq mm0, [ebx+8*ecx-8]
paddb mm0, [edx+8*ecx-8]
movq qword [edx+8*ecx-8], mm0 ;Store the sum
movq mm1, [edx+8*ecx-8]
dec ecx
cmp ecx, 0
ja .Add_Array
;loop .Add_Array
```

```
movq mm5, [Array_2] ;Move sums to MMX
movq mm6, [Array_2+8]
movq mm7, [Array_2+16]
emms
ret
```

```
_MMX_Reset
```

```
movq mm0, [ClearMMX]
movq mm1, mm0
movq mm2, mm0
movq mm3, mm0
movq mm4, mm0
movq mm5, mm0
movq mm6, mm0
movq mm7, mm0
ret
```