

Pragmatic Multithreaded C++

High or Low level solution ?

- **First choice – high level structure and tools**
- Pros:
 - Quick results
 - Practical problem identification
 - (Typically) Better readability and portability
 - Quick pattern implementation
 - Better separation of responsibilities
- Cons:
 - Maybe not enough performance (measure it)
 - The wrong tool/structure/pattern/containerf/... for the problem
 - Threads oversubscription
 - Destroy without calling get()

std::async – context of use

- For:
 - Simple background tasks
 - Return result at end (job like)
 - Easy, traceability
 - Low thread execution control
- Not for:
 - Inter-thread synchronization
 - Shared data
 - Thread count control

***Before we talk about
std::async, what does it
return?***

`std::future<...>`

- Non-copyable – move semantics
- No thread safety! - one thread `get()`
- Moved data – `MoveConstructible`
- `.get()` - move data
- `.valid()` return false after move (one-shoot move)
- Need MOVE to ONE thread

`std::shared_future<...>`

- Copyable
- Thread safety! - many `get()`
- Copied data – CopyConstructible
- `.get()` - return const ref
- `.valid()` return „permanent true” (if `shared_future` copy)
- Need COPY to MANY thread

`std::*future<...> state`

- States:
 - `future_status::deferred` – lazy execution
 - `future_status::ready` – result ready
 - `future_status::timeout` – under calculation...
- Get by `.wait*()` call

Back to the `std::async(...)`

- Launch policy (BitMaskType):
 - `std::launch::deferred` – lazy (after `.get()`) run in current thread
 - `std::launch::async` – run on different thread
 - `std::launch::default` – (*not specified*), implementation specified

`std::launch::default == std::launch::deferred | std::launch::async`

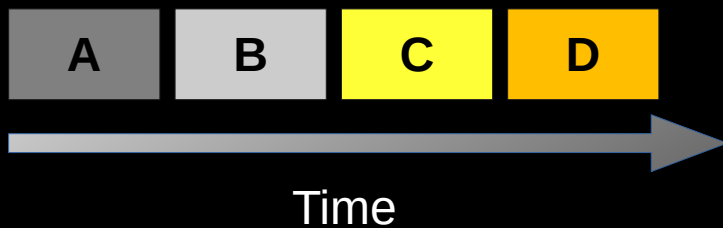
- Arguments:
 - Callable object – function, lambda, functional object
 - Args to call – Copyable (if ref, `std::ref(...)`)

std::async(...) - oversubscription

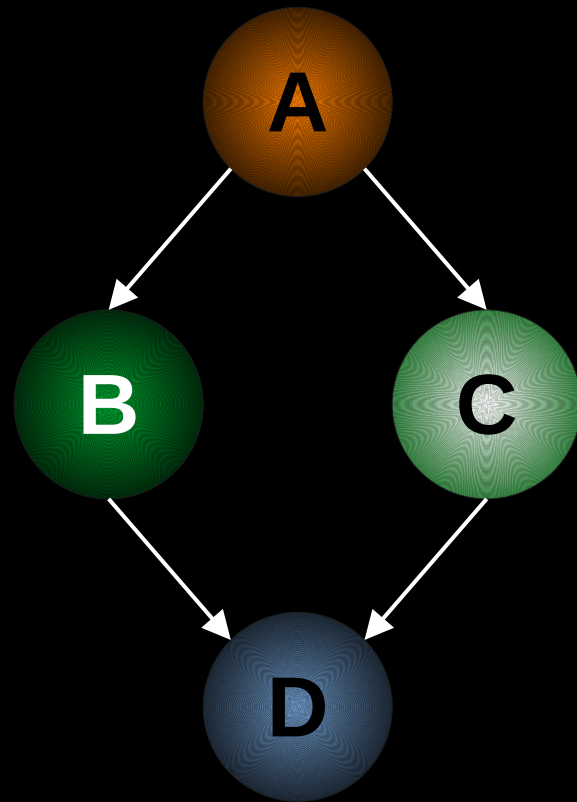
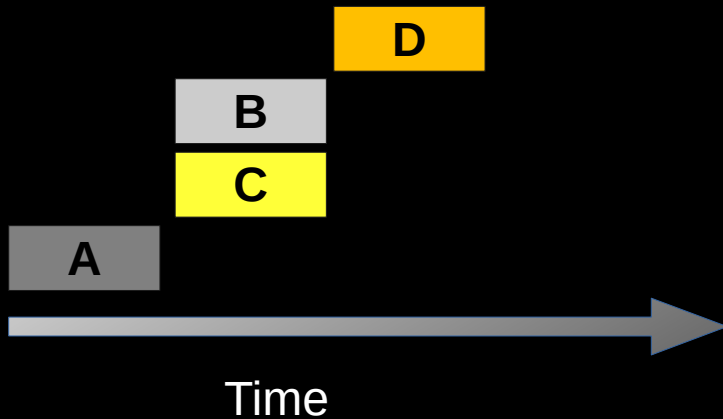
- I/O – not so dangerous...
 - os classifies them correctly (i/o intensive process/thread)
 - waiting threads, sleeping (no cpu consumption)
 - natural barrier: bandwidth/latency
- Computational – not recommended
 - scheduler overload
 - easy full system utilize
 - dangerous for one core systems

std::async graph?

- `std::launch::deferred`



- `std::launch::async`



async_graph.cpp

std::async – in practice

- Pros:

- Simple
- Work controller
- Containerization possible (via future)
- Simple async synchronization
- Easy progress control (future)

- Cons:

- Difficult intra-dependency
- Start control? ... no...
- Implicit dependencies between executions
- Imprecise progress control
- Easy oversubscription