Linear Algebra

1 Determinant

1.1 Expansion formula

For any $A \subseteq \mathcal{Y}$,

$$\sum_{A \subseteq Y \subseteq \mathcal{Y}} \det(\mathbf{L}_Y) = \det(\mathbf{L} + \mathbf{I}_{\bar{A}}), \tag{1.1}$$

1.2 Rearrangement

$$\sum_{(I',J')\in\mathcal{S}(I,J)} \det(\mathbf{Z}_{Y,I'}) \det(\mathbf{Z}_{Y,J'}) \le \sum_{(I',*)\in\mathcal{S}(I,j)} \det(\mathbf{Z}_{Y,I'})^2$$
(1.2)

where $I_{\bar{A}}$ is the diagonal matrix with ones in the diagonal positions with indices in \bar{A} and zeros elsewhere.

1.3 Weinstein-Aronszajin identity

If \boldsymbol{A} and \boldsymbol{B} are matrices of size $m \times n$ and $n \times m$ respectively, given that \boldsymbol{AB} is of trass class, then

$$\det(\mathbf{I} + \mathbf{A}\mathbf{B}) = \det(\mathbf{I} + \mathbf{B}\mathbf{A}) \tag{1.3}$$

1.4 DPP related

1.4.1 Propsosal matrix for NDPP

Given V, B, D such that $L = VV^{\top} + B(D - D^{\top})B^{\top}$, let $\{\rho_i, v_i\}_{i=1}^K$ be the eigendecomposition of VV^{\top} and $\{(\sigma_j, y_{2j-1}, y_{2j})\}$ be the Youla decomposition of $B(D - D^{\top})B^{\top}$. Denote $Z := [v_1, \dots, v_K, y_1, \dots, y_K] \in \mathbb{R}^{M \times 2K}$ and

$$\begin{split} \boldsymbol{X} &:= \operatorname{diag} \left(\rho, \dots, \rho_K, \begin{bmatrix} 0 & \sigma_1 \\ -\sigma_1 & 0 \end{bmatrix}, \dots \begin{bmatrix} 0 & \sigma_{K/2} \\ -\sigma_{K/2} & 0 \end{bmatrix} \right), \\ \hat{\boldsymbol{X}} &:= \operatorname{diag} \left(\rho, \dots, \rho_K, \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_1 \end{bmatrix}, \dots \begin{bmatrix} \sigma_{K/2} & 0 \\ 0 & \sigma_{K/2} \end{bmatrix} \right), \end{split}$$

so that $L = ZXZ^{\top}$ and $\hat{L} = Z\hat{X}Z^{\top}$. Then, for every subset $Y \subseteq [M]$, it holds that

$$\det(\mathbf{L}_Y) \le \det(\hat{\mathbf{L}}_Y) \tag{1.4}$$

and the equality holds when the size of Y is equal to the rank of L.

1.4.2 Propsosal matrix for NDPP II

Given $\boldsymbol{X} \in \mathbb{R}^{n \times d}$ and $\boldsymbol{W}^A \in \mathbb{R}^{d \times d}$ Then,

$$\det([\boldsymbol{X}\boldsymbol{W}^{A}\boldsymbol{X}^{\top}]_{S}) \leq \det([\boldsymbol{X}\hat{\boldsymbol{W}}^{A}\boldsymbol{X}^{\top}]_{S})$$
(1.5)

for every $S \subseteq [n]$. In addition, equality holds when $|S| \geq d$.

1.4.3 DPP probability expansion

$$\mathbb{P}_{\hat{\boldsymbol{L}}}(Y) = \frac{\det(\hat{\boldsymbol{L}}_Y)}{\det(\hat{\boldsymbol{L}} + \boldsymbol{I})} = \sum_{E \subseteq [2K], |E| = |Y|} \det(\underbrace{\boldsymbol{Z}_{Y,E} \boldsymbol{Z}_{Y,E}^{\top}}_{\text{elementary DPP}}) \prod_{i \in E} \frac{\lambda_i}{\lambda_i + 1} \prod_{i \notin E} \frac{1}{\lambda_i + 1}$$
(1.6)

- 1. Choose an elementary DPP according to its mixture weight
- 2. Sample a subset from the selected elementary DPP

1.4.4 DPP probability expansion II

The probability of sampling $S \in \binom{n}{k}$ from the k-DPP with $\hat{\boldsymbol{L}}$ can be decomposed into the following

$$\frac{\det(\hat{\boldsymbol{L}}_S)}{e_k(\{\lambda_i\}_{i=1}^d)} = \sum_{E \in {[d] \choose k}} \frac{\prod_{i \in E} \lambda_i}{e_k(\{\lambda_i\}_{i=1}^d)} \cdot \det(\boldsymbol{K}_S^E)$$
(1.7)

where K^E is a rank-k projection matrix consisting of eigenvalues of \hat{L} .

1.5 Ratio

Given that $\det(\mathbf{Q}\mathbf{S}\mathbf{Q}^{\top}) \neq 0$

$$\frac{\det(\boldsymbol{Q}(\boldsymbol{S}+\boldsymbol{R})\boldsymbol{Q}^{\top})}{\det(\boldsymbol{Q}\boldsymbol{S}\boldsymbol{Q}^{\top})} \leq \det(\boldsymbol{I}_{2} + (\boldsymbol{Q}\boldsymbol{S}\boldsymbol{Q}^{\top})^{-1/2}\boldsymbol{Q}\boldsymbol{R}\boldsymbol{Q}^{\top}(\boldsymbol{Q}\boldsymbol{S}\boldsymbol{Q}^{\top})^{-1/2})$$
(1.8)

1.6 Inverse of trace

For an invertible matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$,

$$\operatorname{tr}(\boldsymbol{A}^{-1}) = \sum_{i=1}^{n} \det(\boldsymbol{A}_{-i}) / \det(\boldsymbol{A}), \tag{1.9}$$

where $A_{-i} \in \mathbb{R}^{n-1 \times n-1}$ is the submatrix of A where the ith row and column of A are removed.

2 Vectorziation

$$\operatorname{vec}(\boldsymbol{A}\boldsymbol{X}\boldsymbol{B}) = (\boldsymbol{B}^{\top} \otimes \boldsymbol{A})\operatorname{vec}(\boldsymbol{X}) \tag{2.1}$$

Lyapunov Equation.

$$AX + XB = C (2.2)$$

$$AXI + IXB = C (2.3)$$

$$(I \otimes A)\operatorname{vec}(X) + (B^{\top} \otimes I)\operatorname{vec}(X) = \operatorname{vec}(C)$$
 (2.4)

$$\operatorname{vec}(\boldsymbol{X}) = (\boldsymbol{I} \otimes \boldsymbol{A} + \boldsymbol{B}^{\top} \otimes \boldsymbol{I})^{-1} \operatorname{vec}(\boldsymbol{C})$$
 (2.5)

3 Trace

$$\operatorname{tr}(\boldsymbol{A}\boldsymbol{B}\boldsymbol{C}) = \operatorname{vec}(\boldsymbol{A}^{\top})^{\top}(\boldsymbol{I} \otimes \boldsymbol{B})\operatorname{vec}(\boldsymbol{C})$$
(3.1)

$$\operatorname{tr}(\boldsymbol{A}^{\top}\boldsymbol{B}\boldsymbol{C}\boldsymbol{D}^{\top}) = \operatorname{vec}(\boldsymbol{A})^{\top}(\boldsymbol{D}\otimes\boldsymbol{B})\operatorname{vec}(\boldsymbol{C})$$
(3.2)

3.1 Von Neumann's trace inequality

Theorem 3.1. If A, B are complex $n \times n$ matrices with singular values

$$\alpha_1 \ge \dots \ge \alpha_n, \quad \beta_1 \ge \dots \beta_n,$$
 (3.3)

respectively, then

$$|\operatorname{tr}(\boldsymbol{A}\boldsymbol{B})| \le \sum_{i=1}^{n} \alpha_i \beta_i$$
 (3.4)

4 Inversion

4.1 Woodbury identity

$$[A + BCD]^{-1} = A^{-1} - A^{-1}B[C^{-1} + DA^{-1}B]^{-1}DA^{-1}$$
(4.1)

given that $m{A}^{-1}$ and $m{C}^{-1}$ exist. If $m{B} = m{x}, m{C} = m{I}, m{D} = m{y}^{ op}$

$$(\mathbf{A} + \mathbf{x}\mathbf{y}^{\top})^{-1} = \mathbf{A}^{-1} - \frac{(\mathbf{A}^{-1}\mathbf{x})(\mathbf{y}\mathbf{A}^{-1})}{1 + \mathbf{y}^{\top}\mathbf{A}^{-1}\mathbf{x}}$$
 (4.2)

4.2 Schur Complement

Schur Complement essentially is a block Cholesky factorization of a matrix

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} I & BD^{-1} \\ 0 & I \end{bmatrix} \begin{bmatrix} (A - BD^{-1}C) & 0 \\ 0 & D \end{bmatrix} \begin{bmatrix} I & 0 \\ D^{-1}C & I \end{bmatrix}$$
(4.3)

 $A - BD^{-1}A$ is called the Schur complement of D.

5 Hadamard Product

5.1 Quadratic Relation

$$\boldsymbol{x}^{\top} (\boldsymbol{A} \odot \boldsymbol{B}) \boldsymbol{y} = \operatorname{tr} \left(\operatorname{Diag}(\boldsymbol{x}) \boldsymbol{A} \operatorname{Diag}(\boldsymbol{y}) \boldsymbol{B}^{\top} \right)$$
 (5.1)

By setting x = y, it shows that the Hadamard product of two PSD matrices is PSD.

5.2 Rank Relation

$$rank(\mathbf{A} \odot \mathbf{B}) \le rank(\mathbf{A})rank(\mathbf{B}) \tag{5.2}$$

5.3 Spectrum Relation

$$\prod_{i=k}^{n} \lambda_i(\mathbf{A} \odot \mathbf{B}) \ge \prod_{i=k}^{n} \lambda_i(\mathbf{A}\mathbf{B}), \ \forall k = 1, \dots, n$$
(5.3)

with $\lambda_i(\cdot)$ denotes PD matrix.

5.4 Determinant

$$|\mathbf{A} \odot \mathbf{B}| \ge |\mathbf{A}| |\mathbf{B}| \tag{5.4}$$

6 Matrix Calculus

6.1 Matrix Chain rule

$$[\nabla_{\mathbf{X}} f(g(\mathbf{X}))]_{ij} = \sum_{k=1}^{p} \sum_{\ell=1}^{q} \frac{\partial f(G)}{\partial g_{k\ell}} \frac{\partial g_{k\ell}}{x_{ij}}$$

$$\tag{6.1}$$

Differentials 6.2

$$d(\operatorname{tr} \boldsymbol{X}) = \operatorname{tr} d\boldsymbol{X} \tag{6.2}$$

$$d(X \otimes Y) = (dX) \otimes Y + X \otimes (dY)$$
(6.3)

$$d\mathbf{X}^{-1} = -\mathbf{X}^{-1} \cdot d\mathbf{X} \cdot \mathbf{X}^{-1} \tag{6.4}$$

$$d(\det(\boldsymbol{X})) = tr(\operatorname{adj}(\boldsymbol{X}) d\boldsymbol{X})$$
(6.5)

$$d \det(\mathbf{X}) = \det(\mathbf{X}) \operatorname{tr}(\mathbf{X}^{-1} d\mathbf{X})$$
(6.6)

$$d \log(\det(\boldsymbol{X})) = \operatorname{tr}(\boldsymbol{X}^{-1} d\boldsymbol{X}) \tag{6.7}$$

$$d\sigma(a) = (Diag(\sigma) - Diag(\sigma)^{2}) da$$
(6.8)

$$d(\operatorname{softmax}(\theta)) = (\operatorname{Diag}(\boldsymbol{y}) - \boldsymbol{y}\boldsymbol{y}^{\mathsf{T}}) d\theta \tag{6.9}$$

Note: Elementwise function은 일단 Diagonal 형태로 바꿔서 생각해 보삼 ㅋ

Useful first derivatives

$$\frac{\partial \operatorname{tr} \boldsymbol{X}}{\partial \boldsymbol{X}} = \boldsymbol{I} \tag{6.10}$$

$$\frac{\partial \operatorname{tr} \mathbf{X}}{\partial \mathbf{X}} = \mathbf{I}$$

$$\frac{\partial \operatorname{tr} \mathbf{X}^{-1}}{\partial \mathbf{X}} = -\mathbf{X}^{-2}$$

$$\frac{\partial \operatorname{tr} (\mathbf{A}\mathbf{X})}{\partial \mathbf{X}} = \mathbf{A}^{\top}$$
(6.10)
$$(6.11)$$

$$\frac{\partial \operatorname{tr} (\boldsymbol{A} \boldsymbol{X})}{\partial \boldsymbol{X}} = \boldsymbol{A}^{\top} \tag{6.12}$$

$$\frac{\partial \mathbf{X}}{\partial \mathbf{X}} = k \cdot (\mathbf{X}^{\top})^{k-1}$$
(6.13)

$$\frac{\partial \operatorname{tr} \left(\boldsymbol{X} \boldsymbol{A} \boldsymbol{X} \boldsymbol{B} \right)}{\partial \boldsymbol{X}} = \boldsymbol{B}^{\top} \boldsymbol{X}^{\top} \boldsymbol{A}^{\top} + \boldsymbol{A}^{\top} \boldsymbol{X}^{\top} \boldsymbol{B}^{\top}$$
(6.14)

$$\frac{\partial \mathbf{A} \mathbf{X}^{-1} \mathbf{B}}{\partial \mathbf{X}} = -\mathbf{X}^{\top} \mathbf{A}^{\top} \mathbf{B}^{\top} \mathbf{X}^{-\top}$$
(6.15)

$$\frac{\partial \log \det(\boldsymbol{X})}{\partial \boldsymbol{X}} = \boldsymbol{X}^{-\top} \tag{6.16}$$

$$\frac{\partial \det(\mathbf{X}^{-1})}{\partial \mathbf{X}} = \frac{\mathbf{X}^{-\top}}{\det \mathbf{X}}$$

$$\frac{\partial \det(\mathbf{X}^{k})}{\partial \mathbf{X}} = k \det(\mathbf{X}^{k}) \mathbf{X}^{-\top}$$
(6.18)

$$\frac{\partial \det(\boldsymbol{X}^k)}{\partial \boldsymbol{X}} = k \det(\boldsymbol{X}^k) \boldsymbol{X}^{-\top}$$
(6.18)

$$\frac{\partial \log \det(\boldsymbol{X} \boldsymbol{X}^{\top})}{\partial \boldsymbol{X}} = 2\boldsymbol{X} [\boldsymbol{X}^{\top} \boldsymbol{X}]^{-1} \cdot \det(\boldsymbol{X} \boldsymbol{X}^{\top})$$
(6.19)

$$\frac{\det(\boldsymbol{A}\boldsymbol{X}\boldsymbol{B})}{\partial \boldsymbol{X}} = \det(\boldsymbol{A}\boldsymbol{X}\boldsymbol{B})\boldsymbol{A}^{\top}(\boldsymbol{A}\boldsymbol{X}\boldsymbol{B})^{-\top}\boldsymbol{B}^{\top}$$
(6.20)

6.4 Quadratic form

$$\frac{\partial (\boldsymbol{x} - \boldsymbol{A}\boldsymbol{s})^{\top} \boldsymbol{W} (\boldsymbol{x} - \boldsymbol{A}\boldsymbol{s})}{\partial \boldsymbol{s}} = -2\boldsymbol{A}^{\top} \boldsymbol{W} (\boldsymbol{x} - \boldsymbol{A}\boldsymbol{s})$$

$$\frac{\partial (\boldsymbol{x} - \boldsymbol{s})^{\top} \boldsymbol{W} (\boldsymbol{x} - \boldsymbol{s})}{\partial \boldsymbol{x}} = 2\boldsymbol{W} (\boldsymbol{x} - \boldsymbol{s})$$
(6.21)

$$\frac{\partial (x-s)^{\top} W(x-s)}{\partial x} = 2W(x-s)$$
 (6.22)

$$\frac{\partial (x - As)^{\top} W(s - As)}{\partial x} = 2W(s - As)$$
(6.23)

$$\frac{\partial (x - As)^{\top} W(s - As)}{\partial x} = 2W(s - As)$$

$$\frac{\partial (x - As)^{\top} W(x - As)}{\partial A} = -2W(x - As)s^{\top}$$
(6.23)

6.5 Hessian product rule

Given two functions $f, g: \mathbb{R}^n \to \mathbb{R}$,

$$H_c(fg) = (H_c f)g(c) + \nabla_c f^{\top} \nabla_c g + \nabla_c g^{\top} \nabla_c f + f(c)H_c g$$
(6.25)

6.6 Integration by parts

Given vector valued function φ and scalar function f with vanishing condition,

$$\int_{\mathbb{R}^d} \varphi(\boldsymbol{x}) \cdot \nabla f(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x} = -\int_{\mathbb{R}^d} (\nabla \cdot \varphi(\boldsymbol{x})) f(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}$$
 (6.26)

7 Eigenvalues and Eigenvectors

7.1 General Properties

Assume that $\mathbf{A} \in \mathbb{R}^{n \times m}$ and $\mathbf{B} \in \mathbb{R}^{m \times n}$,

$$\operatorname{eig}(\mathbf{A}\mathbf{B}) = \operatorname{eig}(\mathbf{B}\mathbf{A}) \tag{7.1}$$

$$rank(\mathbf{A}) = r \Rightarrow \text{ At most } r \text{ non-zero } \lambda_i \tag{7.2}$$

7.2 Symmetric

Assume \boldsymbol{A} is symmetric, then

$$VV^{\top} = I \tag{7.3}$$

$$\lambda_i \in \mathbb{R} \tag{7.4}$$

$$\operatorname{tr}(\boldsymbol{A}^{p}) = \sum_{i} \lambda_{i}^{p} \tag{7.5}$$

$$\operatorname{eig}(\mathbf{I} + c\mathbf{A}) = 1 + c\lambda_i \tag{7.6}$$

$$\operatorname{eig}(\boldsymbol{A} - c\boldsymbol{I}) = \lambda_i - c \tag{7.7}$$

$$\operatorname{eig}(\boldsymbol{A}^{-1}) = \lambda_i^{-1} \tag{7.8}$$

For a symmetric, positive matrix \boldsymbol{A}

$$\operatorname{eig}(\mathbf{A}^{\top}\mathbf{A}) = \operatorname{eig}(\mathbf{A}\mathbf{A}^{\top}) = \operatorname{eig}(\mathbf{A}) \circ \operatorname{eig}(\mathbf{A})$$
(7.9)

7.3 Singular Value Decomposition

Any $n \times m$ matrix \boldsymbol{A} can be written as

$$\boldsymbol{A} = \boldsymbol{U}\boldsymbol{D}\boldsymbol{V}^{\top} \tag{7.10}$$

where

$$egin{aligned} oldsymbol{U} &= & ext{eigenvectors of } oldsymbol{A} oldsymbol{A}^ op n imes n \ oldsymbol{D} &= \sqrt{ ext{diag}(ext{eigen}(oldsymbol{A} oldsymbol{A}^ op)} \quad n imes m \ oldsymbol{V} &= & ext{eigenvectors of } oldsymbol{A}^ op oldsymbol{A} \ m imes m \end{aligned}$$

7.3.1 Square decomposed into rectangular

Assume $V_*D_*U_*^{\top}=0$ then we can expand the SVD of A into

$$\boldsymbol{A} = \begin{bmatrix} \boldsymbol{V} & \boldsymbol{V}_* \end{bmatrix} \begin{bmatrix} \boldsymbol{D} & \boldsymbol{0} \\ \boldsymbol{0} & \boldsymbol{D}_* \end{bmatrix} \begin{bmatrix} \boldsymbol{U}^{\top} \\ \boldsymbol{U}_*^{\top} \end{bmatrix}$$
 (7.11)

where the SVD of \boldsymbol{A} is $\boldsymbol{A} = \boldsymbol{V}\boldsymbol{D}\boldsymbol{U}^{\top}$

7.4 LU decomposition

Assume A is a square matrix with non-zero leading prinipal minors, then

$$\mathbf{A} = \mathbf{L}\mathbf{U} \tag{7.12}$$

where L is a unique unit lower triangular matrix and U is a unique upper triangular matrix.

7.5 Cholesky decomposition

Assume A is a symmetric positive definite square matrix, then

$$\boldsymbol{A} = \boldsymbol{U}^{\top} \boldsymbol{U} = \boldsymbol{L} \boldsymbol{L}^{\top} \tag{7.13}$$

where U is an unique upper triangular matrix and L is a lower triangular matrix.

7.6 Eigenvalues of its reverse

Proposition 7.1. Given $M \times K$ matrix $\boldsymbol{A}, \boldsymbol{B}$, the nonzero eigenvalues of $\boldsymbol{A}\boldsymbol{B}^{\top} \in \mathbb{C}^{M \times M}$ and $\boldsymbol{B}^{\top}\boldsymbol{A} \in \mathbb{C}^{K \times K}$ are identical. If addition, if $(\lambda, \boldsymbol{v})$ is an eigenpair of $\boldsymbol{B}^{\top}\boldsymbol{A}$ with $\lambda \neq 0$, then $(\lambda, \boldsymbol{A}\boldsymbol{v}/\|\boldsymbol{A}\boldsymbol{v}\|_2)$ is an eigenpair of $\boldsymbol{A}\boldsymbol{B}^{\top}$.

7.7 Row stochastic matrix

Fact. The operator norm of a row-stochastic matrix is 1.

8 Inverses

8.1 Rank-1 update of the inverse of inner product

Denote $A = (X^{\top}X)^{-1}$ and that X is extended to include a new column vector in the end $\tilde{X} = [X, v]$, let $N = v^{\top}(I - XAX^{\top})v$ then

$$(\tilde{\boldsymbol{X}}^{\top}\tilde{\boldsymbol{X}})^{-1} = N^{-1} \begin{bmatrix} N\boldsymbol{A} + \boldsymbol{A}\boldsymbol{X}^{\top}\boldsymbol{v}(\boldsymbol{A}\boldsymbol{X}^{\top}\boldsymbol{v})^{\top} & -\boldsymbol{A}\boldsymbol{X}^{\top}\boldsymbol{v} \\ -\boldsymbol{v}^{\top}\boldsymbol{X}\boldsymbol{A}^{\top} & 1 \end{bmatrix}$$
(8.1)

8.2 Approximations

The following identity is known as the *Neuman series* of a matrix, which holds when $|\lambda_i| < 1$ for all eigenvalues λ_i

$$(I - A)^{-1} = \sum_{n=0}^{\infty} A^n$$
 (8.2)

$$(I + A)^{-1} = \sum_{n=0}^{\infty} (-1)^n A^n$$
(8.3)

$$A - A(I + A)^{-1}A = A - A(I + A^{-1})^{-1}$$
(8.4)

$$= \mathbf{A}(\mathbf{I} - (\mathbf{I} + \mathbf{A}^{-1})^{-1}) \tag{8.5}$$

$$\approx \mathbf{A}(\mathbf{I} - \mathbf{I} + \mathbf{A}^{-1} - \mathbf{A}^{-2}) \tag{8.6}$$

$$= \mathbf{I} - \mathbf{A}^{-1} \tag{8.7}$$

8.3 Block matrix

Using Schur complements

$$C_1 = A_{11} - A_{12}A_{22}^{-1}A_{21}$$
 (8.8)

$$C_2 = A_{22} - A_{21}A_{11}^{-1}A_{12} (8.9)$$

as

$$\left[\frac{A_{11} | A_{12}}{A_{21} | A_{22}} \right]^{-1} = \left[\frac{C_1^{-1} | -A_{11}^{-1} A_{12} C_2^{-1}}{-C_2^{-1} A_{21} A_{11}^{-1} | C_2^{-1}} \right]$$
(8.10)

9 PSD matrix

9.1 Decomposition

- 1. The matrix is PSD with rank $r \iff$ there exists a matrix \pmb{B} of rank r such that $\pmb{A} = \pmb{B} \pmb{B}^{\top}$
- 2. The matrix is PD \iff there exists an invertible matrix B such that $A = BB^{\top}$
- 3. Given \boldsymbol{A} is an $n \times n$ PSD matrix, there exists an $n \times r$ matrix \boldsymbol{B} of rank r such that $\boldsymbol{B}^{\top} \boldsymbol{A} \boldsymbol{B} = \boldsymbol{I}$.

9.2 Sylvester's characterization

$$A \succeq 0 \iff \text{All } 2^n - 1 \text{ principal minors are nonnegative.}$$
 (9.1)

$$A \succ 0 \iff \text{All } n \text{ leading principal minors are positive.}$$
 (9.2)

9.3 Eqution with zeros

Assume **A** is PSD, then $\mathbf{X}^{\top} \mathbf{A} \mathbf{X} = \mathbf{0} \Rightarrow \mathbf{A} \mathbf{X} = 0$

9.4 Rank of product

Assume A is positive definite, then $rank(BAB^{\top}) = rank(B)$

9.5 Outer product

If $X \in n \times r$, where $n \leq r$ and rank(X) = n, then XX^{\top} is positive definite.

9.6 Small pertubations

If A is positive definite, and B is symmetric, then A - tB is positive definite for sufficiently small t.

9.7 Hadamard inequality

If A is a positive definite or semi-definite matrix, then

$$\det(\mathbf{A}) \le \prod_{i} A_{ii} \tag{9.3}$$

9.8 Loewner order

Fact. Let A and B be hermitian positive definite. Then

$$A \succeq B \iff I \succeq A^{-1/2}BA^{-1/2}$$
 (9.4)

9.9 Inverse of PSD

Fact. Suppose that A, B and A - B are all positive definite, then $B^{-1} - A^{-1}$ is also positive definite.

10 Symmetric and skew-symmetric matrix

10.1 Properties of symmetric matrix

- 1. Every real symmetric matrix can be orthogonally diagonalizable. ¹
- 2. The rank of a symmetric matrix A is equal to the number of non-zero eigenvalues of A.
- 3. If A and B are $n \times n$ real symmetric matrices that commute, then they can be simultaneously diagonalized by an orthogonal matrix.

10.2 Youla decomposition

Given $\boldsymbol{B} \in \mathbb{R}^{M \times K}$ and $D \in \mathbb{R}^{K \times K}$, consider a rank-K skew-symmetric matrix $\boldsymbol{B}^{\top}(\boldsymbol{D} - \boldsymbol{D}^{\top})\boldsymbol{B}^{\top}$. Then, we can write

$$\boldsymbol{B}(\boldsymbol{D} - \boldsymbol{D}^{\top})\boldsymbol{B} = \sum_{j=1}^{K/2} i\sigma_j(\boldsymbol{a}_j + i\boldsymbol{b}_j)(\boldsymbol{a}_j + i\boldsymbol{b}_j)^H - i\sigma_j(\boldsymbol{a} - J - i\boldsymbol{b}_j)(\boldsymbol{a}_j - i\boldsymbol{b}_j)^H$$
(10.1)

$$= \sum_{j=1}^{K/2} 2\sigma_j (\boldsymbol{a}_j \boldsymbol{b}_j^{\top} - \boldsymbol{b}_j \boldsymbol{a}_j^{\top})$$
 (10.2)

$$= \sum_{j=1}^{K/2} \begin{bmatrix} \boldsymbol{a}_j - \boldsymbol{b}_j & \boldsymbol{a}_j + \boldsymbol{b}_j \end{bmatrix} \begin{bmatrix} 0 & \sigma_j \\ -\sigma_j & 0 \end{bmatrix} \begin{bmatrix} \boldsymbol{a}_j^\top - \boldsymbol{b}_j^\top \\ \boldsymbol{a}_j^\top + \boldsymbol{b}_j^\top \end{bmatrix}$$
(10.3)

Note that $\mathbf{a}_1 \pm \mathbf{b}_1, \dots \mathbf{a}_{K/2} \pm \mathbf{b}_{K/2}$ are real-valued orthonormal vectors. The pair $\{(\sigma_j, \mathbf{a}_j - \mathbf{b}_j, \mathbf{a}_j + \mathbf{b}_j)\}_{j=1}^{K/2}$ is often called the Youla decomposition of $\mathbf{B}(\mathbf{D} - \mathbf{D}^\top)\mathbf{B}^\top$.

11 Some techniques

11.1 Binary analysis

어떤 matrix의 operator norm을 분석하기 위해 matrix를 binary matrix로 decomposition하는 것은 유용할 수 있다.

Example

Let v be the unit-normed vector that realizes the operator norm of $D^{-1}A$. We define the sequence of binary matrices B^0, B^1, B^2 as follows:

$$B_{i,j}^t := 1_{\left\{2^{-t-1}\sqrt{\alpha/n} < [\mathbf{D}^{-1}\mathbf{A}]_{i,j} \le 2^{-t}\sqrt{\alpha/n}\right\}} \text{ for every integers } t \ge 0, \tag{11.1}$$

¹Think of it this way: every symmetric matrix can be triangulated and normality is preserved under a similar transform. When is the triangular matrix normal? Of course, it is the diagonal matrix.

where $\sqrt{\alpha/n}$ is the upper bound for entries of $D^{-1}A$. Then we have the following inequalities for the entries and the l_2 -norm:

$$[\boldsymbol{D}^{-1}\boldsymbol{A}]_{i,j} \le \sqrt{\alpha/n} \sum_{t=0}^{\infty} 2^{-t} \cdot [\boldsymbol{B}^t]_{i,j}$$
(11.2)

$$[\mathbf{D}^{-1}\mathbf{A}]_{i,j} \leq \sqrt{\alpha/n} \sum_{t=0}^{\infty} 2^{-t} \cdot [\mathbf{B}^t]_{i,j}$$

$$\|\mathbf{D}^{-1}\mathbf{A} \cdot \mathbf{v}\|_{2} \leq \sqrt{\alpha/n} \sum_{t=0}^{\infty} 2^{-t} \cdot \|\mathbf{B}^t \mathbf{v}\|_{2}$$

$$(11.2)$$

만약 B^t matrix의 row, column들의 non-zero elements를 estimate 하면 $\|B^t v\|_2^2$ 도 estimate 할 수 있고 $D^{-1}A$ 의 operator norm의 bound도 estimate 할 수 있다.