



# HICHIP EC1106S 使用说明文档

## 1. 文档履历

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### HICHIP EC1106S 使用说明文档

- 文档履历
- 概述
  - 编写目的
  - 读者对象
- 模块介绍
- linux
  - 模块接口说明
  - 模块测试用例与Sample Code
    - 开启模块
    - 设备树的配置
    - 编译
- rtos
  - 模块接口说明
  - 模块测试用例与Sample Code
    - 如何开启测试命令
    - menuconfig的配置
    - 设备树配置
    - 编译
- 调试信息

## 2. 概述

## 2.1 编写目的

介绍hichip平台下的EC1106S旋转编码器的使用;

## 2.2 读者对象

hichip软件开发工程师和技术支持工程师。

## 3. 模块介绍

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- 目前hichip平台上EC1106S旋转编码器只支持左旋右旋;

## 4. linux

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### 4.1 模块接口说明

1、可以通过read函数读取misc节点下ec1106s获得旋转计数; 2、通过input节点可以获取旋转方向;

### 4.2 模块测试用例与Sample Code

```
1  int fd = open(input_path, O_RDONLY);
2  pfd.fd = fd;
3  pfd.events = POLLIN | POLLRDNORM;
4
5  if (fd < 0) {
6      printf("can't open %s\n", input_buf);
7      return -1;
8  }
9
10 char name[256] = "Unknown";
11 ioctl(fd, EVIOCGNAME(sizeof(name)), name);
12 printf("\nInput Device Name:[%s]. \n", name);
13
14 while (1) {
15     if (poll(&pfd, 1, -1) <= 0)
16         continue;
17
18     if (read(fd, &t, sizeof(t)) != sizeof(t))
19         continue;
20
21     printf("type:%d, code:%d, value:0x%lx\n", t.type, t.code,
22           t.value);
23 }
24
25 close(fd);
```

### 4.2.1 开启模块

在SDK根目录下：输入make linux-menuconfig，根据路径打开测试命令

```
1  There is no help available for this option.
2  Symbol: HC_ES1106S [=y]
3  Type   : boolean
4  Prompt: es1106s encoder
5  Location:
6      -> Device Drivers
7      -> HC drivers
8      -> input driver (HC_INPUT [=y])
9      -> misc driver (HC_MISC [=y])
10     -> rotate encoder driver (HC_ROTATE_ENCODER [=y])
11  Defined at drivers/hcd/drivers/input/misc/rotate_encoder/Kconfig:1
12  Depends on: HC_INPUT [=y] && HC_MISC [=y] && HC_ROTATE_ENCODER [=y]
```

### 4.2.2 设备树的配置

在/board/hichip/hc16xx/common/dts/hc16xx-common.dtsi文件下添加

```
1  ec1106s:ec1106s@0 {
2      compatible = "hichip,ec1106s";
3      gpio-input-a = <&gpio_B 12 GPIO_ACTIVE_HIGH>;           //
4      irq-pin
5      gpio-input-b = <&gpio_B 13 GPIO_ACTIVE_HIGH>;           //
6      irq-pin
7      status = "disabled";
8  };
```

在对应的板子dts文件下，比如：/board/hichip/hc16xx/common/dts/hc16xx-db-d3100-v30.dts添加以下节点：

```
1  &ec1106s {
2      status = "okay";
3  };
```

### 4.2.3 编译

执行命令：make linux-rebuild all;

## 5. rtos

## 5.1 模块接口说明

1、可以通过read函数读取/dev/ec1106s获得旋转计数；2、通过input节点可以获取旋转方向；

## 5.2 模块测试用例与Sample Code

```
1 static int input_test(int argc, char *argv[])
2 {
3     int fd;
4     struct input_event t;
5     struct pollfd pfd;
6     char input_buf[BUF_SIZE];
7     char *s = "/dev/input/event0";
8
9     long tmp;
10
11     fd = open(input_buf, O_RDONLY);
12     pfd.fd = fd;
13     pfd.events = POLLIN | POLLRDNORM;
14
15     if (fd < 0) {
16         printf("can't open %s\n", input_buf);
17         return -1;
18     }
19
20     while (1) {
21         if (poll(&pfd, 1, -1) <= 0)
22             continue;
23
24         if (read(fd, &t, sizeof(t)) != sizeof(t))
25             continue;
26
27         printf("type:%d, code:%d, value:0x%lx\n", t.type, t.code,
28             t.value);
29     }
30
31     close(fd);
32
33     return 0;
34 }
```

测试代码位置：components/cmds/source/input\_event/input\_test.c;

### 5.2.1 如何开启测试命令

```

1 | There is no help available for this option.
2 | Symbol: CONFIG_CMDS_INPUT [=y]
3 | Type : bool
4 | Prompt: input event operations
5 |   Location:
6 |     -> Components
7 |       -> Cmds (BR2_PACKAGE_CMDS [=y])
8 |   Defined at source:46
9 |   Depends on: BR2_PACKAGE_CMDS [=y] && CONFIG_DRV_INPUT [=y]

```

编译命令: make cmds-rebuild all

## 5.2.2 menuconfig的配置

```

1 | There is no help available for this option.
2 | Symbol: CONFIG_HC_ES1106S [=y]
3 | Type : bool
4 | Prompt: es1106s
5 |   Location:
6 |     -> Components
7 |       -> kernel (BR2_PACKAGE_KERNEL [=y])
8 |       -> Drivers
9 |         -> input event (CONFIG_DRV_INPUT [=y])
10 |          -> rotary key (CONFIG_ROTARY_KEY [=y])
11 |   Defined at rotary_key:5
12 |   Depends on: BR2_PACKAGE_KERNEL [=y] && CONFIG_DRV_INPUT [=y] &&
CONFIG_ROTARY_KEY [=y]

```

## 5.2.3 设备树配置

```

1 | ec1106s:ec1106s@0 {
2 |     gpio-input-a = <PINPAD_B12 GPIO_ACTIVE_HIGH>;           //
   irq-pin
3 |     gpio-input-b = <PINPAD_B13 GPIO_ACTIVE_HIGH>;           //
   irq-pin
4 |     status = "okay";
5 | };

```

## 5.2.4 编译

make kernel-rebuild all

# 6. 调试信息

暂无。

