Linear Algebra

ME 2004



Outline

- 1.1: Interpreting Matrices
- 1.2: Existence of Solutions
- 1.3: Uniqueness of Solutions

1.1: Interpreting Matrices







• General form of m simultaneous linear equations with n unknowns:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n = b_m$$

• *m* rows, *n* columns



Introduction

• These linear equations are condensed into:

$$Ax = b$$

$$A = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ & & \ddots & \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$



Introduction

 We are usually given A and b from the governing equations, so we need to find x:

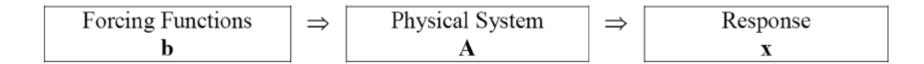
$$Ax = b \rightarrow x = A^{-1}b$$

- Many ways to compute *x*:
 - Row reduction/Gauss-Jordan Elimination
 - Computing A^{-1}
 - LU/QR Decomposition
 - Gauss-Seidel
 - etc.



Cause-Effect Relationship

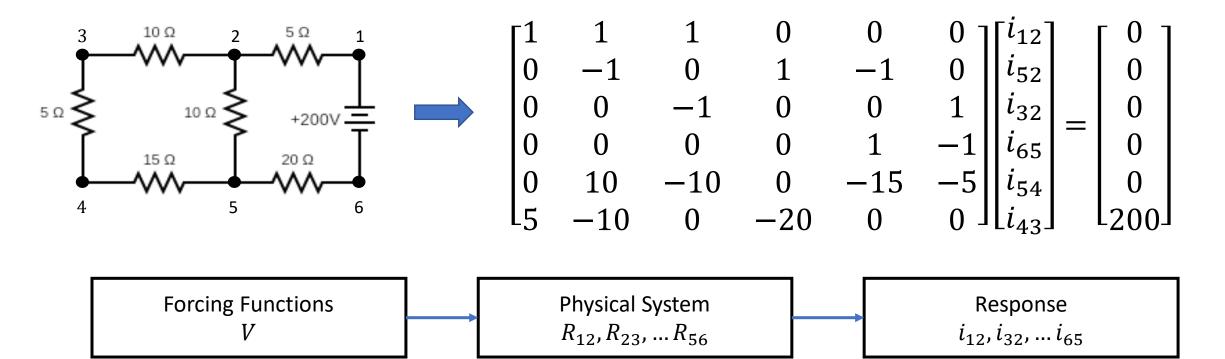
- Linear systems represent a cause-effect relationship:
 - A: contains the system parameters. How do parts of the system interact?
 - b: forcing functions. What is acting on the system?
 - x: response. How to the independent variables react to the forcing functions?





Cause-Effect Relationship

Finding the currents in a circuit:





Geometric Interpretations

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

Row interpretation: interpreting each row of the system as lines

$$A_{11}x_1 + A_{12}x_1 = b_1 A_{21}x_1 + A_{22}x_2 = b_2$$

- Solution: intersection of the lines
- Column interpretation: interpreting each column of the system as a vector

$$\begin{bmatrix} A_{11} \\ A_{21} \end{bmatrix} x_1 + \begin{bmatrix} A_{12} \\ A_{22} \end{bmatrix} x_2 = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

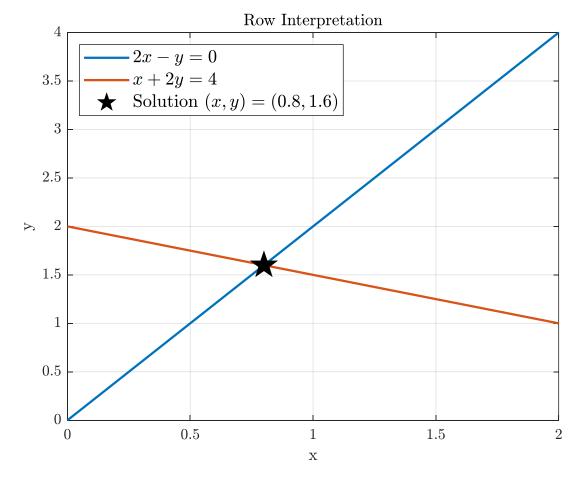
Solution: values which form b as a linear combination of the column vectors

Geometric Interpretations

$$\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

$$2x - y = 0$$
$$x + 2y = 4$$

$$\rightarrow$$
 (x , y) = (0.8,1.6)

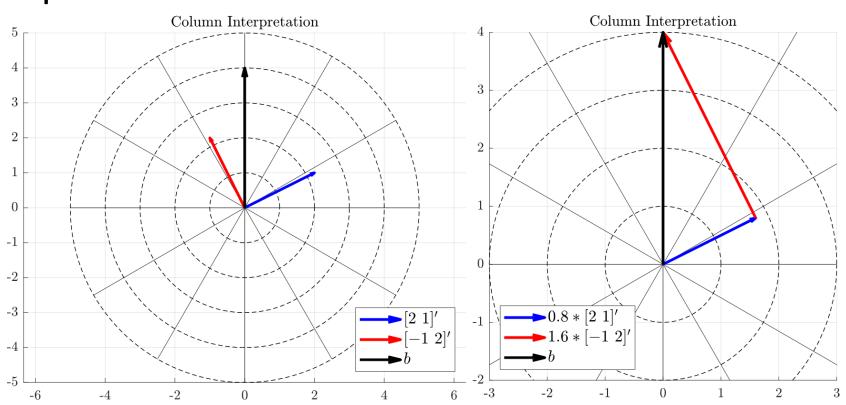


Geometric Interpretations

$$\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} x + \begin{bmatrix} -1 \\ 2 \end{bmatrix} y = \begin{bmatrix} 0 \\ 4 \end{bmatrix} \begin{bmatrix} -1 \\ -2 \end{bmatrix}$$

$$\rightarrow$$
 (x , y) = (0.8,1.6)



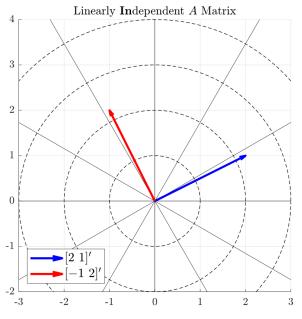
1.2: Existence of Solutions



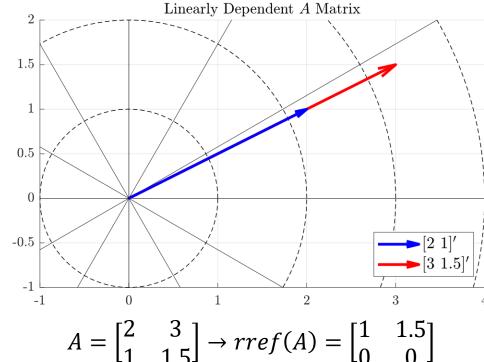




• A is linearly INdependent if no columns are a linear combination of the other columns (A has a pivot in each row; $det(A) \neq 0$, etc.)



$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \rightarrow rref(A) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix} \rightarrow rref(A) = \begin{bmatrix} 1 & 1.5 \\ 0 & 0 \end{bmatrix}$$

Rank and Consistency

Interpreting Matrices

- Rank: number of linearly INdependent columns of A
 - Full rank: rank(A) = # columns of A
 - Rank deficient: rank(A) < # columns of A
- Consistency: characterizes whether a system of equations has solutions
 - Augmented matrix: $\tilde{A} = [A \ b]$
 - System is consistent (at least one solution exists) if $rank(A) = rank(\tilde{A})$
 - System is inconsistent (solutions do not exist) if $rank(A) \neq rank(\tilde{A})$

Rank and Consistency

$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}, b = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

- Compute rank(A)
- Compute $rank(\tilde{A})$
- Is the system consistent?

Command Window

```
>> A = [2 -1; 1 2]; b = [0 4]';
>> rref(A)
ans =
                                   A is linearly
                                  independent
>> rank(A)
ans =
                                   A is full rank
>> rank([A b])
ans =
                     rank(\tilde{A}) = rank(A) = 2
                       → system is consistent
```

Rank and Consistency

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

- Compute rank(A)
- Compute $rank(\tilde{A})$
- Is the system consistent?

```
Command Window
  >> A = [2 3; 1 1.5]; b = [-1 6]';
  >> rref(A)
  ans =
                                        A is linearly
       1.0000
                  1.5000
                                        dependent
  >> rank(A)
  ans =
                                  A is rank deficient
  >> rank([A b])
  ans =
                            rank(\tilde{A}) \neq rank(A)
                           → system is inconsistent
```

1.3: Uniqueness of Solutions





Uniqueness of Solutions

- A unique solution exists if:
 - rank(A) = n
 - $rank(\tilde{A}) = rank(A)$
- Infinite solutions exist if:
 - rank(A) < n
 - $rank(\tilde{A}) = rank(A)$
- No solutions exist if:
 - rank(A) < n
 - $rank(\tilde{A}) = rank(A) + 1$

Uniqueness of Solutions

$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$
, $b = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$

- Compute rank(A)
- Compute $rank(\tilde{A})$
- Is the system consistent?
 - If the system is consistent, what is/are the solution(s)?

Command Window

```
>> A = [2 -1; 1 2]; b = [0 4]';
>> rref(A)
ans =
                                   A is linearly
                                   independent
>> rank(A)
ans =
                                   A is full rank
>> rank([A b])
ans =
                    rank(\tilde{A}) = rank(A) = 2
                      → system is consistent
                  and there is a unique solution
```

Uniqueness of Solutions

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

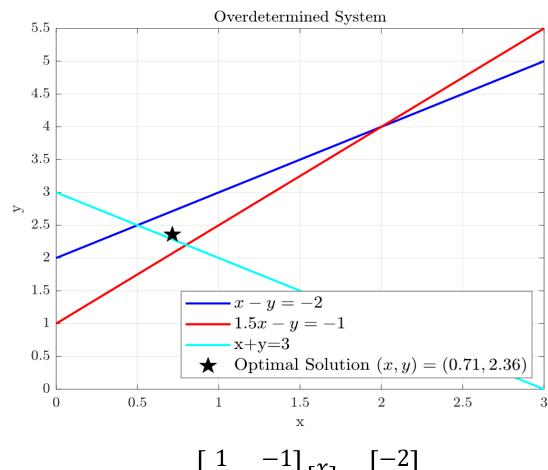
- Compute rank(A)
- Compute $rank(\tilde{A})$
- Is the system consistent?
 - If the system is consistent, what is/are the solution(s)?

```
Command Window
  >> A = [2 3; 1 1.5]; b = [-1 6]';
  >> rref(A)
  ans =
                                        A is linearly
       1.0000
                   1.5000
                                        dependent
  >> rank(A)
  ans =
                                  A is rank deficient
  >> rank([A b])
  ans =
                             rank(\tilde{A}) \neq rank(A)
                            → system is inconsistent
```





- Overdetermined system: more equations than unknowns (m > n)
- In general, no solution satisfies the system
- Application: curve fitting (least-squares regression)

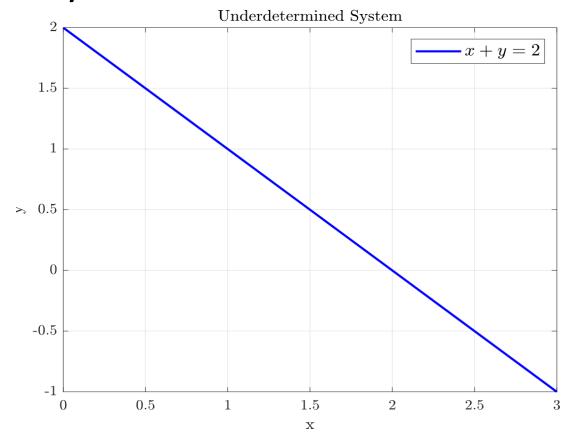


$$\begin{bmatrix} 1 & -1 \\ 1.5 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix}$$



Over/Underdetermined Systems

- Underdetermined system: more unknowns than equations (n > m)
- In general, infinite solutions satisfy the system
- Application: integer programming



$$\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \end{bmatrix}$$

Summary

• Express m simultaneous linear equations with n unknowns in matrix form:

$$A = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ & & \ddots & \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

Forcing Functions \Rightarrow Physical System \Rightarrow Response \mathbf{x}



Understand the system

- What are A, b, x?
- What are m, n?

Do solutions exist?

- Consistency
 - Rank
 - Linear independence

If solutions exist, are they unique?

- Compare:
 - rank(A) vs n
 - rank(A) vs $rank(\tilde{A})$
- Over/underdetermined

Summary

Review Linear Algebra terminology if you haven't already!!!

In particular:

Invertible Matrix Theorem