

# Numerical Differentiation

ME 2004

# Outline

- 1.1: Numerical Differentiation via Taylor Series
- 1.2: Example

# 1.1: Numerical Differentiation via Taylor Series

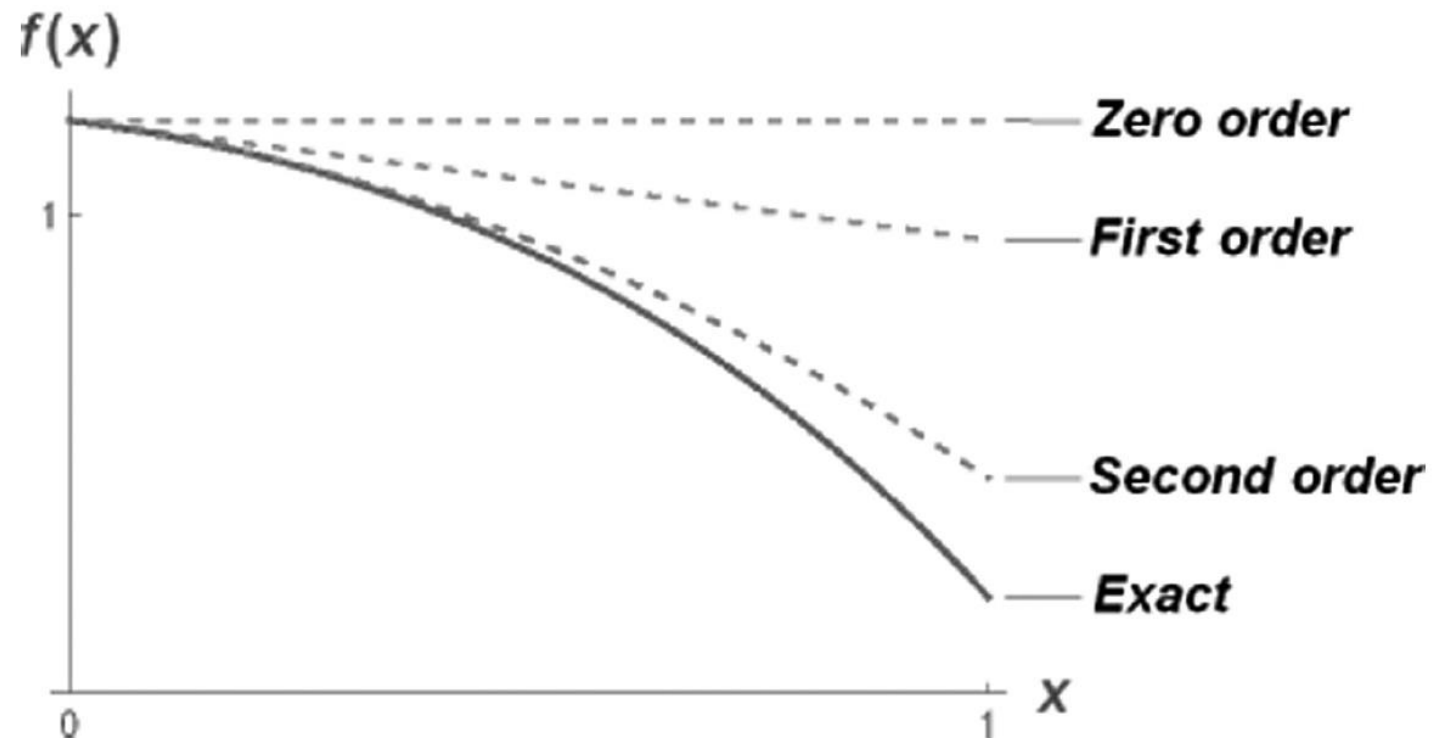


# Numerical Differentiation

- Given  $f(x)$ , compute  $\frac{d^n x}{dy^n}$  at the point  $x_i$ 
  - Can be difficult, especially if  $f(x)$  is discrete data instead of a mathematical function
- Numerical differentiation suffers from a conflict between truncation errors and computation time/data availability

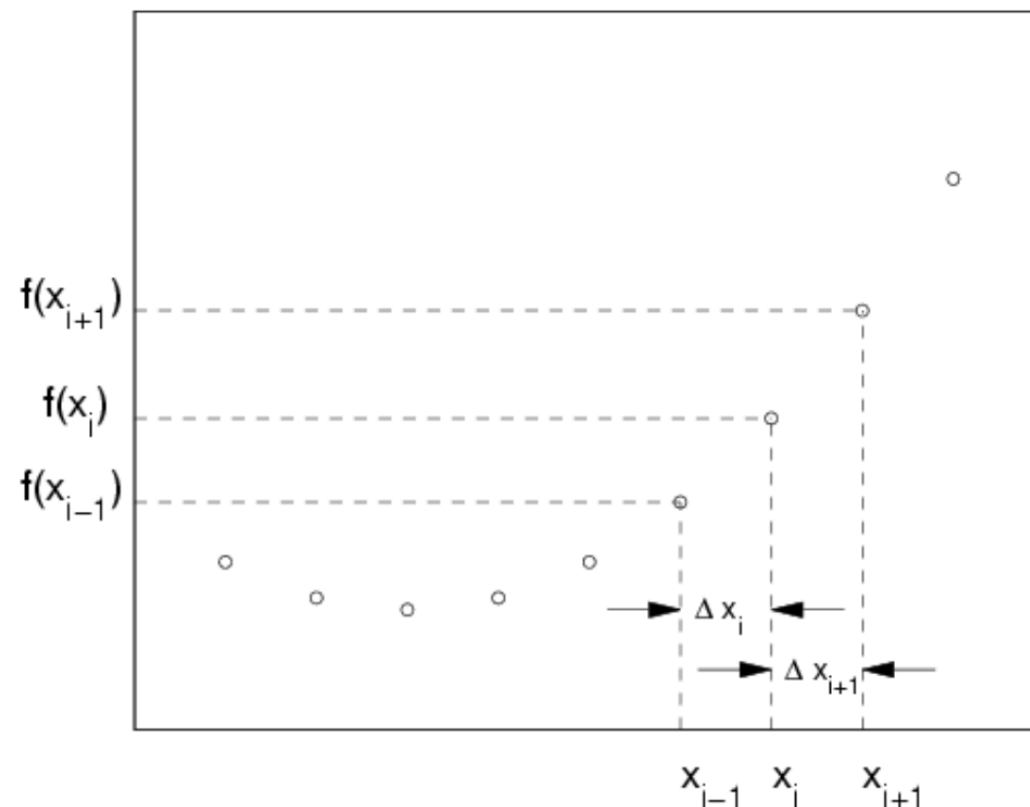
# Taylor Series Revisited

- The Taylor Series can be used to predict  $f(x_{i+1})$  given  $x_i$  and  $\frac{d^n x}{dy^n}$
- $\rightarrow$  If we have  $f(x_{i+1})$  and  $x_i$ , we can estimate  $\frac{d^n x}{dy^n}$



# Taylor Series Revisited

- Suppose we have  $N$  potentially unevenly spaced data points
  - $\Delta x_i \neq \Delta x_{i+1}$  (potentially)



- Taylor Series expansion about  $x = x_i$ :

$$f(x_{i+1}) = f(x_i) + (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + \left( \frac{(\Delta x_{i+1})^2}{2} \right) \left( \frac{d^2y}{dx^2} \Big|_{x=x_i} \right) + \dots + \left( \frac{(\Delta x_{i+1})^n}{n!} \right) \left( \frac{d^ny}{dx^n} \Big|_{x=x_i} \right)$$

# Taylor Series Revisited

$$f(x_{i+1}) = f(x_i) + (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + \cancel{\left( \frac{(\Delta x_{i+1})^2}{2} \right) \left( \frac{d^2 y}{dx^2} \Big|_{x=x_i} \right)} + \dots + \cancel{\left( \frac{(\Delta x_{i+1})^n}{n!} \right) \left( \frac{d^n y}{dx^n} \Big|_{x=x_i} \right)}$$

$$\rightarrow f(x_{i+1}) \cong f(x_i) + (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_{i+1})^2)$$

$$\rightarrow \boxed{\frac{dy}{dx} \Big|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_i)}{\Delta x_{i+1}} + O(\Delta x_{i+1})}$$

Forward Difference

# Taylor Series Revisited

- Taylor Series expansion about  $x = x_i$  (backwards):

$$f(x_{i-1}) = f(x_i) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + \left( \frac{(\Delta x_i)^2}{2} \right) \left( \frac{d^2 y}{dx^2} \Big|_{x=x_i} \right) + \dots + \left( \frac{(\Delta x_i)^n}{n!} \right) \left( \frac{d^n y}{dx^n} \Big|_{x=x_i} \right)$$

$$\rightarrow f(x_{i-1}) \cong f(x_i) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_i)^2)$$

$$\rightarrow \boxed{\frac{dy}{dx} \Big|_{x=x_i} \cong \frac{f(x_i) - f(x_{i-1})}{\Delta x_i} + O(\Delta x_i)}$$

Backward Difference



# Taylor Series Revisited

- We have the forward and the backward differences, but surely there's a middle ground?

$$f(x_{i+1}) \cong f(x_i) + (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_{i+1})^2)$$
$$f(x_{i-1}) = f(x_i) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_i)^2)$$

$$\rightarrow f(x_{i+1}) - f(x_{i-1}) \cong (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_{i+1})^2) + O((\Delta x_i)^2)$$

# Taylor Series Revisited

$$f(x_{i+1}) - f(x_{i-1}) \cong (\Delta x_{i+1}) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_{i+1})^2) + O((\Delta x_i)^2)$$

$$\rightarrow f(x_{i+1}) - f(x_{i-1}) \cong (\Delta x_{i+1} - \Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + O((\Delta x_{i+1})^2) + O((\Delta x_i)^2)$$

$$\rightarrow \boxed{\frac{dy}{dx} \Big|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_{i-1})}{\Delta x_{i+1} - \Delta x_i} + O((\Delta x_i)^2) \cong \frac{f(x_{i+1}) - f(x_{i-1})}{2\Delta x_i} + O((\Delta x_i)^2)}$$

Central Difference

# Taylor Series Revisited

- Forward difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_i)}{\Delta x_{i+1}} + O(\Delta x_{i+1})$
- Backward difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_i) - f(x_{i-1})}{\Delta x_i} + O(\Delta x_i)$
- Central difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_{i-1}))}{\Delta x_{i+1} - \Delta x_i} + O((\Delta x_i)^2)$
- These formulas apply for (un)equally spaced data, although more accurate methods exist for unequally spaced data

# Taylor Series Revisited

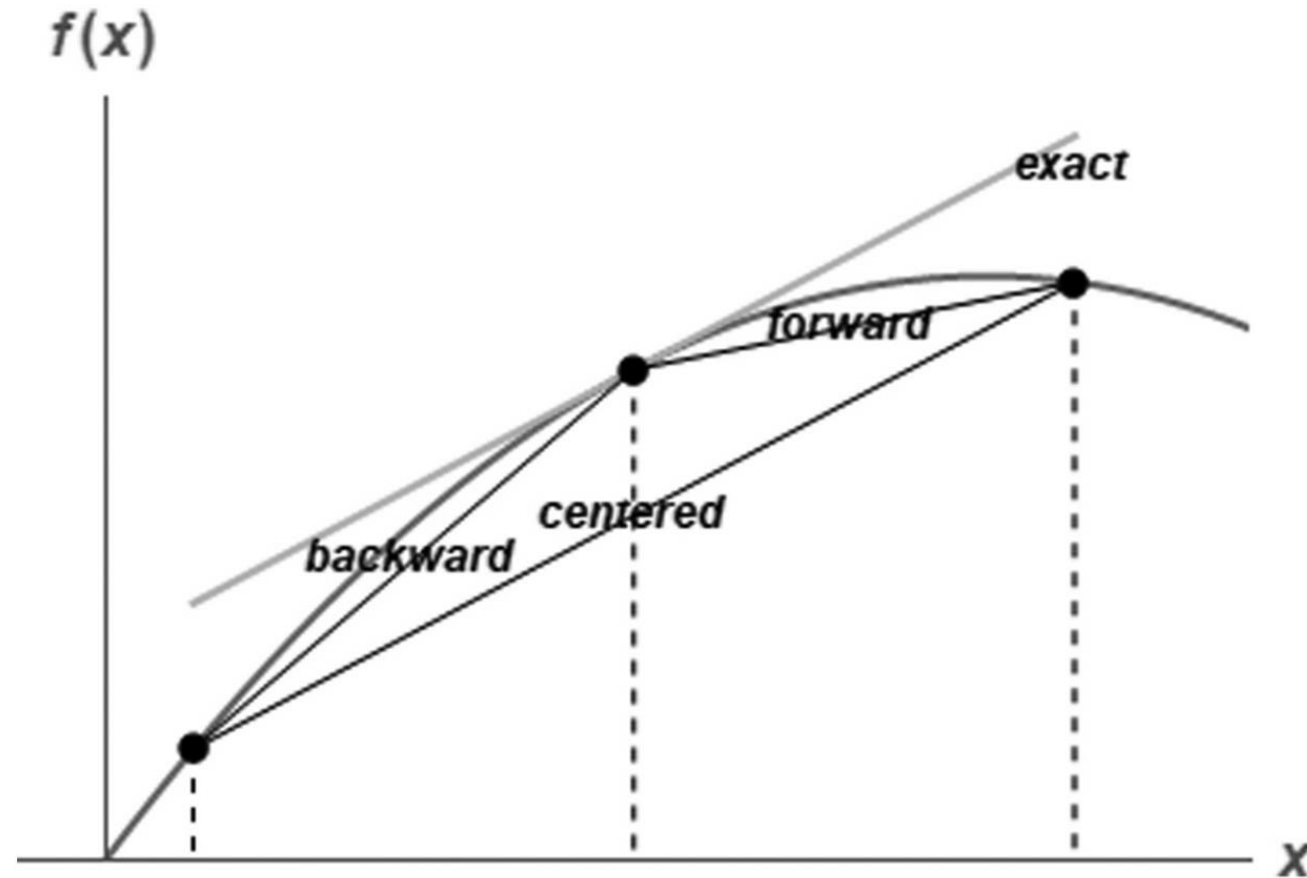
- Assuming a constant step size,  $h$ :

- Forward difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_i)}{h} + O(h)$

- Backward difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_i) - f(x_{i-1})}{h} + O(h)$

- Central difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_{i-1}))}{2h} + O(h^2)$

# Taylor Series Revisited





# Taylor Series Revisited

- **Big O notation:** allows us to compare the truncation errors of numerical methods
- $O(h^n)$ : truncation error is proportional to the step size raised to the  $n$ th power
- Forward and Backward differences have error  $O(\Delta x_{i+1})$  and  $O(\Delta x_i)$ , so truncation errors are **linearly proportional** to the step size
  - Halving the step size halves the truncation error
- Central difference has error  $O((\Delta x_i)^2)$ , so truncation error is **quadratically proportional** to the step size
  - Halving the step size quarters the truncation error

# Taylor Series Revisited

- To increase the accuracy (decrease truncation error), we could also algebraically combine multiple Taylor Series expansions about other points

$$\left. \frac{dy}{dx} \right|_{x=x_i} \cong \frac{\left(-\frac{11}{6}\right) f(x_i) + 3f(x_{i+1}) - \left(\frac{3}{2}\right) f(x_{i+2}) + \left(\frac{1}{3}\right) f(x_{i+3})}{h} + O((\Delta x_{i+1})^3)$$

Forward difference, 3<sup>rd</sup> order accuracy (assumes equal step size)

- ...but computation time becomes a concern.

# Taylor Series Revisited

- An even bigger concern is the lack of available data:

| t (s) | 0 | 1 | 2 | 3   | 4   |
|-------|---|---|---|-----|-----|
| x (m) | 0 | 2 | 3 | 3.1 | 3.7 |

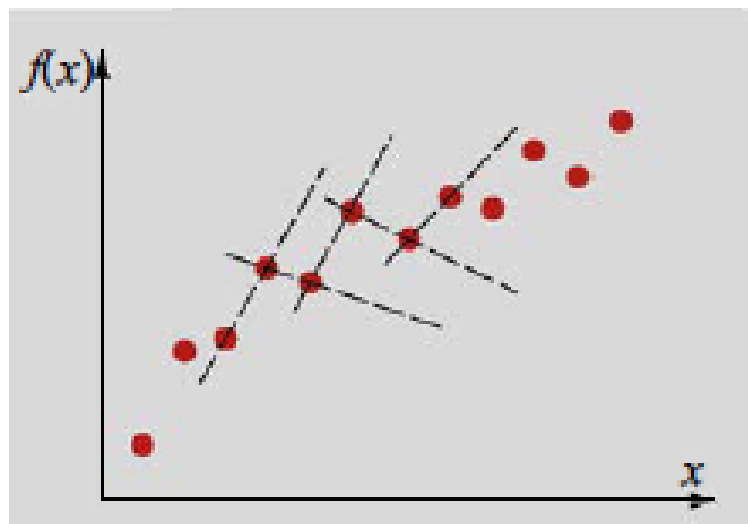
- Central difference:  $\frac{dy}{dx}\bigg|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_{i-1})}{\Delta x_{i+1} - \Delta x_i} + O((\Delta x_i)^2)$
- ...so we can't compute  $\frac{dx}{dt}\bigg|_{t=4}$  using the central (or forward) difference because the next point does not exist.





# Taylor Series Revisited

- Minimizing error in the dataset is imperative!



- Large variations of  $\frac{dy}{dx}$  will be seen from point to point

## 1.2: Example



# Example

- Compute  $\left. \frac{dx}{dt} \right|_{t=1}$  using the forward difference.

| t (s) | 0 | 1 | 2 | 3   | 4   |
|-------|---|---|---|-----|-----|
| x (m) | 0 | 2 | 3 | 3.1 | 3.7 |

$$\left. \frac{dx}{dt} \right|_{t=1} \cong \frac{x(t_{i+1}) - x(t_i)}{\Delta t_{i+1}} = \frac{x(3) - x(2)}{t(3) - t(2)} = \frac{3 - 2}{2 - 1}$$

$$\rightarrow \boxed{\left. \frac{dx}{dt} \right|_{t=1} \cong 1 \frac{m}{s}}$$

MATLAB Notation!!!!!!

# Example

- Compute  $\left. \frac{dx}{dt} \right|_{t=1}$  using the backward difference.

| t (s) | 0 | 1 | 2 | 3   | 4   |
|-------|---|---|---|-----|-----|
| x (m) | 0 | 2 | 3 | 3.1 | 3.7 |

$$\left. \frac{dx}{dt} \right|_{t=1} \cong \frac{x(t_i) - x(t_{i-1})}{\Delta t_i} = \frac{x(2) - x(1)}{t(2) - t(1)} = \frac{2 - 0}{1 - 0}$$

$$\rightarrow \boxed{\left. \frac{dx}{dt} \right|_{t=1} \cong 2 \frac{m}{s}}$$

MATLAB Notation!!!!!!

# Example

- Compute  $\left. \frac{dx}{dt} \right|_{t=1}$  using the central difference.

| t (s) | 0 | 1 | 2 | 3   | 4   |
|-------|---|---|---|-----|-----|
| x (m) | 0 | 2 | 3 | 3.1 | 3.7 |

$$\left. \frac{dx}{dt} \right|_{t=1} \cong \frac{x(t_{i+1}) - x(t_{i-1}))}{\Delta t_{i+1} - \Delta t_i} = \frac{x(3) - x(1)}{t(3) - t(1)} = \frac{3 - 0}{2 - 0}$$

$$\rightarrow \boxed{\left. \frac{dx}{dt} \right|_{t=1} \cong 1.5 \frac{m}{s}}$$

MATLAB Notation!!!!!!

# Higher-Order Derivatives

- To obtain higher-order derivatives  $\left(\frac{d^2y}{dx^2}, etc.\right)$ , incorporate more terms of the Taylor Series expansion

$$f(x_{i-1}) = f(x_i) - (\Delta x_i) \left( \frac{dy}{dx} \Big|_{x=x_i} \right) + \left( \frac{(\Delta x_i)^2}{2} \right) \left( \frac{d^2y}{dx^2} \Big|_{x=x_i} \right) + \dots + \left( \frac{(\Delta x_i)^n}{n!} \right) \left( \frac{d^n y}{dx^n} \Big|_{x=x_i} \right)$$

- Common assumption is the data are equally spaced (constant step size)

# Higher-Order Derivatives

- [Finite difference tables](#): gives coefficients (weights) to various data points to compute high-order and/or high-accuracy derivatives

Central finite difference [\[edit\]](#)

This table contains the coefficients of the **central** differences, for several orders of accuracy and with uniform grid spacing:<sup>[1]</sup>

| Derivative | Accuracy | -5 | -4     | -3     | -2    | -1   | 0       | 1   | 2     | 3     | 4      | 5 |
|------------|----------|----|--------|--------|-------|------|---------|-----|-------|-------|--------|---|
| 1          | 2        |    |        |        |       | -1/2 | 0       | 1/2 |       |       |        |   |
|            | 4        |    |        |        | 1/12  | -2/3 | 0       | 2/3 | -1/12 |       |        |   |
|            | 6        |    |        | -1/60  | 3/20  | -3/4 | 0       | 3/4 | -3/20 | 1/60  |        |   |
|            | 8        |    | 1/280  | -4/105 | 1/5   | -4/5 | 0       | 4/5 | -1/5  | 4/105 | -1/280 |   |
| 2          | 2        |    |        |        |       | 1    | -2      | 1   |       |       |        |   |
|            | 4        |    |        |        | -1/12 | 4/3  | -5/2    | 4/3 | -1/12 |       |        |   |
|            | 6        |    |        | 1/90   | -3/20 | 3/2  | -49/18  | 3/2 | -3/20 | 1/90  |        |   |
|            | 8        |    | -1/560 | 8/315  | -1/5  | 8/5  | -205/72 | 8/5 | -1/5  | 8/315 | -1/560 |   |



# Higher-Order Derivatives

- High-order/high-accuracy schemes are best implemented in MATLAB, especially if the data is unequally spaced (many custom programs treat unequally spaced data with an advanced algorithm)
- [diffxy\(\)](#) function: NOT built-in; download from MATLAB's File Exchange
  - Not used in this class, but may want to keep it for later



# Summary

- Forward difference:  $\left. \frac{dy}{dx} \right|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_i)}{\Delta x_{i+1}} + O(\Delta x_{i+1})$
- Backward difference:  $\left. \frac{dy}{dx} \right|_{x=x_i} \cong \frac{f(x_i) - f(x_{i-1})}{\Delta x_i} + O(\Delta x_i)$
- Central difference:  $\left. \frac{dy}{dx} \right|_{x=x_i} \cong \frac{f(x_{i+1}) - f(x_{i-1}))}{\Delta x_{i+1} - \Delta x_i} + O((\Delta x_i)^2)$
- Accuracy can be increased by reducing step size and/or combining multiple Taylor Series expansions about other points
- Some schemes cannot be applied at the boundaries of a dataset (forward difference cannot be applied at the last point, etc.)
- Implement high-order/high-accuracy schemes in MATLAB if you ever need them in a future class/research