

# Linear Algebra

ME 2004

# Outline

- 1.1: Interpreting Matrices
- 1.2: Existence of Solutions
- 1.3: Uniqueness of Solutions

# 1.1: Interpreting Matrices



# Introduction

- General form of  $m$  simultaneous linear equations with  $n$  unknowns:

$$\begin{aligned}a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \cdots + a_{1n}x_n &= b_1 \\a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \cdots + a_{2n}x_n &= b_2 \\&\vdots \\a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \cdots + a_{mn}x_n &= b_m\end{aligned}$$

- $m$  rows,  $n$  columns

# Introduction

- These linear equations are condensed into:

$$Ax = b$$

$$A = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ & & \ddots & \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

# Introduction

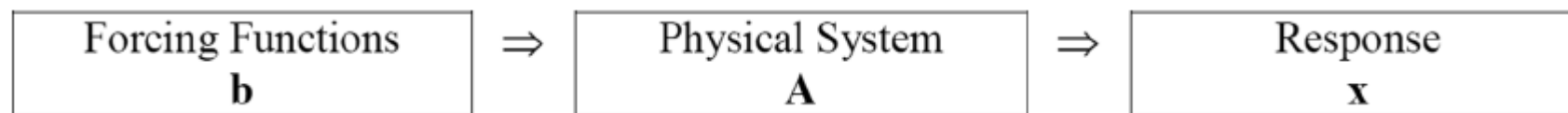
- We are usually given  $A$  and  $b$  from the governing equations, so we need to find  $x$ :

$$Ax = b \rightarrow x = A^{-1}b$$

- Many ways to compute  $x$ :
  - Row reduction/Gauss-Jordan Elimination
  - Computing  $A^{-1}$
  - LU/QR Decomposition
  - Gauss-Seidel
  - etc.

# Cause-Effect Relationship

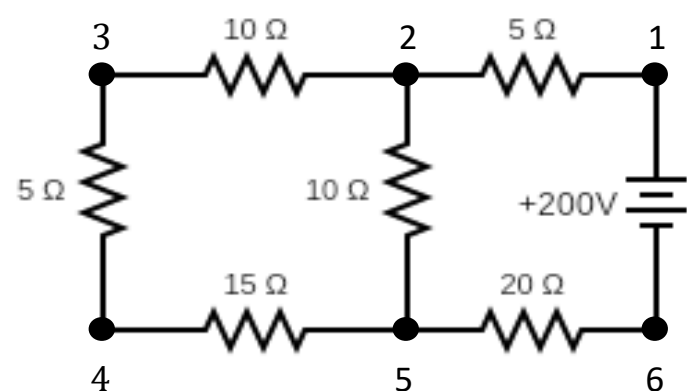
- Linear systems represent a **cause-effect relationship**:
  - $A$ : contains the **system parameters**. How do parts of the system interact?
  - $b$ : **forcing functions**. What is acting on the system?
  - $x$ : **response**. How do the independent variables react to the forcing functions?



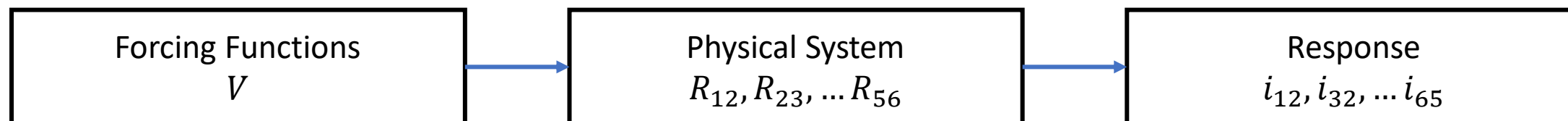


# Cause-Effect Relationship

- Finding the currents in a circuit:



$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & -1 & 0 \\ 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 10 & -10 & 0 & -15 & -5 \\ 5 & -10 & 0 & -20 & 0 & 0 \end{bmatrix} \begin{bmatrix} i_{12} \\ i_{52} \\ i_{32} \\ i_{65} \\ i_{54} \\ i_{43} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 200 \end{bmatrix}$$





# Geometric Interpretations

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

- **Row interpretation:** interpreting each row of the system as lines

$$A_{11}x_1 + A_{12}x_2 = b_1$$

$$A_{21}x_1 + A_{22}x_2 = b_2$$

- Solution: intersection of the lines

- **Column interpretation:** interpreting each column of the system as a vector

$$\begin{bmatrix} A_{11} \\ A_{21} \end{bmatrix} x_1 + \begin{bmatrix} A_{12} \\ A_{22} \end{bmatrix} x_2 = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

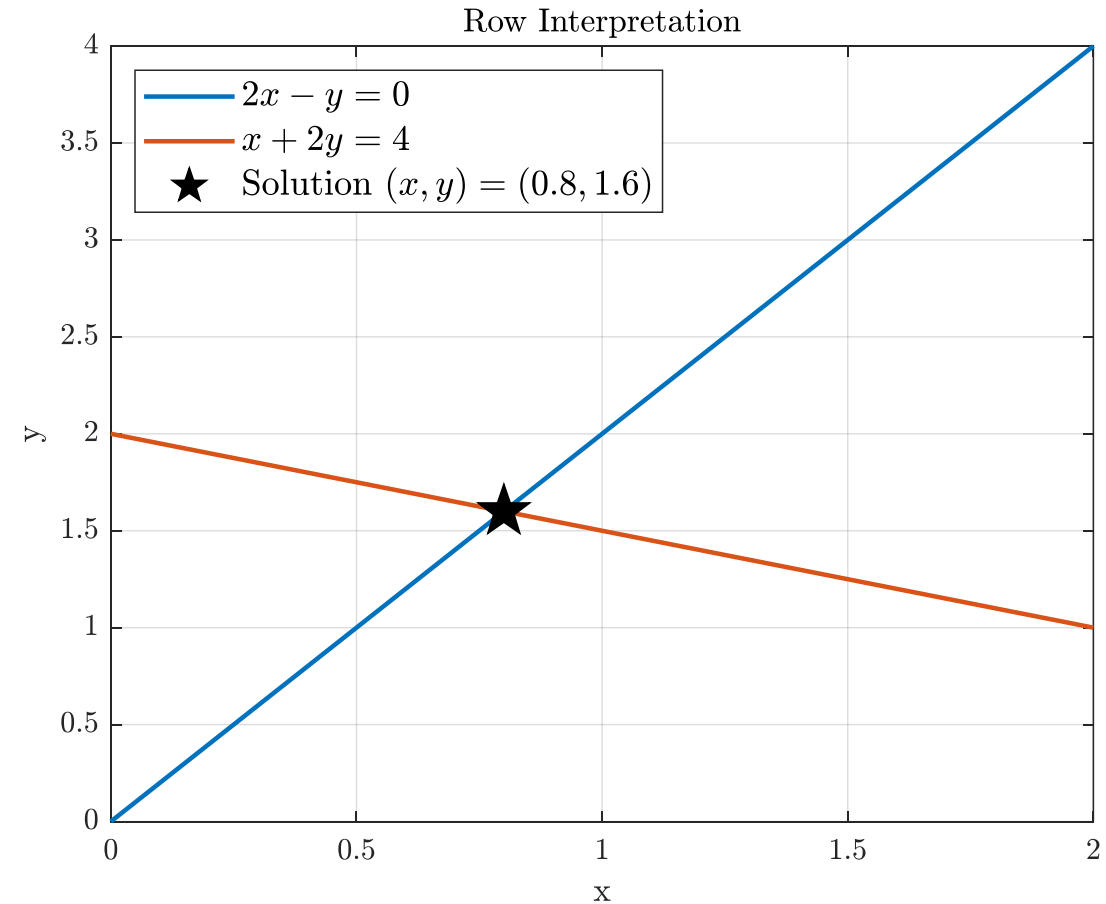
- Solution: values which form  $b$  as a linear combination of the column vectors

# Geometric Interpretations

$$\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

$$\begin{aligned} 2x - y &= 0 \\ x + 2y &= 4 \end{aligned}$$

$$\rightarrow (x, y) = (0.8, 1.6)$$



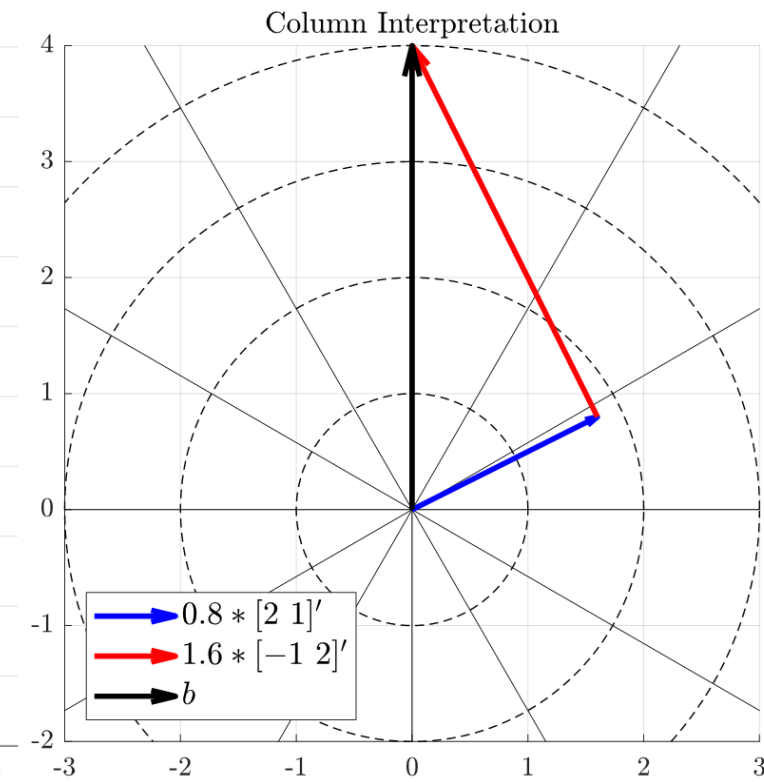
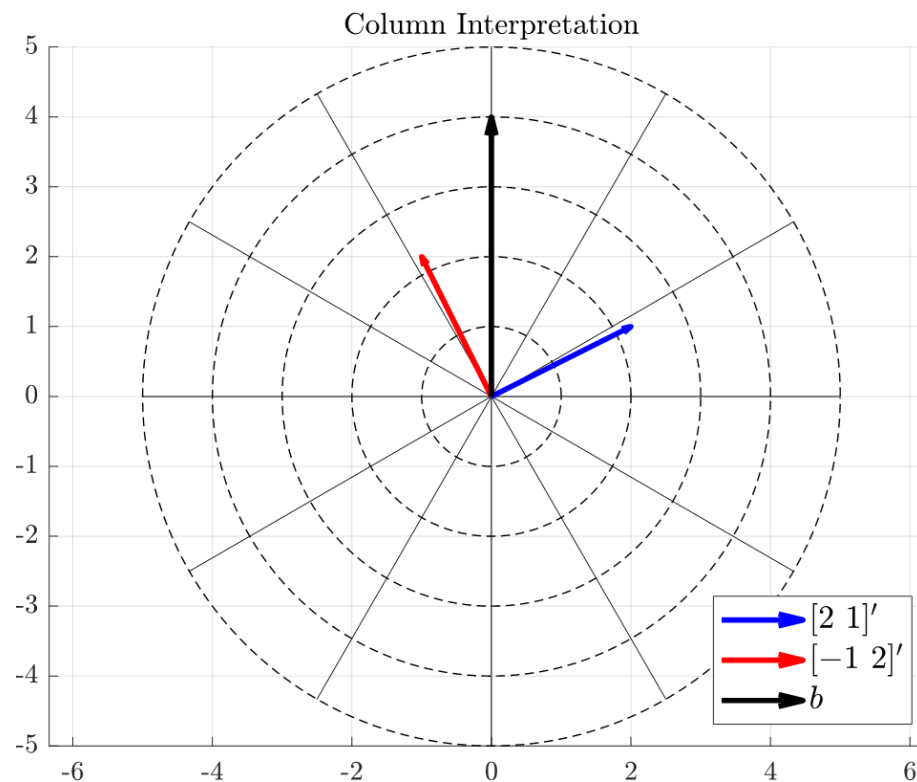


# Geometric Interpretations

$$\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} x + \begin{bmatrix} -1 \\ 2 \end{bmatrix} y = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

$$\rightarrow (x, y) = (0.8, 1.6)$$

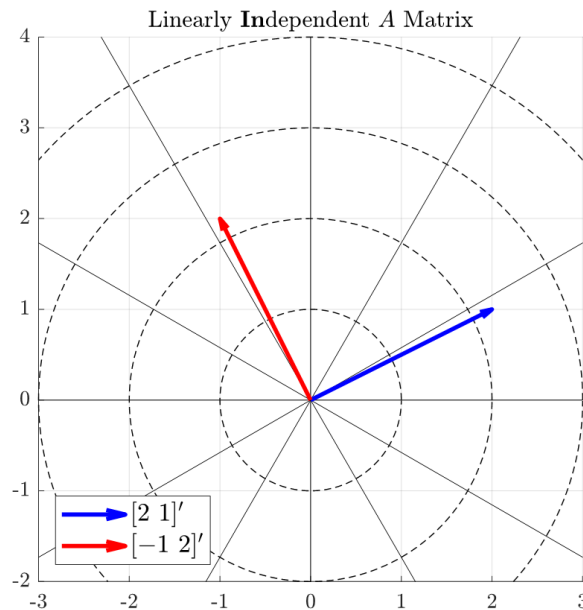


## 1.2: Existence of Solutions

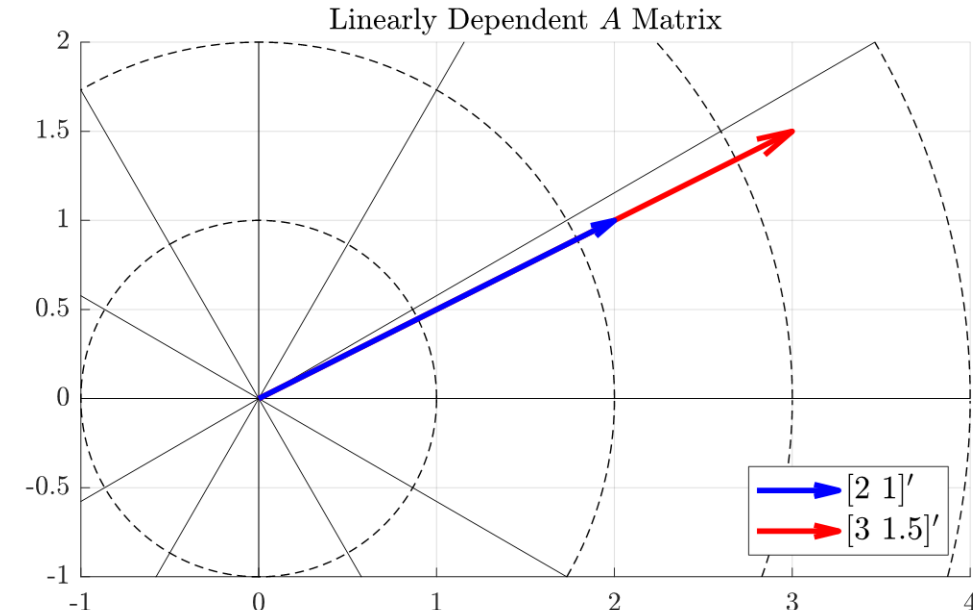


# Linear (In)Dependence

- $A$  is **linearly INdependent** if no columns are a linear combination of the other columns ( $A$  has a pivot in each row;  $\det(A) \neq 0$ , etc.)



$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \rightarrow rref(A) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix} \rightarrow rref(A) = \begin{bmatrix} 1 & 1.5 \\ 0 & 0 \end{bmatrix}$$

# Rank and Consistency

- **Rank:** number of linearly INdependent columns of  $A$ 
  - **Full rank:**  $\text{rank}(A) = \# \text{ columns of } A$
  - **Rank deficient:**  $\text{rank}(A) < \# \text{ columns of } A$
- **Consistency:** characterizes whether a system of equations has solutions
  - Augmented matrix:  $\tilde{A} = [A \ b]$
  - System is **consistent** (at least one solution exists) if  $\text{rank}(A) = \text{rank}(\tilde{A})$
  - System is **inconsistent** (solutions do not exist) if  $\text{rank}(A) \neq \text{rank}(\tilde{A})$

# Rank and Consistency

$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}, b = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

- Compute  $\text{rank}(A)$
- Compute  $\text{rank}(\tilde{A})$
- Is the system consistent?

## Command Window

```
>> A = [2 -1; 1 2]; b = [0 4]';
>> rref(A)
```

```
ans =
```

```
1 0
0 1
```

←  $A$  is linearly independent

```
>> rank(A)
```

```
ans =
```

```
2
```

←  $A$  is full rank

```
>> rank([A b])
```

```
ans =
```

```
2
```

←  $\text{rank}(\tilde{A}) = \text{rank}(A) = 2$   
→ system is consistent

# Rank and Consistency

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

- Compute  $\text{rank}(A)$
- Compute  $\text{rank}(\tilde{A})$
- Is the system consistent?

## Command Window

```
>> A = [2 3; 1 1.5]; b = [-1 6]';
>> rref(A)
```

```
ans =
```

```
1.0000    1.5000
         0         0
```

←  $A$  is linearly dependent

```
>> rank(A)
```

```
ans =
```

```
1
```

←  $A$  is rank deficient

```
>> rank([A b])
```

```
ans =
```

```
2
```

←  $\text{rank}(\tilde{A}) \neq \text{rank}(A)$   
→ system is inconsistent



## 1.3: Uniqueness of Solutions



# Uniqueness of Solutions

- A unique solution exists if:
  - $\text{rank}(A) = n$
  - $\text{rank}(\tilde{A}) = \text{rank}(A)$
- Infinite solutions exist if:
  - $\text{rank}(A) < n$
  - $\text{rank}(\tilde{A}) = \text{rank}(A)$
- No solutions exist if:
  - $\text{rank}(A) < n$
  - $\text{rank}(\tilde{A}) = \text{rank}(A) + 1$

# Uniqueness of Solutions

$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}, b = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

- Compute  $\text{rank}(A)$
- Compute  $\text{rank}(\tilde{A})$
- Is the system consistent?
  - If the system is consistent, what is/are the solution(s)?

```
>> rref([A b])
```

```
ans =
```

```
1.0000    0    0.8000
0    1.0000    1.6000
```

## Command Window

```
>> A = [2 -1; 1 2]; b = [0 4]';
```

```
>> rref(A)
```

```
ans =
```

```
1    0
0    1
```

←  $A$  is linearly independent

```
>> rank(A)
```

```
ans =
```

```
2
```

←  $A$  is full rank

```
>> rank([A b])
```

```
ans =
```

```
2
```

$\text{rank}(\tilde{A}) = \text{rank}(A) = 2$

→ system is consistent

and there is a unique solution

# Uniqueness of Solutions

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 1.5 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

- Compute  $\text{rank}(A)$
- Compute  $\text{rank}(\tilde{A})$
- Is the system consistent?
  - If the system is consistent, what is/are the solution(s)?

```
>> rref([A b])
```

```
ans =
```

```
1.0000    1.5000    0
      0         0    1.0000
```

Command Window

```
>> A = [2 3; 1 1.5]; b = [-1 6]';
>> rref(A)
```

```
ans =
```

```
1.0000    1.5000
      0         0
```

←  $A$  is linearly dependent

```
>> rank(A)
```

```
ans =
```

```
1
```

←  $A$  is rank deficient

```
>> rank([A b])
```

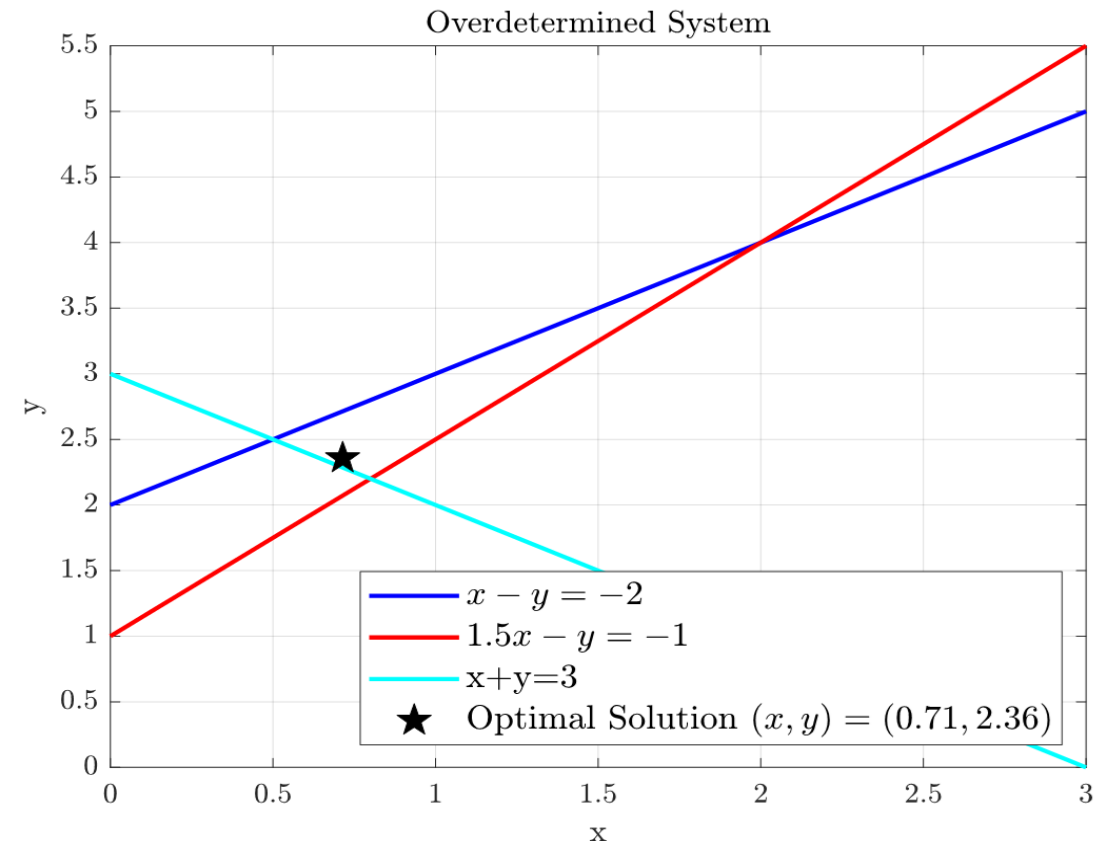
```
ans =
```

```
2
```

←  $\text{rank}(\tilde{A}) \neq \text{rank}(A)$   
→ system is inconsistent

# Over/Underdetermined Systems

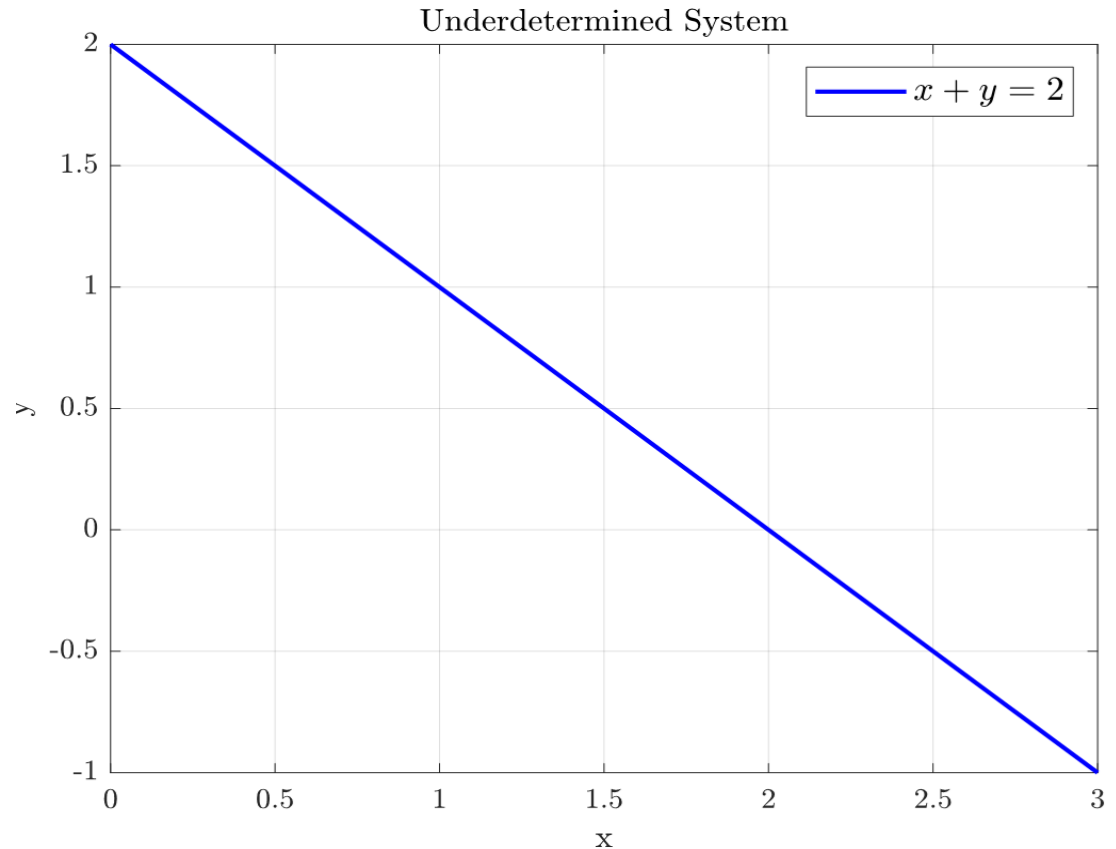
- **Overdetermined system:** more equations than unknowns ( $m > n$ )
- In general, *no solution* satisfies the system
- Application: curve fitting (least-squares regression)



$$\begin{bmatrix} 1 & -1 \\ 1.5 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix}$$

# Over/Underdetermined Systems

- **Underdetermined system:**  
more unknowns than equations ( $n > m$ )
- In general, *infinite solutions* satisfy the system
- Application: integer programming

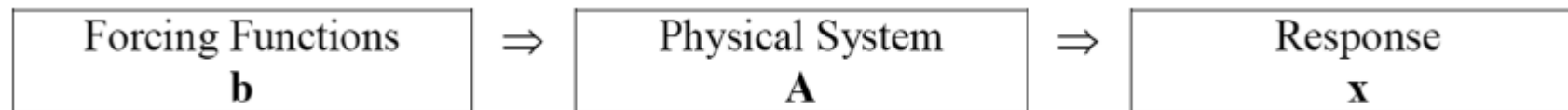


$$\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \end{bmatrix}$$

# Summary

- Express  $m$  simultaneous linear equations with  $n$  unknowns in matrix form:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix}, b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$



# Summary

## Understand the system

- What are  $A, b, x$ ?
- What are  $m, n$ ?

## Do solutions exist?

- Consistency
  - Rank
    - Linear independence

## If solutions exist, are they unique?

- Compare:
  - $\text{rank}(A)$  vs  $n$
  - $\text{rank}(A)$  vs  $\text{rank}(\tilde{A})$
- Over/underdetermined





# Summary

Review Linear Algebra terminology if you haven't already!!!

In particular:

[Invertible Matrix Theorem](#)