

# Notes in ECEN 5623

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## Bureaucracy

Liu and Layland Paper read by tuesday  
Chapter 11 in the text.  
Saturday at 5pm exercise 1 start.  
Exercise 2 starts now.  
Quiz 1 next Thursday.

## Lecture

Real-time service implementation.

Safe Resource Utilization Bound.

High-Level Design

Input and Output Hardware design and characterization.  
Services: What are they?  
System level methodology:  
UML, and such.

Space Transportation System-shuttle example.  
paper by Carlow for exercise 2.  
Ascent and entry guidelines  
Phases of flight divided into Major modes  
each mode has real-time scheduling.  
control and sensors in high frequency  
navigation in medium frequency  
guidance in low frequency  
Ask Lucy Pao about this.

sirtf caltech. [www.sirtf.caltech.edu](http://www.sirtf.caltech.edu)  
A CU example

RM assumptions:  
All services requested on periodic basis, the period is constant  
Completion time  $\leq$  Period  
Service Requests are independent (no known phasing)  
Run-time is known and deterministic.

RM constraints:  
Deadline=Period by definition

Fixed Priority, preemptive, run-to-completion scheduling

critical instant: longest response time for a service occurs when all system services are requested simultaneously

No other shared resources- not in the paper, but it is a key assumption they make

derivation of RM LUB for 2 tasks  
can you safely exceed the LUB

Note that there can be up to the  $\lceil T_2/T_1 \rceil$  releases of  $S_1$  in  $T_2$ .

Next time: finish RM LUB derivation  
discuss pitfalls  
introduce extensions to overcome pitfalls.

Quiz will be largely over chapters 1 and 2. Look at methodology.