

Black Box as a Diagnostic Reasoning Benchmark for LLMs

Assessing Hidden State Identification Through Test Selection, Constraint Tracking, and Belief Updating

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Diagnostic reasoning—identifying hidden states from observable evidence under a known causal model—is fundamental to medical diagnosis, fault detection, and troubleshooting. This study uses the classic Black Box game as a benchmark to assess LLM capabilities in diagnostic reasoning. Black Box requires the core processes of diagnosis: generating hypotheses about hidden states, selecting informative tests, tracking constraints as evidence accumulates, and updating beliefs appropriately. Unlike medical benchmarks that may reward pattern matching to training data, Black Box provides out-of-distribution problems with verifiable ground truth. We present baseline results comparing Claude model variants (Haiku, Sonnet, Opus) across prompt conditions. Our findings reveal systematic limitations in the component processes of diagnostic reasoning that persist despite scaling and prompt engineering, with implications for the deployment of LLMs in medical diagnosis and other domains requiring hidden state identification.

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1 Introduction

1.1 The Deployment Reality

AI systems are increasingly deployed for diagnostic tasks—identifying hidden states or conditions from observable evidence. Medical AI tools assist with diagnosis from imaging, lab results, and symptoms. Industrial systems perform fault diagnosis on complex machinery. Customer service agents troubleshoot technical problems through iterative questioning.

Yet deployment has outpaced our understanding of whether these systems actually perform diagnostic *reasoning* or sophisticated pattern matching. Wen et al. (2025) demonstrate that high performance on medical benchmarks—the multiple-choice question answering (MCQA) format derived from clinical licensing examinations—may reflect “context matching” rather than clinical reasoning. Their analysis invalidates three assumptions underlying MCQA-based assessment: that knowledge is applied rather than memorized, that semantic consistency leads to consistent answers, and that models can recognize situations with no valid answer.

If LLMs achieve high scores on medical board examinations through pattern matching rather than inference, benchmark performance provides false assurance about deployment readiness for genuine diagnostic tasks.

1.2 The Evaluation Crisis

The fundamental problem is that current benchmarks may not test diagnostic reasoning at all. Most medical AI benchmarks use static question-answering formats: given a case description, select the correct diagnosis from options. This tests recognition, not the iterative process of gathering evidence and refining hypotheses that characterizes actual diagnosis.

We need benchmarks that test the *process* of diagnostic reasoning, not just its end product. But creating such benchmarks in medical or industrial domains is difficult: cases are complex, ground truth is often uncertain, and training data contamination is hard to control. We need controlled environments where the component processes of diagnostic reasoning can be isolated and measured.

1.3 What is Diagnostic Reasoning?

Diagnostic reasoning is the cognitive process of identifying which hidden state (or states) is present based on observable evidence, given a known or partially known model of how hidden states produce observations.

The structure of diagnostic reasoning:

- **Given:** A causal model mapping hidden states to observations (diseases cause symptoms; faults cause error codes; atom configurations cause ray behaviors)
- **Task:** Identify which hidden state is present based on observations
- **Process:** Iteratively gather evidence and refine hypotheses until confident

Diagnostic reasoning is distinct from:

- **Causal structure discovery:** Learning *what causes what* (the causal graph itself)
- **Causal effect estimation:** Measuring *how much* an intervention affects an outcome
- **Mechanism discovery:** Understanding *how* a cause produces its effect

In diagnostic reasoning, we typically know (or assume) the causal structure—we know that certain diseases cause certain symptoms, or that certain faults produce certain error patterns. The challenge is identifying *which* specific state from a known set is present.

Component processes of diagnostic reasoning:

Process	Description
Hypothesis Generation	Generate candidate hidden states that could explain observations
Forward Reasoning	Predict what observations would occur under each hypothesis
Test Selection	Choose which observation to gather next to best discriminate among hypotheses
Constraint Tracking	Maintain which hidden states have been ruled in or out
Belief Updating	Revise hypothesis probabilities when new evidence arrives
Stopping Decision	Decide when evidence is sufficient to commit to a diagnosis

These processes must be *integrated*: test selection depends on current hypotheses; hypotheses depend on accumulated evidence; the decision to stop depends on confidence in the leading hypothesis. Failures in any component can cascade through the diagnostic process.

1.4 Black Box as a Diagnostic Instrument

We propose the Black Box game as a diagnostic instrument for understanding LLM reasoning limitations. Black Box is a classic deduction game designed by Eric Solomon in 1978 (Wikipedia contributors 2024). Players face an 8×8 grid containing four hidden “atoms” at unknown locations. By firing rays into the grid and observing their behavior—absorption, deflection, or reflection—players must infer the atom positions.

Black Box is not merely another game benchmark. It is a *minimal realization of diagnostic reasoning*—requiring all six component processes in an integrated task:

Diagnostic Process	Black Box Analog
Hypothesis Generation	Consider which atom configurations could explain observations
Forward Reasoning	Predict ray behavior under a hypothesized configuration
Test Selection	Choose which ray to fire next to discriminate among hypotheses
Constraint Tracking	Maintain which cells are ruled out by accumulated evidence
Belief Updating	Revise candidate configurations when new ray results arrive
Stopping Decision	Decide: fire more rays or commit to a guess?

This structural correspondence makes Black Box findings informative about diagnostic reasoning generally, while providing advantages that clinical or scientific domains lack:

1. **Out-of-distribution:** While the rules are simple and fully specifiable, any particular game configuration is almost certainly not in training data
2. **Ground truth:** We know the correct atom positions and can precisely measure both forward reasoning accuracy (Predict mode) and inverse reasoning accuracy (Play mode)
3. **Decomposable errors:** We can analyze extended thinking traces to categorize failures as occurring in experiment design, world model simulation, constraint tracking, or belief updating

1.5 Addressing the Spatial Reasoning Confound

A methodological concern is whether Black Box’s spatial reasoning requirements confound interpretation. Many diagnostic reasoning problems—medical diagnosis, fault detection, troubleshooting—do not involve spatial relationships, so spatial failures on Black Box might not predict failures on non-spatial diagnostic tasks.

We address this through experimental design. Our two-mode structure allows partial decomposition:

- **Predict mode** tests forward reasoning (heavily spatial): given atom positions, trace the ray’s path
- **Play mode** tests the full diagnostic loop: spatial reasoning is one input, but experiment design, abductive inference, and constraint tracking are the primary challenges

Comparing performance across modes provides diagnostic information: good Predict performance with poor Play performance would implicate non-spatial reasoning limitations (abduction, constraint tracking, experiment design), while poor performance on both would suggest spatial reasoning is at least partly responsible.

Additionally, we use *mean atoms per ray*—a measure of spatial complexity—as a moderator variable. If treatment effects (model, prompt style, extended thinking) are constant across spatial complexity, the limitations lie in inferential machinery rather than spatial processing. If effects are moderated by spatial complexity, spatial reasoning contributes to observed failures.

Finally, we analyze extended thinking traces to categorize errors:

- **Spatial errors:** Ray path traced incorrectly
- **Constraint errors:** Failed to track ruled-out positions
- **Experiment design errors:** Fired uninformative rays
- **Belief updating errors:** Did not revise hypotheses when evidence contradicted them

Black Box alone cannot fully separate spatial from non-spatial limitations. However, our findings can be triangulated with non-spatial benchmarks (ZebraLogic for constraint satisfaction, LogicGame for rule-based planning) to identify common factors. If LLMs fail on Black Box *and* on non-spatial reasoning benchmarks, the shared limitation is inferential machinery, not spatial processing specifically.

1.6 Research Questions

This study addresses the following questions:

1. **Diagnostic Reasoning Capability:** Can LLMs perform the integrated reasoning loop required for diagnostic inference on novel problems?
2. **Forward vs. Inverse Reasoning:** Do limitations arise primarily in world model simulation (Predict mode) or in the inferential machinery of hypothesis generation and updating (Play mode)?
3. **Decomposition of Failures:** What proportion of errors reflect spatial reasoning failures versus non-spatial failures (constraint tracking, experiment design, belief updating)?
4. **Prompt and Scaffold Effects:** Do augmented instructions, visualizations, or extended thinking improve performance, and do these effects interact with spatial complexity?
5. **Scaling Effects:** Do larger models show improved diagnostic reasoning, and if so, is improvement sufficient to approach human-level competence?
6. **Implications for Deployment:** What do the observed limitations suggest about the readiness of LLMs for medical diagnosis, fault detection, and other diagnostic tasks?

2 Literature Review

The case for Black Box as a diagnostic instrument rests on documented limitations in each component capability required for diagnostic reasoning. If LLMs struggle with constraint satisfaction, spatial reasoning, world model simulation, and abductive inference *in isolation*, we should expect compounding failures when these capabilities must be integrated. The literature reviewed below provides this supporting evidence, organized by the component capabilities Black Box requires.

A comprehensive survey by Giadikiaroglou et al. (2024) provides a useful taxonomy for understanding LLM puzzle-solving capabilities. They distinguish between *rule-based puzzles* (with explicit victory conditions and game rules, including deterministic puzzles like Sudoku and Chess, and stochastic puzzles like Minesweeper and Poker) and *rule-less puzzles* (requiring world knowledge and inference, such as riddles and commonsense reasoning). Black Box falls squarely in the rule-based deterministic category, making findings from this literature directly relevant. The survey notes that advanced prompting methods like Tree-of-Thoughts and Everything-of-Thoughts yield improvements of 26-70% over basic Chain-of-Thought on deterministic puzzles, yet “significant challenges in complex puzzle scenarios” persist, revealing gaps between LLM capabilities and human-like reasoning.

2.1 Constraint Satisfaction and LLMs

Constraint satisfaction problems (CSPs) require finding values for variables that satisfy a set of constraints. Classic examples include Sudoku, scheduling problems, and logic puzzles. Recent research has systematically evaluated LLM performance on such tasks.

The ZebraLogic benchmark (Lin et al. 2024) evaluates LLMs on logic grid puzzles (also known as Zebra puzzles), a well-established CSP format used in standardized tests like the LSAT. Results indicate that while LLMs show some capability on simple puzzles, performance degrades substantially as problem complexity increases. The benchmark reveals that LLMs lack several abilities required for complex logical reasoning, including counterfactual thinking, reflective reasoning, and compositional generalization.

Bonlarron, Régis, and De Maria (2024) demonstrate that LLMs “excel at generating fluent text but struggle to enforce external constraints because they generate tokens sequentially without explicit control mechanisms.” Their GenCP framework addresses this by combining LLM predictions with constraint programming (CP) reasoning, treating text generation as a CSP. This hybrid approach significantly outperforms pure LLM methods, suggesting that constraint satisfaction may require symbolic reasoning components that LLMs lack.

Michailidis, Tsouros, and Guns (2024) evaluated LLMs on translating natural language problem descriptions into formal constraint models. They found that zero-shot prompting yields essentially no success, and even few-shot prompting produces inconsistent results. This aligns

with Freuder (2024)’s observation that successful constraint satisfaction often requires iterative refinement through dialogue, not single-shot generation.

The LogicGame benchmark (Gui et al. 2024) directly evaluates rule-based reasoning—the ability to understand, execute, and plan according to predefined rules. Using game scenarios at varying difficulty levels, they found that even the best-performing model (claude-3.5-sonnet) achieves only 19.15% overall accuracy, with performance falling below 20% on complex tasks requiring multi-step planning. Critically, they observed that while execution tasks improve modestly with few-shot examples, planning tasks often *deteriorate* with additional demonstrations, and any improvements diminish substantially at higher difficulty levels. This suggests that LLMs struggle not just with constraint tracking but with the multi-step planning required to design informative experiments.

The implications for Black Box are direct: tracking which cell locations are ruled out by each ray observation is fundamentally a constraint satisfaction problem. If LLMs struggle with CSPs generally, they should struggle with the constraint-tracking aspect of Black Box.

2.2 Spatial Reasoning Limitations

Spatial reasoning—the ability to mentally represent and manipulate spatial relationships—is a well-documented weakness of current LLMs.

The PLUGH benchmark (Tikhonov et al. 2024) evaluates spatial understanding and reasoning using text adventure game scenarios that require building mental maps from textual descriptions. Results show that while some commercial LLMs exhibit moderate reasoning abilities, “all models still have significant room for improvement.” The benchmark identifies typical failure modes including difficulty maintaining consistent spatial representations across multiple textual updates.

Chen et al. (2024) conducted an empirical analysis of spatial reasoning in large multimodal models, finding that even GPT-4o achieves only 27.5% accuracy on questions requiring reasoning from a human’s viewpoint in an image. Performance degrades further on multi-hop spatial reasoning questions that require integrating multiple spatial relationships.

Bos (2024) provides a practitioner’s perspective on LLM spatial reasoning, noting that “all of the LLMs failed immediately on the easiest problems” involving mental box folding—a standard spatial reasoning task in human cognitive assessments. Interestingly, LLMs performed better on reasoning about objects in photographs than on abstract spatial diagrams, suggesting reliance on statistical patterns from image-caption training data rather than genuine spatial reasoning.

A synthesis of spatial reasoning research (Quan et al. 2025) notes that “empirical assessments consistently show a characteristic pattern: models exhibit moderate competence in simple, direct spatial tasks but rapidly deteriorate as the problem scale or compositional/geometric

complexity increases, with performance losses ranging from 42% to over 80% as task complexity grows.”

The BALROG benchmark (Paglieri et al. 2024) evaluates LLMs and vision language models on diverse game environments ranging from tasks “solvable by non-experts in seconds to extremely difficult challenges like NetHack requiring years to master.” Their findings reveal that current models achieve only partial success on simpler games but “struggle significantly with more challenging tasks.” Most striking is their discovery of “severe deficiencies in vision-based decision-making”—several models actually perform *worse* when given visual representations of environments compared to text-only descriptions. This counterintuitive result suggests that visual processing may introduce noise rather than helpful spatial information.

J. Wang et al. (2025) addresses a related challenge: tasks requiring both semantic understanding and adherence to visual grid constraints. Using crossword puzzles as a benchmark, they demonstrate that “mathematical reasoning training doesn’t necessarily generalize to tasks requiring linguistic and spatial integration.” This finding is particularly relevant to Black Box, which similarly requires integrating rule-based reasoning (ray physics) with spatial constraint tracking (grid positions).

For Black Box, ray tracing requires understanding how rays move through 2D space and how they deflect upon encountering atoms. The documented limitations in spatial reasoning suggest LLMs will struggle with accurate ray path simulation.

2.3 Reasoning Complexity and Performance Collapse

A critical question for evaluating LLM reasoning is how performance scales with problem complexity. Shojaee et al. (2025) provide a systematic investigation using controllable puzzle environments that allow precise manipulation of compositional complexity while maintaining consistent logical structures.

Their findings reveal three distinct performance regimes. In low-complexity tasks, standard models surprisingly outperform reasoning models (those using extended thinking or chain-of-thought), suggesting that extended reasoning can introduce unnecessary complexity for simple problems. In medium-complexity tasks, extended thinking provides clear advantages, demonstrating the intended benefit of reasoning-augmented models. However, in high-complexity tasks, both standard and reasoning models exhibit complete accuracy collapse—a fundamental ceiling that persists regardless of model capability or available computational resources.

Particularly striking is their observation that reasoning models exhibit *declining effort* at higher complexity levels despite adequate token budgets. Rather than leveraging available computational resources more intensively when problems become harder, models show inconsistent reasoning patterns across similar problems. This suggests that current reasoning mechanisms are not genuinely algorithmic but rather approximate heuristics that fail when problems exceed certain complexity thresholds.

The PuzzlePlex benchmark (Authors 2025b) extends this analysis to multi-turn adversarial environments, evaluating LLM reasoning and planning across 24 diverse puzzles including both deterministic and stochastic games. Their findings are sobering: “LLMs still significantly lag behind even simple heuristics in puzzles.” This result suggests that the limitations are not merely about single-step reasoning accuracy but extend to the sequential decision-making and strategic planning that characterizes game play. For tasks requiring iterative hypothesis refinement based on accumulated evidence—like Black Box—this predicts systematic failures in experiment design and belief updating.

For Black Box, these findings predict a non-linear relationship between game difficulty (determined by atom configurations, number of atoms, and observation ambiguity) and model performance. Simple configurations may be solved adequately, but complex configurations requiring deep inference chains should trigger the same “reasoning collapse” observed across other puzzle domains.

2.4 World Models and Mental Simulation

A “world model” refers to an internal representation that can be used to simulate how states evolve over time. The question of whether LLMs possess genuine world models—versus sophisticated pattern matching—is actively debated.

Harig et al. (2025) investigated this question using mechanical reasoning about pulley systems. Their findings are striking: while LLMs showed some ability to estimate mechanical advantage, they appeared to use a “pulley counting heuristic” rather than genuine simulation. The best model (GPT-4o) achieved only 26.1% accuracy on exact predictions. When problems were modified to be superficially similar but mechanically different, performance collapsed, suggesting “abilities are often fragile and dependent on superficial features rather than deep understanding.”

R. Wang et al. (2024) directly tested whether LLMs can serve as text-based world simulators. Using a benchmark of 76,369 state transitions from text adventure games, they found that GPT-4’s best single-step accuracy was 59.9%. Because simulation errors accumulate, after 10 steps the expected accuracy drops to less than 1% (0.599^{10}). They conclude that “LLMs are not yet able to reliably act as text world simulators.”

This literature suggests that LLMs may appear to reason about world dynamics but are actually relying on heuristic shortcuts that fail when problems require genuine simulation. For Black Box’s “Predict” mode—where the model must trace a ray’s path given known atom positions—we should expect systematic errors reflecting heuristic approximation rather than accurate simulation.

However, recent work suggests that targeted post-training on decision-making games can substantially improve LLM reasoning in those specific domains. Y. Wang et al. (2025) developed data synthesis strategies for training LLMs on Doudizhu (a Chinese card game) and Go,

demonstrating that game-based training data can complement traditional code and mathematics datasets for reasoning enhancement. Their “Mastermind” models achieved 90% action accuracy matching expert data and 98% similarity in thought processes for Doudizhu. Critically, this approach uses hierarchical training pipelines that decompose complex decisions into subtasks—possible action prediction, opponent strategy modeling, and final action selection—rather than relying on direct policy learning.

For our purposes, this work highlights an important distinction: Black Box is designed as an *out-of-distribution* benchmark that tests zero-shot reasoning capabilities on novel configurations. The success of task-specific training reported by Y. Wang et al. (2025) does not contradict predictions of poor zero-shot performance; rather, it suggests that observed limitations may reflect training distribution gaps rather than fundamental architectural constraints. Whether fine-tuning on Black Box traces would improve performance—and whether such improvement would generalize to other spatial reasoning tasks—remains an empirical question addressed in our future directions.

2.5 Abductive Reasoning and Hypothesis Generation

Abductive reasoning—inferring the most plausible explanation for observations—is the core inferential process in diagnostic reasoning. A growing body of research examines LLM capabilities in this domain.

Yang et al. (2025) provides a comprehensive framework for understanding LLM hypothesis discovery, organizing methods according to Peirce’s reasoning paradigm: abduction (hypothesis generation), deduction (hypothesis application), and induction (hypothesis validation). They note that “most existing work assessing LLM reasoning centers almost exclusively on multi-step deductive tasks, leaving abduction and induction, the engines of hypothesis discovery, largely unexplored.”

Z. Wang et al. (2025) directly tests whether LLMs follow Occam’s Razor—the principle of preferring simpler explanations. Using a synthetic benchmark (InAbHyD) designed to test inductive and abductive reasoning, they find that “current LLMs can’t generate high-quality hypotheses that match human-level intelligence.” LLMs frequently produce overly complex explanations when simpler ones suffice, failing a fundamental principle of diagnostic reasoning.

Liu, Neubig, and Andreas (2024) characterizes the current state as “an incomplete loop,” arguing that while LLMs can perform some aspects of each reasoning type, they fail to integrate abduction, deduction, and induction into a coherent reasoning cycle. This fragmentation prevents genuine hypothesis-driven inquiry.

Rodriguez et al. (2025) argues from a theoretical perspective that LLMs face fundamental limitations in abductive reasoning: “(1) They cannot work with counterfactuals, relying only on correlational datasets. (2) They are unable to perform true abductive reasoning.” While

LLMs may appear to generate hypotheses, this reflects parameter-controlled variation rather than genuine inference to the best explanation.

For Black Box, the inverse problem—inferring atom locations from ray observations—is quintessentially abductive. The literature predicts systematic failures in generating parsimonious hypotheses and in appropriately updating beliefs as evidence accumulates.

2.6 Test Selection in Diagnostic Reasoning

A distinguishing feature of diagnostic reasoning is *active* test selection—choosing which observations to gather based on current hypotheses to maximally discriminate among candidate diagnoses. Most LLM benchmarks present static problems where all information is provided upfront. Few benchmarks test the ability to strategically select tests and iteratively refine hypotheses.

Auto-Bench (Authors 2025a) evaluates LLMs on a task structurally similar to diagnosis: discovering hidden graph structures through iterative experimentation. The task proceeds in cycles: the model receives previous observations, proposes a hypothesis about the hidden structure, and designs an intervention to test that hypothesis. An oracle executes the intervention and returns new observations, continuing until the hypothesis matches ground truth or a limit is reached. This directly parallels diagnostic reasoning: observe effects, hypothesize hidden states, select tests to discriminate. The key finding is that LLMs struggle with strategic test selection—they often propose uninformative experiments that fail to disambiguate among hypotheses.

This finding is particularly relevant for Black Box. Effective play requires selecting rays that maximally constrain the hypothesis space—firing into regions where different candidate configurations would produce different outcomes. Random or poorly-chosen rays waste resources and may never converge on the correct answer. The documented failures in Auto-Bench predict that LLMs will struggle with strategic ray selection in Black Box’s Play mode.

2.7 Base Rate Neglect in Clinical Diagnosis

A particularly consequential manifestation of abductive reasoning failure is base rate neglect—the tendency to overweight salient observations while underweighting prior probabilities. Omar et al. (2025) provide the first large-scale demonstration of this phenomenon in LLMs applied to clinical diagnosis.

Using 300 synthetic clinical vignettes tested across 20 LLMs with approximately 1.8 million responses, they found that models systematically selected rare “zebra” diagnoses linked to salient but non-decisive cues (such as travel history or animal exposure) more often than epidemiologically correct diagnoses (49.8% vs 37.7%). This pattern persisted even when models were explicitly asked to identify the “most likely” diagnosis. Critically, prompts that explicitly invoked base rates and epidemiology reduced but did not eliminate this saliency bias.

The implications are profound: LLMs that achieve high performance on medical board examinations—demonstrating factual knowledge of disease prevalence and diagnostic criteria—nevertheless fail to appropriately weight this knowledge when salient distractors are present. As the authors note, this represents “associative pattern matching rather than stable probabilistic reasoning.” Training on medical literature, which overrepresents rare and dramatic conditions in case reports and teaching materials, may systematically bias models toward zebra diagnoses.

For Black Box, this finding suggests that even when LLMs possess accurate knowledge of ray physics, they may be systematically distracted by salient features of observations (e.g., absorption events, unusual deflection patterns) at the expense of systematic constraint tracking and hypothesis evaluation. The base rate neglect documented in clinical diagnosis may manifest as premature hypothesis commitment or failure to consider the full space of configurations consistent with accumulated evidence.

2.8 Implications for Diagnostic AI Systems

The limitations documented above converge on a concerning picture for LLM deployment in diagnostic contexts.

The LLM-Modulo framework (Kambhampati et al. 2024; Valmeekam et al. 2023) proposes a pragmatic response: accept that LLMs cannot plan or reason reliably, but use them as components within hybrid systems that include external verifiers and symbolic reasoners. Under this view, the LLM’s role is translation and suggestion, not autonomous diagnostic reasoning. A physician might use an LLM to suggest differential diagnoses, but should not rely on it to track constraints or select optimal tests.

This matters because AI diagnostic systems are already being deployed. Medical AI tools assist with diagnosis from imaging, lab results, and symptoms. Industrial systems perform fault diagnosis on complex machinery. The failure modes documented throughout this review—failure to track constraints, inability to select informative tests, base rate neglect, and premature hypothesis commitment—map directly onto the requirements of diagnostic reasoning.

Diagnostic benchmarks that can characterize *when* and *why* these failures occur are needed before broader deployment in high-stakes diagnostic domains.

2.9 Summary: Predictions for Diagnostic Reasoning in Black Box

Based on the documented limitations in component processes of diagnostic reasoning, we derive the following predictions:

1. **Forward reasoning (Predict mode)** will show substantial errors, consistent with documented failures in spatial reasoning and world model simulation.

2. **Inverse reasoning (Play mode)** will show even greater errors, as it compounds spatial reasoning with abductive inference and constraint satisfaction.
3. **Prompt engineering** will provide modest improvements but will not overcome fundamental limitations.
4. **Scaling** (larger models) will show improvement but not to human-level performance.
5. **Error patterns** will reveal heuristic approximation rather than systematic reasoning—e.g., over-reliance on surface features, failure to track constraints, non-parsimonious hypotheses.
6. **Tool augmentation** (e.g., giving the LLM a ray-tracing verifier) will help with verification but not with hypothesis generation, as the limitation is in search/inference, not just simulation.
7. **Uninformative test selection:** Following findings from Auto-Bench (Authors 2025a), models will frequently choose rays that fail to disambiguate among hypotheses—firing into already-constrained regions or missing opportunities for informative observations. Strategic test selection requires anticipating which observations would most reduce uncertainty, a capability that current models lack.
8. **Complexity-dependent collapse:** Following Shojaee et al. (2025), performance will show a non-linear pattern—adequate performance on simple configurations but catastrophic failure on complex configurations requiring extended inference chains, regardless of available thinking budget.
9. **Saliency-driven distraction:** Following Omar et al. (2025), models will be systematically distracted by salient observations (e.g., absorption events, dramatic deflections) and may anchor prematurely on hypotheses suggested by striking but non-decisive evidence, even when simpler explanations are more consistent with the full observation set.
10. **Spatial-inferential decomposition:** If spatial reasoning is the primary bottleneck, we expect:
 - (a) poor Predict mode performance,
 - (b) treatment effects moderated by spatial complexity (mean atoms per ray), and
 - (c) error traces dominated by ray path miscalculations. If inferential machinery is the primary bottleneck, we expect:
 - (c) relatively better Predict than Play performance, (b) treatment effects constant across spatial complexity, and
 - (c) error traces showing constraint tracking failures, uninformative experiment choices, and belief updating errors.
11. **Convergent validity:** If Black Box limitations reflect general diagnostic reasoning failures rather than spatial-specific failures, we expect correlations with findings from non-spatial benchmarks (ZebraLogic, LogicGame). Models that perform poorly on constraint satisfaction and rule-based planning should also perform poorly on Black Box’s non-spatial components.

3 Methods

3.1 The Black Box Game Implementation

We implemented Black Box as a web-based application using React, allowing both human play and automated LLM interaction through the Anthropic API. The implementation follows standard Black Box rules:

- **Grid:** 8×8 cells, with 4 randomly placed atoms (non-adjacent placement enforced)
- **Rays:** Fired from any of 32 edge positions (8 per side)
- **Ray behavior:**
 - Direct hit on atom: **Absorbed** (marked “H” for hit)
 - Atom diagonally adjacent to entry cell: **Reflected** (marked “R”)
 - Atom diagonally adjacent to path: **Deflected** 90° away from atom
 - Atoms on both sides of path: **Reflected** (reverses direction)
 - Clear path: Ray exits at opposite edge

3.2 Task Modes

3.2.1 Predict Mode (Forward Reasoning)

In Predict mode, the LLM is shown: - The 8×8 grid with atom positions marked - A ray entry point (e.g., “NORTH-4”)

The LLM must predict the ray’s outcome: exit position, absorption, or reflection. This tests world model accuracy—can the LLM correctly simulate ray physics?

3.2.2 Play Mode (Inverse Reasoning)

In Play mode, the LLM:
- Receives the game rules
- Chooses which rays to fire (up to 20)
- Receives feedback after each ray (exit position, absorption, or reflection)
- Must guess all 4 atom positions

This tests the full reasoning pipeline: experiment design, observation integration, constraint tracking, and abductive inference.

3.3 Prompt Conditions

We developed two prompt styles with optional visualization augmentation:

3.3.1 Baseline (Human-Equivalent)

Comprehensive instructions adapted from the traditional Emacs Black Box rules, comparable to what a human player would receive. The prompt includes:

- Complete rules with ASCII diagram examples showing deflection, reflection, and absorption
- Scoring information (rays cost points, missed atoms cost 5 points each)
- JSON response format specification

Key excerpt:

Your opponent has hidden 4 balls within this box. By shooting rays into the box and observing where they emerge, it is possible to deduce the positions of the hidden balls.

There are three possible outcomes for each ray you send into the box:

- DETOUR: The ray is deflected and emerges somewhere other than where you sent it in.
- REFLECTION (R): The ray is reflected and emerges in the same place it was sent in.
- HIT (H): The ray strikes a ball directly and is absorbed.

3.3.2 Augmented

Extended instructions including:

- Explicit coordinate system explanation
- Detailed deflection geometry with worked examples
- Strategy guidance (triangulation, multiple rays)
- Common error warnings
- Explicit note that single observations are typically ambiguous

3.3.3 Visualization Options

Either prompt style can be combined with:

- **Include Visualization:** Text-based board visualization showing current state
- **VoT (Visualization of Thought) Options:**
 - Grid State (Play only): Shows current board state in prompt
 - Ray Trace: Shows ray path visualization
 - Hypothesis (Play only): Shows marked hypothesis positions

3.4 Models

We evaluated three Claude 4.5 model variants:

- **Claude Haiku 4.5** (`claude-haiku-4-5-20251001`): Smallest, fastest
- **Claude Sonnet 4.5** (`claude-sonnet-4-5-20250929`): Mid-tier
- **Claude Opus 4.5** (`claude-opus-4-5-20251101`): Largest, most capable

All models were accessed through the Anthropic API with extended thinking enabled to capture reasoning processes.

3.5 Experimental Design

The experiment uses a factorial design with factors that differ slightly between Predict and Play modes. Ten fixed atom configurations ensure reproducibility across conditions.

3.5.1 Predict Mode Factors

Factor	Levels	Description
Model	Haiku 4.5, Sonnet 4.5, Opus 4.5	Model variant
Prompt Style	Baseline, Augmented	Human-equivalent vs. detailed strategy guidance
Extended Thinking	Yes (with budget), No	Enable extended thinking with token budget
VoT Ray Trace	Yes, No	Include ray trace visualization in prompt
Atom Configuration	10 fixed configurations	Predetermined atom placements for reproducibility

Model	Prompt	Extended Thinking	Vot (None, B Ray Trace)
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	None
*Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	VoT B Ray Trace Visualization
*Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	None
*Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	VoT B Ray Trace Visualization

Model	Prompt	Extended Thinking	VoT (None, B Ray Trace)
*Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	None
*Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	VoT B Ray Trace Visualization
*Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	None
*Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	VoT B Ray Trace Visualization

3.5.2 Play Mode Factors

Play Mode Experiment Log

Table 5: Play Mode Experiment Log

Model	Prompt	Extended Thinking	VoT (None, A, B, or C)
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	None
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	VoT A Grid State Tracking
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	VoT B Ray Trace Visualization
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	No	VoT C Hypothesis Verification
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	None
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	VoT A Grid State Tracking
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	VoT B Ray Trace Visualization
Haiku 4.5, Sonnet 4.5, Opus 4.5	baseline	10K	VoT C Hypothesis Verification
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	None
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	VoT A Grid State Tracking
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	VoT B Ray Trace Visualization

Model	Prompt	Extended Thinking	VoT (None, A, B, or C)
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	No	VoT C Ray Trace Visualization
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	None
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	VoT A Grid State Tracking
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	VoT B Ray Trace Visualization
Haiku 4.5, Sonnet 4.5, Opus 4.5	augmented	10K	VoT B Ray Trace Visualization

Play mode includes all Predict mode factors plus additional factors for hypothesis management:

Factor	Levels	Description
Model	Haiku 4.5, Sonnet 4.5, Opus 4.5	Model variant
Prompt Style	Baseline, Augmented	Human-equivalent vs. detailed strategy guidance
Include Visualization	Yes, No	Text board visualization in prompt
Extended Thinking	Yes (with budget), No	Enable extended thinking with token budget
Allow Hypotheses	Yes, No	Enable mark/unmark/check actions for hypothesis tracking
VoT Grid State	Yes, No	Show current grid state in prompt (VoT Option A)
VoT Ray Trace	Yes, No	Include ray trace visualization (VoT Option B)
VoT Hypothesis	Yes, No	Show hypothesized atom positions (VoT Option C)
Atom Configuration	10 fixed configurations	Predetermined atom placements for reproducibility

3.5.3 Atom Configurations

Ten fixed atom configurations are used for reproducible experiments:

Config	Pattern	Positions
1	Spread	(2,3), (3,6), (6,2), (7,7)
2	Cluster in corner	(1,1), (1,3), (2,2), (5,6)
3	Diagonal	(2,2), (4,4), (6,6), (8,8)
4	Edge-heavy	(1,4), (4,8), (8,5), (5,1)
5	Central cluster	(3,4), (4,3), (4,5), (5,4)
6	L-shape	(2,2), (2,3), (2,4), (4,2)
7	Corners	(1,1), (1,8), (8,1), (8,8)
8	Asymmetric	(2,7), (3,2), (6,5), (7,3)
9	Row cluster	(4,2), (4,4), (4,6), (4,8)
10	Mixed	(1,5), (3,3), (5,7), (8,2)

3.5.4 Predict Mode Procedure

For each experimental condition (model \times prompt style \times visualization \times thinking \times VoT):

1. For each of the 10 fixed atom configurations:
 - a. For each of 32 possible ray entry points:
 - Present atom positions and ray entry to LLM
 - Record predicted outcome (exit position, absorption, or reflection)
 - Compare to ground-truth ray trace
 - b. Compute accuracy metrics for this configuration
2. Aggregate accuracy across configurations

3.5.5 Play Mode Procedure

For each experimental condition (model \times prompt style \times visualization \times thinking \times hypotheses \times VoT options):

1. For each of the 10 fixed atom configurations:
 - a. Initialize game with hidden atom positions
 - b. LLM selects rays iteratively (max 20)
 - c. After each ray, provide outcome feedback
 - d. If hypotheses enabled, LLM can mark/unmark suspected positions
 - e. LLM submits final guess of 4 atom positions (via guess or check action)
 - f. Record: rays used, invalid moves, atoms correct, reasoning trace, thinking
2. Aggregate performance metrics across configurations

3.6 Dependent Variables

3.6.1 Predict Mode

- **Accuracy:** Proportion of rays with correct outcome prediction
- **Error types:** Absorption/deflection/reflection confusion patterns
- **Response time:** API response latency (ms)
- **Token usage:** Input and output tokens per prediction

3.6.2 Play Mode

- **Atoms correct:** 0-4 atoms in correct positions
- **Rays used:** Number of rays before guessing
- **Invalid moves:** Attempts to fire into used positions
- **Efficiency:** Atoms correct / rays used
- **Score:** Game score (lower is better: ray costs + 5 × missed atoms)
- **Response time:** Total API response time (ms)
- **Token usage:** Total input and output tokens

3.6.3 Process Measures (from Extended Thinking)

- **Thinking traces:** Full extended thinking content when enabled
- **Reasoning explanations:** Model's stated reasoning for each action
- **Hypothesis tracking:** Marked positions over time (when enabled)
- **Constraint tracking accuracy:** Quality of constraint maintenance
- **Hypothesis revision patterns:** How beliefs change with new evidence

3.7 Analysis Plan

3.7.1 Statistical Approach

Unlike most LLM benchmarks that report only accuracy rankings, we employ factorial ANOVA with effect size estimation to quantify the unique contribution of each experimental factor. This approach allows us to determine not just *which* conditions produce better performance, but *how much* each factor contributes and whether effects depend on problem complexity (interaction effects). While less common in LLM evaluation, this statistical framework is standard in experimental psychology and provides stronger inferences about the mechanisms underlying diagnostic reasoning failures.

We complement ANOVA with regression analysis to provide interpretable effect magnitudes:

- **ANOVA:** Tests omnibus hypotheses (does model matter? does prompt style matter?) and interaction effects
- **Regression:** Quantifies effect magnitudes (how much does Opus improve over Haiku?) and allows inclusion of continuous covariates (spatial complexity)
- **Effect sizes:** Standardized metrics (η^2 , Cohen's d, odds ratios) allow comparison across studies and DVs

3.7.2 Primary Analyses

1. **Predict Mode:** Logistic regression with Type III ANOVA on prediction accuracy (binary outcome)
2. **Play Mode:** Linear regression with Type III ANOVA on atoms correct (continuous outcome)
3. **Scaling analysis:** Linear trend across model sizes
4. **Effect modification:** Test whether treatment effects vary with spatial complexity (mean atoms per ray)

3.7.3 Effect Size Interpretation Guidelines

Following Cohen (1988), we interpret effect sizes using conventional benchmarks:

Measure	Small	Medium	Large	Notes
η^2 (Eta-squared)	0.01	0.06	0.14	Total variance explained
η^2_p (Partial eta-squared)	0.01	0.06	0.14	Variance explained controlling for other factors
ω^2 (Omega-squared)	0.01	0.06	0.14	Unbiased estimate (preferred over η^2)
Cohen's d	0.20	0.50	0.80	Standardized mean difference
Cohen's f	0.10	0.25	0.40	Effect size for ANOVA ($f = \sqrt{[\eta^2 / (1 - \eta^2)]}$)
Cramér's V	0.10	0.30	0.50	Association strength for categorical variables

Measure	Small	Medium	Large	Notes
Odds Ratio	1.5	3.0	9.0	OR = 1 means no effect; > 1 increases odds

Note: These are heuristics, not absolute cutoffs. Practical significance depends on context and cost-benefit considerations.

3.7.4 Qualitative Analysis

Systematic coding of extended thinking traces to identify:

- Constraint tracking errors
- Spatial reasoning errors
- Hypothesis generation patterns
- Response to contradictory evidence

3.7.5 Spatial-Inferential Decomposition Analysis

To address the concern that spatial reasoning requirements may confound interpretation for non-spatial diagnostic tasks, we employ three complementary analytical strategies:

1. Mode Comparison

Comparing Predict mode (forward reasoning, heavily spatial) to Play mode (full diagnostic loop) performance provides diagnostic information:

- *Good Predict + Poor Play*: Implicates non-spatial limitations (abductive inference, constraint tracking, experiment design)
- *Poor Predict + Poor Play*: Implicates spatial/world model limitations as at least partly responsible
- *Performance delta* (Play accuracy conditional on Predict accuracy): Isolates the contribution of inferential machinery

2. Spatial Complexity Moderation

We use two complementary measures of spatial complexity:

- **Predict mode**: *Cells traveled*—the total number of cells a ray traverses (entry cell + internal path + exit cell). This measures path length complexity.
- **Play mode**: *Mean atoms per ray*—the average number of atoms affecting each ray's path in a game. This measures interaction complexity.

Moderation analysis tests whether treatment effects (model, prompt style, extended thinking) interact with spatial complexity:

- *Constant effects across complexity*: Limitations lie in inferential machinery, not spatial processing
- *Effects moderated by complexity*: Spatial reasoning contributes to observed failures

3. Error Taxonomy from Thinking Traces

We classify errors from extended thinking traces into categories:

Error Type	Spatial?	Description
Ray path error	Yes	Path traced incorrectly through grid
Deflection geometry error	Yes	Misunderstood deflection rules
Constraint tracking error	No	Failed to update ruled-out positions
Experiment design error	No	Fired uninformative/redundant rays
Belief updating error	No	Did not revise hypothesis when contradicted
Premature commitment	No	Anchored on hypothesis before sufficient evidence

The proportion of spatial vs. non-spatial errors indicates which component capabilities drive overall performance.

4 Results

4.1 Predict Mode Results

```
# Load all Predict mode experiment JSON files from Experiment 1/Predict/
predict_json_files <- list.files(
  path = "Experiment 1/Predict",
  pattern = "\\.json$",
  full.names = TRUE
)

# Helper function to count cells traveled by a ray
# Entry cell (outside box) + internal path cells + exit cell (outside box)
count_ray_cells <- function(rayResult) {
```

```

if (is.null(rayResult) || is.null(rayResult$path)) {
  return(NA_real_)
}

path <- rayResult$path
if (!is.matrix(path) || nrow(path) == 0) {
  return(NA_real_)
}

# Start with entry cell (outside box) + all internal path cells
cells <- 1 + nrow(path)

# Add exit cell (outside box) for rays that exit (not absorbed)
# Absorbed rays have absorbed=TRUE and no exit field
# Deflected/reflected rays have absorbed=FALSE and an exit field
if (!is.null(rayResult$absorbed) && !rayResult$absorbed) {
  cells <- cells + 1
}

return(cells)
}

# Helper function: count atoms adjacent (within 1 cell) to any cell in ray path
# Note: jsonlite parses arrays as matrices, so atom_config is 4x2 and path is Nx2
count_atoms_affecting <- function(path, atom_config) {
  if (is.null(path) || length(path) == 0) return(0)
  if (!is.matrix(path)) return(0)

  affected <- 0
  n_atoms <- nrow(atom_config)
  n_cells <- nrow(path)

  for (i in seq_len(n_atoms)) {
    atom_row <- atom_config[i, 1]
    atom_col <- atom_config[i, 2]
    for (j in seq_len(n_cells)) {
      cell_row <- path[j, 1]
      cell_col <- path[j, 2]
      if (abs(atom_row - cell_row) <= 1 && abs(atom_col - cell_col) <= 1) {
        affected <- affected + 1
        break # Count each atom only once per ray
    }
  }
}

```

```

    }
}

affected
}

# Function to extract results from a single Predict JSON file
extract_predict_results <- function(json_file) {
  data <- jsonlite::fromJSON(json_file, simplifyDataFrame = FALSE)

  # Extract results array
  results <- data$results

  # Convert each result to prediction-level rows
  map_dfr(results, function(r) {
    # Each result has a predictions array
    predictions <- r$predictions

    if (is.null(predictions) || length(predictions) == 0) {
      return(tibble())
    }

    # Extract each prediction
    map_dfr(predictions, function(p) {
      # Calculate path complexity metrics
      cells_traveled <- count_ray_cells(p$rayResult)
      atoms_affecting <- count_atoms_affecting(p$rayResult$path, r$atomConfig)

      tibble(
        experiment_id = r$experimentId,
        model = r$model,
        model_name = r$modelName,
        prompt_style = r$promptStyle,
        prompt_condition = r$promptCondition,
        config_index = r$configIndex,
        include_visualization = r$includeVisualization,
        enable_thinking = r$enableThinking,
        thinking_budget = r$thinkingBudget,
        vot_ray_trace = r$votRayTrace,
        ray_entry = p$rayEntry,
        predicted = p$predicted,
        actual = p$actual,
        correct = p$correct,
      )
    })
  })
}

```

```

        reasoning = p$reasoning,
        response_time_ms = p$responseTimeMs,
        input_tokens = p$inputTokens,
        output_tokens = p$outputTokens,
        cells_traveled = cells_traveled,
        atoms_affecting = atoms_affecting,
        source_file = basename(json_file)
    )
}
})
}
}

# Load all results into a single long-format tibble
predict_data <- map_dfr(predict_json_files, extract_predict_results)

```

Data loaded: 11280 predictions from 8 JSON files.

- **Models:** Haiku 4.5, Sonnet 4.5, Opus 4.5
- **Prompt styles:** augmented, baseline
- **Extended thinking:** FALSE, TRUE
- **VoT ray trace:** FALSE, TRUE
- **Configurations tested:** 10
- **Cells traveled range:** 2–13
- **Atoms affecting range:** 0–3

Data Completeness Check

```

**Note on sample size**: Fewer than 32 predictions per configuration is expected due to ray

::: {.cell}

```{.r .cell-code}
predictions_per_config <- predict_data |>
 group_by(model_name, prompt_style, enable_thinking, vot_ray_trace, config_index) |>
 summarise(n_predictions = n(), .groups = "drop")

Create matrix: rows = experimental conditions, columns = configurations
Since all models should have same N per config, take first model's values
predictions_matrix <- predictions_per_config |>
 filter(model_name == first(model_name)) |>

```

```

 mutate(
 condition = paste0(
 substr(prompt_style, 1, 3), "_",
 ifelse(enable_thinking, "think", "no"), "_",
 ifelse(vot_ray_trace, "vot", "no")
)
) |>
 select(condition, config_index, n_predictions) |>
 pivot_wider(names_from = config_index, values_from = n_predictions, names_prefix = "cfg_")

 kable(predictions_matrix,
 caption = "Predictions per Configuration by Experimental Condition",
 col.names = c("Condition", paste0("Config ", 0:9)))

```

Table 10: Predictions per Configuration by Experimental Condition

Condition	Config 0	Config 1	Config 2	Config 3	Config 4	Config 5	Config 6	Config 7	Config 8	Config 9
aug_no_no	46	44	50	56	36	42	48	46	50	52
aug_no_vot	46	44	50	56	36	42	48	46	50	52
aug_think_no	46	44	50	56	36	42	48	46	50	52
aug_think_vot	46	44	50	56	36	42	48	46	50	52
bas_no_no	46	44	50	56	36	42	48	46	50	52
bas_no_vot	46	44	50	56	36	42	48	46	50	52
bas_think_no	46	44	50	56	36	42	48	46	50	52
bas_think_vot	46	44	50	56	36	42	48	46	50	52

```

Check for consistent N across models within each condition
consistency <- predictions_per_config |>
 group_by(prompt_style, enable_thinking, vot_ray_trace, config_index) |>
 summarise(
 n_unique = n_distinct(n_predictions),
 min_n = min(n_predictions),
 max_n = max(n_predictions),
 .groups = "drop"
)

Check for duplicate runs (same condition run multiple times)
runs_per_condition <- predict_data |>
 group_by(prompt_style, enable_thinking, vot_ray_trace, model_name, config_index) |>
 summarise(n_runs = n_distinct(source_file), .groups = "drop")

```

:::

**Consistency:** All models have consistent N per configuration within each condition.

**Duplicate runs:** No duplicate runs detected.

```
Summary statistics by all experimental factors
predict_summary <- predict_data |>
 group_by(model_name, prompt_style, enable_thinking, vot_ray_trace) |>
 summarise(
 n = n(),
 n_correct = sum(correct),
 accuracy = mean(correct),
 accuracy_se = sqrt(accuracy * (1 - accuracy) / n),
 mean_response_time = mean(response_time_ms, na.rm = TRUE),
 .groups = "drop"
) |>
 mutate(across(where(is.numeric) & !c(n, n_correct), \((x) round(x, 3)))
```

```
kable(predict_summary,
 col.names = c("Model", "Prompt", "Thinking", "VoT Ray", "N", "Correct",
 "Accuracy", "SE", "Response Time (ms)"),
 caption = "Predict Mode Performance by Experimental Condition")
```

Table 11: Predict Mode Performance by Experimental Condition

Model	Prompt	Thinking	VoT Ray	N	Correct	Accuracy	SE	Response Time (ms)
Haiku 4.5	augmented	FALSE	FALSE	470	352	0.749	0.020	10740.27
Haiku 4.5	augmented	FALSE	TRUE	470	384	0.817	0.018	12758.47
Haiku 4.5	augmented	TRUE	FALSE	470	426	0.906	0.013	20242.76
Haiku 4.5	augmented	TRUE	TRUE	470	450	0.957	0.009	23141.35
Haiku 4.5	baseline	FALSE	FALSE	470	270	0.574	0.023	11026.42
Haiku 4.5	baseline	FALSE	TRUE	470	202	0.430	0.023	10449.00
Haiku 4.5	baseline	TRUE	FALSE	470	288	0.613	0.022	39523.49
Haiku 4.5	baseline	TRUE	TRUE	470	366	0.779	0.019	66692.71
Opus 4.5	augmented	FALSE	FALSE	470	384	0.817	0.018	10909.51

Model	Prompt	Thinking	VoT Ray	N	Correct	Accuracy	SE	Response Time (ms)
Opus 4.5	augmented	FALSE	TRUE	470	388	0.826	0.018	12618.99
Opus 4.5	augmented	TRUE	FALSE	470	440	0.936	0.011	20568.46
Opus 4.5	augmented	TRUE	TRUE	470	440	0.936	0.011	23033.41
Opus 4.5	baseline	FALSE	FALSE	470	266	0.566	0.023	11015.83
Opus 4.5	baseline	FALSE	TRUE	470	216	0.460	0.023	10431.12
Opus 4.5	baseline	TRUE	FALSE	470	298	0.634	0.022	40646.76
Opus 4.5	baseline	TRUE	TRUE	470	368	0.783	0.019	69663.18
Sonnet 4.5	augmented	FALSE	FALSE	470	366	0.779	0.019	10893.54
Sonnet 4.5	augmented	FALSE	TRUE	470	400	0.851	0.016	12927.71
Sonnet 4.5	augmented	TRUE	FALSE	470	448	0.953	0.010	20636.58
Sonnet 4.5	augmented	TRUE	TRUE	470	450	0.957	0.009	23033.25
Sonnet 4.5	baseline	FALSE	FALSE	470	278	0.591	0.023	11023.54
Sonnet 4.5	baseline	FALSE	TRUE	470	216	0.460	0.023	10322.60
Sonnet 4.5	baseline	TRUE	FALSE	470	292	0.621	0.022	41686.14
Sonnet 4.5	baseline	TRUE	TRUE	470	370	0.787	0.019	68985.51

#### 4.1.1 Predict Mode Leaderboard

Top 10 configurations by overall accuracy. Format matches typical LLM benchmark reporting for cross-study comparison.

```
leaderboard_predict <- predict_data |>
 mutate(
 condition = paste0(
 model_name, " | ",
 ifelse(prompt_style == "augmented", "Aug", "Base"), " | ",
 ifelse(enable_thinking, "Think", "No-Think"), " | ",
 ifelse(vot_ray_trace, "VoT", "No-VoT"))
```

```

)
) |>
group_by(condition, model_name, prompt_style, enable_thinking, vot_ray_trace) |>
summarise(
 n = n(),
 accuracy = mean(correct),
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 .groups = "drop"
) |>
arrange(desc(accuracy)) |>
mutate(
 rank = row_number(),
 accuracy_pct = paste0(round(accuracy * 100, 1), "%"),
 ci_95 = paste0("[", round(ci_lower * 100, 1), "%, ", round(ci_upper * 100, 1), "%]")
) |>
select(rank, condition, accuracy_pct, ci_95, n) |>
head(10)

kable(leaderboard_predict,
 col.names = c("Rank", "Configuration", "Accuracy", "95% CI", "N"),
 caption = "Predict Mode Leaderboard (Top 10 Configurations)")

```

Table 12: Predict Mode Leaderboard (Top 10 Configurations)

Rank	Configuration	Accuracy	95% CI	N
1	Haiku 4.5   Aug   Think   VoT	95.7%	[93.9%, 97.6%]	470
2	Sonnet 4.5   Aug   Think   VoT	95.7%	[93.9%, 97.6%]	470
3	Sonnet 4.5   Aug   Think   No-VoT	95.3%	[93.4%, 97.2%]	470
4	Opus 4.5   Aug   Think   No-VoT	93.6%	[91.4%, 95.8%]	470
5	Opus 4.5   Aug   Think   VoT	93.6%	[91.4%, 95.8%]	470
6	Haiku 4.5   Aug   Think   No-VoT	90.6%	[88%, 93.3%]	470
7	Sonnet 4.5   Aug   No-Think   VoT	85.1%	[81.9%, 88.3%]	470
8	Opus 4.5   Aug   No-Think   VoT	82.6%	[79.1%, 86%]	470
9	Haiku 4.5   Aug   No-Think   VoT	81.7%	[78.2%, 85.2%]	470
10	Opus 4.5   Aug   No-Think   No-VoT	81.7%	[78.2%, 85.2%]	470

#### 4.1.2 Forest Plot: All Configurations

Visual comparison of all experimental factor combinations. Non-overlapping confidence intervals suggest statistically significant differences.

```

Calculate accuracy and 95% CI for all configurations
forest_data <- predict_data |>
 mutate(
 # Create readable configuration labels
 config_label = paste0(
 model_name, " | ",
 ifelse(prompt_style == "augmented", "Aug", "Base"), " | ",
 ifelse(enable_thinking, "Think", "No-Think"), " | ",
 ifelse(vot_ray_trace, "VoT", "No-VoT")
)
) |>
 group_by(config_label, model_name, prompt_style, enable_thinking, vot_ray_trace) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 # 95% CI for proportion using normal approximation
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 .groups = "drop"
) |>
 # Order by accuracy (highest first)
 arrange(desc(accuracy)) |>
 mutate(
 # Create ordered factor for plotting
 config_label = factor(config_label, levels = config_label)
)

Forest plot
p_forest <- ggplot(forest_data, aes(x = accuracy, y = config_label)) +
 geom_point(aes(color = model_name), size = 3) +
 geom_errorbarh(aes(xmin = ci_lower, xmax = ci_upper, color = model_name),
 height = 0.3, linewidth = 0.8) +
 geom_vline(xintercept = 0.5, linetype = "dashed", color = "gray50", alpha = 0.5) +
 geom_text(aes(label = paste0(round(accuracy * 100, 1), "%")),
 hjust = -0.3, size = 3) +
 labs(
 title = "Predict Mode: All Configurations Ranked by Accuracy",
 subtitle = "Error bars show 95% confidence intervals. Non-overlapping CIs suggest significant differences between models",
 x = "Accuracy",
 y = "Configuration",
 color = "Model"
) +

```

```
scale_x_continuous(
 limits = c(0, 1),
 labels = scales::percent,
 breaks = seq(0, 1, 0.1)
) +
theme_minimal(base_size = 11) +
theme(
 axis.text.y = element_text(size = 9, family = "mono"),
 panel.grid.major.y = element_blank(),
 panel.grid.minor = element_blank(),
 legend.position = "top"
)

print(p_forest)
```

Predict Mode: All Configurations Ranked by Accuracy  
 Error bars show 95% confidence intervals. Non-overlapping CIs suggest significant differences.



Total configurations: 24 Best performing: Haiku 4.5 | Aug | Think | VoT Accuracy: 95.7% (95% CI: [93.9%, 97.6%])

### 4.1.3 Factor-Level Comparisons

Shows accuracy by individual factors, collapsing across other dimensions (marginal effects).

```
Calculate marginal effects for each factor
factor_data <- list(
 Model = predict_data |>
 group_by(model_name) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n)
) |>
 mutate(factor = "Model", level = model_name),

 Prompt = predict_data |>
 group_by(prompt_style) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n)
) |>
 mutate(factor = "Prompt", level = prompt_style),

 Thinking = predict_data |>
 group_by(enable_thinking) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n)
) |>
 mutate(factor = "Extended Thinking", level = ifelse(enable_thinking, "Enabled", "Disabled")),

 VoT = predict_data |>
 group_by(vot_ray_trace) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 ci_lower = accuracy - 1.96 * sqrt(accuracy * (1 - accuracy) / n),
 ci_upper = accuracy + 1.96 * sqrt(accuracy * (1 - accuracy) / n)
```

```

) |>
 mutate(factor = "VoT Ray Trace", level = ifelse(vot_ray_trace, "Enabled", "Disabled"))
) |>
 bind_rows() |>
 mutate(factor = factor(factor, levels = c("Model", "Prompt", "Extended Thinking", "VoT Ray

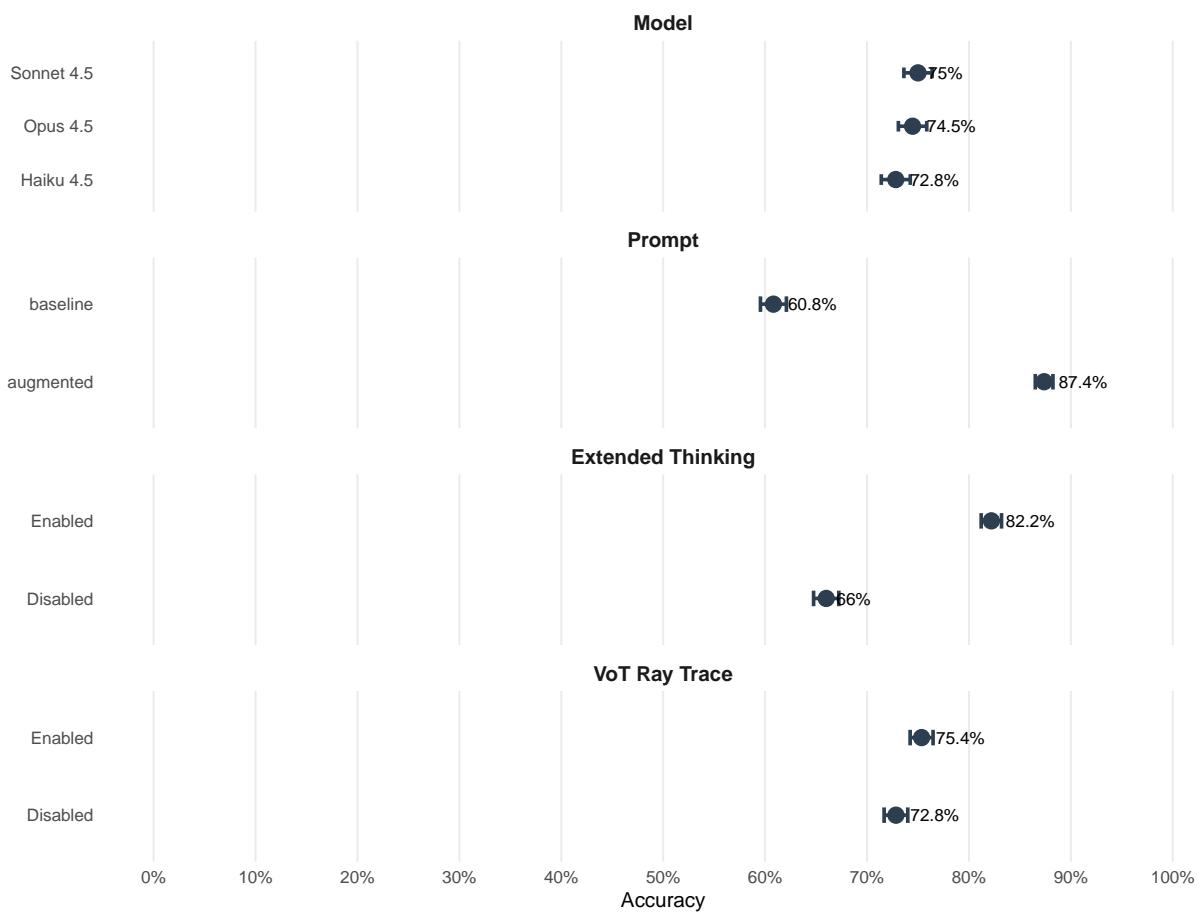
Factor comparison plot
p_factors <- ggplot(factor_data, aes(x = accuracy, y = level)) +
 geom_point(size = 4, color = "#2C3E50") +
 geom_errorbarh(aes(xmin = ci_lower, xmax = ci_upper),
 height = 0.2, linewidth = 1, color = "#2C3E50") +
 geom_text(aes(label = paste0(round(accuracy * 100, 1), "%")),
 hjust = -0.3, size = 3.5) +
 facet_wrap(~factor, ncol = 1, scales = "free_y") +
 labs(
 title = "Main Effects: Accuracy by Individual Factors",
 subtitle = "Marginal effects averaging across all other factors",
 x = "Accuracy",
 y = NULL
) +
 scale_x_continuous(
 limits = c(0, 1),
 labels = scales::percent,
 breaks = seq(0, 1, 0.1)
) +
 theme_minimal(base_size = 12) +
 theme(
 strip.text = element_text(face = "bold", size = 12),
 panel.grid.major.y = element_blank(),
 panel.grid.minor = element_blank()
)
)

print(p_factors)

```

### Main Effects: Accuracy by Individual Factors

Marginal effects averaging across all other factors



```
Accuracy by configuration to assess difficulty variation
predict_by_config <- predict_data |>
 group_by(config_index, model_name) |>
 summarise(
 n = n(),
 accuracy = mean(correct),
 .groups = "drop"
) |>
 pivot_wider(names_from = model_name, values_from = accuracy) |>
 mutate(across(where(is.numeric) & !config_index, \((x) round(x, 3)))) |>
 kable(predict_by_config,
 caption = "Prediction Accuracy by Configuration and Model")
```

Table 13: Prediction Accuracy by Configuration and Model

config_index	n	Haiku 4.5	Opus 4.5	Sonnet 4.5
0	368	0.636	0.614	0.652
1	352	0.761	0.733	0.767
2	400	0.740	0.810	0.770
3	448	0.701	0.692	0.692
4	288	0.722	0.771	0.771
5	336	0.792	0.827	0.845
6	384	0.839	0.833	0.844
7	368	0.625	0.696	0.663
8	400	0.760	0.780	0.795
9	416	0.712	0.707	0.721

#### 4.1.4 ANOVA: Prediction Accuracy

This analysis uses mixed-effects logistic regression to test whether experimental factors significantly affect prediction accuracy, while accounting for clustering within configurations and individual rays.

**Model specification:** - **Outcome:** Correct prediction (binary: 0/1) - **Fixed effects:** Model, prompt style, extended thinking, VoT ray trace, and their interactions - **Covariates:** cells\_traveled (path length), atoms\_affecting (atom density) - **Random effects:** Nested structure with config\_index (configuration-level) and ray\_id nested within config (ray-level)

#### Why nested random effects?

- **Configuration-level (config\_index):** Accounts for overall difficulty due to specific atom placements; allows generalization beyond these 10 configurations
- **Ray-level (ray\_id:config\_index):** Accounts for individual ray difficulty; handles correlation when the same ray is tested across multiple experimental conditions
- **Why nested?:** ray\_id “NORTH\_3” represents different physical rays across configurations (different atom placements), so must be nested, not crossed

**Covariates** (cells\_traveled, atoms\_affecting) are **NOT confounders** (same rays tested across all conditions) but **ARE precision variables** that explain variance and improve statistical power.

```
Convert factors for ANOVA
predict_data <- predict_data |>
 mutate(
 model_name = factor(model_name, levels = c("Haiku 4.5", "Sonnet 4.5", "Opus 4.5")),
 prompt_style = factor(prompt_style, levels = c("baseline", "augmented")),
```

```

enable_thinking = factor(enable_thinking, levels = c(FALSE, TRUE)),
vot_ray_trace = factor(vot_ray_trace, levels = c(FALSE, TRUE)),
config_index = factor(config_index),
Create unique ray identifier (nested within config)
ray_id = paste(toupper(ray_entry$side), ray_entry$pos, sep = "_")
)

Build model formula dynamically based on available factor levels
has_model_var <- length(unique(predict_data$model_name)) > 1
has_prompt_var <- length(unique(predict_data$prompt_style)) > 1
has_thinking_var <- length(unique(predict_data$enable_thinking)) > 1
has_vot_var <- length(unique(predict_data$vot_ray_trace)) > 1

Build formula components
formula_parts <- c()
if (has_model_var) formula_parts <- c(formula_parts, "model_name")
if (has_prompt_var) formula_parts <- c(formula_parts, "prompt_style")
if (has_thinking_var) formula_parts <- c(formula_parts, "enable_thinking")

Add interactions only if all three main effects are present
if (has_model_var && has_prompt_var && has_thinking_var) {
 main_formula <- "model_name * prompt_style * enable_thinking"
} else {
 main_formula <- paste(formula_parts, collapse = " + ")
}

Add VoT if it varies
if (has_vot_var) {
 full_formula <- paste0("correct ~ ", main_formula, " + vot_ray_trace + cells_traveled + atoms_affecting + (1 | config_index/ray_id)")
} else {
 full_formula <- paste0("correct ~ ", main_formula, " + cells_traveled + atoms_affecting + (1 | config_index/ray_id)")
}

model_predict <- glmer(as.formula(full_formula),
 family = binomial(link = "logit"),
 data = predict_data,
 control = glmerControl(optimizer = "bobyqa"))

```

**Model formula:** correct ~ model\_name \* prompt\_style \* enable\_thinking + vot\_ray\_trace + cells\_traveled + atoms\_affecting + (1 | config\_index/ray\_id)

Analysis of Deviance Table (Type III Wald chisquare tests)

```

Response: correct

 Chisq Df Pr(>Chisq)
(Intercept) 39.9101 1 2.659e-10 ***
model_name 1.1597 2 0.5599818
prompt_style 73.8679 1 < 2.2e-16 ***
enable_thinking 86.0499 1 < 2.2e-16 ***
vot_ray_trace 14.2558 1 0.0001596 ***
cells_traveled 381.1024 1 < 2.2e-16 ***
atoms_affecting 140.1087 1 < 2.2e-16 ***
model_name:prompt_style 2.5874 2 0.2742513
model_name:enable_thinking 0.4069 2 0.8158956
prompt_style:enable_thinking 5.2810 1 0.0215594 *
model_name:prompt_style:enable_thinking 1.4111 2 0.4938409

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

#### 4.1.4.1 Odds Ratios with 95% Confidence Intervals

**Interpretation:** OR > 1 means the factor increases odds of correct prediction; OR < 1 means it decreases odds. These are conditional odds ratios (controlling for random effects).

Table 14: Odds Ratios for Prediction Accuracy (Fixed Effects). \* indicates p < 0.05.

Term	Odds Ratio	95% CI Lower	95% CI Upper	p-value	Sig
model_nameSonnet 4.5	1.123	0.909	1.386	0.2815	
model_nameOpus 4.5	1.059	0.858	1.308	0.5907	
prompt_styleaugmented	2.680	2.140	3.355	<0.001	*
enable_thinkingTRUE	2.932	2.336	3.680	<0.001	*
vot_ray_traceTRUE	1.223	1.102	1.358	<0.001	*
cells_traveled	0.816	0.800	0.833	<0.001	*
atoms_affecting	0.616	0.569	0.668	<0.001	*
model_nameSonnet 4.5:prompt_styleaugmented	1.200	0.868	1.659	0.2699	
model_nameOpus	1.294	0.935	1.789	0.1197	
4.5:prompt_styleaugmented	0.948	0.686	1.308	0.7431	
4.5:enable_thinkingTRUE	1.053	0.762	1.455	0.7531	
model_nameOpus 4.5:enable_thinkingTRUE	1.576	1.069	2.324	0.0216	*
prompt_styleaugmented:enable_thinkingTRUE					

Term	Odds Ratio	95% CI Lower	95% CI Upper	p-value	Sig
model_nameSonnet 4.5:prompt_styleaugmented:enable_thinkingTRUE	1.214	0.680	2.167	0.5121	
model_nameOpus 4.5:prompt_styleaugmented:enable_thinkingTRUE	0.846	0.481	1.489	0.5627	

#### 4.1.4.2 Random Effects Variance Components

**Configuration-level random effects** (config\_index): - Accounts for overall difficulty due to specific atom placements - Generalizes inference beyond these 10 configurations - Captures configuration-specific effects (e.g., dense vs sparse atom patterns)

**Ray-level random effects** (ray\_id:config\_index): - Accounts for individual ray difficulty within each configuration - Handles correlation: Same ray tested across multiple conditions - Allows each ray to have its own baseline difficulty - Essential when same rays appear in multiple experimental conditions

Groups	Name	Std.Dev.
ray_id:config_index	(Intercept)	0.64862
config_index	(Intercept)	0.83955

**Intraclass Correlation Coefficient (ICC):** 0.255 — Proportion of variance due to clustering at both configuration and ray-within-config levels.

**Model Fit** (Pseudo R<sup>2</sup>, Nakagawa & Schielzeth): - **Marginal R<sup>2</sup>** (fixed effects only): 0.227 - **Conditional R<sup>2</sup>** (fixed + random effects): 0.424

#### 4.1.4.3 Cramér's V (Effect Size for Categorical Associations)

Interpretation guidelines: 0.10=small, 0.30=medium, 0.50=large

Table 15: Association Strength with Prediction Accuracy

Factor	Cramér's V
Model	0.016
Prompt Style	0.303
Extended Thinking	0.185
VoT Ray Trace	0.027

#### 4.1.4.4 Regression Coefficients for Main Effects

Key findings from mixed-effects logistic regression (fixed effects only).

Table 16: Regression Coefficients for Main Effects (Fixed Effects)

Term	(log-odds)	OR	OR	95% CI	OR	95% CI
			Lower	Upper	p-value	
model_nameSonnet	0.116	1.123	0.909	1.386	0.282	
4.5						
model_nameOpus	0.058	1.059	0.858	1.308	0.591	
prompt_styleaugmented	0.986	2.680	2.140	3.355	<0.001	
enable_thinkingTRUE	1.076	2.932	2.336	3.680	<0.001	
vot_ray_traceTRUE	0.201	1.223	1.102	1.358	<0.001	
cells_traveled	-0.203	0.816	0.800	0.833	<0.001	
atoms_affecting	-0.484	0.616	0.569	0.668	<0.001	

#### 4.1.5 Effect Modification by Path Complexity

Does path complexity (measured as total cells traveled: entry + internal + exit) moderate treatment effects? If treatment effects are constant across spatial complexity levels, limitations lie in inferential machinery rather than spatial processing. If effects are moderated by complexity, spatial reasoning contributes to observed failures.

```
Only run if we have variation in factors and valid cells_traveled data
run_effect_mod <- has_model_var || has_prompt_var || has_thinking_var

if (run_effect_mod) {
 # Build interaction formula
 interaction_parts <- c()
 if (has_model_var) interaction_parts <- c(interaction_parts, "model_name * cells_traveled")
 if (has_prompt_var) interaction_parts <- c(interaction_parts, "prompt_style * cells_traveled")
 if (has_thinking_var) interaction_parts <- c(interaction_parts, "enable_thinking * cells_traveled")

 # Add nested random effects
 pred_mod_formula <- paste0("correct ~ ", paste(interaction_parts, collapse = " + "), " + (1 |"

 model_predict_mod <- glmer(as.formula(pred_mod_formula),
 family = binomial(link = "logit"),
 data = predict_data,
```

```

 control = glmerControl(optimizer = "bobyqa"))
}

```

**Model formula:** correct ~ model\_name \* cells\_traveled + prompt\_style \* cells\_traveled + enable\_thinking \* cells\_traveled + (1 | config\_index/ray\_id)

Analysis of Deviance Table (Type III Wald chisquare tests)

Response: correct

	Chisq	Df	Pr(>Chisq)
(Intercept)	24.8907	1	6.068e-07 ***
model_name	2.6703	2	0.263120
cells_traveled	147.0175	1	< 2.2e-16 ***
prompt_style	32.4483	1	1.224e-08 ***
enable_thinking	6.6848	1	0.009724 **
model_name:cells_traveled	0.4922	2	0.781839
cells_traveled:prompt_style	8.2773	1	0.004014 **
cells_traveled:enable_thinking	34.4661	1	4.337e-09 ***
---			
Signif. codes:	0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1		

**Interpretation of interactions:** - **No interaction:** Treatment effect is constant across simple and complex paths - **Positive interaction:** Treatment effect increases with path complexity - **Negative interaction:** Treatment effect decreases with path complexity

Table 17: Path Complexity Interaction Effects

Interaction Term	(log-odds)	OR	OR 95% CI Lower	OR 95% CI Upper	p-value
model_nameSonnet 4.5:cells_traveled	-0.015	0.985	0.940	1.032	0.51826
model_nameOpus 4.5:cells_traveled	-0.002	0.998	0.953	1.046	0.94219
cells_trav- eled:prompt_styleaugmented	0.058	1.060	1.019	1.103	0.00401
cells_traveled:enable_think- ingTRUE	0.118	1.125	1.082	1.170	< 0.001

**Path Complexity Distribution** (cells traveled):

Statistic	Value
Min	2
Q1	4
Median	6
Q3	9
Max	13
Mean	6.49
SD	2.9

#### 4.1.6 Effect Modification by Atom Density

Does atom density (number of atoms adjacent to ray path) moderate treatment effects?

```
run_effect_mod_atoms <- has_model_var || has_prompt_var || has_thinking_var

if (run_effect_mod_atoms) {
 # Build interaction formula
 interaction_parts <- c()
 if (has_model_var) interaction_parts <- c(interaction_parts, "model_name * atoms_affecting")
 if (has_prompt_var) interaction_parts <- c(interaction_parts, "prompt_style * atoms_affecting")
 if (has_thinking_var) interaction_parts <- c(interaction_parts, "enable_thinking * atoms_affecting")

 # Add nested random effects
 pred_mod_formula_atoms <- paste0("correct ~ ", paste(interaction_parts, collapse = " + "))

 model_predict_mod_atoms <- glmer(as.formula(pred_mod_formula_atoms),
 family = binomial(link = "logit"),
 data = predict_data,
 control = glmerControl(optimizer = "bobyqa"))
}
```

**Model formula:** correct ~ model\_name \* atoms\_affecting + prompt\_style \* atoms\_affecting + enable\_thinking \* atoms\_affecting + (1 | config\_index/ray\_id)

Mixed-effects logistic regression tests whether treatment effects vary with atom density.

Analysis of Deviance Table (Type III Wald chisquare tests)

Response: correct	Chisq	Df	Pr(>Chisq)
(Intercept)	1.8883	1	0.16939

```

model_name 0.3114 2 0.85582
atoms_affecting 4.6401 1 0.03123 *
prompt_style 710.2122 1 < 2.2e-16 ***
enable_thinking 45.9063 1 1.240e-11 ***
model_name:atoms_affecting 1.7506 2 0.41673
atoms_affecting:prompt_style 154.0699 1 < 2.2e-16 ***
atoms_affecting:enable_thinking 37.5996 1 8.686e-10 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

**Interpretation of interactions:** - **No interaction:** Treatment effect is constant across low and high atom density - **Positive interaction:** Treatment effect increases with more atoms affecting path - **Negative interaction:** Treatment effect decreases with more atoms affecting path

Table 19: Atom Density Interaction Effects

Interaction Term	(log-odds)	OR	OR 95% CI Lower	OR 95% CI Upper	p-value
model_nameSonnet	0.109	1.115	0.949	1.311	0.187
4.5:atoms_affecting					
model_nameOpus	0.046	1.047	0.892	1.230	0.574
4.5:atoms_affecting					
atoms_affect- ing:prompt_styleaugmented	-0.907	0.404	0.350	0.466	<0.001
atoms_affecting:enable_think- ingTRUE	0.432	1.540	1.342	1.768	<0.001

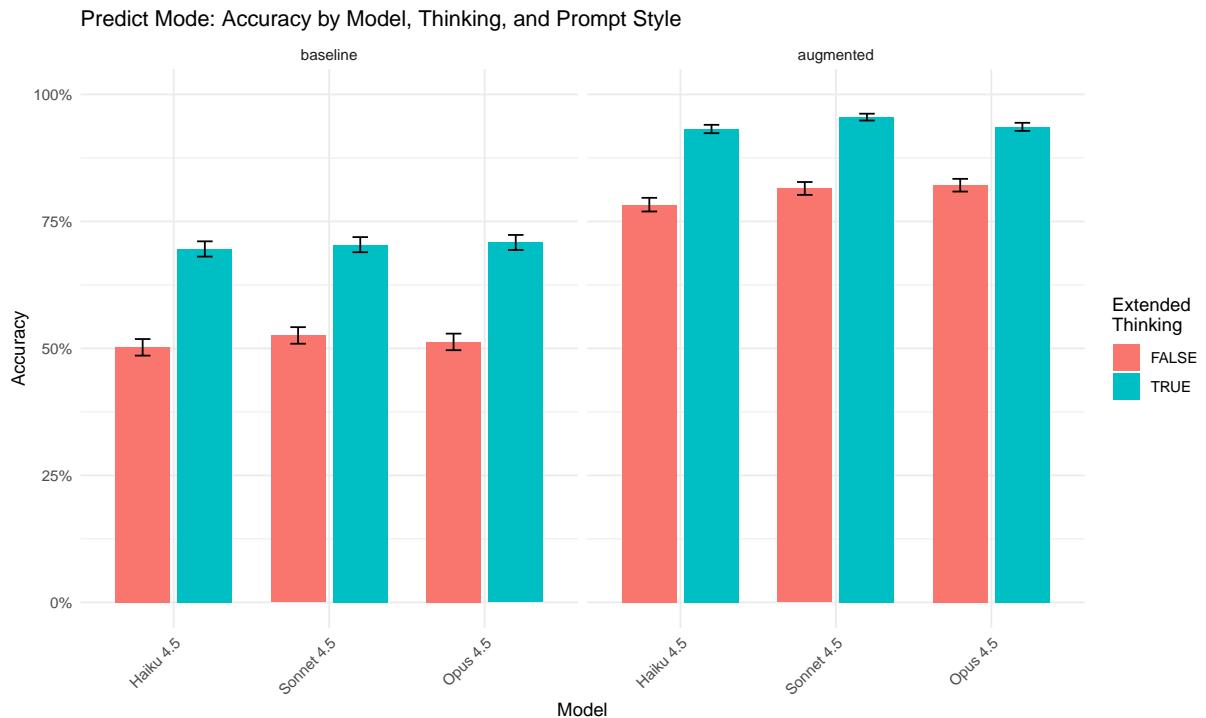
### Atom Density Distribution:

Statistic	Value
Min	0
Q1	1
Median	1
Q3	1
Max	3
Mean	0.97
SD	0.71

```

Accuracy by model and condition
p1_pred <- predict_data |>
 group_by(model_name, prompt_style, enable_thinking) |>
 summarise(accuracy = mean(correct),
 se = sqrt(accuracy * (1-accuracy) / n()),
 .groups = "drop") |>
 ggplot(aes(x = model_name, y = accuracy, fill = enable_thinking)) +
 geom_col(position = position_dodge(0.8), width = 0.7) +
 geom_errorbar(aes(ymin = accuracy - se, ymax = accuracy + se),
 position = position_dodge(0.8), width = 0.2) +
 facet_wrap(~prompt_style) +
 labs(title = "Predict Mode: Accuracy by Model, Thinking, and Prompt Style",
 x = "Model", y = "Accuracy", fill = "Extended\nThinking") +
 scale_y_continuous(limits = c(0, 1), labels = scales::percent) +
 theme(axis.text.x = element_text(angle = 45, hjust = 1))
print(p1_pred)

```



```

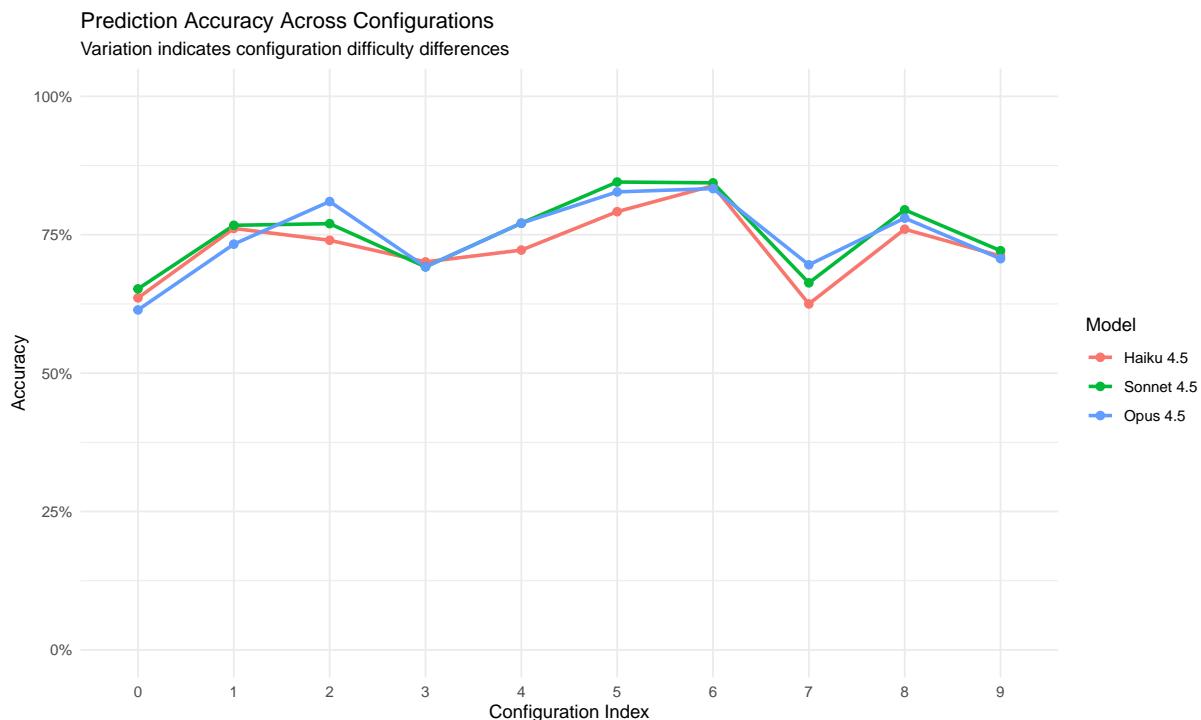
Accuracy by configuration (difficulty analysis)
p2_pred <- predict_data |>
 group_by(config_index, model_name) |>
 summarise(accuracy = mean(correct), .groups = "drop") |>

```

```

ggplot(aes(x = config_index, y = accuracy, color = model_name, group = model_name)) +
 geom_line(linewidth = 1) +
 geom_point(size = 2) +
 labs(title = "Prediction Accuracy Across Configurations",
 subtitle = "Variation indicates configuration difficulty differences",
 x = "Configuration Index", y = "Accuracy", color = "Model") +
 scale_y_continuous(limits = c(0, 1), labels = scales::percent) +
 theme_minimal()
print(p2_pred)

```



```

VoT Ray Trace effect
p3_pred <- predict_data |>
 group_by(model_name, vot_ray_trace) |>
 summarise(accuracy = mean(correct),
 se = sqrt(accuracy * (1-accuracy) / n()),
 .groups = "drop") |>
 ggplot(aes(x = model_name, y = accuracy, fill = vot_ray_trace)) +
 geom_col(position = position_dodge(0.8), width = 0.7) +
 geom_errorbar(aes(ymin = accuracy - se, ymax = accuracy + se),
 position = position_dodge(0.8), width = 0.2) +
 labs(title = "Effect of VoT Ray Trace Visualization",
 x = "Model", y = "Accuracy")

```

```

x = "Model", y = "Accuracy", fill = "VoT Ray\nnTrace") +
scale_y_continuous(limits = c(0, 1), labels = scales::percent) +
theme(axis.text.x = element_text(angle = 45, hjust = 1))
print(p3_pred)

```



```

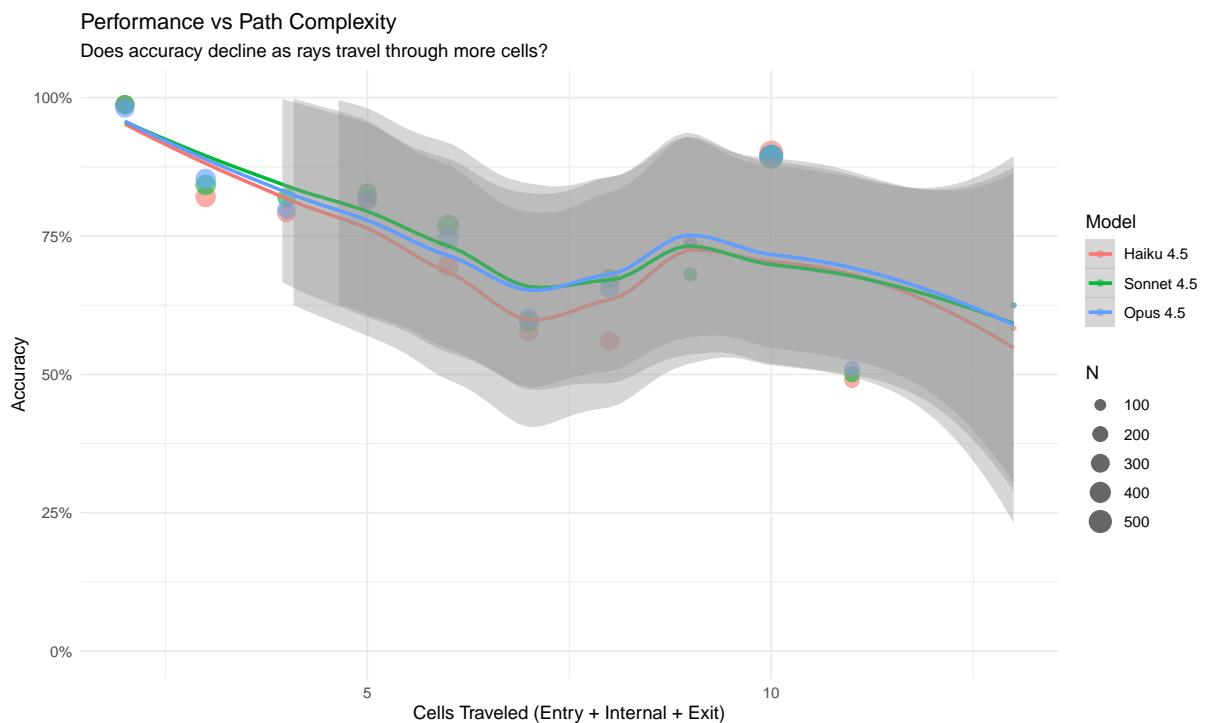
Path complexity vs accuracy
p4_pred <- predict_data |>
 filter(!is.na(cells_traveled)) |>
 group_by(cells_traveled, model_name) |>
 summarise(accuracy = mean(correct),
 n = n(),
 .groups = "drop") |>
ggplot(aes(x = cells_traveled, y = accuracy, color = model_name)) +
 geom_point(aes(size = n), alpha = 0.6) +
 geom_smooth(method = "loess", se = TRUE, linewidth = 1) +
 labs(title = "Performance vs Path Complexity",
 subtitle = "Does accuracy decline as rays travel through more cells?",
 x = "Cells Traveled (Entry + Internal + Exit)",
 y = "Accuracy",
 color = "Model",
 size = "N") +

```

```

scale_y_continuous(limits = c(0, 1), labels = scales::percent) +
 theme_minimal()
print(p4_pred)

```



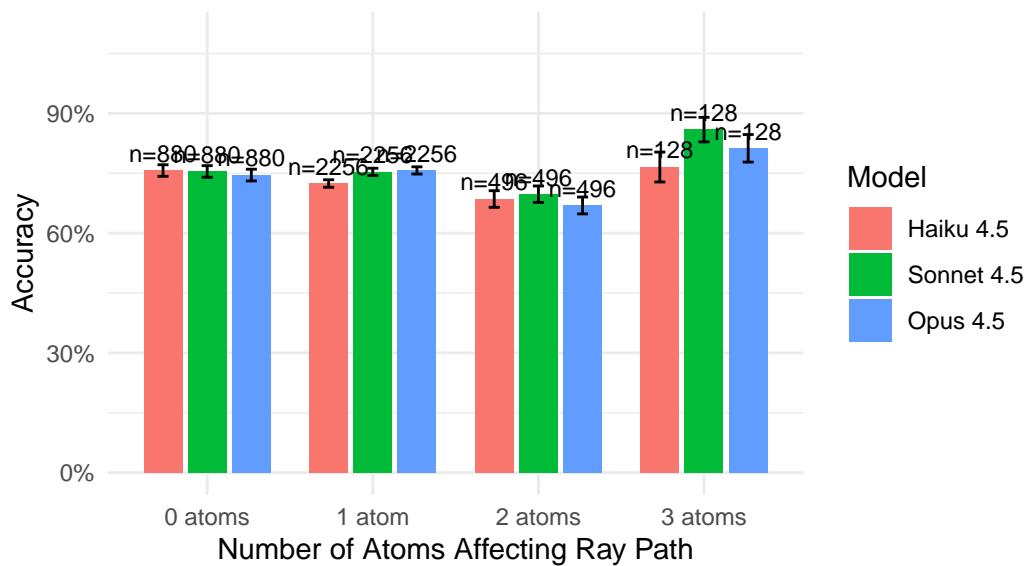
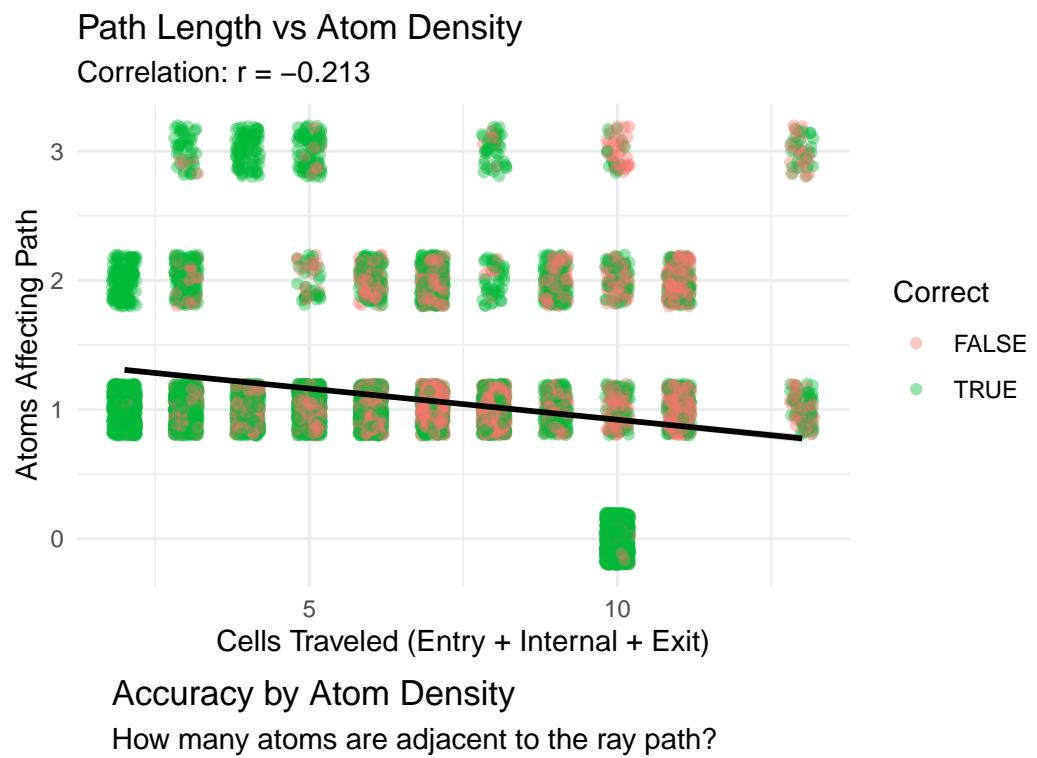
#### 4.1.7 Ray Path Complexity Analysis

```

1. Correlation between complexity measures
complexity_cor <- cor(predict_data$cells_traveled, predict_data$atoms_affecting,
 use = "complete.obs")

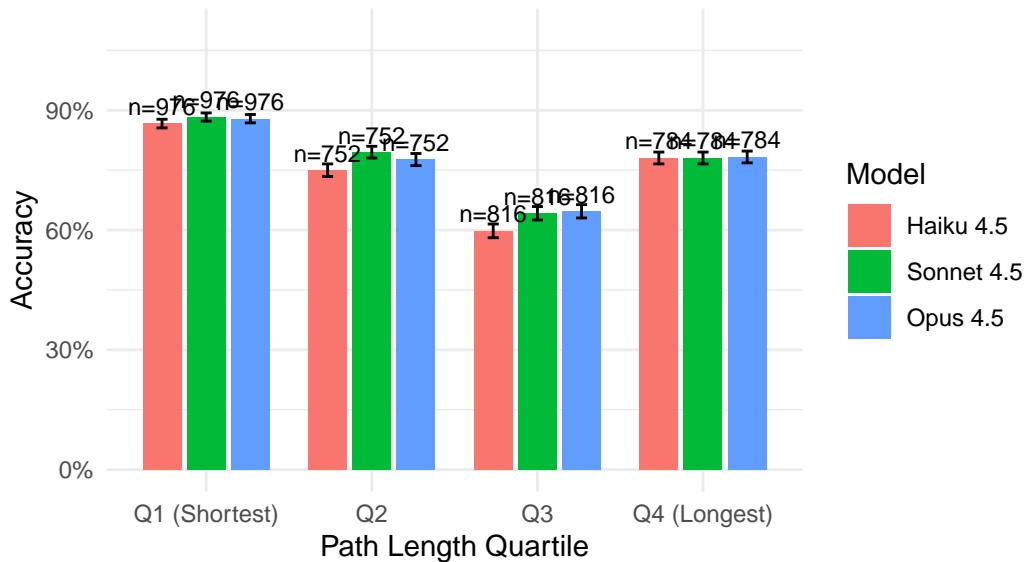
```

Correlation between cells\_traveled and atoms\_affecting: **-0.213**



## Accuracy by Path Length Quartiles

Does accuracy decline for longer ray paths?



```
Analyze error patterns by comparing predicted vs actual
This helps identify systematic errors (e.g., absorption vs deflection confusion)

First, extract the type of result from predicted and actual
predict_errors <- predict_data |>
 filter(!correct) |>
 mutate(
 predicted_type = case_when(
 grepl("absorbed|HIT", predicted, ignore.case = TRUE) ~ "absorbed",
 grepl("reflected|REFLECTION", predicted, ignore.case = TRUE) ~ "reflected",
 TRUE ~ "detour"
),
 actual_type = case_when(
 grepl("absorbed|HIT", actual, ignore.case = TRUE) ~ "absorbed",
 grepl("reflected|REFLECTION", actual, ignore.case = TRUE) ~ "reflected",
 TRUE ~ "detour"
)
)

Error confusion matrix
error_matrix <- predict_errors |>
 count(actual_type, predicted_type) |>
 pivot_wider(names_from = predicted_type, values_from = n, values_fill = 0)
```

```
kable(error_matrix, caption = "Prediction Errors: Actual vs Predicted Outcome Type (Rows = A
```

Table 21: Prediction Errors: Actual vs Predicted Outcome Type (Rows = Actual, Columns = Predicted)

actual_type	detour	reflected	absorbed
absorbed	596	30	0
detour	1238	22	280
reflected	524	0	232

```
Error rates by model
error_by_model <- predict_errors |>
 count(model_name, actual_type, predicted_type) |>
 group_by(model_name) |>
 mutate(prop = n / sum(n)) |>
 ungroup()

error_by_model |>
 group_by(model_name) |>
 slice_max(n, n = 3) |>
 mutate(error_pattern = paste(actual_type, "->", predicted_type)) |>
 select(model_name, error_pattern, n, prop) |>
 mutate(prop = round(prop, 3)) |>
 kable(col.names = c("Model", "Error Pattern (Actual → Predicted)", "Count", "Proportion"),
 caption = "Most Common Error Types by Model (Top 3 per Model)")
```

Table 22: Most Common Error Types by Model (Top 3 per Model)

Model	Error Pattern (Actual → Predicted)	Count	Proportion
Haiku 4.5	detour -> detour	458	0.448
Haiku 4.5	absorbed -> detour	214	0.209
Haiku 4.5	reflected -> detour	178	0.174
Sonnet 4.5	detour -> detour	406	0.432
Sonnet 4.5	absorbed -> detour	180	0.191
Sonnet 4.5	reflected -> detour	162	0.172
Opus 4.5	detour -> detour	374	0.390
Opus 4.5	absorbed -> detour	202	0.210
Opus 4.5	reflected -> detour	184	0.192

## 4.2 Play Mode Results

```
Load all Play mode experiment JSON files from Experiment 1/Play/
play_json_files <- list.files(
 path = "Experiment 1/Play",
 pattern = "\\.json$",
 full.names = TRUE
)

Function to extract results from a single JSON file
extract_play_results <- function(json_file) {
 data <- jsonlite::fromJSON(json_file, simplifyDataFrame = FALSE)

 # Extract results array
 results <- data$results

 # Convert each result to a tibble row
 map_dfr(results, function(r) {
 # Calculate mean complexity measures for each ray fired
 ray_complexity <- lapply(r$raySequence, function(ray) {
 if (!is.null(ray$action) && ray$action == "fire" &&
 !is.null(ray$rayResult) && !is.null(ray$rayResult$path)) {
 list(
 atoms = count_atoms_affecting(ray$rayResult$path, r$atomConfig),
 cells = count_ray_cells(ray$rayResult)
)
 } else {
 list(atoms = NA_real_, cells = NA_real_)
 }
 })
 mean_atoms <- mean(sapply(ray_complexity, function(x) x$atoms), na.rm = TRUE)
 mean_cells <- mean(sapply(ray_complexity, function(x) x$cells), na.rm = TRUE)
 if (is.nan(mean_atoms)) mean_atoms <- NA_real_
 if (is.nan(mean_cells)) mean_cells <- NA_real_

 tibble(
 experiment_id = r$experimentId,
 start_time = r$startTime,
 end_time = r$endTime,
 model = r$model,
 model_name = r$modelName,
```

```

prompt_style = r$promptStyle,
prompt_condition = r$promptCondition,
mode = r$mode,
config_index = r$configIndex,
atom_config = list(r$atomConfig),
include_visualization = r$includeVisualization,
allow_hypotheses = r$allowHypotheses,
enable_thinking = r$enableThinking,
thinking_budget = r$thinkingBudget,
vot_grid_state = r$votGridState,
vot_ray_trace = r$votRayTrace,
vot_hypothesis = r$votHypothesis,
rays_used = r$raysUsed,
atoms_correct = r$atomsCorrect,
atoms_missed = r$atomsMissed,
score = r$score,
invalid_moves = r$invalidMoves,
hypothesis_actions = r$hypothesisActions,
total_api_calls = r$totalApiCalls,
total_input_tokens = r$totalInputTokens,
total_output_tokens = r$totalOutputTokens,
total_response_time_ms = r$totalResponseTimeMs,
mean_atoms_per_ray = mean_atoms,
mean_cells_per_ray = mean_cells,
source_file = basename(json_file)
)
})
}
}

Load all results into a single long-format tibble
play_data <- map_dfr(play_json_files, extract_play_results)

```

Data loaded: 480 experiment results from 16 JSON files.

- **Models:** Haiku 4.5, Sonnet 4.5, Opus 4.5
- **Prompt styles:** augmented, baseline
- **Configurations tested:** 10
- **Mean atoms per ray range:** 0–2
- **Mean cells per ray range:** 2–10

```

::: {.cell}

```{.r .cell-code}
# Summary statistics by model, prompt, and thinking
play_summary <- play_data |>
  group_by(model_name, prompt_style, enable_thinking) |>
  summarise(
    n = n(),
    atoms_correct_mean = mean(atoms_correct),
    atoms_correct_sd = sd(atoms_correct),
    score_mean = mean(score),
    score_sd = sd(score),
    mean_atoms_ray = mean(mean_atoms_per_ray, na.rm = TRUE),
    rays_used_mean = mean(rays_used),
    .groups = "drop"
  ) |>
  mutate(across(where(is.numeric) & !n, \x) round(x, 2)))

kable(play_summary,
      col.names = c("Model", "Prompt", "Thinking", "N",
                    "Atoms Correct (M)", "Atoms Correct (SD)",
                    "Score (M)", "Score (SD)",
                    "Atoms/Ray", "Rays Used"))

```

Model	Prompt	Thinking	N	Atoms Correct (M)	Atoms Correct (SD)	Score (M)	Score (SD)	Atoms/Ray	Rays Used
Haiku	augmented	FALSE	40	0.88	1.20	31.52	8.20	1.02	11.03
4.5									
Haiku	augmented	TRUE	40	1.77	1.44	26.40	10.17	0.97	10.95
4.5									
Haiku	base-line	FALSE	40	0.82	1.32	26.80	6.72	1.12	7.90
4.5									
Haiku	base-line	TRUE	40	0.75	1.17	29.82	6.84	1.00	9.50
4.5									
Opus	augmented	FALSE	40	1.18	1.30	29.62	8.96	1.03	10.88
4.5									
Opus	augmented	TRUE	40	1.80	1.40	25.88	9.77	1.04	10.72
4.5									
Opus	base-line	FALSE	40	0.92	1.19	28.20	6.43	1.05	8.95
4.5									

Model	Prompt	Think-ing	N	Atoms Correct (M)	Atoms Correct (SD)	Score (M)	Score (SD)	Rays Atoms/Ra Used
Opus 4.5	base-line	TRUE	40	0.92	1.29	28.35	7.50	0.96 9.00
Sonnet 4.5	aug-mented	FALSE	40	1.23	1.31	30.92	10.06	1.00 11.72
Sonnet 4.5	aug-mented	TRUE	40	1.57	1.30	27.68	8.97	0.98 10.97
Sonnet 4.5	base-line	FALSE	40	0.98	1.35	27.48	7.59	1.04 8.90
Sonnet 4.5	base-line	TRUE	40	0.95	1.15	28.00	8.00	0.97 9.03

:::

```
# Summary by VoT factors
play_summary_vot <- play_data |>
  group_by(vot_grid_state, vot_ray_trace, vot_hypothesis) |>
  summarise(
    n = n(),
    atoms_correct_mean = mean(atoms_correct),
    atoms_correct_sd = sd(atoms_correct),
    score_mean = mean(score),
    score_sd = sd(score),
    mean_atoms_ray = mean(mean_atoms_per_ray, na.rm = TRUE),
    .groups = "drop"
  ) |>
  mutate(across(where(is.numeric) & !n, \(x) round(x, 2)))

kable(play_summary_vot,
      col.names = c("VoT Grid", "VoT Ray", "VoT Hyp", "N",
                    "Atoms Correct (M)", "Atoms Correct (SD)",
                    "Score (M)", "Score (SD)", "Atoms/Ray"))
```

VoT Grid	VoT Ray	VoT Hyp	N	Atoms Correct (M)	Atoms Correct (SD)	Score (M)	Score (SD)	Rays Atoms/Ray
FALSE	FALSE	FALSE	120	1.16	1.34	28.00	8.02	1.01
FALSE	FALSE	TRUE	120	1.17	1.29	28.66	8.35	1.03
FALSE	TRUE	FALSE	120	1.13	1.35	27.83	8.13	1.01

VoT Grid	VoT Ray	VoT Hyp	N	Atoms Correct (M)	Atoms (SD)	Score (M)	Score (SD)	Atoms/Ray
TRUE	FALSE	FALSE	120	1.13	1.32	29.07	9.24	1.00

4.2.1 Play Mode Leaderboard

Top 10 configurations by atoms correct. Format matches typical LLM benchmark reporting for cross-study comparison.

```
leaderboard_play <- play_data |>
  mutate(
    condition = paste0(
      model_name, " | ",
      ifelse(prompt_style == "augmented", "Aug", "Base"), " | ",
      ifelse(enable_thinking, "Think", "No-Think")
    )
  ) |>
  group_by(condition, model_name, prompt_style, enable_thinking) |>
  summarise(
    n = n(),
    atoms_correct_mean = mean(atoms_correct),
    atoms_correct_se = sd(atoms_correct) / sqrt(n),
    score_mean = mean(score),
    perfect_games = sum(atoms_correct == 4),
    .groups = "drop"
  ) |>
  arrange(desc(atoms_correct_mean), score_mean) |>
  mutate(
    rank = row_number(),
    atoms_ci = paste0(round(atoms_correct_mean, 2), " ± ", round(atoms_correct_se, 2)),
    perfect_pct = paste0(round(perfect_games / n * 100, 1), "%")
  ) |>
  select(rank, condition, atoms_ci, score_mean, perfect_pct, n) |>
  head(10)

kable(leaderboard_play,
  col.names = c("Rank", "Configuration", "Atoms Correct (M ± SE)", "Score (M)", "Perfect
```

caption = "Play Mode Leaderboard (Top 10 Configurations)")

Table 25: Play Mode Leaderboard (Top 10 Configurations)

Rank	Configuration	Atoms Correct (M ± SE)	Score (M)	Perfect Games	N
1	Opus 4.5 Aug Think	1.8 ± 0.22	25.875	15%	40
2	Haiku 4.5 Aug Think	1.77 ± 0.23	26.400	22.5%	40
3	Sonnet 4.5 Aug Think	1.57 ± 0.21	27.675	10%	40
4	Sonnet 4.5 Aug No-Think	1.23 ± 0.21	30.925	12.5%	40
5	Opus 4.5 Aug No-Think	1.18 ± 0.21	29.625	12.5%	40
6	Sonnet 4.5 Base No-Think	0.98 ± 0.21	27.475	10%	40
7	Sonnet 4.5 Base Think	0.95 ± 0.18	28.000	2.5%	40
8	Opus 4.5 Base No-Think	0.92 ± 0.19	28.200	5%	40
9	Opus 4.5 Base Think	0.92 ± 0.2	28.350	7.5%	40
10	Haiku 4.5 Aug No-Think	0.88 ± 0.19	31.525	7.5%	40

4.2.2 ANOVA: Play Mode Performance

Full factorial ANOVA using mixed-effects models with configuration-level random effects. Covariates (mean_atoms_per_ray, mean_cells_per_ray) capture ray difficulty.

```
# Convert factors
play_data <- play_data |>
  mutate(
    model_name = factor(model_name, levels = c("Haiku 4.5", "Sonnet 4.5", "Opus 4.5")),
    prompt_style = factor(prompt_style, levels = c("baseline", "augmented")),
    enable_thinking = factor(enable_thinking, levels = c(FALSE, TRUE)),
    vot_grid_state = factor(vot_grid_state, levels = c(FALSE, TRUE)),
    vot_ray_trace = factor(vot_ray_trace, levels = c(FALSE, TRUE)),
    vot_hypothesis = factor(vot_hypothesis, levels = c(FALSE, TRUE))
  )

# Build model formula dynamically
has_model_var <- length(unique(play_data$model_name)) > 1
has_prompt_var <- length(unique(play_data$prompt_style)) > 1
has_thinking_var <- length(unique(play_data$enable_thinking)) > 1
has_vot_grid <- length(unique(play_data$vot_grid_state)) > 1
has_vot_ray <- length(unique(play_data$vot_ray_trace)) > 1
has_vot_hyp <- length(unique(play_data$vot_hypothesis)) > 1

# Build main formula
formula_parts <- c()
```

```

if (has_model_var) formula_parts <- c(formula_parts, "model_name")
if (has_prompt_var) formula_parts <- c(formula_parts, "prompt_style")
if (has_thinking_var) formula_parts <- c(formula_parts, "enable_thinking")

if (has_model_var && has_prompt_var && has_thinking_var) {
  main_formula <- "model_name * prompt_style * enable_thinking"
} else {
  main_formula <- paste(formula_parts, collapse = " + ")
}

# Add VoT factors
vot_parts <- c()
if (has_vot_grid) vot_parts <- c(vot_parts, "vot_grid_state")
if (has_vot_ray) vot_parts <- c(vot_parts, "vot_ray_trace")
if (has_vot_hyp) vot_parts <- c(vot_parts, "vot_hypothesis")

if (length(vot_parts) > 0) {
  atoms_formula <- paste0("atoms_correct ~ ", main_formula, " + ",
                           paste(vot_parts, collapse = " + "),
                           " + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)")
} else {
  atoms_formula <- paste0("atoms_correct ~ ", main_formula,
                           " + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)")
}

model_atoms <- lmer(as.formula(atoms_formula), data = play_data)

```

4.2.2.1 Model 1: Atoms Correct (0-4)

Testing which factors affect the number of atoms correctly identified.

Model formula: atoms_correct ~ model_name * prompt_style * enable_thinking + vot_grid_state + vot_ray_trace + vot_hypothesis + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)

Analysis of Deviance Table (Type III Wald chisquare tests)

Response: atoms_correct

	Chisq	Df	Pr(>Chisq)
(Intercept)	27.2631	1	1.776e-07 ***
model_name	0.3670	2	0.8323348
prompt_style	0.0036	1	0.9520407

```

enable_thinking          0.8654  1  0.3522327
vot_grid_state           0.0599  1  0.8065953
vot_ray_trace            0.0614  1  0.8042212
vot_hypothesis           0.0005  1  0.9822117
mean_cells_per_ray       14.2036 1  0.0001641 ***
mean_atoms_per_ray       10.0086 1  0.0015581 **
model_name:prompt_style   1.4129  2  0.4933897
model_name:enable_thinking 0.3365  2  0.8451256
prompt_style:enable_thinking 15.3121 1  9.113e-05 ***
model_name:prompt_style:enable_thinking 3.9425  2  0.1392848
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

Groups	Name	Std.Dev.
config_index	(Intercept)	0.86425
	Residual	0.79650

Random Effects — Configuration (config_index) variance accounts for config-level difficulty and allows generalization beyond these 10 configurations.

ICC: 0.541 — Proportion of variance due to configuration clustering

Model Fit: - **Marginal R²** (fixed effects only): 0.123 - **Conditional R²** (fixed + random effects): 0.597

```

# Model 2: Score (main effects with config random effects)
if (length(vot_parts) > 0) {
  score_formula <- paste0("score ~ ", main_formula, " + ",
                          paste(vot_parts, collapse = " + "),
                          " + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)")
} else {
  score_formula <- paste0("score ~ ", main_formula,
                          " + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)")
}

model_score <- lmer(as.formula(score_formula), data = play_data)

```

4.2.2.2 Model 2: Score (Lower is Better)

Testing which factors affect game score.

Model formula: score ~ model_name * prompt_style * enable_thinking + vot_grid_state + vot_ray_trace + vot_hypothesis + mean_cells_per_ray + mean_atoms_per_ray + (1 | config_index)

Analysis of Deviance Table (Type III Wald chisquare tests)

Response: score

	Chisq	Df	Pr(>Chisq)	
(Intercept)	23.5213	1	1.235e-06	***
model_name	0.3128	2	0.85524	
prompt_style	11.5430	1	0.00068	***
enable_thinking	5.5337	1	0.01865	*
vot_grid_state	1.9582	1	0.16171	
vot_ray_trace	0.0620	1	0.80331	
vot_hypothesis	1.9525	1	0.16231	
mean_cells_per_ray	55.5404	1	9.156e-14	***
mean_atoms_per_ray	4.3600	1	0.03679	*
model_name:prompt_style	2.0350	2	0.36150	
model_name:enable_thinking	4.0974	2	0.12890	
prompt_style:enable_thinking	19.1000	1	1.240e-05	***
model_name:prompt_style:enable_thinking	5.8130	2	0.05467	.
<hr/>				
Signif. codes:	0	'***'	0.001	'**'
	0.01	'*'	0.05	'. '
	0.1	' '	1	

Groups	Name	Std.Dev.
config_index	(Intercept)	6.4130
	Residual	5.3934

ICC: 0.586

Model Fit: - Marginal R²: 0.104 - Conditional R²: 0.629

Effect Modification by Ray Complexity (Play Mode)

Does ray complexity (mean atoms per ray) moderate treatment effects?

```
...: {.cell}
`~`{.r .cell-code}
run_play_effect_mod <- has_model_var || has_prompt_var || has_thinking_var

if (run_play_effect_mod) {
  # Build interaction formula with random effect
  interaction_parts <- c()
```

```

if (has_model_var) interaction_parts <- c(interaction_parts, "model_name * mean_atoms_per_ray")
if (has_prompt_var) interaction_parts <- c(interaction_parts, "prompt_style * mean_atoms_per_ray")
if (has_thinking_var) interaction_parts <- c(interaction_parts, "enable_thinking * mean_atoms_per_ray")

atoms_mod_formula <- paste0("atoms_correct ~ ",
                             paste(interaction_parts, collapse = " + "),
                             " + (1 | config_index)")
score_mod_formula <- paste0("score ~ ",
                            paste(interaction_parts, collapse = " + "),
                            " + (1 | config_index)")

model_atoms_mod <- lmer(as.formula(atoms_mod_formula), data = play_data)
model_score_mod <- lmer(as.formula(score_mod_formula), data = play_data)
}

```

:::

Atoms Correct Model: atoms_correct ~ model_name * mean_atoms_per_ray + prompt_style * mean_atoms_per_ray + enable_thinking * mean_atoms_per_ray + (1 | config_index)

Analysis of Deviance Table (Type III Wald chisquare tests)

Response: atoms_correct

	Chisq	Df	Pr(>Chisq)
(Intercept)	5.1668	1	0.023022 *
model_name	0.4739	2	0.789024
mean_atoms_per_ray	1.2987	1	0.254447
prompt_style	8.8511	1	0.002929 **
enable_thinking	1.4040	1	0.236057
model_name:mean_atoms_per_ray	0.9369	2	0.625956
mean_atoms_per_ray:prompt_style	1.3581	1	0.243861
mean_atoms_per_ray:enable_thinking	0.0355	1	0.850581

Signif. codes:	0 '***'	0.001 '**'	0.01 '*'
	0.05 '.'	0.1 ' '	1

Score Model: score ~ model_name * mean_atoms_per_ray + prompt_style * mean_atoms_per_ray + enable_thinking * mean_atoms_per_ray + (1 | config_index)

Analysis of Deviance Table (Type III Wald chisquare tests)

```

Response: score
              Chisq Df Pr(>Chisq)
(Intercept)      134.4055  1 < 2.2e-16 ***
model_name        0.9796  2  0.6127337
mean_atoms_per_ray 17.1909  1  3.381e-05 ***
prompt_style     11.0847  1  0.0008704 ***
enable_thinking    0.6117  1  0.4341481
model_name:mean_atoms_per_ray 1.0161  2  0.6016530
mean_atoms_per_ray:prompt_style 13.9388  1  0.0001889 ***
mean_atoms_per_ray:enable_thinking 0.0267  1  0.8701434
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

4.2.3 Regression Analysis: Play Mode

Regression complements ANOVA by providing interpretable effect magnitudes. Coefficients show the expected change in outcome per unit change in predictor.

```

# Build formula with factors that have variation
regression_parts <- formula_parts # From earlier: model_name, prompt_style, enable_thinking
if (has_vot_grid) regression_parts <- c(regression_parts, "vot_grid_state")
if (has_vot_ray) regression_parts <- c(regression_parts, "vot_ray_trace")
if (has_vot_hyp) regression_parts <- c(regression_parts, "vot_hypothesis")
regression_parts <- c(regression_parts, "mean_atoms_per_ray", "mean_cells_per_ray")

atoms_reg_formula <- paste0("atoms_correct ~ ", paste(regression_parts, collapse = " + "),
                            " + (1 | config_index)")

lmer_atoms <- lmer(as.formula(atoms_reg_formula), data = play_data)

# Tidy summary (fixed effects only)
atoms_reg_summary <- tidy(lmer_atoms, effects = "fixed", conf.int = TRUE) |>
  mutate(across(c(estimate, conf.low, conf.high, statistic), ~round(., 3)),
         p.value = format.pval(p.value, digits = 3, eps = 0.001)) |>
  select(term, estimate, std.error, statistic, p.value, conf.low, conf.high)

kable(atoms_reg_summary,
      col.names = c("Term", "Coefficient", "SE", "t-statistic", "p-value", "95% CI Lower",
      caption = "Regression Coefficients: Atoms Correct (Fixed Effects)")

```

Table 26: Regression Coefficients: Atoms Correct (Fixed Effects)

Term	(Coefficient)	SE	t-statistic	p-value	95% CI Lower	95% CI Upper
(Intercept)	2.361	0.4790025	4.930	< 0.001	1.404	3.319
model_nameSonnet 4.5	0.135	0.0911824	1.481	0.13916	-0.044	0.314
model_nameOpus 4.5	0.164	0.0908236	1.802	0.07227	-0.015	0.342
prompt_styleaugmented	0.494	0.0742062	6.656	< 0.001	0.348	0.640
enable_thinkingTRUE	0.236	0.0754796	3.122	0.00191	0.087	0.384
vot_grid_stateTRUE	-0.024	0.1047820	-0.230	0.81816	-0.230	0.182
vot_ray_traceTRUE	-0.025	0.1047642	-0.242	0.80867	-0.231	0.180
vot_hypothesisTRUE	-0.005	0.1049183	-0.050	0.95976	-0.211	0.201
mean_atoms_per_ray	-0.575	0.2067574	-2.782	0.00562	-0.981	-0.169
mean_cells_per_ray	-0.174	0.0425068	-4.101	< 0.001	-0.258	-0.091

```
r2_atoms_reg <- performance::r2_nakagawa(lmer_atoms)

# Model for Score
score_reg_formula <- paste0("score ~ ", paste(regression_parts, collapse = " + "),
                            " + (1 | config_index)")

lmer_score <- lmer(as.formula(score_reg_formula), data = play_data)

score_reg_summary <- tidy(lmer_score, effects = "fixed", conf.int = TRUE) |>
  mutate(across(c(estimate, conf.low, conf.high, statistic), ~round(., 3)),
         p.value = format.pval(p.value, digits = 3, eps = 0.001)) |>
  select(term, estimate, std.error, statistic, p.value, conf.low, conf.high)

kable(score_reg_summary,
      col.names = c("Term", " (Coefficient)", "SE", "t-statistic", "p-value", "95% CI Lower",
      caption = "Regression Coefficients: Score (Fixed Effects)")
```

Table 27: Regression Coefficients: Score (Fixed Effects)

Term	(Coefficient)	SE	t-statistic	p-value	95% CI Lower	95% CI Upper
(Intercept)	18.409	3.3575784	5.483	<0.001	11.673	25.144
model_nameSonnet 4.5	-0.619	0.6173580	-1.003	0.3165	-1.832	0.594
model_nameOpus 4.5	-0.869	0.6149246	-1.413	0.1585	-2.077	0.340
prompt_styleaugmented	0.633	0.5024199	1.260	0.2082	-0.354	1.621
enable_thinkingTRUE	-1.230	0.5110886	-2.407	0.0165	-2.235	-0.226
vot_grid_stateTRUE	0.967	0.7094300	1.363	0.1736	-0.427	2.361
vot_ray_traceTRUE	-0.174	0.7093091	-0.246	0.8061	-1.568	1.220
vot_hypothesisTRUE	0.995	0.7103532	1.401	0.1619	-0.401	2.391
mean_atoms_per_ray	-3.464	1.4037725	-2.467	0.0140	-6.222	-0.705
mean_cells_per_ray	2.233	0.2880145	7.752	<0.001	1.667	2.799

```
r2_score_reg <- performance::r2_nakagawa(lmer_score)

# Standardized coefficients for comparison
std_coef_atoms <- standardize_parameters(lmer_atoms, method = "refit")
std_coef_score <- standardize_parameters(lmer_score, method = "refit")
```

Model Fit — Atoms Correct: - Marginal R²: 0.099 - Conditional R²: 0.584

Model Fit — Score: - Marginal R²: 0.085 - Conditional R²: 0.62

4.2.3.1 Standardized Coefficients (Beta Weights)

Allows comparison of relative importance across fixed effects (based on fixed effects only).

Atoms Correct (Top 10):

```
# Standardization method: refit
```

Parameter	Std. Coef.	95% CI
<hr/>		
prompt style [augmented]	0.37	[0.26, 0.48]
enable thinking [TRUE]	0.18	[0.07, 0.29]

mean cells per ray		-0.13	[-0.20, -0.07]
mean atoms per ray		-0.13	[-0.22, -0.04]
model name [Opus 4.5]		0.12	[-0.01, 0.26]
model name [Sonnet 4.5]		0.10	[-0.03, 0.24]
vot ray trace [TRUE]		-0.02	[-0.17, 0.14]
vot grid state [TRUE]		-0.02	[-0.17, 0.14]
vot hypothesis [TRUE]		-4.01e-03	[-0.16, 0.15]

Score (Top 10):

```
# Standardization method: refit
```

Parameter		Std. Coef.		95% CI
<hr/>				
mean cells per ray		0.27	[0.20, 0.34]	
enable thinking [TRUE]		-0.15	[-0.26, -0.03]	
mean atoms per ray		-0.12	[-0.22, -0.02]	
vot hypothesis [TRUE]		0.12	[-0.05, 0.28]	
vot grid state [TRUE]		0.11	[-0.05, 0.28]	
model name [Opus 4.5]		-0.10	[-0.25, 0.04]	
prompt style [augmented]		0.08	[-0.04, 0.19]	
model name [Sonnet 4.5]		-0.07	[-0.22, 0.07]	
vot ray trace [TRUE]		-0.02	[-0.19, 0.14]	

4.2.4 Interpretation: Why Configuration Random Effects?

Play mode data structure: - Unit of analysis: Entire games (one game per config × condition) - LLM chooses which rays to fire (endogenous ray selection) - Different conditions may fire different rays - Multiple games per configuration (clustering)

Why config-level random effects?

1. Games within same config share atom placement
2. Some configs are inherently harder/easier (random variation)
3. Generalizes inference beyond these 10 specific configurations
4. Accounts for correlation among games within same config

Why NOT ray-level random effects (unlike Predict mode)?

1. Rays are not predetermined—LLM chooses them
2. Different conditions may fire different rays
3. Ray selection is part of the strategy (endogenous)
4. No repeated measures at individual ray level

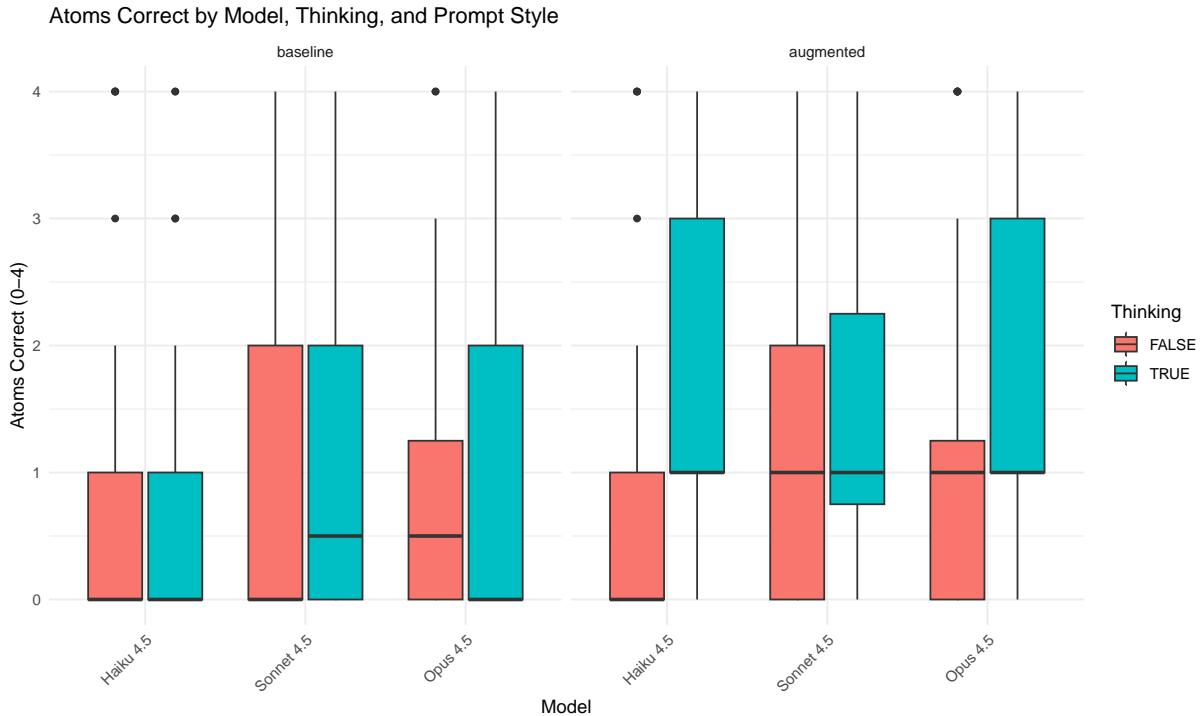
Covariates (mean_cells_per_ray, mean_atoms_per_ray): - **NOT confounders**: Ray choice is endogenous to experimental condition - **ARE precision variables**: Describe difficulty of rays LLM chose to fire - **Improve model fit**: Explain variance, increase power

Impact of ignoring config-level clustering: - Underestimates standard errors - Inflates Type I error (false positives) - Invalid inference (cannot generalize beyond these 10 configs)

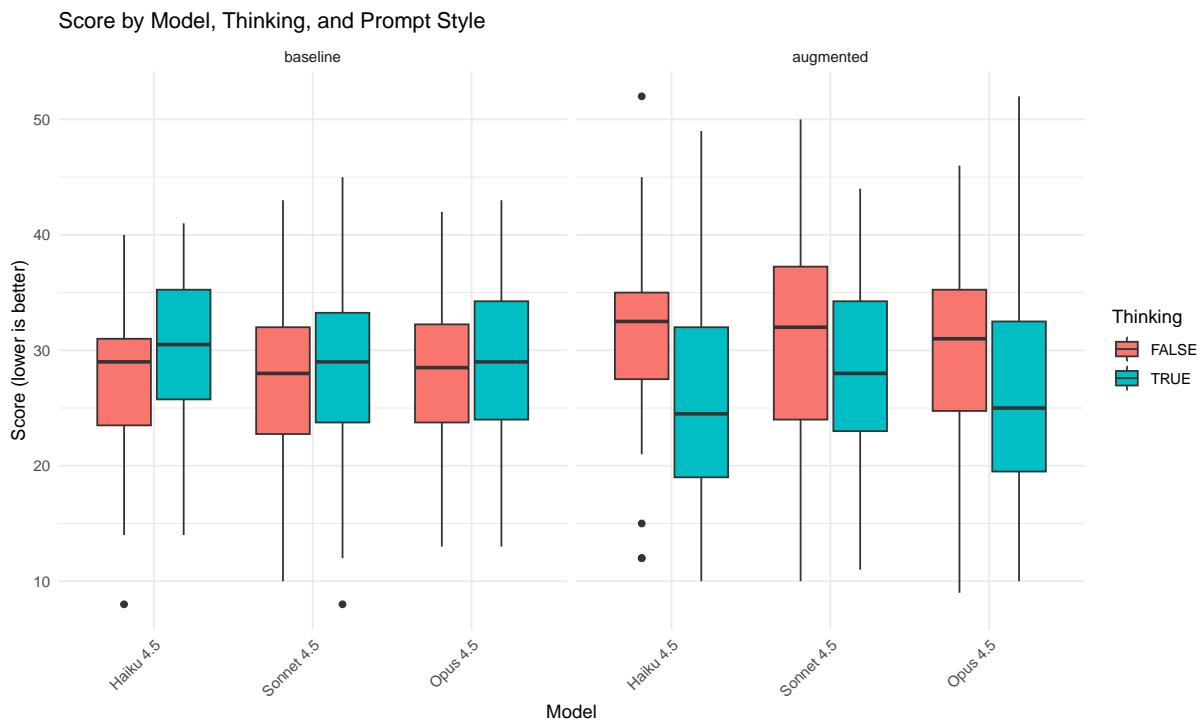
```
::: {.cell}

```{r .cell-code}
Atoms correct by model and thinking
p1 <- ggplot(play_data, aes(x = model_name, y = atoms_correct, fill = enable_thinking)) +
 geom_boxplot() +
 facet_wrap(~prompt_style) +
 labs(title = "Atoms Correct by Model, Thinking, and Prompt Style",
 x = "Model", y = "Atoms Correct (0-4)", fill = "Thinking") +
 theme(axis.text.x = element_text(angle = 45, hjust = 1))
print(p1)

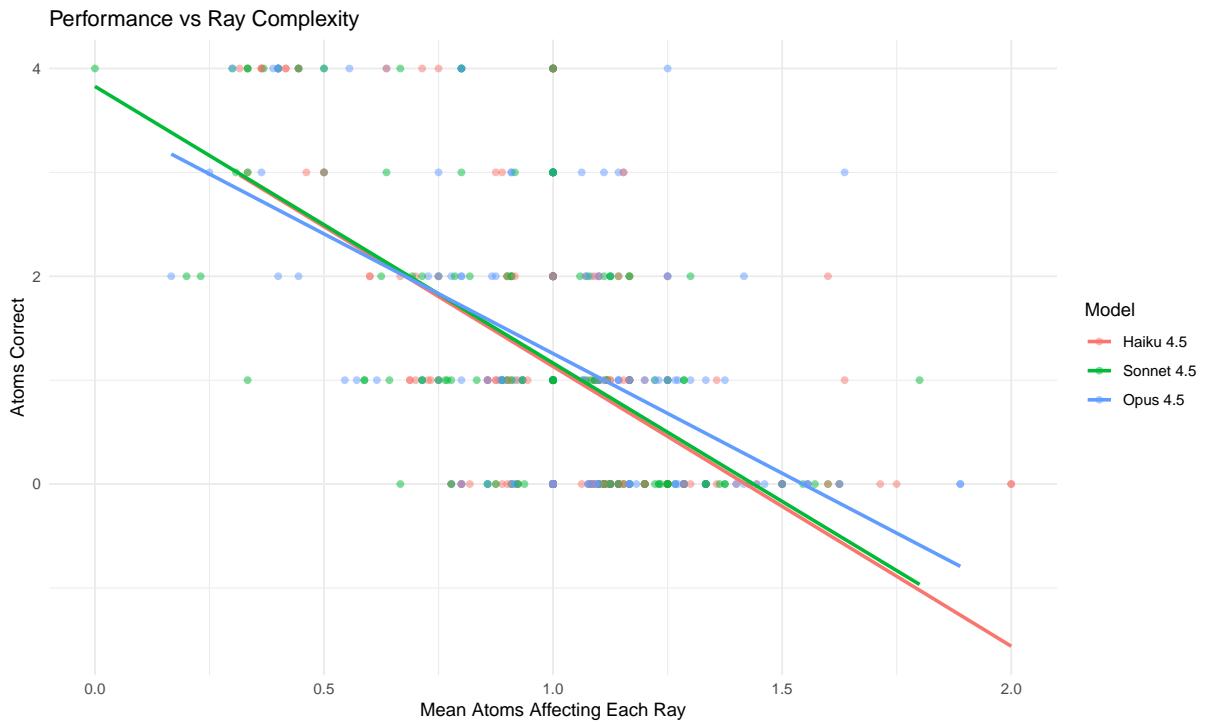
```



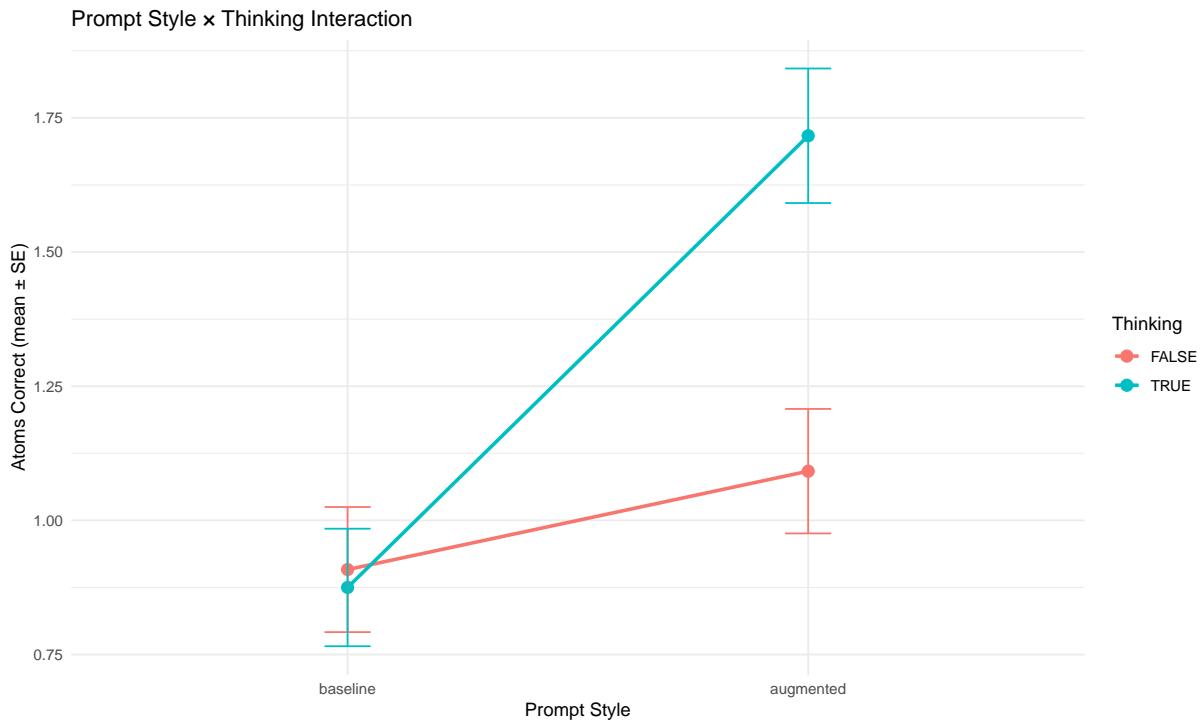
```
Score distribution
p2 <- ggplot(play_data, aes(x = model_name, y = score, fill = enable_thinking)) +
 geom_boxplot() +
 facet_wrap(~prompt_style) +
 labs(title = "Score by Model, Thinking, and Prompt Style",
 x = "Model", y = "Score (lower is better)", fill = "Thinking") +
 theme(axis.text.x = element_text(angle = 45, hjust = 1))
print(p2)
```



```
Mean atoms per ray relationship with performance
p3 <- ggplot(play_data, aes(x = mean_atoms_per_ray, y = atoms_correct, color = model_name)) +
 geom_point(alpha = 0.5) +
 geom_smooth(method = "lm", se = FALSE) +
 labs(title = "Performance vs Ray Complexity",
 x = "Mean Atoms Affecting Each Ray", y = "Atoms Correct",
 color = "Model") +
 theme_minimal()
print(p3)
```



```
Interaction plot: Prompt Style × Thinking
p4 <- ggplot(play_data, aes(x = prompt_style, y = atoms_correct,
 color = enable_thinking, group = enable_thinking)) +
 stat_summary(fun = mean, geom = "point", size = 3) +
 stat_summary(fun = mean, geom = "line", linewidth = 1) +
 stat_summary(fun.data = mean_se, geom = "errorbar", width = 0.1) +
 labs(title = "Prompt Style × Thinking Interaction",
 x = "Prompt Style", y = "Atoms Correct (mean ± SE)",
 color = "Thinking") +
 theme_minimal()
print(p4)
```



⋮

### 4.3 Error Analysis

```
Placeholder for error taxonomy
Will categorize errors from extended thinking traces

error_categories <- c(
"Constraint tracking failure",
"Spatial reasoning error",
"Non-parsimonious hypothesis",
"Failure to update on evidence",
"Experiment design inefficiency"
)
```

[Error analysis to be added after data collection]

## **5 Discussion**

### **5.1 Summary of Findings**

[To be completed after data collection]

### **5.2 Relation to Literature**

#### **5.2.1 Constraint Satisfaction**

[Discuss how results relate to ZebraLogic, GenCP findings]

#### **5.2.2 Spatial Reasoning**

[Discuss how results relate to PLUGH, spatial reasoning benchmarks]

#### **5.2.3 World Models**

[Discuss how results relate to pulley system, text world simulator findings]

#### **5.2.4 Abductive Reasoning**

[Discuss how results relate to Occam's Razor, hypothesis generation findings]

## **5.3 Implications**

### **5.3.1 For LLM Deployment in Diagnostic Domains**

[Discuss implications for medical diagnosis, fault detection, and other diagnostic tasks]

### **5.3.2 For LLM-Modulo Architectures**

[Discuss whether tool augmentation addresses the limitations]

### **5.3.3 For Benchmark Development**

[Discuss Black Box as a diagnostic tool for reasoning assessment]

## 5.4 Limitations

1. **Single game domain:** Results may not generalize to all reasoning tasks
2. **Prompt sensitivity:** Different prompt formulations might yield different results
3. **Model versions:** Rapid model updates may change performance characteristics
4. **Sample size:** [Discuss statistical power]

## 5.5 Future Directions

1. **Extended model comparison:** GPT-4, Gemini, open-source models
2. **Tool augmentation study:** Provide ray-tracing verification tool
3. **Difficulty manipulation:** Vary grid size, atom count, atom arrangement
4. **Human baseline:** Compare LLM performance to human players
5. **Fine-tuning study:** Following the approach of Y. Wang et al. (2025), who demonstrated substantial reasoning improvements through game-specific training on Doudizhu and Go, test whether task-specific training on Black Box traces improves performance. Of particular interest is whether such training would generalize to novel atom configurations (in-distribution transfer) and to other spatial reasoning tasks (out-of-distribution transfer), or whether improvements would be limited to memorized patterns—the “catastrophic forgetting” phenomenon observed in their work when game training interfered with unrelated reasoning tasks

## 6 Conclusion

[To be completed after data collection]

## 7 References

## 8 Appendix A: Prompt Texts

### 8.1 Baseline Play Prompt

You are playing Black Box, a game of hide and seek played on an 8 by 8 grid.

Your opponent has hidden 4 balls within this box. By shooting rays into the box and observing where they emerge, it is possible to deduce the positions of the hidden balls.

GRID: 8x8, rows 1-8 (top to bottom), columns 1-8 (left to right).

RAYS: Fire from edge positions - NORTH/SOUTH use columns 1-8, EAST/WEST use rows 1-8.

There are three possible outcomes for each ray you send into the box:

DETOUR: The ray is deflected and emerges somewhere other than where you sent it in. Detours are denoted by matching pairs of numbers.

REFLECTION (R): The ray is reflected and emerges in the same place it was sent in.

HIT (H): The ray strikes a ball directly and is absorbed.

[ASCII diagram examples showing deflection, reflection, and hit patterns...]

SCORING:

Your goal is to minimize your score. Lower is better.

- Each ray entry point costs 1 point
- Each ray exit point costs 1 point (detours cost 2 total, reflections cost 1)
- Each missed atom costs 5 points

RULES:

- You cannot fire from positions already used as entry or exit points.
- Maximum 20 rays.

Respond with JSON only:

```
{"action": "fire", "side": "north|south|east|west", "position": 1-8, "reasoning": "..."}
{"action": "guess", "atoms": [[row,col], [row,col], [row,col], [row,col]], "reasoning": "..."}
```

## 8.2 Baseline Predict Prompt

Predict where a ray will exit in Black Box.

GRID: 8x8, rows 1-8 (top to bottom), columns 1-8 (left to right).

EDGES: NORTH/SOUTH use columns 1-8, EAST/WEST use rows 1-8.

As a ray approaches a ball it is deflected ninety degrees. Rays can be deflected multiple times.

[ASCII diagram examples showing deflection, reflection, and hit patterns...]

Respond with JSON only:

```
{"exit_side": "north|south|east|west", "exit_position": 1-8, "reasoning": "..."}
OR for absorption: {"absorbed": true, "reasoning": "..."}
OR for reflection: {"reflected": true, "reasoning": "..."}
```

### 8.3 Augmented Prompt

[Full augmented prompt text to be included]

### 8.4 Hypothesis-Enabled Play Prompt Extension

When hypotheses are enabled, the response format is extended:

Respond with JSON only:

```
{"action": "fire", "side": "north|south|east|west", "position": 1-8, "reasoning": "..."}
{"action": "mark", "row": 1-8, "col": 1-8, "reasoning": "..."} - mark suspected atom
{"action": "unmark", "row": 1-8, "col": 1-8, "reasoning": "..."} - remove marked position
{"action": "check", "reasoning": "..."} - submit answer (requires exactly 4 marked positions)
```

## 9 Appendix B: Sample Game Traces

[Representative game traces showing LLM reasoning]

## 10 Appendix C: Error Taxonomy

[Detailed coding scheme for error analysis]

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