

robOS2.hardware.sick.PLS112Driver.query

```
graph LR; A[robOS2.hardware.sick.PLS112Driver.query] --> B[robOS2.utility.SICKHelper.intToByteArray]; A --> C[robOS2.serial.Connection.writeData];
```

robOS2.utility.SICKHelper.intToByteArray

robOS2.serial.Connection.writeData