

robOS2.hardware.sick.SICKData.buildFromFile



```
graph LR; A[robOS2.hardware.sick.SICKData.buildFromFile] --> B[robOS2.hardware.sick.SICKData.processLine]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'robOS2.hardware.sick.SICKData.buildFromFile'. The right box is white with a black border and contains the text 'robOS2.hardware.sick.SICKData.processLine'. A blue arrow points from the right side of the left box to the left side of the right box.

robOS2.hardware.sick.SICKData.processLine