


robOS2.serial.Config.getBaudRate



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graph LR; A[robOS2.serial.Config.getBaudRate] --> B[robOS2.serial.Device.getBaudRate]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'robOS2.serial.Config.getBaudRate'. The right box is white with a black border and contains the text 'robOS2.serial.Device.getBaudRate'. A dark blue arrow points from the right side of the left box to the left side of the right box.

robOS2.serial.Device.getBaudRate