

robOS2.hardware.sick.PLS112Driver.toSetupMode

```
graph LR; A[robOS2.hardware.sick.PLS112Driver.toSetupMode] --> B[robOS2.utility.SICKHelper.intToByteArray]; A --> C[robOS2.serial.Connection.writeData];
```

The diagram illustrates a method call sequence. A gray rectangular box on the left contains the text 'robOS2.hardware.sick.PLS112Driver.toSetupMode'. Two blue arrows originate from the right side of this box. The top arrow points to a white rectangular box containing 'robOS2.utility.SICKHelper.intToByteArray'. The bottom arrow points to another white rectangular box containing 'robOS2.serial.Connection.writeData'.

robOS2.utility.SICKHelper.intToByteArray

robOS2.serial.Connection.writeData