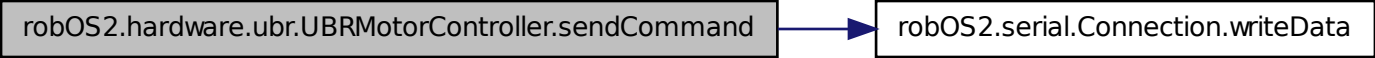


robOS2.hardware.ubr.UBRMotorController.sendCommand



```
graph LR; A[robOS2.hardware.ubr.UBRMotorController.sendCommand] --> B[robOS2.serial.Connection.writeData]
```

robOS2.serial.Connection.writeData