

robOS2.simulator.InputParser.InputParser

```
graph LR; A[robOS2.simulator.InputParser.InputParser] --> B[robOS2.simulator.InputParser.parse]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and contains the text 'robOS2.simulator.InputParser.InputParser'. The right box has a white background and contains the text 'robOS2.simulator.InputParser.parse'. A dark blue arrow points from the right side of the left box to the left side of the right box.

robOS2.simulator.InputParser.parse