

robOS2.hardware.interfaces.drivers.ILIDAR



```
graph BT; A[robOS2.hardware.sick.PLS112Driver] --> B[robOS2.hardware.interfaces.drivers.ILIDAR];
```

The diagram illustrates an inheritance relationship between two ROS2 driver classes. At the bottom is a white box labeled 'robOS2.hardware.sick.PLS112Driver'. A blue arrow points vertically upwards from this box to a gray box at the top labeled 'robOS2.hardware.interfaces.drivers.ILIDAR', indicating that the PLS112Driver class inherits from the ILIDAR interface.

robOS2.hardware.sick.PLS112Driver