

robOS2.hardware.ubr.UBRMotorController.updateRobotStatusScreen



```
graph LR; A[robOS2.hardware.ubr.UBRMotorController.updateRobotStatusScreen] --> B[robOS2.serial.Connection.writeData]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'robOS2.hardware.ubr.UBRMotorController.updateRobotStatusScreen'. The right box is white and contains the text 'robOS2.serial.Connection.writeData'. A blue arrow points from the right side of the gray box to the left side of the white box.

robOS2.serial.Connection.writeData