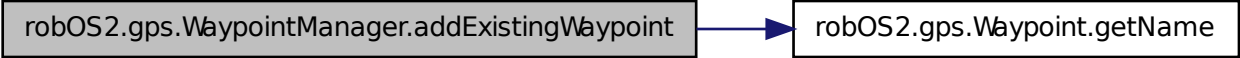


robOS2.gps.WaypointManager.addExistingWaypoint



```
graph LR; A[robOS2.gps.WaypointManager.addExistingWaypoint] --> B[robOS2.gps.Waypoint.getName];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'robOS2.gps.WaypointManager.addExistingWaypoint'. The right box is white with a black border and contains the text 'robOS2.gps.Waypoint.getName'. A blue arrow points from the right side of the gray box to the left side of the white box.

robOS2.gps.Waypoint.getName