

robOS2.hardware.sick.PLS112Driver.constantBaud

```
graph LR; A[robOS2.hardware.sick.PLS112Driver.constantBaud] --> B[robOS2.utility.SICKHelper.intToByteArray]; A --> C[robOS2.serial.Connection.writeData];
```

The diagram illustrates a variable, `robOS2.hardware.sick.PLS112Driver.constantBaud`, which is highlighted with a gray background. Two blue arrows originate from the right side of this variable box. The top arrow points to a box containing the method `robOS2.utility.SICKHelper.intToByteArray`. The bottom arrow points to a box containing the method `robOS2.serial.Connection.writeData`. All boxes have black borders and are arranged horizontally from left to right.

robOS2.utility.SICKHelper.intToByteArray

robOS2.serial.Connection.writeData