

robOS2.hardware.sick.PLS112Driver.toRequestOnlyMode

```
graph LR; A[robOS2.hardware.sick.PLS112Driver.toRequestOnlyMode] --> B[robOS2.utility.SICKHelper.intToByteArray]; A --> C[robOS2.serial.Connection.writeData];
```

The diagram illustrates a method call sequence. A central node, 'robOS2.hardware.sick.PLS112Driver.toRequestOnlyMode', is shown in a grey box. Two blue arrows originate from its right side, pointing to two separate white boxes. The top arrow points to 'robOS2.utility.SICKHelper.intToByteArray', and the bottom arrow points to 'robOS2.serial.Connection.writeData'.

robOS2.utility.SICKHelper.intToByteArray

robOS2.serial.Connection.writeData