Name: Tarun Tanmay Class: MBATech CE Sem: 6 Roll No: N049 SAP ID: 70471018055 In []: #Experiment 7 #CNN for large database of images In []: #This code is used to mount the drive on the colab notebook through code as everytime you leave the notebo ok, #you will have to mount it again. from google.colab import drive drive.mount('/content/drive') Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force remount=True) . In []: path1='/content/drive/My Drive/v_data/train' path2='/content/drive/My Drive/v data/test' In []: from keras.preprocessing.image import ImageDataGenerator from keras.models import Sequential from keras.layers import Conv2D, MaxPooling2D from keras.layers import Activation, Dropout, Flatten, Dense from keras import backend as bck In []: width, height=224, 224 train_data_dir=path1 validation_data_dir=path2 In []: train samples=400 validation_samples=100 no epochs=10 In []: #This code it used to specify whether the number of channels (RGB planes) is coming first or last. if bck.image data format() == 'channels first': input_sh=(3,width,height) else: input_sh=(width,height,3) In []: model=Sequential() #First convolutional layer model.add(Conv2D(32, (2,2), input_shape=input_sh)) model.add(Activation('relu')) model.add(MaxPooling2D(pool size=(2,2))) #Second convolutional layer model.add(Conv2D(32, (2,2)))model.add(Activation('relu')) model.add(MaxPooling2D(pool_size=(2,2))) #Third convolutional layer model.add(Conv2D(64, (2,2))) model.add(Activation('relu')) model.add(MaxPooling2D(pool size=(2,2)))

```
model.add(Flatten())
model.add(Dense(64))
model.add(Activation('relu'))
model.add(Dropout(0.5))
model.add(Dense(1))
model.add(Activation('sigmoid'))
In [ ]:
model.compile(loss='binary crossentropy',optimizer='rmsprop',metrics=['accuracy'])
In [ ]:
#Augmenting the dataset i.e. creating new images by working on the given images to create more samples and
prevent overfitting
#shear means shrinking in one direction and elongating in another
#zoom here is zooming the image
#horizontal flip means flipping the image horizontally
#Images normalised by dividing all of them by 255
#Randomly a few images will under go this augmentation. Not all images are augmented.
train \ data = Image Data Generator (rescale = 1./255, \ shear\_range = 0.2, zoom\_range = 0.2, horizontal\_flip = True)
test data=ImageDataGenerator(rescale=1./255)
In [ ]:
train_set=train_data.flow_from_directory(train_data_dir, target_size=(width,height), batch_size=16,class_m
ode='binary')
validation set=test data.flow from directory(validation data dir, target size=(width, height), batch size=1
6, class mode='binary')
Found 400 images belonging to 2 classes.
Found 100 images belonging to 2 classes.
In [ ]:
#As we are using augmented data set and flow from directory, we use model.fit generator
#no labels
#400 models are exhausted in number of iterations 16 at a time
model.fit generator(train set, steps per epoch=train samples//16, epochs=no epochs, validation data=valida
tion set)
/usr/local/lib/python3.7/dist-packages/tensorflow/python/keras/engine/training.py:1844: UserWarning: `Model
.fit generator` is deprecated and will be removed in a future version. Please use `Model.fit`, which suppor
ts generators.
 warnings.warn('`Model.fit generator` is deprecated and '
Epoch 1/10
25/25 [=========== ] - 5s 195ms/step - loss: 1.0676 - accuracy: 0.5601 - val_loss: 0.3891
- val accuracy: 0.9500
Epoch 2/10
- val accuracy: 0.9100
Epoch 3/10
25/25 [========== ] - 5s 189ms/step - loss: 0.4489 - accuracy: 0.7954 - val loss: 0.2507
- val_accuracy: 0.9000
Epoch 4/10
25/25 [========== ] - 5s 190ms/step - loss: 0.4452 - accuracy: 0.8281 - val loss: 0.3068
- val accuracy: 0.9000
Epoch 5/10
- val accuracy: 0.8800
Epoch 6/10
- val_accuracy: 0.8900
Epoch 7/10
- val_accuracy: 0.8300
Epoch 8/10
- val_accuracy: 0.8900
Epoch 9/10
- val_accuracy: 0.8400
Epoch 10/10
- val accuracy: 0.8700
Out[]:
<tensorflow.python.keras.callbacks.History at 0x7f81e855aa50>
```

In []:

```
model.save('adv cnn.h5')
In [ ]:
from keras.models import load model
model=load model('adv cnn.h5')
In [ ]:
predict=model.predict_classes(validation_set)
/usr/local/lib/python3.7/dist-packages/tensorflow/python/keras/engine/sequential.py:450: UserWarning: `mode
l.predict_classes()` is deprecated and will be removed after 2021-01-01. Please use instead:* `np.argmax(mo
del.predict(x), axis=-1)`, if your model does multi-class classification (e.g. if it uses a `softmax` l ast-layer activation).* `(model.predict(x) > 0.5).astype("int32")`, if your model does binary classificat ion (e.g. if it uses a `sigmoid` last-layer activation).
  warnings.warn('`model.predict_classes()` is deprecated and '
In [ ]:
# here class '0' is car, '1' is plane
predict[1]
Out[]:
array([0], dtype=int32)
In [ ]:
train set.class indices
Out[]:
{'cars': 0, 'planes': 1}
In [ ]:
import matplotlib.pyplot as plt
plt.imshow(validation set[0][0][1])
<matplotlib.image.AxesImage at 0x7f81c63422d0>
   0
  25
  50
  75
 100
 125
 150
 175
```

200

100

150

200