Last time:

momentum, position, relocity of a system of many particles

$$\hat{\vec{p}} = \vec{m}, \vec{V}, + m_z \vec{V}_2 + \dots + m_N \vec{V}_N$$

$$\vec{\nabla} = \frac{m_1 \vec{v}_1 + m_2 \vec{v}_2 + \dots + m_N \vec{v}_N}{m_1 + m_2 + \dots + m_N}$$

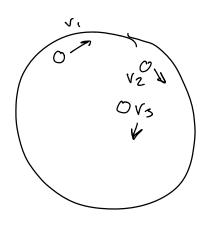
$$\vec{r} = \frac{M_1 \vec{r}_1 + m_2 \vec{r}_2 + \dots + m_N \vec{r}_N}{m_1 + m_2 + \dots + m_N}$$

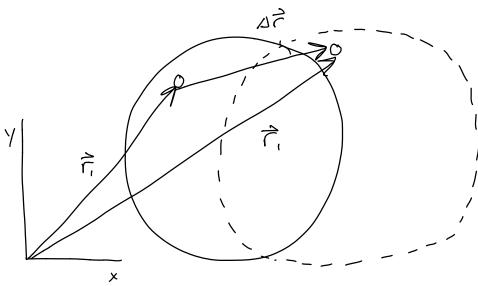
Conclusion: The system behaves like its own particle!

Show Phet sims

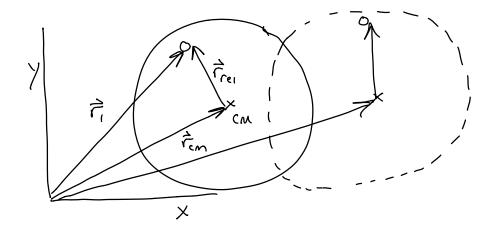
The energy of a multiparticle system

 $K = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 + \dots + \frac{1}{2} m_N v_N^2$





$$\vec{\nabla}_{i} = \vec{\partial}_{i} \vec{r}_{i}$$



position of m, = position of cm +

position of M,

relative to cm

$$\overrightarrow{V}_{1} = \frac{d}{dt} = \frac{d}{dt} \left(\overrightarrow{r}_{cm} + \overrightarrow{r}_{j,rel} \right)$$

$$\overrightarrow{V}_{1} = \overrightarrow{V}_{cm} + \overrightarrow{V}_{l,rel}$$

$$\overrightarrow{V}_{1} = \frac{1}{2} m V_{1}^{2}$$

$$\overrightarrow{V}_{1} = \left(V_{x} + V_{1x}, V_{y} + V_{1y}, V_{z} + V_{1z} \right)$$

 $V_{i}^{2} = (V_{x} + V_{ix})^{2} + (V_{y} + V_{iy})^{2} + (V_{z} + V_{iz})^{2}$

$$V_{i}^{2} = V_{x}^{2} + V_{ix}^{2} + \lambda V_{x}V_{ix}$$

$$+ V_{y}^{2} + V_{iy}^{2} + \lambda V_{y}V_{iy}$$

$$+ V_{z}^{2} + V_{iz}^{2} + \lambda V_{z}V_{iz}$$

$$K_{1} = \frac{1}{Z} m_{1} \left(V_{cm}^{2} + V_{rel,1} + 2 \vec{V}_{cm} \cdot \vec{V}_{rel,1} \right)$$

$$K_{1} = \frac{1}{Z} m_{1} V_{cm}^{2} + \frac{1}{Z} m_{1} V_{rel,1} + m_{1} \vec{V}_{sm} \cdot \vec{V}_{rel,1}$$

$$K_{+n+} = K_1 + K_2 + \dots + K_N$$

$$= \frac{1}{2} m_1 \sqrt{c_m} + \frac{1}{2} m_1 \sqrt{c_{\text{rel},1}} + m_1 \sqrt{c_{\text{rel},2}}$$

+
$$\frac{1}{2}$$
 m_z V_{cn} + $\frac{1}{2}$ m_z $V_{rei,2}$ + m_z \overrightarrow{V}_{cm} $\cdot \overrightarrow{V}_{rei,1}$

$$= \frac{1}{2} \left(m_1 + m_2 + ..., m_N \right) V_{i,m}^2$$

$$= \frac{1}{Z} M V_{cm}^{2} + \sum_{i=1}^{N} \frac{1}{Z} m_{i} V_{rei,i}^{2} + \overrightarrow{V}_{cm} \cdot \overrightarrow{p}_{rei}^{2}$$

$$\overrightarrow{P}_{rel} = \overrightarrow{P} - \overrightarrow{P}_{en}$$

$$= (m_1 \overrightarrow{V}_1 + m_2 \overrightarrow{V}_2 + ..., m_N \overrightarrow{V}_N) - (m_1 \overrightarrow{V}_1 + m_2 \overrightarrow{V}_2 + ...)$$

$$= 0$$

What do these terms mean?

I m Ven is the "normal" Kinetic energy

IF I throw the frisher (m= 140)

a + 20 m/s, then

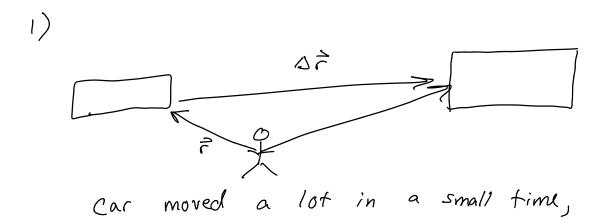
 $\frac{1}{2} m V_{cm} = \frac{1}{2} (0.14 \text{ kg}) (20 \text{ m/s})^2 = 28 \text{ J}$

what is $\frac{1}{2} \geq m_i \sqrt{n_{ei}}$???

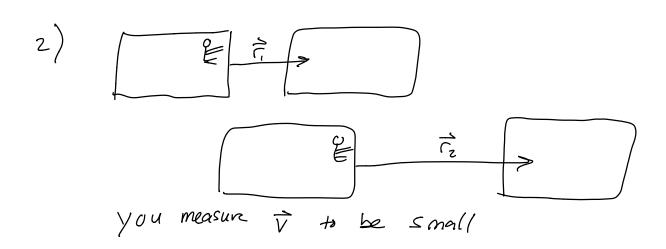
Vrei is the velocity relative to the center of mass

Relative velocity

If a car speeds past you while you stand on the side of the road:



you measure a large v



who is right? Both!

What is Vrel?

The velocity we see if we are traveling inside the object at the same speed as the center of mass

- Same thing as if the ball is rotating in place

Conclusion:

translational

L = K +vans + Krel

Krei = Krot + Kvib

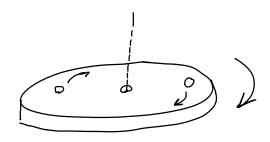
What is Krot?

- Consider a rigid body (shape isn't Changing)

Which is rotating about an axis

Axis of rotation:

-the straight line through all fixed points of a rotating object around which all other points rotate



View from top down

f = # rotations/sec

This point travels a distance
2Tr per rotation

The point completes "f" rotations
per second

So each second, it travels $2\pi rf$ so, $|\vec{V}| = 2\pi rf$

-This means that atoms for away from the axis of rotation are moving faster Usually, we specify the speed of rotation as rad/sec, rather than rot/sec

w = rad/sec

 $\omega = \frac{\text{rot}}{\text{sec}} \times \frac{\text{rad}}{\text{rot}} = 2\pi f$

 $\omega = 2\pi f$

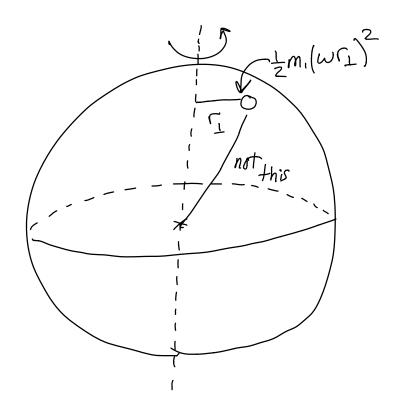
So $\sqrt{e} = \omega$

 $K_{rot} = \frac{1}{Z} m_1 V_{1, rel} + \frac{1}{Z} m_2 V_{2, rel} + \frac{1}{Z} m_3 V_{3, rel} + \dots$

w is the same for each particle

 $K_{rot} = \frac{1}{2}m_{1}(\omega r_{11})^{2} + \frac{1}{2}m_{2}(\omega r_{12})^{2} + \frac{1}{2}m_{2}(\omega r_{13})^{2} + \dots$

I is the perpendicular distance to axis of rotation



$$K_{rot} = \frac{1}{2}m_{1}(\omega r_{11})^{2} + \frac{1}{2}m_{2}(\omega r_{12})^{2} + \frac{1}{2}m_{2}(\omega r_{13})^{2} + \dots$$

$$= \left(\frac{1}{2} m_{1} \Gamma_{1}^{2} + \frac{1}{2} m_{2} \Gamma_{12}^{2} + \frac{1}{2} m_{3} \Gamma_{13}^{2} + \dots\right) \omega^{2}$$

$$T \equiv \frac{1}{2} m_1 C_1^2 + \frac{1}{2} m_2 C_{12}^2 + \frac{1}{2} m_3 C_{13}^2 + \dots$$

$$I = \frac{1}{2} \sum_{i} M_{i} C_{i}^{2}$$

$$K_{rot} = \frac{1}{2} I \omega^2$$

Compare to:
$$L_{trans} = \frac{1}{Z} m v^2$$

$$m \longrightarrow I$$

I: resists change in w

Takes more energy to increase ω if:

- object is more massive

- mass is located further from axis of rotation