

Main concepts so far:

$$\text{velocity: } \vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$$

$$\vec{v} = \frac{d \vec{r}}{dt}$$

$$\text{momentum: } \vec{p} = m \vec{v}$$

$$\text{momentum principle: } \Delta \vec{p} = \vec{F}_{\text{net}} \Delta t$$

Book lists the so called
"position update equation"

$$\vec{r}_f = \vec{r}_i + \vec{v}_{\text{avg}} \Delta t$$

Not a new equation!

Same thing as

$$\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$$

The momentum update equation

$$\vec{p}_f = \vec{p}_i + \vec{F}_{\text{net}} \Delta t$$

Same eqn as

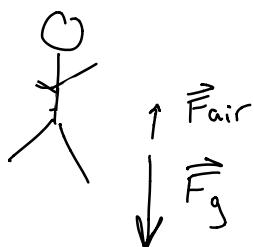
$$\Delta \vec{p} = \overrightarrow{\text{F}_{\text{net}}} \Delta t$$

QC 2.2.c

Future momentum depends on 2

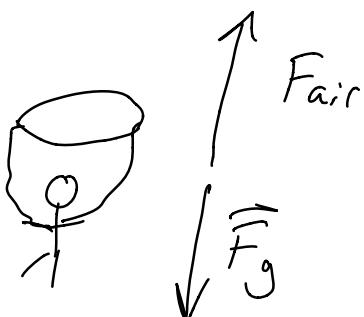
things: \vec{p}_{now} , $\overrightarrow{\text{F}_{\text{net}}} \Delta t_{\text{now}}$

Skydiver Example



initially, she accelerates downward

later, she opens her chute which increases air resistance so that the forces balance



Which best describes her motion from this point on?

- a) float w/o moving up or down
- b) continue falling at increasing speed
- c) fall at const speed

$\vec{F}_{\text{net}} = 0$, so $\Delta \vec{p} = 0$, so her momentum won't change. But, she already has downward momentum

$$\vec{p}_{\text{future}} \rightarrow \vec{p}_{\text{now}}$$
$$\vec{p}_{\text{future}} \rightarrow \vec{F}_{\text{net}} \Delta t$$

If an object has momentum, we can assume it interacted at some point in the past

- We don't need to know the entire history of an object, just \vec{p}_{now}

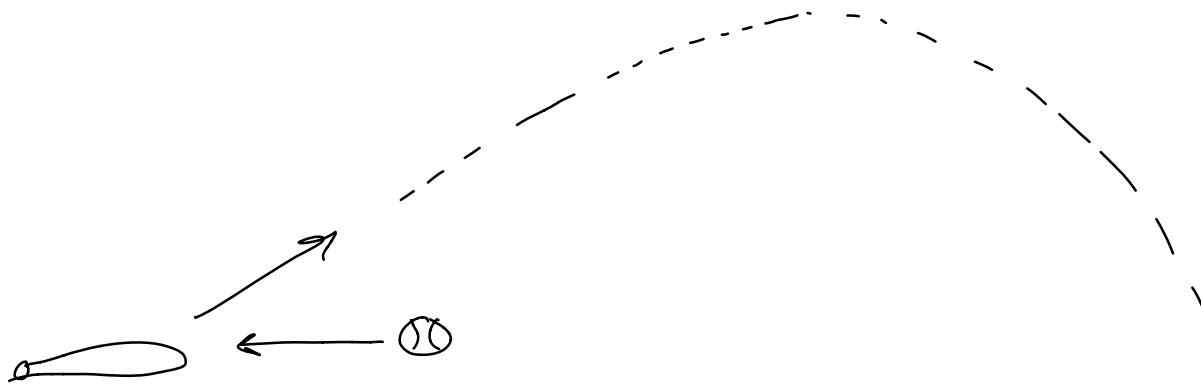
QC 2.4.b

2.4.c

Example:

Ball moving under influence of gravity

Gravity: $|\vec{F}| = mg$, $g = 9.81 \frac{\text{m}}{\text{s}^2}$



How?

1) Find \vec{p}_{now}

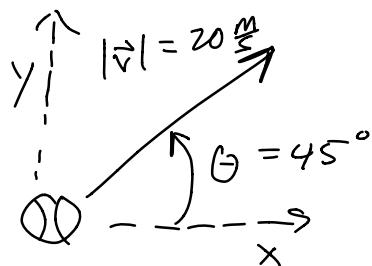
2) Find $\vec{F}_{\text{net, now}}$

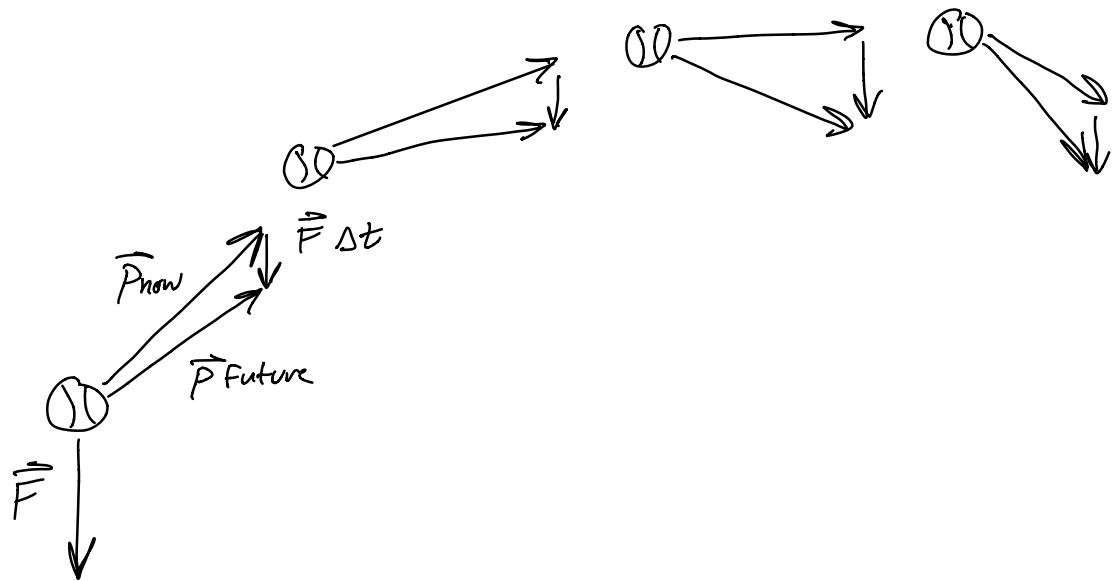
3) $\vec{p}_{\text{future}} = \vec{p}_{\text{now}} + \vec{F}_{\text{net, now}} \Delta t$

4) $\vec{r}_{\text{future}} = \vec{r}_{\text{now}} + \vec{v}_{\text{avg}} \Delta t$, if Δt is small,
 $m = 0.15 \text{ kg}$

$$\vec{v}_{\text{avg}} = \frac{\vec{p}_{\text{future}}}{m}$$

repeat

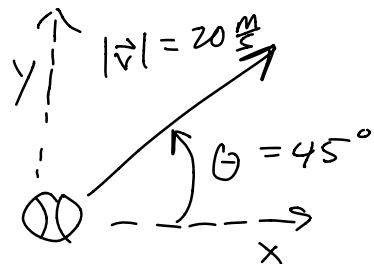




Start:

initial momentum?

$$m = 0.15 \text{ kg}$$



$$\vec{v} = 20 \frac{\text{m}}{\text{s}} \left\langle \cos \frac{\pi}{4}, \sin \frac{\pi}{4}, 0 \right\rangle$$

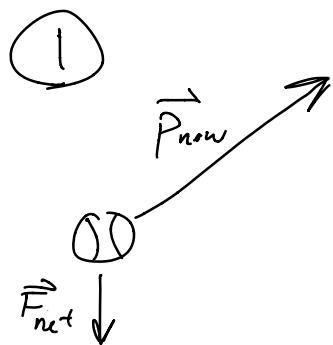
$$= 20 \frac{\text{m}}{\text{s}} (0.71, 0.71, 0)$$

$$\vec{v} = \langle 14.1, 14.1, 0 \rangle \frac{\text{m}}{\text{s}}$$

$$\vec{P}_{\text{now}} = m\vec{v} = 0.15 \text{ kg} \langle 14.1, 14.1, 0 \rangle \frac{\text{m}}{\text{s}}$$

$$\vec{P}_{\text{now}} = \langle 2.1, 2.1, 0 \rangle \frac{\text{kg m}}{\text{s}}$$

Let Δt be 0.5 s



$$|\vec{F}_g| = mg$$

direction is $-Y$
any other forces?

$$\vec{F}_{\text{net}}^{\text{now}} = \langle 0, -9.8 \times 0.15, 0 \rangle \text{ N} = \langle 0, -1.47, 0 \rangle \text{ N}$$

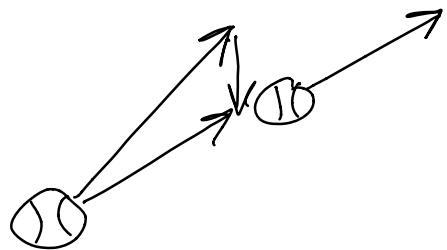
$$\begin{aligned}\vec{P}_{\text{future}} &= \vec{P}_{\text{now}} + \vec{F}_{\text{net}} \Delta t \\ &= \langle 2.1, 2.1, 0 \rangle \frac{\text{kg m}}{\text{s}} + 0.5 \langle 0, -1.47, 0 \rangle \text{ N} \cdot \text{s}\end{aligned}$$

$$\vec{P}_{\text{future}} = \langle 2.1, 1.37, 0 \rangle \frac{\text{kg m}}{\text{s}}$$

$$\vec{v}_{\text{avg}} = \frac{\vec{P}_{\text{future}}}{m} = \langle 14.1, 9.13, 0 \rangle \frac{\text{m}}{\text{s}}$$

$$\begin{aligned}\vec{r}_{\text{future}} &= \vec{r}_i + \vec{v}_{\text{avg}} \Delta t \\ &= \langle 0, 2, 0 \rangle \text{ m} + \langle 7.05, 4.57, 0 \rangle \text{ m}\end{aligned}$$

$$\vec{r}_{\text{future}} = \langle 7.05, 6.57, 0 \rangle \text{ m}$$



$$② \vec{p}_{\text{now}} = \langle 2.1, 1.37, 0 \rangle \frac{\text{kg m}}{\text{s}}$$

$$\vec{F}_{\text{net}} = \langle 0, -1.47, 0 \rangle \text{ N}$$

$$\begin{aligned}\vec{p}_{\text{future}} &= \vec{p}_{\text{now}} + \vec{F}_{\text{net}} \Delta t \\ &= \langle 2.1, 1.37, 0 \rangle \frac{\text{kg m}}{\text{s}} + \langle 0, -0.74, 0 \rangle \frac{\text{kg m}}{\text{s}}\end{aligned}$$

$$\vec{p}_{\text{future}} = \langle 2.1, 0.63, 0 \rangle \frac{\text{kg m}}{\text{s}}$$

$$\vec{v}_{\text{avg}} = \frac{\vec{p}_{\text{future}}}{m} = \langle 14.1, 4.2, 0 \rangle \frac{\text{m}}{\text{s}}$$

$$\begin{aligned}
 \vec{r}_{\text{future}} &= \vec{r}_{\text{now}} + \vec{v}_{\text{avg}} \Delta t \\
 &= (7.05, 6.57, 0) + 0.5(14.1, 4.2, 0) \\
 &= (14.1, 8.67, 0) \text{ m}
 \end{aligned}$$

We can do better.

What I want:

Given the initial conditions of the ball

$(\vec{r}_i, \vec{p}_i, m)$ and a constant

Force \vec{F}_{net} , I can tell you

- 1) where the ball is
- 2) its momentum (+ velocity)

at any time just by plugging

t into a formula

Consider:

Object starts with

\vec{p}_i , \vec{r}_i , + is subject to a
constant force \vec{F}_{net}

First look at 1 dimension:

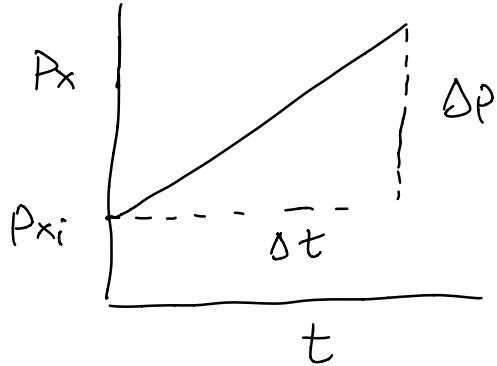
$$\vec{p}_i = p_{xi}$$

$$\vec{F}_{\text{net}} = F_x$$

$$\Delta \vec{p} = \vec{F}_{\text{net}} \Delta t$$

$$\Delta p_x = F_x \Delta t$$

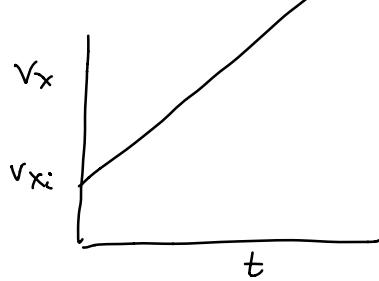
$$\frac{\Delta p_x}{\Delta t} = F_x = \text{const}$$



$$p_x(t) = p_{xi} + F_x t$$

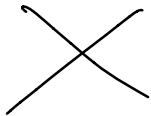
$$p_x(t) = m v_x(t)$$

$$v_x(t) = v_{xi} + \frac{F_x}{m} t$$



We can't just say that

$$x(t) = x_i + v_x \cdot t$$



Because v_x is always changing

- instead

$v_x(t)$ is instantaneous velocity

$$\vec{v} = \frac{d\vec{r}}{dt}$$

$$v_x = \frac{dx}{dt}$$

$$dx = v_x dt$$

$$dx = (v_{xi} + \frac{F_x}{m} t) dt$$

$$\int_{x_i}^x dx = \int_0^t \left(v_{xi} + \frac{F_x}{m} t \right) dt$$

$$x - x_i = v_{xi} t + \frac{1}{2} \frac{F_x}{m} t^2$$

$$x(t) = x_i + v_{xi} t + \frac{1}{2} \frac{F_x}{m} t^2$$

Another way:

$$v_{avg,x} = \frac{v_i + v_f}{2} = \frac{v_i + v_{xi} + \frac{F_x}{m} t}{2}$$

$$v_{avg,x} = \frac{2v_{xi} + \frac{F_x}{m} t}{2}$$

$$v_{avg,x} = v_{xi} + \frac{1}{2} \frac{F_x}{m} t$$

$$\vec{v}_{avg} = \frac{\Delta \vec{r}}{\Delta t}$$

$$v_{avg,x} = v_{xi} + \frac{1}{2} \frac{F_x}{m} t = \frac{x - x_i}{t}$$

$$x(t) = x_i + v_{xi}t + \frac{1}{2} \frac{F_x}{m} t^2$$

Kinematic Equations (constant F_x)

$$p_x(t) = p_i + F_x t$$

$$v_x(t) = \frac{p_i}{m} + \frac{F_x}{m} t$$

$$v_{avg}(t) = v_{xi} + \frac{1}{2} \frac{F_x}{m} t$$

$$x(t) = x_i + v_{xi}t + \frac{1}{2} \frac{F_x}{m} t^2$$

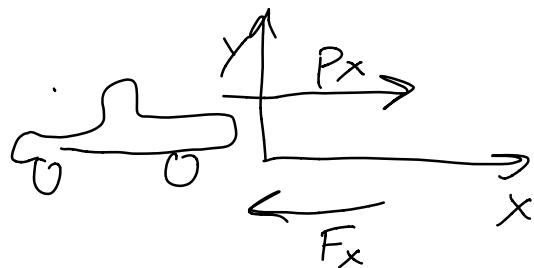
Example: mass 1200 kg
 A car driving at $30 \frac{\text{m}}{\text{s}}$ spots a pedestrian and slams the brakes, applying a constant force of 9000 N .

- How long for car to stop?
- How much distance travelled during that time?

$$P_{xi} = m V_{xi} = (1200 \text{ kg}) (30 \frac{\text{m}}{\text{s}}) = 36000 \frac{\text{kg m}}{\text{s}}$$

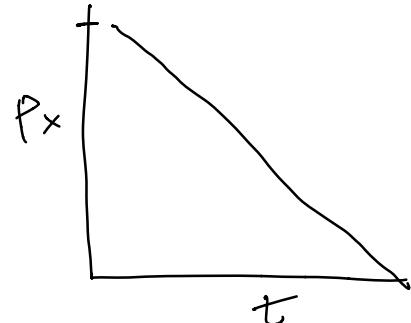
$$P_{xi} = 36000 \frac{\text{kg m}}{\text{s}}$$

$$F_{net} = ? \quad F_{net} = -9000 \text{ N}$$



$$P_x(t) = P_{xi} + F_x t$$

$$P_x(t) = 36000 - 9000t$$



Car stops when $p_x(t) = 0$

$$0 = 3600 - 900t$$

$$900t = 3600$$

$$t = 4 \text{ s}$$

$$x(t) = x_i + v_{xi}t + \frac{1}{2} \frac{F_x}{m} t^2$$

$$x_i = 0$$

$$t = 4$$

$$F_x = -900$$

$$v_{xi} = \frac{p_{xi}}{m} = 30$$

$$\begin{aligned} x(4) &= 0 + (30)(4) + \frac{1}{2} \left(\frac{-900}{1200} \right) (4)^2 \\ &= 120 + (-6) \end{aligned}$$

$$x(4) = 114 \text{ m}$$

$$\Delta x = 114 \text{ m}$$