Example: a pendulum

$$\overrightarrow{7} = \overrightarrow{7} \times \overrightarrow{F}$$

$$\hat{\Theta}_{x} = \frac{3\pi}{2} + \hat{\Theta}$$

$$\theta_{\gamma} = \pi + \theta$$

$$\vec{\Gamma} = \mathcal{L} \left( \cos(\frac{3\pi}{2} + \Theta), \cos(\pi + \Theta) \right)$$

$$\vec{F} = \langle o, -ma \rangle$$

$$\widehat{C} = \overrightarrow{r} \times \overrightarrow{F}$$

$$= \left( l \sin \theta \hat{x} - l \cos \theta \hat{y} \right) \times -mg \hat{y}$$

$$\frac{d\vec{l}}{dt} = \hat{\vec{c}}$$

$$\vec{L} = \vec{I} \vec{\omega}$$
,  $\vec{L} = \vec{L}_{cm} + m \ell^2 = m \ell^2$ 

Parallel axis thm

$$\vec{L} = ml^2 \vec{\omega}$$

$$\frac{d\vec{L}}{dt} = ml^2 \frac{d\vec{\omega}}{dt}$$

$$ml^2 \frac{d\vec{\omega}}{dt} = -mgl \sin \theta \hat{z}$$

$$\frac{d\omega}{dt} = -\frac{9}{2} \sin \theta$$

$$\omega = \frac{d\theta}{dt}$$

$$\frac{d^2\theta}{dt^2} = -\frac{3}{2} \sin\theta$$

Need a computer for this!

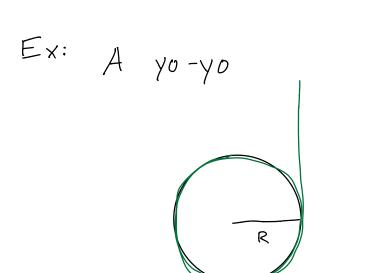
if 
$$|\Box|$$
 is very small, then  $\sin \Theta \approx \Theta$ 

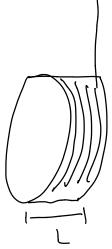
$$\frac{d^2\Theta}{dt^2} = -\frac{9}{l}\Theta$$

Compare to: 
$$\frac{d^2x}{dt^2} = -\frac{k}{m} \times \left(\frac{1}{2}\right) = A\cos\left(\sqrt{\frac{k}{m}}\right)$$

$$\Theta(t) = A \cos\left(\sqrt{\frac{9}{2}} t\right)$$

$$T = 2\pi \sqrt{\frac{\lambda}{3}}$$





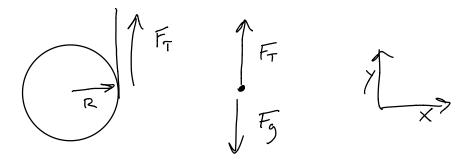
How fast is the yo-yo spinning when it is unspooled? (60 cm)

I dea:

Gravity exerts a torque on the yo-yo which increases I

Find ?

Find  $\Delta t$  (time to unspect) then  $\vec{L} = \vec{\nabla} \Delta t$  What force exerts the torque? String tension



Momentum Principle:

$$\frac{dP_Y}{dt} = F_T - F_g = F_T - mg$$

$$\frac{dp_{y}}{dt} = -ma = F_{r} - mg$$

$$F_{T} = mg - ma$$



Angular momentum principle

$$\frac{d\vec{l}}{dt} = \hat{7}$$

$$r = R \times$$

$$\overrightarrow{F} = F_{\tau}^{\Lambda}$$

$$\hat{\vec{c}} = \frac{d}{dt}\hat{\vec{c}} = \frac{d}{dt}(\vec{c})$$

$$= I d\omega 2$$

$$\frac{I}{Jt} = \frac{J}{X} = RF_{T}$$

$$F_{T} = \frac{F}{R}X$$

$$F_{\tau} = \frac{I}{R} d$$

$$P \stackrel{16}{\triangle t} = V$$
 $V = R \omega$ 

$$[\alpha = R ]$$

$$F_{\tau} = mg - ma$$

$$F_{T} = \frac{I}{R} d$$

SU:

$$F_{T} = \frac{I}{R} \left( \frac{\alpha}{R} \right) = \frac{I}{R^{2}} \alpha$$

$$F_{+} = mg - ma = \frac{I}{R^2}a$$

$$a = \frac{mgR^2}{I + mR^2}$$

$$a = g \left( \frac{1}{1 + \frac{I}{mR^2}} \right)$$

constant accel

$$\alpha \leq g$$
,  $\alpha = g$  if  $I = 0$ 

$$\frac{dL}{dt} = 7$$

$$\frac{d\omega}{dt} = C$$

$$\frac{d\omega}{dt} = \frac{C}{T}$$

$$\left(\frac{dv}{dt} = \frac{F}{m}\right)$$

$$\omega = \omega_i + \frac{\tau}{L} t \qquad \left( v = v_i + \frac{F}{m} t \right)$$

$$\Theta = \Theta_i + \omega_i t + \frac{12}{2\Gamma} t^2 \qquad \left( y = y_i + v_i t + \frac{12}{2\Gamma} t^2 \right)$$

$$\omega : = 0$$

$$RJG = Jy = > JG = \frac{Jy}{R}$$

$$\Delta G = \frac{\Delta y}{R}$$

$$C = RF_{T} = R \frac{F}{R^{2}} \alpha = \frac{\Gamma}{R} \alpha ; \quad \alpha = g \left(\frac{1}{1 + \frac{\Gamma}{mR^{2}}}\right)$$

$$\frac{\Delta y}{R} = \frac{1}{2} \frac{\alpha}{R} t^{2}$$

$$\Delta y = \frac{1}{2} a z^{2} \qquad (!)$$

$$t^2 = \frac{Z\Delta y}{a}$$

$$t = \sqrt{\frac{2ay}{a}}$$

$$\omega = \omega_i + \frac{c}{L}t$$

$$\omega = \frac{a}{R} \left(\frac{z \Delta y}{a}\right)^{\frac{1}{2}}$$

$$\omega = \left(\frac{z \Delta y}{R^2}\right)^{\frac{1}{2}}$$

$$a = g \left( \frac{1}{1 + \frac{I}{mR^2}} \right)$$

$$\omega = \sqrt{g \left(\frac{1}{1 + \frac{I}{mR^2}}\right) - \frac{2 dy}{R^2}}$$

$$T = \frac{1}{2} m R^2$$

$$\omega = \sqrt{\frac{4}{3}} \frac{9}{2} \frac{3y}{R^2}$$