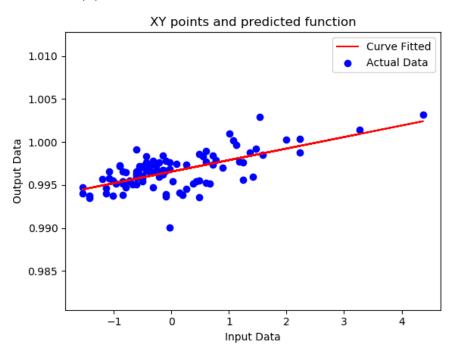
Machine Learning (COL774) Assignment #1

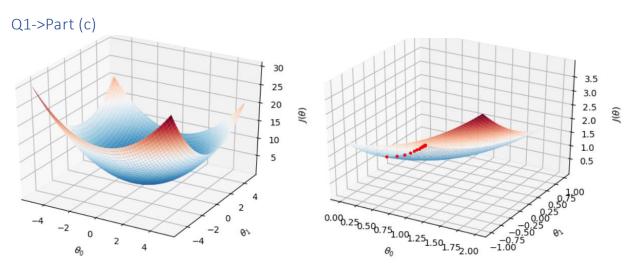
Tanu Kanvar (2018EEY7537)

Q1->Part (a)

Learning Rate = 0.003 Stopping Criteria = J0 - JPvs <= 1e-13 Theta Vector = [0.0013401936587243866, 0.9966183451740515]

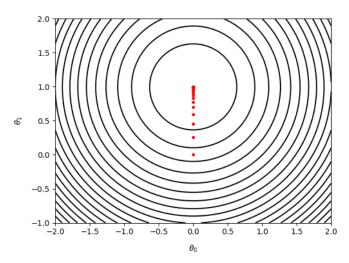
Q1->Part (b)





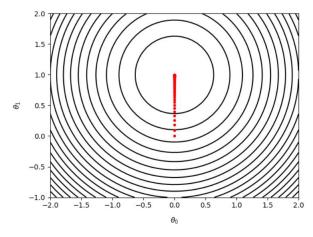
Q1->Part (d)

Contour for learning rate = 0.003

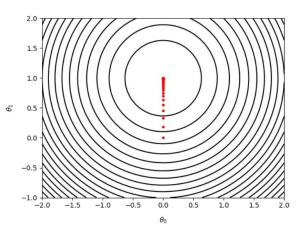


Q1->Part (e)

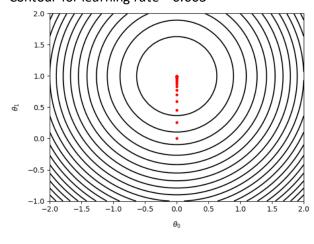
Contour for learning rate = 0.001



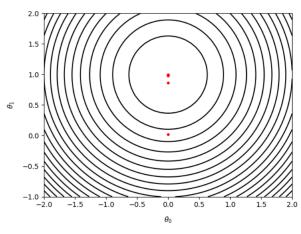
Contour for learning rate = 0.002



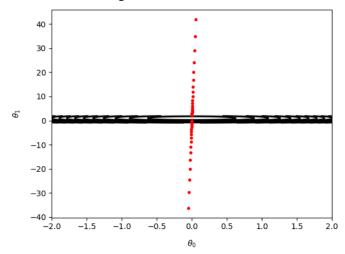
Contour for learning rate = 0.003



Contour for learning rate = 0.02



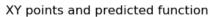
Contour for learning rate = 2.1

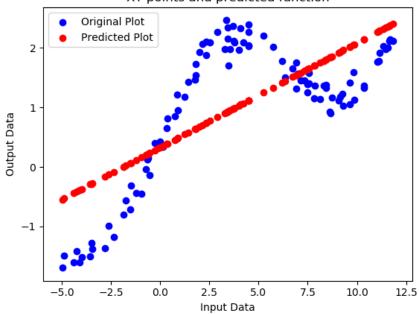


As the learning rate increases, the number of steps to converge to optimum point with minimum error decreases. After a certain value (for example in this case, learning rate above 2.1) the gradient descent starts to diverge. And thus never converges to optimum point.

Q2->Part (a)

Theta Vec = [0.10277078407327364, 1.03128116]

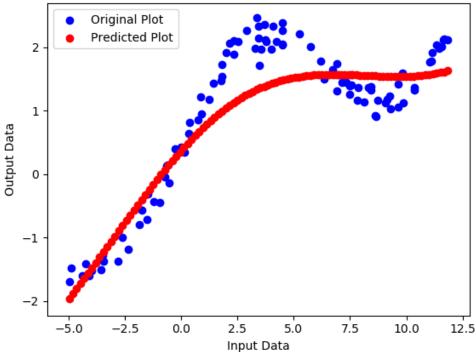


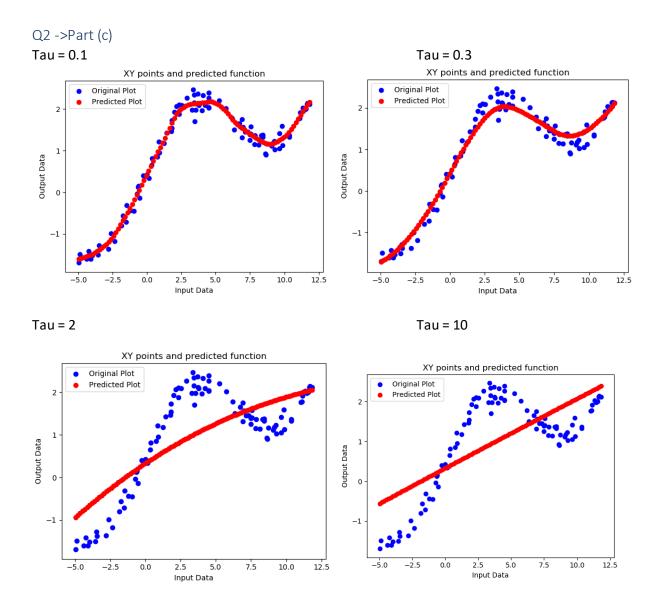


Q2->Part (b)

Tau = 0.8

XY points and predicted function





Tau = 0.3 shows the best fit.

The dependence of a point (p) on its neighboring points decreases exponentially as we go farther away from the point p.

For a point p and considering its some neighboring point q, lower the value of tau, higher will be the term $\frac{(x-x^{(i)})^2}{2\tau^2}$. Therefore lower will be $\exp{(-\frac{(x-x^{(i)})^2}{2\tau^2})}$ because of negative exponent. And the weight on point q will decrease exponentially for lower tau.

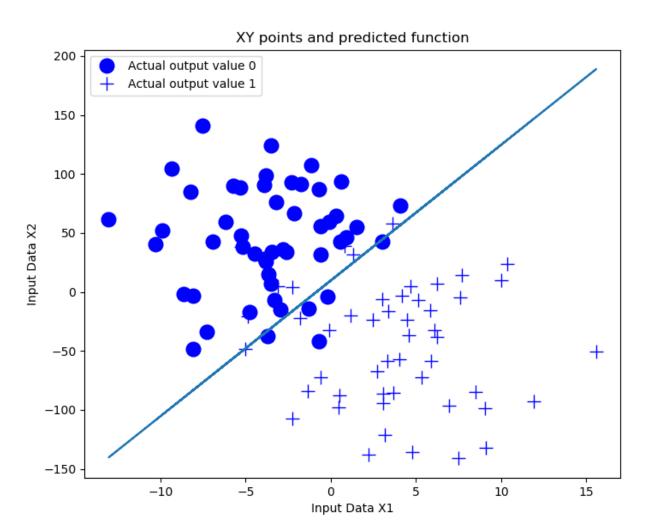
So for a given point (p), as tau decreases, the number of neighboring points considered for fitting a curve to p also decreases.

Hence very low value of tau might give wrong fit to points as not much neighboring points are considered (as can be seen for tau = 0.1 case). For very high tau, the curve fitting of a point depends on almost all points in graph and so approaches linear regression (as can be seen in tau = 10)

Q3->Part (a)

Theta Vector = [2.588547696944719, -2.7255884878403966, 0.40125316054552557]

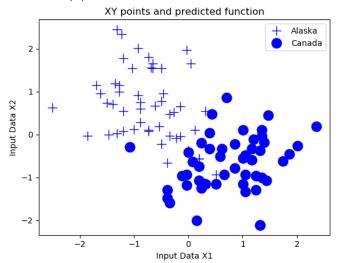
Q3->Part (b)



Q4->Part (a)

 $\begin{aligned} \text{Mu0} &= [[\ 0.75529433] \quad [-0.68509431]] \\ \text{Mu1} &= [[-0.75529433] \quad [\ 0.68509431]] \\ \text{Sigma} &= [[\ 0.42953048 \ -0.02247228] \\ \quad \quad \quad [-0.02247228 \quad 0.53064579]] \end{aligned}$

Q4->Part (b)



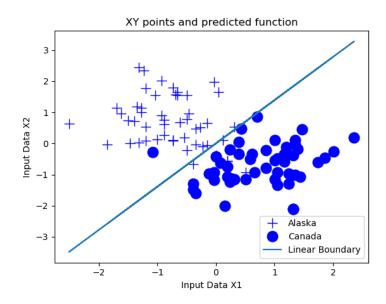
Q4->Part (c)

Linear Boundary is expressed as

$$p(\mathcal{C}_1|\mathbf{x}) = \sigma(\mathbf{w}^{\mathrm{T}}\mathbf{x} + w_0)$$

$$\mathbf{w} = \mathbf{\Sigma}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_2)$$

$$w_0 = -\frac{1}{2}\boldsymbol{\mu}_1^{\mathrm{T}}\mathbf{\Sigma}^{-1}\boldsymbol{\mu}_1 + \frac{1}{2}\boldsymbol{\mu}_2^{\mathrm{T}}\mathbf{\Sigma}^{-1}\boldsymbol{\mu}_2 + \ln\frac{p(\mathcal{C}_1)}{p(\mathcal{C}_2)}.$$



Q4->Part (d)

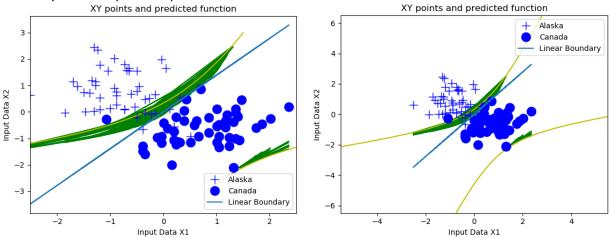
Q4->Part (e)

Quadratic Boundary is expressed as

$$\begin{split} X^TAX + BX + C &= 0 \\ Where \ A &= \Sigma_0^{-1} - \Sigma_1^{-1} \\ B &= -2 * (\ \mu_0^T \Sigma_0^{-1} - \ \mu_1^T \Sigma_1^{-1}) \\ C &= (\mu_0^T \Sigma_0^{-1} \ \mu_0 - \ \mu_1^T \Sigma_1^{-1} \ \mu_1 - 2 * \log (\ ((1/\phi) - 1) * (\ | \Sigma_1 \ | \ / \Sigma_0 \)) \end{split}$$

Green shaded = 'Quadratic Boundary using input data'
Yellow line = 'Quadratic Boundary by taking points in range'

Yellow line is to show how a boundary would look like. However the green shaded area is the actual boundary for the input data points.



Q4->Part (f)

As can be seen in the above figures, the quadratic is partitioning the data better than linear. The quadratic boundary is specifying the boundary for + and circles more accurately that linear.