

Research paper

Planning woody biomass supply in hot systems under variable chips energy content

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ARTICLE INFO

Keywords:

Biomass supply chain planning
 Forest residues
 Synchronization of chipping and transportation
 Moisture content
 Energy content
 Mathematical programming

ABSTRACT

The growing economic importance of the biomass-for-bioenergy in Europe motivates research on biomass supply chain design and planning. The temporally and geographically fragmented availability of woody biomass makes it particularly relevant to find cost-effective solutions for biomass production, storage and transportation up to the consumption facility. This paper addresses tactical decisions related with optimal allocation of wood chips from forest residues at forest sites to terminals and power plants. The emphasis is on a “hot-system” with synchronized chipping and chips transportation at the roadside. Thus, decisions related with the assignment of chippers to forest sites are also considered. We extend existing studies by considering the impact of the wood chips energy content variation in the logistics planning. This is a key issue in biomass-for-bioenergy supply chains. The higher the moisture content of wood chips, the lower its net calorific value and therefore, a larger amount of chips is needed to meet the contracted demand. We propose a Mixed Integer Programming (MIP) model to solve this problem to optimality. Results of applying the model in a biomass supply chain case in Finland are presented. Results suggest that a 20% improvement in the supplier profit can be obtained with the proposed approach when compared with a baseline situation that relies on empirical estimates for a fixed and known moisture content in the end of an obliged storage age.

1. Introduction

Design and planning of biomass-for-energy supply chains (BESC) has been widely studied, as society reinforces the major role of biomass as a global primary energy source. In the case of woody biomass (produced from branches and other by-products of forestry operations), as in other forms of biomass (e.g. residues from agriculture, forestry, fisheries and municipal waste), the availability is temporally and geographically fragmented, which makes it particularly relevant to find cost-effective solutions for biomass production, storage and transportation up to the consumption facility (e.g. Ref. [17]).

In this paper, the company in focus is a biomass supplier that buys the forest residues from forest owners (suppliers) and delivers the wood chips to power plants (customers) in order to meet their contracted demand of energy content, expressed in terms of MWh. The sequence of operations that are responsibility of the company are: 1) Logging, ie., tree felling, delimiting the trunk and cross-cutting into pre-defined lengths with specialized harvesters or manual harvesting with chain-saws; 2) Forwarding the logs and residues with skidders, forwarders or other types of tractors from the logging site up to pre-defined stacking

locations at the roadside; 3) Chipping forest residues into smaller size wood chips, with specialized chippers located at the roadside or in terminals for longer term storage; 4) Transporting forest residues or wood chips by truck from the forest sites; and finally 5) Temporary storing and drying the residues and/or chips at the roadside or in terminals. Drying usually occurs under favorable sun and wind open-air conditions, but technical drying systems can be used in terminals, with addition of heat and with forced ventilation in order to reach much lower moisture content levels.

This research focus on planning chipping, transportation and storage operations, especially during the heating season when the power plants are operating. The emphasis is on “hot systems” where wood chipping and transportation operations are synchronized at the roadside. In this case, the trailer-mounted chipper feeds directly a chargeable container mounted in the truck, which will transport the chips ultimately to the plants. The company main decisions with respect to chipping are: 1) *when and where to produce the wood chips, to match wood chips availability and plants demand*; 2) *which chipper to assign to forest residues piles at the forest site*. Main decisions with respect to transportation are: 1) *amounts from where, to where, when, what product (flows)*;

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2) transportation capacity needed in each period. In respect to storage, the company main decision is: 3) how long to store/dry forest residues/wood chips and where (roadside or terminals)? It is noteworthy that, in case of hot systems, there is no intermediate storage of wood chips between these operations, but there is usually storage of forest residues at the logging sites because chipping is done some time after harvesting. Contrarily, the “cold system” encompasses the transport of forest residues to the terminals for later chipping and storage (e.g. Ref. [11]).

The literature shows several examples of mathematical programming techniques to help plan chipping and transportation operations with the aim to minimize the cost per kWh generated (e.g. Refs. [4,6,30]). Previous research from Ref. [19] addressed the case of a large Swedish biomass-supplying entrepreneur. They developed a model to decide when and where forest residues have to be converted into chips, transported and stored in order to satisfy the contracted demand at the sawmill at a minimum cost. They assume that harvesting (and chipping) in each stand occurs in a single period and do not address the assignment of machinery to these operations. Continuous variables determine biomass flows from harvest sites and sawmills to heating plants in each time period and binary variables determine whether forest residues are forwarded or chipped, whether a sawmill has been contracted and a terminal is used in a certain time period (one month) over a planning horizon of one year. The problem was solved with a heuristic approach and applied in six scenarios of possible variations in the supply chain design. In a similar context [14], apply a MIP model to the optimization of inventory planning at the terminals in order to support the choice of chipping technology and location and the route to the heating plants. The model was implemented in a Decision Support Tool called FuelOpt. [23] and [18] also studied the biomass supply in case studies in Austria. The former proposed a Linear Programming model while the latter applies a simple stepwise heuristic approach based on the calculation of available regional forest fuel potential.

Despite these relevant efforts, the dependency between chipping and transportation operations that characterize “hot systems” is still poorly addressed. Previous research (e.g. Refs. [11,12,24]) develop simulation-based approaches to assess productivity issues related with alternative chipping systems as well as to show the importance of balancing chipping and transportation capacity to avoid unnecessary costs related with the trucks waiting time and chippers idle time. In a case similar to this [3], proposes a discrete-event simulation model to find optimal set-ups for the supply chain of crushed material, made from stumps at different road transport distances. Yet, optimization models for jointly planning chipping and transportation remain undone.

Moreover, the impact of wood chips moisture in storage and logistics planning is not yet properly addressed, although it is a key aspect of the business. Usually companies use the chips with lower moisture content as possible, because this corresponds to a higher energy content, meaning that less energy is spent to vapor the water in the wood instead of heating. Moisture content also affects negatively the efficiency of combustion (higher emissions of carbon monoxide, hydrocarbon and fine particles), increases the risk of decay during storage, and increases the transportation costs [27]. Chips moisture content is higher just after harvesting and tends to decrease along the time spent in storage (e.g. Refs. [20,21,28]). Yet, the drying rate depends on the initial moisture content, the weather conditions (specially sun and wind) during the drying period, the drying capacity of the wood, phytosanitary conditions, pile cover type and arrangement, and other features of the storage yard (e.g. dimension, soil drainage capacity) [27].

One of the few studies addressing the impact of moisture content variation in logistics planning was done by Ref. [8]. They apply a simulation model built with a state-task-network approach. Another study by Ref. [31] proposes a ‘stochastic programming-robust optimization’ model to tackle biomass supply planning, addressing uncertainty in biomass quality and biomass availability. [16] quantifies

the impact of incorporating terminals between harvest locations and biorefineries. In this analysis, the decrease in moisture content is one of the considered factors for evaluating the potential benefits of intermediate storage locations. Nevertheless, most planning models for biomass supply fail to effectively capture the impact of the changes in the product properties according to storage time, and do not incorporate the storage age into the model.

The main contributions of this paper are to formulate and solve the tactical biomass supply planning problem, thus extending the work of [14,19] by explicitly considering the variation in chips energy content (or moisture content) over time in storage. Furthermore, it addresses the dependency between chipping and transportation at the roadside that characterize the “hot systems” as well as the space-time continuity of chipping operations.

The remainder of this paper is as follows. Chapter 2 presents the problem description, with emphasis on identifying the impact of the variation of the wood chips energy content in the logistics planning as well as explaining the dependencies between chipping and transportation operations that characterize the hot systems. Chapter 3 presents the proposed modelling approach. It further discusses possible variations to the general Mixed-Integer Programming model for cases where the storage age is not dealt with or the movements of the chippers between piles can be simplified. Chapter 4 presents the computational experiments for a case study of a biomass supply company in Finland. Finally, chapter 5 presents the concluding remarks.

2. Problem description

The woody biomass supply planning problem in hot systems under variable chips energy content can be formulated as follows. Considering a set of power plants (M) with a given demand of energy content (MWh) per week, the problem consists in determine 1) which piles (P) of forest residues should be chipped according to its availability and moisture content; 2) by which chippers (K), and 3) where to transport the chips, considering the possibility to use forest sites and terminals (O) for temporary storage (Fig. 1). The objective is to maximize the operational net profit, considering the revenue from wood chips sales to the plants as well as the costs of chipping, transportation and storage. This is a multi-period flow problem, where the planning periods be half-a-day, one day or even week, and the planning horizon can range from 1 to up to 6 months, the latter corresponding to the expected duration of the heating season, when the power plants are operating.

2.1. Incorporating wood chips energy content variation in logistics planning

The energy demand at the power plants is specified in MWh. This corresponds to the minimum supply during the entire cold season, when the plant is operating, while the maximum supply can be approximated by the plants processing capacity. The price per MWh vary from plant to plant and the supplier was no control over pricing, which is assumed to be fixed within the planning horizon. Depending on the

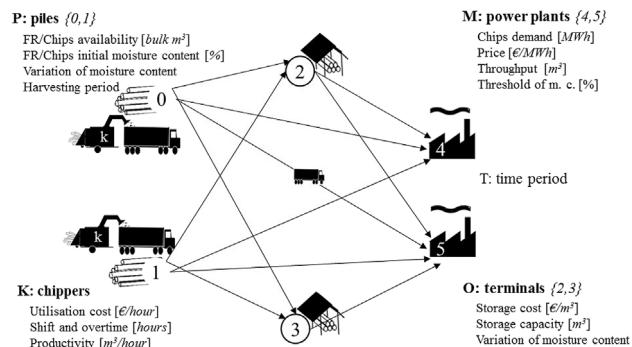


Fig. 1. Graphical representation of the biomass supply planning problem.

type of boilers installed, some plants also define thresholds in respect to the minimum energy content accepted. But in general, the larger the plant the more tolerant it is to variations in the fuel properties.

Forest residues and wood chips availability is specified in bulk m³. This is the unit of measurement for small pieces of loose wood (e.g. wood chips, sawdust, wood pieces) that attain a total volume of one cubic meter including air gaps [25]. 1 bulk m³ wood chips corresponds to 0.33 m³ round wood equivalent. The piles of forest residues become available at the roadside since the period when harvesting occurred, which is known beforehand. Also the amount of forest residues available in each pile is known and is usually estimated as a percentage of the total stand volume, which can be predicted with yield and growth models based on forest inventory data.

The conversion MWh to m³ is the wood chips energy content or its net calorific value or net heating value (ε). It corresponds to the usable heating volume released in complete burning of a specific volume of fuel, after subtracting the heat of vaporization of the water vapor (2.44 MJ per kg of water). It is computed mainly as a function of the moisture content (ϑ) (Equation (1)); other parameters are the net calorific value of oven-dry wood (ε_0) (18.5 MJ/kg) and bulk density (ρ) (kg/bulk m³), whose values for the main tree species and moisture content can be found in the Wood Fuels Handbook [25]:

$$\varepsilon = \left(\frac{\varepsilon_0(100 - \vartheta) - 2.44\vartheta}{100} \right) 0.278 \cdot \rho \text{ (KWh/m}^3\text{)} \quad (1)$$

Consequently, the wood chips moisture content is the key parameter for the business. The higher the moisture content the higher the volume necessary to meet the demand. Thus, it is measured often in the course of biomass supply processes with portable measuring devices. The wood moisture content (or water content, or moisture content percentage on green basis (ϑ)) is the mass of water present in relation to the mass of fresh wood. $\vartheta = \frac{W_w - W_0}{W_w} \times 100$, where W_w is the wet weight of wood and W_0 is the oven-dry weight of wood. Note that some portable devices may measure the wood humidity (or moisture content on oven-dry basis (ϑ)), corresponding to the ratio between the mass of water present and the mass of oven-dry wood. In those situations the following conversion formula can be used $\vartheta = \frac{100\theta}{100 + \theta}$. As rules of thumb in the literature (e.g. Ref. [25]), newly-chopped fresh wood has half of water and half of wood substance ($\theta = 100\%$, $\vartheta = 50\%$). Fresh wood chips have ϑ between 45% and 55%. After drying for a couple of months under favorable open air conditions it lowers to 25–40%, while in case of technical drying can reach below 20%. [27] and [15]. According to [25], the net calorific value of wood chips is around 3.4 KWh/kg (or MWh/ton).

The variation of moisture content of forest residues/wood chips along the time spent in open-air drying at the forest sites or terminals can be estimated by means of local field tests, drying curves or mathematical models or even other alternative empirical approaches. Experimental field tests help to determine the key factors impacting in the drying process (e.g. Refs. [5,28,29]). As an example [20], concluded that the key impacting factors in spruce piles (forest residues and wood chips) in Central European conditions are season, storage duration, assortment and fleece cover. In winter period (November to April), wood chips moisture content varied from 56% to 53% (average of 0,15% per week), while in summer (May to October) varied from 48% to 34% (average of 0,7% per week). Forest residues dried faster than chips. Piles covered with fleece also dried much faster due to heat accumulation and lower heat dissipation.

Graphical drying curves help to predict the expected moisture content along the time spent drying under case-specific conditions (e.g. Ref. [26]). As an example [21], proposed drying curves for spruce and beech piles in central European conditions, starting in the winter season. The maximum moisture content is reached in the beginning of the storage period and then decreases during the year until reaching the minimum moisture in summer. After this period, the wood moisture

content may increase again due to rain and increased air humidity. Existing mathematical models usually predict change in moisture content as a function of mean air temperature and relative moisture. Still other studies propose more general mathematical models that predict moisture content change as a function of mean air temperature and relative moisture (e.g. Refs. [10,32]).

This research considers all these methods equally valid and can be adopted by the biomass company for the purpose of biomass supply planning at the tactical level. If fact, this research is built under two main assumptions: 1) Existing stock (and moisture content) at the beginning of the planning period is known; 2) The variation of moisture content along the time spent in storage is also known in advance for each storage location (piles and terminals), by means of local field tests, drying curves or mathematical models or even other alternative empirical approaches.

In cases where no mathematical model is available, a generic logistic function can be used (see Equation (2)) where $\alpha > 0$ is a parameter that defines the sigmoid curve's steepness, π sets the sigmoid curve's midpoint in the t axis, ϑ_0 is the initially measured wood moisture content and ϑ_{eq} is the curve's horizontal lower asymptote and may be estimated by the lowest moisture content measured in a one-year period. As an example, for the spruce piles stored in Freising, Germany during 2 consecutive years (Dec. 2002 to Nov. 2004) presented in Ref. [21], $\alpha = 0.9$ and $\pi = 4.6$.

$$\vartheta(t) = \vartheta_{eq} + \frac{\vartheta_0 - \vartheta_{eq}}{1 + e^{\alpha(t-\pi)}} \quad (2)$$

2.2. Addressing the dependency between chipping and transport at the roadside (hot system) in biomass supply planning

Chipping and transportation operations have a start-to-start dependency, meaning that both need to be present and available at the roadside so that both operations can be performed. Similarly, there is a finish-to-finish dependency. This is because forest residues are chipped directly into the trucks' container and transported just after the container is full (i.e. in the same period). Consequently, biomass supply planning should seek for an optimal balance between productivity/capacity of chippers and trucks, in order to avoid unnecessary costs related with the trucks waiting time and chippers idle time.

There are other relevant business rules related with chipping that need to be taken into account for biomass supply planning. The first is that the chipper processes one pile at a time. The chipper productivity in terms of m³/hour depends on the type of chipper and the pile characteristics (e.g. size of the wood fuels) [25]. Low power chippers (engine ~50 kW), usually installed on the rear three point hitch of a tractor or on a trailer, only processing small diameters (up to 20 cm) and chipping productivity below 10 bulk m³ of wood chips per hour; medium power chippers (engine 50–110 kW), usually trailer-mounted, can chip diameters up to 30 cm and the chipping productivity is up to 50 bulk m³ of wood chips per hour; high power chippers (engine > 110 kW) installed in trailers or trucks, can chip large diameters (> 30 cm) and produce more than 100 bulk m³ of wood chips per hour. Once chipping starts (and a truck is available) the productivity is assumed constant for that chipper in that pile. There is a daily cost of having a chipper assigned to a pile and a hourly utilization cost, that varies according to the type of equipment and ownership but it is the same either it is working or paused because no truck is available for loading. Hourly costs are higher when chipping occurs beyond the number of working hours of a regular shift. It is not mandatory that all piles are chipped within the time horizon.

Other important aspects that condition the assignment of chippers to piles are here called **space-time continuity constraints**. Temporal continuity means that the chipper remains in a pile until all the material is transported. Consequently, chipping may extend over several consecutive time periods. This is the same as saying that chipping

operations cannot be interrupted once started, known in the production scheduling literature as a non-preemptive requirement (e.g Ref. [22]). Spatial continuity relates to the fact that for trailer-mounted chippers, there is a second type of truck needed to move the chipper to and from the pile, with extra operational costs. Consequently, chippers should be moved to a nearby pile to avoiding unnecessary chipper's transportation costs (and unproductive time).

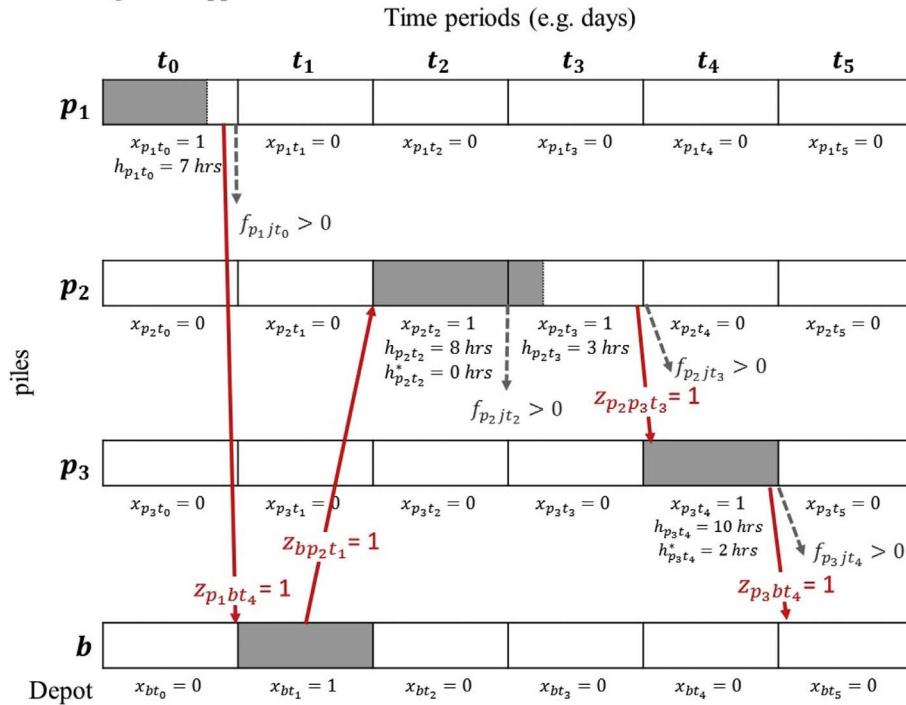
In respect to transportation, this research assumes that there is an homogenous fleet of available trucks, with a coupled trailer with sidewalls or container. The loading capacity of each truck is around 87 bulk m³ (21ton). Trucks' usage cost also varies with ownership. The supplier preferably uses their own chipper and trucks. If the company does not have enough chippers and/or trucks to comply with the power plants' energy demands, then the company is able to subcontract chippers.

3. Problem modelling

The proposed modelling approach for the biomass supply chain problem builds on the MIP model developed by Ref. [19] and extends it according to the problem description. The assignment variables are extended to address hot systems. x_{kpt} take value 1 if chipping and transportation operations will occur in pile p in period t by chipper k , and 0 otherwise. As in Ref. [19], continuous variables represent the biomass flows. The linking constraints between the assignment variables and the flow variables assure that flow only exists if and when the operations are performed, therefore implementing the dependency between chipping and transportation that characterize the hot systems.

New auxiliary binary variables are added for modelling chipping movements. $z_{kp_1p_2t}$ take value 1 if there is movement of chipper k from p_1 to p_2 in the end of period t . In respect to spatial continuity, a feasible movement of the chipper between piles p_1 and p_2 requires that $z_{kp_1p_2(t-1)}$ take value 1 if $x_{p_1t_{(t-1)}} = 1$ and $x_{p_2t} = 1$. Therefore, $z_{kp_1p_2(t-1)} \geq x_{kp_1t_{(t-1)}} + x_{kp_2t} - 1$. For each pile p_1 it can happen at most once along the entire planning period ($\sum_u \sum_{p_2} z_{p_1p_2t} \leq 1, \forall p_1$). To assure flow connectivity, it is necessary a new set of constraints that

For a given chipper k :



balance the inflows and the outflows for each pile-time period, as explained in 3.2. In respect to temporal continuity, the previous constraints are sufficient to force the chipper to remain in pile p_1 in consecutive periods whenever needed, because 1) the chipper either continues in that pile p_1 or moves to another pile p_2 : ($p_2 \in P \cup \{depot\}; p_2 \neq p_1\}$; 2) can only move from p_1 to another pile p_2 once i.e. cannot come back to p_1 to complete the task and them move again from p_1 with minimum costs (see Fig. 2).

New continuous decision variables account for machinery/crew total number of working hours, including the shift duration and the overtime work, i.e. beyond the regular working shift duration. There variables are instrumental for dealing with the pool of chippers with heterogeneous productivity in terms of m³/hour. Additional continuous variables h_{kpt}^* account for the amount of overtime chipping work. In cases where there is still some minor amounts left to chip in the end of a working shift in t , these variables are instrumental for modelling the trade-off between concluding chipping in that period t with additional overtime costs or delaying operations to $t+1$ with additional costs related with the chipper daily utilization (see Fig. 2).

The continuous variables representing biomass flows and stock need to be adapted to take into account the variation of moisture content according to the storage age. Previous work in logistics planning dealing with perishability in food goods (e.g. Ref. [2]) use decision variables $w_{u,t}^e$ to define the initial inventory of product u , with age e available at period t , $a=0, \dots, \min\{a_u - 1; t - 1\}$, where a_u is the shelf-life duration of product u , right after being produced. The inventory balance constraints account for the spoilage rate for each product. This research proposes a similar modelling approach that considers a set of moisture content classes ($e \in E$). A set of continuous variables $f_{ijet_1t_2}$ represent the amount of wood chips with moisture content class e transported from supply point $i \in I$ to demand point $j \in J$ in period $t_2 \in T$, that arrived to i in period $t_1 \in T^o: \{t|t \in T, t < t_2\}$ (m³). The period between t_1 and t_2 corresponds to the storing age. Similarly, variables $s_{oet_1t_2}$ are the amount of wood chips with moisture class e stored in supply point $o \in O$ in period t_2 that arrived in period t_1 .

Fig. 2. Generic representation of an admissible solution for one chipper k 3 piles $\{p_1, p_2, p_3\}$, 5 time periods $\{t_1, \dots, t_5\}$ in respect to decision variables x_{kpt} , h_{kpt} , h_{kpt}^* , $z_{kp_1p_2t}$ and f_{pjt} . For simplification purposes, the index k was omitted in the figure.

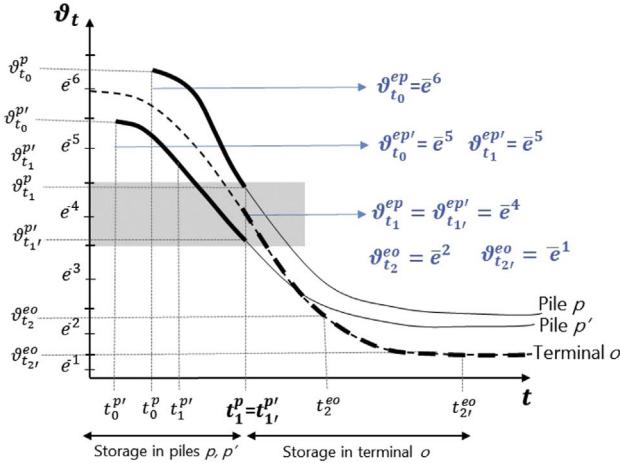


Fig. 3. Residues/wood chips drying process in the roadside pile and at the terminal. Where: \bar{e}^e : Average moisture content of class e ; ϑ_t^p , $\vartheta_t^{p'}$, ϑ_t^o : Moisture content period t of residues/chips located at the roadside pile p , p' or terminal o , respectively; t_0^p , $t_0^{p'}$: Time period since which the roadside piles p and p' are available, respectively; t_1^p , $t_1^{p'}$, t_1^o : Time periods when residues/chips are transported from the piles p or p' ; t_2^{eo} , t_2^{eo} : Time periods when chips that arrived to terminal o with initial moisture content e are transported from terminal o (to plant).

3.1. Procedure for calculating moisture content variation

In this framework, a procedure is needed to compute the variation of moisture content in forest residues/chips during the time in storage (at roadside piles and/or terminals), which can be generically represented with a drying curve (Fig. 3).

Concerning storage in a roadside pile, for a given pile p the time spent in storage corresponds to $t_1^p - t_0^p$, where t_1^p is time period when residues/chips are transported from the pile to the terminal or to the plant; and t_0^p is the time period since which the pile p is available (i.e., forest harvesting operations are concluded). The initial moisture content $\vartheta_{t_0}^p$ is measured in t_0^p with an appropriate device (Assumption 1). The moisture content $\vartheta_{t_1}^p$ is estimated with the drying curve/mathematical model, which is assumed to be known (Assumption 2), as discussed in section 2.1. It is noteworthy that there can be multiple outflows from the same pile in different time periods (and for different destinations), generically represented in Fig. 3 as t_1^p , $t_1^{p'}$.

In period t_1^p , the residues/chips transportation costs (€/m³) depend on unit transportation cost τ^I (€/ton/km), distance (km) and the bulk density ρ^e (kg/bulk m³) (Equation (4)). The latter varies with the moisture content. The price of chips at the plant (€/MWh) also depends on its net calorific value ε^e (MWh/m³), which is calculated as a function of the moisture content (Equation (1)). Therefore, $\vartheta_{t_1}^p$ will take the average value of the corresponding class e , i.e. $\vartheta_{t_1}^{ep} = \bar{e}^e$. For implementation purposes, this can be generically represented by $\vartheta_t^p = \sum_{e \in E} \beta_{pet} \bar{e}^e$, where auxiliary binary parameters β_{pet} take the value 1 when the moisture content class $e \in E$ is applied to $p \in P$ in period $t \in T$, and 0 otherwise. These parameters are pre-processed before running the model, for all possible combinations of (p, e, t) and $\sum_{e \in E} \beta_{pet} = 1, \forall p, \forall e, \forall t$.

$$\tau_{ij} = \tau^I d_{ij} \rho^e, \forall i \in I, \forall j \in J \quad (4)$$

Concerning storage in the terminal, the procedure handles batches of biomass that arrive to that terminal in the same period and belonging, in that period, to the same moisture content class, disregarding the pile of origin. This means that if the chips coming from roadside piles p and p' arrive to the same terminal in the same period and with the same moisture content class, thereafter are considered a single batch. The terminal is empty in the beginning of the planning horizon. The moisture content at the beginning of the storage time in the terminal is the same as of the departure from the pile $\vartheta_{t_1}^{ep}$, while the

moisture at the time of departure from the terminal ($\vartheta_{t_2}^{eo}$) is estimated with the drying curve/mathematical model specific for that terminal, which is also assumed to be known (Assumption 2). The same approach for modelling the drying process in piles applies to terminals. The terminal may have several drying curves for distinct initial moisture content classes, and according to the season when storage began (e.g. summer or winter). Notice that there can be multiple outflows from the same batch in different time periods (and for different plants), generically represented in Fig. 3 as t_2^{eo} , t_3^{eo} .

Variables $s_{oet_1 t_2}$ will deal with the stock balancing. Whenever the outflows occur, the current moisture class e for that period is determined, and it may be the same or lower than the one at the moment of arrival to the terminal. For example, in Fig. 3, moisture class decreased from \bar{e}^4 in t_1 , to \bar{e}^2 , \bar{e}^1 in t_2 , t_3 respectively. Transportation costs and prices for the chips coming from the terminal are calculated based on current class e , as described before. For modelling and implementation purposes, a new auxiliary parameter is used to account for the transitions between the moisture content classes for any $(t_2 - t_1)$. The parameter $\eta_{e_1 e_2 t_1 t_2}^o$ takes value 1, if chips arriving in terminal $o \in O$ with energy content scale $e_1 \in E$ in period $t_1 \in T^o = \{t | t \in T, t < t_2\}$, are expected to be in energy content scale $e_2 \in E$ in period $t_2 \in T$; 0, otherwise. The values are obtained from the drying curve/model during the model preprocessing phase, for all possible combinations of (o, e, t_1) and $\sum_{e_2 \in E} \eta_{e_1 e_2 t_1 t_2}^o = 1, \forall o, \forall e_1, \forall t_1$.

3.2. Mixed Integer Programming model

The formulation of the MIP model is as follows:
Sets

T	Set of planning periods, $T = \{0, \dots, T - 1\}$
P	Set of piles of raw material at the roadside
P^b	Set of piles of raw material at the roadside, including the depot $P^b = P \cup \{b\}$
M	Set of power plants (mills)
O	Set of terminals (intermediate stockyards)
I	Set of supply points, $I = P \cup O$
J	Set of demand points, $J = M \cup O$
K	Set of chipping machines/crews
E	Set of classes of wood chips moisture content

Parameters

a_p	Availability of wood chips in pile $p \in P$ (m ³)
d_m	Demand of energy content from wood chips at plant $m \in M$ (MWh) for the entire planning period
c_m^M	Maximum throughput of wood chips at plant $m \in M$ (MWh)
c_o^O	Storage capacity in terminal $o \in O$ (m ³)
c^V	Transportation capacity of each truck (10 ³ kg)
c_k^K	Unit cost of using chipper k (€)
N	Number of available trucks
r_k	Productivity of chipper $k \in K$ in pile $p \in P$ (m ³ /h)
$y_k^m; y_k^*$	Minimum, regular and max. extra-hours working time of chipper/crew $k \in K$ (h)
$\omega_{kp}; \omega_{kp}^*$	Standard and Overtime hourly chipping cost of using chipper $k \in K$ in pile $p \in P$ (€/h)
γ_o	Unit storage cost of wood chips per period at terminal $o \in O$ (€/m ³)
τ	Unit wood chips' transportation cost (€/ton/km)
χ_k	Unit transportation cost of chipper k (€/km)
d_{ij}	Distance between the point of origin i (pile or terminal) and the point of destination j (km)

θ_t^p	Moisture content of residues/chips in pile $p \in P$ (%) in the period t
t_0^p	Time period since which pile/depot $p \in P^b$ is available to be chipped
ρ_e	Bulk density of wood chips in energy class e (10^3 kg/m 3)
ε_e	Energy content per volume unit of wood chips in energy class e (MWh/m 3)
φ_{em}	Price paid energy content unit delivered to plant $m \in M$ (€/MWh)
β_{pet}	Auxiliary parameter that takes value 1 when the moisture content class $e \in E$ is applied to $p \in P$ in period $t \in T$; 0 otherwise ($\sum_{e \in E} \beta_{pet} = 1$, $\forall p, \forall e, \forall t$).
$\eta_{e_1 e_2 t_1 t_2}^o$	Auxiliary parameter that takes value 1, if chips arriving in terminal $o \in O$ with energy content scale $e_1 \in E$ in period $t_1 \in T^\emptyset = \{t t \in T, t < t_2\}$, are expected to be in energy content scale $e_2 \in E$ in period $t_2 \in T$; 0, otherwise ($\sum_{e_2 \in E} \eta_{e_1 e_2 t_1 t_2}^o = 1$, $\forall o, (e_1, t_1), t_2$)

Decision variables

x_{kpt}	1, if chipping-transportation occur in pile $p \in P^b$ in period $t \in T$, with chipper $k \in K$; 0, otherwise
f_{jet1t_2}	Amount of wood chips with energy content e transported from supply point $i \in I$ to demand point $j \in J$ in period $t_2 \in T$ that arrived in period $t_1 \in T^\emptyset = \{t t \in T, t < t_2\}$ (m3)
s_{oet1t_2}	Amount of wood chips stored at terminal $o \in O$ with energy content scale $e \in E$ in period $t_2 \in T$ that arrived in period $t_1 \in T^\emptyset = \{t t \in T, t < t_2\}$ (m3)
h_{kpt}	Number of total hours used by machine/crew $k \in K$ in pile $p \in P$ in period $t \in T$ (h)
h_{kpt}^*	Number of overtime hours used by machine/crew $k \in K$ in pile $p \in P$ in period $t \in T$ (h)
$z_{kp_1 p_2 t}$	1, if chipper $k \in K$ moves from pile $p_1 \in P^b$ to $p_2 \in P^b$ at the end of period $t \in T$; 0, otherwise

Model [M1]

$$\begin{aligned} \max F = & \sum_{i \in I} \sum_{m \in M} \sum_{e \in E} \sum_{t_2 \in T} \sum_{t_1 \in T^\emptyset} \varphi_{em} \varepsilon_e f_{imet1t_2} - \sum_{k \in K} \sum_{p \in P} \sum_{t \in T} C_k^K x_{kpt} \\ & - \sum_{k \in K} \sum_{p \in P} \sum_{t \in T} [\omega_{kp} (h_{kpt} - h_{kpt}^*) + \omega_{kp}^* h_{kpt}^*] \\ & - \sum_{i \in I} \sum_{j \in J} \sum_{e \in E} \sum_{t_1 \in T^\emptyset} \sum_{t_2 \in T} \tau d_{ij} \rho_e f_{jet1t_2} \\ & - \sum_{k \in K} \sum_{p_1 \in P^b} \sum_{p_2 \in P^b} \sum_{t \in T} \chi_k d_{p_1 p_2} z_{kp_1 p_2 t} \\ & - \sum_{o \in O} \sum_{e \in E} \sum_{t_1 \in T^\emptyset} \sum_{t_2 \in T} \gamma_o s_{oet1t_2} \end{aligned} \quad (5)$$

Subject to:

$$d_m \leq \sum_{i \in I} \sum_{e \in E} \sum_{t_1 \in T^\emptyset} \sum_{t_2 \in T} \varepsilon_e f_{imet1t_2} \leq C_m^M \quad \forall m \in M \quad (6)$$

$$\sum_{e \in E} \sum_{t_1 \in T^\emptyset} \sum_{t_2 \in T} f_{jet1t_2} \leq a_p \quad \forall p \in P \quad (7)$$

$$x_{kpt} y_k^m \leq h_{kpt} \leq (y_k + y_k^*) x_{kpt} \quad \forall k \in K, \forall p \in P, \forall t \in T \quad (8)$$

$$h_{kpt} - y_k \leq h_{kpt}^* \leq y_k^* \quad \forall k \in K, \forall p \in P, \forall t \in T \quad (9)$$

$$\sum_{k \in K} h_{kpt} \cdot r_{kp} = \sum_{j \in J} \sum_{e \in E} \sum_{t_1 \in T^\emptyset} f_{jet1t_2} \quad \forall p \in P, \forall t_2 \in T \quad (10)$$

$$s_{oet2t_2} = \sum_{p \in P} \sum_{t_1 \in T^\emptyset} f_{poet1t_2} \quad \forall o \in O, \forall e \in E, \forall t_2 \in T \quad (11)$$

$$\begin{aligned} s_{oet1t_2} &= s_{oet1(t_2-1)} \\ &- \sum_{m \in M} \sum_{e' \in E} \eta_{oe'e't_1t_2} f_{ome't_1t_2} \quad \forall o \in O, \forall e \in E \\ &\forall t_1 \in \{t | t \in T, t_1 < t_2\}, \forall t_2 \in T \end{aligned} \quad (12)$$

$$\sum_{e \in E} \sum_{t_1 \in T^\emptyset} s_{oet1t_2} \leq c_o^O \quad \forall o \in O, \forall t_2 \in T \quad (13)$$

$$\sum_{i \in I} \sum_{j \in J} \sum_{e \in E} \sum_{t_1 \in T^\emptyset} \rho_e f_{jet1t_1} \leq c^V N \quad \forall t \in T \quad (14)$$

$$\sum_{p \in P^b} x_{kpt} = 1 \quad \forall k \in K, \forall t \in T \quad (15)$$

$$z_{kp_1 p_2 (t-1)} \geq x_{kp_1 (t-1)} + x_{kp_2 t} - 1 \quad \forall k \in K, \forall p_1, p_2 \in P^b: p_1 \neq p_2, \forall t \in T \setminus \{0\} \quad (16)$$

$$z_{kp_1 b (t-1)} \geq x_{kp_1 (t-1)} \quad \forall k \in K, \forall p_1 \in P, t = |T| \quad (17)$$

$$x_{kp_1 t} + \sum_{p_2 \in P^b} z_{kp_2 p_1 t} = x_{kp_1 (t+1)} + \sum_{p_2 \in P^b} z_{kp_1 p_2 t} \quad \forall k \in K, \forall p_1 \in P, \forall t \in T \quad (18)$$

$$\sum_{k \in K} \sum_{p_2 \in P^b} \sum_{t \in T} z_{kp_1 p_2 t} \leq 1 \quad \forall p_1 \in P \quad (19)$$

$$x_{kpt} \in \{0,1\} \quad \forall k \in K, \forall p \in P^b, \forall t \in T: t \geq t_0^p \quad (20)$$

$$0 \leq f_{jet1t_2} \leq \beta_{pet2} a_p \quad \forall p \in P, \forall j \in J, \forall e \in E, \forall t_1, t_2 \in T: t_1 = t_0^p, t_2 \geq t_1$$

$$0 \leq f_{omet1t_2} \leq \sum_{p \in P: t_1 \geq t_0^p} \sum_{e_1 \in E} \beta_{pe1t_1} \eta_{oe_1 et_1 t_2} c_o^O \quad \forall o \in O, \forall m \in M, \forall e \\ \in E, \forall t_1, t_2 \in T: t_2 > t_1$$

$$0 \leq s_{oet1t_2} \leq \sum_{p \in P: t_1 \geq t_0^p} \beta_{pet1} c_o^O \quad \forall o \in O, \forall e \in E, \forall t_1, t_2 \in T: t_1 \leq t_2$$

$$0 \leq h_{kpt} \leq y_k + y_k^* \quad \forall k \in K, \forall p \in P, \forall t \in T: t \geq t_0^p$$

$$0 \leq h_{kpt}^* \leq y_k^* \quad \forall k \in K, \forall p \in P, \forall t \in T: t \geq t_0^p$$

$$z_{kp_1 p_2 t} \in \{0,1\} \quad \forall k \in K, \forall p_1, p_2 \in P^b: p_1 \neq p_2, \forall t \in T \\ : \{t \geq t_0^{p_1}, t + 1 \geq t_0^{p_2}\}$$

The objective function maximizes the total profit of the biomass supplier, including the revenues from the sales of the wood chips delivered at the plants (5i) coming from the roadside piles or terminals; the daily cost of using each chipper (5ii); hourly costs of the roadside chipping operations, including the overtime work (5iii); wood chips' total transportation costs, including from the roadside to terminals or to plants and from terminals to plants (5iv); chippers' movement costs between piles (5v); and total storage costs at the terminals (5vi).

Constraints (6) define the energy content of the wood chips delivered at each power plant between the minimum demand and the maximum processing capacity. Constraints (7) state that the total flows of wood chips from piles at the roadside is at most the total availability. Constraints (8) account for the total number of chipping hours, that is upper bounded by the duration of the working shift plus the maximum allowed overtime, and lower bounded by the minimum working hours, if there is a chipper assigned to a pile. It is noteworthy that the minimum working hours in this constraint corresponds to the chippers usage cost. Below this number of hours, in principle it is more cost-efficient to conclude the work using overtime hours in the previous planning period. Complementary, constraints (9) set the number of overtime hours worked by each machinery/team, bounded by maximum allowed overtime. Constraints (10) establish the linkage between chippers' work hours and wood chips flows with origin in piles.

Constraints (11) and (12) balance the stocks per energy content at

the terminals, taking into account the variation in energy content. Specifically, (11) set the amount of stock entering each terminal in each time period and moisture content class. Constraints (12) decrease the stock levels at the terminal in a given moisture content class by the amount of the outgoing flows. Which in turn are determined by the auxiliary parameter $\eta_{e_1 e_2 t_1 t_2}^0$ that predicts the transition between moisture content classes, as explained in section 3.1. Constraints (13) bound the stock to the maximum capacity of the terminal. Constraints (14) bound the wood chips flows in a given period to the maximum transportation capacity available.

Constraints (15) to (18) deal with the assignment of chippers to piles and the space-time continuity of chipping operations. Specifically, Constraints (15) assure that a chipper is assigned to exactly one pile (or depot) in each time period. Constraints (16) and (17) account for the movement of the chipper between the piles (spatial continuity), where constraints (17) ensure that the chipper transportation cost for returning to the depot is considered at the end of the timeline. Constraints (18) ensure a flow conservation from t to $t+1$ in each pile p . These constraints were adapted from the balanced network flow constraints in a single machine lot sizing problem in Ref. [1]. Specifically, the two summands in the first member of the equation relate to t and cannot take value 1 simultaneously, i.e., either the chipper has already been in pile p_1 in period t ($x_{kp_1 t} = 1$), or the chipper has moved to pile p_1 in the end of period t ($\sum_{p_2 \in P^b} z_{kp_2 p_1 t} = 1$). The two summands of the second member of the equation related to $t+1$ are also mutually exclusive and are logically constrained by t . If $x_{kp_1 t} = 1$ then the chipper may continue in pile p_1 in $t+1$ ($x_{kp_1(t+1)} = 1$), or move to another pile p_2 at the end of period t ($\sum_{p_2 \in P^b} z_{kp_1 p_2 t} = 1$). If $\sum_{p_2 \in P^b} z_{kp_2 p_1 t} = 1$, then the chipper will necessarily stay in pile p_1 in period $t+1$, as imposed by constraints (16). Constraints (19) assure that there is at the most one movement from each pile p , along the entire time horizon.

Constraints (20) set the domain of the decision variables. These constraints take advantage of the previously defined parameters in order to eliminate non-admissible decision variables. For example, wood chips' flows from piles (or terminals) to power plants in a certain moisture content class are unfeasible if wood chips never reach those moisture content values. It is noteworthy that, although variables $z_{kp_1 p_2 t}$ take binary values, they may be linearized to improve the model performance.

3.3. Model variations

A simplification of the model is possible if the variation of the moisture content of the biomass at the terminals is not explicitly dealt in the model as a function of the storage age. In fact, there may be situations where the terminal is managed in a way that assures that the moisture content of the chips coming out of the terminal is fixed and previously determined in the beginning of the planning process. This may happen for example in large terminals, or when technical drying is used. In this case, the moisture content at the terminals in each time period is a parameter of the model, and is independent from the characteristics of the incoming flows that are set by the model.

Hence, the moisture content in each time period is a parameter varying with the terminal, which can be defined by the user in the beginning of the planning process. Model [M2] is significantly reduced in this aggregated approach since the set of classes of wood chips moisture content does not need to be considered and it is not necessary to keep track of the storage age of the wood chips batches. Thus, variables $f_{jet_1 t_2}$ are replaced by f_{ijt} , representing the amount of wood chips transported from origin $i \in I$ to destination $j \in J$ in period $t \in T$ (m^3). While variables $s_{oet_1 t_2}$ are replaced by s_{ot} , amount of wood chips stored at terminal $o \in O$ in the end of period $t \in T$. Similarly, parameters ε^e , ρ^e , φ_{em} , are replaced by ε_{it} (energy content per volume unit of wood chips at origin $i \in I$ in period $t \in T$ (MWh/m^3)), ρ_{it} (bulk density wood chips at origin $i \in I$ in period $t \in T$ (kg/m^3)), and φ_{int} (Price paid

per volume unit of wood chips with origin in $i \in I$, delivered to power plant $m \in M$ in period $t \in T$ ($€/m^3$)). Consequently, in model [M2] the objective function is simplified (5b) and constraints (6), (7), (11) to (14) are replaced by (6b), (7b), (11b) to (14b). New constraints (21) are needed to assure that the wood chips remain in the terminal for at least one period.

Model [M2]:

$$\begin{aligned} \max F = & \sum_{i \in I} \sum_{m \in M} \sum_{t \in T} \varphi_{int} f_{int} - \sum_{k \in K} \sum_{p \in P} \sum_{t \in T} [\omega_{kp} (h_{kpt} - h_{kpt}^*) + \omega_{kp}^* h_{kpt}^*] \\ & - \sum_{k \in K} \sum_{p \in P} \sum_{t \in T} C_k^K x_{kpt} - \sum_{j \in J} \sum_{j \in J} \sum_{t \in T} \tau_{ijt} \\ & f_{ijt} - \sum_{k \in K} \sum_{p_1 \in P^b} \sum_{p_2 \in P^b} \sum_{t \in T} \chi_k d_{p_1 p_2} z_{kp_1 p_2 t} - \sum_{o \in O} \sum_{t \in T} \gamma_o s_{ot} \end{aligned} \quad (5b)$$

Subject to: constraints (8), (9), (15), (16), (17), (18), (19), (20) and

$$d_m \leq \sum_{i \in I} \sum_{t \in T} \varepsilon_{it} f_{int} \leq C_m^M \quad \forall m \in M \quad (6b)$$

$$\sum_{j \in J} \sum_{t \in T} f_{ijt} \leq a_p \quad \forall p \in P \quad (7b)$$

$$\sum_{k \in K} h_{kpt_2} \cdot \eta_{kp} = \sum_{j \in J} \sum_{t_1 \in T^{\emptyset}} f_{pj t_1 t_2} \quad \forall p \in P, \forall t_2 \in T \quad (10b)$$

$$\sum_{p \in P} f_{pot} = s_{ot} \quad \forall o \in O, \forall t \in T: t = 0 \quad (11b)$$

$$s_{o(t-1)} + \sum_{p \in P} f_{pot} - \sum_{m \in M} f_{omt} = s_{ot} \quad \forall o \in O, \forall t \in T \setminus \{0\} \quad (12b)$$

$$s_{ot} \leq C_o^O \quad \forall o \in O, \forall t \in T \quad (13b)$$

$$\sum_{i \in I} \sum_{j \in J} \rho_{it} f_{ijt} \leq C^V \quad \forall t \in T \quad (14b)$$

$$\sum_{m \in M} f_{omt} \leq s_{o(t-1)} \quad \forall o \in O, \forall t \in T \setminus \{0\} \quad (21)$$

Another possible model variation is a simplification of the movements of the chippers between piles (constraints 16) to improve model performance in case of instances of significant size. In fact, constraints (16) are computationally expensive due to the exponentially increasing number of $z_{kp_1 p_2 t}$ decision variables when the number of piles increases. The proposed simplification approach consists in outlining a set of Q pre-defined geographical and non-overlapping neighborhoods for each pile p - $\psi_p = \psi_p^0 \cup \psi_p^1 \cup \dots \cup \psi_p^{Q-1}$ - given some distance radius criteria and re-set constraints (16) to (18) accordingly. For example, considering a certain pile p , where $Q = 4$: the first neighborhood (ψ_p^0) could be composed by all piles within 20min distance of pile p , the second neighborhood (ψ_p^1) by piles within 40min distance (not including the ones already contained in ψ_p^0) and ψ_p^2 by all remaining piles. For each one of these neighborhoods we compute the average of the distances between pile p and the locations in the neighborhood, which is then multiplied by the unit chippers' transportation cost to be incorporated in the model's objective function. Additionally, and due to the special characteristics of this location, an additional neighborhood (ψ_p^3) containing only the depot is also set, so that this location can still be distinguished within the model.

Consequently, in the new model formulation [M3], decision variables $z_{kp_1 p_2 t}$ would be replaced by variables z_{kpqt} , taking value 1, if chipper $k \in K$ moves from pile $p \in P$ to another location contained in neighborhood ψ_p^q at the end of period $t \in T$; 0, otherwise. **Constraints (16)–(18)** would change to **constraints (16b)–(18b)** as described below.

Model [M3]:

Objective function (5) or (5b)

Subjected to: constraints (6) to (15), (20) and

$$z_{kp_1q(t-1)} \geq x_{kp_1(t-1)} + \sum_{p_2 \in \psi_p^q} x_{kp_2t} - 1 \quad \forall k \in K, \forall p_1 \in P^b, \forall q, \forall t \in T \setminus \{0\} \quad (16b)$$

$$z_{kp_1q(t-1)} \geq x_{kp_1(t-1)} \quad \forall k \in K, \forall p_1 \in P, q = Q - 1, t = |T| \quad (17b)$$

$$x_{kp_1t} \leq x_{kp_1(t+1)} + \sum_{q \in Q} z_{kp_1qt} \quad \forall k \in K, \forall p_1 \in P, \forall t \in T \quad (18b)$$

$$\sum_{k \in K} \sum_{q \in Q} \sum_{t \in T} z_{kp_1qt} \leq 1 \quad \forall p_1 \in P \quad (19b)$$

4. Computational experiments

The proposed model [M3] was applied to a case study inspired in a wood chips supplier company operating in Southern Finland. The model was implemented in the Gurobi 7.5.1 solver and was run in a 2.60 GHz CPU with capacity for 32 simultaneous processing threads. Model M3 was tested with three different planning horizons were tested: 1 month (40 half-day planning periods), 1.5 months (60 periods) and 2 months (80 periods). Then, the results for 1 month were analyzed in detail. An additional computational experience was conducted to compare the proposed planning approach under variable wood chips moisture content with the baseline situation that relies on empirical estimates for a fixed and known moisture content in the end of an obliged storage age.

4.1. Case study

The company manages their own chipping and transport operations, based on biomass supply contracts with the power plants. The company acquires the piles of forest residues that are byproducts of harvesting operations. The case under study encompasses 84 piles of forest residues of spruce, geographically distributed and ready to be chipped. Because a significant number of piles have very low availabilities and their distances to other piles are residual in some cases, a clustering procedure was implemented in order to reduce the problem size. After this procedure, a total number of 55 clusters of piles were considered, hereafter called macro-piles. The macro-pile location is generically represented by the centroid of the circular cluster, computed with the GIS software based on the location of its piles; the movements of the chippers between the piles of the same cluster are neglected. The problem also contains 4 terminals and 12 power plants. The terminals are assumed empty in the beginning of the planning period. There are also 9 chippers available to do the work. Planning periods are halves of a day - 3.5 h, assumed to be the length of the regular chipping shift. The parameters of the model [M3] are summarized in Table 1.

This case considers 5 moisture content classes (class $e_1 \in [15\%, 20\%]$ to $e_5 \in [50\%, 60\%]$). The bulk density for the average value of the class e (ρ^e) (kg/bulk m^3) is given by reference values for the most common wood fuels (e.g. Ref. [15]). Similarly, the wood chips net calorific value for each class e^e (KWh/m^3) is computed with Equation (1) in respect to e^e . The moisture content variation was obtained with the logistics function (equation (2)) adjusted for the data set of [21] as described in section 2.1. For each week of the planning period, moisture content was calculated, framed into its corresponding moisture content class and parameters β_{pe} and $\eta_{e1e2t1t2}^o$ were set accordingly.

The other parameters of the model were inspired in a former biomass plan done by the company, including the location and availability of the piles; the location, demand and throughput of the plants, the location and capacity of the terminals; number and type of chippers, working hours and transportation capacity. Chipping and storage costs were inspired in the company business and perhaps below the range of the values found in the literature (e.g. Ref. [15]). The transportation costs were computed with Equation (4), considering a unit transportation cost of 0,08 €/m3/km. The distances between locations were

Table 1
Values of the parameters of the model in the case study.

Sets/Parameter	Value
T: Planning periods	Varies between 40 and 80 (halves of a day)
E: Classes of moisture content	$e_1 \in [15,20[; e_2 \in [20,30[; e_3 \in [30,40[; e_4 \in [40,50[; e_5 \in [50,60[$
ρ^e : Bulk density for each class e	$\rho^1 = 354, \rho^2 = 424, \rho^3 = 483, \rho^4 = 572, \rho^5 = 632 \text{ kg/m}^3$
e^e : Wood chips net calorific value	$e^1 = 1.92, e^2 = 1.87, e^3 = 1.8, e^4 = 1.73, e^5 = 1.47 \text{ MWh/m}^3$
P: Macro-Piles	55
a_p : Chips availability	Varies between 10 and 2500 bulk m^3
ϑ_0^P : Initial moisture content	Varies between 30% and 50%
t_0^P : Time since when pile is available	Varies between period 1 and 40
M: Power plants (or mills)	12
d_m : Demand	Varies between 512 and 6144 MWh for the total planning horizon
c_m^M : Throughput	5% more than the demand in each plant
φ_{em} : Price of wood chips	13€/MWh
T: Terminals	4
c_0^O : Capacity	Varies between 4000 and 40000 m^3
γ_o : Unit storage cost	Varies between 0,10 and 1,00€/ m^3
K: Chippers	3
r_{kp} : productivity	Varies according to chipper and pile, between 34 and 48 bulk m^3/hour
$y_k^m; y_k; y_k^*$: Min, regular, max working hours	0; 3,5; 0,5 h, equal for all chippers
$\omega_{kp}; \omega_{kp}^*$: Regular, overtime hourly chipping cost	300; 450 €/hour, equal to all piles
χ_k : Unit chipper transportation cost	3,0 €/km, equal for all chippers
C_k^K : Chipper usage cost	700€/period, equal for all chippers
Wood fuel Transportation	
c^V : Truck transportation capacity	30 ton
N : Number of available trucks	20
τ : Unit transportation cost	0,08 €/ton/km

computed by resorting to the national road dataset of Finland (<http://www.liikennevirasto.fi/avoindata/digiroad#.WPi-W1OGPfC>). Prices of wood chips vary according to its moisture content and the power plant they are delivered to. These prices were estimated considering a fixed price of 13€/MWh [9]. Only 7 of the 12 power plants accept wood chips regardless of their moisture content. Note that, although in this particular case the price is fixed, there is still an incentive for the model to opt for wood chips delivery of lower moisture content, as the price is fixed by energy content unit.

In sum, the entire instance of 80 periods exhibits a total availability of approximately 19,050 m^3 of spruce wood chips in 55 macro-piles and the total demand in the 9 power plants is 26,951 MWh (corresponding to 16,844 m^3 of chips in the higher moisture class accepted by the power plants). Total available storage capacity is 52,000 m^3 . The chipping capacity ranges between 119 m^3 and 240 m^3 per planning period and maximum transportation capacity per period is 600ton.

Table 2

Computational results for model [M3], for 40 to 80 planning periods.

Instance Size				Model size			Computational time		
T	I	a m ³	D MWh (m ³)	# bin.	# cont.	# const.	OF	Runtime (s)	Gap %
40	17	16819	13475 (7018–11229)	2529	49462	21870	89465	9978	0.01
60	45	18098	20213 (10527–16705)	6705	128451	63486	129962	172800	0.13
80	55	19050	26951 (14036–22274)	12699	242020	122501	166996	172800	0.91

T: N. time periods, I: N. macro-piles available up to the end of T; a: total availability of wood chips up to T (m³); d: total demand up to T (in MWh and the range of corresponding m³); # bin.: number of binary variables; # cont.: number of continuous variables; # const.: Number of constraints in the model; OF: value of the objective function (€); Runtime until optimality proven (sec.).

4.2. Comparison of the model performance and results for 40, 60 and 80 time periods

Considering the three different planning horizons, the total demanded MWh increase proportionally to the number of planning periods. The wood chips availability also increases because at the beginning of the planning horizon a minority of the piles are available to be chipped, therefore, the longer the time horizon, the higher number of piles available (see Table 2).

The instance with 40 periods (17 macro-piles, demand of 13,475 MWh) results in a MIP problem with 2529 binary variables, 49,462 continuous variables and 21,870 constraints, which is solved to optimality in approximately 2 h and 45 min. The total profit of the biomass supplier is 89,465 €. The profit gained at the end of 60 periods (45 macro-piles, demand of 20,213 MWh) increases to 129,962 €. In this case, the M3 model has 38% more decision variables, 190% more constraints and takes 48 h to solve the problem to a gap of 0.13% (Table 3). For the instance with 80 periods (55 macro-piles, demand of 26,951 MWh), the model size increases to 12,699 binary variables, 242,020 continuous variables and 187,440 constraints, which reaches the objective function value of 166,996 € with a gap of 0.91% after 48 h. The analysis of the performance of the model suggests that this approach is adequate to solve problems to up to 40 periods (1 month) in a common computer, thus requiring more sophisticated solution approaches for larger problem instances.

In respect to the comparison of the model results, the number of chippers used along the planning horizon varies between 2 (40 periods) and 7 (80 periods) and the average number of trucks is kept steady around 5 trucks per period. This happens because the chipper usage cost is considerably high and the optimal solution will favor using a chipper's capacity to its maximum instead of resorting to additional chippers. In these instances, terminals have excess capacity, so one terminal is sufficient in all test cases to accommodate all wood chips transshipment flows from macro-piles.

Table 3

Results for model M3, for 40, 60 and 80 planning periods.

T	I'	a' m ³	d' MWh (m ³)	k	h hours	s	G periods	n
40	9	7505	14150 (7505)	2	176	1	6.7	94.7
60	13	11273	21224 (11273)	3	273	1	5.8	91.1
80	17	15050	28299 (15050)	7	367	1	6.2	87.8

T: N. time periods, I': N. macro-piles used; a': total availability of wood chips effectively used (m³); d': total demand fulfilled (MWh and m³); k: N. chippers used; h: total number of working hours, including overtime work; s: N. of terminals used; g: average storage age (periods); n: average transportation capacity used per period (ton).

As time periods increase, it is also observable that the average storage age in piles and terminals tends to decrease. This fact is hardly justified by the model behavior and seems to be related with the characteristics of the instance under study. In fact, many piles become available (after harvesting) closer to the end on the planning horizon. Considering the 80 period's instance, the average period when piles become available is 43.4. Furthermore, the difference between piles' availability and power plants' demand decreases significantly and it forces the wood chips to be delivered to the plants sooner, thus spending less time in storage.

4.3. Results of the test case of 40 periods

In the 40 periods instance, the total profit from wood chips sales sums up 89,465€, while total costs sum 98,799€, corresponding to 8297€ of wood chips transportation costs, 55,533€ of chipping costs, 31,500€ of chipper usage costs, 3127€ of chipper transportation costs and 342€ of storage costs. Therefore, 12% of the costs relate to transportation and 88% of the costs to chipping.

Chipping operations: require 2 chippers and a total of 176 chipping hours to produce 7504 m³ of wood chips in 9 macro-piles (corresponding to 18 piles). The schedule of chipping and transportation roadside in macro-piles is presented in Fig. 4a). For example, in macro-pile 19 chipping starts in period 14 with chipper 3 and extends up to period 19, resulting in 1008 m³ of wood chips, of which 90 m³ are transported directly to plant 11 with moisture content e_3 [30–40%], and 918 m³ are transported to plant 12, arriving there also with moisture content class e_3 . All the selected macro-piles require more than one period to be fully chipped. This schedule confirms that temporal continuity constraints are fully satisfied as chipping extends over consecutive periods.

A complementary view of the chipper's schedules shows the optimum sequence of macro-piles for the selected chippers along the planning horizon (Fig. 4b). For example, chipper 6 starts working in period 23 in macro-pile 42, moves to macro-pile 6 in the end of period 26, then to macro-pile 3 in the end of period 30 and finally to macro-pile 9 in the end of period 35. The total chipping hours are 68.7, including 5.7 h of overtime work. The total chipping cost associated to the daily work of chipper 6 is 21,462 €. The schedule shows that spatial continuity constraints are fully satisfied as the chipper moves to neighboring clusters after all the available amount of forest residues in the pile is chipped and transported. It is noteworthy that chipping operations only start after period 14. This is due to the fact that, as expected, the optimal solution fulfills exactly all the demand at the plants and delays chipping as much as possible, to take advantage of the decrease of moisture content while in storage at the piles or terminals. Despite that fact, the chipping capacity in the last planning periods remains sub-used due to the high daily chipper utilization costs.

The trade-off between the chipper utilization costs (700€/period) and the cost of regular and overtime work (300 €/hour and 450 €/hour

Macro-Pile ID	Chipper ID	Macro-Piles' outgoing flows per planning period (plant/terminal of destination, amount m³, moisture content class)																																									
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40		
Total	2																																										
MP 3	6																																										
MP 6	6																																										
MP 9	6																																								(Plant 16, 840 m³, e3)		
MP 16	3																																									(Plant 15, 229 m³, e3)	(Plant 16, 281 m³, e3)
MP 19	3																																									(Plant 11, 90 m³, e3) (Plant 12, 918 m³, e3)	
MP 28	3																																									(Terminal 3, 1709 m³, e3)	
MP 30	3																																									(Plant 14, 161 m³, e3) (Plant 16, 478 m³, e3)	
MP 31	3																																									(Plant 02, 362 m³, e3) (Plant 09, 313 m³, e3)	
MP 42	6																																									(Plant 11, 598 m³, e3) (Plant 13, 74 m³, e3)	

(a) *Macro-piles schedule*

(b) Complementary view of chipper schedule

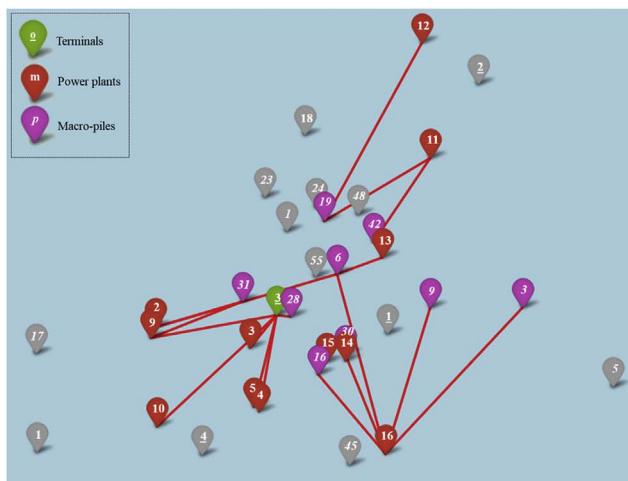
Fig. 4. Schedule chipping and transportation operations over the 40 periods in the 7 selected macro-piles with the 2 selected chippers.

respectively) is shown in the model results. For example, chipper 6 remains in macro-pile 9 for 5 periods and uses a total of 17.5 h of regular work and 2.5 h of overtime, corresponding to a cost of 5250 € for regular work and 1125 € for overtime work, which is still lower than the additional cost of 1525 € for chipping the remaining amount in another period (700 € for an additional period, plus 600 € for regular work and 225 € for overtime work).

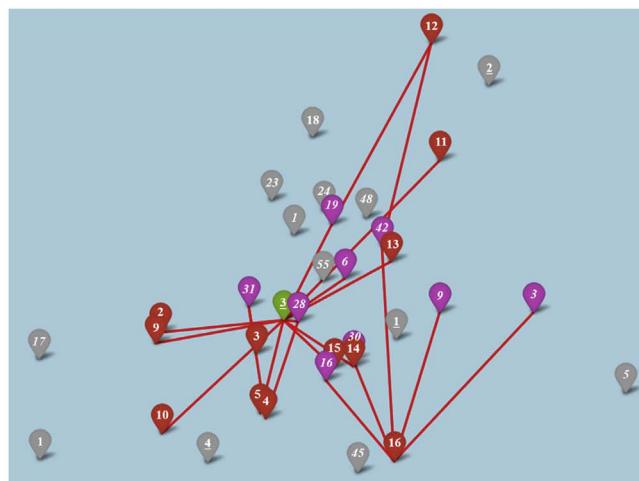
Transportation of wood chips/forest residues: the average transportation capacity used per period is 94.7 ton, corresponding to 5 trucks. Transportation starts in period 14, which is also when chipping

starts, thus confirming the consistency of the model in respect to the synchronization of these roadside operations. From period 14 up to period 21, the transportation flows per period are 72 ton approximately, corresponding to 4 trucks. Then, here is significant increase of the transportation flows until reaching a maximum of 204 ton (11 trucks) in periods 23–28. From then up to the end of the timeline the transportation flows decrease and stabilize to a range corresponding to the use of 8 trucks. The total transportation network is presented in Fig. 5a).

Storage: only terminal 3 is used, because it is the one that is closest



(a) Solution obtained with the new planning approach acknowledging the variation of the wood chips moisture content along the time spent in storage



(b) Solution obtained for the baseline situation

Fig. 5. Transportation network between macro-piles, terminals and power plants for all the periods.

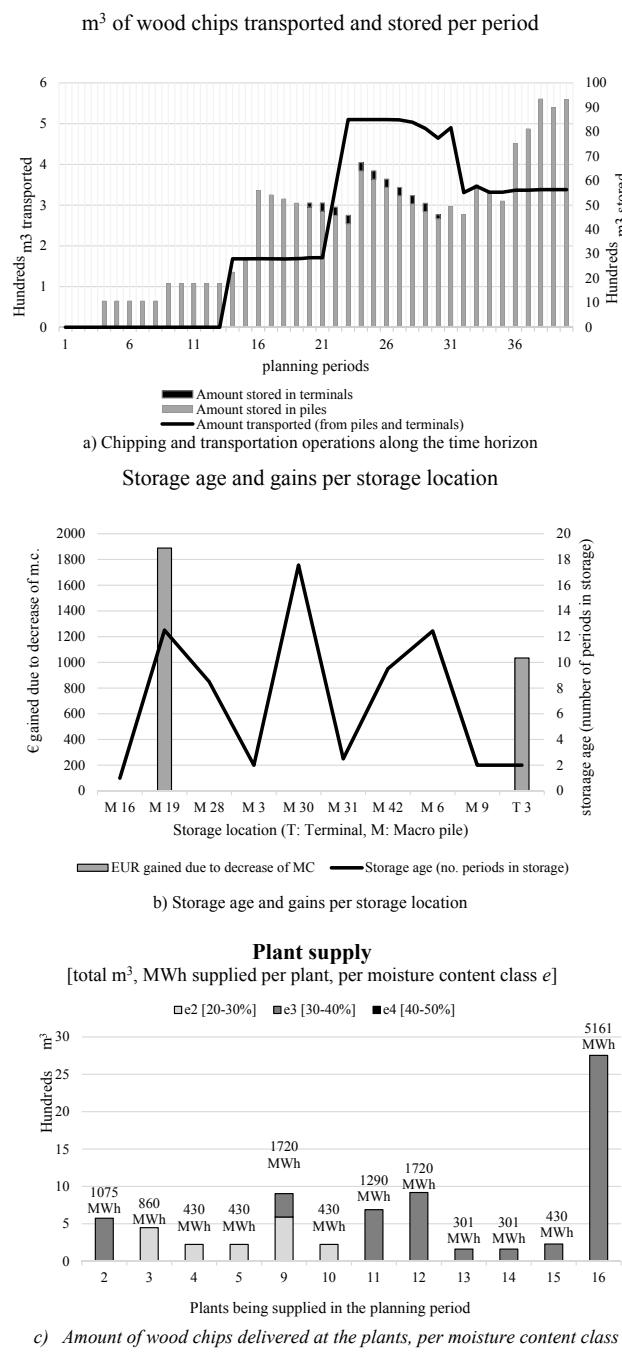


Fig. 6. Chipping, transportation, storage and plant supply for the case of 40 periods.

to the macro-piles that are used. Furthermore, this terminal is the one that has the lowest utilization costs. Still the level of its utilization is very low. The maximum storage capacity used is 342 m^3 between periods 20 and 28, significantly below the terminal capacity (4000 m^3). There are only 10 incoming flows for terminal 3 (between periods 20 and 29 from macro-pile 28, with moisture content e3). The average storage age is 2 periods, which is most likely a consequence of the parameters of the drying curve used in this case. For the forest residues stored in piles, the average storage age is 6.7 periods (Table 3).

The distribution of the transportation and storage amounts along the time horizon is presented in Fig. 6a). The piles are the main stocking location. There is an average of 4161 m^3 stocked in the piles per period. The maximum of the stock occurs in period 38 when most of the piles used are already available.

In respect to the profit increase due to the loss of moisture content

during the time in storage, the 1709 m^3 stored in terminal 3 correspond to an increase of profit of 1034€ . The gain due to storage in the roadside piles is 1888€ , corresponding to the decrease of moisture content from e5 to e3 in macro pile 19 (Fig. 6b)). The total gain sums up 2923€ , about 3.3% of the total profit. It is noteworthy that this value may be under-estimated since the decrease of moisture content for the remaining macro piles did not correspond to a reduction of the moisture content class, consequently the gain is not quantified. This is a drawback of the discretization approach with the class length corresponding to 10% variation. When the initial moisture content is closer to the upper limit of the moisture class, the short storage age may not be enough to decrease to a lower class, while if the moisture content is closer to the lower limit of the class it will likelier decrease.

Demand fulfillment: As expected in this demand-driven problem, the amount supplied is equal to the maximum amount demanded by the plant, summing $14,150 \text{ MWh}$ (Fig. 6c)). The majority of the plants was exclusively supplied with wood chips with moisture content e3 [30–40%], except for plants 3 to 5 and 9 to 10, which receive a total amount of 1709 m^3 of wood chips with lower moisture content from terminal 3. This can be justified due to the fact that these plants are the closest ones to terminal 3, therefore benefitting from the fact that the wood chips have a longer drying age and were subjected to most favorable drying conditions (i.e. better drying curve) in that terminal than in other terminals or roadside piles.

4.4. Comparison of the proposed planning approach under variable wood chips moisture with the baseline situation

The baseline situation for supply planning corresponds to relying exclusively on empirical estimates for a fixed and known moisture content in the end of a fixed storage age that may vary according to each storage location. This is often the case when portable devices are not available or not frequently used to monitor the moisture content variation along the time spent in storage. In opposite, model [M3] used in this study explicitly handles the variation of moisture content along the variable time in storage, thus representing a change in the company current business practices that can help to reduce operational costs.

In this study, we assumed a baseline corresponding to an initial moisture content in the wood piles (after harvesting) of 48%, unchangeable regardless the time remaining in storage; and of 30% after 10 periods spent drying in a given terminal. The steps to simulate the baseline include: 1) Adapt the data set to consider the empirical estimates of moisture content of 48% in the wood piles, unchangeable regardless the time remaining in storage; and of 30% after 10 periods spent drying in a given terminal; 2) Use [M2] to compute values of the decision variables x_{kpt} , h_{kpt} , h_{kpt}^* , $z_{kp_1p_2t}$, f_{ijt} , s_{ot} under those assumptions; 3) Compute the $f_{ijet_{1t_2}}$ equivalent to f_{ijt} and the $s_{oet_{1t_2}}$ equivalent to s_{ot} and then inject the values of the decision variables x_{kpt} , h_{kpt} , h_{kpt}^* , $z_{kp_1p_2t}$, $f_{ijet_{1t_2}}$, $s_{oet_{1t_2}}$ in [M3] to compute the value of the objective function.

The value of the objective function for the BAU obtained with this procedure is $70,475\text{€}$. This is 21.2% less than the total profit obtained with our proposed approach that explicitly handles the variation of moisture content along the variable time in storage ($89,465\text{€}$).

In fact, our approach shows that it is more cost-effective to leave the wood chips to dry in the wood piles at the roadside. The flows to terminals are significantly reduced and the chips remain there 2 periods, in average, instead of 10 as considered in the BAU. Consequently, wood chips transportation costs are $15,138\text{€}$, 82% higher than with the proposed approach, not only because of the increase in chips' moisture content in piles, but also due to the additional transport of wood chips to terminals. The average transportation capacity used per period increases from 156 ton (8 trucks) to 347 ton (18 trucks). Similarly, storage costs in the BAU are 3255€ , more than 850% higher than with the proposed approach. This is because the BAU forces the material that goes to terminal 3 to remain there for at least 10 periods. The total

transportation network for the 40 periods is presented in Fig. 5b). By comparing both maps we can conclude that chippers perform chipping in the same piles, and the optimal solution in the BAU favors visits to terminal 3, while in the proposed approach the terminal is only used if chips' delivery is made in a nearby location.

5. Concluding remarks

This paper presents a novel mathematical programming model for tactical biomass supply planning problem, in case of synchronized chipping and transportation at the roadside ("hot systems"), and explicitly considering the variation in chips energy content (or moisture content) over time in storage. It builds on previous research from Refs. [19] and [14]. 2 model variations were discussed. The first, does not account for moisture content classes, as it assumes that moisture content of the chips coming out from storage is a user-defined parameter, known at the beginning of the planning process. The second, is an simplified way to model the movement of the chipper between piles that considers geographic neighborhoods for each pile that at defined beforehand. This approach reduces the number of constraints, therefore improving the model performance for larger problem instances. The latter modelling approach is successfully used to solve to optimality within 3 hoursrs, problem instances with 17 macro-piles, 40 periods (half days), 4 terminals (for intermediate storage) and 12 power plants. 6 moisture content classes were considered, ranging from 30% to 55%. 9 chippers (with heterogeneous productivity) and 20 trucks (with homogenous capacity) were available. The results were presented in the form of a chipping-transportation schedule for each macro-pile/chipper and a flow map. Results suggest that a 20% improvement in the supplier profit can be obtained with the proposed approach that explicitly handles the variation of moisture content along the variable time in storage, when compared with a baseline situation that relies on empirical estimates for a fixed and known moisture content in the end of an obliged storage age.

Future work will seek alternative modelling approaches to solve larger instances that characterize real-life planning situations (e.g. 145 piles and up to 350 periods). For this purpose, a novel formulation will be developed, inspired in the generalized lotsizing and scheduling problem [13]. Alternative heuristic procedures may also be considered. Robust optimization or stochastic programming may be tested to address relevant uncertainty sources, both at the supply level (e.g. uncertainty in the moisture content values in each pile) and at the demand level (e.g. MWh demanded by each plant). Future work may also seek for optimizing the daily routing and scheduling for each chipper and truck (at hourly level), taking into account the synchronization constraints (e.g. Ref. [7]).

Acknowledgments

This research has received funding from the European Union Seventh Framework Programme (FP7/2007–2013) under grant agreement number [604286]. This work is also financed by the ERDF – European Regional Development Fund through the Operational Programme for Competitiveness and Internationalisation - COMPETE 2020 Programme and by National Funds through the Portuguese funding agency, FCT - Fundação para a Ciência e a Tecnologia within project POCI-01-0145-FEDER-016733 (Easyflow). Further funding was obtained from the Project "NORTE-01-0145-FEDER-000020 (TEC4Growth - Pervasive Intelligence, Enhancers and Proofs of Concept with Industrial Impact)", financed by the North Portugal Regional Operational Programme (NORTE 2020), under the PORTUGAL 2020 Partnership Agreement, and through the European Regional Development Fund (ERDF)European Regional Development Fund.

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