

## Process

- code, data, stack (own address space usually)
- program state (CPU registers, program counter, stack ptr)
- only 1 process runs at a time
  - multi-core CPU multiple processes
- loader relocates instructions by <sup>(bases)</sup> addresses to each other
  - ↳ processor & OS provide virtual memory

## Memory Hierarchy

- cache  $\Rightarrow$  L1 (CPU chip), L2 (on/off chip), L3 (off chip SDRAM)
- main memory (DRAM)
- disk

- memory management goal: lay components out in memory

## Fixed Partition: Multiple Programs

- fixed partitions
  - divide memory into fixed space
  - assign processes to space when free
- mechanisms
  - separate input queues for each partition

## Multiprogramming

- needs relocation & protection
- OS can't be certain where a program will be loaded in memory
  - $\rightarrow$  must keep memory separate

## Base & Limit Registers

- base: start of process's memory partition
  - limit: length of process's memory partition
  - physical address = location in actual memory
  - ~~logical~~ address = base + logical address
  - logical address = location from process's POV
- } contained in registers
- (error if logical > physical)



- Allocating Memory: searches thru region list to find large space
  - first fit = first suitable hole on list
  - next fit = first suitable after previously allocated hole
  - best fit = smallest hole larger than desired region (wastes least space)
  - worst fit = leaves largest space

- Freeing memory:
  - easy w/ bitmaps
  - modify adjacent elements in linked list
  - merge adjacent free regions to 1 region

- Buddy Allocation: allocate memory in powers of 2
  - split large chunks into 2
  - when freed, see if you can combine w/ buddy to rebuild

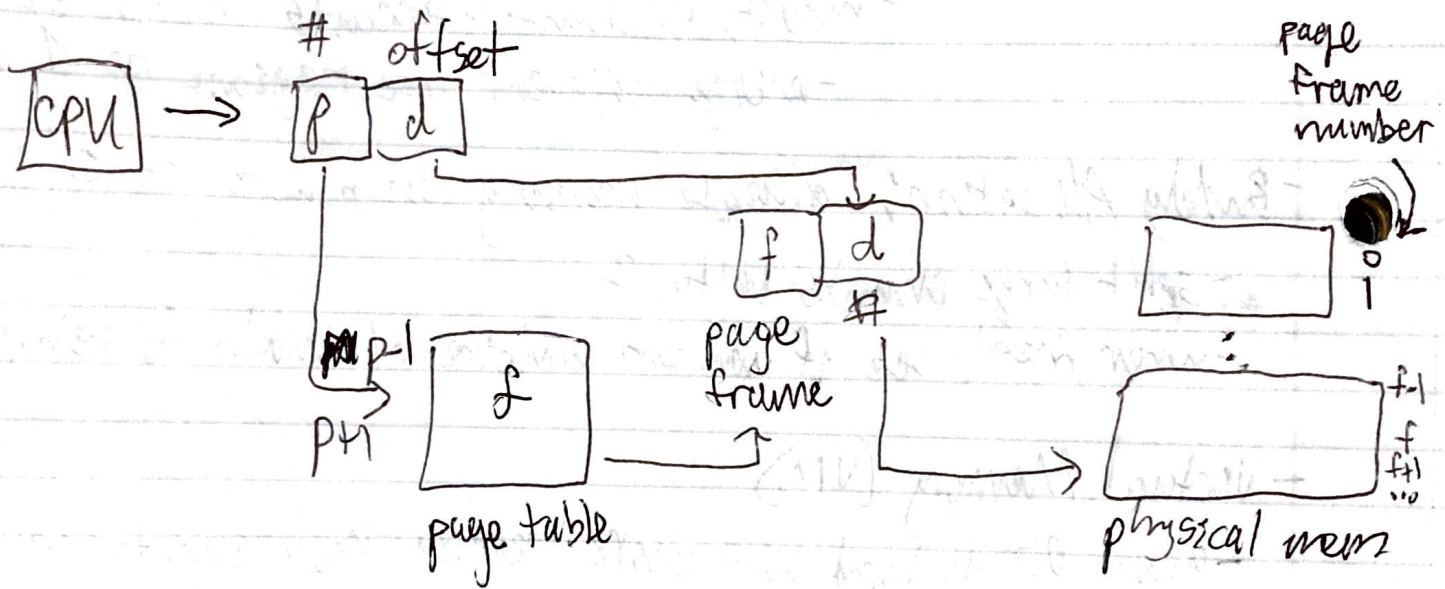
- Virtual Memory (VM)
  - allow OS to hand out more memory than exists on system
  - keep used in physical memory, move rest to disk
- virtual address mapped to physical addresses = paging
  - ↳ page table translates virtual page number to physical page number (but not all VM has physical pages)

- Page Entry:
  - valid bit (has corresponding physical frame)
  - page frame # (page in physical memory)
  - referenced bit (if data was accessed)
  - dirty/modified bit (if modified)

Mapping Process:

- split address into page #  $p$  & offset  $d$
- page #: - index into table
  - contains base address of page in phys mem
- page offset: added to base address to get actual physical mem address

(page size =  $2^d$  bytes)



## Process Model

- conceptual model of multiprogramming  $\wedge$  programs (independent, runs sequentially)
- only 1 process active at any instant
  - can be short, only applies if single CPU in system
- process created by
  - ① system initialization
  - ② execution of process creation system call

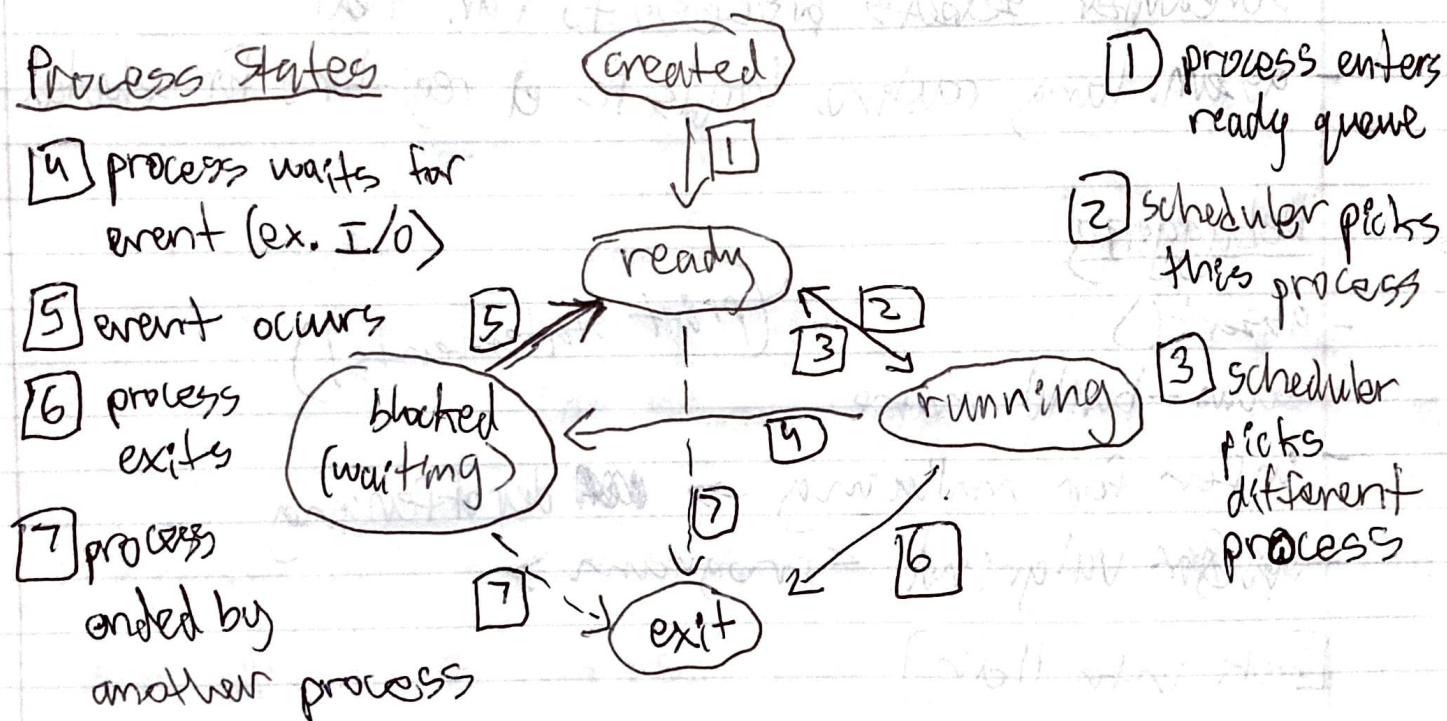


- Process ends: ① voluntary (normal or error exit)
- ② involuntary (fatal error / killed by another process)

## Process Hierarchies

- parent creates child process, child can create own children
- Unix forms hierarchy "process group"
- if terminated, children inherited by terminated process's parent

## Process States



## Process Table Entry

registers  
 program counter  
 CPU status word

} may be stored on stack

## Trap/Interrupt

- hardware saves program counter (stack/register)
- hardware loads new PC & identifies interrupt
- assembly lang routine saves registers
- " " sets up stack
- " " calls C to run service routine
- service routine calls scheduler
- scheduler selects process to run next
- assem. lang routine loads PC & registers for selected process

## Debugging

- assert() (print statements!)
- scan-build make
- infer for mallocing → ~~not~~ dereferencing
- ~~valgrind~~ valgrind <program>

[look into lldb]

## Hashing & Bloom Filters

- binary search in sorted array =  $O(\log(n))$
- hashing
  - $O(1)$  search time on average,  $O(n)$  worst case



## - Hash Table (HT)

- unordered collection of key-value pairs
- efficient lookup, insert, & delete operations

$\Rightarrow \text{hash}(\text{key}) = \text{index} \in [0, m-1]$  w/  $m$  slots

- function uses all input data
- computation is fast
- minimizes hash collisions

- division based: 
$$h(k) = k \bmod m$$
  
(key) (table size)

- string-valued: take characters from key, compute int using method, int  $\bmod$  table size

- load factor ( $\lambda$ ) = # of slots filled out of total slots in HT

- hash collision = 2 data pieces have same hash value  
 $\hookrightarrow$  rare in good hash funcs w/ proper range

but unavoidable if # of keys  $>$  # of hash values

[linear probing, quadratic probing, double hashing]

## - Cache performance

- chaining = bad as keys are stored in linked lists
- open addressing = good as everything stored in same table

## - space

- chaining uses extra space for links
  - part of MT never used
- no links in open addressing, slot can be used even if input isn't mapped to it

## - Bloom Filter (BF)

- data struct, tells if element in set  $\Rightarrow$  bit array
- ex)  $k=3$  hash func

pass elements  $\{x, y, z\}$  thru all 3  
and set corresponding bits in BF

- check if key exists in MT
- returns possibly in set or definitely not in set

$$\hookrightarrow \text{false (+) probability} = \left(1 - e^{-\frac{kn}{m}}\right)^k$$

( $n$  = # of inserted elements,  $m$  = # of bits in array,  $k$  = # of hash functions)

- $O(k)$  hash func, space of what holds data  $O(m)$