Development of a Simple Near-Ground Path Loss Model Verified by Measurements

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16gr751 1st Semester WCS





Test af antenner

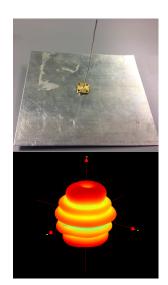
Test og Målinger

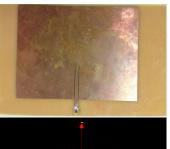
Databehandling

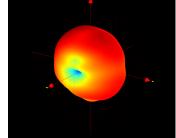
Parameternes betydning

Foreslået PL model

Model fit







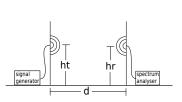


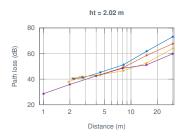
Måling af path loss

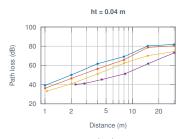
Test og Målinger

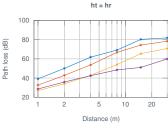
Foreslået PL model

Model fit









hr = 0.08 m hr = 0.14 m hr = 0.36 m hr = 2.02 m



Databehandling

Test og Målinger

Databehandling

Foreslået PL model

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- ► Find PL fra måling
- ► Find mean af PL for de forskellige parameter
- ► Find 95% confidence intervallet for hver parameter

$$PL = \frac{\text{Måling} \cdot \text{system tab}}{\text{Antenne gains}}$$

$$PL(par) = mean(PL_{par})$$

	Vertical	Vertical	Horizontal	Horizontal	Vertical	Vertical	Horizontal	Horizontal	Patch	Patch	Monopole	Monopole
	Patch	Monopole	Patch	Monopole	Hal	P-plads	Hal	P-plads	Hal	P-plads	Hal	P-plads
		Hal vs	P-plads			Patch vs I	Monopole			Vertical vs	Horizontal	
+/- 5	80%	52%	53%	50%	55%	72%	25%	47%	83%	53%	53%	43%
+/- 10	10%	23%	27%	28%	37%	25%	50%	43%	13%	32%	15%	33%
+/- 15	5%	15%	10%	17%	7%	3%	13%	5%	2%	12%	15%	22%
Andre	5%	10%	10%	5%	2%	0%	12%	5%	2%	3%	17%	2%



Parameternes betydning

Test og Målinger Databehandling

Parameternes betydning

Foreslået PL model Model fit

z paramotoron

Distance	1 m	2 m	4 m
PL	(34.7±1.6) dB	(41.4±1.4) dB	(49.0±1.7) dB

Distance	8 m	15 m	30 m
PL	(57.3±2.1) dB	(66.1±2.5) dB	(72.3±2.3) dB

$h_t \setminus h_r$	0.04 m	0.14 m	0.36 m	2.02 m
0.04 m	(63.7±5.2) dB	(60.7±5.1) dB	(55.4±4.7) dB	(52.4±3.8) dB
0.14 m	(60.7±5.1) dB	(58.1±5.2) dB	(53.4±4.5) dB	(50.2±3.2) dB
0.36 m	(55.4±4.7) dB	(53.4±4.5) dB	(49.0±2.9) dB	(47.6±4.8) dB
2.02 m	(52.4±3.8) dB	(50.2±3.2) dB	(47.6±4.8) dB	(44.4±3.1) dB

Hal	Parkerings plads	Monopol	Patch
(52.4±1.8) dB	(54.6±2.2) dB	(55.6±2.0) dB	(51.4±2.0) dB

Vertikal	Horisontal		
(51.8±1.9) dB	(55.1±2.1) dB		



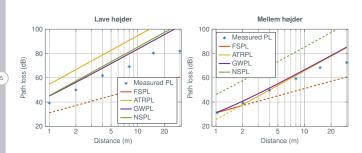
Foreslået PL model

Test og Målinger Databehandling

Parameternes betydning

Foreslået PL model

Model fit



$$PPL = \left(ATRPL^{-1} + NSPL^{-1}\right)^{-1}$$

$$PPL = \frac{d^4}{h_t^2 h_r^2 + h_0^4}$$



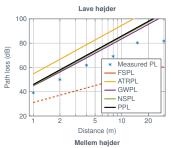
Model fit

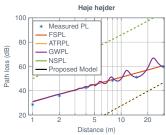
Test og Målinger

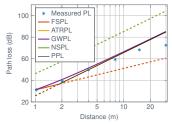
Parameternes

Foreslået PL model

Model fit







Models	MSE	Anvendelighed
FSPL	15.95	35 %
ATRPL	141.58	65 %
GWPL	35.49	100 %
NSPL	230.05	30 %
PPL	60.18	65 %



z parameteren

Test og Målinger

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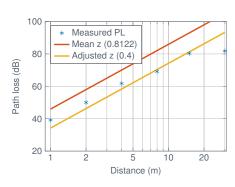
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$$z_V = \frac{\sqrt{\epsilon_0 - \cos^2 \theta}}{\epsilon_0}$$

$$z_H = \sqrt{\epsilon_0 - \cos^2 \theta}$$



Questions

