

# The Natural Rate of Interest in a Nonlinear DSGE Model\*

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## Abstract

This paper investigates how and to what extent nonlinearities, including the zero lower bound on the nominal interest rate, affect the estimate of the U.S. natural rate of interest in a dynamic stochastic general equilibrium model. The estimated natural rate in a nonlinear model is substantially different from that in its linear counterpart after the global financial crisis because of the zero lower bound. Other nonlinearities such as price and wage dispersion, from which a linear model abstracts, play a negligible role in identifying the natural rate.

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# 1 Introduction

The natural rate of interest—the equilibrium real interest rate that yields price stability (Wicksell, 1898)—has been a key concept for monetary policy analysis. In particular, a modern New Keynesian framework relates the concept of the natural rate to intertemporally optimizing agents and makes it relevant for social welfare (Woodford, 2003; Galí, 2008). The level of the natural interest rate in this framework is a useful indicator for policymakers because it is a benchmark as to whether policy is too tight or too loose from a welfare perspective.<sup>1</sup> However, the natural rate is unobservable and must be estimated. Whereas the literature has developed various empirical methods to infer the natural rate, an increasing number of researchers have estimated the natural rate measures based on New Keynesian dynamic stochastic general equilibrium (DSGE) models.<sup>2</sup> Examples for the U.S. economy include Andrés, López-Salido, and Nelson (2009), Barsky, Justiniano, and Melosi (2014), Cúrdia (2015), Cúrdia, Ferrero, Ng, and Tambalotti (2015), Del Negro, Giannone, Giannoni, and Tambalotti (2017), Edge, Kiley, and Laforte (2008), Justiniano and Primiceri (2010), and Neiss and Nelson (2003).

This paper estimates the natural rate of interest in the U.S. economy using a nonlinear New Keynesian DSGE model with a zero lower bound (ZLB) constraint on the nominal interest rate and examines how and to what extent nonlinearities affect the estimates of the natural rate and its driving forces. Whereas the previous studies estimate the DSGE-based natural rate only in a linear setting that abstracts from the ZLB, this paper is one of the first to estimate the natural rate in a fully nonlinear and stochastic setting that incorporates the ZLB.<sup>3</sup>

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<sup>1</sup>Closing the gap between the actual real interest rate and the natural rate is not necessarily optimal in the economy where “divine coincidence” (Blanchard and Galí, 2007) does not hold. However, Barsky, Justiniano, and Melosi (2014) demonstrate that, even in such a circumstance, a central bank would be able to stabilize both inflation and the welfare-relevant output gap to a considerable degree by tracking the natural rate using an estimated New Keynesian model.

<sup>2</sup>Another stream of the literature estimates the long-run natural interest rate based on semi-structural or reduced-form models. See, for instance, Holston, Laubach, and Williams (2017), Johannsen and Mertens (2021), Kiley (2015), Laubach and Williams (2003, 2016), Lubik and Matthes (2015), Pescatori and Turunen (2016), and Williams (2015).

<sup>3</sup>A contemporaneous paper by Iiboshi, Shintani, and Ueda (2020), which evolved independently from our work, estimates a nonlinear small-scale New Keynesian model for Japan and extracts a sequence of the natural rate.

Our analysis is motivated by the following two strands of literature. First, Fernández-Villaverde and Rubio-Ramírez (2005) and Fernández-Villaverde, Rubio-Ramírez, and Santos (2006) demonstrate that the level of likelihood and parameter estimates based on a linearized model can be significantly different from those based on the original nonlinear model. The same may be true for the estimation of unobservable state variables, including the natural rate. If substantial differences in the estimates of the natural rate arise between linear and nonlinear models, it will cast doubt on the common practice in which the natural rate is estimated based on a linear model. Over- or under-estimation of the natural rate would be misleading in evaluating the stance of monetary policy.

Second, the recent experience of the global financial crisis and the extremely low interest rate period that followed has led researchers to conduct empirical analyses based on nonlinear DSGE models in order to take the ZLB into consideration. For instance, Gust, Herbst, López-Salido, and Smith (2017) incorporate the ZLB into a medium-scale DSGE model similar to those developed by Christiano, Eichenbaum, and Evans (2005) and Smets and Wouters (2007), and estimate the model in a nonlinear setting using U.S. macroeconomic time series. Plante, Richter, and Throckmorton (2018) and Richter and Throckmorton (2016a, 2016b) estimate a nonlinear version of a prototypical New Keynesian model with the ZLB for the U.S. economy, and Iiboshi, Shintani, and Ueda (2020) estimate a similar model for the Japanese economy. Aruoba, Cuba-Borda, and Schorfheide (2018) consider Markov switching between the targeted-inflation and deflation regimes in a New Keynesian framework with the ZLB and estimate the probabilities of the U.S. and Japan having been in either the targeted-inflation or deflation regime using a nonlinear filtering technique. The present paper contributes to this strand of the literature by focusing on the estimation of the natural rate.

In estimating the natural rate of interest, we follow a two-step approach. First, to parameterize the model, we estimate a piecewise linear version of the model, in which the ZLB constraint is imposed but all the equilibrium conditions are linearized, using the OccBin toolbox developed by Guerrieri and Iacoviello (2015) and the inversion filter following Guerrieri and Iacoviello (2017). Regarding this estimation strategy, Atkinson, Richter, and Throckmorton (2020) demonstrate that piecewise linear and fully-nonlinear approaches give rise to similar parameter estimates. Thus, the piecewise linear approach enables us not only to avoid a computational burden that would increase

exponentially in the estimation of a fully nonlinear model, but also to obtain reliable estimates of parameters.

Next, given the estimated parameters, we solve the model in a fully nonlinear and stochastic setting with the ZLB and apply a nonlinear filter to extract the sequence of the natural interest rate. The literature (e.g., Boneva, Braun, and Waki, 2016; Fernández-Villaverde, Gordon, Guerrón-Quintana, and Rubio-Ramírez, 2015; Gavin, Keen, Richter, and Throckmorton, 2015; Gust, Herbst, López-Salido, and Smith, 2017; Nakata, 2016, 2017; Ngo, 2014; and Richter and Throckmorton, 2016a) has emphasized the importance of considering nonlinearities and related uncertainty effects in assessing the quantitative implications of New Keynesian models that include the ZLB. The natural rate estimated in the present paper takes account of these important features. Moreover, our analysis is based on an empirically richer DSGE model than the prototypical New Keynesian model. The model features habit persistence in consumption preferences, price and wage stickiness, backward-looking components in price and wage settings, and monetary policy smoothing.

The main results are summarized as follows. Comparing the estimated natural interest rate based on the nonlinear model with that based on the linear counterpart, we find that the former is higher than the latter by up to 2 percent after the global financial crisis when the nominal interest rate was bounded at virtually zero. This difference is non-negligible; if we relied on the linear model, we would overestimate the tightness of monetary policy due to the ZLB to the substantial degree. The difference is ascribed to a contractionary effect arising from the ZLB, which is considered only in the nonlinear model. Although such a contractionary effect lowers expected output and inflation, actual output and inflation are pegged to the corresponding observables in the filtering process. Then, larger positive shocks to aggregate demand must be identified in order to satisfy the household's intertemporal Euler equation that equates the marginal utility of consumption today and the expected discounted one in the future. As a consequence, the estimated natural rate increases in the nonlinear setting. Although price and wage dispersion potentially affect the identification of shocks and the estimate of the natural rate, their effects turn out to be negligible.

These findings allure researchers to use a piecewise linear model because such a model is easier to solve than a fully nonlinear model. In this regard, we demonstrate that the piecewise linear model can well replicate the natural interest rate based on the nonlinear model in the aftermath of

the global financial crisis, although it can slightly underestimate the natural rate due to ignoring uncertainty at the ZLB.

The remainder of the paper proceeds as follows. Section 2 describes the model used in our analysis and a strategy for estimating the natural interest rate. Section 3 presents our results. Section 4 is the conclusion.

## 2 Model and Estimation Strategy

This section begins by describing the model used in our analysis. In the model economy, there are households, perfectly competitive final-good firms, monopolistically competitive intermediate-good firms, and a central bank that faces the ZLB constraint on the nominal interest rate. To ensure a better fit to the macroeconomic time series, the model features habit persistence in consumption preferences, price and wage stickiness, backward-looking components in price and wage settings, and monetary policy smoothing.<sup>4</sup> In the model, the natural rate of interest is defined as the real interest rate that would prevail if prices and wages were fully flexible without any markup shocks.<sup>5</sup>

To obtain the estimates of the natural interest rate, we implement a two-step approach. First, we estimate a piecewise linear version of the model, in which the ZLB constraint is imposed but all the equilibrium conditions are linearized using the OccBin toolbox and a inversion filter. Next, given the estimated parameters, we solve the model in a fully nonlinear and stochastic setting with the ZLB using a projection method and apply a particle filter to extract the sequence of the natural rate.

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<sup>4</sup>Regarding modeling choice, we consider nominal wage rigidities as in Erceg, Henderson, and Levin (2000) as well as price rigidities to incorporate additional nonlinearities through a wage dispersion term and its variability. A medium-scale model with capital accumulation could take account of more nonlinearities, but we leave an analysis using such a larger-scale model for future work.

<sup>5</sup>This definition follows from Barsky, Justiniano, and Melosi (2014) and is the most commonly used in the literature that estimates the natural rate based on DSGE models. Cúrdia, Ferrero, Ng, and Tambalotti (2015) estimate the efficient interest rate, which is defined as the real interest rate under flexible prices and perfect competition with zero markups.

## 2.1 The model

### 2.1.1 Households

Each household  $h \in [0, 1]$  consumes final goods  $C_{h,t}$ , supplies labor  $l_{h,t} = \int_0^1 l_{f,h,t} df$  to intermediate-good firms  $f \in [0, 1]$ , and purchases one-period riskless bonds  $B_{h,t}$  so as to maximize the following utility function

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t \left( \prod_{k=1}^t d_k \right)^{-1} \left[ \log (C_{h,t} - \gamma C_{t-1}) - \frac{l_{h,t}^{1+\eta}}{1+\eta} \right],$$

subject to the budget constraint

$$P_t C_{h,t} + B_{h,t} = W_{h,t}^n l_{h,t} + R_{t-1}^n B_{h,t-1} + T_{h,t},$$

where  $\beta \in (0, 1)$  is the subjective discount factor,  $\gamma \in [0, 1]$  is the degree of external habit persistence in consumption preferences ( $C_{t-1}$  is the aggregate consumption in period  $t-1$ ),  $\eta \geq 0$  is the inverse of the labor supply elasticity,  $P_t$  is the price of final goods,  $W_{h,t}^n$  is the nominal wage for household  $h$ ,  $R_t^n$  is the gross nominal interest rate, and  $T_{h,t}$  is the sum of a lump-sum public transfer and profits received from firms. Following Christiano, Eichenbaum, and Rebelo (2011), a shock to the discount factor  $d_t$  affects the weight of the utility in period  $t+1$  relative to the one in period  $t$ . In the present model, this shock is broadly interpreted as a shock to aggregate demand. The log of the discount factor shock follows an AR(1) process

$$\log d_t = \rho_d \log d_{t-1} + \varepsilon_{d,t}, \quad (1)$$

where  $\rho_d \in [0, 1)$  is an autoregressive coefficient and  $\varepsilon_{d,t}$  is a normally distributed innovation with mean zero and standard deviation  $\sigma_d$ . The first-order conditions for optimal decisions on consumption and bond-holding are identical among households, and therefore become

$$\Lambda_t = \frac{1}{C_t - \gamma C_{t-1}}, \quad (2)$$

$$\Lambda_t = \frac{\beta}{d_t} R_t \mathbb{E}_t \frac{\Lambda_{t+1}}{\Pi_{t+1}}, \quad (3)$$

where  $\Lambda_t$  is the marginal utility of consumption, and  $\Pi_t = P_t/P_{t-1}$  denotes gross inflation.

### 2.1.2 Wage setting

A labor packer collects differentiated labor  $\{l_{f,h,t}\}$  from each household  $h$  and resells a labor package augmented by a CES aggregator  $l_{f,t} = \left[ \int_0^1 l_{f,h,t}^{(\theta_w-1)/\theta_w} dh \right]^{\theta_w/(\theta_w-1)}$  to intermediate-good firms indexed by  $f$ , where  $\theta_w > 1$  represents the elasticity of substitution among labor varieties. Given the nominal wage for each household  $W_{h,t}^n$ , cost minimization yields a set of labor demand schedules  $l_{f,h,t} = \left( W_{h,t}^n / W_t^n \right)^{-\theta_w} l_{f,t}$  and the aggregate wage index  $W_t^n = \left( \int_0^1 W_{h,t}^{n \cdot 1-\theta_w} dh \right)^{1/(1-\theta_w)}$ .

Given the demand for labor by the labor packers, labor unions representing each household  $h$  set nominal wages on a staggered basis, as in Erceg, Henderson, and Levin (2000). In each period, a fraction  $1 - \xi_w \in (0, 1)$  of labor unions reoptimizes their nominal wages, whereas the remaining fraction  $\xi_w$  indexes nominal wages to the economy's trend growth  $\gamma_a$  and a weighted average of past inflation  $\Pi_{t-1}$  and steady-state inflation  $\bar{\Pi}$ . The labor unions that reoptimize their nominal wages in the current period then maximize expected utility as follows

$$\mathbb{E}_t \sum_{j=0}^{\infty} \xi_w^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \left[ \frac{\gamma_a^j W_{h,t}^n}{P_{t+j}} \prod_{k=1}^j (\Pi_{t+k-1}^{\iota_w} \bar{\Pi}^{1-\iota_w}) \Lambda_{h,t+j} l_{h,t+j} - \frac{l_{h,t+j}^{1+\eta}}{1+\eta} \right],$$

subject to the labor demand

$$l_{f,h,t+j} = \left[ \frac{\gamma_a^j W_{h,t}^n}{W_{t+j}^n} \prod_{k=1}^j (\Pi_{t+k-1}^{\iota_w} \bar{\Pi}^{1-\iota_w}) \right]^{-\theta_w} l_{f,t+j},$$

where  $l_{h,t} = \int_0^1 l_{f,h,t} df$  is the amount of labor supplied by each household  $h$ , and  $\iota_w \in [0, 1)$  is the weight of wage indexation to past inflation relative to steady-state inflation. The first-order condition for the reoptimized wage  $W_t^{n,o}$  is given by

$$\left( \frac{W_t^{n,o}}{W_t^n} \right)^{1+\eta\theta_w} = \frac{\theta_w}{\theta_w - 1} \frac{\mathbb{E}_t \sum_{j=0}^{\infty} \xi_w^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \left[ \left( \prod_{k=1}^j \Pi_{t+k-1}^{\iota_w} \bar{\Pi}^{1-\iota_w} \frac{\gamma_a^j W_t^n}{W_{t+j}^n} \right)^{-(1+\eta)\theta_w} l_{d,t+j}^{1+\eta} \right]}{\mathbb{E}_t \sum_{j=0}^{\infty} \xi_w^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \left[ \left( \prod_{k=1}^j \Pi_{t+k-1}^{\iota_w} \bar{\Pi}^{1-\iota_w} \frac{\gamma_a^j W_t^n}{W_{t+j}^n} \right)^{1-\theta_w} \Lambda_{t+j} \frac{W_{t+j}^n}{P_{t+j}} l_{d,t+j} \right]}, \quad (4)$$

where  $l_{d,t} = \int_0^1 l_{f,t} df$  is the total labor demand. The aggregate nominal wage index  $W_t^n = \left( \int_0^1 W_{h,t}^{n \cdot 1-\theta_w} dh \right)^{1/(1-\theta_w)}$  can be written as

$$W_t^n = \left[ (1 - \xi_w) (W_t^{n,o})^{1-\theta_w} + \xi_w (\Pi_{t-1}^{\iota_w} \bar{\Pi}^{1-\iota_w} \gamma_a W_{t-1}^n)^{1-\theta_w} \right]^{\frac{1}{1-\theta_w}}. \quad (5)$$

### 2.1.3 Firms

The representative final-good firm produces output  $Y_t$  under perfect competition by choosing a combination of intermediate inputs  $\{Y_{f,t}\}$  so as to maximize profit  $P_t Y_t - \int_0^1 P_{f,t} Y_{f,t} df$ , subject to a CES production technology  $Y_t = \left[ \int_0^1 Y_{f,t}^{(\theta_p-1)/\theta_p} df \right]^{\theta_p/(\theta_p-1)}$ , where  $P_{f,t}$  is the price of intermediate good  $f$  and  $\theta_p > 1$  denotes the elasticity of substitution among the variety of intermediate goods. The first-order condition for profit maximization yields the final-good firm's demand for each intermediate good  $Y_{f,t} = (P_{f,t}/P_t)^{-\theta_p} Y_t$  and the aggregate price index  $P_t = \left( \int_0^1 P_{f,t}^{1-\theta_p} df \right)^{1/(1-\theta_p)}$ .

Each intermediate-good firm  $f$  produces a differentiated good  $Y_{f,t}$  under monopolistic competition by choosing a labor input  $l_{f,t}$ , given the real wage  $W_t = W_t^n/P_t$ , and subject to the production function

$$Y_{f,t} = A_t l_{f,t},$$

where  $A_t$  represents total factor productivity. The log of the productivity level follows a nonstationary stochastic process

$$\log A_t = \log \gamma_a + \log A_{t-1} + a_t, \quad (6)$$

where  $\log \gamma_a$  represents the steady-state growth rate of productivity and  $a_t$  is a shock to the productivity growth. The productivity shock follows an AR(1) process

$$a_t = \rho_a a_{t-1} + \varepsilon_{a,t}, \quad (7)$$

where  $\rho_a \in [0, 1)$  is an autoregressive coefficient and  $\varepsilon_{a,t}$  is a normally distributed innovation with mean zero and standard deviation  $\sigma_a$ . Assuming the existence of a shock to real marginal cost  $z_t$ , which is interpreted as an inefficient cost-push shock, the first-order condition for cost minimization is given by<sup>6</sup>

$$MC_t = \frac{W_t}{A_t} z_t. \quad (8)$$

The log of the cost-push shock follows an AR(1) process

$$\log z_t = \rho_z \log z_{t-1} + \varepsilon_{z,t}, \quad (9)$$

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<sup>6</sup>The first-order condition also indicates that the real marginal cost  $MC_t$  is identical across the intermediate-good firms.



where  $\rho_z \in [0, 1)$  is an autoregressive coefficient and  $\varepsilon_{z,t}$  is a normally distributed innovation with mean zero and standard deviation  $\sigma_z$ .

In the face of the final-good firm's demand and marginal cost, the intermediate-good firms set the prices of their products on a staggered basis, as in Calvo (1983). In each period, a fraction  $1 - \xi_p \in (0, 1)$  of intermediate-good firms reoptimizes their prices, whereas the remaining fraction  $\xi_p$  indexes prices to a weighted average of past inflation  $\Pi_{t-1}$  and steady-state inflation  $\bar{\Pi}$ . The firms that reoptimize their prices in the current period then maximize expected profit as follows

$$\mathbb{E}_t \sum_{j=0}^{\infty} \xi_p^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \frac{\Lambda_{t+j}}{\Lambda_t} \left[ \frac{P_{f,t}}{P_{t+j}} \prod_{k=1}^j (\Pi_{t+k-1}^{\iota_p} \bar{\Pi}^{1-\iota_p}) - MC_{t+j} \right] Y_{f,t+j},$$

subject to the final-good firm's demand

$$Y_{f,t+j} = \left[ \frac{P_{f,t}}{P_{t+j}} \prod_{k=1}^j (\Pi_{t+k-1}^{\iota_p} \bar{\Pi}^{1-\iota_p}) \right]^{-\theta_p} Y_{t+j},$$

where  $\iota_p \in [0, 1)$  denotes the weight of price indexation to past inflation relative to steady-state inflation. The first-order condition for the reoptimized price  $P_t^o$  is given by

$$\frac{P_t^o}{P_t} = \frac{\theta}{\theta - 1} \frac{\mathbb{E}_t \sum_{j=0}^{\infty} \xi_p^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \frac{\Lambda_{t+j}}{\Lambda_t} \left[ \left( \prod_{k=1}^j \left[ \left( \frac{\Pi_{t+k-1}}{\bar{\Pi}} \right)^{\iota_p} \frac{\bar{\Pi}}{\Pi_{t+k}} \right] \right)^{-\theta_p} MC_{t+j} Y_{t+j} \right]}{\mathbb{E}_t \sum_{j=0}^{\infty} \xi_p^j \beta^j \left( \prod_{k=1}^j d_k \right)^{-1} \frac{\Lambda_{t+j}}{\Lambda_t} \left[ \left( \prod_{k=1}^j \left[ \left( \frac{\Pi_{t+k-1}}{\bar{\Pi}} \right)^{\iota_p} \frac{\bar{\Pi}}{\Pi_{t+k}} \right] \right)^{1-\theta_p} Y_{t+j} \right]}. \quad (10)$$

The final-good's price  $P_t = \left( \int_0^1 P_{f,t}^{1-\theta_p} df \right)^{1/(1-\theta_p)}$  can be written as

$$P_t = \left[ (1 - \xi_p) (P_t^o)^{1-\theta_p} + \xi_p (\Pi_{t-1}^{\iota_p} \bar{\Pi}^{1-\iota_p} P_{t-1})^{1-\theta_p} \right]^{\frac{1}{1-\theta_p}}. \quad (11)$$

#### 2.1.4 Market clearing conditions

The final-good market clearing condition is

$$Y_t = C_t, \quad (12)$$

whereas the labor market clearing condition leads to

$$l_t = \frac{\Delta_{p,t} \Delta_{w,t} Y_t}{A_t}, \quad (13)$$

where  $l_t = \int_0^1 \int_0^1 l_{f,h,t} df dh$  is the aggregate labor input,  $\Delta_{p,t} = \int_0^1 (P_{f,t}/P_t)^{-\theta_p} df$  is price dispersion across the intermediate-good firms, and  $\Delta_{w,t} = \int_0^1 \left( W_{h,t}^n / W_t^n \right)^{-\theta_w} dh$  is wage dispersion across the

labor unions. Equation (13) can be rewritten in terms of  $l_{d,t} = \int_0^1 l_{f,t} df$  as

$$l_{d,t} = \frac{\Delta_{p,t} Y_t}{A_t}. \quad (14)$$

In the present model, the price and wage dispersion evolve according to

$$\Delta_{p,t} = (1 - \xi_p) \left( \frac{P_t^o}{P_t} \right)^{-\theta_p} + \xi_p \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{\theta_p} \left( \frac{\Pi_{t-1}}{\bar{\Pi}} \right)^{-\iota_p \theta_p} \Delta_{p,t-1}, \quad (15)$$

$$\Delta_{w,t} = (1 - \xi_w) \left( \frac{W_t^{n,o}}{W_t^n} \right)^{-\theta_w} + \xi_w \left( \frac{\Pi_t W_t}{\bar{\Pi} \gamma_a W_{t-1}} \right)^{\theta_w} \left( \frac{\Pi_{t-1}}{\bar{\Pi}} \right)^{-\iota_w \theta_w} \Delta_{w,t-1}. \quad (16)$$

### 2.1.5 Flexible wage and price equilibrium

Natural output  $Y_t^*$  and the natural rate of interest  $R_t^*$  are defined as the levels that would prevail if both wages and prices were perfectly flexible with no cost-push shocks. Such a flexible wage and price equilibrium is obtained with  $\xi_w = \xi_p = 0$ ,  $W_{h,t}^n = W_t^n$ ,  $P_{f,t} = P_t$ , and  $z_t = 1$  for all  $h, f$ , and  $t$  in the model above and is characterized by the following equations:

$$(Y_t^* - \gamma Y_{t-1}^*) \left( \frac{Y_t^*}{A_t} \right)^\eta = \mu A_t, \quad (17)$$

$$R_t^* = \frac{d_t}{\beta} \left( \mathbb{E}_t \frac{Y_t^* - \gamma Y_{t-1}^*}{Y_{t+1}^* - \gamma Y_t^*} \right)^{-1}, \quad (18)$$

where  $\mu = \frac{\theta_w - 1}{\theta_w} \frac{\theta_p - 1}{\theta_p}$  is the product of price and wage markups. Thus, the law of motion for natural output  $Y_t^*$  is determined by (17), given the sequence of total factor productivity  $A_t$ . The natural rate of interest  $R_t^*$  is determined by (18), given the sequences of natural output  $Y_t^*$  and the discount factor shock  $d_t$ .

### 2.1.6 Central bank

A monetary policy rule is specified as

$$R_t^n = \max[\hat{R}_t^n, 1], \quad (19)$$

where

$$\hat{R}_t^n = (\hat{R}_{t-1}^n)^{\phi_r} \left[ \bar{R} \bar{\Pi} \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{\phi_\pi} \left( \frac{Y_t}{A_t} \right)^{\phi_y} \left( \frac{Y_t}{\gamma_a Y_{t-1}} \right)^{\phi_{\Delta y}} \right]^{1-\phi_r} \exp(\varepsilon_{r,t}). \quad (20)$$

$\hat{R}_t^n$  denotes the notional nominal interest rate that the central bank would set according to a Taylor (1993) type monetary policy rule in the absence of the ZLB constraint, where  $\bar{R}$  is the steady-state

gross real interest rate,  $\phi_r \in [0, 1)$  is the policy-smoothing parameter, and  $\phi_\pi \geq 0$ ,  $\phi_y \geq 0$ , and  $\phi_{\Delta y} \geq 0$  are the degrees of the interest rate policy response to inflation, detrended output, and output growth.  $\varepsilon_{r,t}$  is a monetary policy shock, which is normally distributed with mean zero and standard deviation  $\sigma_r$ . The max function in (19) constrains the nominal interest rate to be greater than or equal to zero. If  $\hat{R}_t^n > 1$ , the ZLB constraint is not imposed, i.e.,  $R_t^n = \hat{R}_t^n$ . If  $\hat{R}_t^n \leq 1$ , the ZLB is binding, i.e.,  $R_t^n = 1$ .

### 2.1.7 Equilibrium

An equilibrium is given by the sequences  $\{Y_t, C_t, \Lambda_t, W_t, W_t^n, W_t^{n,o}, l_t, l_{d,t}, MC_t, \Pi_t, P_t, P_t^o, \Delta_{p,t}, \Delta_{w,t}, Y_t^*, R_t^*, R_t^n, \hat{R}_t^n, d_t, A_t, a_t, z_t\}_{t=0}^\infty$  satisfying the equilibrium conditions (1)–(20) and two definitional equations,  $W_t = W_t^n/P_t$  and  $\Pi_t = P_t/P_{t-1}$ .

Because total factor productivity  $A_t$  is nonstationary, as specified by (6), we rewrite the equilibrium conditions in terms of stationary variables detrended by  $A_t$ , as follows:  $y_t = Y_t/A_t$ ,  $c_t = C_t/A_t$ ,  $\lambda_t = \Lambda_t A_t$ ,  $w_t = W_t/A_t$ ,  $w_t^n = W_t^n/A_t$ ,  $w_t^{n,o} = W_t^{n,o}/A_t$ ,  $mc_t = MC_t/A_t$ , and  $y_t^* = Y_t^*/A_t$ , so that we can derive a nonstochastic steady state for the detrended variables.

## 2.2 Estimation of parameters

To parameterize the model, we estimate a piecewise linear version of the model, in which the ZLB constraint is imposed but all the equilibrium conditions are linearized. More specifically, such a piecewise linear model is solved using the OccBin toolbox developed by Guerrieri and Iacoviello (2015), and the likelihood function is evaluated with the inversion filter following Guerrieri and Iacoviello (2017). While it is computationally very intensive to estimate a fully nonlinear model using a projection method and a particle filter, the piecewise linear approach considerably reduces the computational burden. Regarding estimation accuracy, Atkinson, Richter, and Throckmorton (2020) demonstrate that the piecewise linear and fully-nonlinear approaches result in similar parameter estimates.

The model is fitted to four U.S. quarterly time series: the per capita real GDP growth rate ( $100\Delta \log GDP_t$ ), the inflation rate of the GDP implicit price deflator ( $100\Delta \log PGDP_t$ ), the

federal funds rate ( $FF_t$ ), and the log of hours worked ( $100 \log H_t$ ).<sup>7</sup> Following Wolters (2018), the data on hours worked is adjusted for low-frequency movements due to sectoral and demographic changes so that the data is consistent with the model. The sample period is from 1987:III to 2016:III. The beginning of the sample period is set at the time when Alan Greenspan became the Chairman of the Fed, because thereafter, the style of the Fed’s policy conduct seems consistent and stable. The linearized equilibrium conditions and observation equations are presented in Appendix A.

The parameters are estimated using Bayesian methods. The prior distributions of parameters are presented in the second to fourth columns of Table 1. For most of the parameters, each prior mean is set at the corresponding prior mean used in the literature including Smets and Wouters (2007). The prior mean of the policy-smoothing parameter  $\phi_r$  is set at 0.5, which is lower than that in Smets and Wouters (2007) because a higher value of the estimated  $\phi_r$  would lead to a nonconvergence problem in the next step for solving our nonlinear model.<sup>8</sup> As for the steady-state values of output growth, inflation, and real interest rates and hours worked  $(\bar{a}, \bar{\pi}, \bar{r}, \bar{l})$ , the priors are centered at the sample mean. The prior mean of the AR(1) coefficient for the discount factor shock  $\rho_d$  is 0.75, whereas those for the productivity and cost-push shocks  $(\rho_a, \rho_z)$  is 0.5. For the standard deviations of the shocks  $(100\sigma_d, 100\sigma_a, 100\sigma_z, 100\sigma_r)$ , we assign inverse-gamma distributions with a mean of 0.5 and a standard deviation of 2.0.

Following Guerrieri and Iacoviello (2017), 50,000 posterior draws are generated using the Random-Walk Metropolis-Hastings algorithm, and the first 10,000 draws are discarded. The posterior mean and 90 percent credible interval for each parameter are reported in the middle columns labeled “Piecewise linear” of Table 1. For the sake of comparison, we estimate a linear version of the model that omits the ZLB constraint, and the results are shown in the last two columns of Table 1. The parameter estimates are similar to each other. Looking into the details, however, we find that the posterior mean estimates of the monetary policy response to inflation  $\phi_\pi$  and the steady-state inflation rate  $\bar{\pi}$  are larger in the piecewise linear model. This finding is consistent with the main result in Hirose and Inoue (2016), who conduct a Monte Carlo analysis and demonstrate

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<sup>7</sup>The series of hours worked is demeaned.

<sup>8</sup>For the same reason, relatively tight priors are used for the parameters that determine the persistency of endogenous variables in the model.

Table 1: Prior and posterior distributions of parameters

Parameter	Prior			Posterior			
	Distribution	Mean	S.D.	Piecewise linear		Linear (No ZLB)	
				Mean	90% interval	Mean	90% interval
$\gamma$	Beta	0.500	0.050	0.663	[0.609, 0.718]	0.648	[0.587, 0.707]
$\eta$	Gamma	2.000	0.250	1.854	[1.477, 2.277]	1.902	[1.509, 2.350]
$\xi_w$	Beta	0.500	0.050	0.726	[0.661, 0.771]	0.713	[0.636, 0.766]
$\iota_w$	Beta	0.500	0.050	0.487	[0.405, 0.569]	0.498	[0.415, 0.579]
$\xi_p$	Beta	0.500	0.050	0.829	[0.778, 0.872]	0.815	[0.766, 0.864]
$\iota_p$	Beta	0.500	0.050	0.483	[0.398, 0.573]	0.503	[0.413, 0.593]
$\phi_\pi$	Gamma	1.500	0.250	1.663	[1.424, 1.921]	1.606	[1.362, 1.875]
$\phi_y$	Gamma	0.500	0.100	0.166	[0.139, 0.193]	0.138	[0.117, 0.160]
$\phi_{\Delta y}$	Gamma	0.125	0.050	0.227	[0.130, 0.338]	0.253	[0.145, 0.366]
$\phi_r$	Beta	0.500	0.050	0.743	[0.702, 0.784]	0.792	[0.757, 0.824]
$\bar{a}$	Normal	0.337	0.100	0.318	[0.226, 0.410]	0.339	[0.245, 0.432]
$\bar{\pi}$	Normal	0.536	0.100	0.608	[0.512, 0.709]	0.548	[0.440, 0.653]
$\bar{r}$	Gamma	0.314	0.100	0.232	[0.160, 0.312]	0.246	[0.169, 0.326]
$\bar{l}$	Normal	0.000	0.100	0.037	[-0.123, 0.201]	0.014	[-0.142, 0.170]
$\rho_d$	Beta	0.750	0.050	0.828	[0.794, 0.860]	0.848	[0.815, 0.878]
$\rho_a$	Beta	0.500	0.050	0.415	[0.351, 0.482]	0.414	[0.349, 0.484]
$\rho_z$	Beta	0.500	0.050	0.603	[0.521, 0.681]	0.626	[0.538, 0.709]
$100\sigma_d$	Inv. Gamma	0.500	2.000	0.434	[0.333, 0.563]	0.376	[0.287, 0.493]
$100\sigma_a$	Inv. Gamma	0.500	2.000	0.566	[0.507, 0.631]	0.565	[0.506, 0.630]
$100\sigma_z$	Inv. Gamma	0.500	2.000	4.495	[2.600, 7.173]	3.988	[2.375, 6.670]
$100\sigma_r$	Inv. Gamma	0.500	2.000	0.126	[0.109, 0.145]	0.113	[0.101, 0.128]

Note: Each posterior mean and 90% credible interval are calculated from 50,000 draws (the first 10,000 draws are discarded) generated using the Metropolis-Hastings algorithm.

that omitting the ZLB in estimation causes biased estimates of these parameters.

In the subsequent analysis, the parameters are fixed at the posterior mean estimates of the piecewise linear model.

### 2.3 Nonlinear solution and filtering

Given the posterior mean estimates for the piecewise linear model obtained above, the model is solved in a fully nonlinear and stochastic setting with the ZLB constraint using a projection method. The model has seven endogenous state variables (output  $y_{t-1}$ , inflation  $\Pi_{t-1}$ , the real wage  $w_{t-1}$ , the notional nominal interest rate  $\hat{R}_{t-1}^n$ , price dispersion  $\Delta_{p,t-1}$ , wage dispersion  $\Delta_{w,t-1}$ , and natural output  $y_{t-1}^*$ ) and four exogenous shocks (the discount factor shock  $d_t$ , the productivity shock  $a_t$ , the cost-push shock  $z_t$ , and the monetary policy shock  $\varepsilon_{r,t}$ ). The policy functions satisfying the detrended equilibrium conditions can be written as

$$\mathbb{S}_t = g(\mathbb{S}_{t-1}, \tau_t),$$

where  $\mathbb{S}_{t-1} = [y_{t-1}, \Pi_{t-1}, w_{t-1}, \hat{R}_{t-1}^n, \Delta_{p,t-1}, \Delta_{w,t-1}, y_{t-1}^*]'$  and  $\tau_t = [d_t, a_t, z_t, \varepsilon_{r,t}]'$ .

To compute the policy functions, we employ a projection method with an index function approach as in Aruoba, Cuba-Borda, and Schorfheide (2018), Gust, Herbst, López-Salido, and Smith (2017) and Nakata (2017). For interpolating the policy functions within a time iteration algorithm, we adapt a standard linear interpolation to reduce approximation errors that tend to be large particularly when the ZLB binds due to large negative shocks to the economy.<sup>9</sup> The details of the solution method are described in Appendix B.

According to an artificial sample of 40,000 periods simulated from the nonlinear solution of the model, the economy is at the ZLB for 7.6 percent of quarters, and the average duration of ZLB spells is 3.9 quarters. These statistics indicate that our model economy is more frequently constrained by the ZLB and that the average duration of ZLB spells is longer than the simulation results in the previous studies that employ nonlinear New Keynesian models, such as Fernández-Villaverde, Gordon, Guerrón-Quintana, and Rubio-Ramírez (2015) and Gust, Herbst, López-Salido, and Smith

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<sup>9</sup>Because of the high dimensionality of state variables, we use a supercomputer system to utilize parallel computing.

(2017).<sup>10</sup> This is mainly because the steady-state real interest in our model (below one percent), which is set at its mean estimate for the recent sample from 1987 to 2016, is lower than that in their models (roughly 2.5 percent). Given the steady-state inflation rate, the low steady-state real interest rate depresses the nominal interest rate and makes it more likely to hit the ZLB.

We apply a particle filter as in Fernández-Villaverde and Rubio-Ramírez (2007) to extract the sequence of the state variables and then compute the estimates of the natural interest rate.<sup>11</sup> The data used for filtering is the same as those used for the parameter estimation in Section 2.2. To facilitate the use of the particle filter, measurement errors are added in the observation equations. The size of the measurement errors of output growth, inflation, the nominal interest rate, and hours worked are respectively set to be one percent of the standard deviations of the data so that we can reduce the effect of measurement errors on the filtered estimates of the natural interest rate and its related variables. We use 100,000 particles and confirmed that any further increase in the number of particles delivered almost the same results as those presented below.

### 3 Results

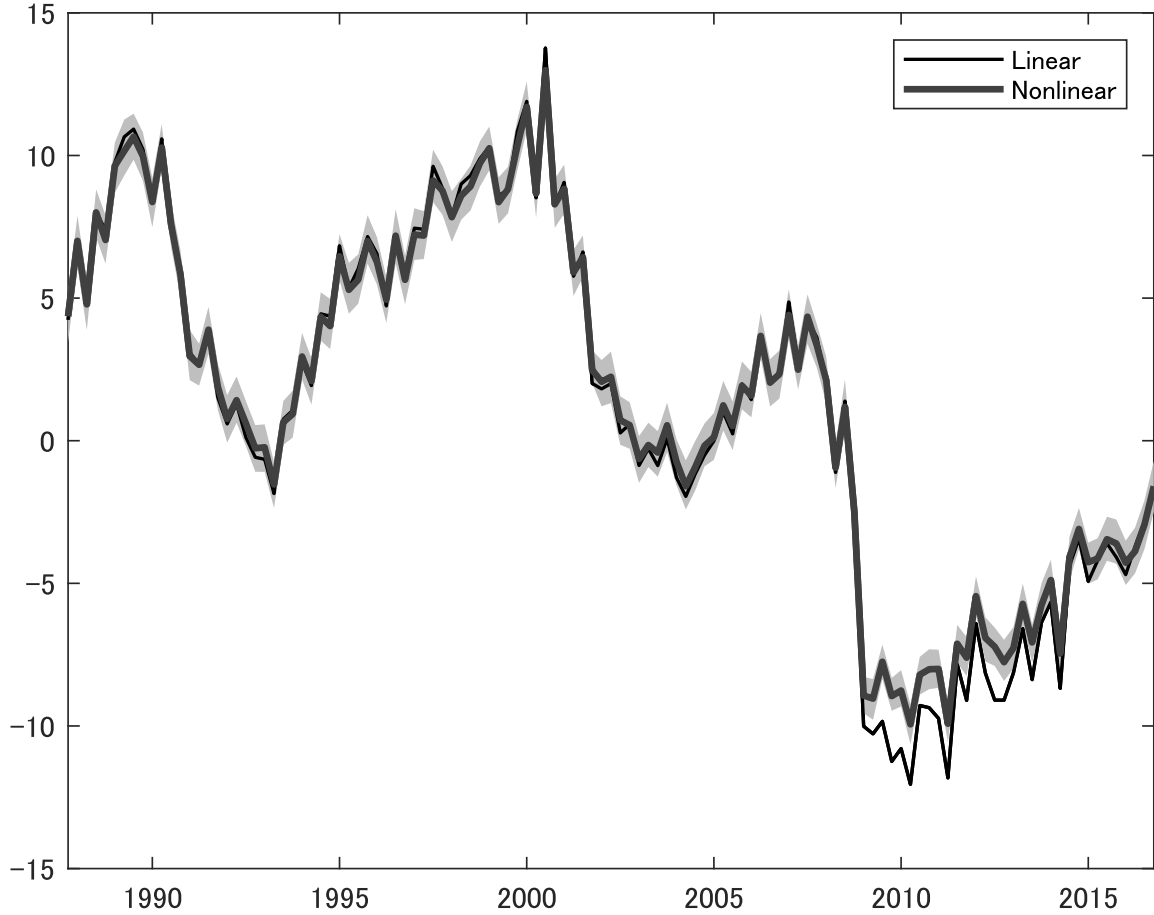
This section presents the estimate of the natural interest rate based on the nonlinear model and compares it with that based on its linear counterpart. To understand the source of the difference between the two estimates, we investigate how the natural rate of interest is identified in each case. Moreover, we consider the piecewise linear model, which is used for estimating model parameters, to examine whether it can be a useful substitute for estimating the natural rate accurately.

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<sup>10</sup>Fernández-Villaverde, Gordon, Guerrón-Quintana, and Rubio-Ramírez (2015) simulate a small-scale model calibrated for the U.S. economy and show that the economy spends 5.5 percent of quarters at the ZLB and that the average duration at the ZLB is 2.1 quarters. Gust, Herbst, López-Salido, and Smith (2017) estimate a medium-scale model in a nonlinear setting using U.S. data from 1983:I to 2014:I, and the simulation of their estimated model demonstrates that the economy is at the ZLB for about 4 percent of quarters on average and that the average duration of the ZLB spells is just over 3.5 quarters.

<sup>11</sup>For a textbook treatment of a particle filter, see Fernández-Villaverde, Rubio-Ramírez, and Schorfheide (2016) or Herbst and Schorfheide (2015).

Figure 1: Natural rate of interest



Note: The figure shows the filtered mean estimate of the natural interest rate, in annualized percentage terms, based on the nonlinear model (thick solid line) with its 90 percent interval (shaded area) and that based on the linear model (thin solid line).

### 3.1 Estimated natural rate of interest

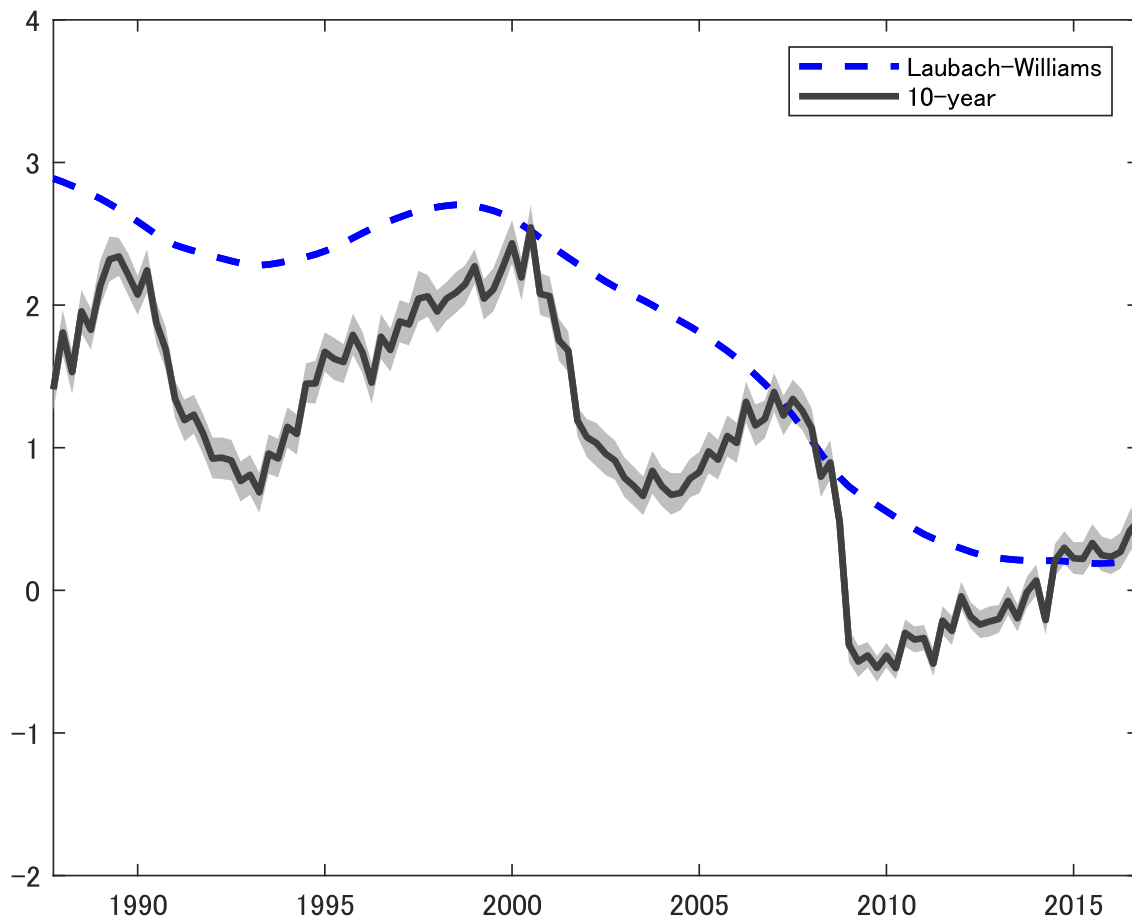
The thick solid line in Figure 1 shows the filtered mean estimate of the natural rate of interest on an annualized basis, based on the nonlinear model. The gray shaded area is the 90 percent interval obtained from the distributions of particles in each period. The estimated natural rate measure peaked more than 10 percent at the end of 1980s and the beginning of 2000, then fell to about  $-9$  percent in the aftermath of the global financial crisis, and thereafter increased to nearly zero toward the end of the sample period.<sup>12</sup> The overall cyclical movements and variability of the

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<sup>12</sup>In an earlier version of this paper (Hirose and Sunakawa, 2017), the estimates of the natural rate were too volatile,



Figure 2: Long-run natural rate of interest



Note: The figure shows the filtered mean estimate of the 10-year natural interest rate, in annualized percentage terms, based on the nonlinear model (solid line) with its 90 percent interval (shaded area) and the estimate of the natural interest rate based on Laubach-Williams (2003) model (dashed line).

natural rate are similar to those estimated by Barsky, Justiniano, and Melosi (2014), who employ a medium-scale New Keynesian DSGE model with capital accumulation.

In the present framework, the natural interest rate is driven by structural shocks and hence exhibits short-run fluctuations. To make it comparable to the estimates of the long-run natural rate based on a semi-structural or reduced-form model as in Laubach and Williams (2003), we calculate

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ranging from  $-15$  to  $15$  percent. This issue was resolved by employing the hours data constructed by Wolters (2018). As mentioned in Section 2.2, the data is adjusted for sectoral and demographic changes, and hence it is less volatile than the original data.

the 10-year natural rate  $R_t^{*10Y}$  according to the expectation hypothesis of the term structure of interest rates

$$\log R_t^{*10Y} = \frac{1}{40} \sum_{i=0}^{39} \mathbb{E}_t \log R_{t+i}^*.$$

Figure 2 compares the filtered mean estimate of the 10-year natural rate based on the nonlinear model (solid line) with the estimate of the natural rate based on Laubach-Williams (2003) model (dashed line, henceforth, the LW estimate).<sup>13</sup> Two notable differences emerge. First, the 10-year natural rate is more volatile than the LW estimate. Second, the 10-year natural rate is mostly lower than the LW estimate throughout the sample period, whereas these two estimates are almost the same in the last few years. The second difference arises because of the difference in the estimation sample. The sample for the LW estimate begins in 1961:I, and hence the steady-state real interest rate in their model is estimated to be higher than that in our model.

The primary objective of this paper is to examine how and to what extent nonlinearities, including the ZLB, affect the estimates of the natural interest rate. To this end, we estimate the natural rate using a linear counterpart of the model, as in the previous studies, and compare it with the one obtained above. The thin solid line in Figure 1 shows the filtered estimate of the natural interest rate based on the linearized version of the model with the same parameters and data set as used in the nonlinear case.<sup>14</sup> The figure indicates that the natural rate based on the linear model is mostly very similar to that based on the nonlinear model, except for the period after 2009, when the actual nominal interest rate was bounded at virtually zero. The difference amounts to more than 2 percent during 2009 and remains substantial thereafter.

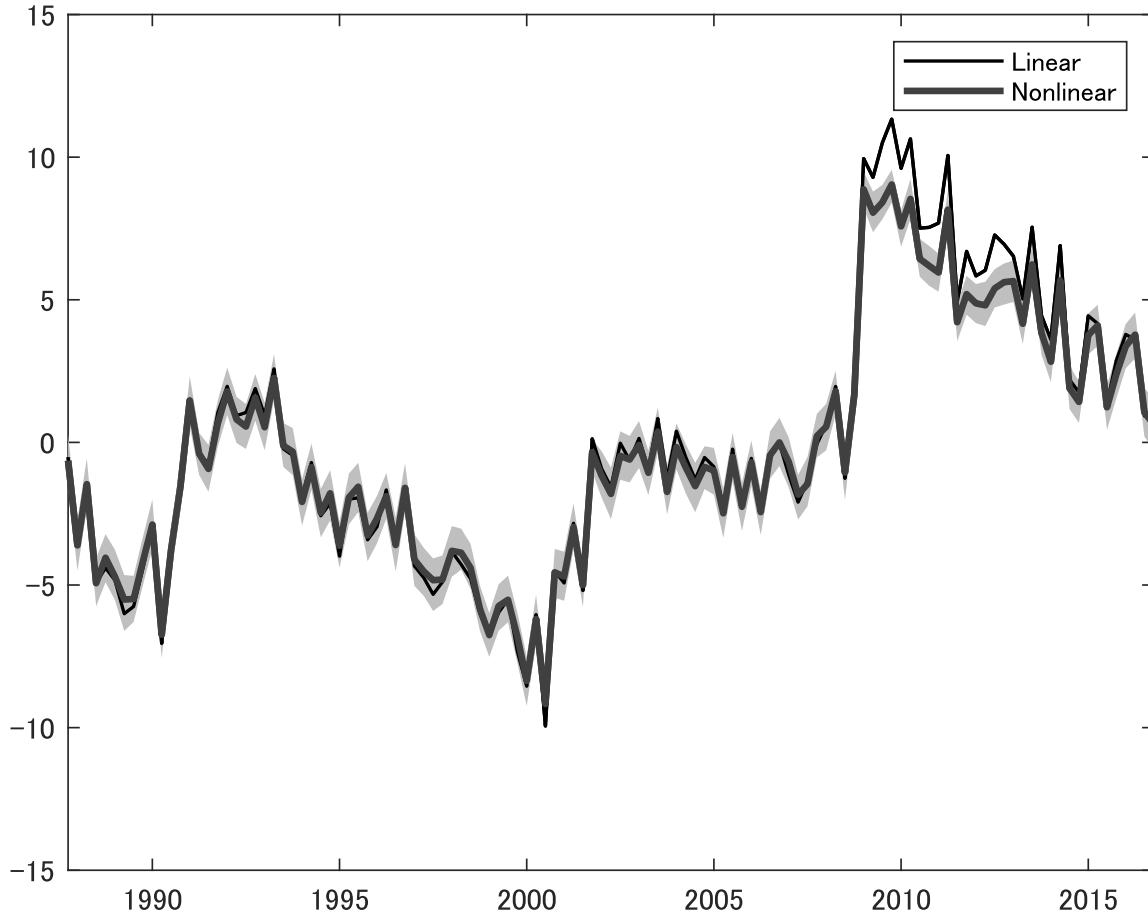
This difference matters when we evaluate the Fed’s monetary policy stance after the global financial crisis. In the present framework, the natural interest rate is a benchmark for whether monetary policy is too tight or too loose from a welfare perspective. Such a policy stance is

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<sup>13</sup>The latter estimate is available at the website of the Federal Reserve Bank of New York.

<sup>14</sup>In the linear setting, the model is solved by the standard linear solution method and the filtered estimates of model variables are computed using the Kalman filter with zero measurement errors. As a preliminary analysis, we applied a particle filter to the linear model and obtained a very similar estimate of the natural rate. Thus, we confirmed that the difference in the filtering methods with and without measurement errors is not the major source of the difference in the estimated natural rates between the linear and nonlinear models.

Figure 3: Interest rate gap



Note: The figure shows the real interest rate gap, in annualized percentage terms, based on the nonlinear model (thick solid line) with its 90 percent interval (shaded area) and that based on the linear model (thin solid line).

measured by the interest rate gap—the difference between the actual (ex-post) real interest rate and the natural rate. A larger value of the interest rate gap indicates a tighter policy stance. As shown in Figure 3, both measures of the interest rate gap were around zero from 2002 to 2008, but thereafter jumped to about 10 percent. More precisely, while the gap in the nonlinear model increased to 9 percent, its linear counterpart increased to 11 percent. These jumps are due to the existence of the ZLB; that is, the Fed was not able to lower the policy rate any more in response to the severe economic downturn, and hence the policy stance was evaluated to be too tight. In this context, if we relied on the linear model, the estimated natural rate and the resulting interest rate gap would overestimate the tightness of the policy stance by more than 20 percent ( $\equiv (11 - 9)/9$ ).

### 3.2 What accounts for the difference?

To understand what causes the difference between the two estimates of the natural interest rate, we consider how the natural rate is identified in each case. As addressed in Section 2.1, equation (17), i.e.,  $(Y_t^* - \gamma Y_{t-1}^*)(Y_t^*/A_t)^\eta = \mu A_t$ , determines natural output  $Y_t^*$ , given the sequence of total factor productivity  $A_t$  (or, equivalently, the productivity shock  $a_t$ ). The natural rate  $R_t^*$  can be traced out from equation (18), i.e.,  $R_t^* = d_t/\beta [\mathbb{E}_t(Y_t^* - \gamma Y_{t-1}^*)/(Y_{t+1}^* - \gamma Y_t^*)]^{-1}$ , given the sequences of natural output  $Y_t^*$  and the discount factor shock  $d_t$ . Thus, the natural rate is pinned down by identifying the two shocks,  $a_t$  and  $d_t$ .

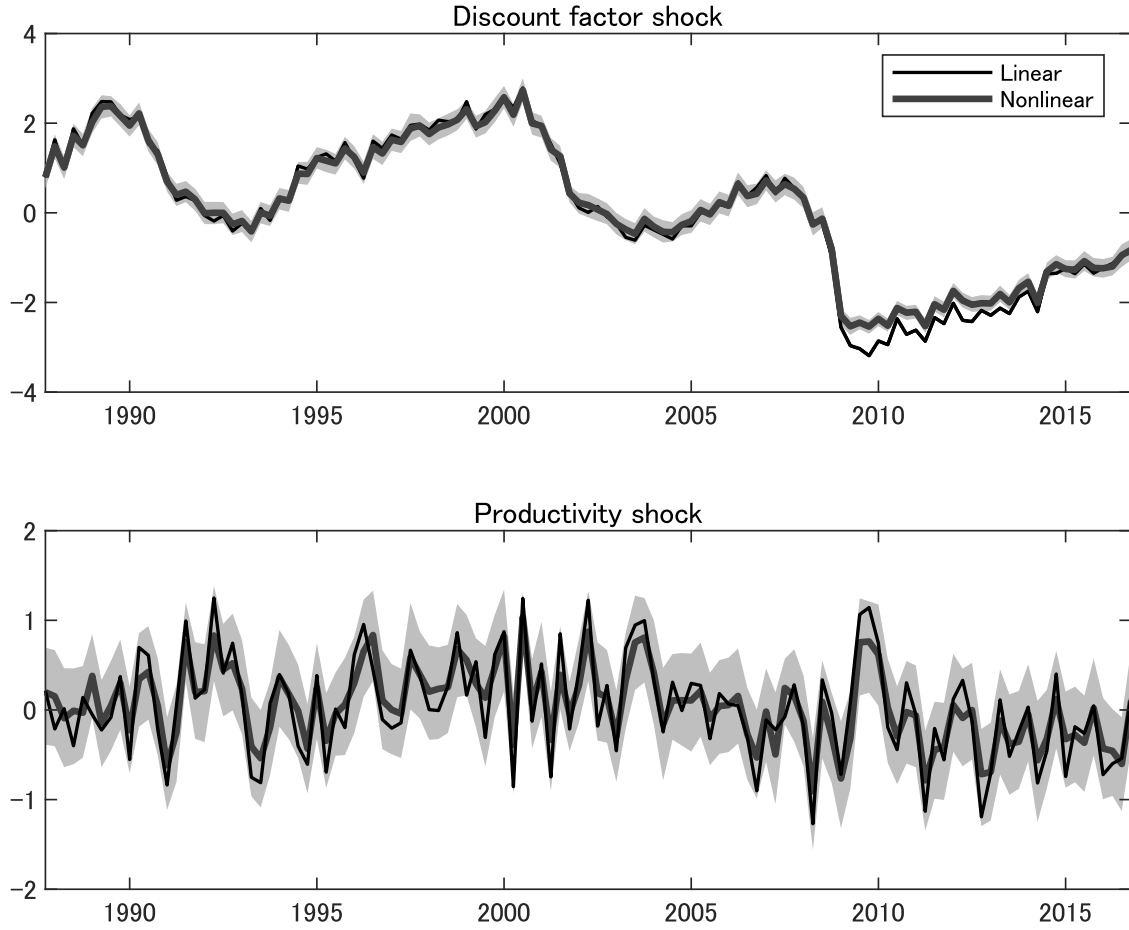
In the linear model, the productivity shock  $a_t$  is explicitly identified by the data on output and hours worked because detrending and log-linearizing the labor market clearing condition (13) yields  $\tilde{y}_t = \tilde{l}_t$  and because the associated observation equations are  $100\Delta \log GDP_t = \bar{a} + \tilde{y}_t - \tilde{y}_{t-1} + a_t$  and  $100 \log H_t = \bar{l} + \tilde{l}_t$ , where  $\bar{a}$  and  $\bar{l}$  are the steady-state growth rate and hours worked, respectively, and the variables with  $\sim$  represent percentage deviations from their steady-state values. In the nonlinear model, however, equation (13) contains the price and wage dispersion,  $\Delta_{p,t}$  and  $\Delta_{w,t}$ , and can be written as  $y_t = l_t/(\Delta_{p,t}\Delta_{w,t})$  in detrended terms. These dispersion terms fluctuate so that  $\Delta_{p,t} \geq 1$  and  $\Delta_{w,t} \geq 1$ , as the price and wage deviate from the steady state. Thus,  $y_t$  becomes lower than in the linear case where the dispersion terms are suppressed. Consequently, to satisfy the observation equation for output growth,  $a_t$  is identified to be larger in the nonlinear case. From equations (17) and (18), higher productivity raises natural output and results in the higher estimate of the natural rate.

Identification of the discount factor shock  $d_t$  is more complicated and influenced by the whole structure of the model. However, taking account of the finding that the two estimates of the natural interest rate differ from each other during the periods when the nominal interest rate was bounded at zero, the existence of the ZLB, from which the linear model abstracts, possibly affects the identification of  $d_t$  in the nonlinear model. The literature has established that the ZLB has a contractionary effect on the economy not only when the nominal interest is already binding at zero, but also when uncertainty exists about whether the ZLB will bind in the future.<sup>15</sup> Although

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<sup>15</sup>Hills, Nakata, and Schmidt (2016) quantify such an uncertainty effect on inflation in the face of the interest rate lower bound.

Figure 4: Estimated shocks

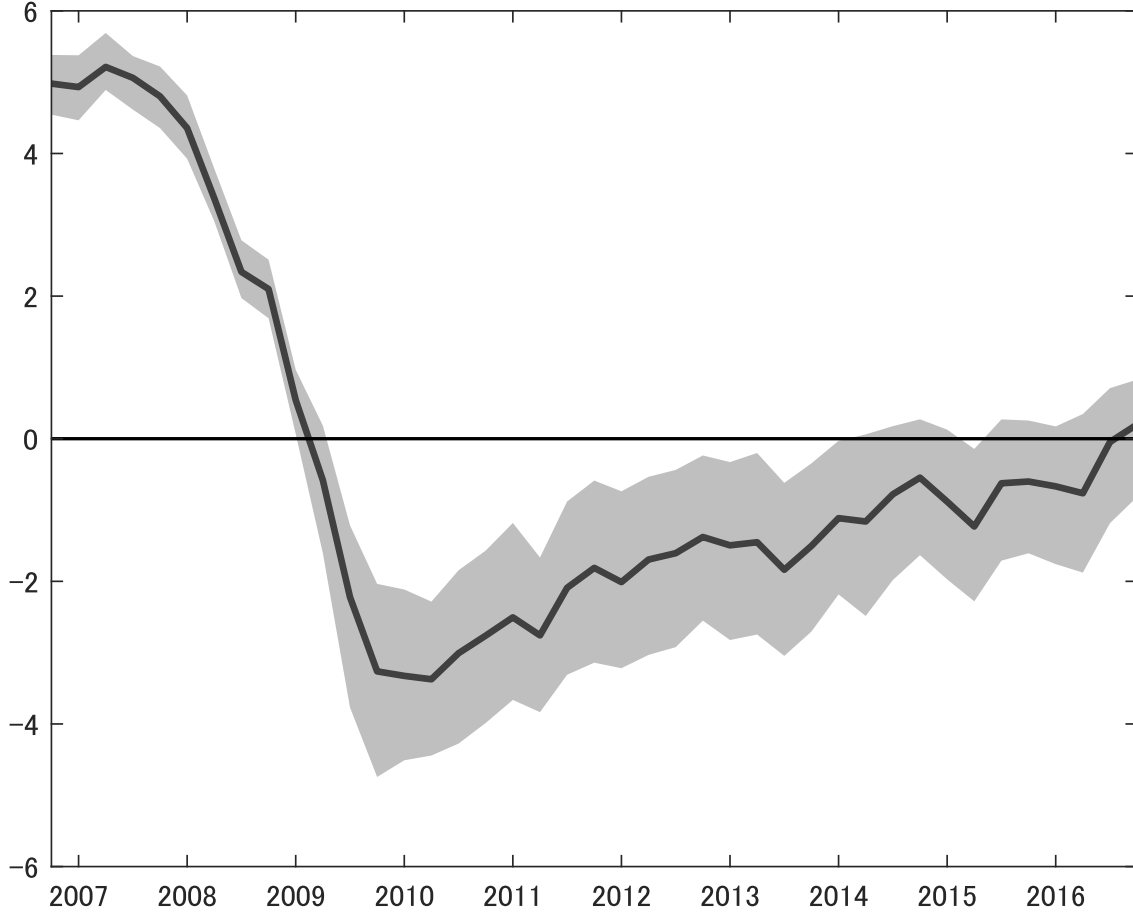


Note: The figure shows the filtered mean estimates of the discount factor shocks  $d_t$  and the productivity shocks  $a_t$ , in percentage terms, based on the nonlinear model (thick solid lines) with their 90 percent intervals (shaded areas) and those based on the linear model (thin solid lines).

such a contractionary effect lowers expected output and inflation, the filtering procedure pegs contemporaneous output and inflation to the corresponding observables, which are the same in the linear and nonlinear cases. Then, in the nonlinear case, the discount factor shock  $d_t$  must increase to satisfy the consumption Euler equation that equalize the marginal utility of consumption today with the expected discounted one in the future. As a result, the estimated natural rate becomes higher.

To quantify the differences in the sequences of identified shocks, Figure 4 shows the filtered mean estimates of the discount factor shocks  $d_t$  and the productivity shocks  $a_t$ , in percentage

Figure 5: Notional rate

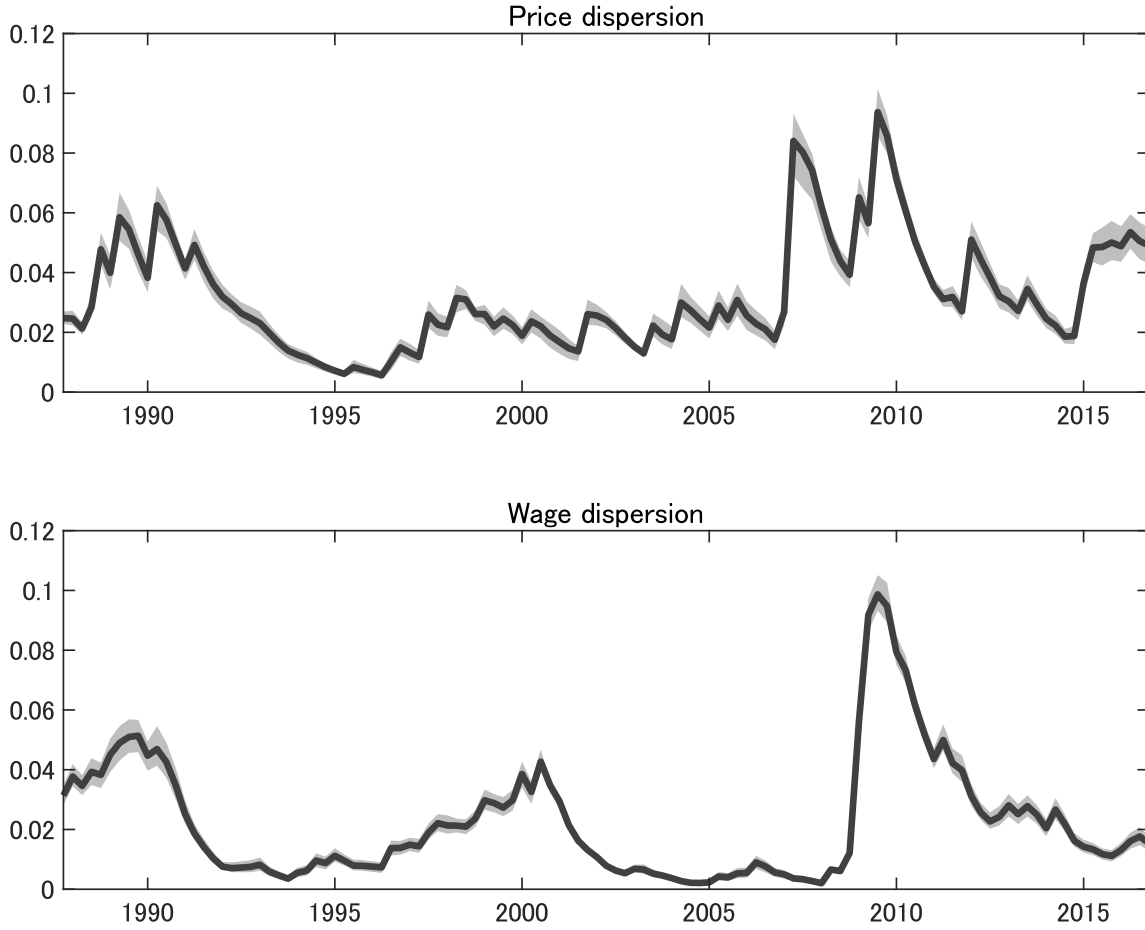


Note: The figure shows the filtered mean estimate of the notional nominal interest rate and its 90 percent interval (shaded area), in annualized percentage terms.

terms, based on the nonlinear model (thick solid lines) and its linear counterpart (thin solid lines). The gray shaded areas are the 90 percent intervals for the filtered estimates in the nonlinear model. The sequence of  $d_t$  identified in the nonlinear model is remarkably different from that in the linear model after the global financial crisis. In particular, the difference is pronounced in 2009–2010, when the notional nominal interest rate  $\hat{R}_t^n$  sharply fell below zero, as shown in Figure 5. Thus, whether the ZLB constraint is imposed or not substantially affects the identification of  $d_t$ .

On the other hand, the movements of the productivity shocks  $a_t$  are very similar between the two estimates although temporary deviations are found. The finding of the small difference in  $a_t$  implies that the price and wage dispersion terms,  $\Delta_{p,t}$  and  $\Delta_{w,t}$ , play a minor role in the nonlinear

Figure 6: Price and wage dispersion



Note: The figure shows the filtered mean estimates of the price and wage dispersion and their 90 percent intervals (shaded areas) in terms of percentage deviation from the steady state.

model. Indeed, as shown in Figure 6, the estimates of  $\Delta_{p,t}$  and  $\Delta_{w,t}$  based on the nonlinear model fluctuate little, i.e., 0.1 percent at most, even though they exhibit cyclical movements over the sample period.

### 3.3 The natural rate of interest based on the piecewise linear model

The analysis thus far suggests that the existence of the ZLB constraint plays a crucial role in identifying the natural interest rate in a nonlinear setting, but that the role of price and wage dispersion is negligible. These findings tempt researchers to exploit a piecewise linear model, in which the ZLB constraint is imposed but all the equilibrium conditions are linearized, for estimating

the natural rate measures, because such a model is easier to solve than a fully nonlinear model. While the literature argues that the solution for this sort of piecewise linear models can give rise to an inaccurate assessment of the ZLB,<sup>16</sup> Atkinson, Richter, and Throckmorton (2020) demonstrate that the piecewise linear and fully-nonlinear approaches lead to similar results with regard to parameter estimates. In what follows, we examine whether the piecewise linear model can be a useful substitute for estimating the natural rate.

As in the estimation of parameters described in Section 2.2, the piecewise linear version of the model is solved using the OccBin toolbox, and the filtered estimates are computed using the inversion filter.<sup>17</sup> Figure 7 depicts the filtered estimate of the natural interest rate in the piecewise linear setting (dashed line) along with the estimates in the fully nonlinear (thick solid line) and linear (thin solid line) settings. The estimate based on the piecewise linear model coincides with that based on the linear model before the global financial crisis, but in the aftermath, it is very close to that based on the fully nonlinear model. Thus, the higher estimate of the natural rate in the nonlinear model from 2009 to 2011 is well replicated by the piecewise linear model.

However, the natural rate in the piecewise linear model moves closer to that in the linear model after 2012, when the notional rate shown in Figure 5 approached toward zero. This is because the OccBin solution, by its construction, does not take into account uncertainty about the future. An uncertainty effect enhances the contractionary effect of the ZLB because agents expect that monetary policy will be unable to accommodate negative shocks to the economy. As addressed in the previous subsection, the contractionary effect of the ZLB leads to the higher estimate of the natural rate in the nonlinear model. This effect is reduced in the absence of uncertainty, and hence the piecewise linear model slightly underestimates the natural rate.

These mechanisms are confirmed by the upper panel in Figure 8. The estimated series of the discount factor shock  $d_t$  in the piecewise linear model (dashed line) is substantially larger than that in the linear model (thin solid line) for a few years after the global financial crisis, whereas it is

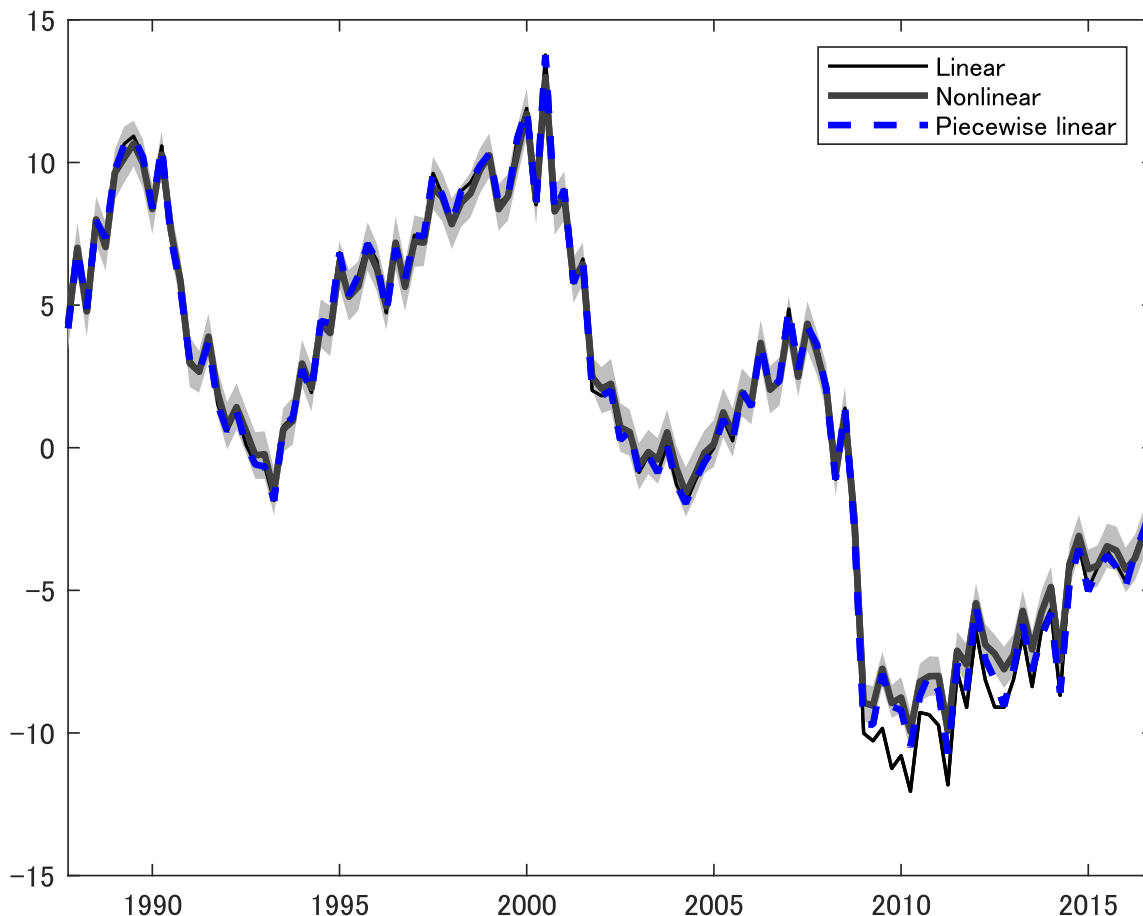
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<sup>16</sup>See Boneva, Braun, and Waki (2016), Fernández-Villaverde, Gordon, Guerrón-Quintana, and Rubio-Ramírez (2015), Gavin, Keen, Richter, and Throckmorton (2015), Gust, López-Salido, and Smith (2017), Nakata (2016, 2017), Ngo (2014), and Richter and Throckmorton (2016a).

<sup>17</sup>To run the inversion filter, the measurement errors are set to zero as in the Kalman filter for the linear model.



Figure 7: Natural rate of interest: Comparison with piecewise linear model



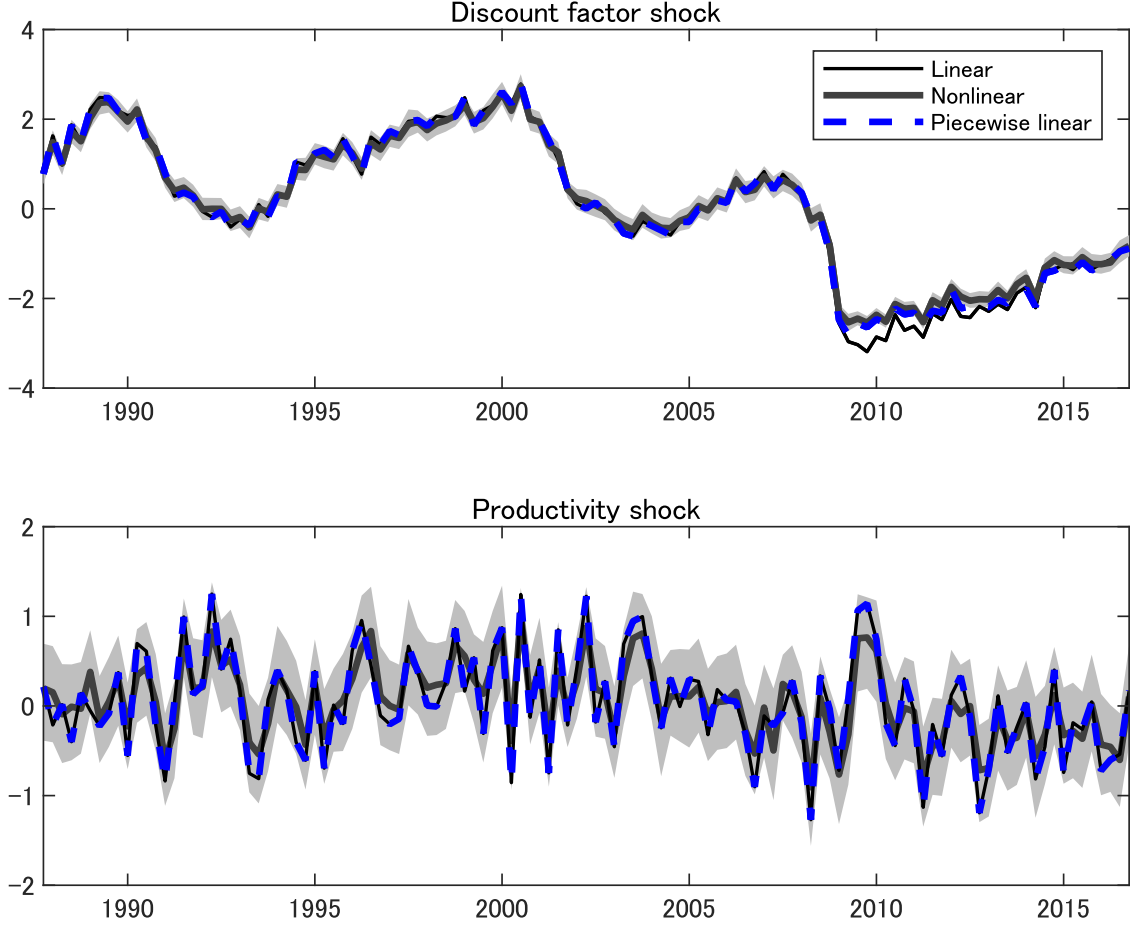
Note: The figure shows the filtered mean estimate of the natural interest rate, in annualized percentage terms, based on the nonlinear model (thick solid line) with its 90 percent interval (shaded area) and those based on the linear model (thin solid line) and the piecewise linear model (dashed line).

smaller to a lesser extent than that in the nonlinear model (thick solid line) until the end of the sample period.

The lower panel in Figure 8 compares the estimates of the productivity shock  $a_t$ . The piecewise linear model abstracts from price and wage dispersion as does the linear model, and hence the estimated productivity shocks in the two models exactly coincide with each other.

In summary, a piecewise linear model incorporating the ZLB can be a possible substitute for a fully nonlinear model in estimating the natural rate measures, although it can slightly underestimate the natural rate due to ignoring uncertainty at the ZLB.

Figure 8: Estimated shocks: Comparison with piecewise linear model



Note: The figure shows the filtered mean estimates of the discount factor shocks  $d_t$  and the productivity shocks  $a_t$ , in percentage terms, based on the nonlinear model (thick solid lines) with their 90 percent intervals (shaded areas) and those based on the linear model (thin solid lines) and the piecewise linear model (dashed line).

## 4 Concluding Remarks

This paper has estimated the natural rate of interest in a nonlinear New Keynesian model using U.S. macroeconomic data and compared it with the one estimated with the model's linear counterpart. We have found that the natural rate based on the nonlinear model is substantially higher than that based on the linear model during the period when the nominal interest rate was bounded at zero. This difference is explained by a contractionary effect of the ZLB, which is omitted in the linear model. Although the existence of the price and wage dispersion terms potentially affects the estimate of the natural rate in the nonlinear setting, their effects are negligible.

Whereas the present paper employs an empirically richer DSGE model than the prototypical New Keynesian model, existing studies, including Barsky, Justiniano, and Melosi (2014), Cúrdia, Ferrero, Ng, and Tambalotti (2015), Edge, Kiley, and Laforge (2008), Del Negro, Giannone, Giannoni, and Tambalotti (2017), and Justiniano and Primiceri (2010) estimate the natural interest rate using medium-scale DSGE models with capital accumulation in a linear setting. Our analysis could be extended to exploit such a medium-scale model so that the estimated natural rate would be comparable to the rates obtained in these studies. We conjecture that our results regarding the higher estimate of the natural rate in a nonlinear setting would still hold, even if we extended our model to a larger scale, because the main mechanism through which the ZLB can affect the identification of the natural rate remains unchanged.

## Appendix

### A Linearized Equilibrium Conditions and Observation Equations

Log-linearizing the detrended equilibrium conditions around the nonstochastic steady state, and rearranging the resulting equations, yields

$$\begin{aligned}
\tilde{y}_t &= \frac{\gamma_a}{\gamma_a + \gamma} (\mathbb{E}_t \tilde{y}_{t+1} + \mathbb{E}_t a_{t+1}) + \frac{\gamma}{\gamma_a + \gamma} (\tilde{y}_{t-1} - a_t) - \frac{\gamma_a - \gamma}{\gamma_a + \gamma} (\tilde{R}_t^n - \mathbb{E}_t \tilde{\Pi}_{t+1} - \tilde{d}_t), \\
\tilde{w}_t &= \tilde{w}_{t-1} - \tilde{\Pi}_t + \iota_w \tilde{\Pi}_{t-1} - a_t + \beta (\mathbb{E}_t \tilde{w}_{t+1} - \tilde{w}_t + \mathbb{E}_t \tilde{\Pi}_{t+1} - \iota_w \tilde{\Pi}_t + \mathbb{E}_t a_{t+1}) \\
&\quad + \frac{(1 - \xi_w)(1 - \xi_w \beta)}{\xi_w(1 + \eta \theta_w)} \left[ \eta \tilde{l}_t + \frac{1}{\gamma_a + \gamma} (\gamma_a \tilde{y}_t - \gamma \tilde{y}_{t-1} + \gamma a_t) - \tilde{w}_t \right], \\
\tilde{y}_t &= \tilde{l}_t, \\
\tilde{\Pi}_t &= \frac{\beta}{1 + \beta \iota_p} \mathbb{E}_t \tilde{\Pi}_{t+1} + \frac{\iota_p}{1 + \beta \iota_p} \tilde{\Pi}_{t-1} + \frac{(1 - \xi_p)(1 - \xi_p \beta)}{\xi_p(1 + \beta \iota_p)} (\tilde{w}_t + \tilde{z}_t), \\
\tilde{y}_t^* &= \frac{\gamma}{\gamma_a(1 + \eta) - \gamma \eta} (\tilde{y}_{t-1}^* - a_t), \\
\tilde{R}_t^n &= \phi_r \tilde{R}_{t-1}^n + (1 - \phi_r) \left[ \phi_\pi \tilde{\Pi}_t + \phi_y \tilde{y}_t + \phi_{\Delta y} (\tilde{y}_t - \tilde{y}_{t-1} + a_t) \right] + \varepsilon_{r,t}, \\
\tilde{d}_t &= \rho_d \tilde{d}_{t-1} + \varepsilon_{d,t}, \\
a_t &= \rho_a a_{t-1} + \varepsilon_{a,t}, \\
\tilde{z}_t &= \rho_z \tilde{z}_{t-1} + \varepsilon_{z,t},
\end{aligned}$$

where the variables with  $\sim$  represent percentage deviations from their steady-state values.

The observation equations are

$$\begin{bmatrix} 100 \Delta \log GDP_t \\ 100 \Delta \log PGDP_t \\ FF_t \\ 100 \log H_t \end{bmatrix} = \begin{bmatrix} \bar{a} \\ \bar{\pi} \\ \bar{r} + \bar{\pi} \\ \bar{l} \end{bmatrix} + \begin{bmatrix} \tilde{y}_t - \tilde{y}_{t-1} + a_t \\ \tilde{\Pi}_t \\ \tilde{R}_t^n \\ \tilde{l}_t \end{bmatrix},$$

where  $\bar{a} = 100 \log \gamma_a$ ,  $\bar{\pi} = 100 \log \bar{\Pi}$ ,  $\bar{r} = 100 \log \bar{R} (= 100 \log(\gamma_a/\beta))$ , and  $\bar{l}$  are, respectively, the steady-state growth rate, the inflation rate, the real interest rate, and hours worked.

## B Nonlinear Solution Method

### B.1 Recursive forms of the price and wage setting equations

After detrending, the equilibrium conditions (10) and (4) can be written in the following recursive forms:

$$\begin{aligned}
\frac{P_t^o}{P_t} &= \frac{S_{p,t}}{F_{p,t}} \\
S_{p,t} &= \theta_p w_t z_t + \xi_p \beta d_t^{-1} \mathbb{E}_t \left[ \left( \frac{\Pi_{t+1}}{\bar{\Pi}} \right) \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p} \frac{y_{t+1}}{y_t} \frac{\lambda_{t+1}}{\lambda_t} S_{p,t+1}, \\
F_{p,t} &= (\theta_p - 1) + \xi_p \beta d_t^{-1} \mathbb{E}_t \left[ \left( \frac{\Pi_{t+1}}{\bar{\Pi}} \right) \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p - 1} \frac{y_{t+1}}{y_t} \frac{\lambda_{t+1}}{\lambda_t} F_{p,t+1}, \\
\left( \frac{W_t^{n,o}}{W_t^n} \right)^{1+\eta\theta_w} &= \frac{S_{w,t}}{F_{w,t}} \\
S_{w,t} &= \theta_w l_{d,t}^\eta \lambda_t^{-1} + \xi_w \beta d_t^{-1} \mathbb{E}_t \left[ \left( \frac{\Pi_{w,t+1}}{\bar{\Pi}} \exp(a_{t+1}) \right) \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{-\iota_w} \right]^{(1+\eta)\theta_w} \frac{l_{d,t+1}}{l_{d,t}} \frac{\lambda_{t+1}}{\lambda_t} S_{w,t+1}, \\
F_{w,t} &= (\theta_w - 1) w_t + \xi_w \beta d_t^{-1} \mathbb{E}_t \left[ \left( \frac{\Pi_{w,t+1}}{\bar{\Pi}} \exp(a_{t+1}) \right) \left( \frac{\Pi_t}{\bar{\Pi}} \right)^{-\iota_w} \right]^{\theta_w - 1} \frac{l_{d,t+1}}{l_{d,t}} \frac{\lambda_{t+1}}{\lambda_t} F_{w,t+1},
\end{aligned}$$

where  $\Pi_{w,t} = \Pi_t w_t / w_{t-1}$  and  $l_{d,t} = \Delta_{p,t} y_t$ .

### B.2 Solution algorithm

In what follows, we drop the time subscript and use  $-1$  and  $'$  for previous- and next-period variables, respectively. To solve for the policy functions on each grid point of the state space  $(\mathbb{S}_{-1}, \tau)$ , where  $\mathbb{S}_{-1} = [y_{-1}, \Pi_{-1}, w_{-1}, \widehat{R}_{-1}^n, \Delta_{p,-1}, \Delta_{w,-1}, y_{-1}^*]'$  and  $\tau = [d, a, z, \varepsilon_r]'$ , we follow an index-function approach as in Aruoba, Cuba-Borda, and Schorfheide (2018), Gust, Herbst, López-Salido, and Smith (2017) and Nakata (2017).<sup>18</sup> First, regime-specific expectation functions are defined as

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<sup>18</sup>See also Hirose and Sunakawa (2019) for details about the solution algorithm with an example of a prototypical New Keynesian model with the ZLB.

follows:

$$\begin{aligned}
e_{\lambda,s}(\mathbb{S}_{-1}, \tau) &\equiv \beta d^{-1} R^n \int_{\tau'} \left\{ \frac{1}{\gamma_a \exp(a') \bar{\Pi}'} \right\} \Phi(\tau'|\tau) d\tau', \\
e_{sp,s}(\mathbb{S}_{-1}, \tau) &\equiv \theta_p w z + \xi_p \beta d^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{\Pi'}{\bar{\Pi}} \right) \left( \frac{\Pi}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p} \frac{y' \lambda' S'_p}{y \lambda} \right\} \Phi(\tau'|\tau) d\tau', \\
e_{fp,s}(\mathbb{S}_{-1}, \tau) &\equiv \theta_p - 1 + \xi_p \beta d^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{\Pi'}{\bar{\Pi}} \right) \left( \frac{\Pi}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p-1} \frac{y' \lambda' F'_p}{y \lambda} \right\} \Phi(\tau'|\tau) d\tau', \\
e_{sw,s}(\mathbb{S}_{-1}, \tau) &\equiv \theta_w l_d^\eta \lambda^{-1} + \xi_w \beta d^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{\Pi'_w \exp(a')}{\bar{\Pi}} \right) \left( \frac{\Pi}{\bar{\Pi}} \right)^{-\iota_w} \right]^{(1+\eta)\theta_w} \frac{l'_d \lambda' S'_w}{l_d \lambda} \right\} \Phi(\tau'|\tau) d\tau', \\
e_{fw,s}(\mathbb{S}_{-1}, \tau) &\equiv (\theta_w - 1) w + \xi_w \beta d^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{\Pi'_w \exp(a')}{\bar{\Pi}} \right) \left( \frac{\Pi}{\bar{\Pi}} \right)^{-\iota_w} \right]^{\theta_w-1} \frac{l'_d \lambda' F'_w}{l_d \lambda} \right\} \Phi(\tau'|\tau) d\tau',
\end{aligned}$$

where the index  $s \in \{\text{NZLB}, \text{ZLB}\}$  is associated with the interest-rate regime in which the notional nominal interest rate  $\widehat{R}^n$  implied by its unconstrained policy function  $g_{\widehat{R}^n, \text{NZLB}}(\mathbb{S}_{-1}, \tau)$  is either above or below the lower bound. Then, the expectation functions are constructed as weighted averages of the regime-specific functions

$$e_x(\mathbb{S}_{-1}, \tau) = e_{x, \text{NZLB}}(\mathbb{S}_{-1}, \tau) 1_{\{\widehat{R}^n > 1\}} + e_{x, \text{ZLB}}(\mathbb{S}_{-1}, \tau) 1_{\{\widehat{R}^n \leq 1\}},$$

where  $1_{\{D\}}$  is the indicator function that equals one if the condition  $D$  is true and zero otherwise.

We obtain the policy functions by a time iteration method, which takes the following steps.

1. Make an initial guess for the expectation functions  $e_s^{(0)} = (e_{\lambda,s}^{(0)}, e_{sp,s}^{(0)}, e_{fp,s}^{(0)}, e_{sw,s}^{(0)}, e_{fw,s}^{(0)})$  for  $s \in \{\text{NZLB}, \text{ZLB}\}$ .
2. For  $i = 1, 2, \dots$  ( $i$  is an index for the number of iterations), taking as given the expectation functions previously obtained  $e_s^{(i-1)}$ , solve the relevant equations to obtain the policy functions  $g_s^{(i)} = (g_{\Pi,s}^{(i)}, g_{\Delta_p,s}^{(i)}, g_{\Pi_w,s}^{(i)}, g_{\Delta_w,s}^{(i)}, g_{y,s}^{(i)}, g_{w,s}^{(i)}, g_{l_d,s}^{(i)}, g_{\widehat{R}^n,s}^{(i)})$ .
3. Update the expectation functions  $e_s^{(i)}$  by interpolating the policy functions  $g_s^{(i)}$ .
4. Repeat Steps 2-3 until  $\|e_s^{(i)} - e_s^{(i-1)}\|$  is small enough.

In Step 2, taking as given the values of  $e_{x,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)$  for  $x \in \{\lambda, sp, fp, sw, fw\}$  at each grid

point indexed by  $(j, m)$  and each regime  $s \in \{\text{NZLB}, \text{ZLB}\}$ , we have

$$\begin{aligned}
\frac{\Pi_{jms}}{\bar{\Pi}} &= \left( \xi_p^{-1} + (1 - \xi_p^{-1}) \left[ \frac{e_{sp,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)}{e_{fp,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)} \right]^{1-\theta_p} \right)^{\frac{1}{\theta_p-1}} \left( \frac{\Pi_{-1,j}}{\bar{\Pi}} \right)^{\iota_p}, \\
\Delta_{p,jms} &= (1 - \xi_p) \left[ \frac{e_{sp,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)}{e_{fp,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)} \right]^{-\theta_p} + \xi_p \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{\theta_p} \left( \frac{\Pi_{-1,j}}{\bar{\Pi}} \right)^{-\iota_p} \Delta_{p,-1,j}, \\
\frac{\Pi_{w,jms} \exp(a)}{\bar{\Pi}} &= \left( \xi_w^{-1} + (1 - \xi_w^{-1}) \left[ \frac{e_{sw,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)}{e_{fw,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)} \right]^{\frac{1-\theta_w}{1+\eta\theta_w}} \right)^{\frac{1}{\theta_w-1}} \left( \frac{\Pi_{-1,j}}{\bar{\Pi}} \right)^{\iota_w}, \\
\Delta_{w,jms} &= (1 - \xi_w) \left[ \frac{e_{sw,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)}{e_{fw,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)} \right]^{\frac{-\theta_w}{1+\eta\theta_w}} + \xi_w \left( \frac{\Pi_{w,jms} \exp(a_m)}{\bar{\Pi}} \right)^{\theta_w} \left( \frac{\Pi_{-1,j}}{\bar{\Pi}} \right)^{-\iota_w} \Delta_{w,-1,j}, \\
y_{jms} &= e_{\lambda,s}^{(i-1)}(\mathbb{S}_{-1,j}, \tau_m)^{-1} + \frac{\gamma y_{j,-1}}{\gamma_a \exp(a_m)} \\
w_{jms} &= w_{-1} \Pi_{w,jms} / \Pi_{jms}, \\
l_{d,jms} &= \Delta_{p,jms} y_{jms}, \\
\hat{R}_{jms}^n &= (\hat{R}_{-1,j}^n)^{\phi_r} \left[ \bar{R} \bar{\Pi} \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{\phi_\pi} \left( \frac{y_{jms} \exp(a_m)}{y_{-1}} \right)^{\phi_y} \right]^{1-\phi_r} \exp(\varepsilon_{r,m}).
\end{aligned}$$

Then, we can evaluate  $(\Pi_{jms}, \Delta_{p,jms}, \Pi_{w,jms}, \Delta_{w,jms}, y_{jms}, w_{jms}, l_{d,jms}, \hat{R}_{jms}^n)$  at each grid point  $(j, m)$  and each regime  $s$  and the policy functions  $g_{x,s}^{(i)}(\mathbb{S}_{-1}, \tau; \boldsymbol{\theta})$  for  $x = \{\Pi, \Delta_p, \Pi_w, \Delta_w, y, w, l_d, \hat{R}^n\}$  parameterized by a vector of polynomial coefficients  $\boldsymbol{\theta}$  for computing the values off the grid points. Note that this procedure does not rely on any numerical optimization routines to solve the nonlinear equations.

In Step 3, the expectation functions are updated by

$$\begin{aligned}
e_{\lambda,s}^{(i)}(\mathbb{S}_{j,-1}, \tau_m) &= \beta d_m^{-1} R_{jms}^n \int_{\tau'} \left\{ \frac{1}{\gamma_a \exp(a')} \frac{e_{\lambda}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{g_{\Pi}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta})} \right\} \Phi(\tau'|\tau) d\tau', \\
e_{sp,s}^{(i)}(\mathbb{S}_{j,-1}, \tau_m) &= \theta_p w_{jms} z_m + \xi_p \beta d_m^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{g_{\Pi}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{\bar{\Pi}} \right) \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p} \right. \\
&\quad \times \left. \frac{g_y^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{\lambda}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{sp}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{y_{jms} e_{\lambda}^{(i-1)}(\mathbb{S}_{j,-1}, \tau_m; \boldsymbol{\theta})} \right\} \Phi(\tau'|\tau) d\tau',
\end{aligned}$$

$$\begin{aligned}
e_{fp,s}^{(i)}(\mathbb{S}_{j,-1}, \tau_m) &= \theta_p - 1 + \xi_p \beta d_m^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{g_{\Pi}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{\bar{\Pi}} \right) \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p - 1} \right. \\
&\quad \times \left. \frac{g_y^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{\lambda}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{fp}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{y_{jms} e_{\lambda}^{(i-1)}(\mathbb{S}_{j,-1}, \tau_m; \boldsymbol{\theta})} \right\} \Phi(\tau' | \tau) d\tau', \\
e_{sw,s}^{(i)}(\mathbb{S}_{j,-1}, \tau_m) &= \theta_w l_{d,jms}^{\eta} \lambda_{jms}^{-1} + \xi_w \beta d_m^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{g_{\Pi_w}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) \exp(a')}{\bar{\Pi}} \right) \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p} \right. \\
&\quad \times \left. \frac{g_{l_d}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{\lambda}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{sw}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{l_{d,jms} e_{\lambda}^{(i-1)}(\mathbb{S}_{j,-1}, \tau_m; \boldsymbol{\theta})} \right\} \Phi(\tau' | \tau) d\tau', \\
e_{fw,s}^{(i)}(\mathbb{S}_{j,-1}, \tau_m) &= (\theta_w - 1) w_{jms} + \xi_w \beta d_m^{-1} \int_{\tau'} \left\{ \left[ \left( \frac{g_{\Pi_w}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) \exp(a')}{\bar{\Pi}} \right) \left( \frac{\Pi_{jms}}{\bar{\Pi}} \right)^{-\iota_p} \right]^{\theta_p} \right. \\
&\quad \times \left. \frac{g_{l_d}^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{\lambda}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta}) e_{fw}^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})}{l_{d,jms} e_{\lambda}^{(i-1)}(\mathbb{S}_{j,-1}, \tau_m; \boldsymbol{\theta})} \right\} \Phi(\tau' | \tau) d\tau',
\end{aligned}$$

where the values  $(\Pi_{jms}, \Pi_{jms}^w, y_{jms}, w_{jms}, R_{jms}^n)$  and the policy functions  $g_x^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta})$  evaluated at the next period's state  $(\mathbb{S}, \tau')$  are obtained in the previous step. Note that we interpolate  $g_x^{(i)}(\mathbb{S}, \tau'; \boldsymbol{\theta})$  for  $x \in \{\Pi, \Pi_w, y, l_d, \hat{R}^n\}$  off the grid points (or equivalently  $e_x^{(i-1)}(\mathbb{S}, \tau'; \boldsymbol{\theta})$  for  $x \in \{\lambda, sp, fp, sw, fw\}$ ) by piecewise linear interpolation. Numerical integrals are computed with regard to  $\tau'$ .

For interpolating the policy functions at each regime, we set the number of grids as 5 for each endogenous state variable, 15 for the discount factor shock  $d_t$ , and 3 for each of the other shocks. Thus we have  $5^6 \times 15 \times 3^3 = 6,328,125$  grid points in total.<sup>19</sup> The integrals over  $\tau'$  are approximated by the Gauss–Hermite quadrature formula with three nodes for each shock. To deal with such a large number of grid points and quadrature nodes, we use a supercomputer system to run programming codes with parallel computing.

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<sup>19</sup>We can drop the natural output from the endogenous state variables in the time iteration as it is relevant only for the natural rate.



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