

Progress Report Week 9
Professor Montella
Driverless Car Group
10/30/20

Weekly Report

| Name | Hours Worked | Activities in current week | Planned Activities for next week |
|----------|--------------|------------------------------------------------------------------------|-----------------------------------------------------------------------------------------|
| Olivia | 2 | Worked on adding the “goal point” to the score method | Fix score method (hopefully complete it) |
| Wes | 1 | Bought correct sized screws | Figure out wiring |
| Walker | 3 | More ubuntu & opencv trouble | Even more opencv trouble |
| Kingsley | 5 | changed sensor and track representation to line segments and functions | create sliding window of perceivable environment for agent, instead of the entire track |

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|------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------|
| Team Accomplishments | - Getting close to being able to integrate everything |
| Current Issues/Challenges and Remediation Plan | - Trouble determining initial goal point, Montella told me it should be passed in as part of problem params, going to fix that |
| Planned accomplishments in next week | - begin talking about and planning integration of different parts |