

Progress Report Week 7  
Professor Montella  
Driverless Car Group  
10/16/20

### Weekly Report

Name	Hours Worked	Activities in current week	Planned Activities for next week
Olivia	3	Creating scoring method-- nearly complete	Figure out the weights part and completely finish the point mass model for next week
Wes	4	Installing/ordering parts, figuring out compatibility issues	Get motor and odometer fully installed
Walker	4	Building ROS Azure driver, ros melodic, opencv	Get rid of ROS, it's only causing problems
Kingsley	3	Wrote function to calculate function of vector to nearest "wall" in the the 2D array	Graph generated functions and debug

Team Accomplishments	-
Current Issues/Challenges and Remediation Plan	<ul style="list-style-type: none"><li>- Pinion gear compatibility with motor. Fixing this by order a new one</li><li>- Q-learning still needs to be debugged</li></ul>
Planned accomplishments in next week	<ul style="list-style-type: none"><li>- Everyone trying to wrap things up</li></ul>