

Progress Report Week 6
Professor Montella
Driverless Car Group
10/9/20

Weekly Report

Name	Hours Worked	Activities in current week	Planned Activities for next week
Olivia	4	Started scoring method, fixed a bug I realized I found w the angles	Finish the scoring method
Wes	2	Odometer/Motor	Finish installation/Order Parts
Walker	~7	Bunch of ORB-SLAM2 dependency resolution issues	Actually run it
Kingsley	2	Looked into Q-Learning based on function approximation	Visualize sensor data as vectors

Team Accomplishments	- Finishing up a lot of diff parts
Current Issues/Challenges and Remediation Plan	- na
Planned accomplishments in next week	- Finish up various components