Progress Report Week 12
Professor Montella
Driverless Car Group
11/20/20

Weekly Report

Name	Hours Worked	Activities in current week	Planned Activities for next week
Olivia	5	Fixed scoring method, added visualization component	Fix the visualization component, prep for final presentation
Wes	<1	Presentation prep	Review olivia's code/Final presentation. Transfer car to Montella
Walker	1	review sensor model	Extend q learning to an actual map
Kingsley	6	Fixed bug in Q-learning app. Implemented system of csv files with line segment representations, that can be read by python script or MATLAB app.	Connect Python script or MATLAB script to sensor simulation so updates of visualization are automatic.

Team Accomplishments	- Finishing things up, almost ready for final presentation
Current Issues/Challenges and Remediation Plan	- n/a
Planned accomplishments in next week	- Make the final presentation