

r_gripper_finger_link

l_gripper_finger_link

view_frames Result

world

Recorded at time: 1619594440.365

Broadcaster: /map_tf06_fetch1075_1176_3942945486318836978 Broadcaster: /map_tf02_fetch1075_1176_3692503355805986775 Broadcaster: /map_tf08_fetch1075_1176_6728045682097580889 \ Broadcaster: /map_tf04_fetch1075_1176_2111972765112663752 Average rate: 10.269 Hz Average rate: 10.270 Hz Most recent transform: 1619594440.277 (0.088 sec old) Most recent transform: 1619594440.281 (0.084 sec old) Buffer length: 3.603 sec Buffer length: 3.603 sec

eng2/2f

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

torso_fixed_link