

An Efficient Inter-node Communication System with Lightweight-thread Scheduling

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Abstracts

- With many cores in one chip, there are increasing needs to exploit inter/intra-node parallelism efficiently
- We propose a new communication system **MPI+myth**, which enables efficient **overlapping** of inter-node communication and intra-node computation with **little burden** on programmers
- MPI+myth is implemented using MPI and a user-level thread library, MassiveThreads

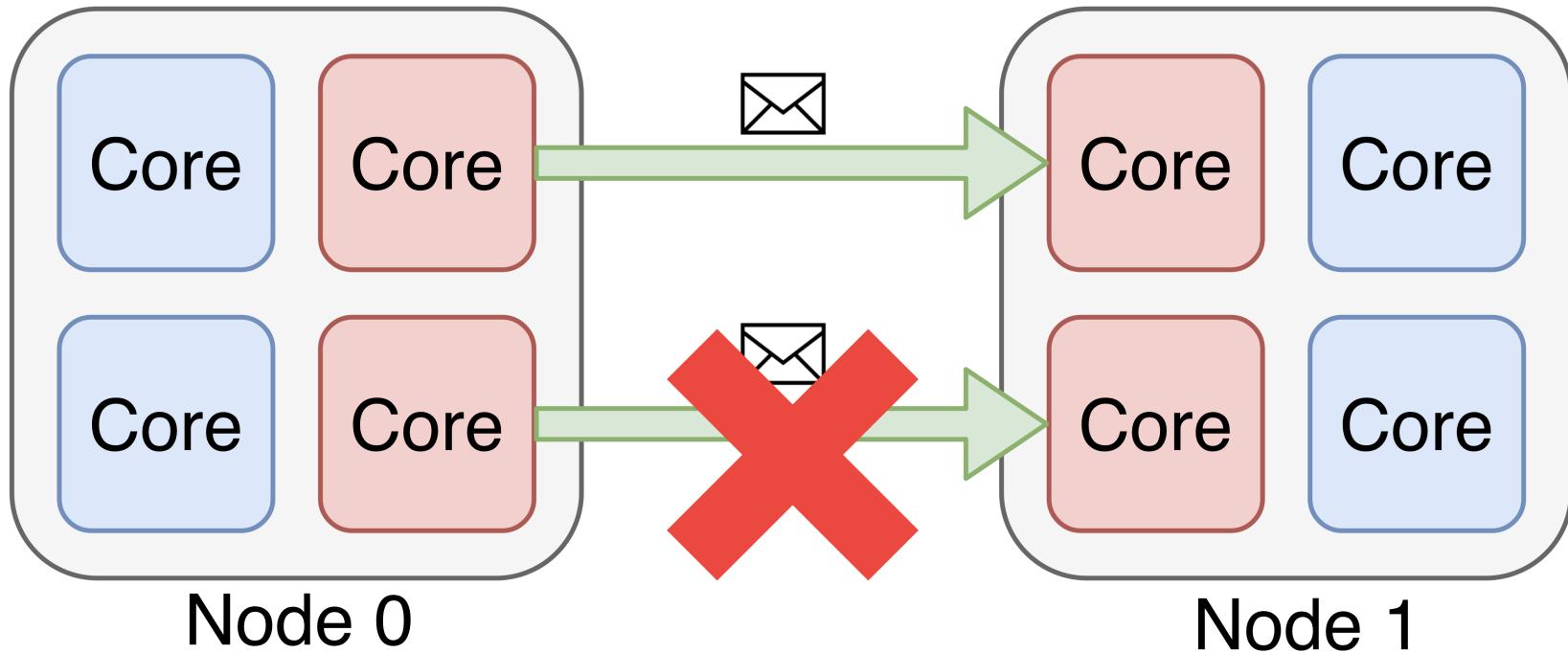
Background

MPI (Message Passing Interface)

- An interface for communication between nodes in a cluster
- Two kinds of APIs: **blocking APIs** and **non-blocking APIs**
- It is normal to use blocking APIs because of its simplicity

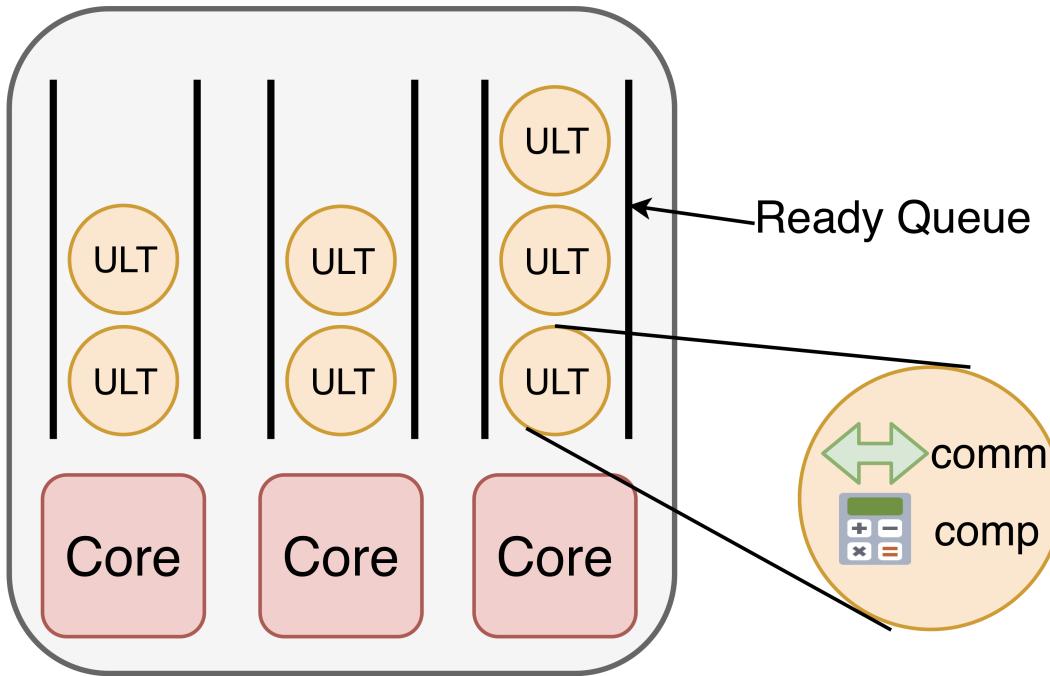
```
// Example usege of non-blocking APIs
MPI_Request req;
int flag;
MPI_Isend(..., &req);
computation();
do{
    MPI_Test(req, &flag, ...)
}while(!flag)
```

The Limitation of multi-threaded invocation of MPI



- In a normal mode, you cannot invoke MPI from multiple threads
- In order to invoke MPI from multiple threads, you have to use a special mode (`MPI_THREAD_MULTIPLE`)
 - It is known to **perform poorly** because of its complex and heavy mutual exclusion.

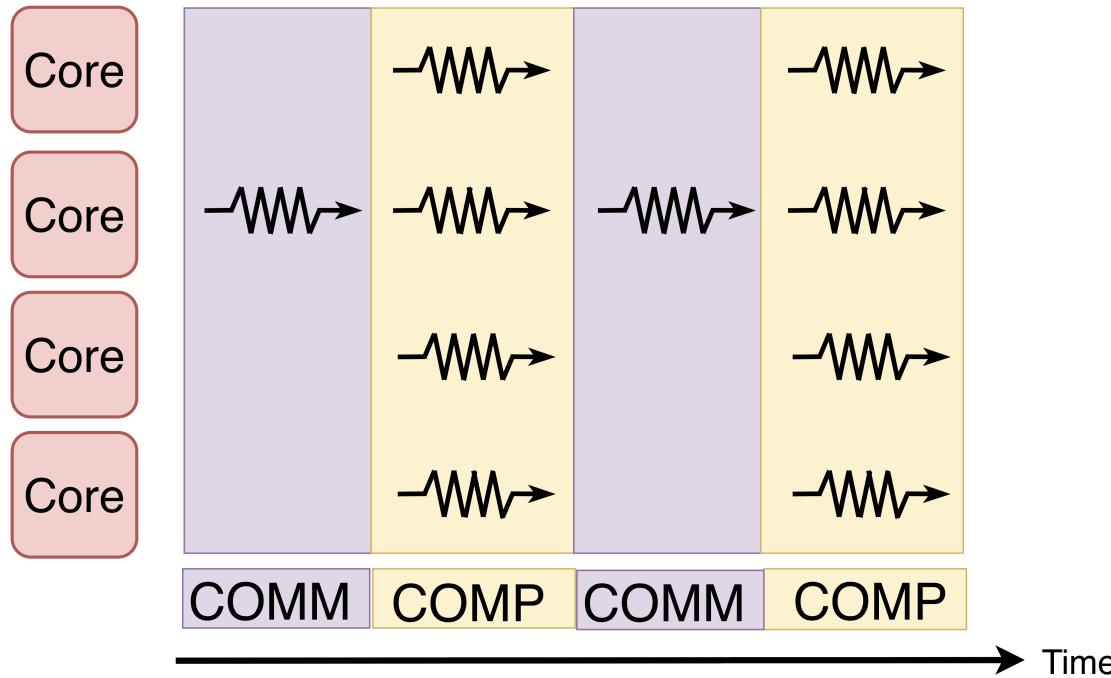
User-level Thread (ULT)



- A ULT is a thread implemented in user space and multiple ULTs can be mapped into one Kernel-level thread (KLT)
- Compared with KLTs, ULTs can be **lightweight** and thread creation and context-switching can be done **at lower cost**.
- ULTs are scheduled through **ready queues** in which executable ULTs can be enqueued and dequeued

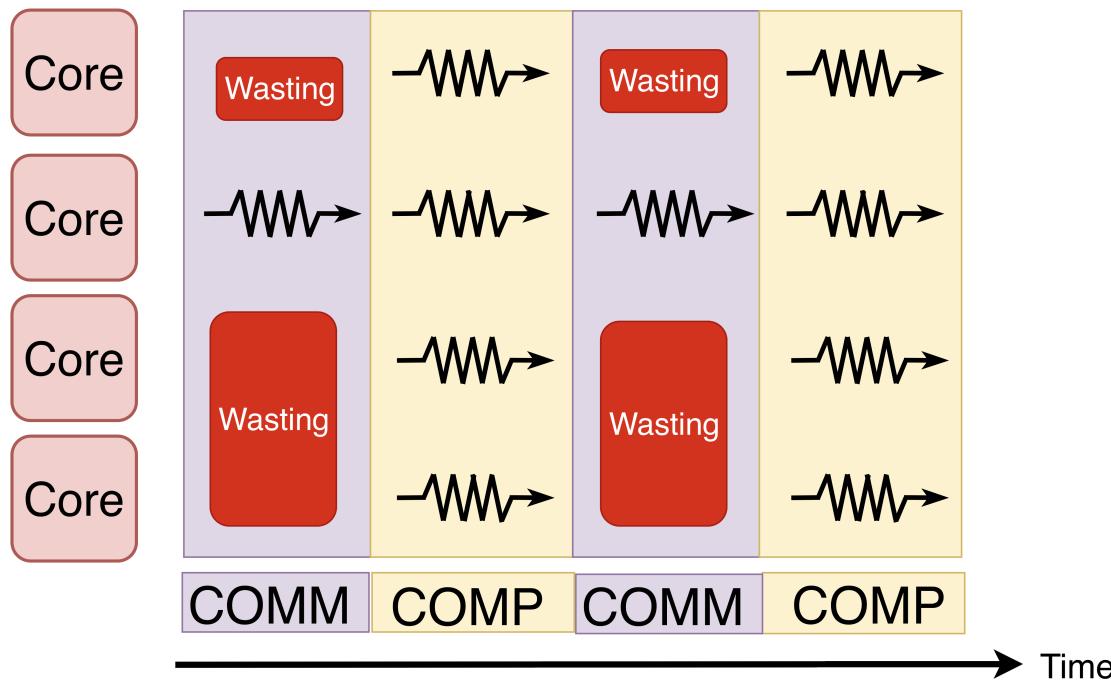
Introduction

Conventional Method for Parallelization



- Separating phases: communication phases and computation phases
- In communication phases, **only a master thread** issues MPI functions
- In computation phases, each threads executes computation through **shared memory**

A Problem in the Conventional Method



- **Waste of resources** of cores which are not in charge of the master thread in communication phases
- In order to use these cores efficiently, programmers have to describe overlapping of communication and computation
 - It requires considering the dependencies
 - It can be **heavy burdens on programmers**

Ideal Description of Parallelization

- Programmers create many ULTs (tasks) in which **communication and computation is issued freely**
 - No needs to separate communication and computation phases
- Programmers do not have to use **non-blocking APIs** of MPI to describe overlapping
 - Little burden on programmers

Obstacles for the Ideal Description

- Multi-threaded MPI invocations are necessary
 - Software Offloading [1] is already proposed to avoid the overhead of MPI_THREAD_MULTIPLE
 - Delegate all communication to one thread
- Just combining SoftwareOffloading and ULT libraries is not enough
 - Other than this, the runtime has to be equipped with a mechanism to overlap communication and computation efficiently

1. Vaidyanathan, K. et al. (2015). Improving Concurrency and Asynchrony in Multithreaded MPI Applications using Software Offloading - SC'15.

Proposed System: MPI+myth

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```
func(){
    MPI_Send();
    computation();
}

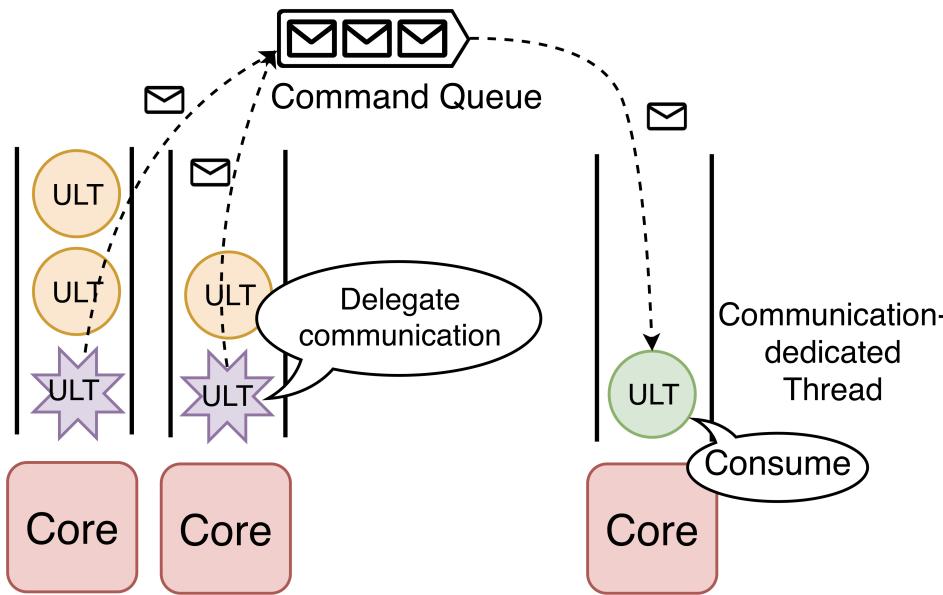
myth_create(*func, args, ...)
```

- MPI+myth combines MPI for inter-node communication and ULTs (user-level threads) for intra-node parallelism
- Programmers describe applications using APIs of ULT libraries, MassiveThreads and blocking APIs of MPI
- The runtime has responsibility in overlapping of communication and computation

Two Characteristics of the Implementation of MPI+myth

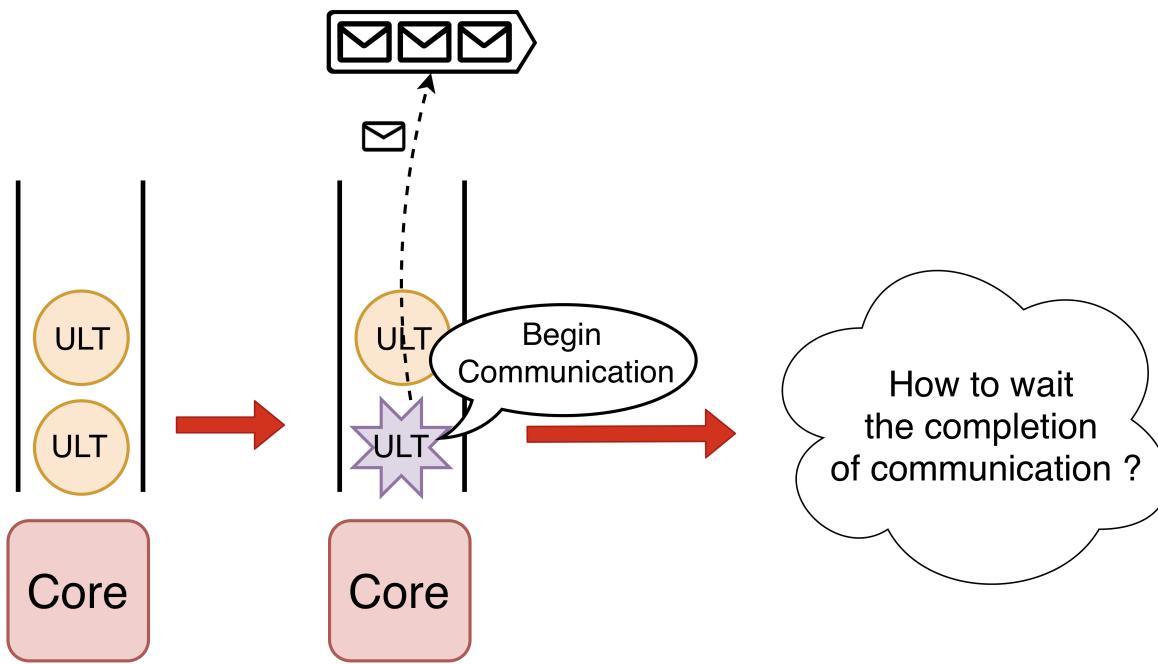
- Improve performance by combining Software Offloading and MassiveThreads and avoiding the use of multi-threaded mode of MPI (MPI_THREAD_MULTIPLE)
- Equipped with a mechanism to overlap communication and computation
 - The runtime detects the communication and communicating ULTs release the core to other ULTs

First Characteristics of MPI+myth: Avoid multi-threaded MPI invocations



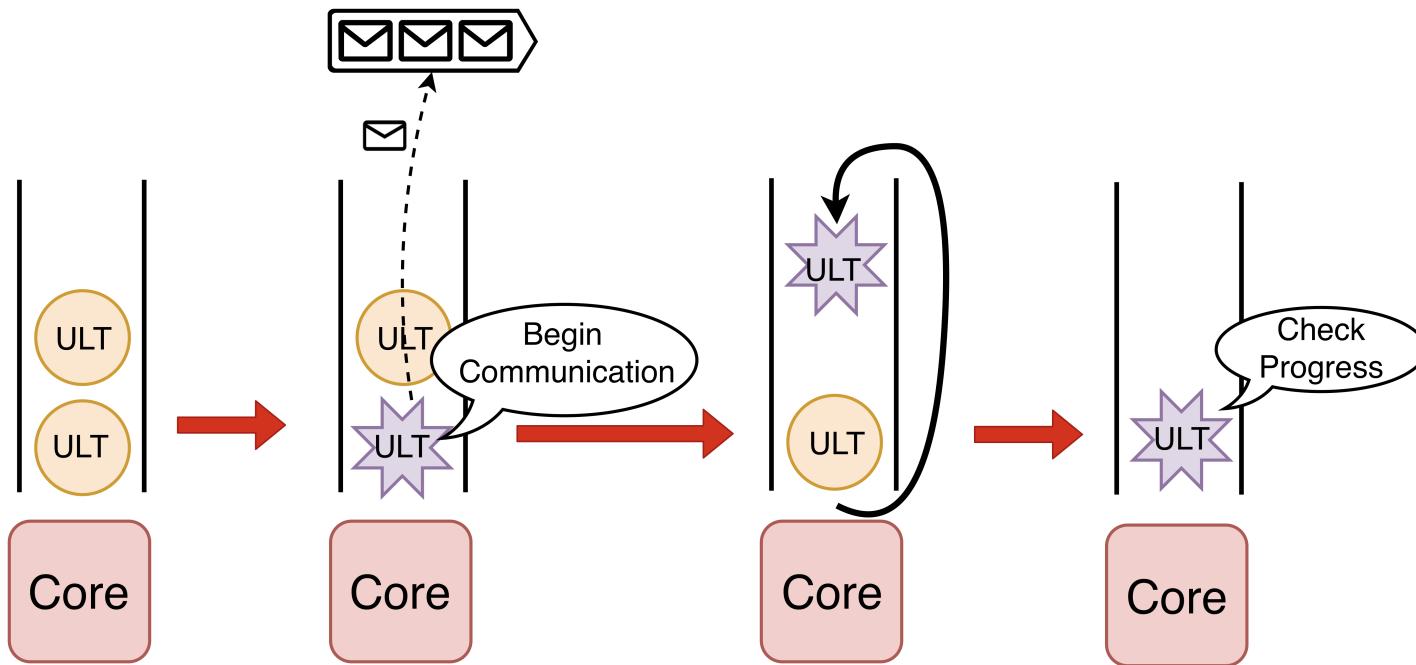
- Introduce a technique called Software Offloading
- Delegate all MPI invocations to **a communication-dedicated thread through a command queue [1]**
- When a ULT issues communication, its name of a communication function and its arguments are inserted into the command queue

Second Characteristics of MPI+myth: Overlap communication and computation



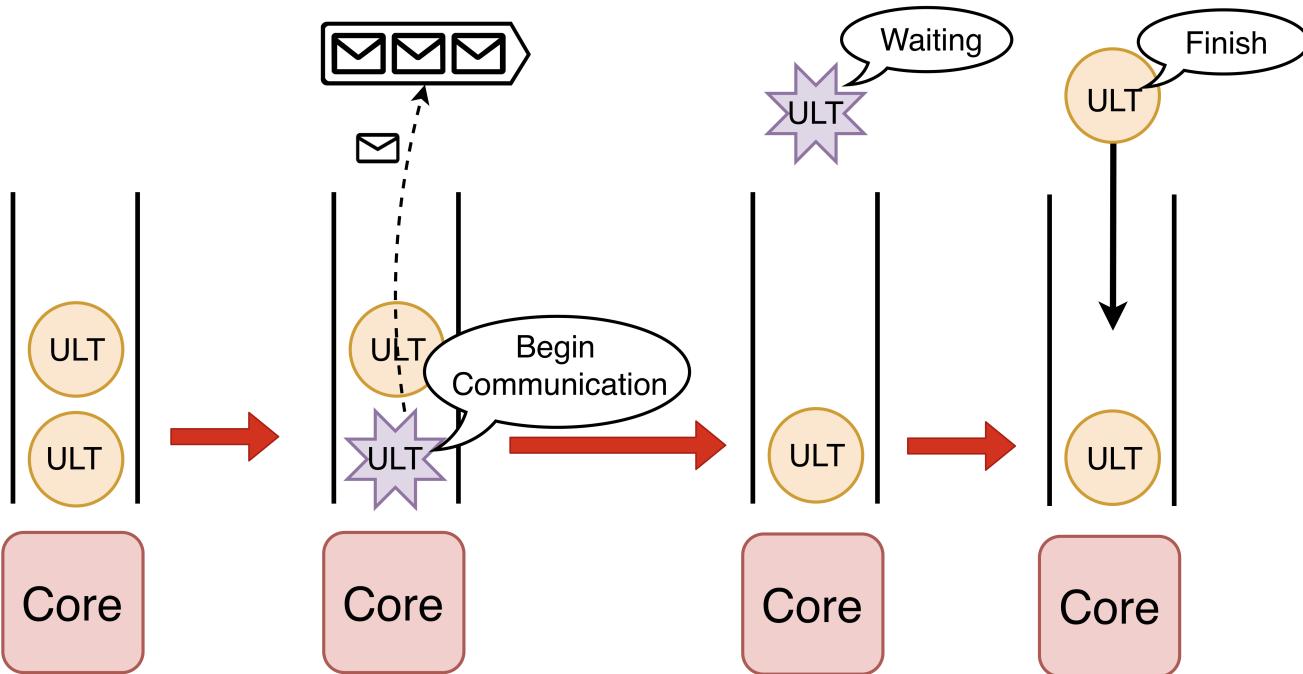
- The runtime is in charge of overlapping communication and computation
- Two kinds of methods for waiting the communication

First Method for Waiting Communication



- First method is to **re-insert** communicating ULTs to the back of ready queue when the communication continues
 - Communicating ULTs check its progress of communication **every time its turn comes**
 - Widely used method due to its low implementation cost

Second Method for Waiting Communication



- Second method is to **remove** communicating ULTs from the ready queue
 - When the communication completes, the ULT is inserted to the back of the ready queue immediately
- Our system adopts **the second method** because it can avoid a situation in which the ready queue is filled with communicating ULTs

Related Work

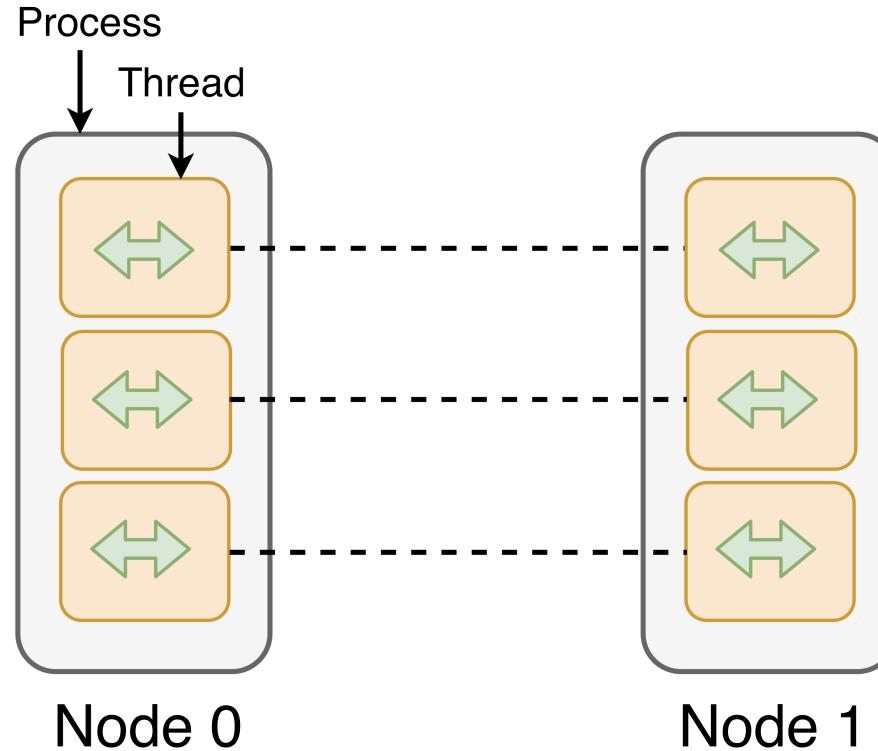
	Avoid Overhead of <code>MPI_THREAD_MULTIPLE</code>	Explicit Description of Overlapping
MPI/SMPSSs [2]	unsupported	necessary
HCMPI [3]	yes	necessary
MPIQ [4]	no	unnecessary
MPI+Argobots [5]	no	unnecessary
MPI+myth	yes	unnecessary

2. V.Marjanović, et al. (2010) Overlapping Communication and Computation by Using a Hybrid MPI/SMPSSs Approach - ICS
3. S. Chatterjee, et al. (2013) Integrating Asynchronous Task Parallelism with MPI - IPDPS'13.
4. D. Stark, et al. (2014) Early Experiences Co-Scheduling Work and Communication Tasks for Hybrid MPI+X Applications
5. H. Lu, et al. (2015). MPI+ULT: Overlapping communication and computation with user-level threads - HPCC'15

Experimental Environment

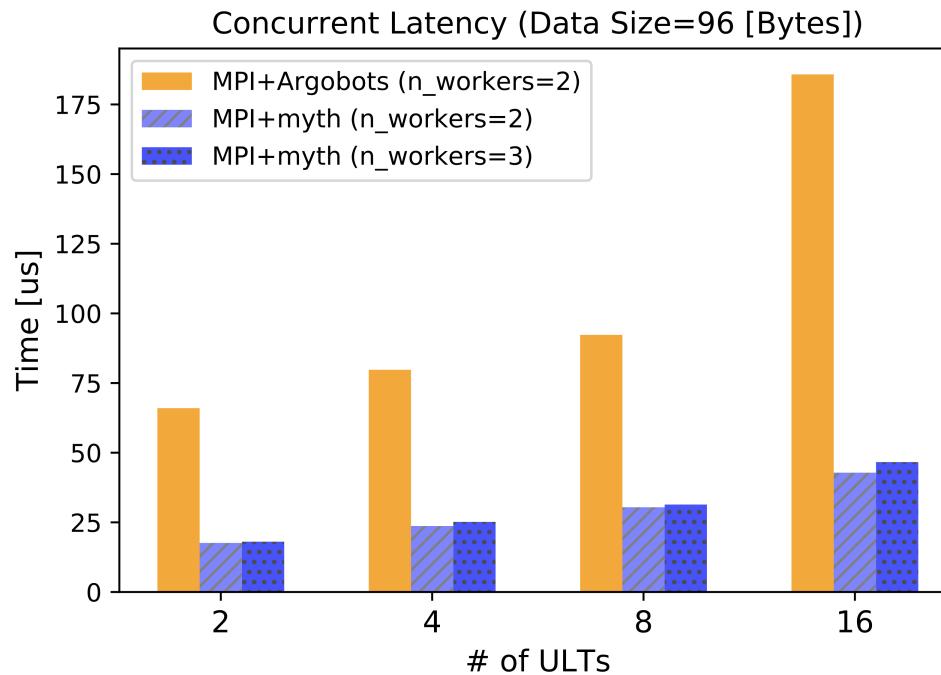
System	Reedbush-U
Interconnect	InfiniBand EDR 4x (100 Gbps)
Processor	Intel Xeon E5-2695v4 (Broadwell-EP)
# of Processors / Node	2
# of cores / Node	36
Memory	256 GB

What is Concurrent Latency ?



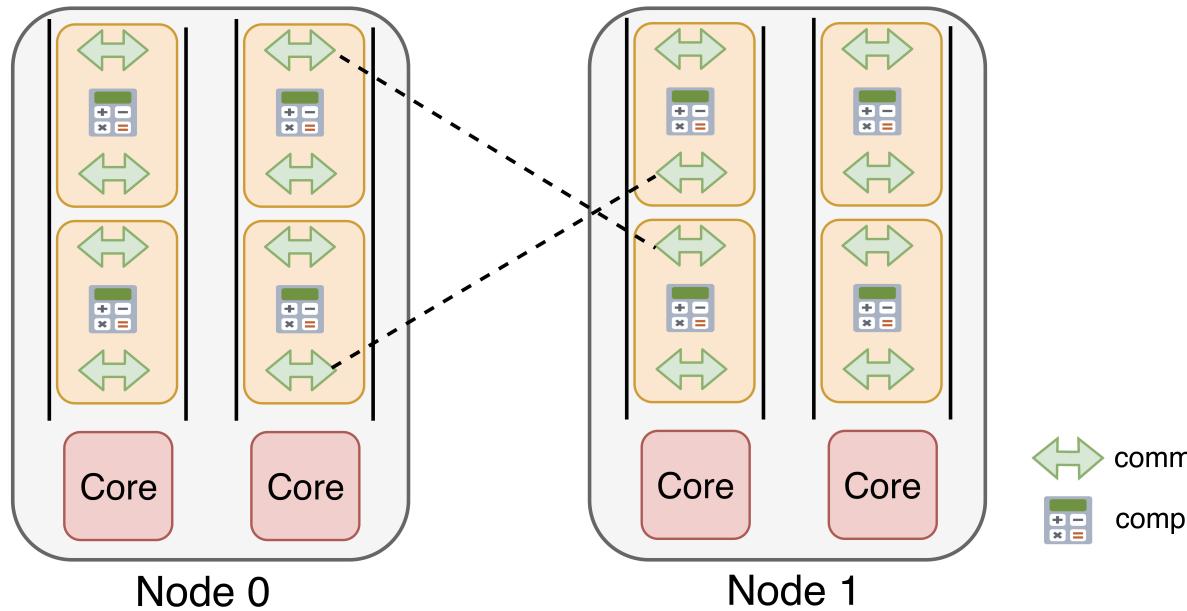
- Two processes are generated and each process generate threads
- Each thread communicate with a thread in another process

Concurrent Latency



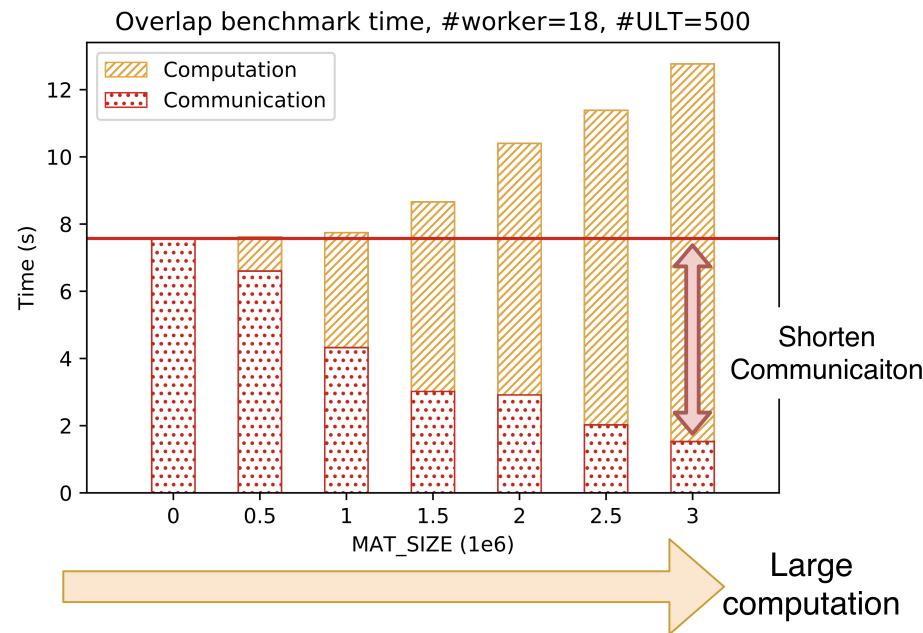
- Compare our system with MPI+Argobots which combines MPI and ULTs
- Our system occupies one core for a communication-dedicated thread
- Our system performs better than MPI+Argobots because our system can **avoid the overhead of MPI_THREAD_MULTIPLE**

Overlap Benchmark



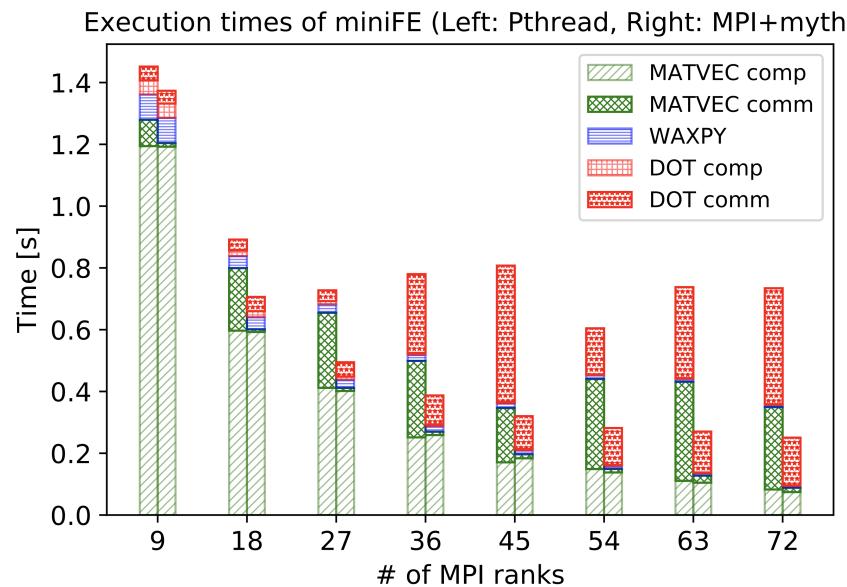
- We create two MPI processes and each process creates multiple ULTs
- One ULT executes blocking communication of 1MB, computation, and blocking communication of 1MB again
- The number of cores is 18 and the number of ULTs is 500

Overlap Benchmark Result



- Fix the amount of communication (1MB) and change the amount of computation (which is in proportion to MAT_SIZE in the figure) and measure the whole time of benchmarks
- The time for computation is measured with no communication settings, and the time for communication is calculated as the difference of the whole time and the computation time.
- The time for communication is shorted, which means **overlap is achieved**

Application Benchmark



- Compare the time of miniFE [6] which is an mini-app for finite element
- In order to exchange the data between nodes, the same number of threads as the number of neighbor nodes are created
- Our system achieves shortening of communication time by introducing **Software Offloading**

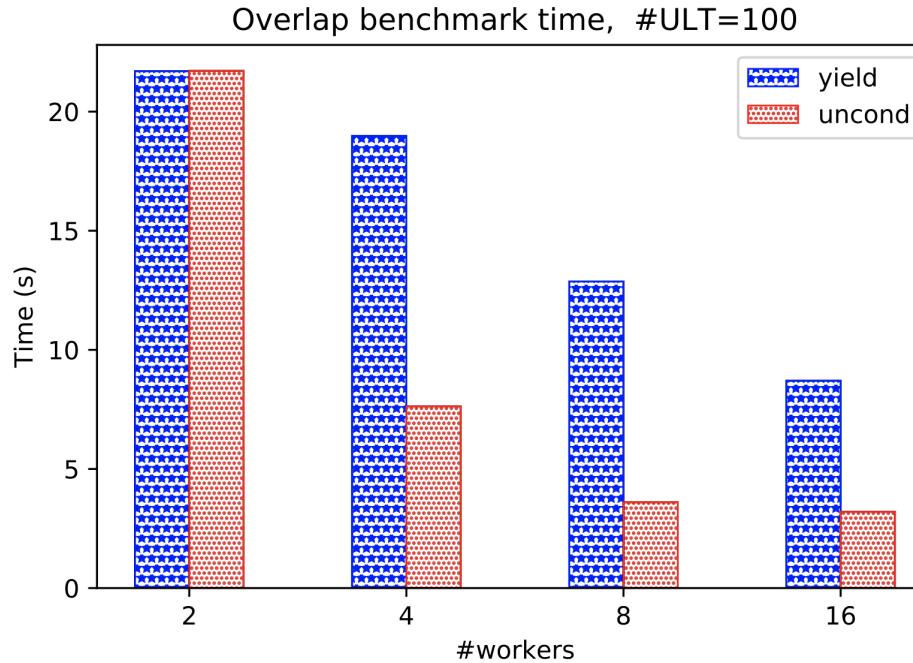
6. <https://github.com/Manteko/miniFE>

Conclusions

- MPI+myth combines MPI and ULT and it lays little burdens on programmers by avoiding the use of non-blocking communication
- Two characteristics of the implementation of MPI+myth
 - Improve performance by combining Software Offloading and ULT library
 - Equipped with a mechanism for overlapping blocking communication and computation with efficient waiting method
- MPI+myth was faster than existing parallel systems by between 2.4 to 5.1 times

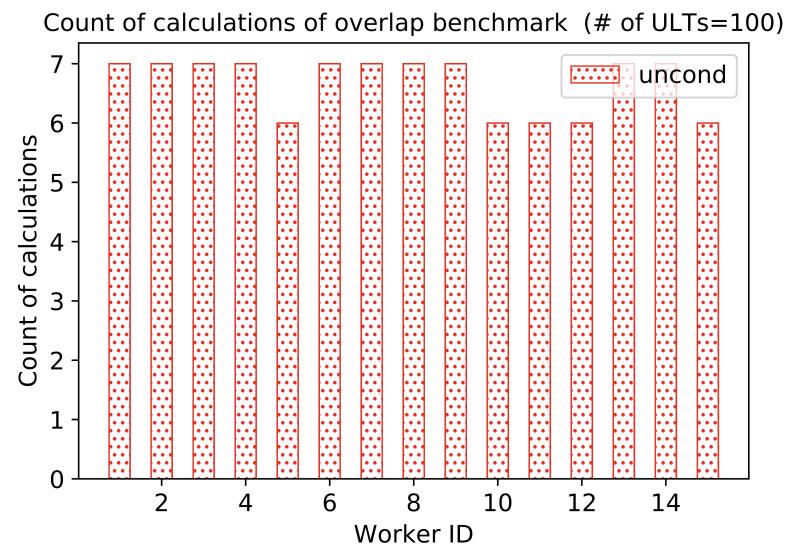
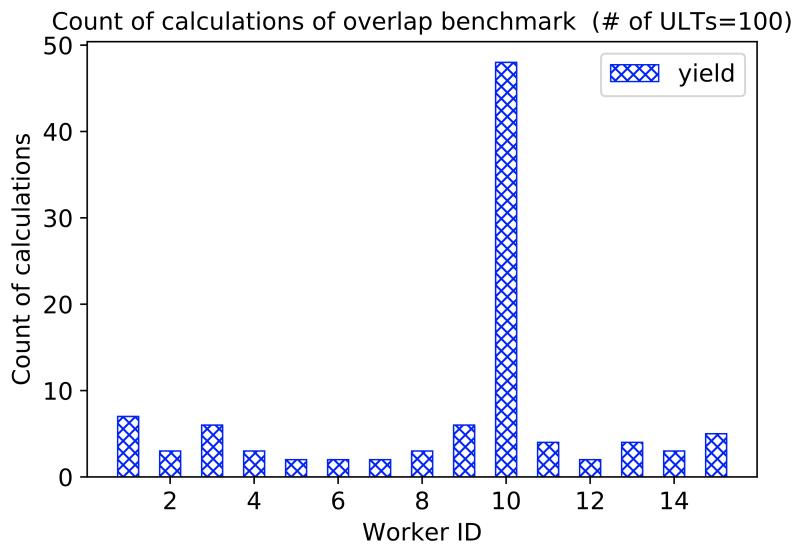
Appendix

Comparison of Waiting Methods



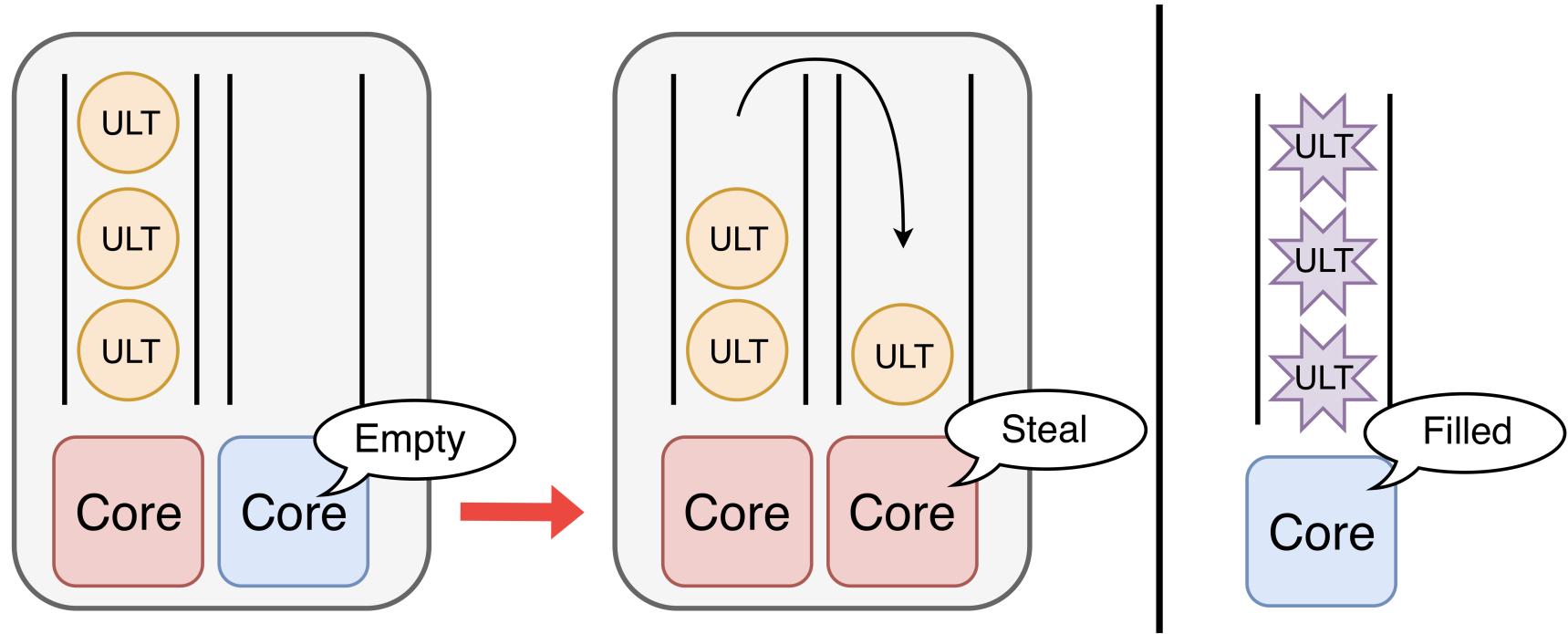
- The blue bar shows the time with **first waiting method** and the red bar shows the time with **second waiting method**, which removes the blocked ULT from a ready queue
- **Second waiting method** performs better

What makes that difference between two scheduling techniques?



- Count the number of computational parts of ULTs each core processed
- With first waiting method, **load balancing** does not work well

Why first waiting method can disturb efficient load balancing?



- When a core has no ULTs in its ready queue, it can **steal** a ULT from other cores (left figure)
- When a ready queue is filled with blocked ULTs, **stealing does not work** (right figure)