

Optimal Partial Transport for Topological Data Analysis

Saint-Flour
10 juillet 2019

Théo Lacombe

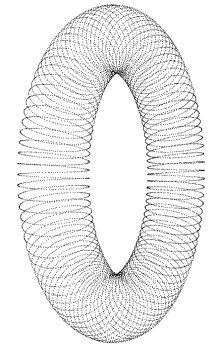
DataShape - Inria Saclay

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The TDA pipeline: persistent homology

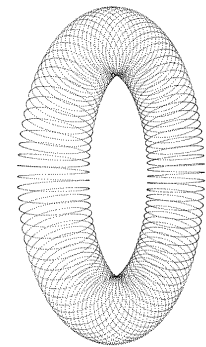
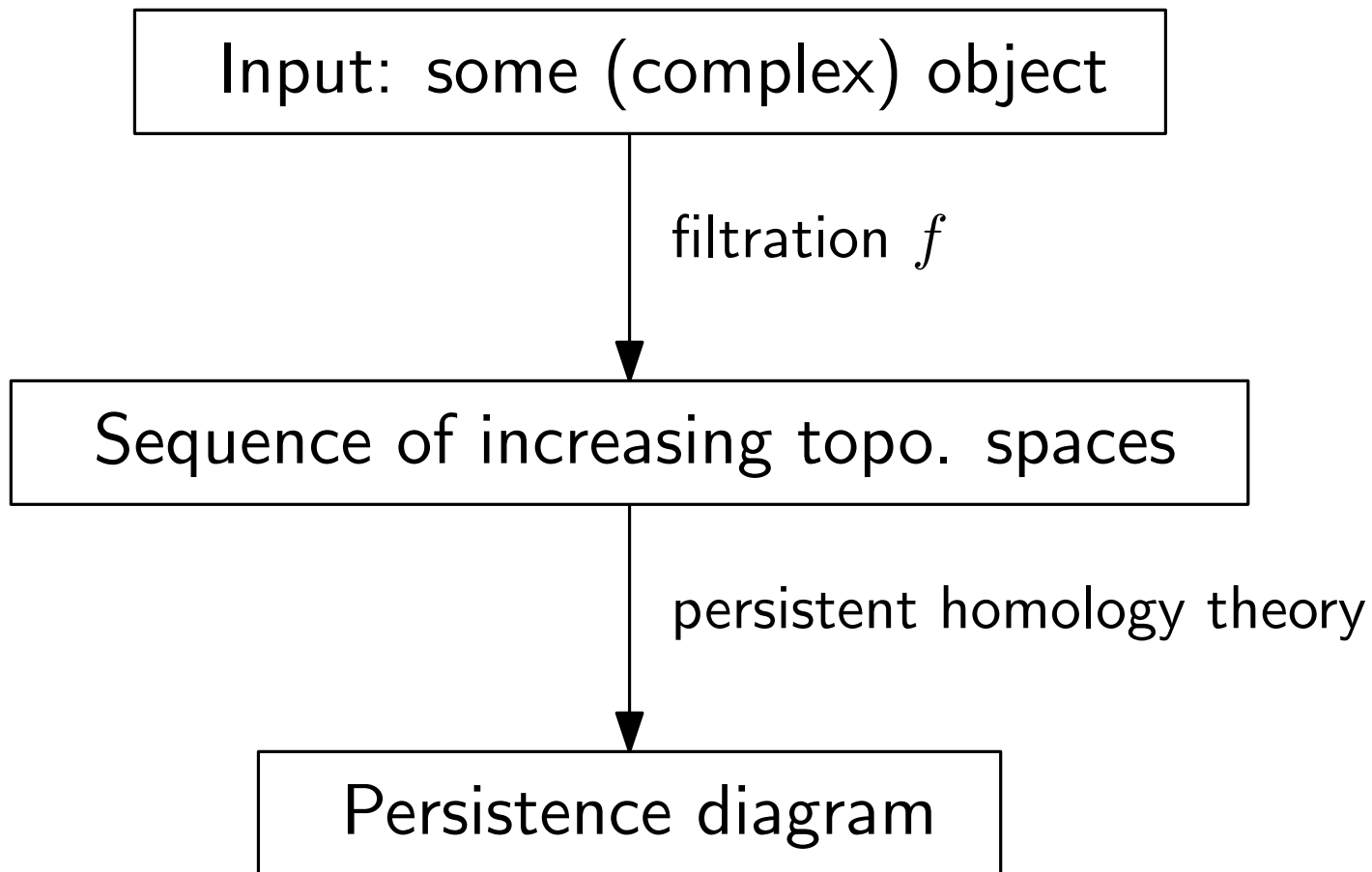
A (very) concise summary:

Input: some (complex) object

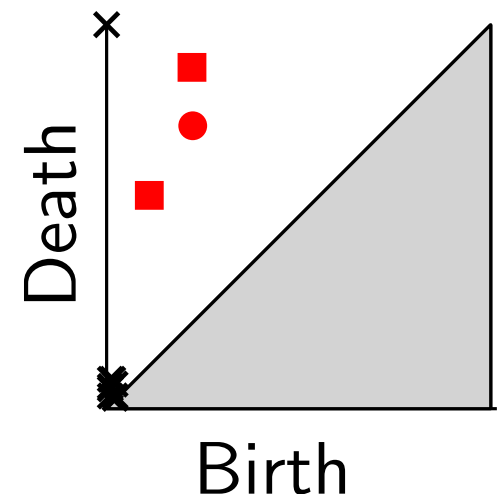


The TDA pipeline: persistent homology

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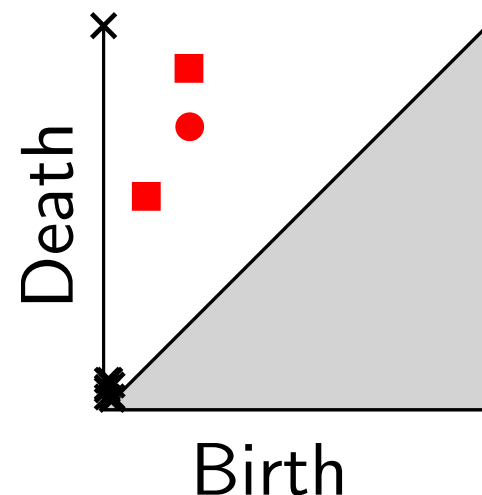
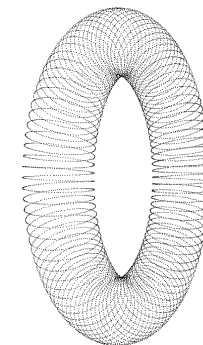
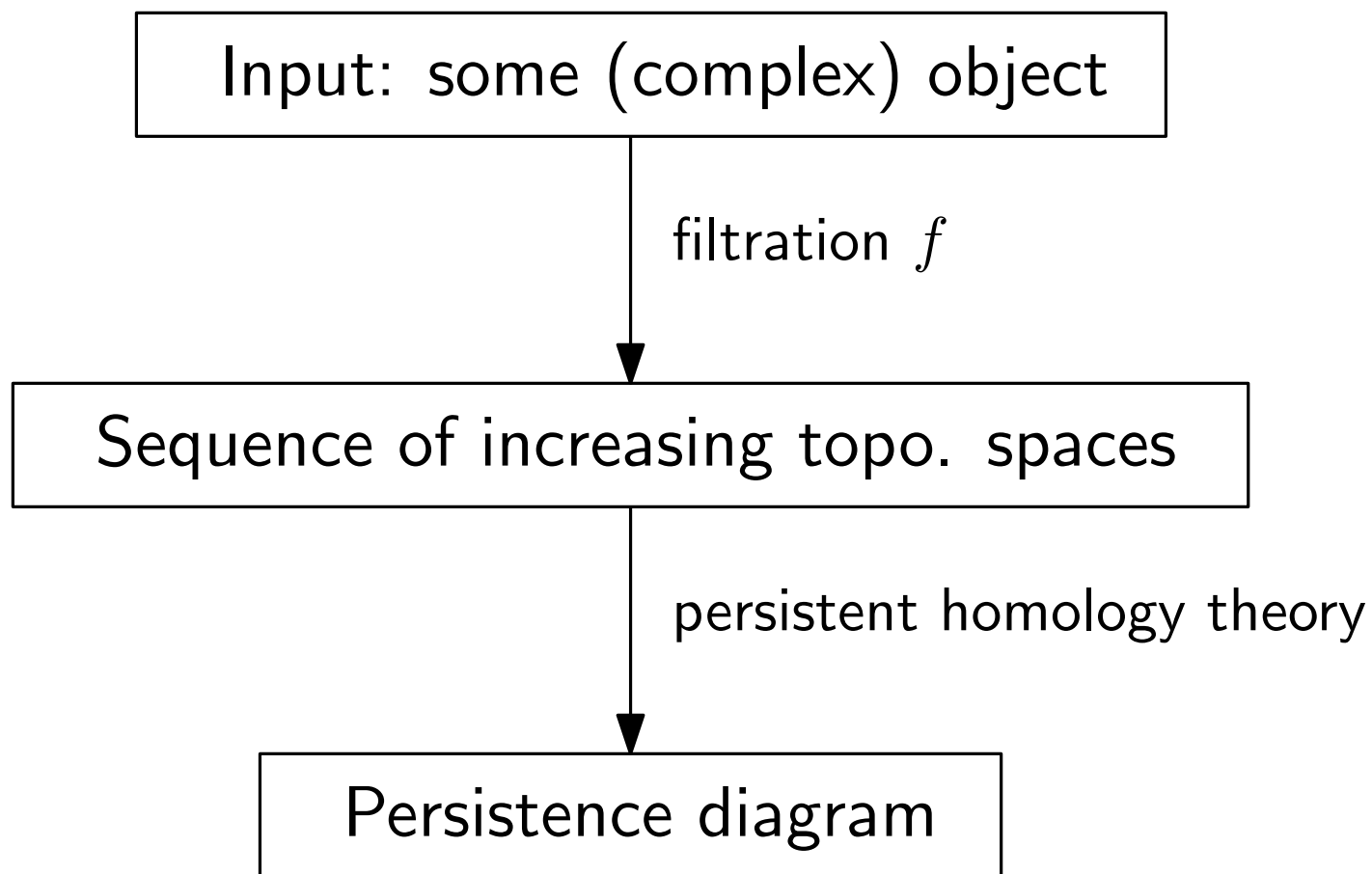


- Point cloud on the plane
 $\{x_1 \dots x_i \dots\}$



The TDA pipeline: persistent homology

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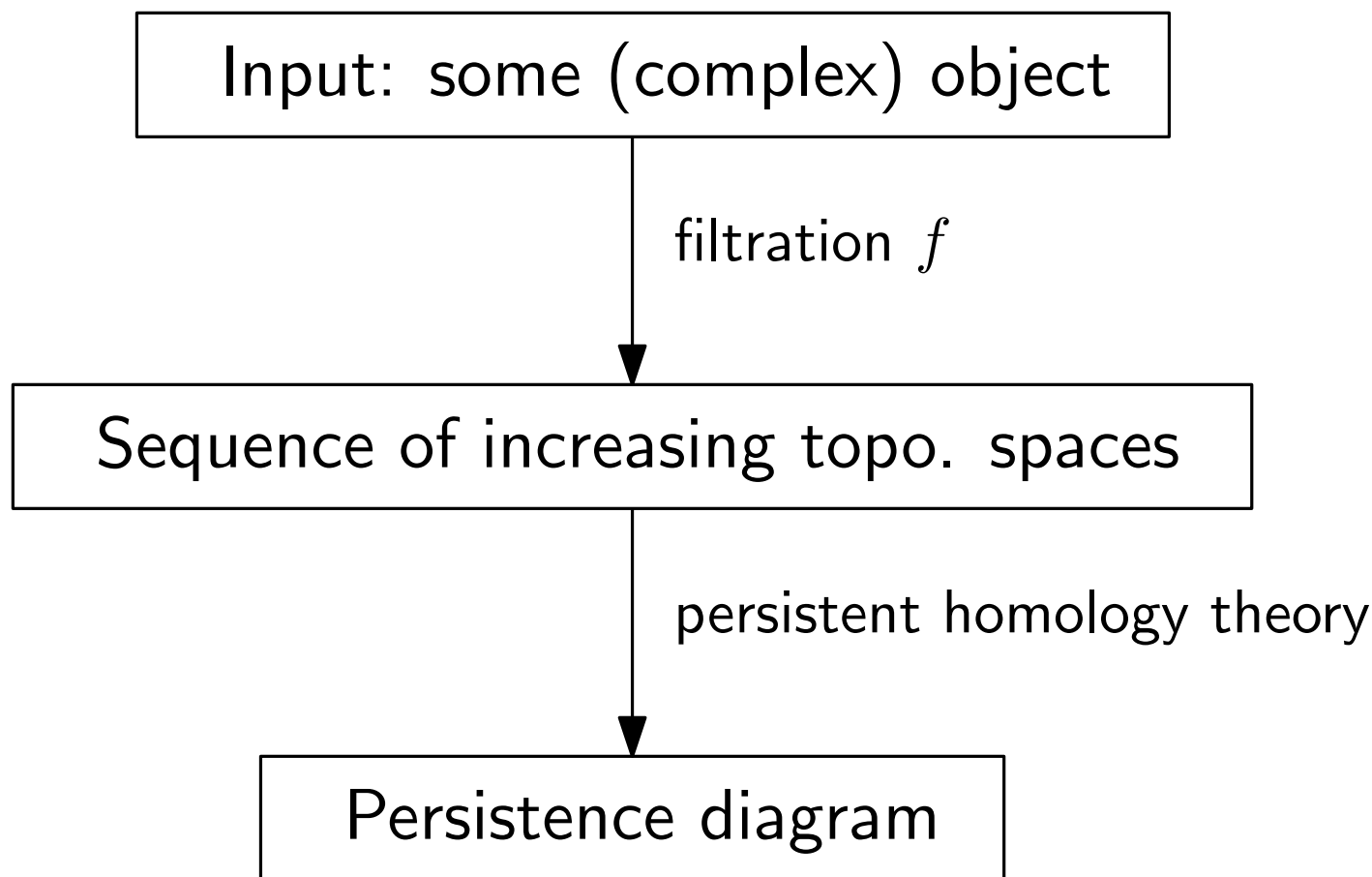


- Radon measures (locally finite Borel measures)

$$\{x_1 \dots x_i \dots\} \leftrightarrow \sum_i \delta_{x_i}$$

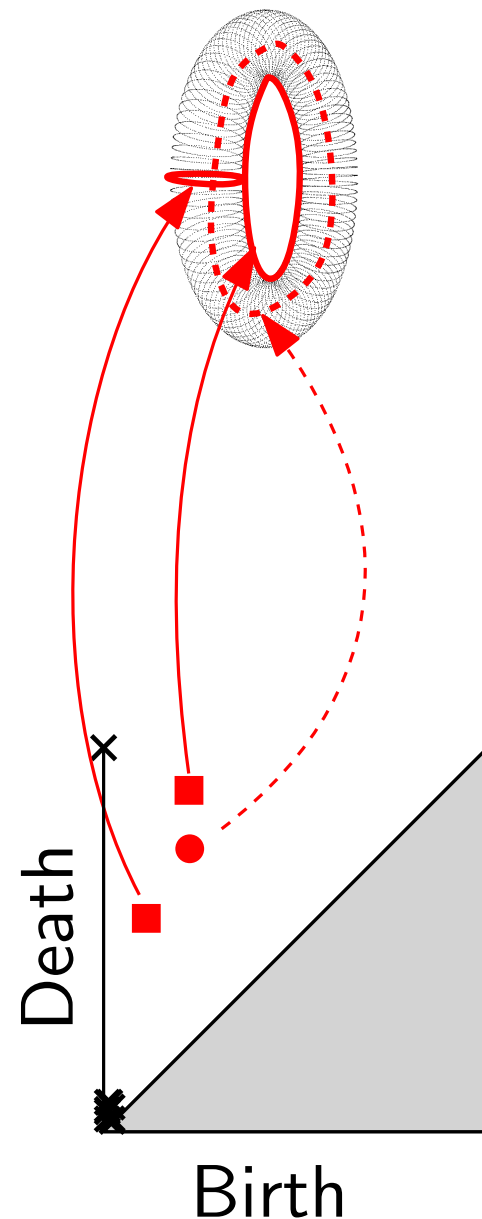
The TDA pipeline: persistent homology

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The space of persistence diagrams (\mathcal{D}^p, d_p)

Persistence diagrams are comparable

- Using matching-like metrics

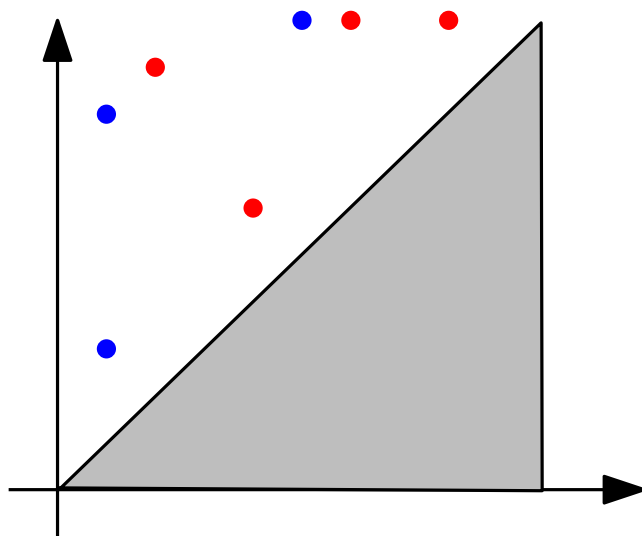
$$d_p(a, b) = \left(\inf_{\zeta} \sum_{(x, y) \in \zeta} \|x - y\|^p + \sum_{u \notin \zeta} \|u - s(u)\|^p \right)^{1/p}$$

partial matching

matched points

unmatched points

proj on diag



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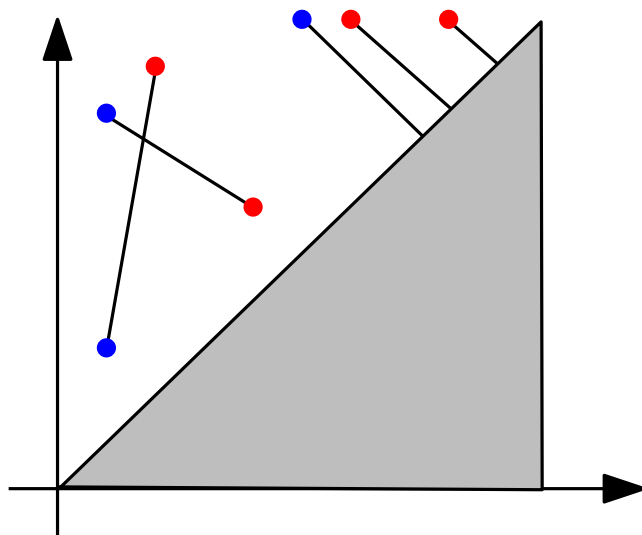
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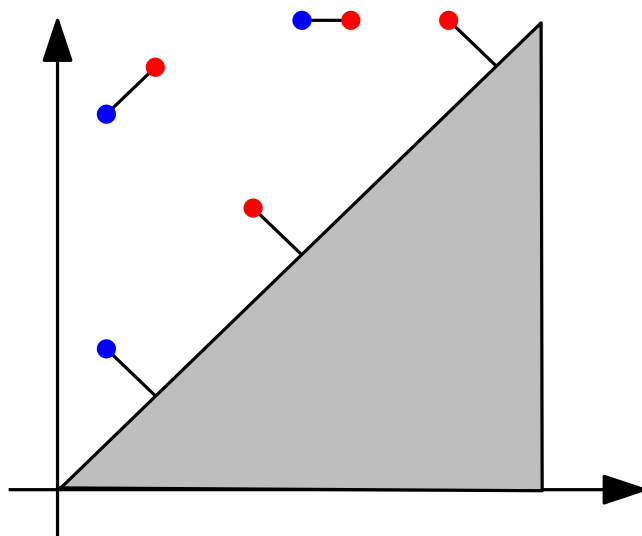
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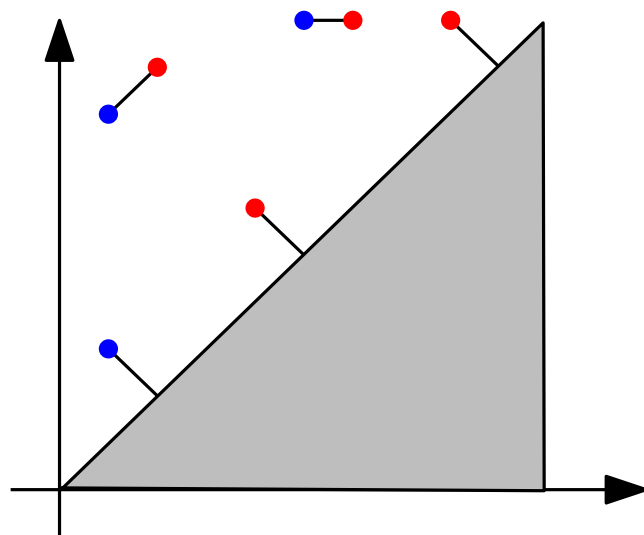
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- Theoretically motivated
- Stable wrt input data

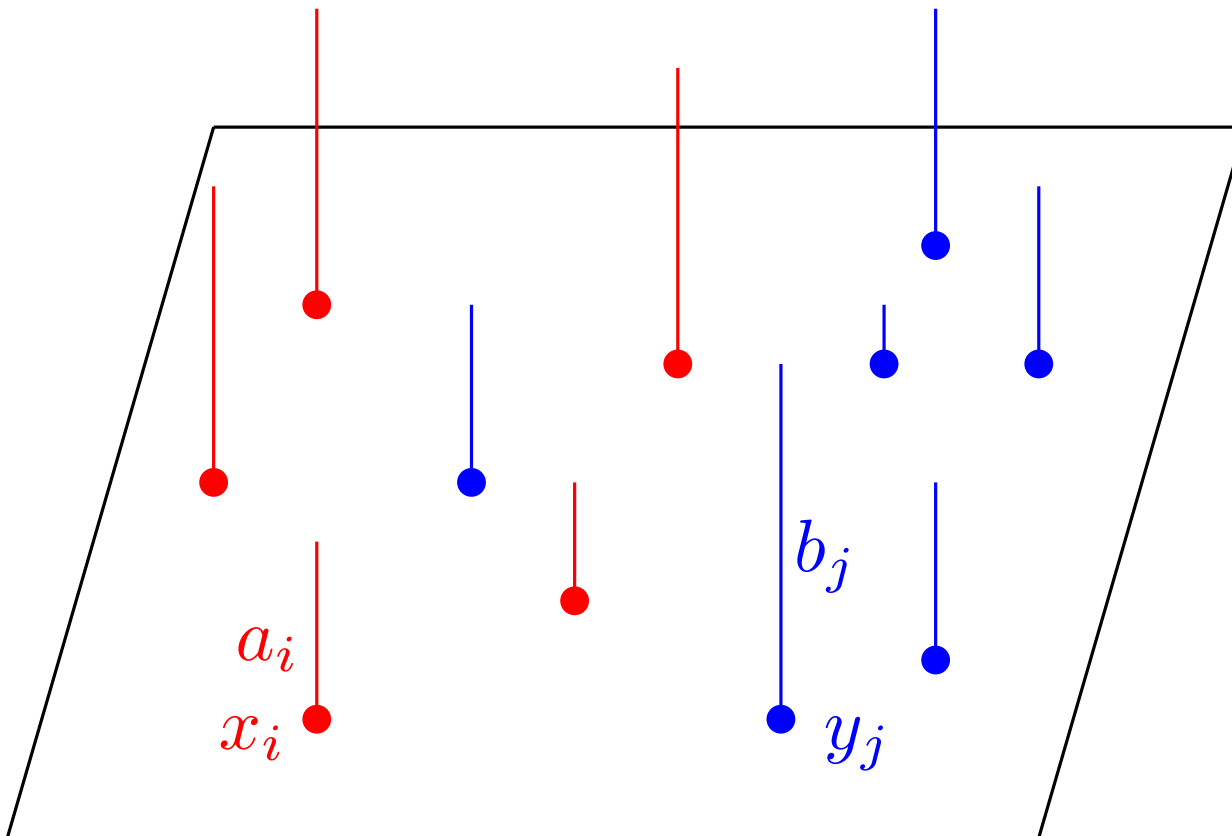
Assume also

$$d_p(a, \emptyset) < \infty$$

Optimal Transport - Generalities

Discrete formulation : μ and ν two probability measures

$$\mu = \sum_i a_i \delta_{x_i} \quad \nu = \sum_j b_j \delta_{y_j}$$

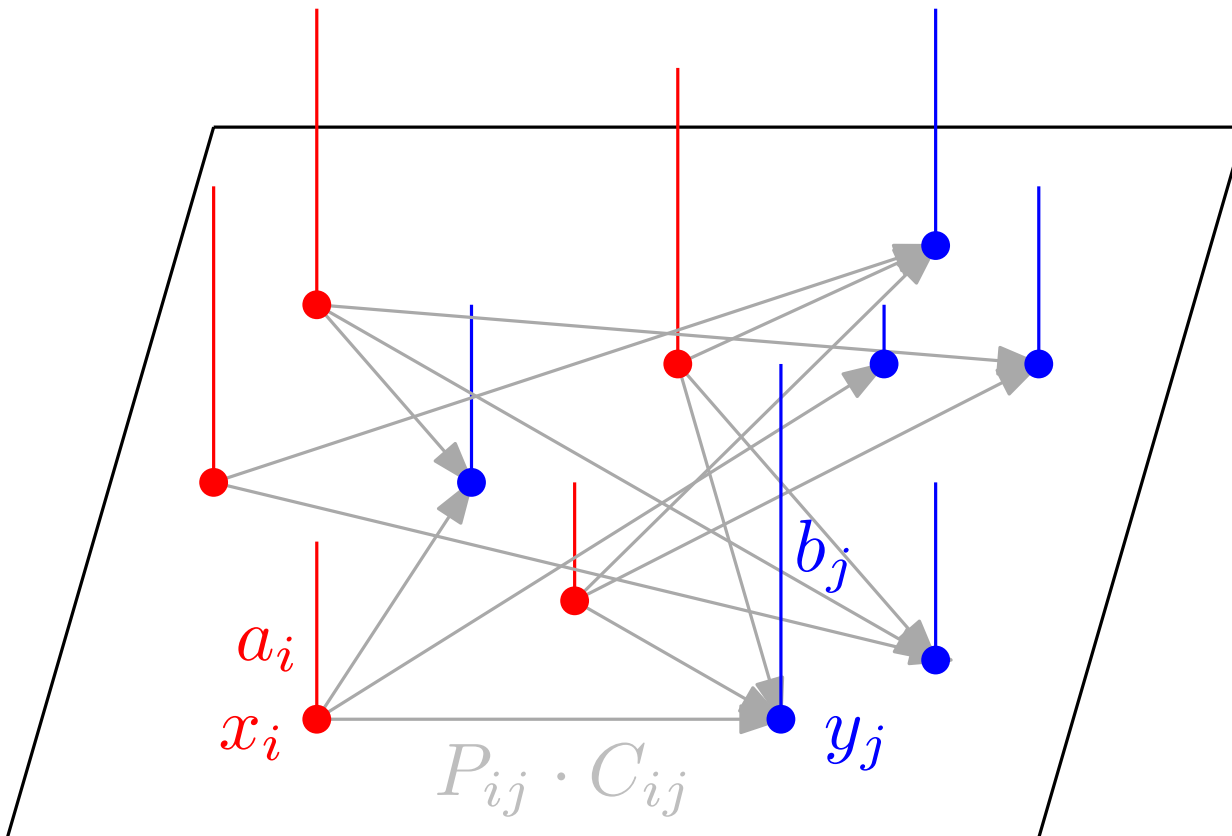


Optimal Transport - Generalities

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$$\mu = \sum_i a_i \delta_{x_i} \quad \nu = \sum_j b_j \delta_{y_j}$$

(P_{ij}) transport plan between μ and ν



$$\sum_j P_{ij} = a_i$$

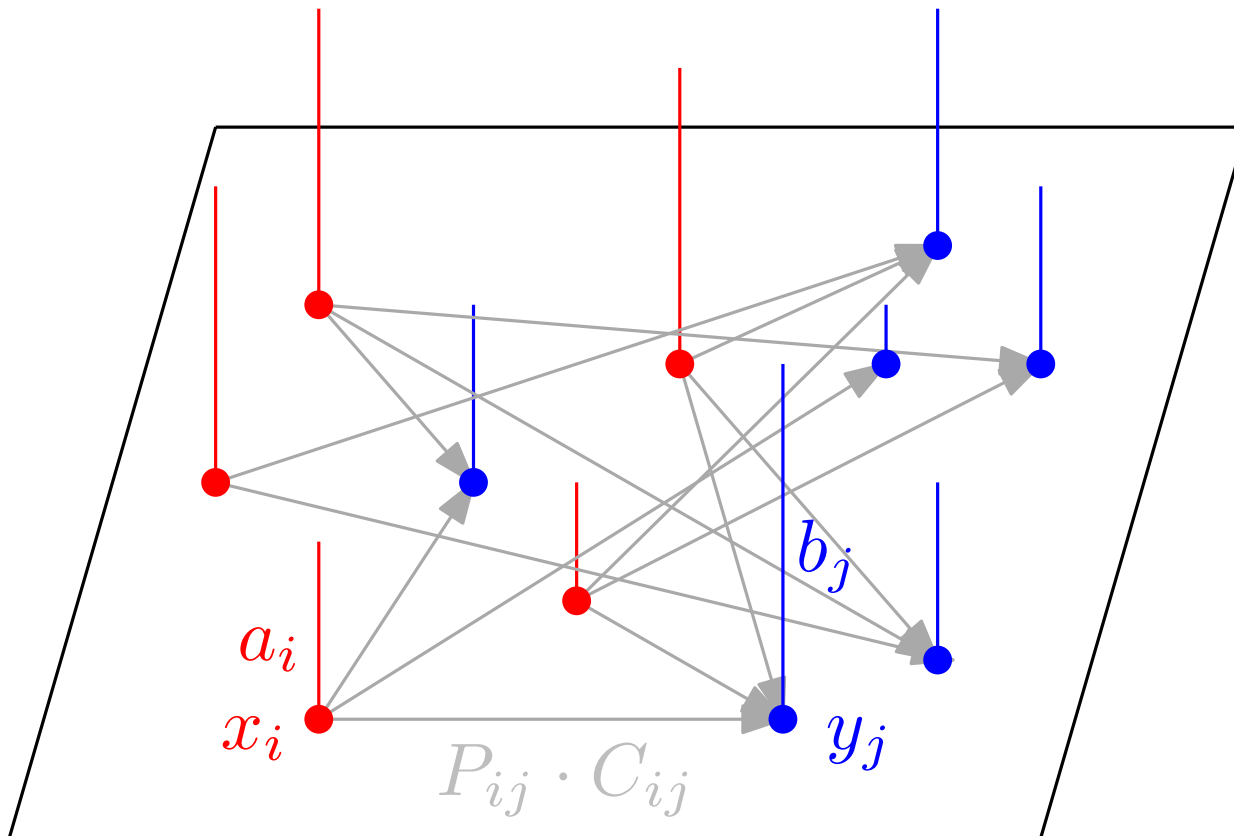
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Optimal Transport - Generalities

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$$\mu = \sum_i a_i \delta_{x_i} \quad \nu = \sum_j b_j \delta_{y_j}$$

$$\langle P, C \rangle = \sum_{ij} P_{ij} C_{ij}$$



where

$$C_{ij} = d(x_i, y_j)^p$$

subject to

$$\sum_j P_{ij} = a_i$$

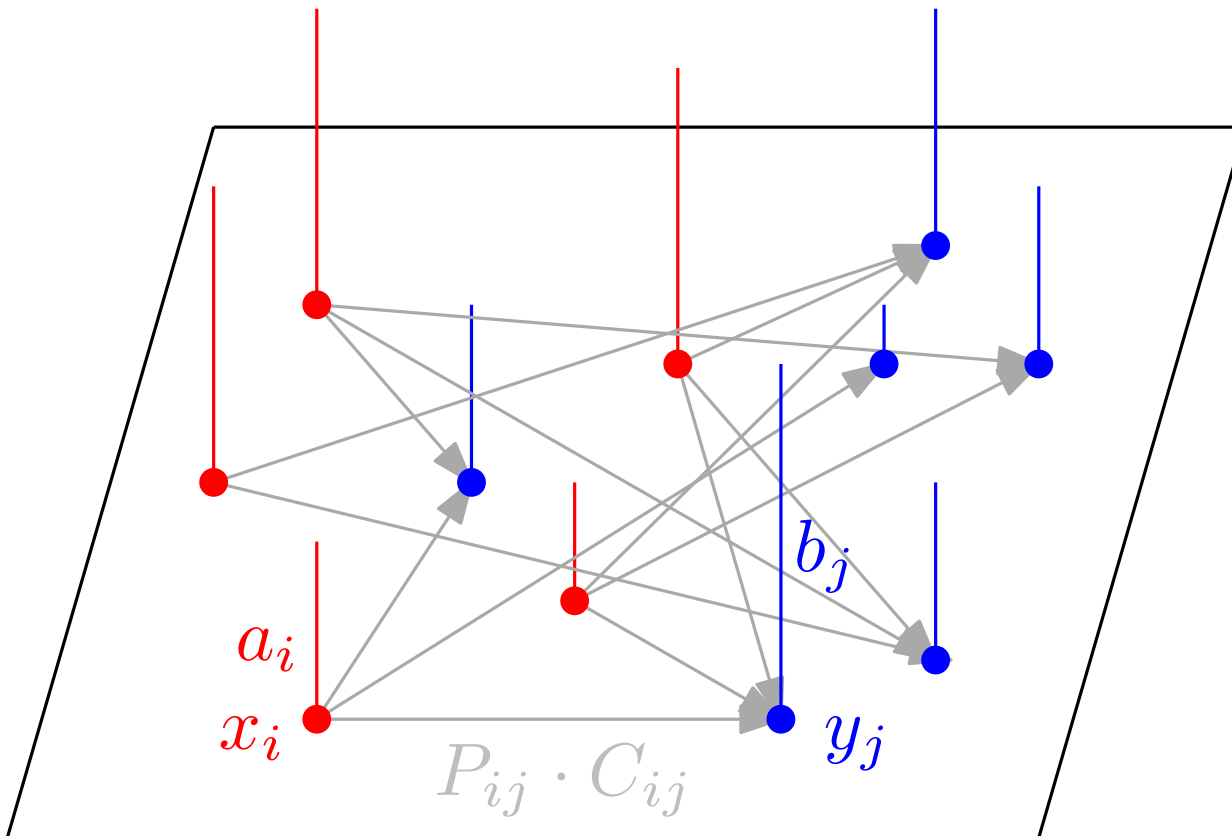
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Discrete formulation : μ and ν two probability measures

$$\mu = \sum_i a_i \delta_{x_i} \quad \nu = \sum_j b_j \delta_{y_j}$$

$$W_p(\mu, \nu)^p = \inf_P \langle P, C \rangle = \inf_P \sum_{ij} P_{ij} C_{ij}$$



where

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subject to

$$\sum_j P_{ij} = a_i$$

$$\sum_i P_{ij} = b_j$$

Optimal Transport - Generalities

General formulation

Consider μ, ν two probability measures on a Polish metric space (\mathcal{X}, d)

$\pi \in \mathcal{M}(\mathcal{X} \times \mathcal{X})$ is a *transport plan* between μ and ν if

$$\pi(A, \mathcal{X}) = \mu(A) \text{ and } \pi(\mathcal{X}, B) = \nu(B)$$

The cost of π is $C_p(\pi) := \iint_{\mathcal{X} \times \mathcal{X}} d(x, y)^p d\pi(x, y)$

and the Wasserstein- p distance between μ and ν is

$$W_p(\mu, \nu) = \left(\inf_{\pi} C_p(\pi) \right)^{\frac{1}{p}}$$

Optimal Transport - Generalities

Properties:

- W_p is a distance over $\{\mu \in \mathcal{P}(\mathcal{X}) : \overbrace{\int_{\mathcal{X}} d(x, x_0)^p d\mu(x)}^{W_p(\mu, \delta_{x_0})^p} < \infty\}$
- It metricizes the weak convergence and the p -th moment convergence.

$$W_p(\mu_n, \mu) \rightarrow 0 \Leftrightarrow \begin{cases} \mu_n \rightarrow \mu \text{ weakly} \\ W_p(\mu_n, \delta_{x_0}) \rightarrow W_p(\mu, \delta_{x_0}) \end{cases}$$

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Reminder:

- $\mu_n \rightarrow \mu$ *weakly* means:

for all f continuous, bounded, $\int_{\mathcal{X}} f(x) d\mu_n(x) = \mu_n(f) \rightarrow \mu(f)$

- $\mu_n \rightarrow \mu$ *vaguely* means:

for all f continuous, compactly supported, $\mu_n(f) \rightarrow \mu(f)$

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- And many other nice properties:
 - Know about barycenters (Fréchet means).
 - Know the geodesics.
 - Many numerical tools (algorithms, libraries)...

Bridging TDA and OT

Persistence Diagrams (\mathcal{D}^p, d_p)

Optimal Transport (\mathcal{W}^p, W_p)

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- Discrete support (+integer mass)

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- General support

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- Measures same masses

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- *Partial* matching distances (can match to the diagonal)

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- Exact *transportation* distances

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Optimal Transport (\mathcal{W}^p, W_p)

- General support
- Measures same masses
- Exact *transportation* distances
- Well-studied theoretically
- Efficient algorithms/libraries

Optimal Partial Transport

Various ways to extend OT to measures with different masses

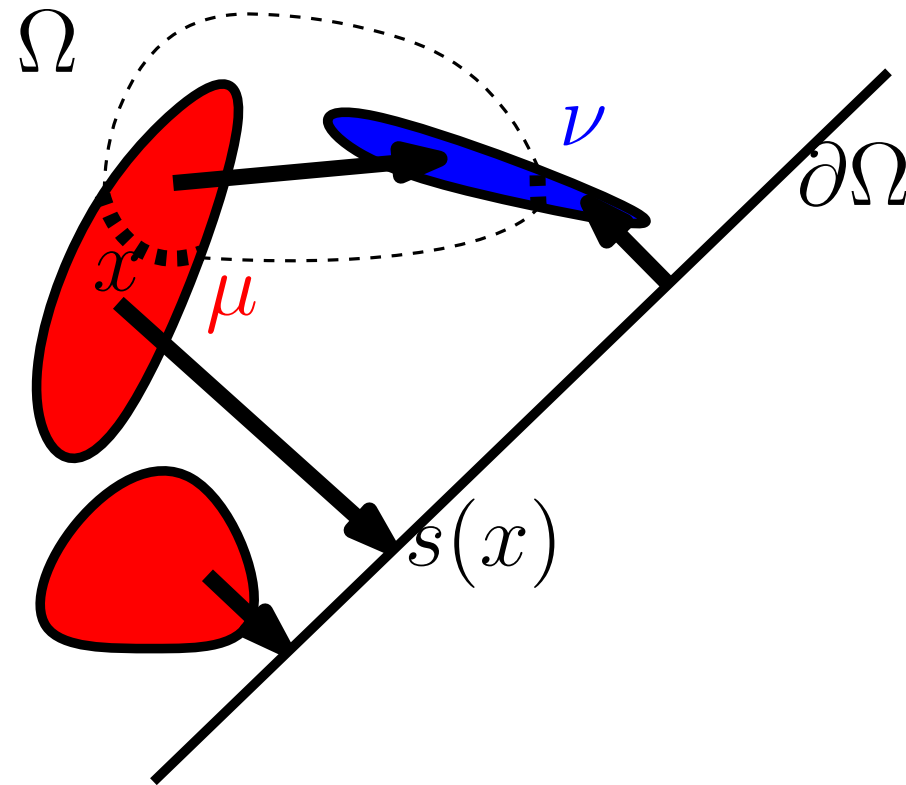
→ see [Chizat, 2017]

Optimal Partial Transport

Various ways to extend OT to measures with different masses

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A. Figalli and N. Gigli (2010)



Introduced to study heat equation with Dirichlet boundary conditions

Optimal Partial Transport

Core idea: Just consider sub-marginal constraints!

Let $\partial\Omega$ be the boundary of Ω , and $\overline{\Omega} = \Omega \cup \partial\Omega$

Given μ, ν two Radon measures on Ω , consider admissible transport plans

$$\begin{aligned} \pi \in \mathcal{M}(\overline{\Omega} \times \overline{\Omega}) \quad \text{such that} \quad & \pi(A \times \overline{\Omega}) = \mu(A) \quad A \subset \Omega \\ & \pi(\overline{\Omega} \times B) = \nu(B) \quad B \subset \Omega \end{aligned}$$

And then just define

$$C_p(\pi) = \iint_{\overline{\Omega} \times \overline{\Omega}} d(x, y)^p d\pi(x, y)$$

$$\text{OT}_p(\mu, \nu) = \left(\inf_{\pi \in \text{Adm}(\mu, \nu)} C_p(\pi) \right)^{1/p}$$

Rem: measures must satisfy $\int_{\Omega} d(x, \partial\Omega)^p d\mu(x) < +\infty$

Studying (\mathcal{D}^p, d_p) using Optimal Partial Transport

Equivalence of formalisms [Divol, L, 2019]

If a, b are persistence diagrams, then $\text{OT}_p(a, b) = d_p(a, b)$

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Elements for the proof:

- Assume a and b are finite (masses n_1, n_2), let $n = n_1 + n_2$.

\mathfrak{S}_n : permutation matrices, \mathcal{B}_n : bi-stochastic matrices.

- We must show that $\inf_{P \in \mathcal{B}_n} \langle P, C \rangle = \inf_{A \in \mathfrak{S}_n} \langle A, C \rangle$

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Question: Is there a direct proof in infinite dimension?

Studying (\mathcal{D}^p, d_p) using Optimal Partial Transport

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Convergence in (\mathcal{D}^p, d_p)

- We have $d_p(a_n, a) \rightarrow 0 \Leftrightarrow \begin{cases} a_n \rightarrow a \text{ vaguely} \\ d_p(a_n, \emptyset) \rightarrow d_p(a, \emptyset) \end{cases}$

Barycenters of persistence diagrams

\mathcal{D}^p is a Polish space [Mukherjee et al. 2011]

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Fréchet means (aka barycenters):

Consider $b_1 \dots b_N$ a set of diagrams

Estimating their Fréchet mean consists in computing

$$\operatorname{argmin} \left\{ \mathcal{E}(a) = \frac{1}{N} \sum_{i=1}^N d_2(a, b_i)^2, \text{ } a \text{ persistence diagram} \right\}.$$

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First results [Turner et al. 2013]:

- \mathcal{E} is not convex. It admits global (and local) minimizers
- Local minimizers can be computed (expensive)

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Properties [Divol, L, 2019]

- \mathcal{E} is now convex, admits global minimizers.
- Some of them are actual diagrams.

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$\operatorname{OT}_2(a, b)^2, a \text{ any Radon measure}$

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- Some of them are actual diagrams.

Numerical considerations [L, Cuturi, Oudot, 2018]

- These can be approximated efficiently (Sinkhorn algorithm).

Conclusion

Take home messages:

- Optimal transport can be extended (in various ways) to handle measures with different masses
- Figalli&Gigli's formulation (2010) of Optimal Partial Transport is a powerful tool to study TDA objects.
(and Radon measures in general)