

# FOSTER: Feature Boosting and Compression for Class-Incremental Learning

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#### **Abstract**

- Background
  - The ability to learn new concepts continually is necessary in this ever-changing world
  - Deep neural networks suffer from catastrophic forgetting when learning new concepts
  - Stability-plasticity dilemma or too much computation or storage overhead
- Proposed method
  - Feature boOSTing and comprEssion for class-incRemental learning (FOSTER)
  - A novel two-stage learning paradigm for adaptive learning of new categories
    - 1) Dynamically expand new modules to fit the residual between the target and the previous output
    - 2) Remove redundant parameters and features via distillation to maintain a single backbone



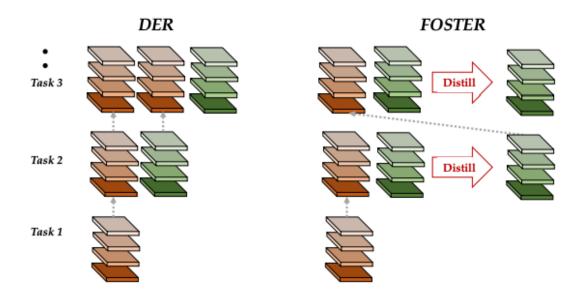
#### Introduction

- Class-incremental learning (CIL)
  - Retraining a model every time new classes emerge is impractical due to high training costs
  - Directly fine-tuning the original neural networks on new data causes catastrophic forgetting
- Knowledge distillation (KD)
  - The most widely recognized and utilized class-incremental learning strategy
  - Constrain the outputs of the new model for old tasks to be similar to that of the old model
- Dynamic architectures
  - Methods based on dynamic architectures achieve state-of-the-art performance
  - Preserve old modules (parameters frozen) and expand new trainable modules for new classes
  - Increase in the number of parameters and inconsistency between the old and new features



#### Introduction

- FOSTER
  - A two-step novel perspective from gradient boosting
  - 1) Apply **feature level boosting** to alleviate the performance decline in incremental settings
  - 2) Eliminate redundant parameters and meaningless dimensions caused by feature boosting





#### Introduction

- Gradient boosting
  - Iteratively trains the weak learners that predict the error (residual) between the outputs
  - $e_t(x_i)$  is decomposed into round t prediction  $h_t(x_i)$  and the residual  $e_{t+1}(x_i)$ ;  $h_0(x_i) = 0$

$$y_i = h_0(x_i) + e_1(x_i)$$
 $e_1(x_i) = h_1(x_i) + e_2(x_i)$ 
 $e_2(x_i) = h_2(x_i) + e_3(x_i)$ 
 $e_t(x_i) = h_t(x_i) + e_{t+1}(x_i)$ 
 $Error$ 
 $decreases$ 



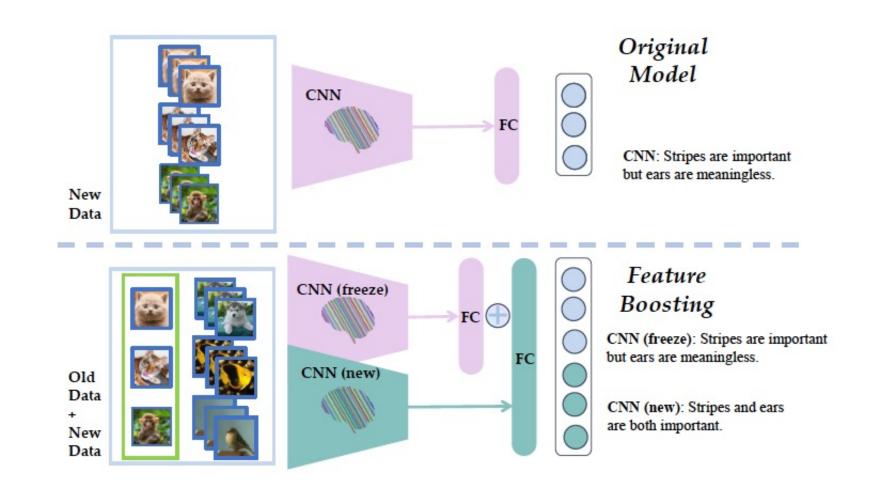
#### **Methods**

- I. Feature boosting
  - Freeze the old model and create a new module to fit the residuals from the old model
  - The new module helps the model learn both the old and new classes better

#### II. Feature compression

- Remove insignificant dimensions and parameters to make compact representations
- Instruct the compressed model using the outputs of the dual branch model
- Different weights are assigned to old and new classes to alleviate the classification bias







- Incremental settings
  - Assume in the  $t^{\text{th}}$  stage,  $F_{t-1}$  is the model saved from the last stage
  - $F_{t-1}$  can be further decomposed into **feature embedding** and **linear classifier**

$$F_{t-1}(\mathbf{x}) = (\mathbf{W}_{t-1})^{\mathsf{T}} \Phi_{t-1}(\mathbf{x})$$
where  $\Phi_{t-1}(\cdot): \mathbb{R}^D \to \mathbb{R}^d$ ,  $\mathbf{W}_{t-1} \in \mathbb{R}^{d \times |\hat{\mathcal{Y}}_{t-1}|}$ 

- Directly fine-tuning  $F_{t-1}$  on new data will impair its capacity for old classes
- Simply freezing  $F_{t-1}$  causes it to lose plasticity for new classes
- What if we train a new model to **fit the residuals** between target y and  $F_{t-1}(x)$ ?

- Training process
  - The new model  $\mathcal{F}_t$  consists of a feature extractor  $\phi_t(\cdot)$  and a linear classifier  $\mathcal{W}_t$

$$\phi_t(\cdot): \mathbb{R}^D \to \mathbb{R}^d, \ \mathcal{W}_t \in \mathbb{R}^{d \times |\hat{\mathcal{Y}}_t|}, \ \mathcal{W}_t = \left[\mathcal{W}_t^{(o)}, \mathcal{W}_t^{(n)}\right]$$

$$where \ \mathcal{W}_t^{(o)} \in \mathbb{R}^{d \times |\hat{\mathcal{Y}}_{t-1}|}, \ \mathcal{W}_t^{(n)} \in \mathbb{R}^{d \times |\mathcal{Y}_t|}$$

• The **training process** can be represented as below (let  $\ell(\cdot,\cdot)$  be the mean squared error)

$$F_t(\mathbf{x}) = F_{t-1}(\mathbf{x}) + \arg\min_{\mathcal{F}_t} \mathbb{E}_{(\mathbf{x}, y) \in \widehat{\mathcal{D}}_t} \left[ \ell(y, F_{t-1}(\mathbf{x}) + \mathcal{F}_t(\mathbf{x})) \right]$$

- Ideal expression of target y
  - We expect  $\mathcal{F}_t(x)$  can fit residuals of y and  $F_{t-1}(x)$  for every  $(x,y) \in \widehat{\mathcal{D}}_t$
  - $S(\cdot)$  is the softmax and  $\mathbf{0} \in \mathbb{R}^{d \times |\mathcal{Y}_t|}$  set to zero matrix or fine-tuned on  $\widehat{\mathcal{D}}_t$  with  $\Phi_{t-1}$  frozen
  - Set **O** to zero matrix as default for experiments

$$\mathbf{y} = \mathbf{F}_{t-1}(\mathbf{x}) + \mathcal{F}_t(\mathbf{x}) = S\left(\begin{bmatrix} \mathbf{W}_{t-1}^{\mathsf{T}} \\ \mathbf{0} \end{bmatrix} \Phi_{t-1}(\mathbf{x})\right) + S\left(\begin{bmatrix} (\mathcal{W}_t^{(o)})^{\mathsf{T}} \\ (\mathcal{W}_t^{(n)})^{\mathsf{T}} \end{bmatrix} \phi_t(\mathbf{x})\right)$$

- Optimization problem
  - Denote the parameters of  $\mathcal{F}_t$  as  $\theta_t$  and  $\mathrm{Dis}(\cdot,\cdot)$  as a **distance matrix** (e.g., Euclidean metric)

$$\theta_t^* = \arg\min_{\theta_t} \operatorname{Dis} \left( \mathbf{y}, S\left( \begin{bmatrix} \mathbf{W}_{t-1}^\mathsf{T} \\ \mathbf{0} \end{bmatrix} \Phi_{t-1}(\mathbf{x}) \right) + S\left( \begin{bmatrix} (\mathcal{W}_t^{(o)})^\mathsf{T} \\ (\mathcal{W}_t^{(n)})^\mathsf{T} \end{bmatrix} \phi_t(\mathbf{x}) \right) \right)$$

• Replace  $S(\cdot) + S(\cdot)$  with  $S(\cdot + \cdot)$  and substitute  $Dis(\cdot, \cdot)$  for the **Kullback-Leibler divergence** 

$$\theta_t^* = \arg\min_{\theta_t} KL \left( \boldsymbol{y} \left\| S \left( \begin{bmatrix} \boldsymbol{W}_{t-1}^{\mathsf{T}} & (\mathcal{W}_t^{(o)})^{\mathsf{T}} \\ \boldsymbol{0} & (\mathcal{W}_t^{(n)})^{\mathsf{T}} \end{bmatrix} \begin{bmatrix} \Phi_{t-1}(\boldsymbol{x}) \\ \phi_t(\boldsymbol{x}) \end{bmatrix} \right) \right)$$

- Module expansion
  - $F_t$  consists of an expanded classifier  $W_t$  and a concatenated super feature extractor  $\Phi_t(\cdot)$

$$\mathbf{W}_{t}^{\mathsf{T}} = \begin{bmatrix} \mathbf{W}_{t-1}^{\mathsf{T}} & (\mathcal{W}_{t}^{(o)})^{\mathsf{T}} \\ \mathbf{0} & (\mathcal{W}_{t}^{(n)})^{\mathsf{T}} \end{bmatrix}, \qquad \Phi_{t}(\mathbf{x}) = \begin{bmatrix} \Phi_{t-1}(\mathbf{x}) \\ \phi_{t}(\mathbf{x}) \end{bmatrix}$$

•  $\mathbf{W}_{t-1}^{\mathsf{T}}$ ,  $\mathbf{0}$ ,  $\Phi_{t-1}$  are all frozen and the trainable modules are  $\phi_t$ ,  $\mathcal{W}_t^{(o)}$ ,  $\mathcal{W}_t^{(n)}$ 

$$\mathbf{F}_{t}(\mathbf{x}) = \mathbf{W}_{t}^{\mathsf{T}} \mathbf{\Phi}_{t}(\mathbf{x}) = \begin{bmatrix} \mathbf{W}_{t-1}^{\mathsf{T}} \mathbf{\Phi}_{t-1}(\mathbf{x}) + (\mathcal{W}_{t}^{(o)})^{\mathsf{T}} \phi_{t}(\mathbf{x}) \\ (\mathcal{W}_{t}^{(n)})^{\mathsf{T}} \phi_{t}(\mathbf{x}) \end{bmatrix}$$



- Logits of F<sub>t</sub> explained
  - a) The logits of the old classes ensure the new module to fit the residuals between y and  $F_{t-1}$
  - b) The logits of new classes guide the new module  $\mathcal{F}_t$  to learn to correctly classify new classes

$$\mathbf{F}_{t}(x) = \mathbf{W}_{t}^{\mathsf{T}} \mathbf{\Phi}_{t}(\mathbf{x}) = \begin{bmatrix} \mathbf{W}_{t-1}^{\mathsf{T}} \mathbf{\Phi}_{t-1}(\mathbf{x}) + (\mathcal{W}_{t}^{(o)})^{\mathsf{T}} \phi_{t}(\mathbf{x}) \\ (\mathcal{W}_{t}^{(n)})^{\mathsf{T}} \phi_{t}(\mathbf{x}) \end{bmatrix} \quad \begin{array}{c} \cdots & a \\ \cdots & b \end{array}$$

- Calibration for old and new
  - Imbalanced training set when training on new tasks  $(\widehat{\mathcal{D}}_t = \mathcal{D}_t \cup \mathcal{V}_t)$
  - The imbalance on categories of  $\widehat{\mathcal{D}}_t$  result in a strong classification bias in the model
- Logits alignment (LA)
  - Strengthen the learning of old instances and mitigate the classification bias
  - Add scale factor  $\gamma$  (a diagonal matrix) to the logits of the old and new classes

$$\gamma \mathbf{W}_{t}^{\mathsf{T}} \Phi_{t}(\mathbf{x}) = \begin{bmatrix} \gamma_{1} \left( \mathbf{W}_{t-1}^{\mathsf{T}} \Phi_{t-1}(\mathbf{x}) + \left( \mathcal{W}_{t}^{(o)} \right)^{\mathsf{T}} \phi_{t}(\mathbf{x}) \right) \\ \gamma_{2} (\mathcal{W}_{t}^{(n)})^{\mathsf{T}} \phi_{t}(\mathbf{x}) \end{bmatrix}, \quad 0 < \gamma_{1} < 1, \quad \gamma_{2} > 1$$

- Logits alignment continued
  - The absolute value of logits reduced for old classes and enlarged for new classes
  - Force  $F_t$  to produce larger logits for old classes and smaller logits for new classes
  - Scale factors  $\gamma_1$ ,  $\gamma_2$  are acquired from the normalized effective number  $E_n$  of each class

$$E_n = \begin{cases} \frac{1 - \beta^n}{1 - \beta}, & \beta \in [0, 1) \\ n, & \beta = 1 \end{cases}$$

$$(\gamma_1, \gamma_2) = \left(\frac{E_{n_{old}}}{E_{n_{old}} + E_{n_{new}}}, \frac{E_{n_{new}}}{E_{n_{old}} + E_{n_{new}}}\right)$$



- Feature enhancement (FE)
  - Assume an extreme scenario where the **residuals of**  $F_{t-1}(x)$  and y is zero
  - The new module will not learn anything about the old classes and damage the performance
  - Prompt the new module  $\mathcal{F}_t$  to further learn old categories through feature enhancement
  - Initialize a new linear classifier  $\mathbf{W}_t^{(a)} \in \mathbb{R}^{d \times |\hat{\mathcal{Y}}_t|}$  for the classification of all seen classes
  - The new feature extractor can still learn to classify the old classes even if the residual is zero

$$\mathcal{L}_{FE} = KL\left(\mathbf{y} \mid S\left(\left(\mathbf{W}_{t}^{(a)}\right)^{\mathsf{T}} \phi_{t}(\mathbf{x})\right)\right)$$



- Feature enhancement continued
  - Training  $\phi_t(\cdot)$  in an imbalanced dataset might lead to **overfitting to small classes**
  - Knowledge distillation to make  $F_t(x)$  have similar output distribution as  $F_{t-1}(x)$  on old data
  - Learn a feature representation with good generalizability for old classes

$$\mathcal{L}_{KD} = KL\left(S(F_{t-1}(\mathbf{x})) \left\| S\left(F_{t-1}(\mathbf{x}) + \left(\mathcal{W}_{t}^{(o)}\right)^{\mathsf{T}} \phi_{t}(\mathbf{x})\right)\right)$$



- Loss function
  - The final FOSTER loss for boosting combines the three components aforementioned

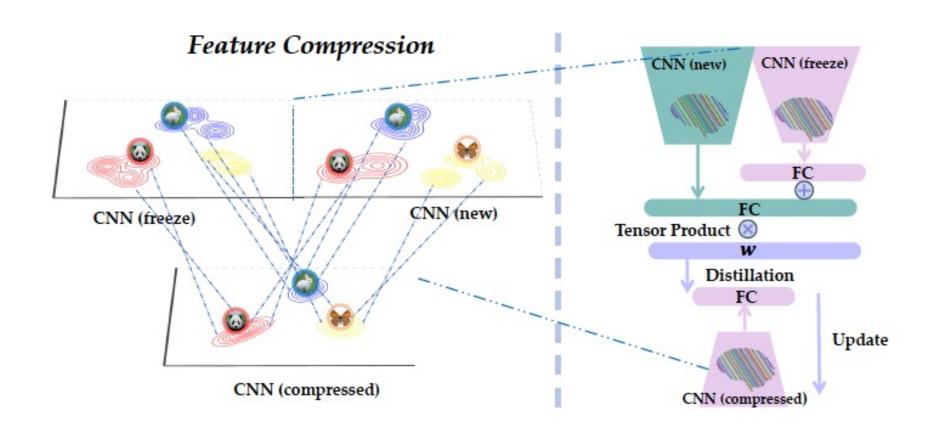
$$\mathcal{L}_{Boosting} = \mathcal{L}_{LA} + \mathcal{L}_{FE} + \mathcal{L}_{KD}$$

Logits alignment loss is as follows:

$$\mathcal{L}_{LA} = KL\left(\mathbf{y} \mid S(\gamma \mathbf{W}_t^{\mathsf{T}} \Phi_t(\mathbf{x}))\right)$$



## **Feature Compression**





#### **Feature Compression**

- Loss function
  - Gradually adding a new module leads to overfull of parameters and feature dimensions
  - Compress the expanded feature space to a smaller one for long-term applicability
  - Knowledge distillation is a simple yet effective way to achieve this goal
- Balanced distillation (BKD)
  - Suppose there is a **single backbone** student model  $F_t^{(s)}$  to be distilled
  - Adjust the weights of distilled information for different classes to mitigate classification bias
  - w is the weighted vector obtained from  $E_n$  and  $\otimes$  refers to the tensor product

$$\mathcal{L}_{BKD} = KL\left(w \otimes S(F_t(x)) \middle\| S(F_t^{(s)}(x))\right)$$





