

# CANopen in the Shell

## Managing and Developing CANopen Applications on Linux

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Me (Tom Flynn):

- BEng. Mechatronics
- Linux User
- Industrial Electronics
- Engineer

# Introduction- Outline

## ① Controller Area Networks - What, Why, How?

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- 1 Controller Area Networks - What, Why, How?
- 2 Cometh the Application Layer

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- ④ The CANopen FOSS Tool Kit
- ⑤ Smooth and Unproblematic Demonstration

# Introduction- GNU Image Manipulation





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- **2011** CiA 301 V 4.2 made public - *Open*



# Controller Area Networks - What, Why, How?- Definition

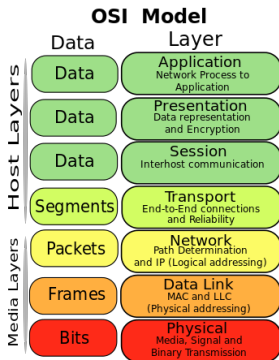
What is a Controller Area Network?

A network of nodes exchanging messages.

# Controller Area Networks - What, Why, How?- Technology Context

## OSI 7 Layer Model

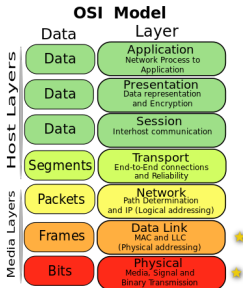
Observing the Open Standards Initiative (OSI) Model we can contextualise the aspects of CAN technology.



# Controller Area Networks - What, Why, How?- CAN as Foundation

## Layers 1 and 2

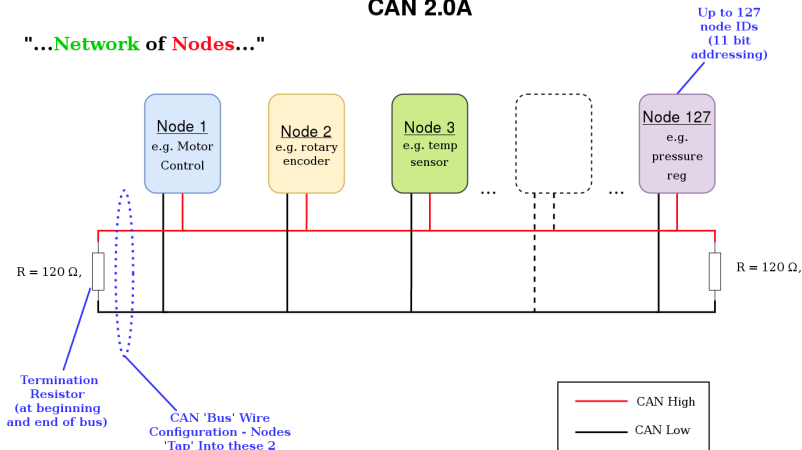
From the bottom up, a CAN network needs to be looked at in terms of its physical implementation. We will consider the Physical (L1) and Data Link (L2) layers.



# Controller Area Networks - What, Why, How?- Network

## Generic Network Topology CAN 2.0A

"...Network of Nodes..."

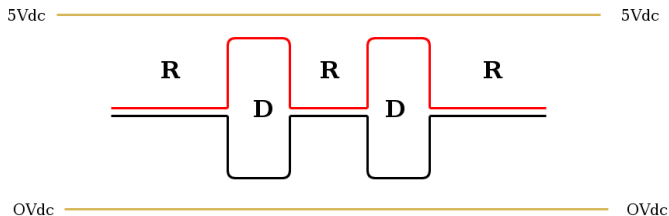


# Controller Area Networks - What, Why, How?- Exchange

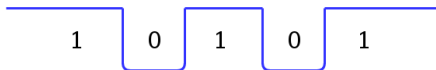
## CAN Signaling

D - Dominant - Both lines in 'on' state - Logical 0

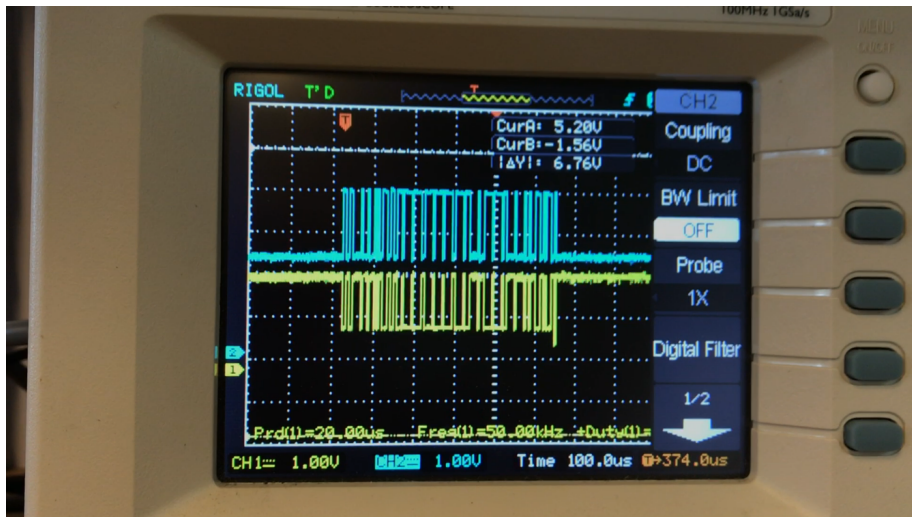
R - Recessive - Both lines in 'off' state - Logical 1



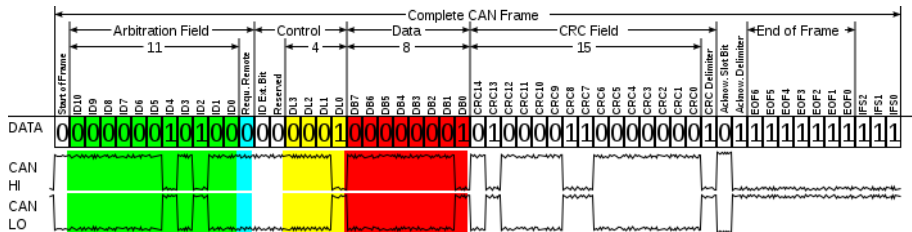
Resulting Data:



# Controller Area Networks - What, Why, How?- Signaling Example



# Controller Area Networks - What, Why, How?- Messages



# Controller Area Networks - What, Why, How?- Theory to Practice

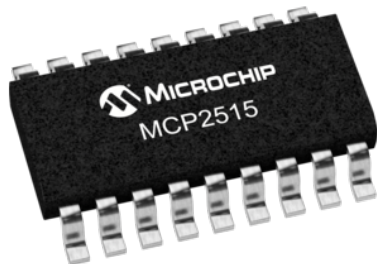
To implement the hardware of a CAN-based device, we need to provide the L1 and L2 features.

Two Options:

- 1 Use a standalone IC that covers both L1 and L2 requirements *OR*
- 2 Use an SoC/MCU with built in CAN module (L2) and possibly a transceiver IC (L1)

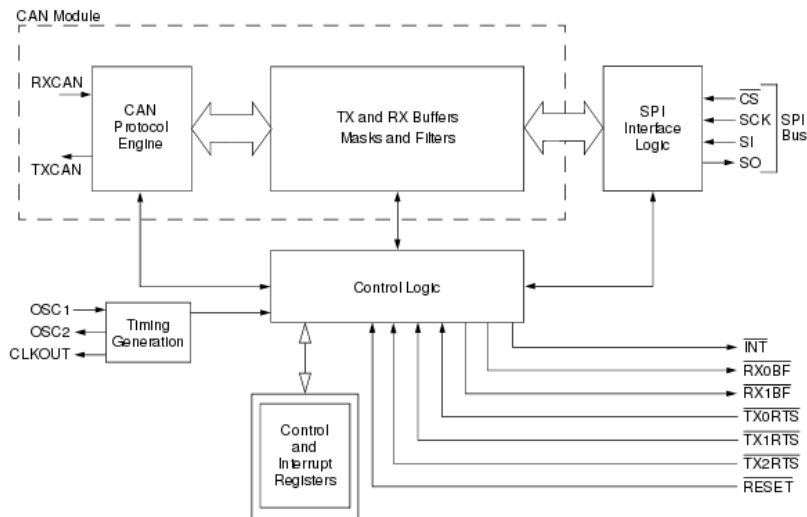


# Controller Area Networks - What, Why, How?- Example - Standalone IC

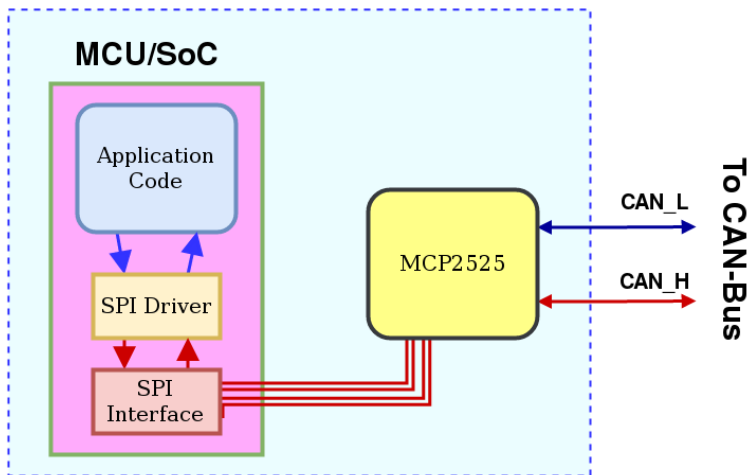


## Microchip MCP2515

# Controller Area Networks - What, Why, How?- Example - MCP2525



# Controller Area Networks - What, Why, How?- Hardware Solution with MCP2525



**Your CAN-Interfaced Device**

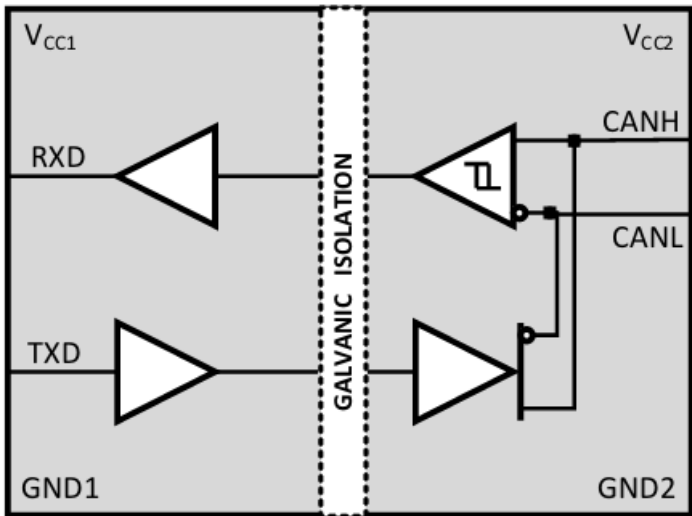
# Controller Area Networks - What, Why, How?- Example - Use Integrated L2 CAN with L1 Transceiver

## Texas Instruments ISO1050 Isolated CAN

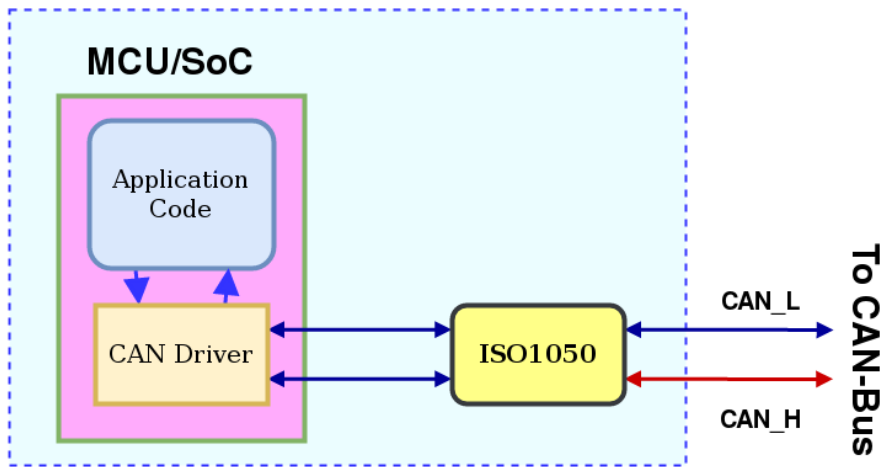


Transceiver

# Controller Area Networks - What, Why, How?- Example - TI ISO1050



# Controller Area Networks - What, Why, How?- Solution with ISO1050



**Your CAN-Interfaced Device**

# Cometh the Protocols- Moving up the Stack

**Q: What to do with all this reliable L1 and L2 infrastructure?**

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**Q: What to do with all this reliable L1 and L2 infrastructure?**

A: Write standards of how our devices will use it!



# Cometh the Protocols- Horses for Courses

Some examples of the protocols using CAN as a foundation:

**J1939 1990** Control in heavy machinery e.g. Trucks, Tractors.  
Created and governed by SAE. Baud rate of 250kbit/s, up to 30 nodes.

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**CANopen 1994** Industrial control. Created/governed by CiA. Up to 1Mbit/s, up to 127 nodes.

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- Purpose

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- Purpose
- Flexibility
- Implementation

# Cometh the Protocols- CANopen Protocol

*CANopen provides several communication objects, which enable device designers to implement desired network behavior into a device. With these communication objects, device designers can offer devices that can communicate process data, indicate device-internal error conditions or influence and control the network behavior.*