



Tyler Liao

BS Mechanical Engineering (Anticipated May 2026)

I want to make things and solve problems. My passions include machining, mechanical design, and fabrication. Currently, I am pursuing a BS in Mechanical Engineering at the University of Rochester. The best parts of my day are when I get the chance to put engineering theory into practice, such as with my time leading the Baja SAE car team. During my time at the University of Rochester, I was awarded membership in the Tau Beta Pi Engineering Honors Society, and Dean's List Scholarship. I also enjoy learning and teaching and have worked as a teaching assistant for a wide range of engineering and fabrication courses. In my spare time, I enjoy playing the trombone with the University of Rochester Symphony Orchestra, playing Ultimate Frisbee, and machining pens and small toys on my Taig micro lathe.

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Baja SAE Chief Mechanic

Role Description:

As Chief Mechanic of the Yellowjacket Racing team I was responsible for all aspects of manufacturing and shop operation.

New Member Training/Onboarding:

- Devised new member training program
- Organized safety sessions for machining and welding

Manufacturing:

- Maintained documentation and knowledge on advanced manufacturing capabilities
- Coordinated manufacturing and test schedule
- Managed car build budget of \$10,000



Weld fixturing and machining



YJR25 Model Unveiling



Baja team at competition



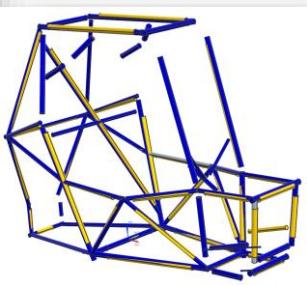
YJR-25 Baja Vehicle

Project Description:

- Lead design, fabrication, and testing cycle of new Baja car
- Improve vehicle robustness and manufacturing accuracy

	Summer + Fall Semester																												
Created: 6/8/24 Edited: 10/2/24	12/13	6/7	6/14	6/21	6/28	7/5	7/12	7/19	7/26	8/2	8/9	8/16	8/23	8/30	9/6	9/13	9/20	9/27	10/4	10/11	10/18	10/25	11/1	11/8	11/15	11/22	11/29	12/6	12/13
Current Date:		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27
Due Date:	7/19/24	-147	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
First Projects + NX Learning	8/26/24	-109	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
Iteration 0	8/30/24	-105																											
OktobajaFest	9/27/24	-77																											
Iteration 1/w. Full Assembly and Analysis	10/25/24	-49																											
Pumpkin launch	10/25/24	-49																											
Spooky Science Day	10/26/24	-48																											
Frame Manufacturing Start	10/25/24	-49																											
PDR General Email	10/28/24	-46																											
PDR Subsystem Emails	11/1/24	-42																											
Arc and Flame Weld Training	11/3/24	-40																											
Makers Faire	11/15/24	-28																											
Design Hard Deadline	11/27/24	-16																											
Virtual Business RFP	12/13/24	0																											
Cockpit Manufacturing	12/15/24	2																											
Manufacturing	3/14/25	91																											
Crowd Funding	2/15/25	64																											
Team Bonding																													
Shop Cleaning																													
Newsletter																													

Gantt Chart Master Schedule



Faro Arm CMM measuring as built vehicle

CNC Prototyping



Vehicle Goals

- Vehicle shall complete 38.5 miles on the RIT Track, 22 of which uninterrupted, to ensure good performance in the endurance event.
- Vehicle shall weigh less than previous model (<485 lb).
- CoG within ± 1.5 ft of driver to fit wide range of drivers, and less than $\frac{1}{4}$ times the frame height from the LFS.
- Ground Clearance range of 11-13" will allow for suspension tuning to dynamic events
- Minimum slow turning radius of 11' w/ parallel steering
- 100ft acceleration time of 4.3 seconds on pavement

Solution Methods:

- Organize design and fabrication Gantt Chart schedule
- Collaborate with design leads on manufacturability
- Verify manufactured components with Faro Arm CMM



- ## Results:
- YJR-25 vehicle completed on schedule even after numerous design delays and manufacturing difficulties
 - Vehicle placement improved from 70th to 24th

Official Competition Placing

24

109

Univ of
Rochester

Yellowjacket
Racing

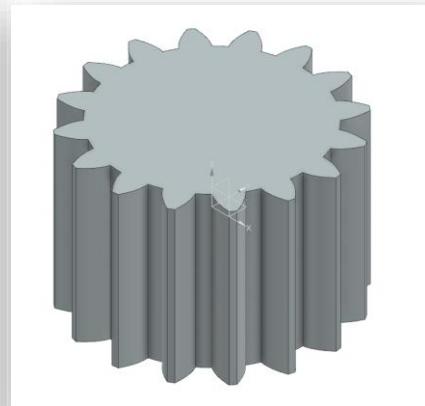
Independent Study: Gears

Project Description:

- Develop procedures to cut, simulate, and heat treat custom gears in-house for the Baja Team
- 4 Credit Independent study project under Dr. Christopher Muir



Torque testing rig



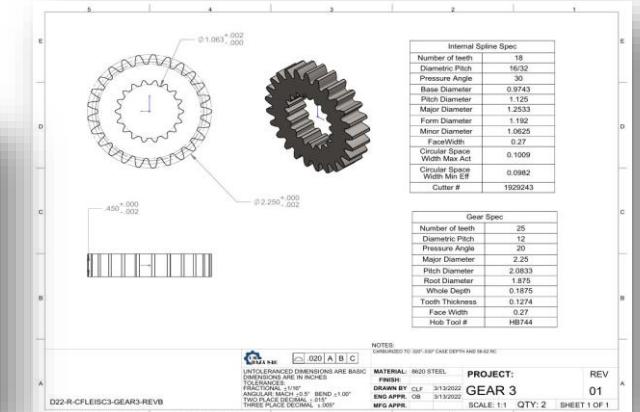
NX involute gear model
from first principles

Future Work:

- Build testing fixture to measure gear loading
- Correlate Faro Scanner data to model geometry
- Simulate and measure dynamic and fatigue lifetime of in-house gears

	Imperial	Metric
# Teeth	25	25
Diametral Pitch	12.000	12.250
Pitch Diameter (in)	2.083	2.0408163265306100000
Pitch Radius (in)	1.042	1.020
Module (mm)	2.042	2.000
Circular Pitch (mm)	6.414	6.283
Base Radius (in)	0.979	0.959
Base Diameter (in)	1.958	1.918
Pressure Angle (°)	20	20
Addendum (in)	0.083	0.082
Dedendum (in)	0.104	0.102

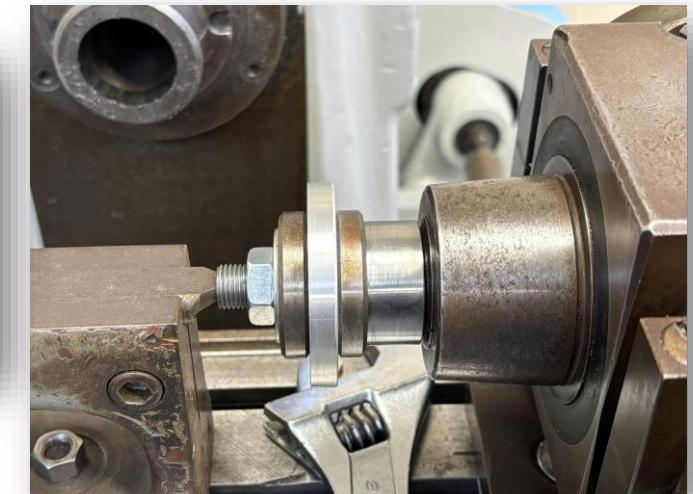
Excel Calculations of gear parameters from AGMA standards. Comparison of imperial and metric gear geometries



Example gears from Baja car

Solution Methods:

- Generate involute profile from first principles in NX
- Machine gear cutting mandrel and arbor



Gear Mandrel

Tritium Science Research

Role Description:

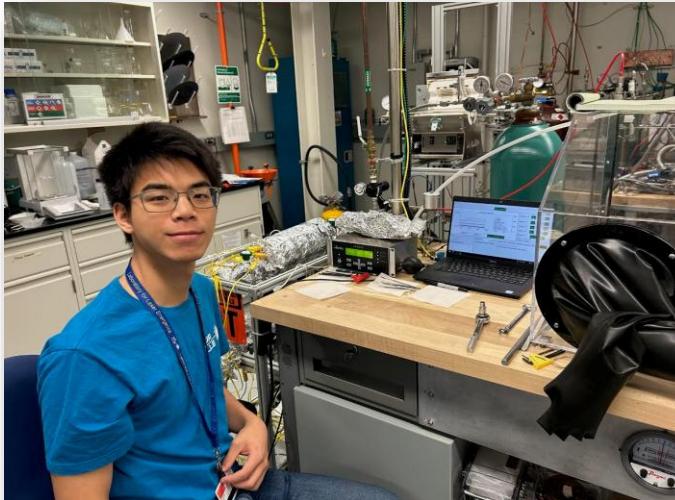
Perform work as research assistant under Dr. Zachary Robinson in Tritium Science group. Work performed at the University of Rochester's Laboratory for Laser Energetics.

Atomic Layer Deposition (ALD):

- Specialized Chemical Vapor Deposition technique
- Self limiting chemical reaction
- Deposit conformal, pinhole free nanometer thin films

ALD Research Goals:

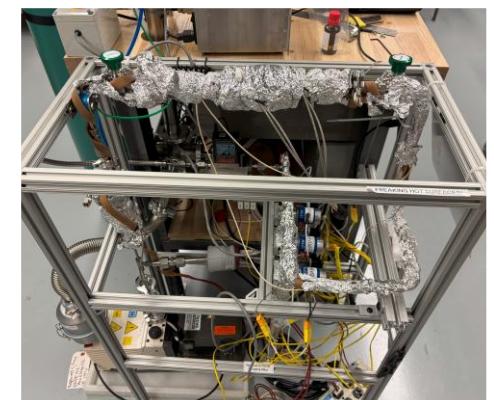
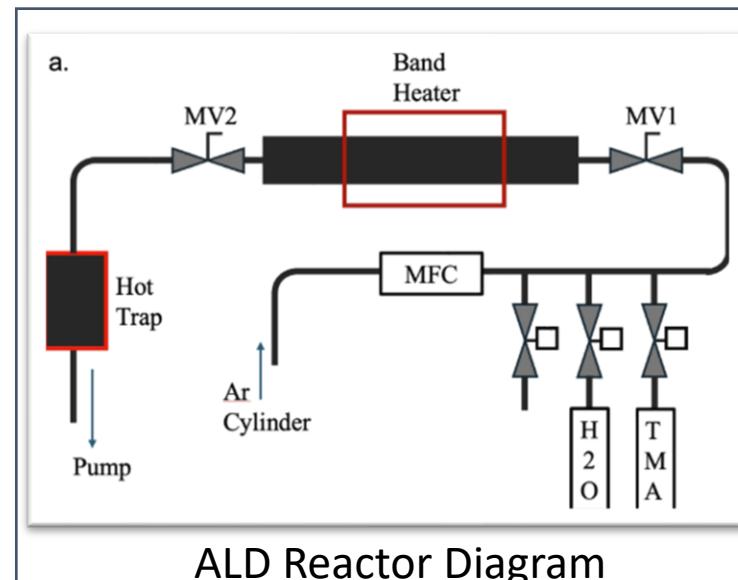
- Study Tritium permeation behavior for nuclear fuel containment applications
- Develop new ALD process conditions for uniform coating of large internal surfaces



Lab Workstation



Supervisor: Dr. Zachary Robinson
LLE Tritium Science Group

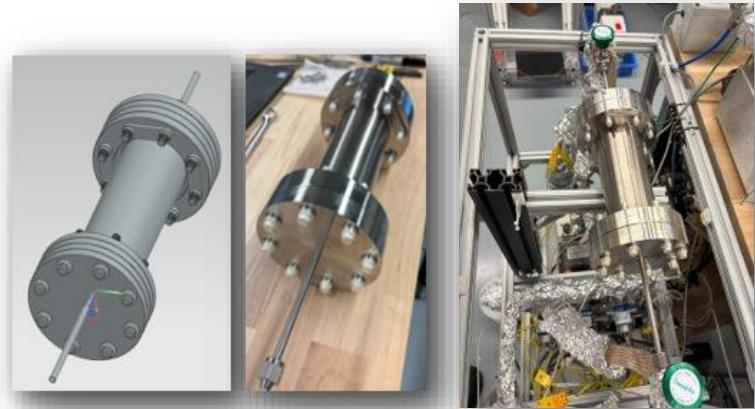


ALD Reactor

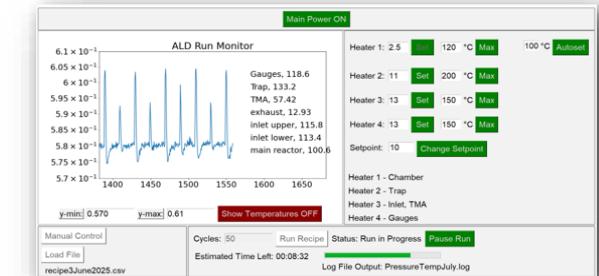
Process Development

Project Description:

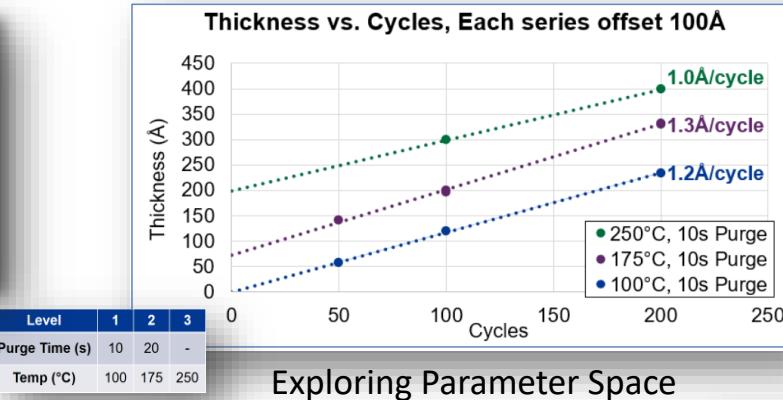
- Perform process development on atomic layer deposition for different reactor geometries
- New control software GUI



Horizontal Chamber Configuration



Python GUI



Exploring Parameter Space

Results:

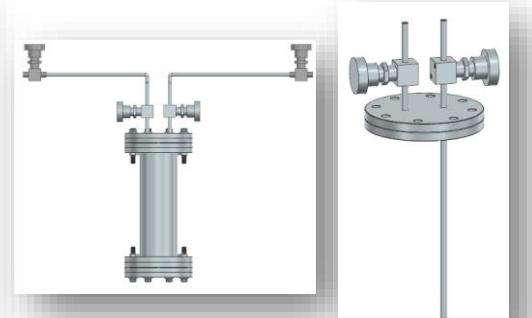
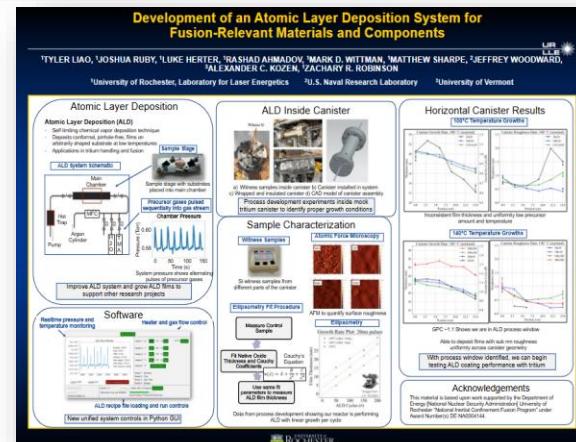
- Poster presentation award winner at New York State Section American Physical Society conference

Future Work:

- Working with Mechanical Engineering department to manufacture new vertical reactor configuration

Solution Methods:

- Developed new control software in Python
- Process development on silicon wafers in 1" Tube Reactor
 - Full factorial design of experiments
- Designed new large horizontal chamber reactor
- Worked with Ebara to source custom heater jacket



New Vertical Chamber Assembly

Mini Projects

Mini Projects:

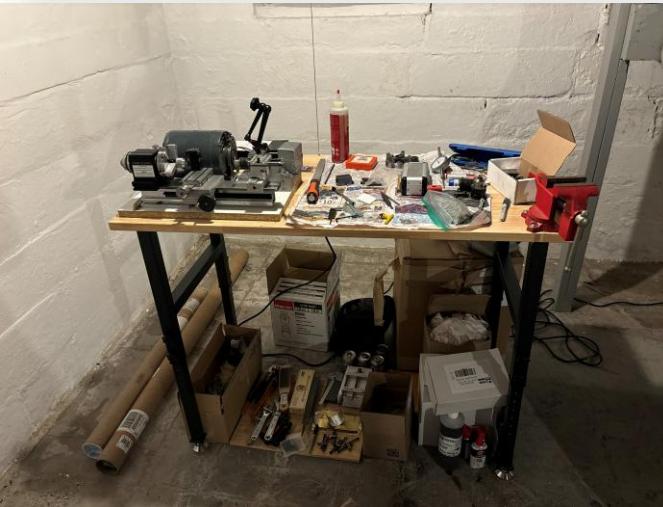
The following are a selection of smaller engineering projects done over the course of my engineering education at the University of Rochester, as well as in my free time

Creative Manufacturing:

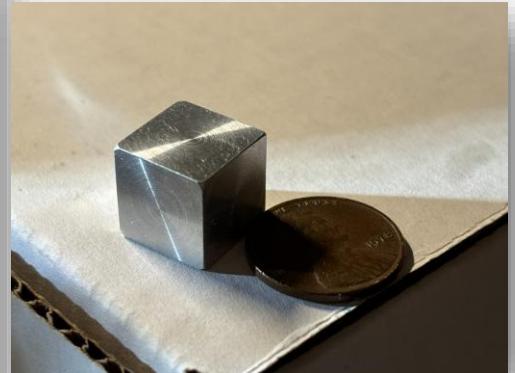
- With these small projects I get to experiment and exercise my creativity in machining
- I own a Taig Micro lathe that I machine on in my spare time



Bolt action pen



Taig Micro Lathe machining small parts



Lathe cube!

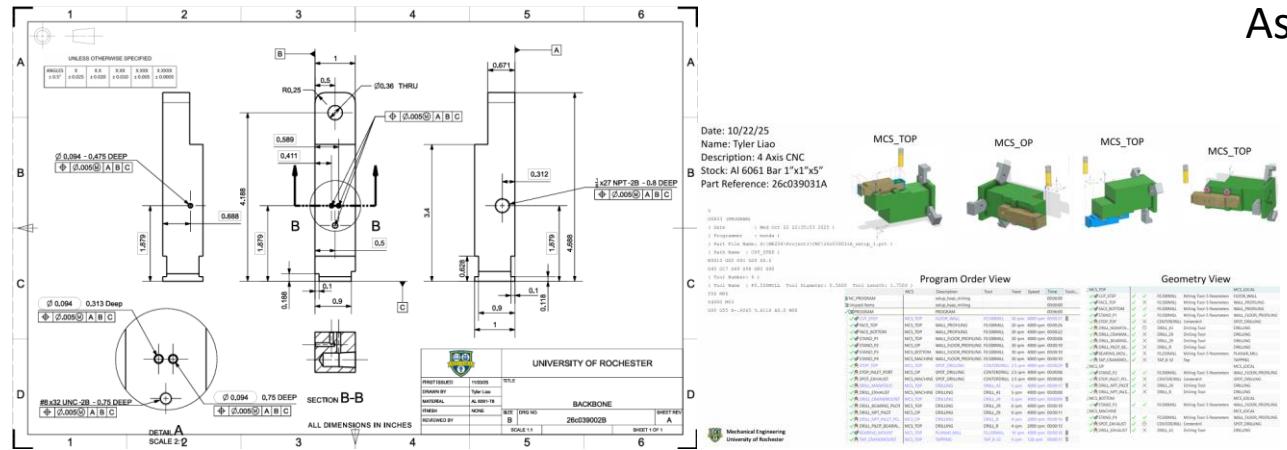


Small clamps and other shop tools

Air Engine

Project Description:

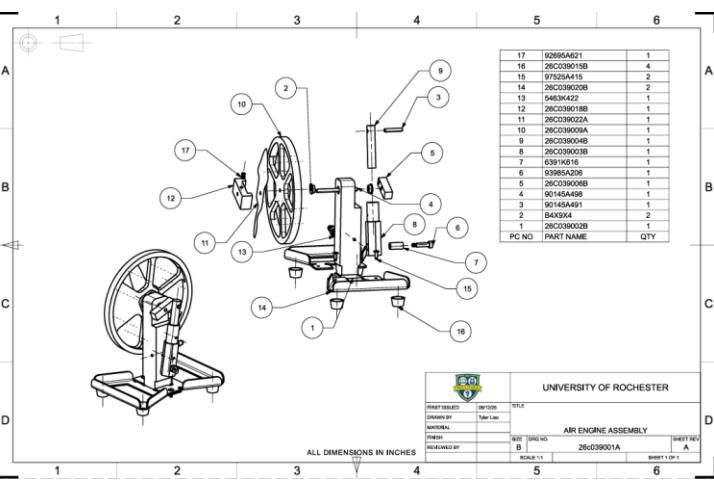
- Create CAD, drawings of air engine with accompanying simulation
 - Fabricate and assemble using a variety of processes



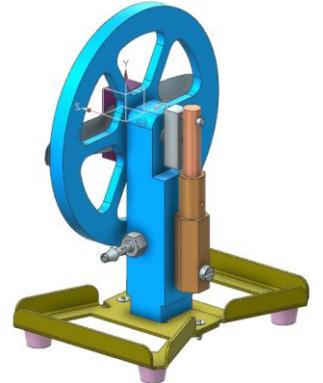
Engine Backbone Drawing and CNC Process Sheet

Results:

- Fabricated and assembled parts for testing
 - Held tight tolerances for smooth operation with as low as 0.5psi air pressure



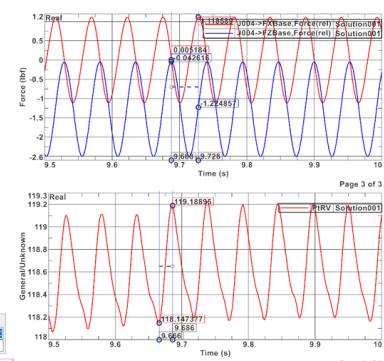
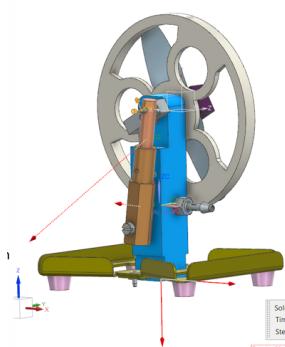
Assembly Drawing and BOM



CAD Model

Solution Methods:

- Drawings and CNC programming done in NX
 - Involved casting and mold design, CNC machining, manual lathing and milling, injection molding, and composite layup
 - Simulated air engine performance using NX



Coefficient of Speed Fluctuation Simulation

Tube Welding Fixture

Project Description:

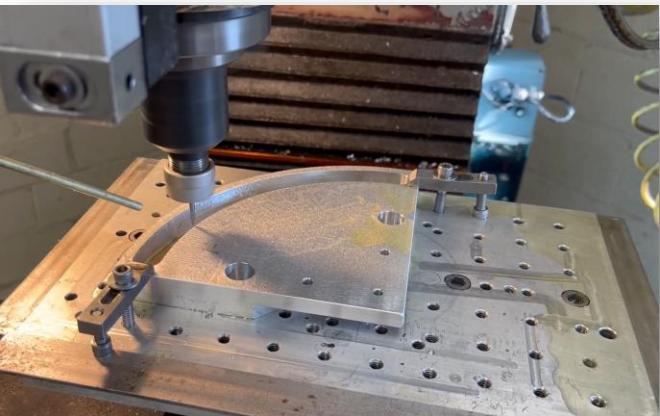
- Tube coping and welding for the Baja team is slow and has accuracy limitations, especially when travelling to competition site
- Design fixture to speed up and increase accuracy of tube coping and welding process



Routed Fixture



DIY fixturing at competition



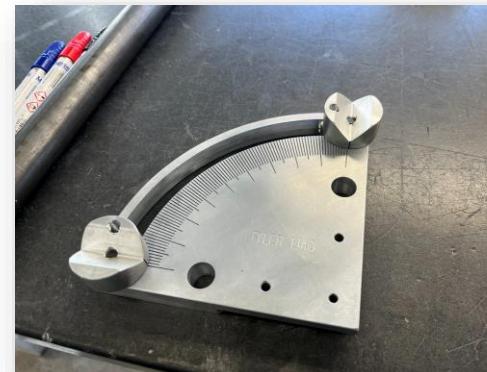
Main baseplate milling with Prototrak 3 Axis



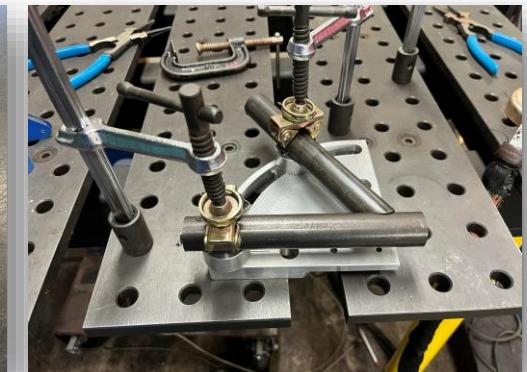
Pucks machined on lathe then processed in milling machine

Results:

- Fabricated and assembled parts for use in tube welding
- Removed need for dedicated fixtures in certain cases



Assembled Part



Set up for welding

Solution Methods:

- Custom angle fixture plate with angle graduations
- Worked with experienced toolmaker to design and fabricate parts using Prototrak 3 Axis milling machine

Machining Pens

Project Description:

- Personal project to make interesting metal pens
- Experiment with small part machining and custom fixture design



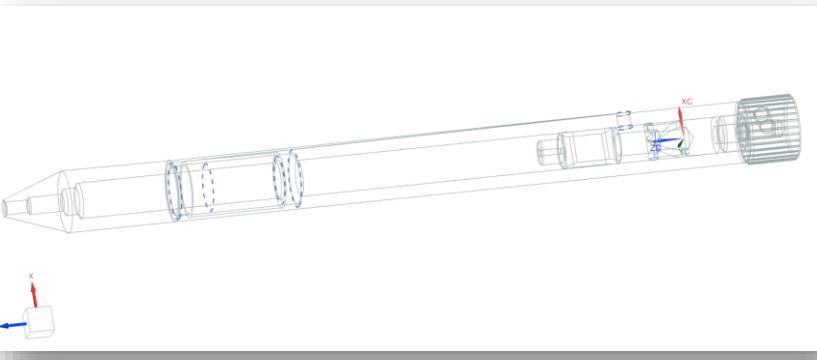
45° Indexing fixture



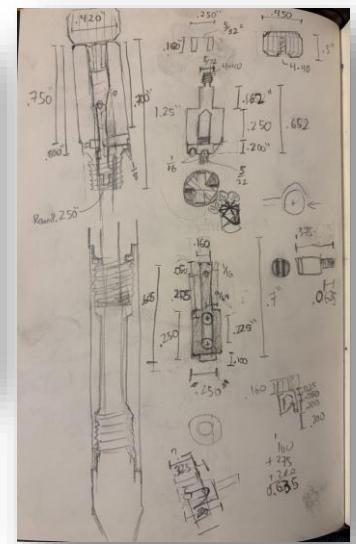
Ratchet Mechanism

Results:

- Assortment of bolt action mechanism pens
- Custom ratcheting twist pen with pressed bronze bearing machined entirely on micro lathe machine



Planning ratcheting pen mechanism



Solution Methods:

- Experiment creatively with fun machining techniques
- Machine custom pens out of brass, aluminum
- Prototype and design mechanisms

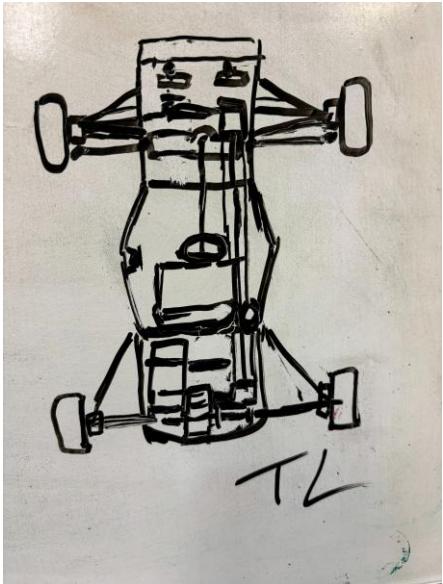


Bolt Action Pens



Ratcheting Mechanism Pen

Baja Bonus Page



Drawing from memory,
proud of my “mind CAD”



Doesn't work quite the same in real life



Pretty sure it's not supposed to look like that



(YJR-23's first competition) live and learn...



(YJR-23's second competition) Or maybe not