

Tree Implementation

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Today's Plan



Recap

BST Implementation

Announcements

Last lecture Mock Final Exam

If you take it you must stay for the duration of the exam

```

#ifndef BST_H_
#define BST_H_
#include <memory>

template<class T>
class BST
{
public:
    BST(); // constructor
    BST(const BST<T>& tree); // copy constructor
    ~BST(); // destructor
    bool isEmpty() const;
    size_t getHeight() const;
    size_t getNumberOfNodes() const;
    void add(const T& new_item);
    void remove(const T& new_item);
    T find(const T& item) const;
    void clear();

    void preorderTraverse(Visitor<T>& visit) const;
    void inorderTraverse(Visitor<T>& visit) const;
    void postorderTraverse(Visitor<T>& visit) const;

    BST& operator= (const BST<T>& rhs);

private:
    std::shared_ptr<BinaryNode<T>> root_ptr_;
}; // end BST

#include "BST.cpp"
#endif // BST_H_

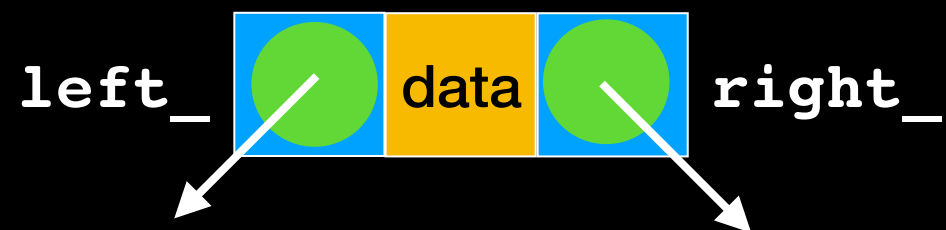
```

We will talk about this at the end of this lecture

Let's try something new and use `shared_ptr`:
A bit of extra syntax at declaration but then you use them as regular pointers with less cleaning up

To implement this as a linked structure what do we need to change in our previous implementation ???

BinaryNode



For shared_ptr

```
#ifndef BinaryNode_H_
#define BinaryNode_H_
#include <memory>

template<class T>
class BinaryNode
{
public:
    BinaryNode();
    BinaryNode(const T& an_item);
    void setItem(const T& an_item);
    T getItem() const;

    bool isLeaf() const;

    auto getLeftChildPtr() const;
    auto getRightChildPtr() const;

    void setLeftChildPtr(std::shared_ptr<BinaryNode<T>> left_ptr);
    void setRightChildPtr(std::shared_ptr<BinaryNode<T>> right_ptr);

private:
    T item_; // Data portion
    std::shared_ptr<BinaryNode<T>> left_; // Pointer to left child
    std::shared_ptr<BinaryNode<T>> right_; // Pointer to right child
}; // end BST

#include "BinaryNode.cpp"
#endif // BinaryNode_H_
```

Lecture Activity

Implement:

```
BinaryNode(const T& an_item);
```

```
bool isLeaf() const;
```

```
void setLeftChildPtr(std::shared_ptr<BinaryNode<T>> left_ptr);
```



```

template<class T>
BinaryNode<T>::BinaryNode(const T& an_item)
    : item_(an_item), left_(nullptr), right_(nullptr)
{ } // end constructor

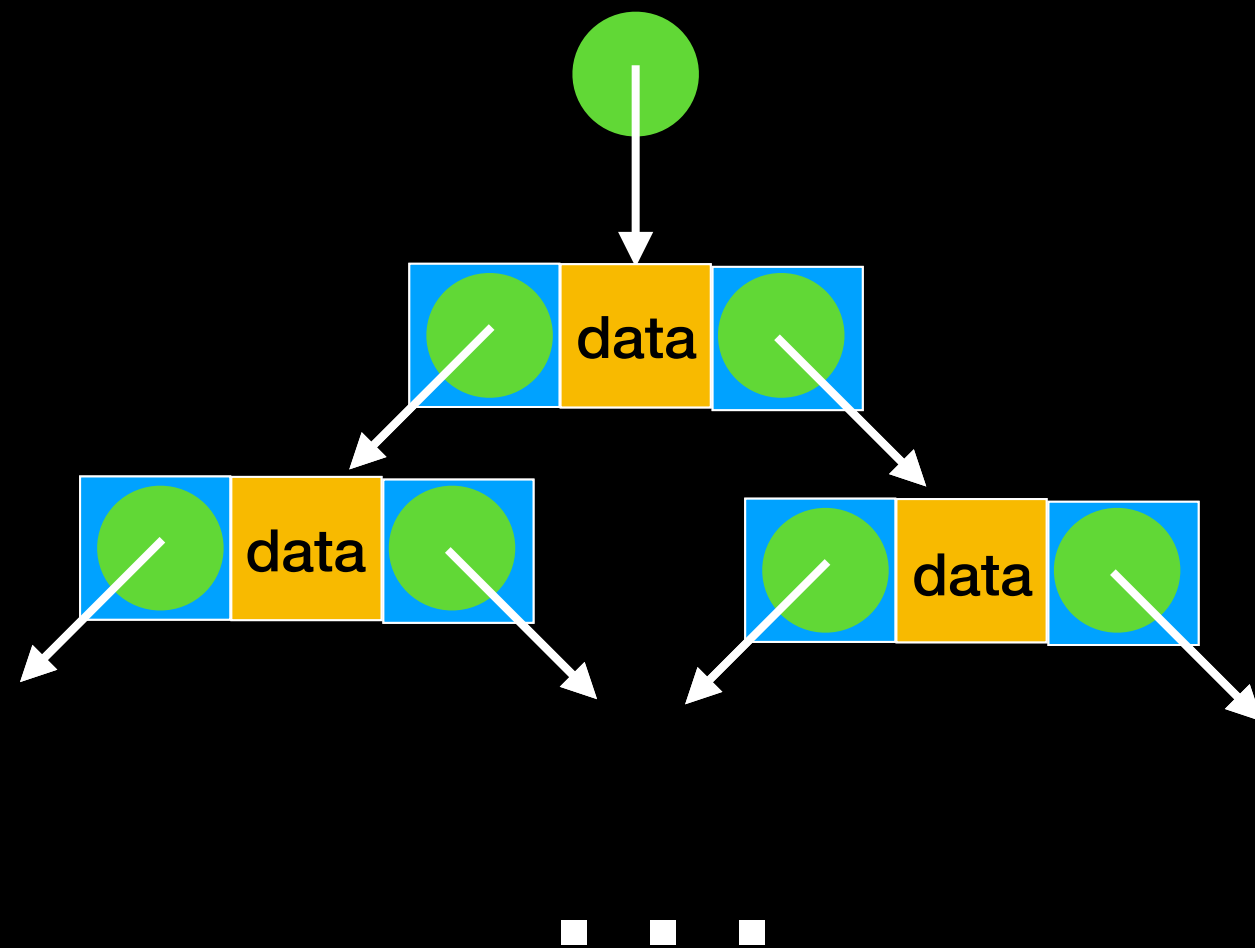
template<class T>
bool BinaryNode<T>::isLeaf() const
{
    return ((left_ == nullptr) && (right_ == nullptr));
} // end isLeaf

template<class T>
void BinaryNode<T>::setLeftChildPtr(std::shared_ptr<BinaryNode<T>> left_ptr)
{
    left_ = left_ptr;
} // end setLeftChildPtr

```

BST

root_ptr_



```

#ifndef BST_H_
#define BST_H_
#include <memory>

template<class T>
class BST
{
public:
    BST(); // constructor
    BST(const BST<T>& tree); // copy constructor
    ~BST(); // destructor
    bool isEmpty() const;
    size_t getHeight() const;
    size_t getNumberOfNodes() const;
    void add(const T& new_item);
    void remove(const T& new_item);
    T find(const T& item) const;
    void clear();

    void preorderTraverse(Visitor<T>& visit) const;
    void inorderTraverse(Visitor<T>& visit) const;
    void postorderTraverse(Visitor<T>& visit) const;

    BST& operator= (const BST<T>& rhs);

private:
    std::shared_ptr<BinaryNode<T>> root_ptr_;
}; // end BST

#include "BST.cpp"
#endif // BST_H_

```

We want our interface to be generic and not tied to implementation. Many of these will therefore use helper functions, which should be private (or protected if you envision inheritance). I do not include them here in the interface for lack of space.

Copy Constructor

root_ptr of
this object

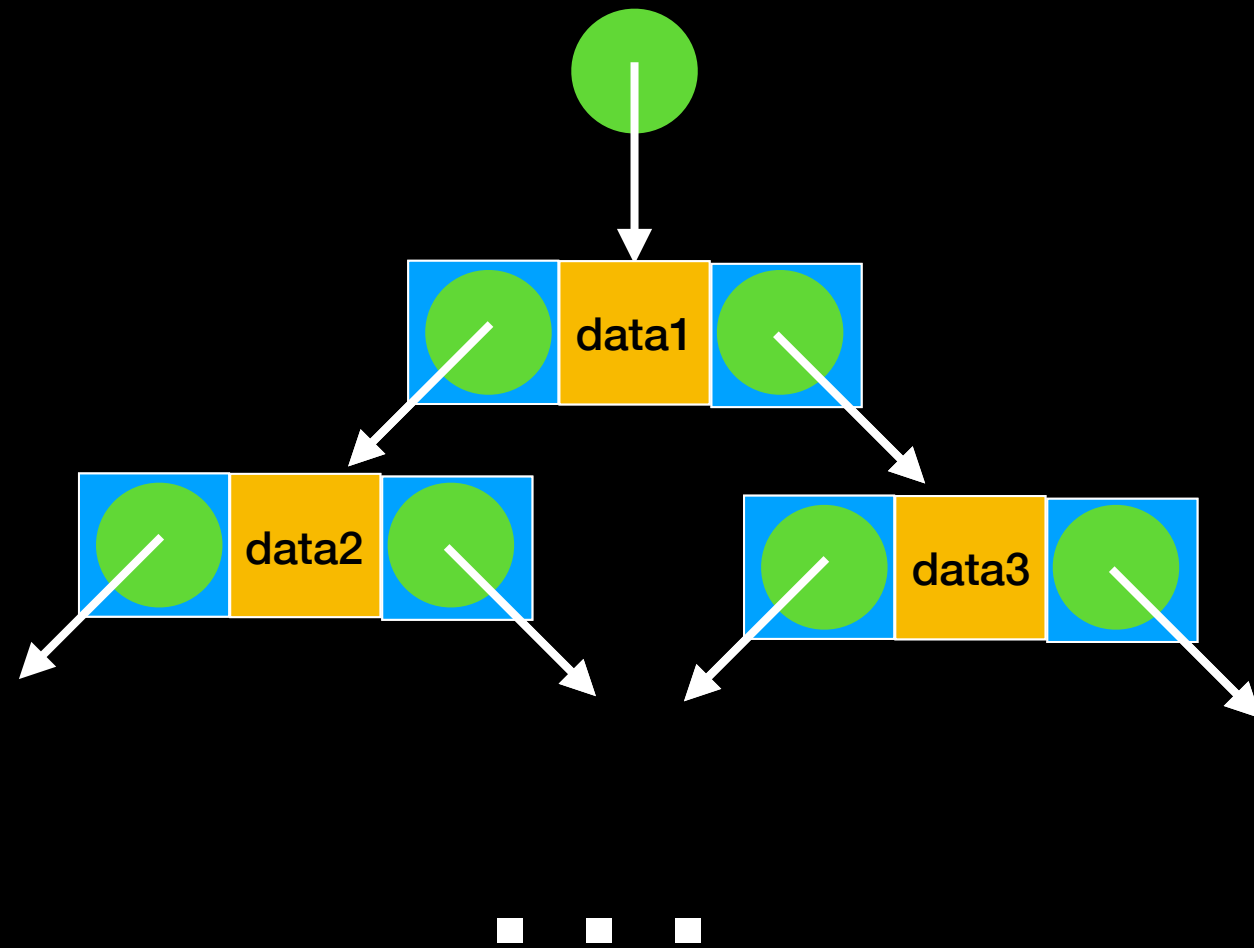
root_ptr of tree: the
object I'm going to copy

```
template<class T>
BST<T>::BST(const BST<T>& tree)
{
    root_ptr_ = copyTree(tree.root_ptr_); // Call helper function
} // end copy constructor
```

I can use the . operator to access a private member variable because it is s within the class definition.

`copyTree(old_tree_root_ptr)`

`old_tree_root_ptr`

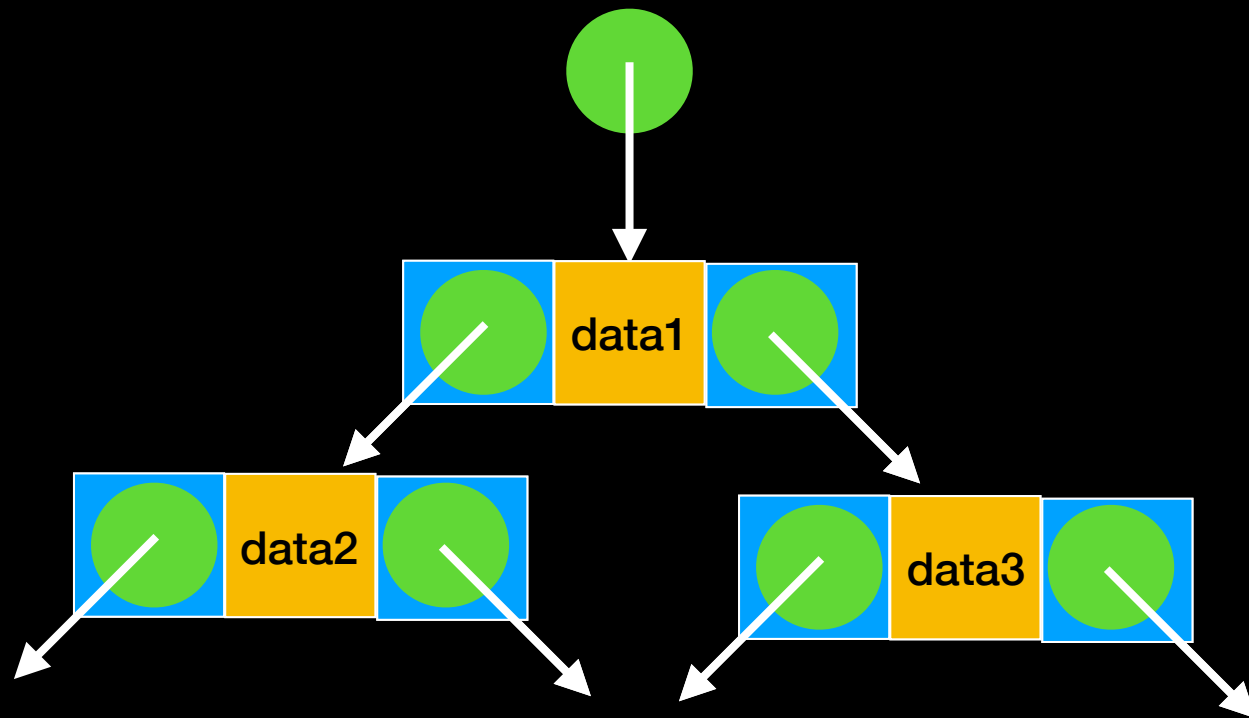


`new_tree_ptr`



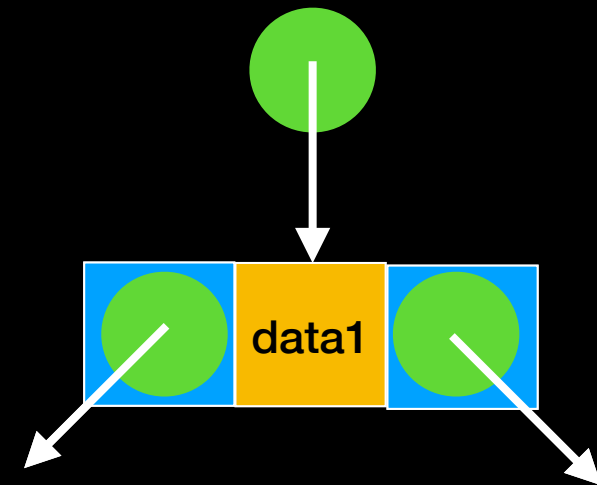
copyTree(`old_tree_root_ptr`)

`old_tree_root_ptr`



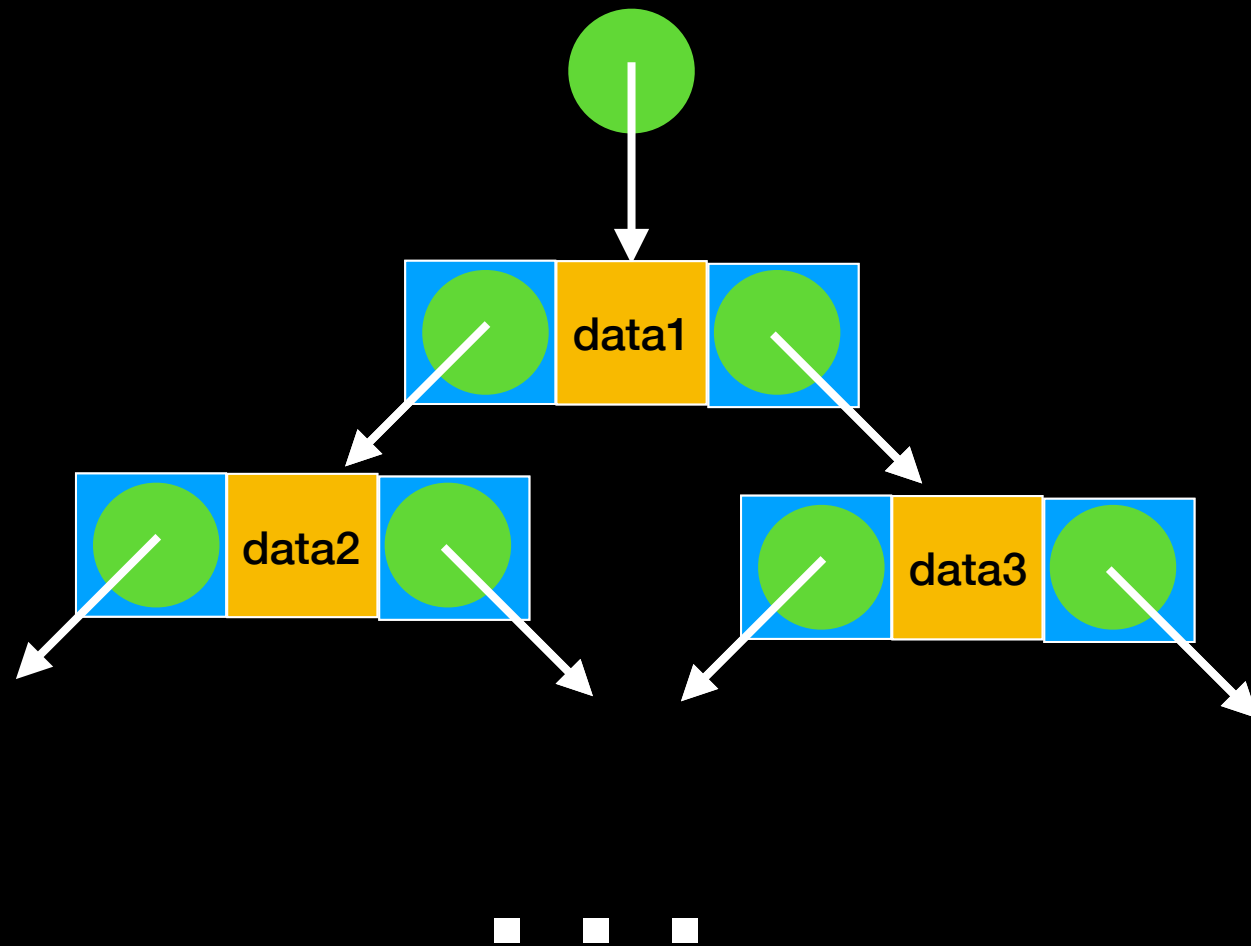
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`new_tree_ptr`

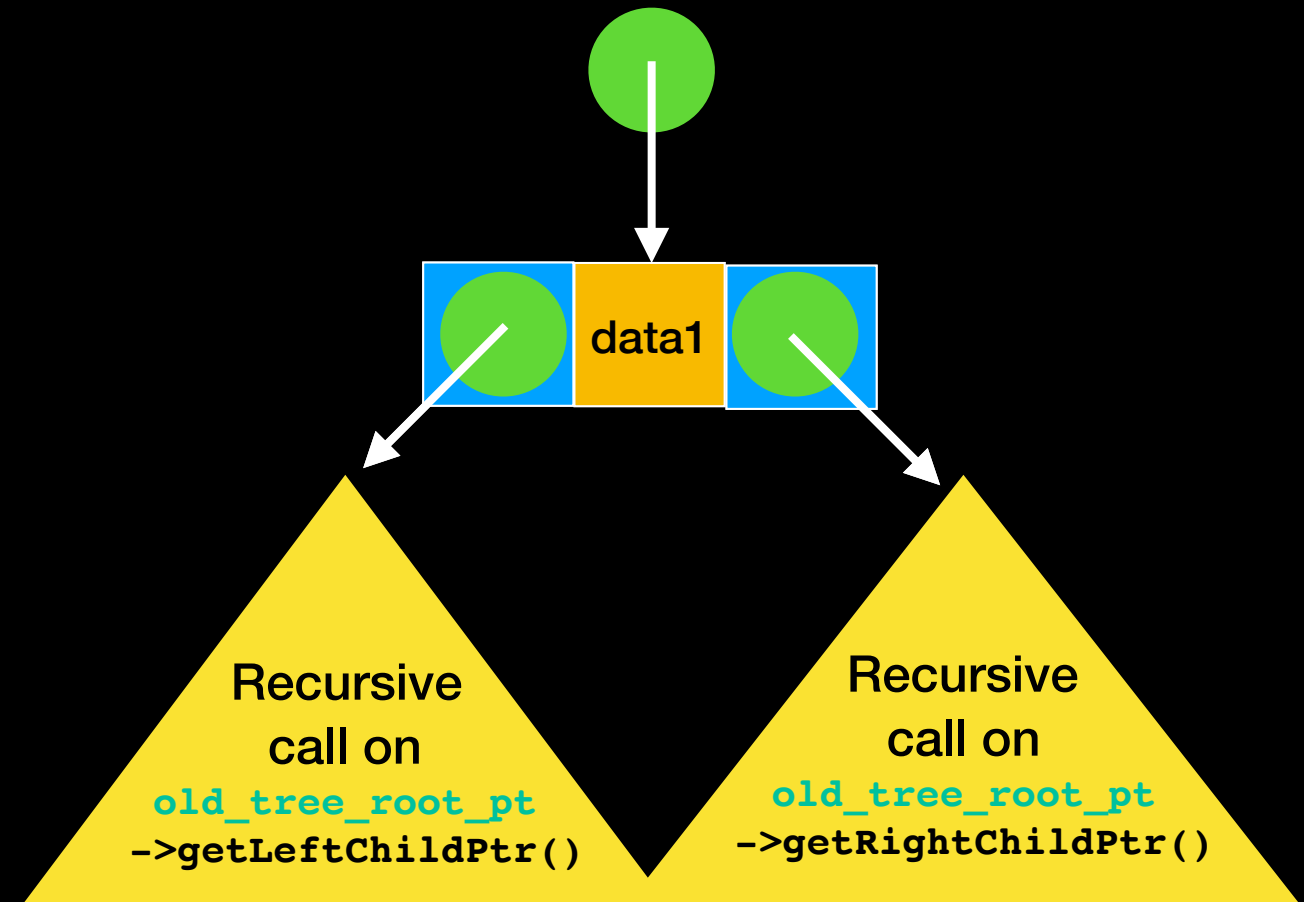


copyTree(`old_tree_root_ptr`)

`old_tree_root_ptr`



`new_tree_ptr`



Copy Constructor Helper Function

Returning
shared_ptr,
cleaner to use
auto return type:
-std=c++14

```
template<class T>
auto BST<T>::copyTree(const std::shared_ptr<BinaryNode<T>> old_tree_root_ptr) const
{
    std::shared_ptr<BinaryNode<T>> new_tree_ptr;

    // Copy tree nodes during a preorder traversal
    if (old_tree_root_ptr != nullptr)
    {
        // Copy node
        new_tree_ptr = std::make_shared<BinaryNode<T>>(old_tree_root_ptr
                                                         ->getItem(), nullptr, nullptr);
        new_tree_ptr->setLeftChildPtr(copyTree(old_tree_root_ptr->getLeftChildPtr()));
        new_tree_ptr->setRightChildPtr(copyTree(old_tree_root_ptr
                                                ->getRightChildPtr()));
    } // end if

    return new_tree_ptr;
} // end copyTree
```

Recall: this is the syntax
for allocating a “new”
object with shared_ptr
pointing to it

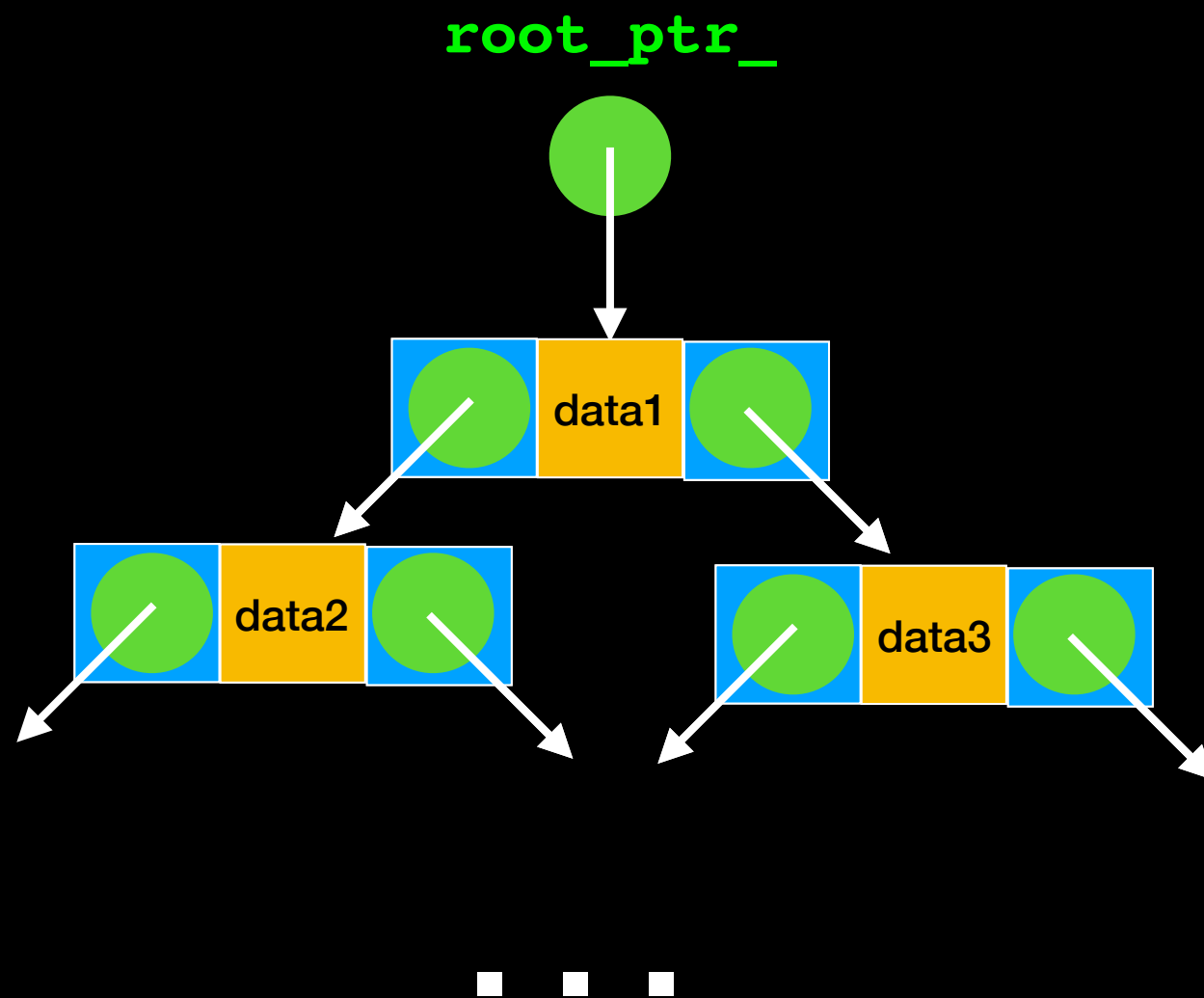
Recursive Calls:
**Don't want to tie interface
to recursive implementation:
Use helper function**

Preorder Traversal Scheme:
copy each node as soon as it
is visited to make exact copy

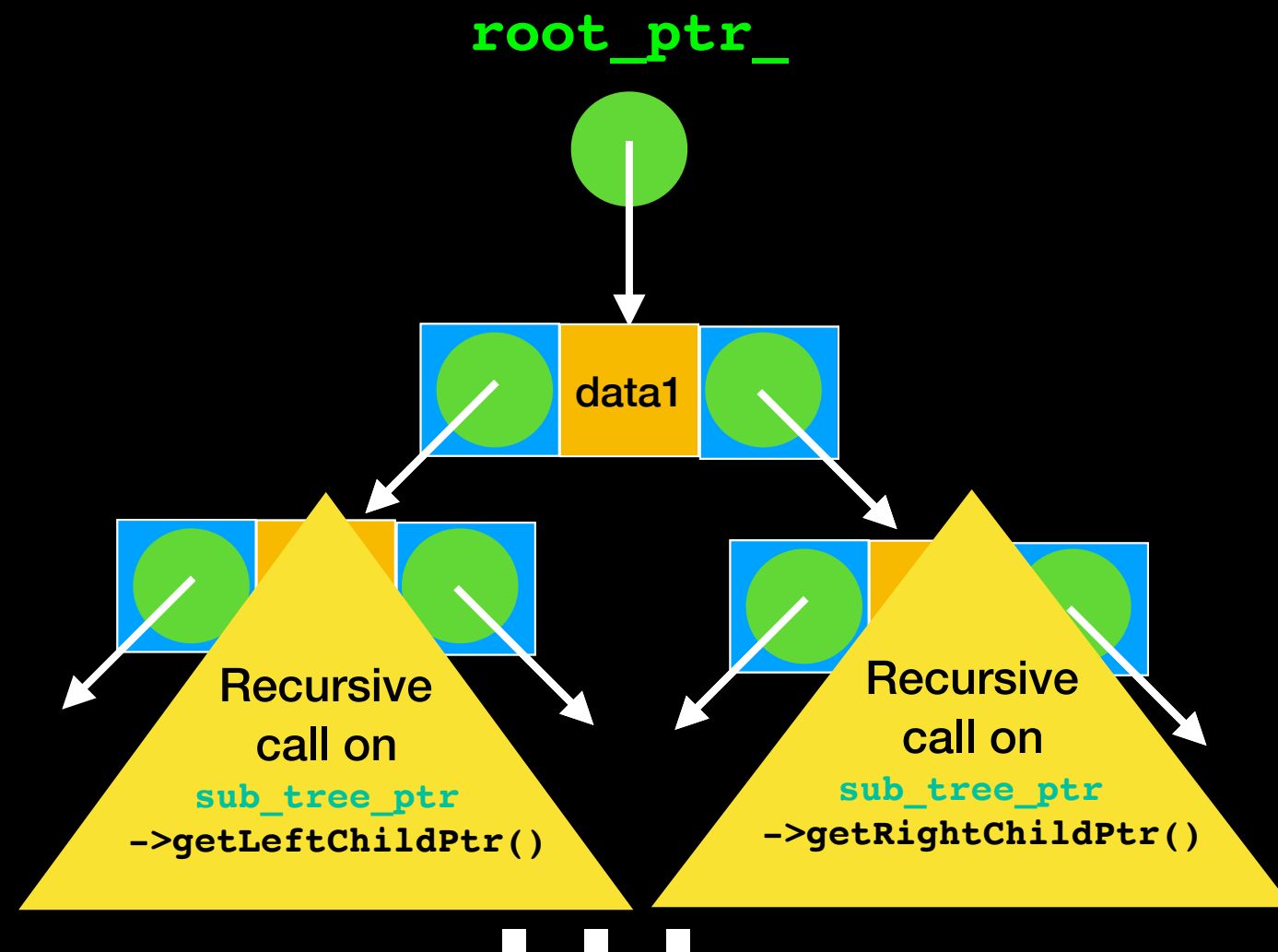
Destructor

```
template<class T>
BST<T>::~~BST()
{
    destroyTree(root_ptr_); // Call helper function
} // end destructor
```

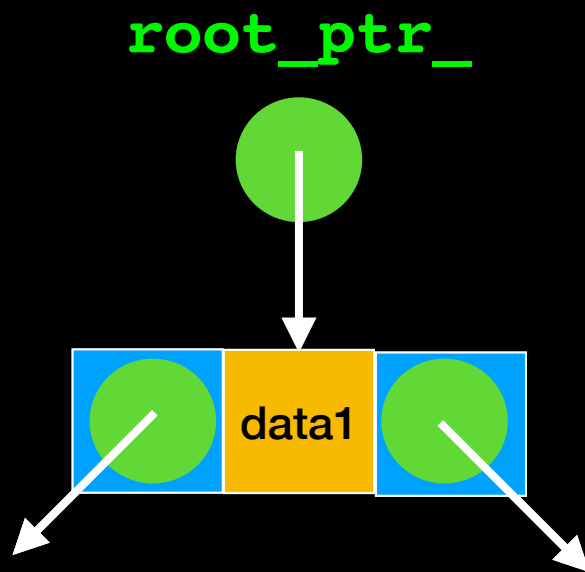
```
destroyTree(sub_tree_ptr)
```



destroyTree(**sub_tree_ptr**)



```
destroyTree(sub_tree_ptr)
```



```
root_ptr_.reset()
```

```
destroyTree(sub_tree_ptr)
```

root_ptr_



Destructor Helper Function

```
template<class T>
void BST<T>::destroyTree(std::shared_ptr<BinaryNode<T>> sub_tree_ptr)
{
    if (sub_tree_ptr != nullptr)
    {
        → destroyTree(sub_tree_ptr->getLeftChildPtr());
        → destroyTree(sub_tree_ptr->getRightChildPtr());
        sub_tree_ptr.reset(); // same as sub_tree_ptr = nullptr for smart pointers
    } // end if
} // end destroyTree
```

Notice: all we have to do is set the `shared_ptr` to `nullptr` with `reset()` and it will take care of deleting the node.

PostOrder Traversal Scheme:
Delete node only after deleting both of its subtrees

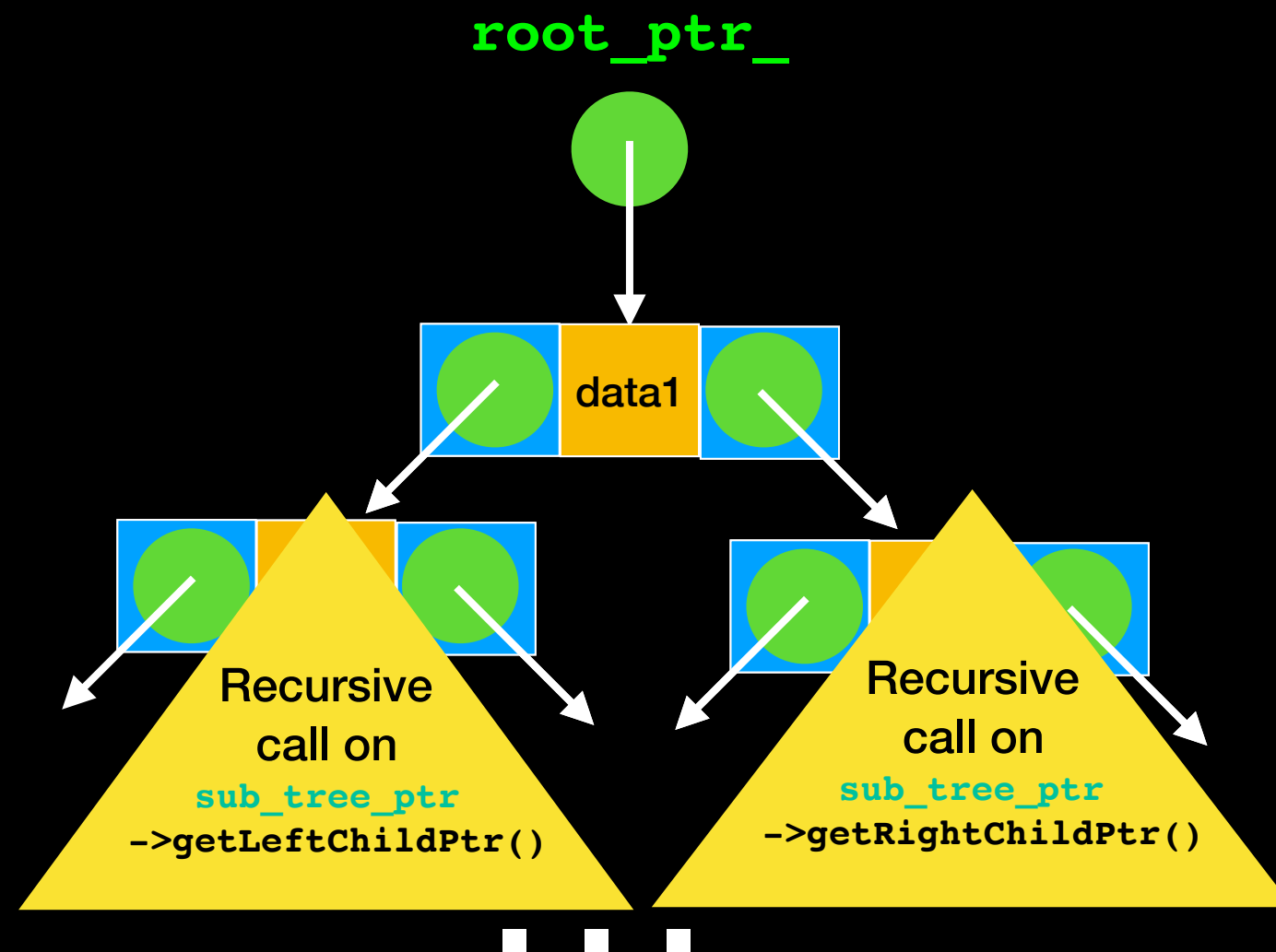
clear

```
template<class T>
void BST<T>::clear()
{
    destroyTree(root_ptr_); // Call helper method
} // end clear
```

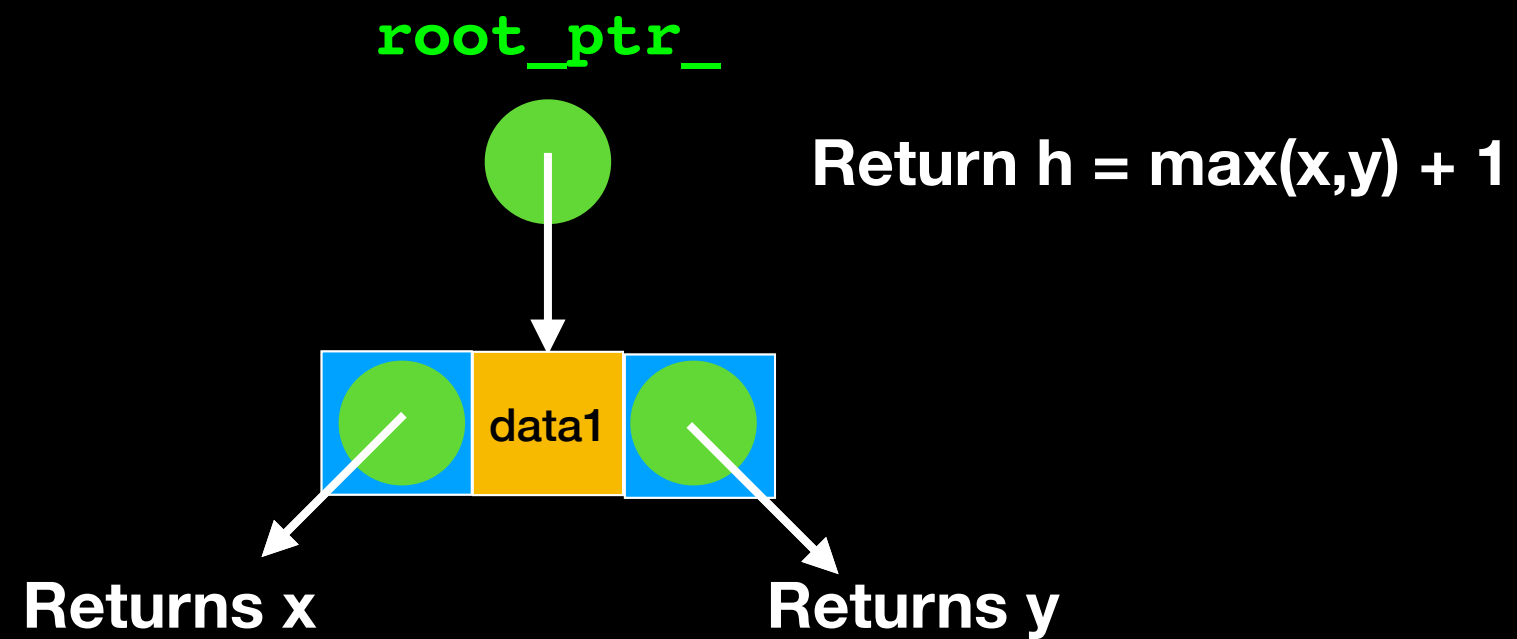
getHeight

```
template<class T>
int BST<T>::getHeight() const
{
    return getHeightHelper(root_ptr_);
} // end getHeight
```


getHeightHelper(**sub_tree_ptr**)

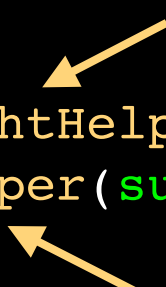


getHeightHelper(**sub_tree_ptr**)



getHeightHelper(**sub_tree_ptr**)

```
template<class T>
int BinaryNodeTree<T>::getHeightHelper(std::shared_ptr<BinaryNode<T>> sub_tree_ptr)
const
{
    if (sub_tree_ptr == nullptr)
        return 0;
    else
        return 1 + std::max(getHeightHelper(sub_tree_ptr->getLeftChildPtr()),
                             getHeightHelper(sub_tree_ptr->getRightChildPtr()));
} // end getHeightHelper
```





Similarly: implement these at home!!!

```
int BinaryNodeTree<T>::getNumberOfNodes() const
{ //try it at home!!!!}
```

```
int BinaryNodeTree<T>::getNumberOfNodesHelper(std::shared_ptr
<BinaryNode<T>> sub_tree_ptr) {//try it at home!!!!}
```

add and remove

Key methods: determine order of data

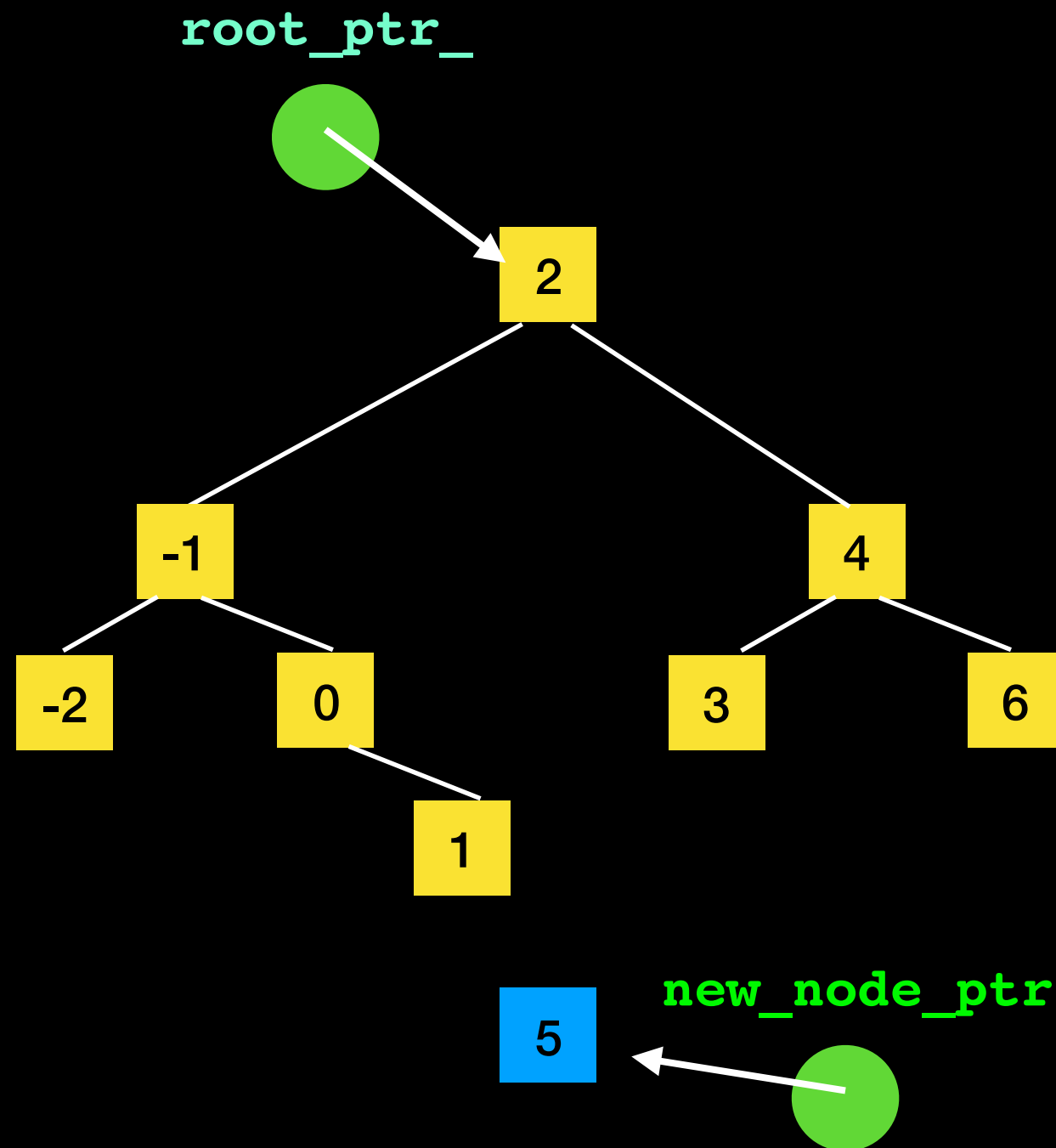
Distinguish between different types of Binary Trees

Implement the BST structural property

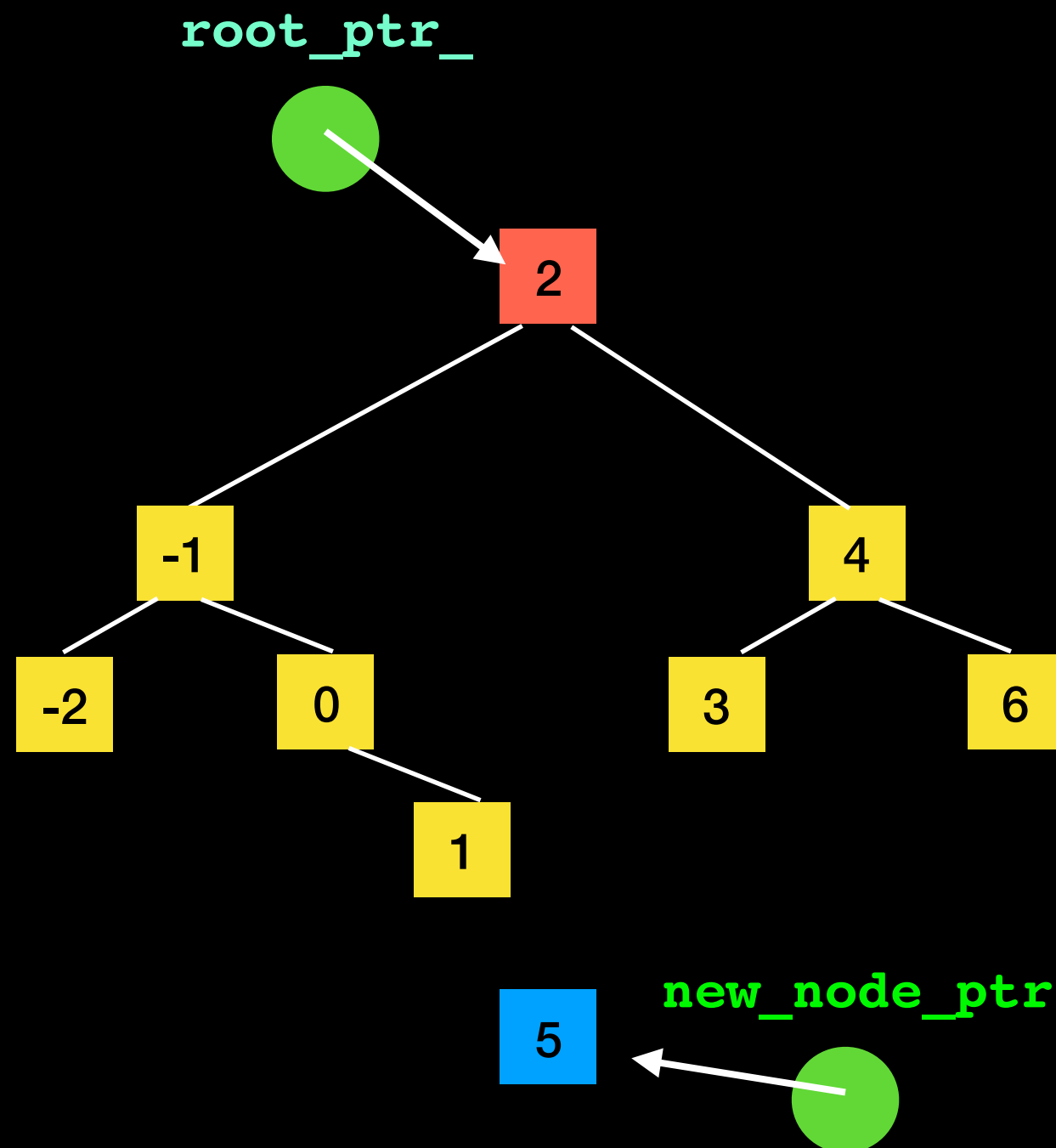
add

```
template<class T>
void BST<T>::add(const T& new_item)
{
    auto new_node_ptr =
        std::make_shared<BinaryNode<T>>(new_item);
    placeNode(root_ptr_, new_node_ptr);
} // end add
```

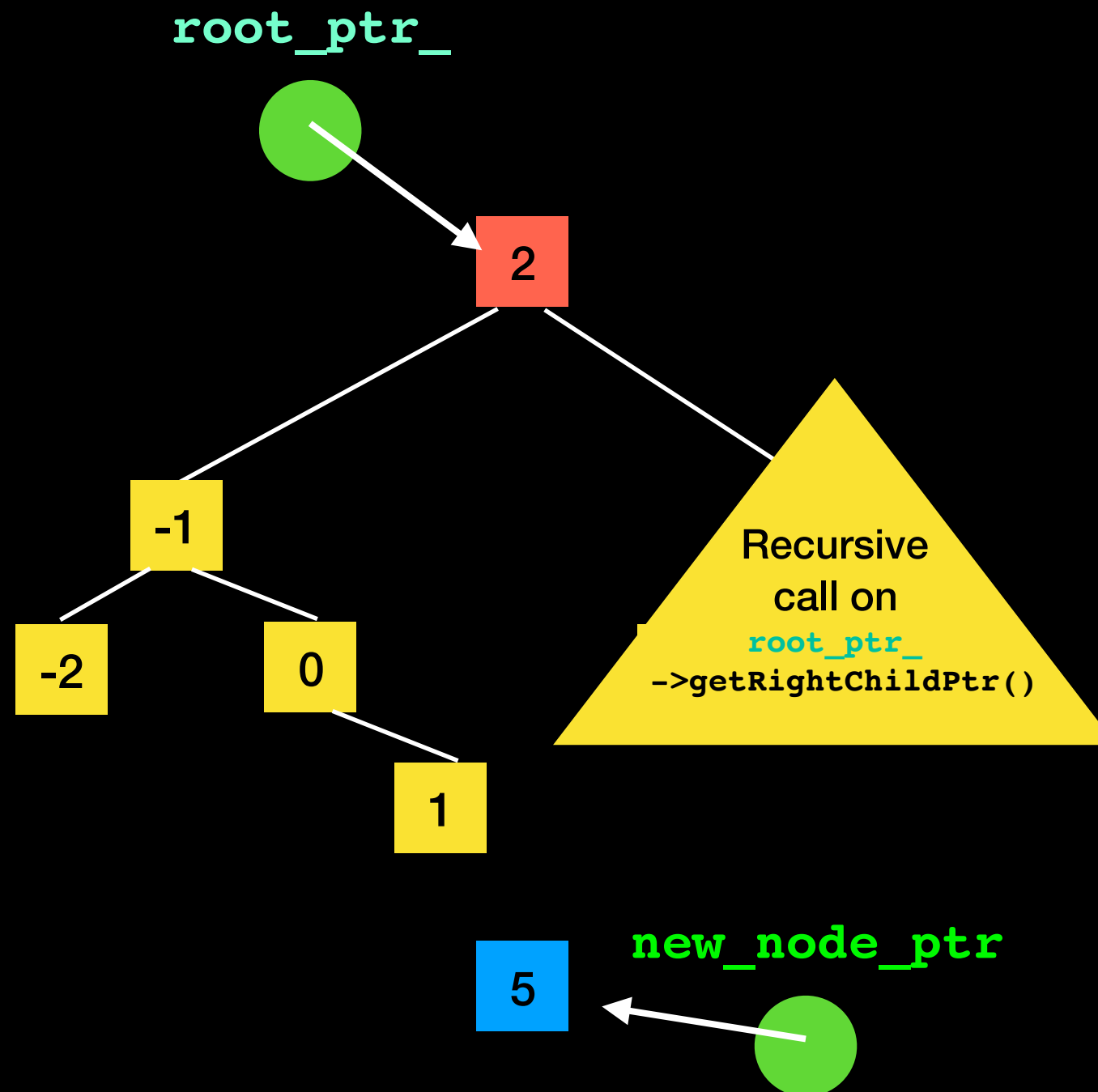
```
placeNode(root_ptr_, new_node_ptr);
```



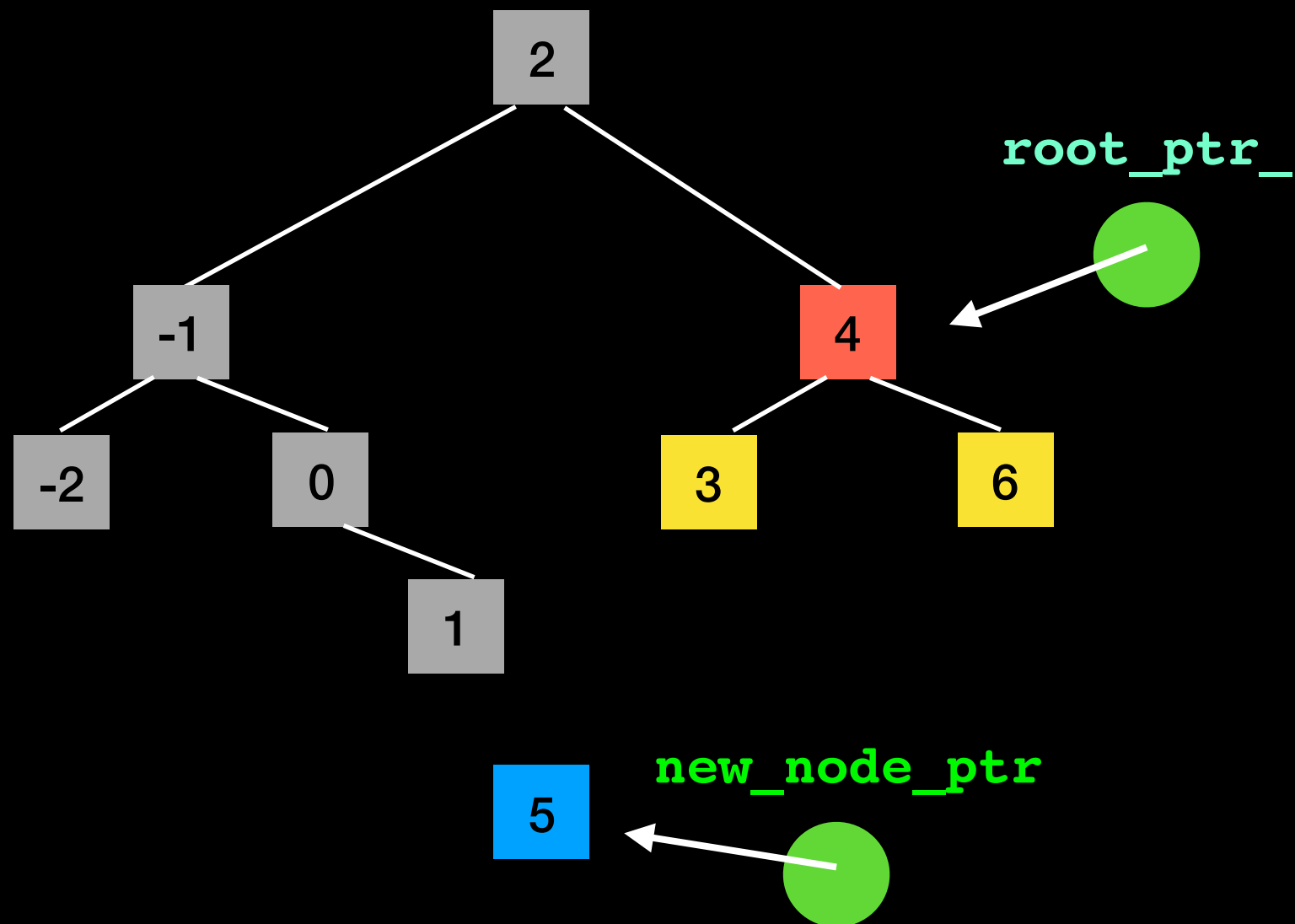
```
placeNode(root_ptr_, new_node_ptr);
```



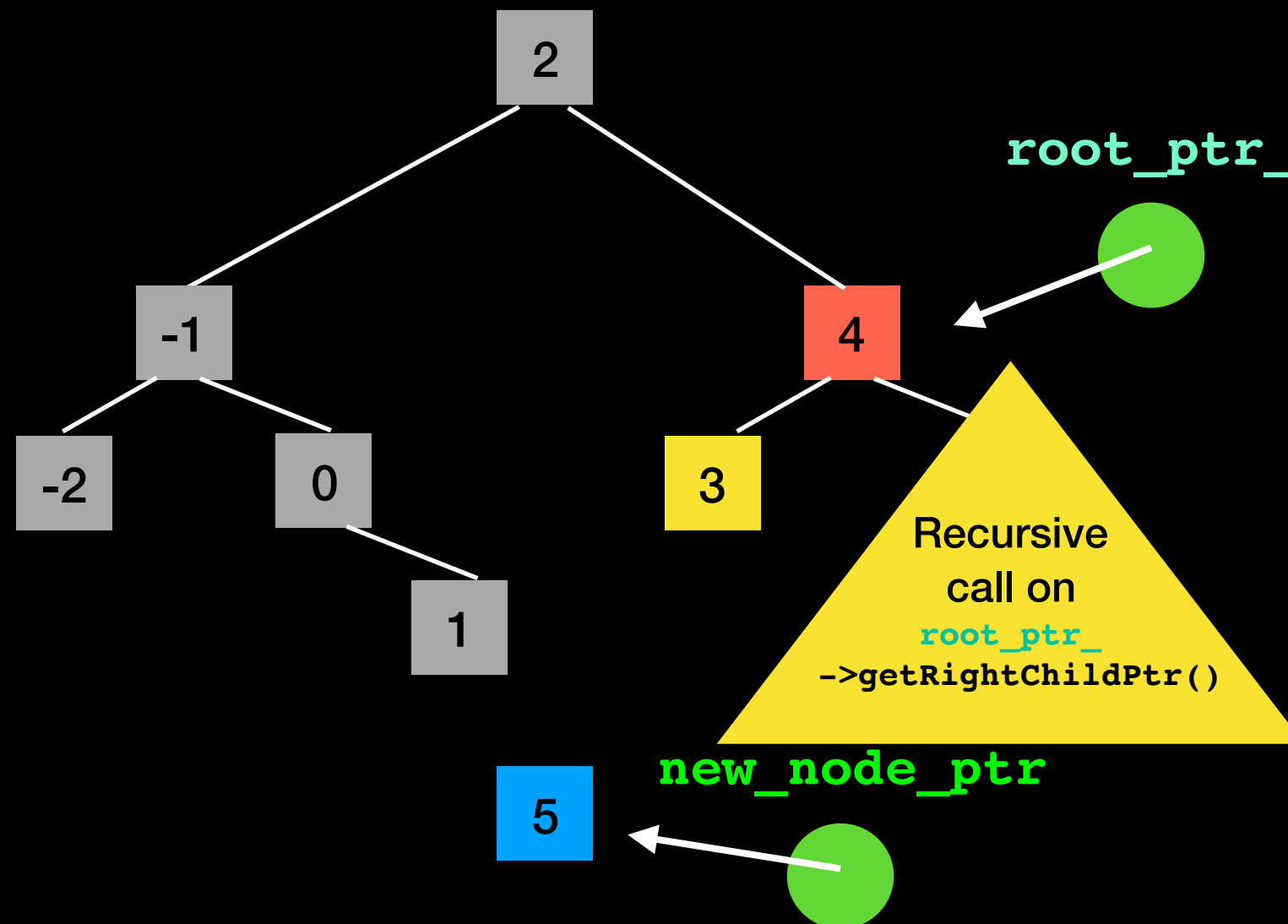

```
placeNode(root_ptr_, new_node_ptr);
```



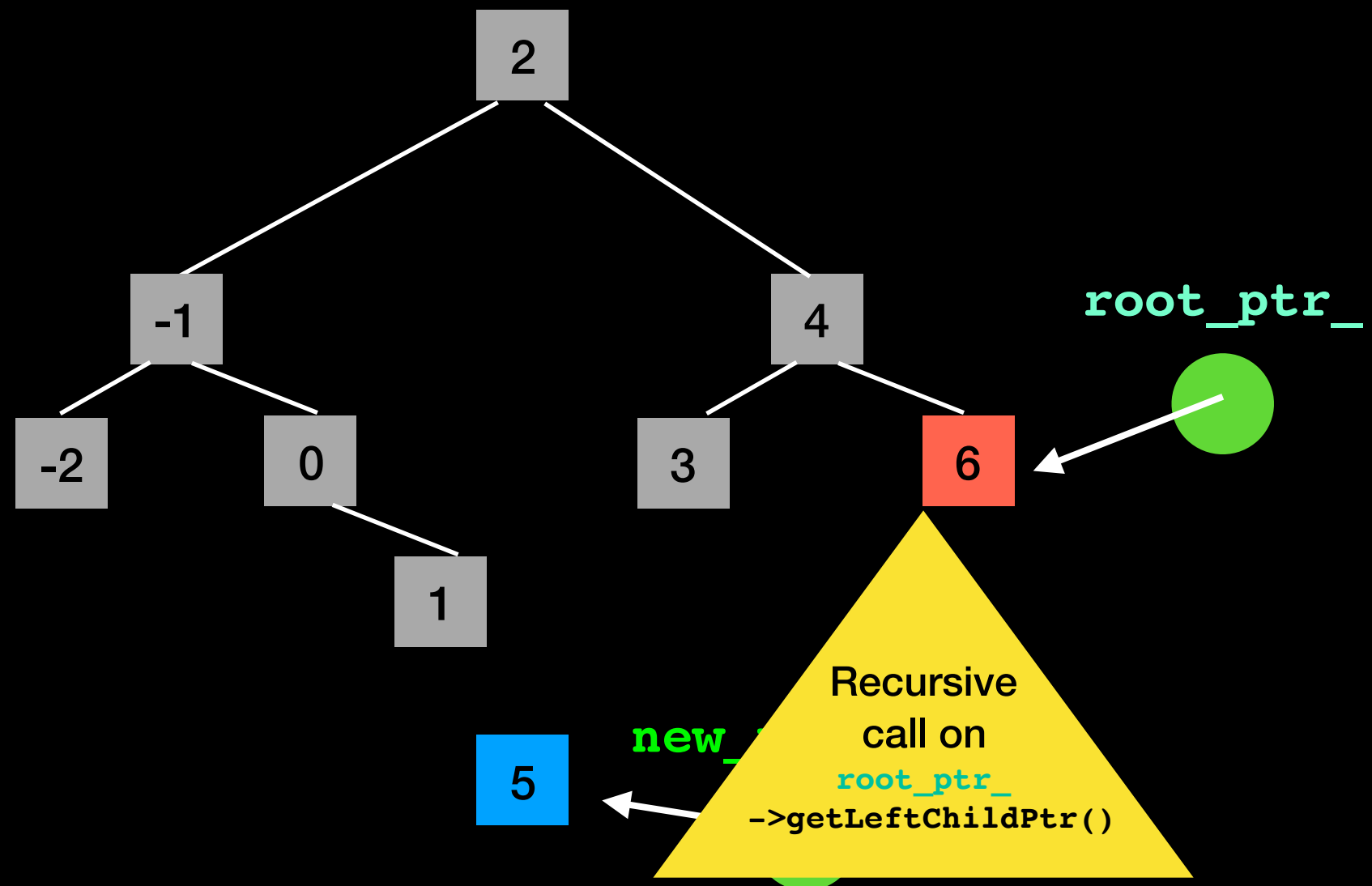
```
placeNode(root_ptr_, new_node_ptr);
```



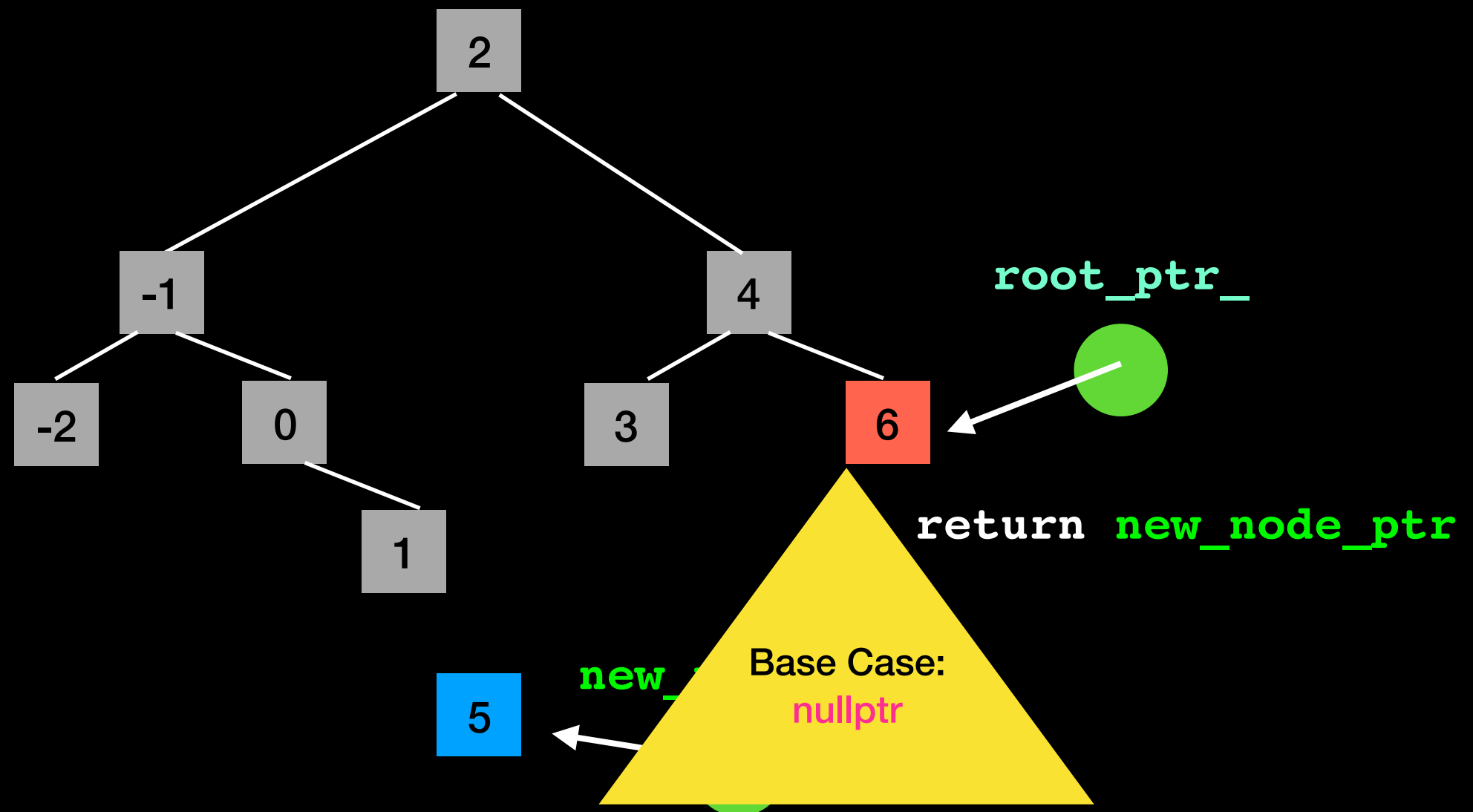
```
placeNode(root_ptr_, new_node_ptr);
```



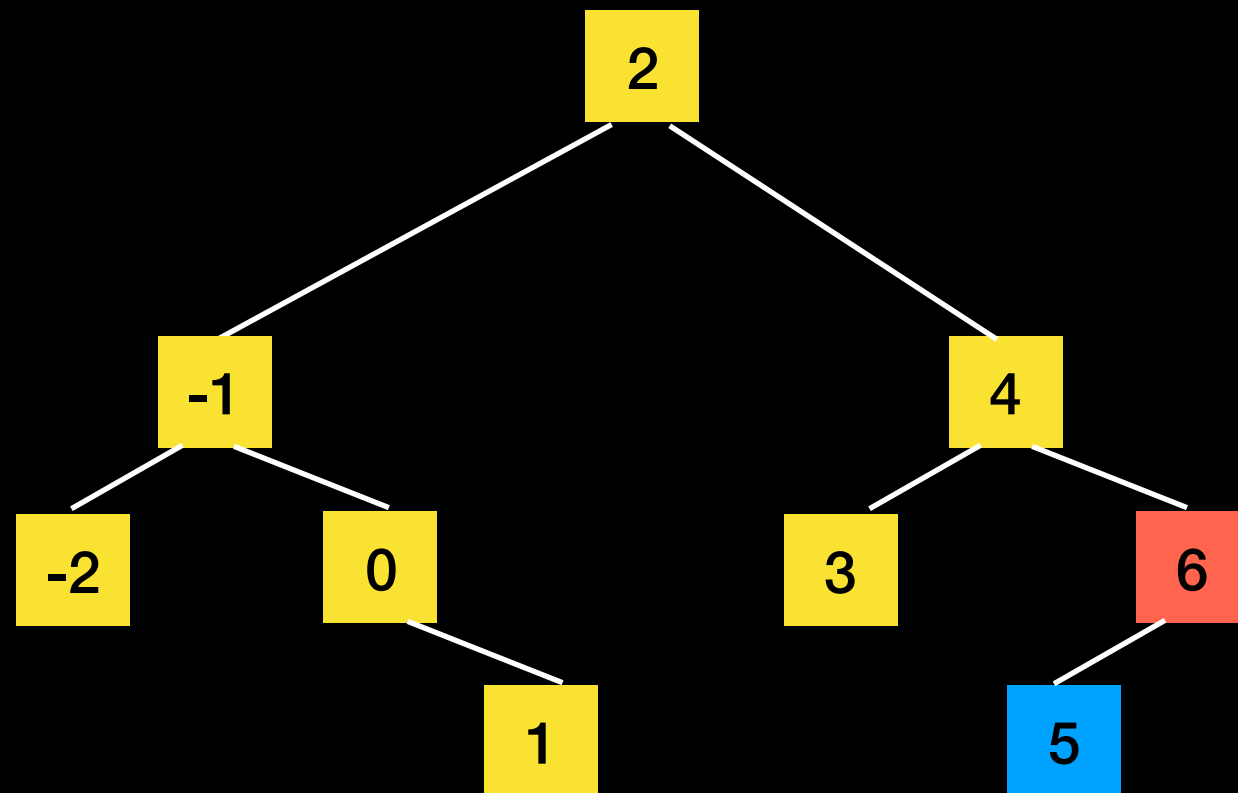
```
placeNode(root_ptr_, new_node_ptr);
```



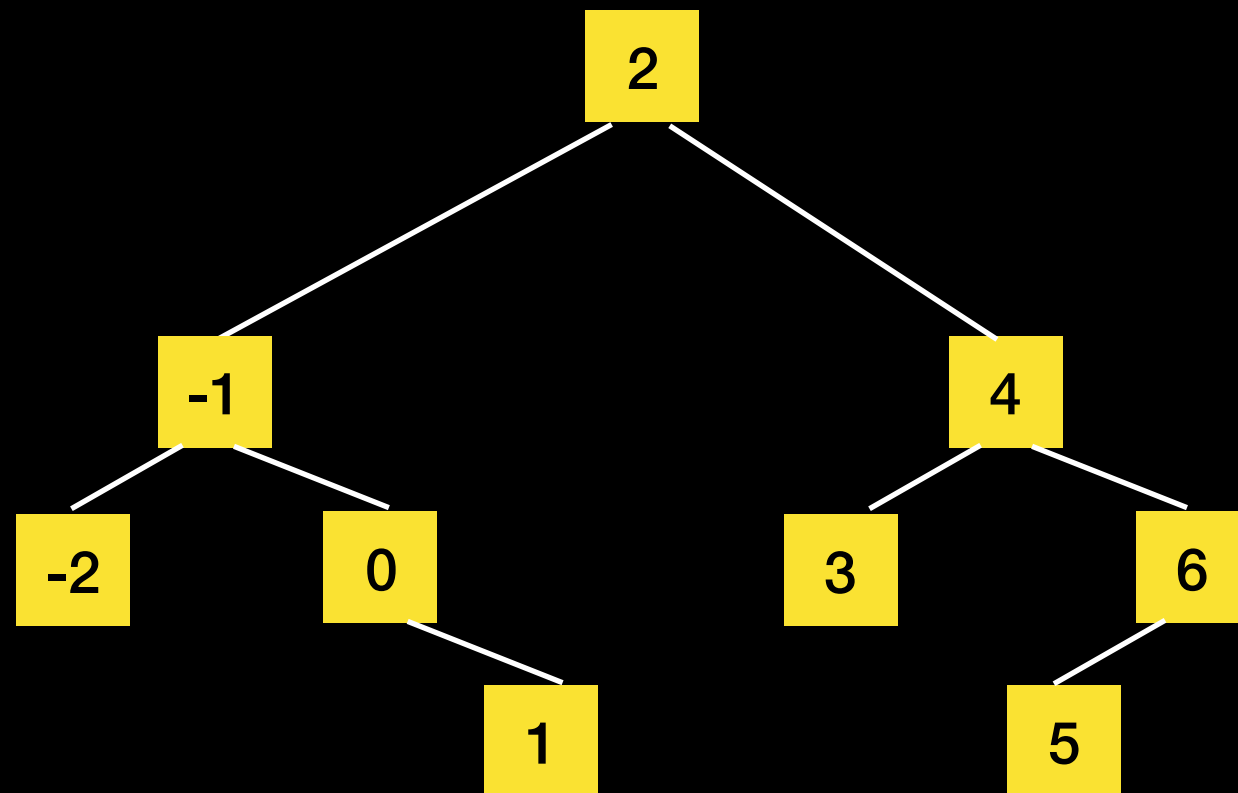
```
placeNode(root_ptr_, new_node_ptr);
```



```
placeNode(root_ptr_, new_node_ptr);
```



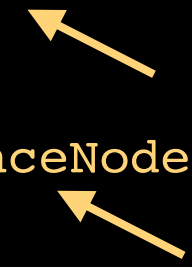
```
placeNode(root_ptr_, new_node_ptr);
```



add helper function

```
template<class T>
auto BST<T>::placeNode(std::shared_ptr<BinaryNode<T>> subtree_ptr,
                      std::shared_ptr<BinaryNode<T>> new_node_ptr)
{
    if (subtree_ptr == nullptr)
        return new_node_ptr; //base case
    else
    {
        if (subtree_ptr->getItem() > new_node_ptr->getItem())
            subtree_ptr->setLeftChildPtr(placeNode(subtree_ptr->getLeftChildPtr(),
                                                    new_node_ptr));
        else
            subtree_ptr->setRightChildPtr(placeNode(subtree_ptr->getRightChildPtr(),
                                                    new_node_ptr));

        return subtree_ptr;
    } // end if
} // end placeNode
```



remove

```
template<class T>
bool BST<T>::remove(const T& target)
{
    bool is_successful = false;
    // call may change is_successful
    root_ptr_ = removeValue(root_ptr_, target, is_successful);
    return is_successful;
} // end remove
```

Safe programming: the public method does not take pointer parameter.
Only protected/private methods have access to pointers and may modify tree structure

remove helper function

Looks for the value
to remove

```
template<class T>
auto BST<T>::removeValue(std::shared_ptr<BinaryNode<T>>
    subtree_ptr, const T target, bool& success)
{
    if (subtree_ptr == nullptr)
    {
        // Not found here
        success = false;
        return subtree_ptr;
    }
    if (subtree_ptr->getItem() == target)
    {
        // Item is in the root of this subtree
        subtree_ptr = removeNode(subtree_ptr);
        success = true;
        return subtree_ptr;
    }
}
```

target not in tree

Found target now
remove the node

remove helper function cont.ed

```
else
{
    if (subtree_ptr->getItem() > target)
    {
        // Search the left subtree
        subtree_ptr->setLeftChildPtr(removeValue(subtree_ptr
                                                ->getLeftChildPtr(), target, success));
    }
    else
    {
        // Search the right subtree
        subtree_ptr->setRightChildPtr(removeValue(subtree_ptr
                                                  ->getRightChildPtr(), target, success));
    }
    return subtree_ptr;
} // end if
} // end removeValue
```

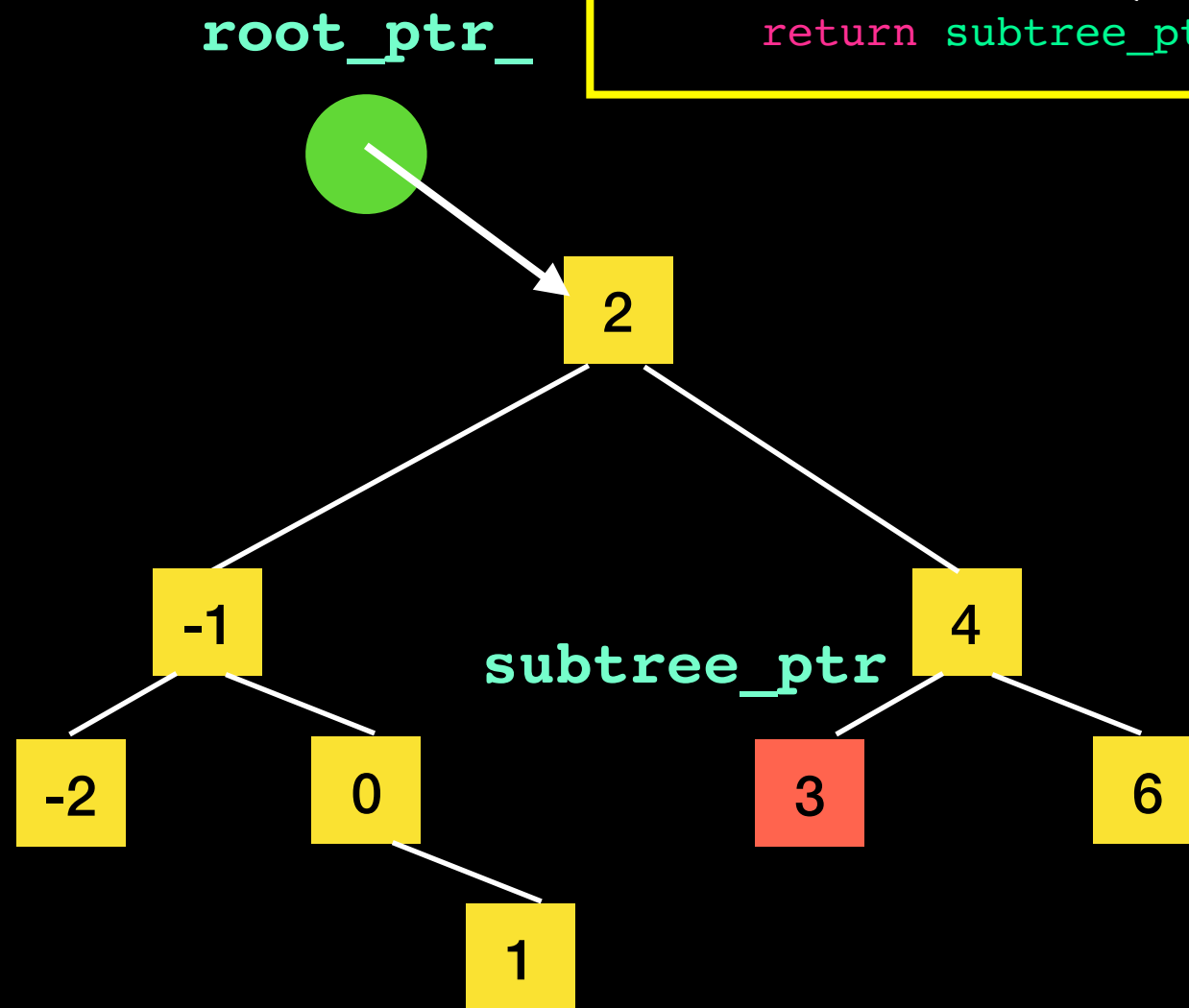
Search for target in left subtree

Search for target in right subtree

removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

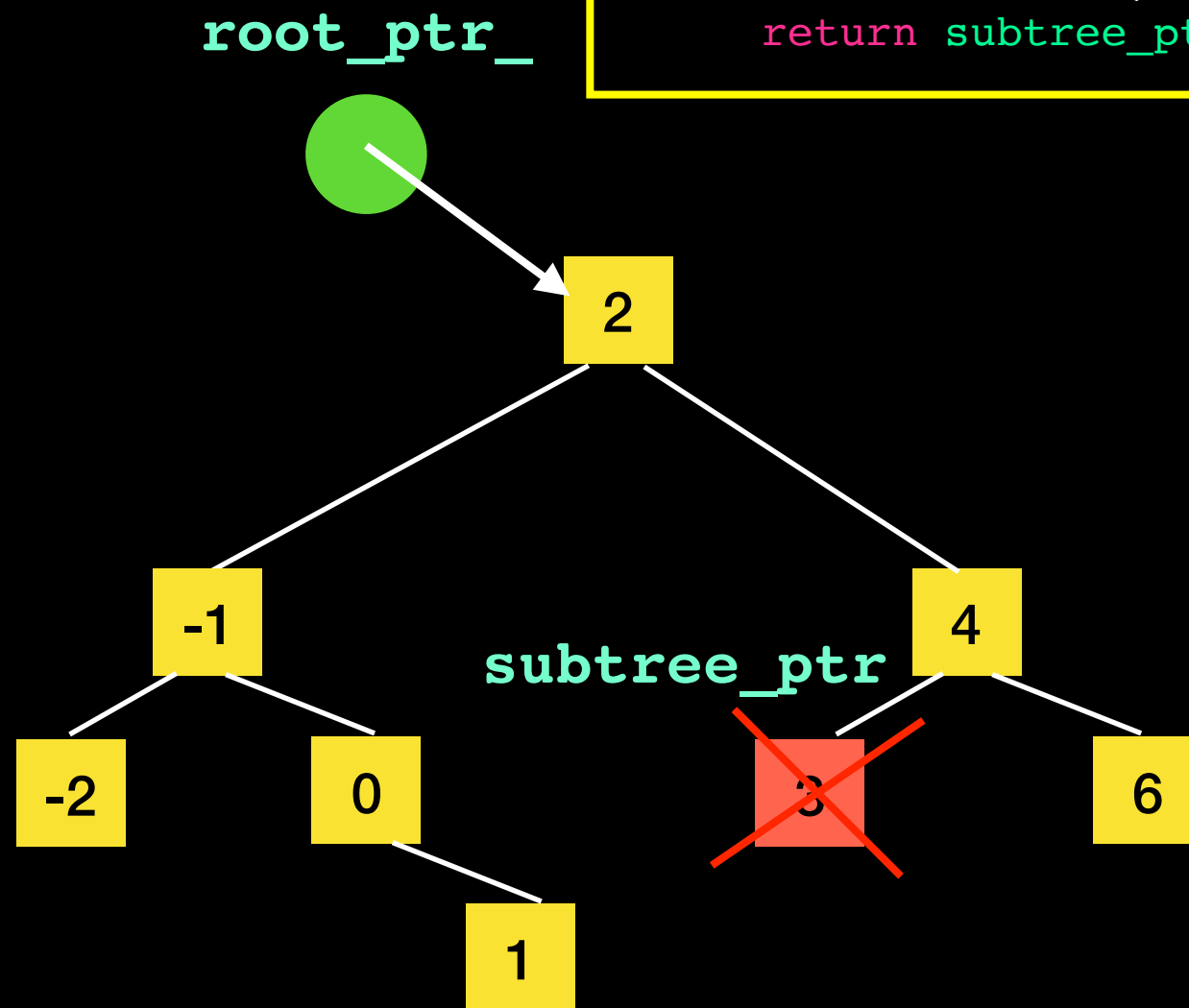
Case 1: target is a leaf



removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

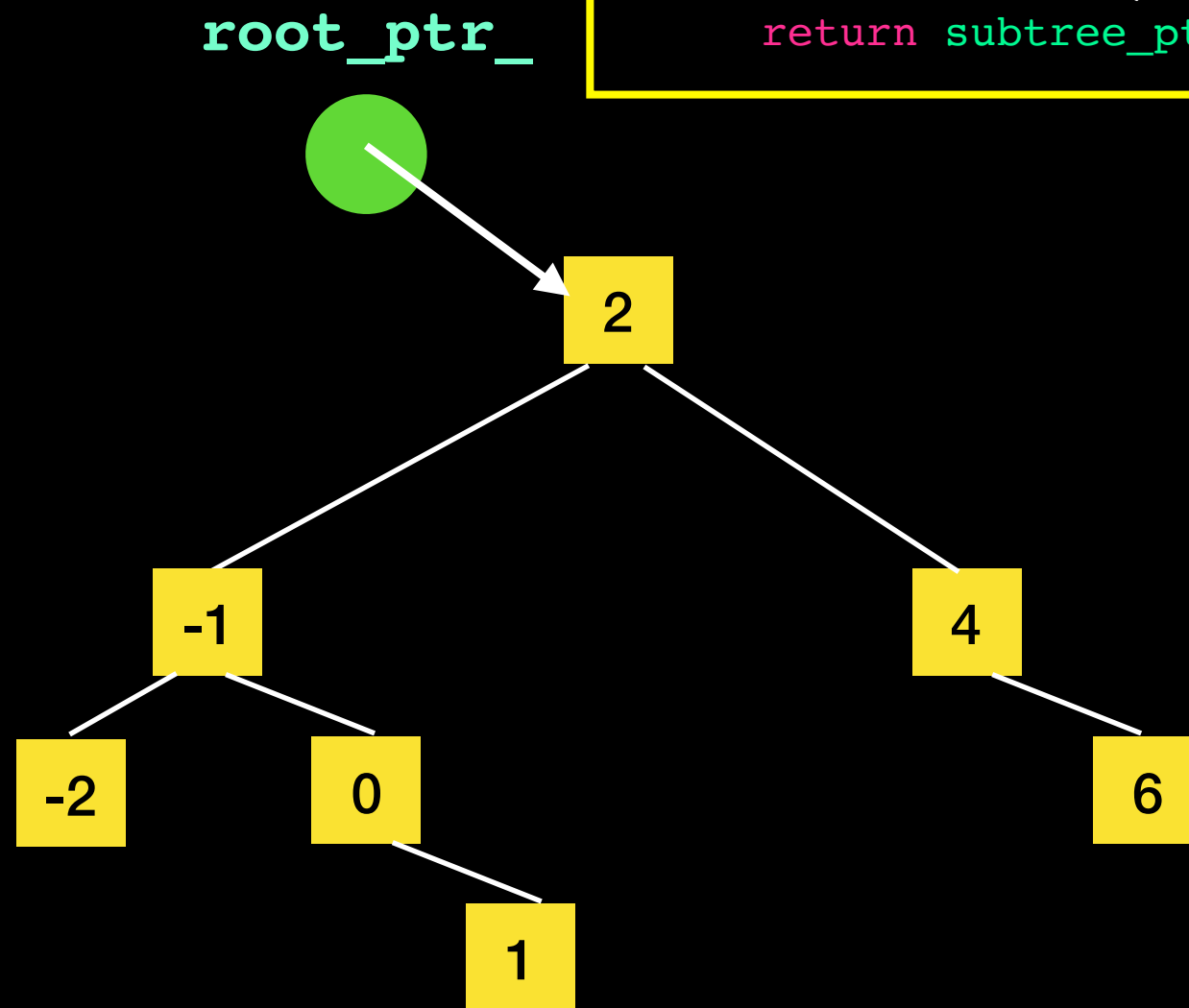
Case 1: target is a leaf



removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

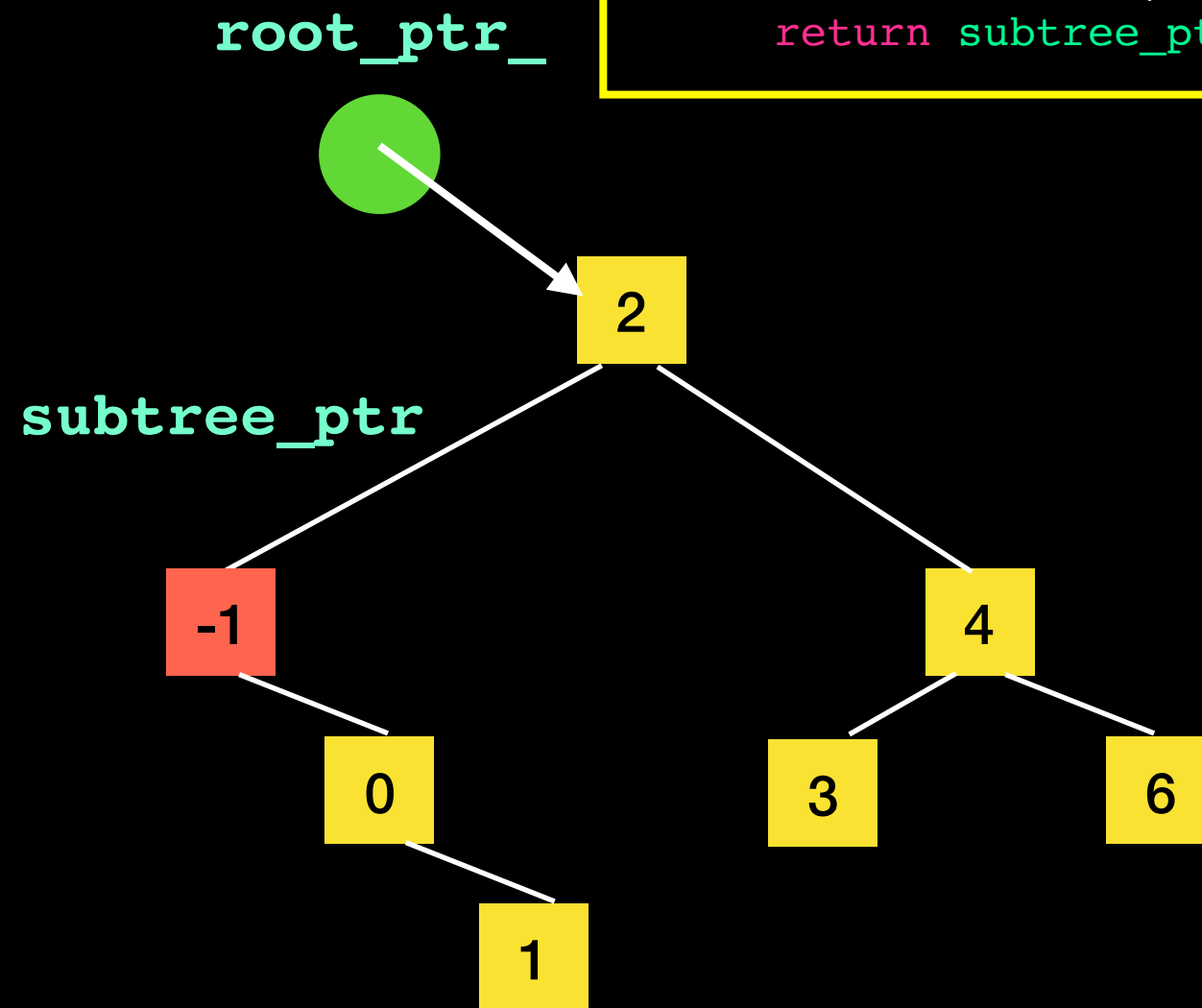
Case 1: target is a leaf



removeNode(subtree_ptr);

Case 2: target has 1 child
Left and right case are symmetric

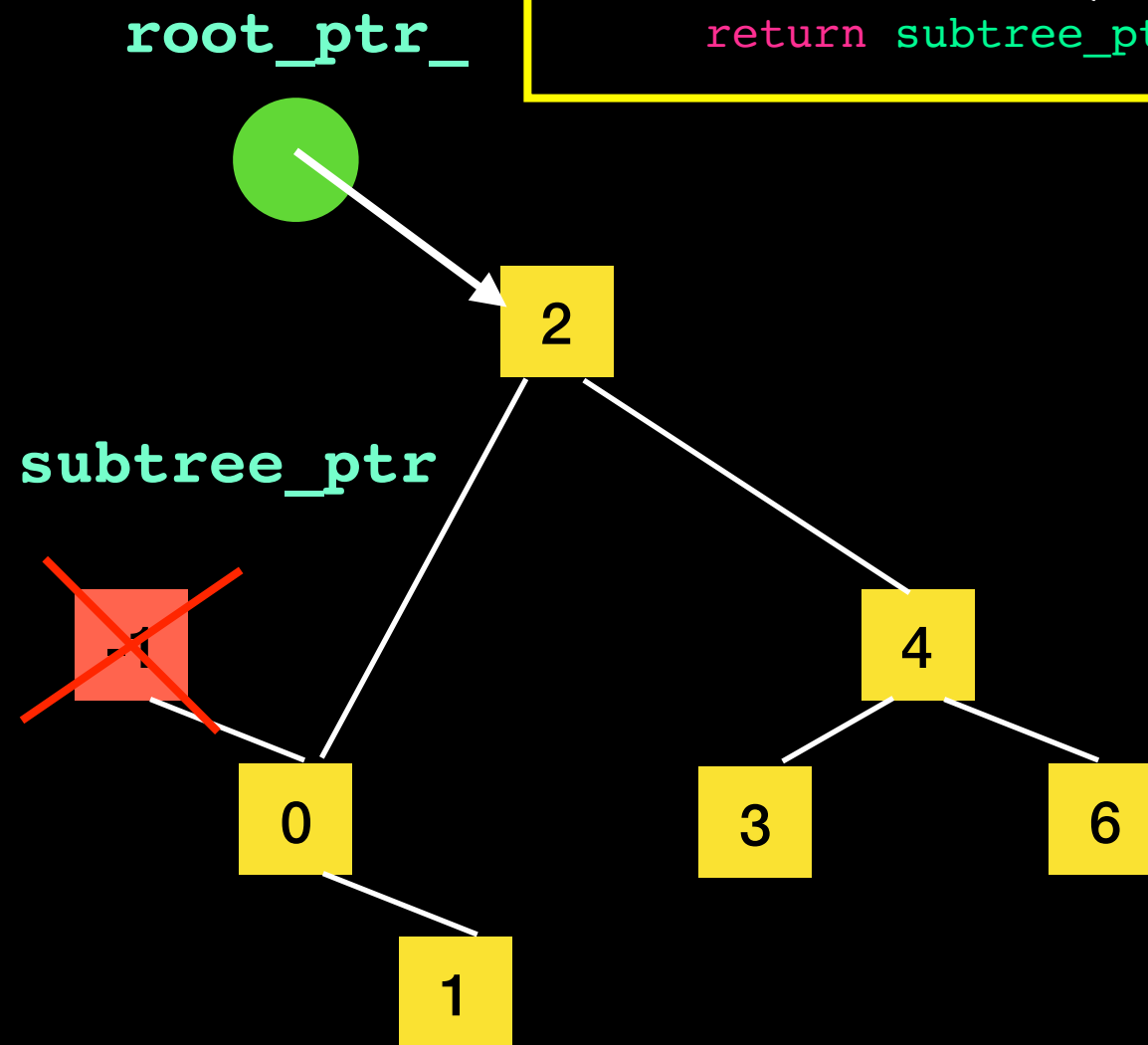
```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```



removeNode(subtree_ptr);

Case 2: target has 1 child
Left and right case are symmetric

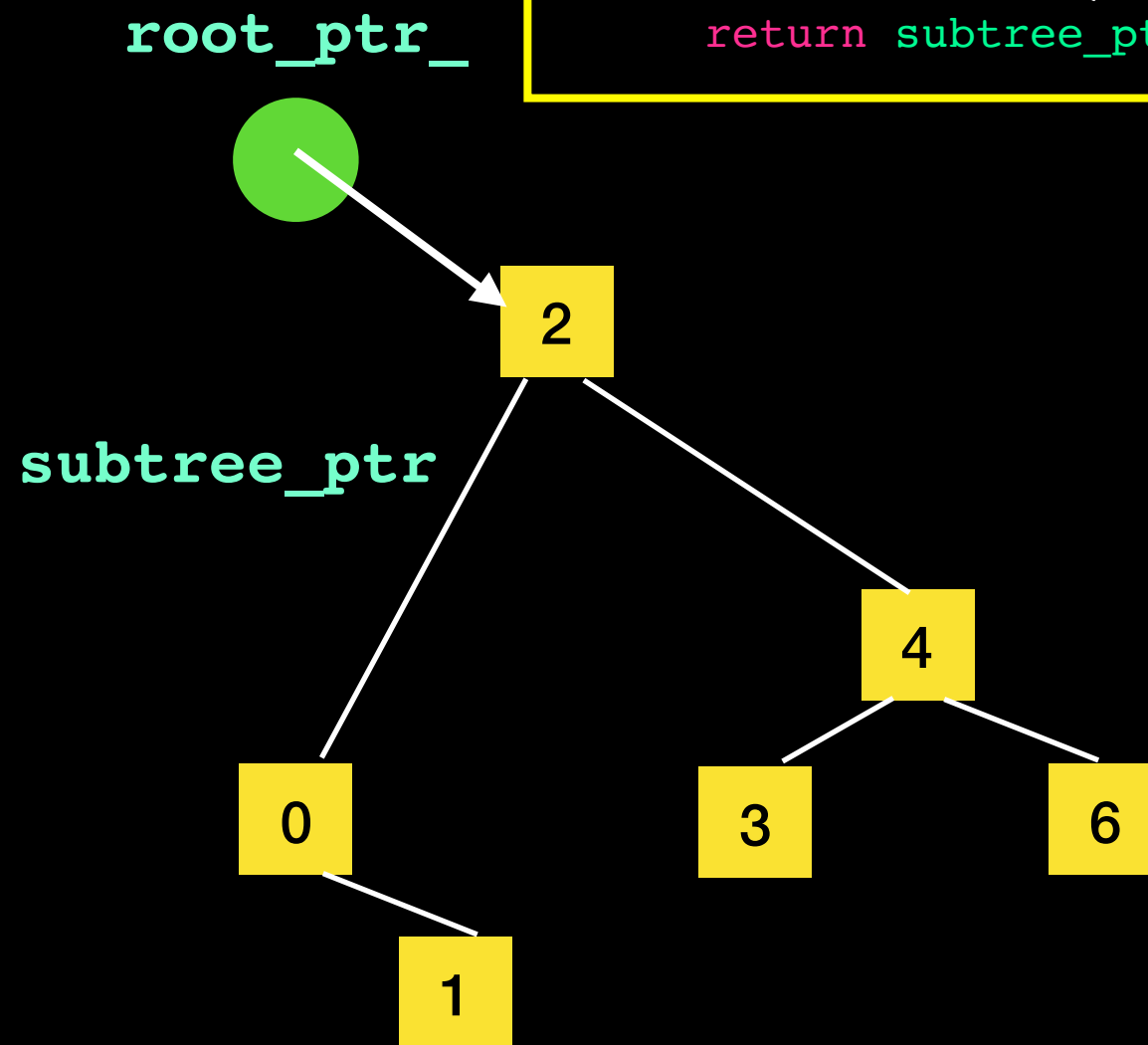
```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```



removeNode(subtree_ptr);

Case 2: target has 1 child
Left and right case are symmetric

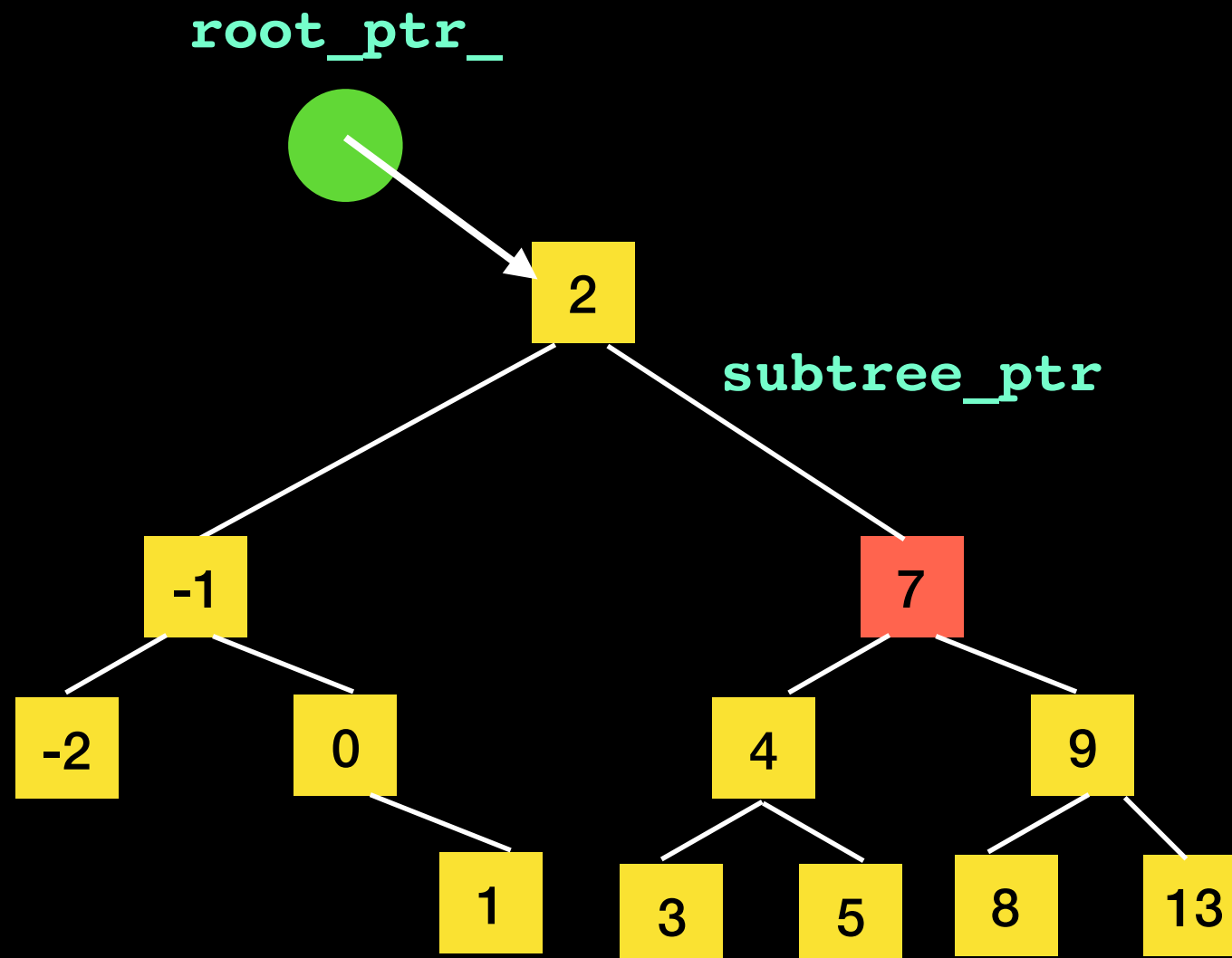
```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```



Lecture Activity

How would you remove node 7?

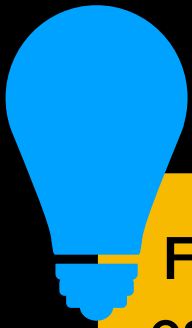
Case 3: target has 2 children



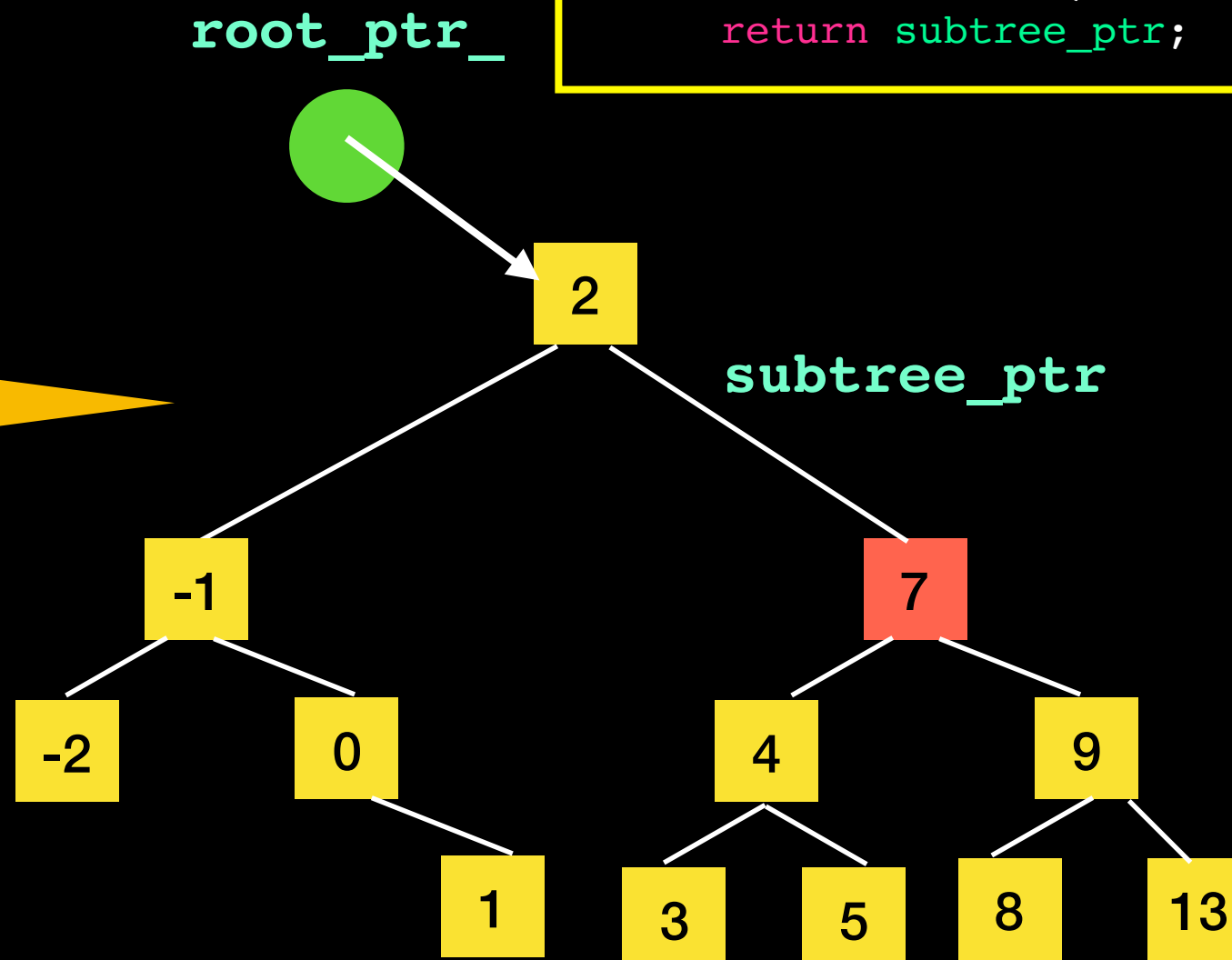
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



Find a node that is easy to remove and remove that one instead.

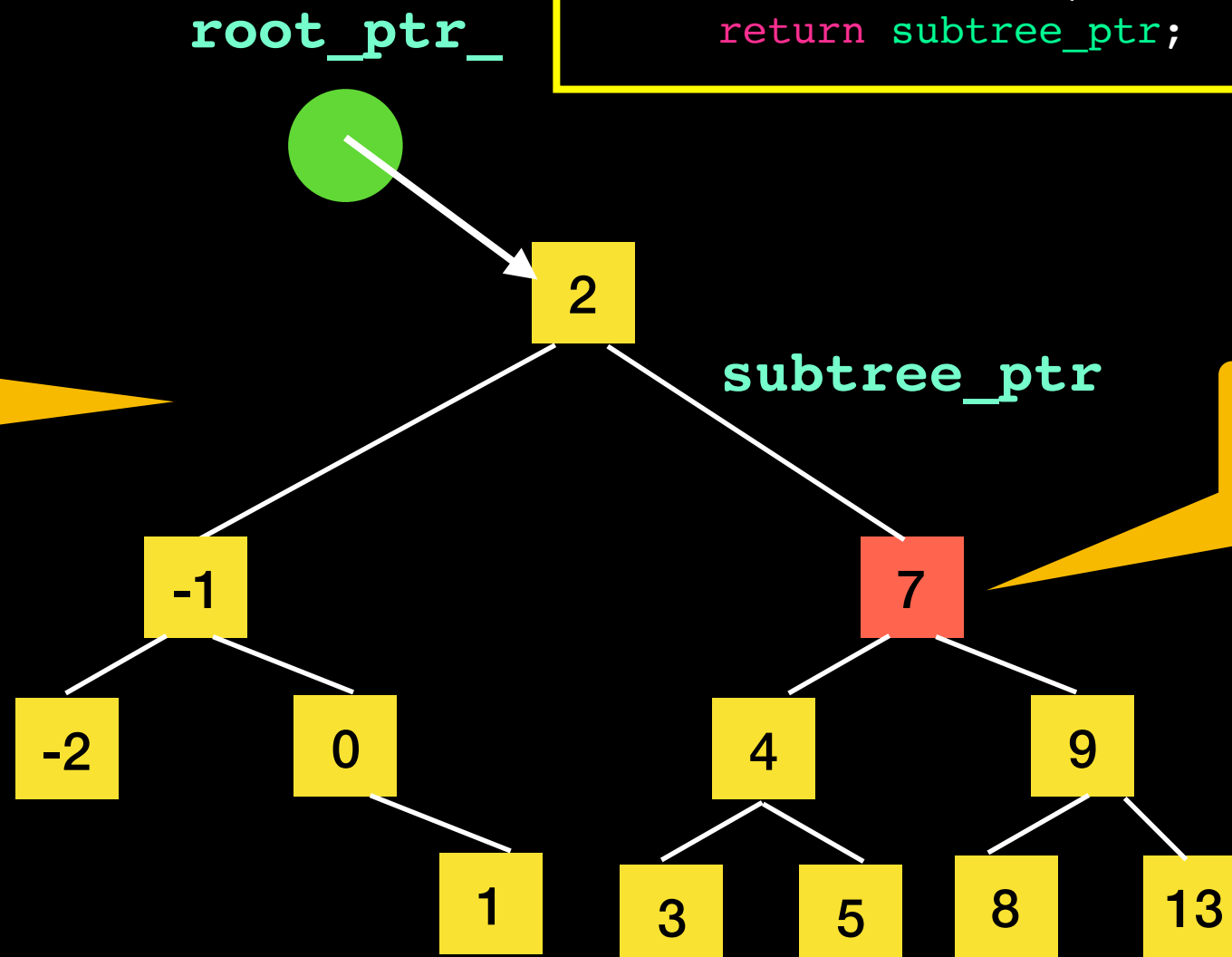


removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.



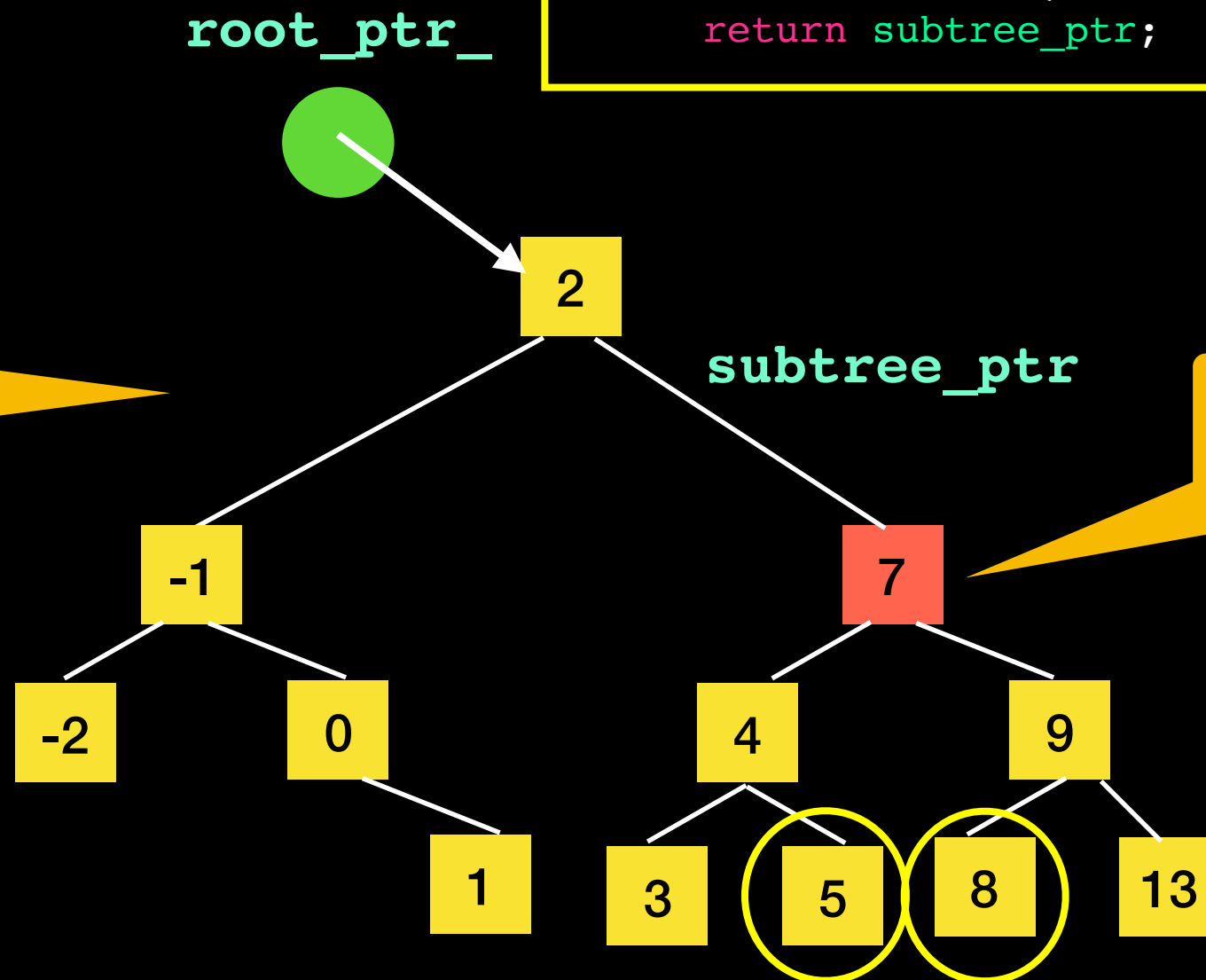
What value should we put here?

removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.

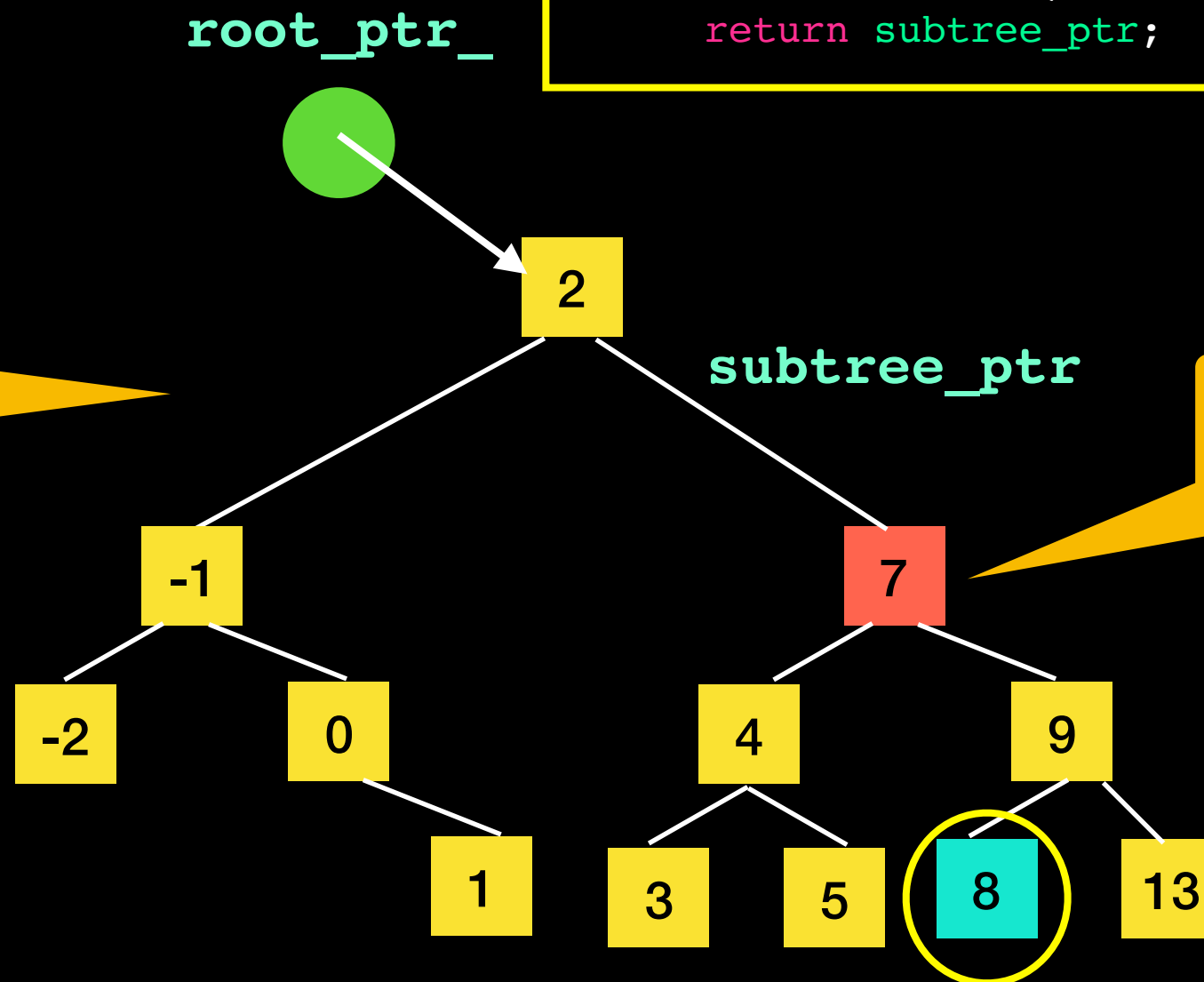


removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.



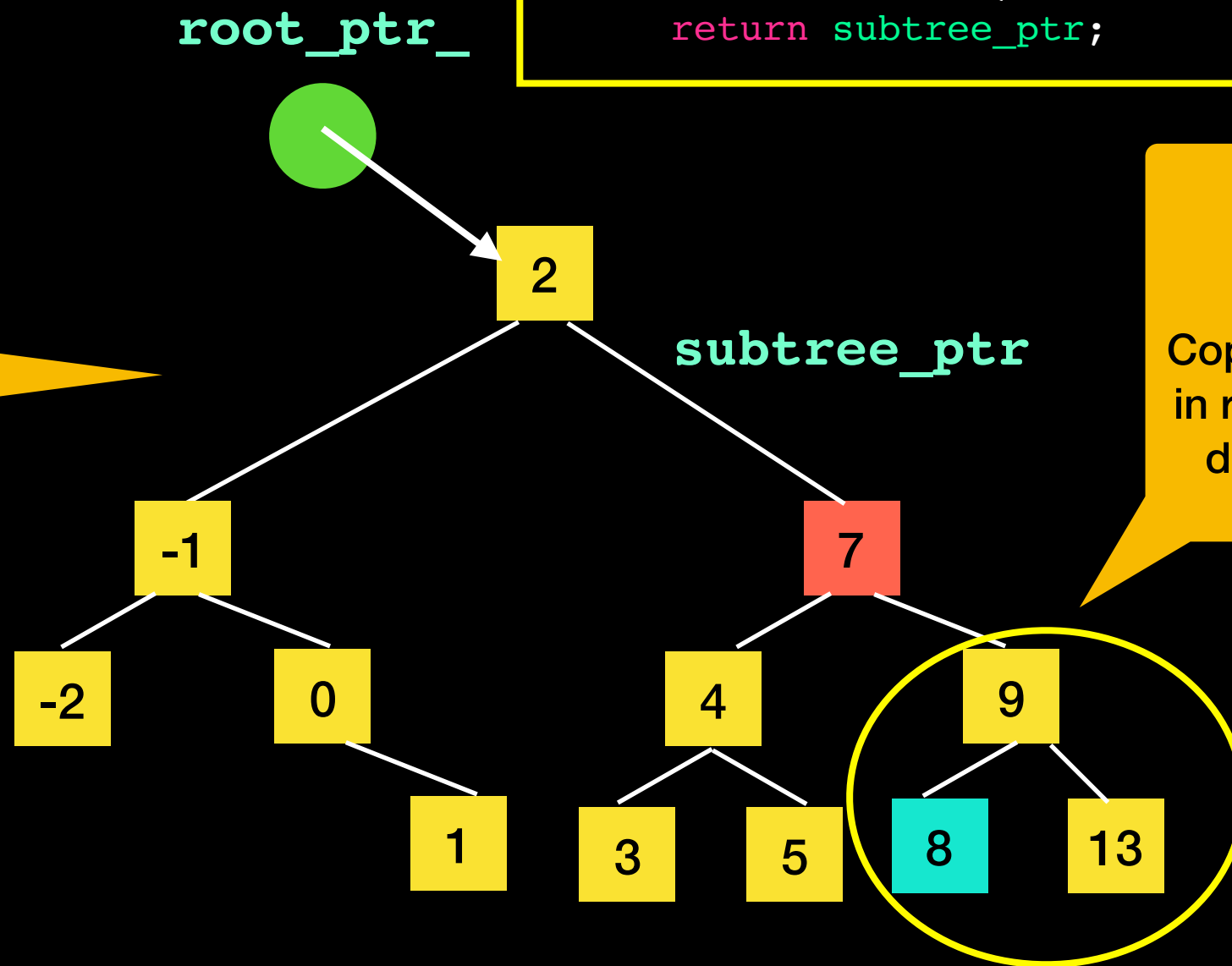
The *inorder* successor

removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.

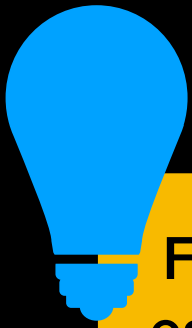


The *inorder* successor:
Copy smallest value in right subtree and delete that node

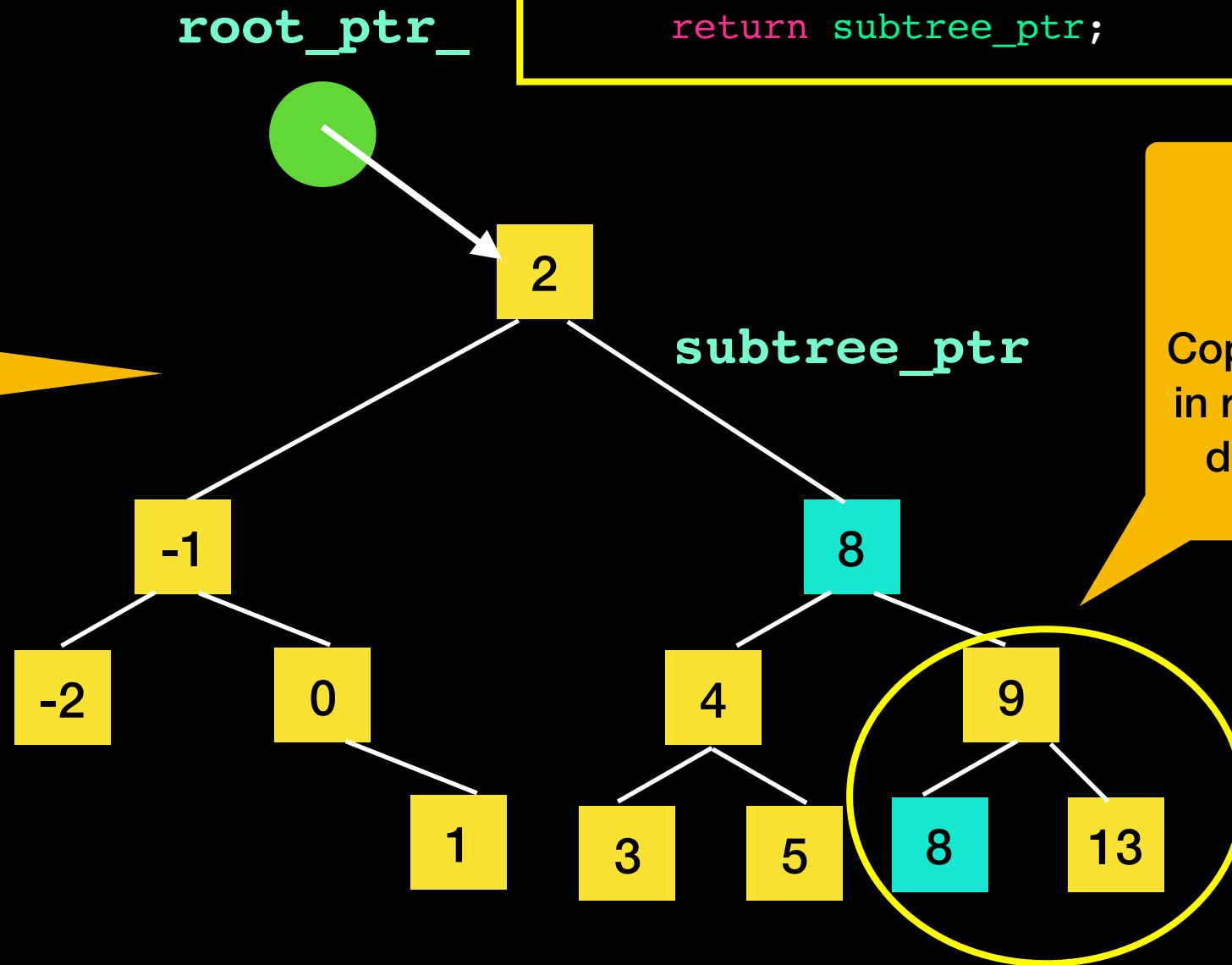
removeNode(subtree_ptr);

Case 3: target has 2 children

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```



Find a node that is easy to remove and remove that one instead.



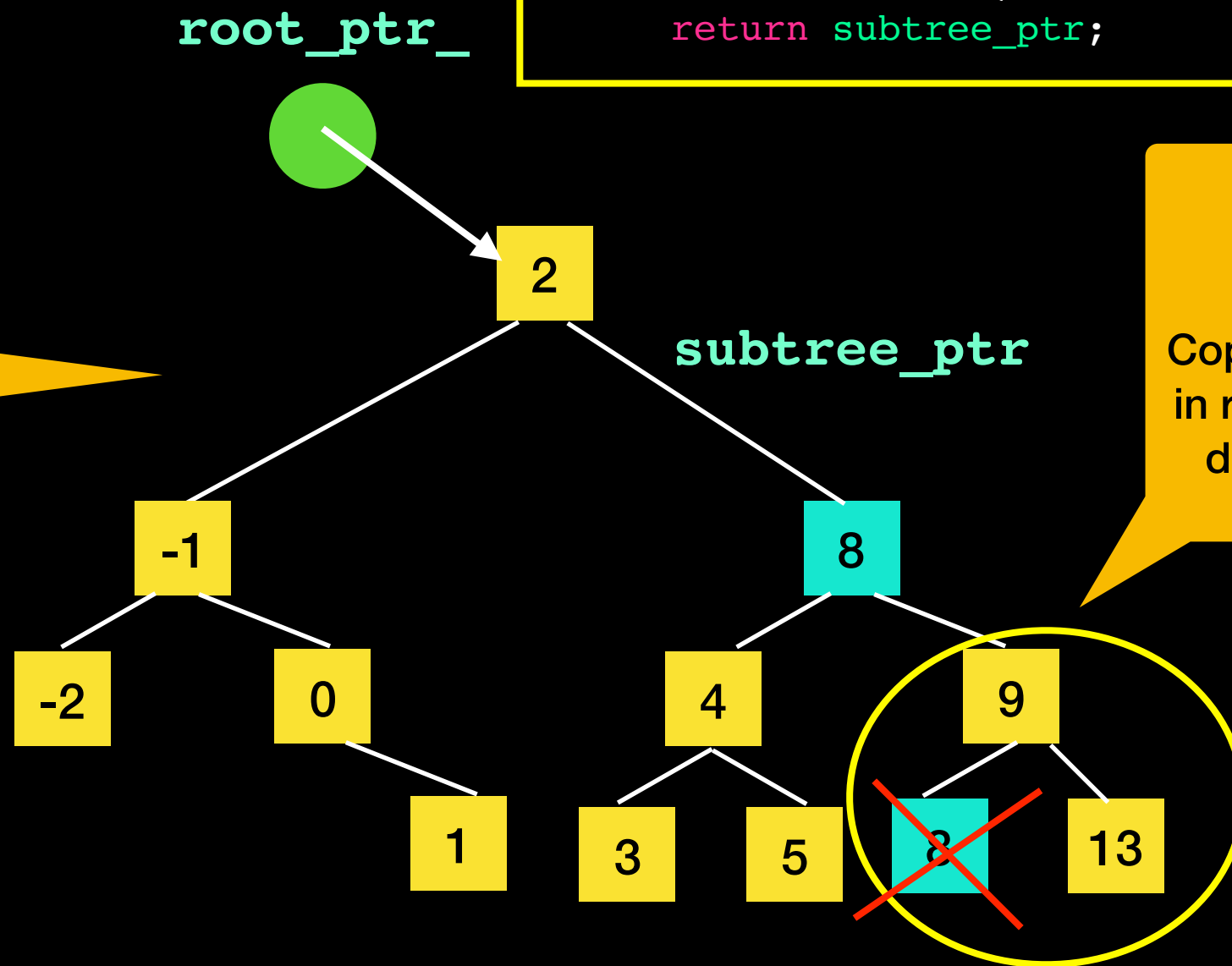
The *inorder successor*:
Copy smallest value in right subtree and delete that node

removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.

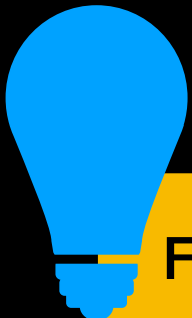


The *inorder successor*:
Copy smallest value in right subtree and delete that node

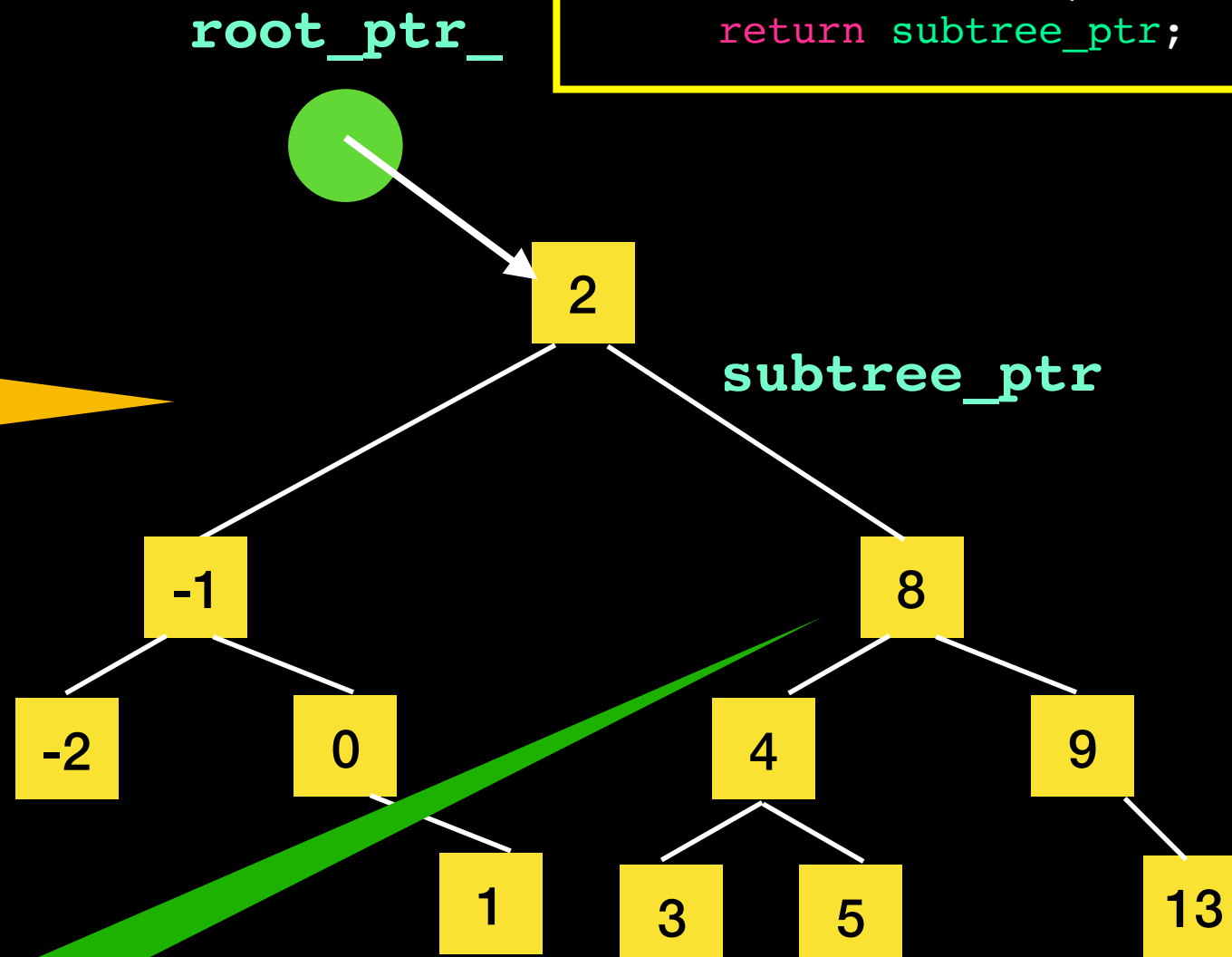
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



Find a node that is easy to remove and remove that one instead.

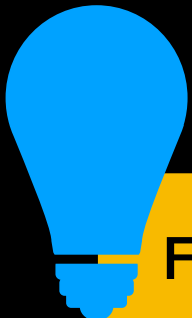


This operation will actually “reorganize” the tree

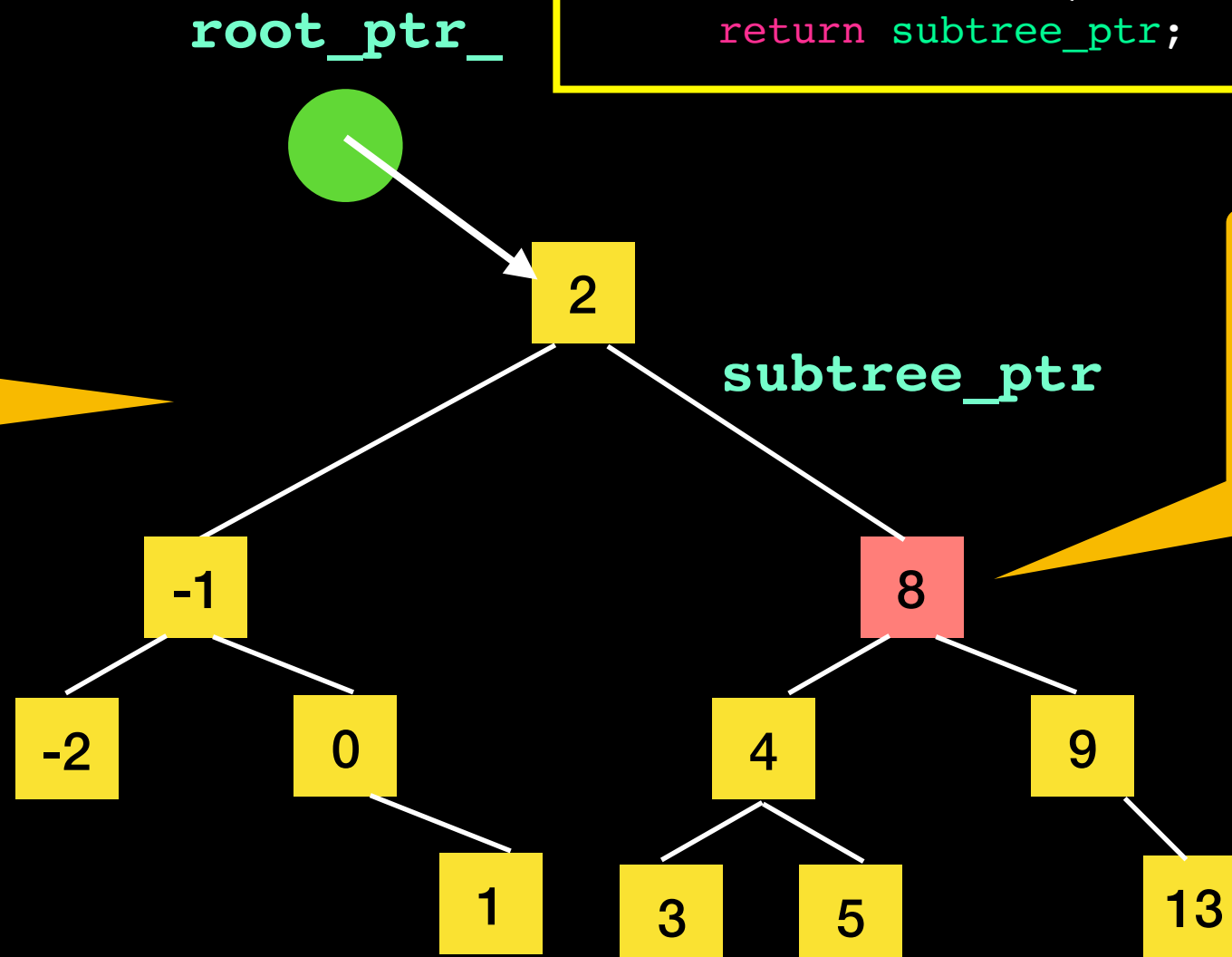
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



Find a node that is easy to remove and remove that one instead.



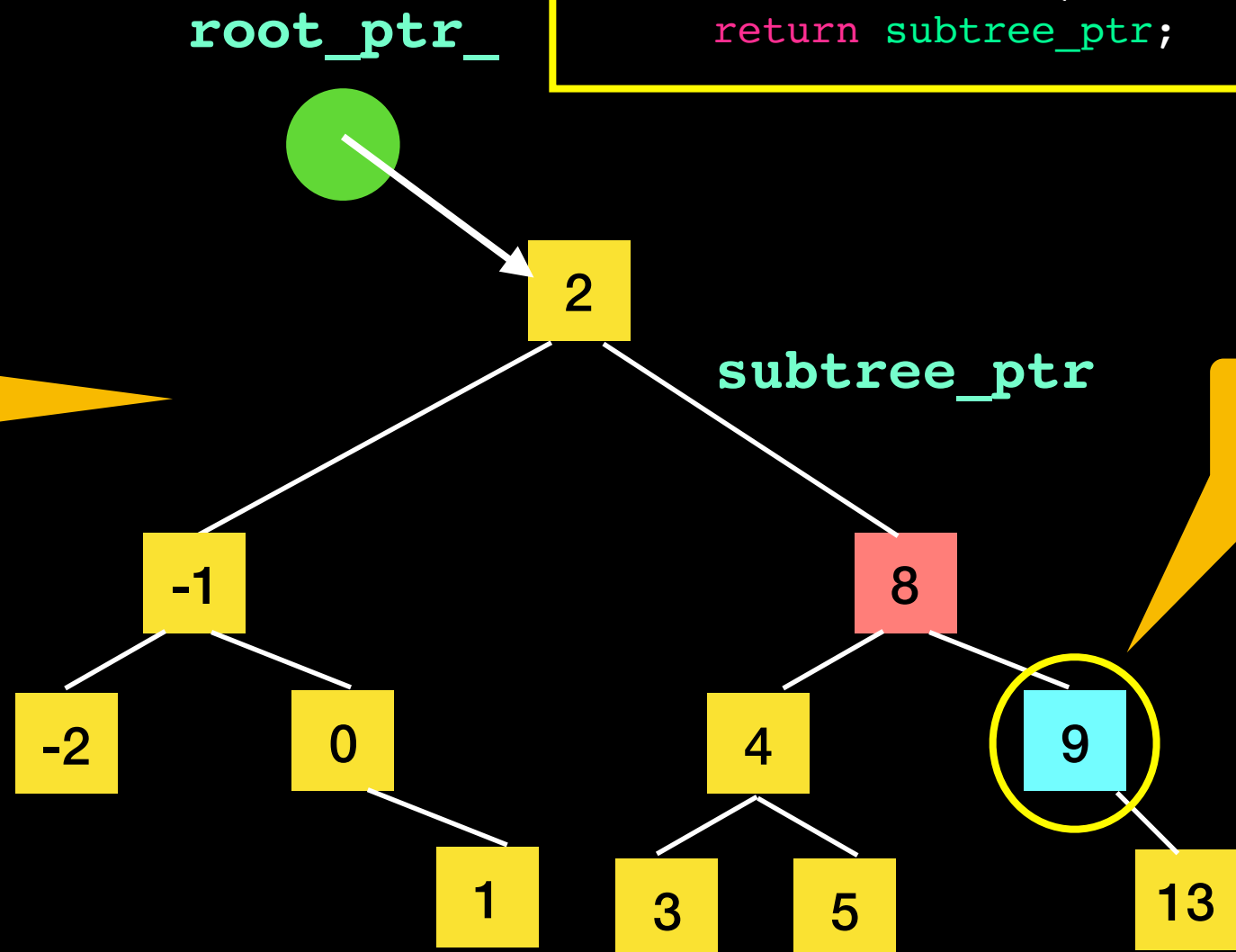
What about removing 8 now?
What value should we put here?

removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children

Find a node that is easy to remove and remove that one instead.

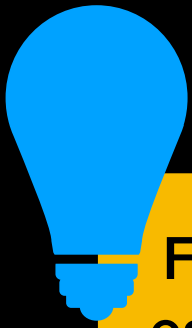


The *inorder successor*

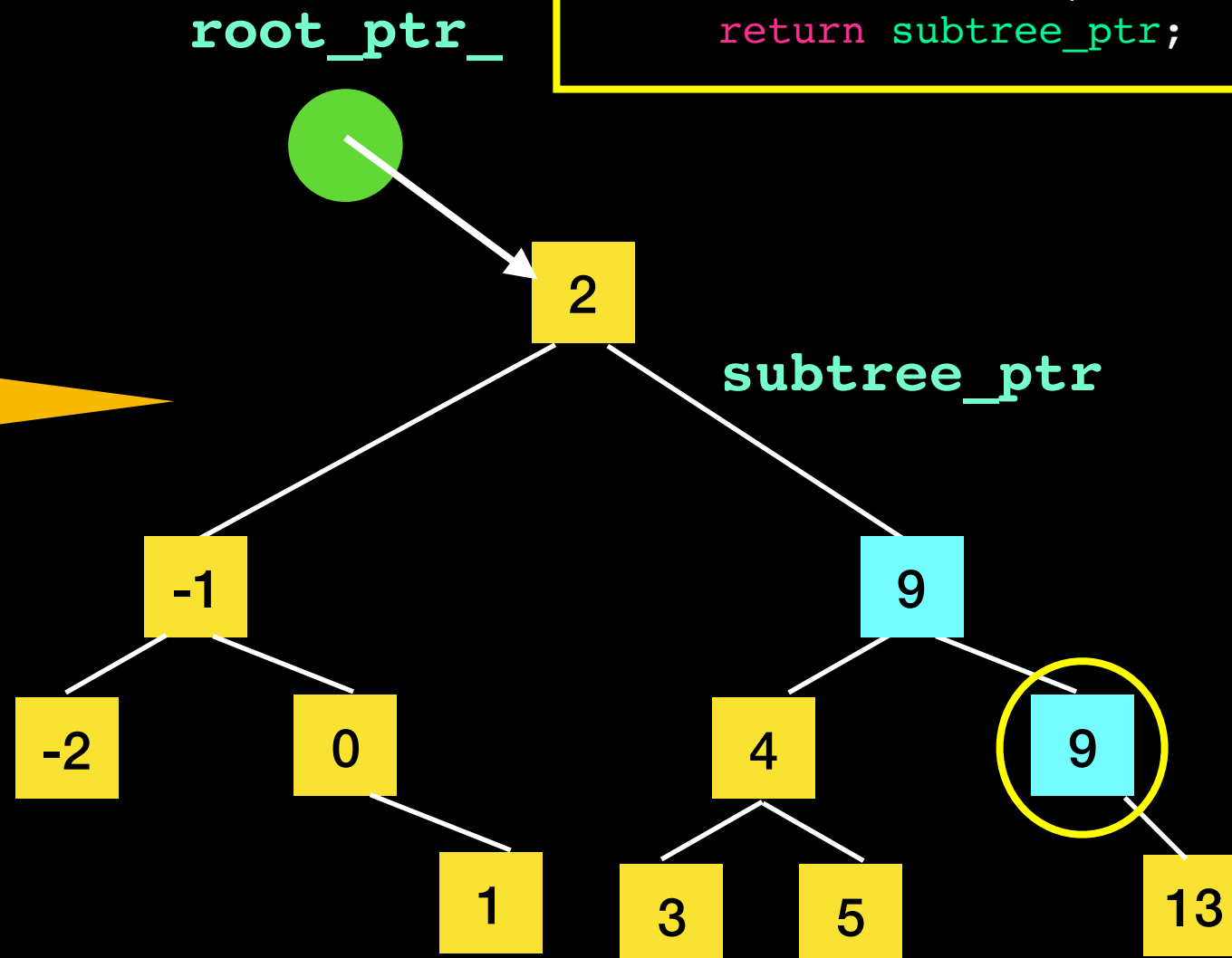
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



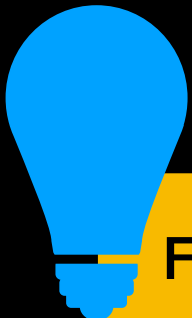
Find a node that is easy to remove and remove that one instead.



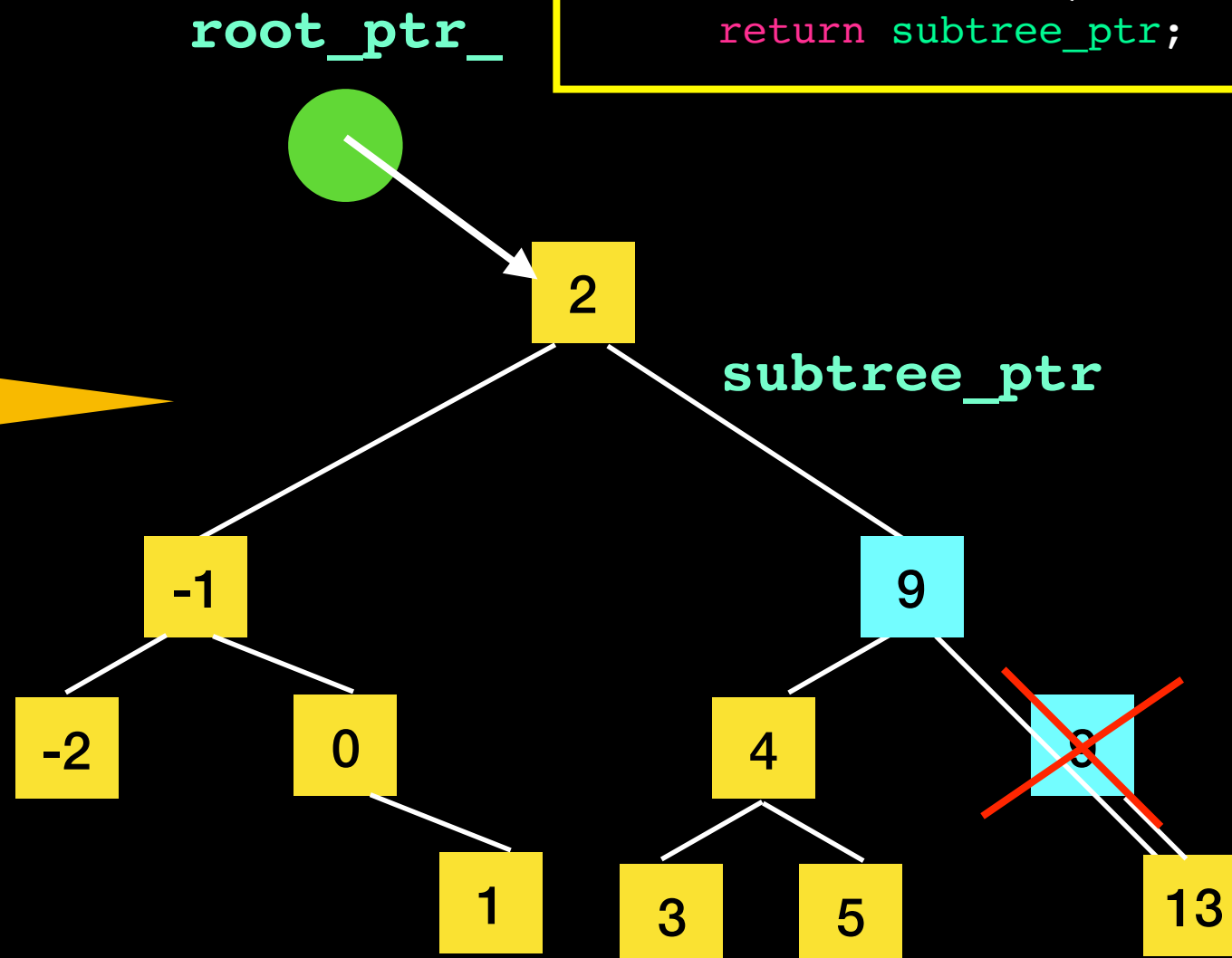
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



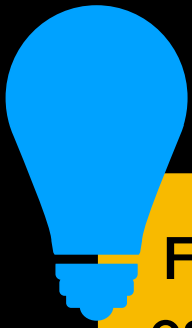
Find a node that is easy to remove and remove that one instead.



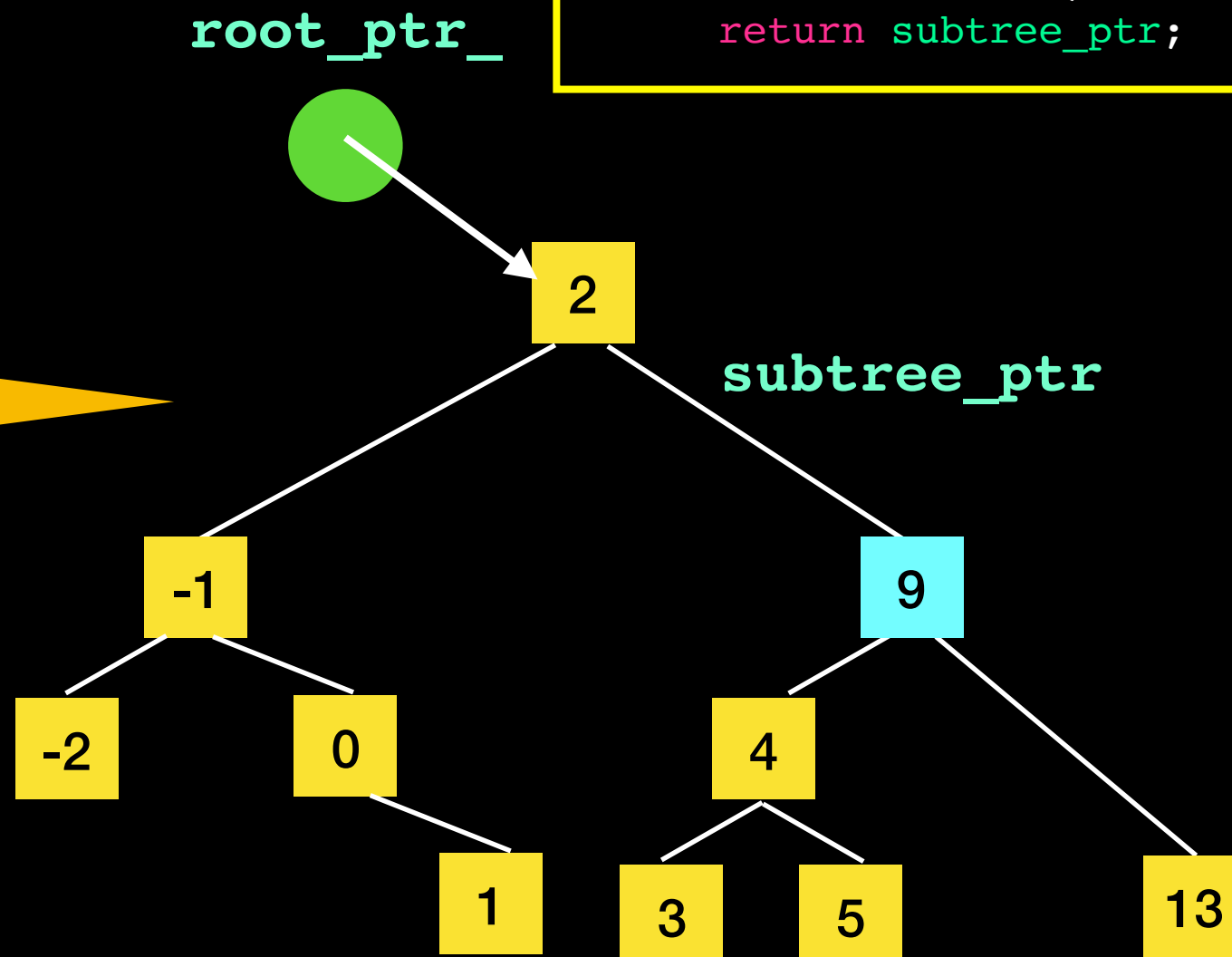
removeNode(subtree_ptr);

```
if (subtree_ptr->getItem() == target)
{
    // Item is in the root of this subtree
    subtree_ptr = removeNode(subtree_ptr);
    success = true;
    return subtree_ptr;
}
```

Case 3: target has 2 children



Find a node that is easy to remove and remove that one instead.



removeNode(*node_ptr*);

```
template<class T>
auto BST<T>::removeNode(std::shared_ptr<BinaryNode<T>> node_ptr)
{
    // Case 1) Node is a leaf - it is deleted
    if (node_ptr->isLeaf())
    {
        node_ptr.reset();
        return node_ptr; // delete and return nullptr
    }
    // Case 2) Node has one child - parent adopts child
    else if (node_ptr->getLeftChildPtr() == nullptr) // Has rightChild only
    {
        return node_ptr->getRightChildPtr();
    }
    else if (node_ptr->getRightChildPtr() == nullptr) // Has left child only
    {
        return node_ptr->getLeftChildPtr();
    }
    // Case 3) Node has two children:
    else
    {
        T new_node_value;
        node_ptr->setRightChildPtr(removeLeftmostNode(node_ptr->getRightChildPtr(),
                                                    new_node_value));

        node_ptr->setItem(new_node_value);
        return node_ptr;
    }
    // end if
} // end removeNode
```

Node is leaf

Node has 1 child

Node has 2 children

Will find leftmost leaf in right subtree, save value in new_node_value and delete

Safe Programming:
reference parameter is local to the private calling function



Implement this at home!!!

```
T find(const T& item) const
{
    //try it at home!!!!
}
```

Traversals

Let's focus on the traversal for now, we will find out what Visitor does next

```
template<class T>
void BST<T>::preorderTraverse(Visitor<T>& visit) const
{
    preorder(visit, root_ptr_);
} // end preorderTraverse
```

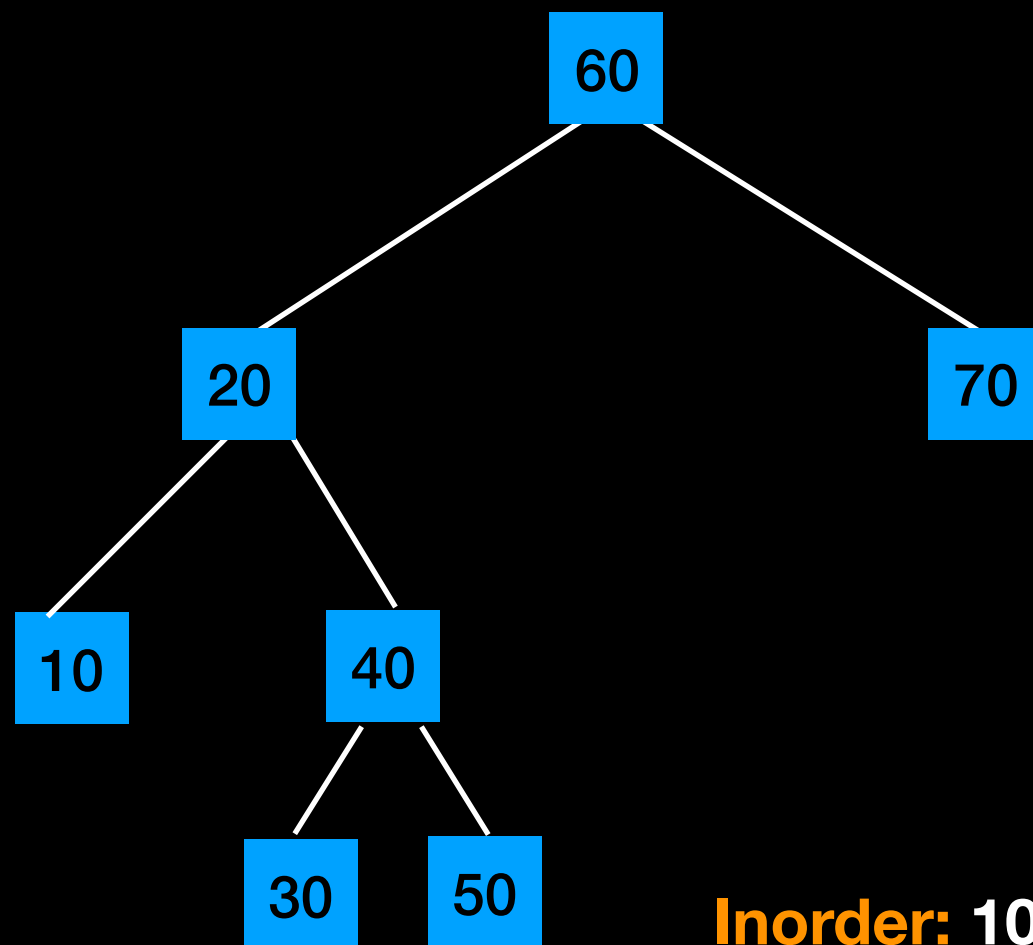
```
template<class T>
void BST<T>::inorderTraverse(Visitor<T>& visit) const
{
    inorder(visit, root_ptr_);
} // end inorderTraverse
```

```
template<class T>
void BST<T>::postorderTraverse(Visitor<T>& visit) const
{
    postorder(visit, root_ptr_);
} // end postorderTraverse
```

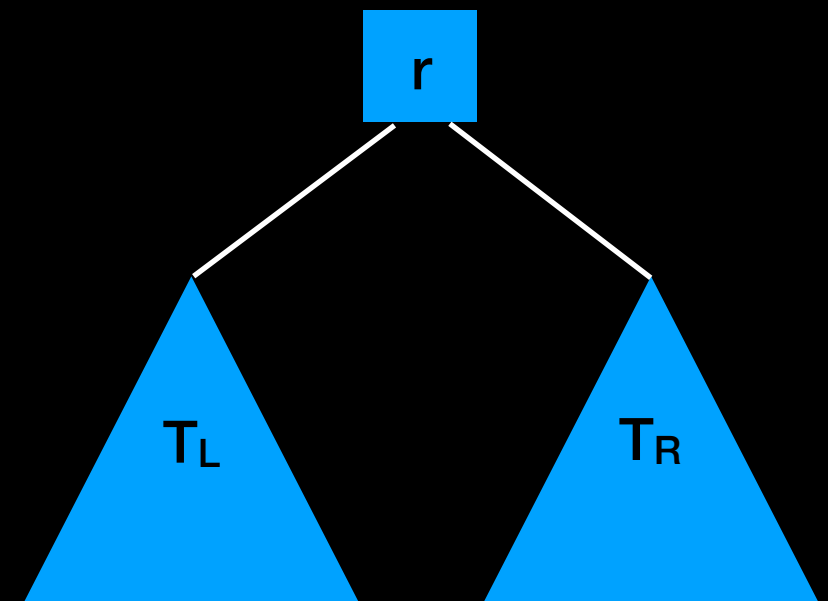
Visit (retrieve, print, modify ...) every node in the tree

Inorder Traversal:

```
if (T is not empty) //implicit base case
{
    traverse TL
    visit the root r
    traverse TR
}
```



Inorder: 10, 20, 30, 40, 50, 60, 70



inorderTraverse Helper Function

```
template<class T>
void BST<T>::inorder(Visitor<T>& visit,
    std::shared_ptr<BinaryNode<T>> tree_ptr) const
{
    if (tree_ptr != nullptr)
    {
        → inorder(visit, tree_ptr->getLeftChildPtr());
        T the_item = tree_ptr->getItem();
        visit(the_item);
        → inorder(visit, tree_ptr->getRightChildPtr());
    } // end if
} // end inorder
```

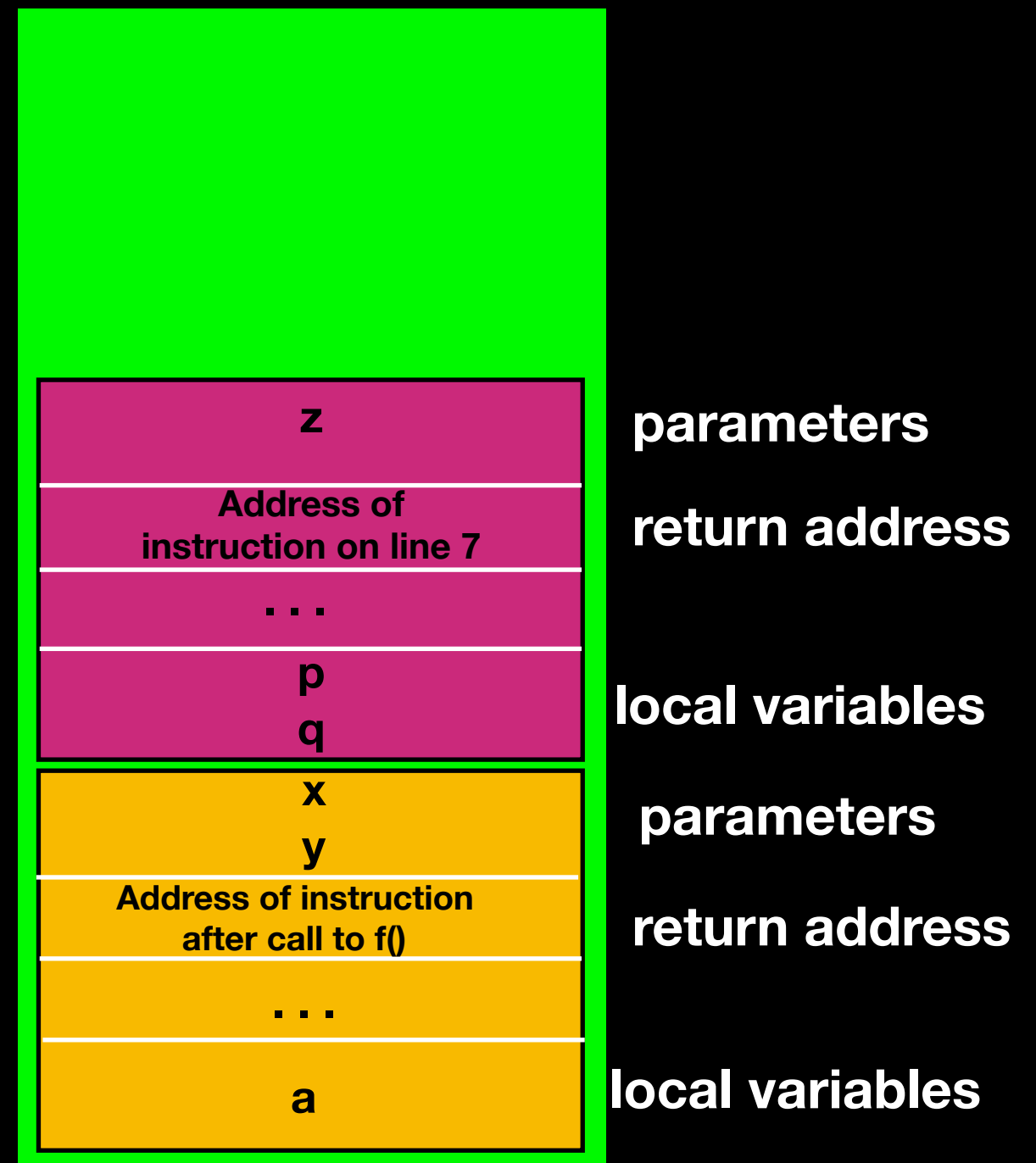
Recall: Program Stack

```
1 void f(int x, int y)
2 {
3     int a;
4     // stuff here
5     if(a<13)
6         a = g(a);
7     // stuff here
8 }
```

**Stack Frame
for g()**

```
9 int g(int z)
10 {
11     int p ,q;
12     // stuff here
13     return q;
14 }
```

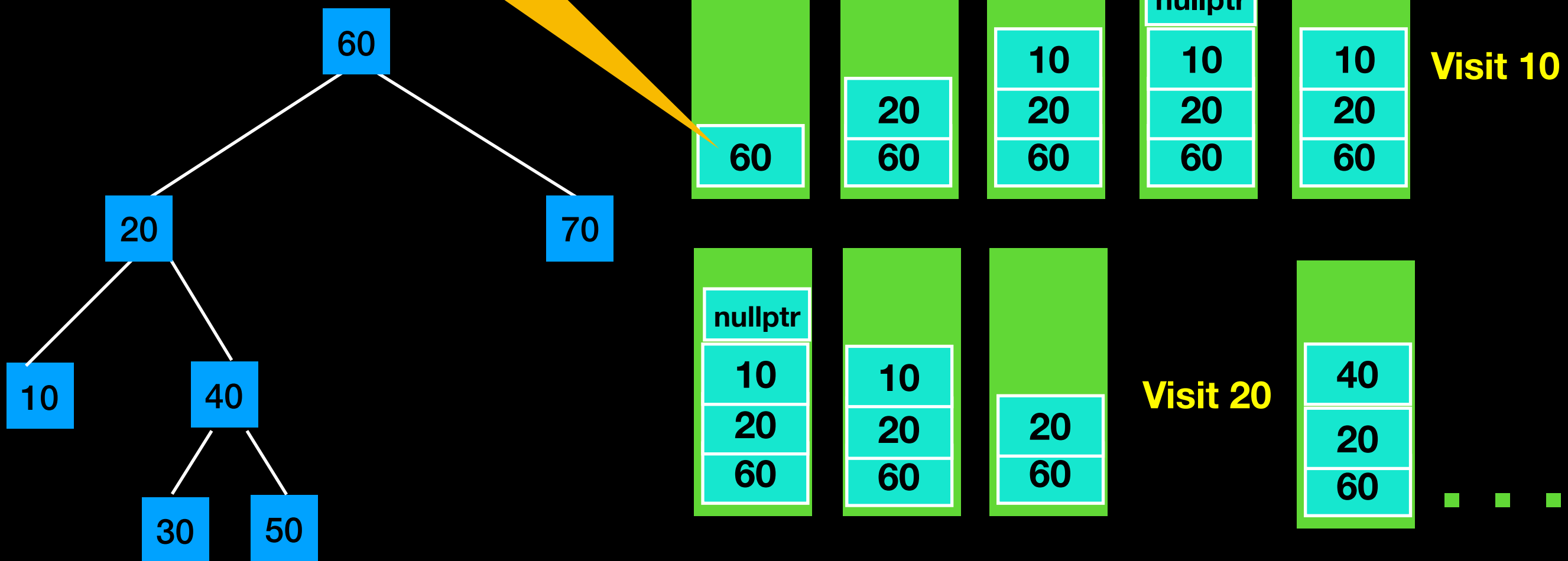
**Stack Frame
for f()**



Recursive Traversal

In recursive solution program stack keeps track of what node must be visited next

Means function call with
tree_ptr pointing to node with
data item 60



Recursive Traversal

With recursion:

- program stack **implicitly** finds node traversal must visit next
- If traversal backs up to node d from right subtree it backs up further to d 's parent as a **consequence of the recursive program execution**

Non-recursive Traversal

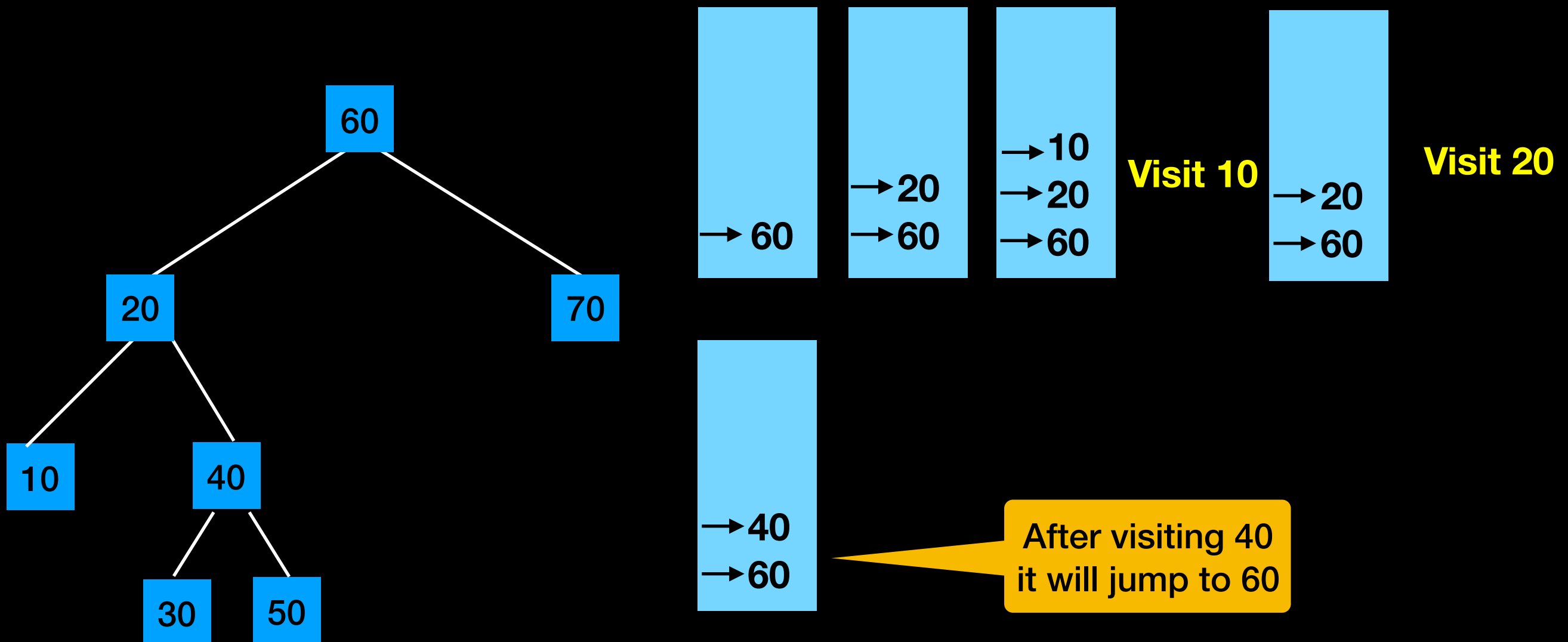
Optimize: Implement iterative approach that maintains an **explicit stack** to keep track of nodes that must be visited

Place pointer to node on stack **only** before traversing it's left subtree but **NOT** before traversing right subtree

This will also save some "steps" that were unnecessary but implicit in recursive implementation

Non-recursive Traversal

Iterative solution explicitly maintains a stack of pointers to nodes to keep track of what node must be visited next



Non-recursive Traversal

```
template<class T>
void BST<T>::inorder(Visitor<T>& visit) const
{
    std::stack<T> node_stack;
    std::shared_ptr<BinaryNode<T>> current_ptr = root_ptr_;
    bool done = false;

    while(!done)
    {
        if(current_ptr != nullptr)
        {
            node_stack.push(current_ptr);

            //traverse left subtree
            current_ptr = current_ptr->getLeftChildPtr();
        }
    }
}
```

Non-recursive Traversal cont.

```
//backtrack from empt subtree and visit the node at top of
//stack, but if stack is empty traversal is completed
else{
    done = node_stack.isEmpty();
    if(!done)
    {
        current_ptr = node_stack.top();
        visit(current_ptr->getItem());
        node_stack.pop();

        //traverse right subtree of node just visited
        current_ptr = current_ptr->getRightChildPtr();
    }
}
}
} // end inorder
```

Traversals

The last cool trick for
you this semester

Looking for
different
behavior

```
template<class T>
void BST<T>::preorderTraverse(Visitor<T>& visit) const
{
    preorder(visit, root_ptr_);
} // end preorderTraverse
```

```
template<class T>
void BST<T>::inorderTraverse(Visitor<T>& visit) const
{
    inorder(visit, root_ptr_);
} // end inorderTraverse
```

```
template<class T>
void BST<T>::postorderTraverse(Visitor<T>& visit) const
{
    postorder(visit, root_ptr_);
} // end postorderTraverse
```

Functors

Objects that by overloading `operator()` can be “called” like a function

```
#ifndef Visitor_hpp
#define Visitor_hpp
#include <string>
```

```
template<class T>
class Visitor
{
public:
```

```
    virtual void operator()(T&) = 0;
    virtual void operator()(T&, T&) = 0;
```

```
};
```

```
#endif /* Visitor_hpp */
```

POLYMORPHISM!

```
#ifndef StringPrinter_hpp
#define StringPrinter_hpp

#include "Visitor.hpp"
#include <iostream>
#include <string>

class StringPrinter: public Visitor<std::string>
{
public:

    void operator()(std::string&) override;
    void operator()(std::string&, std::string&) override;

};

#endif /* StringPrinter_hpp */
```

```
#include "StringPrinter.hpp"
```

```
void StringPrinter::operator()(std::string& x)
{
    std::cout << x << std::endl;
}
```

```
void StringPrinter::operator()(std::string& a, std::string& b)
{
    std::cout << a << b << std::endl;
}
```



```
#ifndef Inverter_hpp
#define Inverter_hpp

#include "Visitor.hpp"
#include <iostream>
#include <string>
#include <algorithm>

class Inverter: public Visitor<std::string>
{
public:

    void operator()(std::string&) override;
    void operator()(std::string&, std::string&) override;

};

#endif /* Inverter_hpp */
```

```
#include "Inverter.hpp"
```

```
void Inverter::operator()(std::string& x)
{
    std::reverse(x.begin(), x.end());
    std::cout << x << std::endl;
}
```

```
void Inverter::operator()(std::string& a, std::string& b)
{
    a.swap(b);
    std::cout << a << b << std::endl;
}
```

Traversal with Functor parameter

```
template<class T>
void BST<T>::inorder(Visitor<T>& visit,
    std::shared_ptr<BinaryNode<T>> tree_ptr) const
{
    if (tree_ptr != nullptr)
    {
        inorder(visit, tree_ptr->getLeftChildPtr());
        T the_item = tree_ptr->getItem();
        visit(the_item);
        inorder(visit, tree_ptr->getRightChildPtr());
    } // end if
} // end inorder
```

```

int main() {

    std::string a_string = "a string";
    std::string anoter_string = "o string";

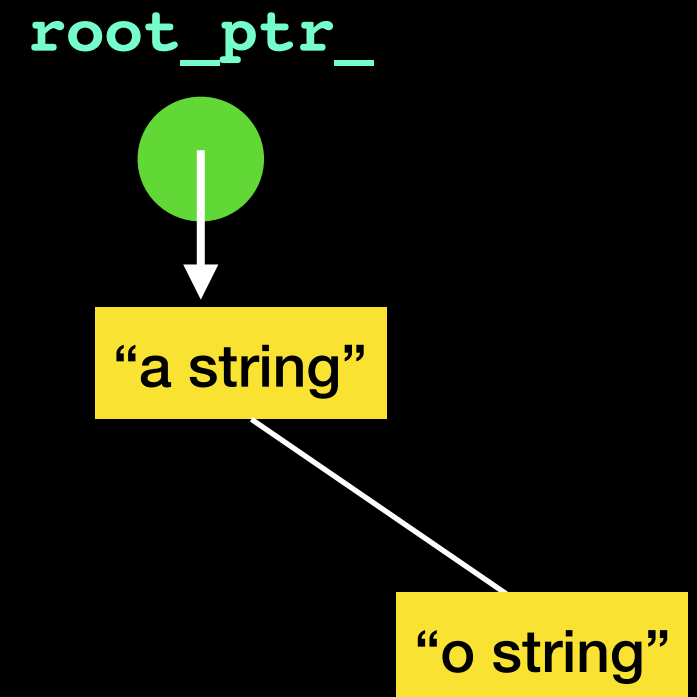
    BST<std::string> a_tree(a_string);
    a_tree.add(anoter_string);

    StringPrinter p;
    Inverter i;

    a_tree.inorderTraverse(p);
    std::cout << std::endl;
    a_tree.inorderTraverse(i);

    return 0;
}

```



```

a string
o string

gnirts a
gnirts o
Program ended with exit code: 0

```

```
int main() {
```

```
    std::string a_string = "a string";  
    std::string anoter_string = "o string";
```

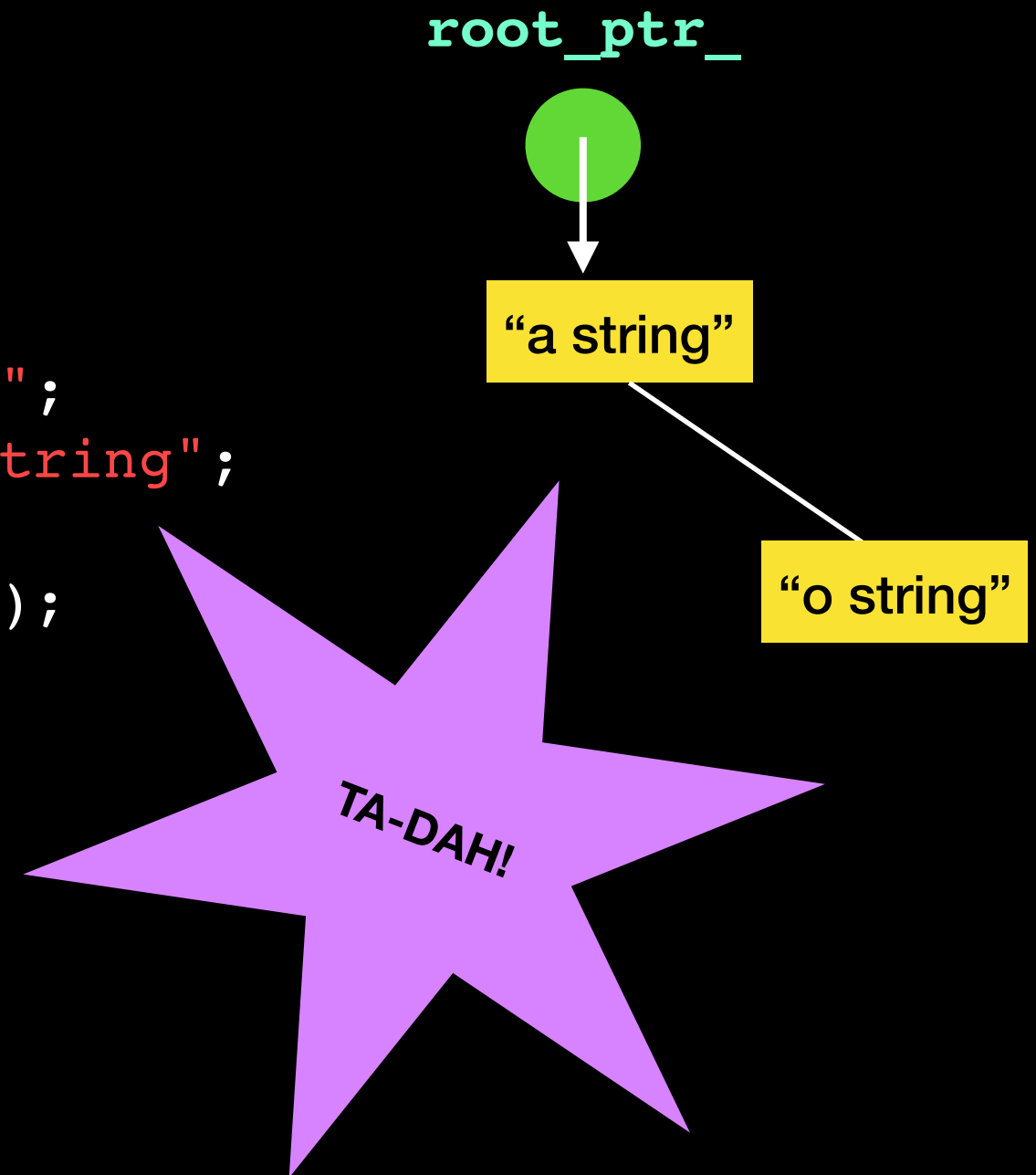
```
    BST<std::string> a_tree(a_string);  
    a_tree.add(anoter_string);
```

```
    Printer p;  
    Inverter i;
```

```
    a_tree.inorderTraverse(p);  
    std::cout << std::endl;  
    a_tree.inorderTraverse(i);
```

```
    return 0;
```

```
}
```



```
a string  
o string  
  
gnirts a  
gnirts o  
Program ended with exit code: 0
```