

MAXIMAL MONOTONICITY AND CYCLIC INVOLUTIVITY OF MULTI-CONJUGATE CONVEX FUNCTIONS

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ABSTRACT. A cornerstone in convex analysis is the crucial relationship between functions and their convex conjugate via the Fenchel-Young inequality. In this dual variable setting, the maximal monotonicity of the contact set $\{(x, y) \mid f(x) + f^*(y) = \langle x, y \rangle\}$ is due to the involution $f^{**} = f$ holding for convex lower-semicontinuous functions defined on any Hilbert space.

We investigate the validity of the cyclic version of involution and maximal monotonicity for multiple (more than two) convex functions. As a result, we show that when the underlying space is the real line, cyclical involutivity and maximal monotonicity induced by multi-conjugate convex functions continue to hold as for the dual variable case. On the other hand, when the underlying space is multidimensional, we show that the corresponding properties do not hold in general unless a further regularity assumption is imposed. We provide detailed examples that illustrate the significant differences between dual- and multi-conjugate convex functions, as well as between uni- and multi-dimensional underlying spaces.

Keywords: multivariate convex analysis, c -monotonicity, c -convex conjugacy, maximal monotonicity, cyclical involutivity, multi-marginal optimal transport.
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Notations and Assumptions.

- \mathcal{H} represents a real Hilbert space equipped with an inner product $\langle \cdot, \cdot \rangle$ on which all functions in the paper are defined. $|x| = \sqrt{\langle x, x \rangle}$ denotes the norm.
- $\langle x, y \rangle$ represents the dot product if $\mathcal{H} = \mathbb{R}^n$, and is also denoted by $x \cdot y$.

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- Unless specified otherwise, all functions have their values in $\mathbb{R} \cup \{+\infty\}$, i.e., functions do not assume the value $-\infty$ (only exception is in Lemma 2.1). And all functions are assumed to be (or verified to be) proper, that is, $f \not\equiv +\infty$ but there exists $x \in \mathcal{H}$ such that $f(x) \in \mathbb{R}$, unless it is stated as $f \equiv +\infty$.
- $\mathcal{A}(\mathcal{H})$ denotes the set of proper, lower-semicontinuous and convex functions defined on \mathcal{H} .
- For $N \in \mathbb{N}$ and $\Gamma \subseteq \mathcal{H}^N$, $S(\Gamma) := \{ \sum_{i=1}^N x_i \in \mathcal{H} \mid (x_1, x_2, \dots, x_N) \in \Gamma \}$.
- For $N \in \mathbb{N}$, $\Delta = \Delta_{\mathcal{H}^N} := \{(x, \dots, x) \in \mathcal{H}^N \mid x \in \mathcal{H}\}$ denotes the diagonal subspace of \mathcal{H}^N .
- $\mathbf{x} = (x_1, \dots, x_N)$ denotes an arbitrary element in the product space \mathcal{H}^N .
- $c = c_N : \mathcal{H}^N \rightarrow \mathbb{R}$ denotes the “cost function”; $c(\mathbf{x}) := \sum_{1 \leq i < j \leq N} \langle x_i, x_j \rangle$.
- For proper functions $\{f_i\}_{i=1, \dots, N}$ satisfying $\sum_{i=1}^N f_i(x_i) \geq c(\mathbf{x})$ for all $\mathbf{x} \in \mathcal{H}^N$, we let $\Gamma = \Gamma_{\{f_i\}_{i=1}^N} := \{\mathbf{x} \in \mathcal{H}^N \mid \sum_{i=1}^N f_i(x_i) = c(\mathbf{x})\}$.
- For proper functions f_1, \dots, f_N on \mathcal{H} , $(\bigoplus_{i=1}^N f_i)(\mathbf{x}) := \sum_{i=1}^N f_i(x_i)$.
- \square denotes the infimal convolution; $(f \square g)(x) := \inf_{y \in \mathcal{H}} (f(y) + g(x - y))$.
- q denotes the quadratic function; $q(x) := \frac{1}{2}|x|^2$.
- $e_f := f \square q$ denotes the Moreau envelope of f .
- For $f \in \mathcal{A}(\mathcal{H})$, Prox_f denotes the proximal mapping ([8, Definition 12.23]).
- $\text{Id} : \mathcal{H} \rightarrow \mathcal{H}$ denotes the identity mapping; $\text{Id}(x) = x$.
- For $A \subseteq \mathcal{H}$, $\text{int}A$ denotes the interior of A .
- For a function f , $\text{dom } f := \{x \in \mathcal{H} \mid f(x) \in \mathbb{R}\}$ denotes the domain of f .
- For $\lambda > 0$, a function f is called λ -strongly convex if $f - \lambda q$ is convex.
- For $\Gamma \subseteq \mathcal{H}^N$ and $i_0 \in \{1, \dots, N\}$, let $\Gamma_{i_0} : \mathcal{H} \rightarrow 2^{\mathcal{H}}$ denote the set-valued mapping; $\Gamma_{i_0}(x_{i_0}) := \{ \sum_{i \neq i_0} x_i \mid (x_1, \dots, x_{i_0}, \dots, x_N) \in \Gamma \}$.
- [34] $f \in \mathcal{A}(\mathcal{H})$ is called essentially smooth if it satisfies the following three conditions for $C = \text{int}(\text{dom } f)$:
 - (a) C is not empty;
 - (b) f is differentiable throughout C ;
 - (c) $\lim_{i \rightarrow \infty} |\nabla f(x_i)| = +\infty$ whenever x_1, x_2, \dots is a sequence in C converging to a boundary point x of C .

1. INTRODUCTION AND OUR CONTRIBUTION

Over the last few decades, the theory and applications of duality in convex analysis and monotone operator theory have advanced significantly ([8], [36]),

the study of dual variables $x, y \in \mathcal{H}$, a function f , and its convex conjugate

$$(1.1) \quad f^*(y) := \sup_{x \in \mathcal{H}} \langle x, y \rangle - f(x)$$

which are linked by the Fenchel-Young inequality (see [8, Proposition 13.15])

$$(1.2) \quad f(x) + f^*(y) \geq \langle x, y \rangle, \quad x, y \in \mathcal{H}.$$

We refer to [9], [10], [2], [3], [4], [11] for recent treatment of duality in optimization and convex analysis. Studies showed that if f, g are convex conjugate to each other, i.e., if $f^* = g$ and $g^* = f$, then the following contact set

$$\begin{aligned} \Gamma &= \{(x, y) \in \mathcal{H}^2 \mid f(x) + g(y) = \langle x, y \rangle\} \\ &= \{(x, y) \in \mathcal{H}^2 \mid y \in \partial f(x)\} \\ &= \{(x, y) \in \mathcal{H}^2 \mid x \in \partial g(y)\} \end{aligned}$$

is *maximally monotone* (Rockafellar [35]), which property turns out to be, by Minty's theorem (see [8, Theorem 21.1]), equivalent to

$$(1.3) \quad S(\Gamma) = \mathcal{H}.$$

Note that if $\Gamma \subseteq \mathcal{H} \times \mathcal{H}$ is *monotone*, i.e.,

$$\langle x - y, u - v \rangle \geq 0 \quad \text{for any } (x, u) \in \Gamma, (y, v) \in \Gamma,$$

then $\Gamma \cap (\Delta^\perp + p)$ is either empty or a singleton for every $p \in \Delta$ (see [5, Corollary 2.4]), where Δ is the diagonal subspace of $\mathcal{H} \times \mathcal{H}$. Thus (1.3) is a maximality assertion, saying there is no “hole” in the monotone set Γ . These results established by Minty, Rockafellar and many others now form important foundation for modern theory of nonlinear monotone operators [15], [37], [38].

Recently, S. Bartz, H.H. Bauschke, H.M. Phan, and X. Wang [5] provided a significant extension of the convex analysis theory into the multivariate, or multi-marginal (i.e., variables more than two), situation, stating that “a comprehensive multi-marginal monotonicity and convex analysis theory is still missing.” We denote $\mathbf{x} = (x_1, \dots, x_N) \in \mathcal{H}^N$ and define $c_N : \mathcal{H}^N \rightarrow \mathbb{R}$ by

$$(1.4) \quad c(\mathbf{x}) = c_N(\mathbf{x}) := \sum_{1 \leq i < j \leq N} \langle x_i, x_j \rangle.$$

We may simply denote by c . An analogous statement of the bi-conjugacy — $f^* = g$ and $g^* = f$ — in the multivariate setting can now be given as follows.

Definition 1.1 (c -conjugate tuple [5]). *For each $1 \leq i \leq N$, let $f_i : \mathcal{H} \rightarrow \mathbb{R} \cup \{+\infty\}$ be a proper function, i.e., not entirely $+\infty$. We say that (f_1, \dots, f_N) is a c -conjugate tuple if for each $1 \leq i_0 \leq N$ and $x_{i_0} \in \mathcal{H}$, we have*

$$f_{i_0}(x_{i_0}) = \left(\bigoplus_{i \neq i_0} f_i \right)^c(x_{i_0}) := \sup_{i \neq i_0, x_i \in \mathcal{H}} c(x_1, \dots, x_{i_0}, \dots, x_N) - \sum_{i \neq i_0} f_i(x_i).$$

Now we focus on the following theorem, which is a culmination of the results in [5] (see Theorems 2.5 and 4.3 in [5]) regarding maximality of the monotone operator induced by several convex functions.

Theorem 1.2 ([5]). *For $1 \leq i \leq N$, suppose $f_i \in \mathcal{A}(\mathcal{H})$ satisfy*

$$\sum_{i=1}^N f_i(x_i) \geq c(\mathbf{x}) \text{ for all } \mathbf{x} \in \mathcal{H}^N.$$

Let $\Gamma = \Gamma_{\{f_i\}_{i=1}^N}$. The following assertions are equivalent:

- (i) *There exist $1 \leq i_0 \leq N$ such that Γ_{i_0} is maximally monotone;*
- (ii) *There exist $1 \leq i_0 \leq N$ such that $\Gamma_{i_0} = \partial f_{i_0}$;*
- (iii) *$\Gamma_i = \partial f_i$ for each $1 \leq i \leq N$;*
- (iv) *$\text{Prox}_{f_1} + \dots + \text{Prox}_{f_N} = \text{Id}$;*
- (v) *$e_{f_1^*} + \dots + e_{f_N^*} = q$;*
- (vi) *$\Gamma + \Delta^\perp = \mathcal{H}^N$;*
- (vii) *$S(\Gamma) = \mathcal{H}$.*

In this case, (f_1, \dots, f_N) is a c -conjugate tuple, and Γ determines (f_1, \dots, f_N) uniquely up to an additive constant tuple (ρ_1, \dots, ρ_N) such that $\sum_{i=1}^N \rho_i = 0$.

Here (iv) represents the partition of the identity into a sum of firmly nonexpansive mappings, and (v) represents Moreau's decomposition of the quadratic function into envelopes in the multivariate settings. In addition, [5] shows that Γ is maximally c -monotone (and, consequently, maximally c -cyclically monotone) if any of the assertions (i)–(vii) hold.

It is natural to ask whether the cyclical conjugacy of (f_1, \dots, f_N) conversely yields the assertions as well. As a result, [5] addresses the following question:

Question 1. *Given any proper c -conjugate tuple $\{f_i\}_{i=1}^N$, is $\Gamma_{\{f_i\}_{i=1}^N}$ maximally monotone in the sense of (1.3) (so that the statements (i)–(vii) hold)?*

According to [5], this question is still open to the best of their knowledge. The question appears to be quite interesting, particularly because it is well known to be affirmative when $N = 2$ by the work of Rockafellar and Minty.

In this regard, the following partial result is given in [5, Theorem 4.6].

Theorem 1.3 ([5]). *Let $N = 3$, $n \in \mathbb{N}$ and $g, h \in \mathcal{A}(\mathbb{R}^n)$. Suppose that $f = (g \oplus h)^c$ and that f is essentially smooth. Let $\Gamma = \Gamma_{\{f, g, h\}}$. Then assertions (i)–(vii) in Theorem 1.2 hold (and therefore Γ is maximally c -monotone).*

While Theorem 1.3 gives the first and affirmative answer to Question 1, it appears to be restricted in the following ways: The value of N must be 3, and one of the c -conjugate convex functions must be smooth. In this regard, our first result addresses the problem of relaxing N to be arbitrary as follows.

Theorem 1.4. *Let $n, N \in \mathbb{N}$, $N \geq 2$ and $f_1, \dots, f_N \in \mathcal{A}(\mathbb{R}^n)$. Suppose that $f_1 = (\bigoplus_{i=2}^N f_i)^c$ and that f_1 is essentially smooth. Let $\Gamma = \Gamma_{\{f_1, \dots, f_N\}}$. Then assertions (i)–(vii) in Theorem 1.2 hold true.*

However, this result is not yet entirely satisfactory because the smoothness assumption must be imposed on one of the c -conjugate functions, which is not necessary when $N = 2$. Can the theorem be proved in full generality, i.e., for any c -conjugate convex functions that only belong in $\mathcal{A}(\mathbb{R}^n)$?

Our next result shows that it is indeed affirmative if $n = 1$, i.e., if $\mathcal{H} = \mathbb{R}$.

Theorem 1.5. *Let $N \geq 2$ and assume that $f_1, \dots, f_N \in \mathcal{A}(\mathbb{R})$ are c -conjugate. Let $\Gamma = \Gamma_{\{f_1, \dots, f_N\}}$. Then assertions (i)–(vii) in Theorem 1.2 hold true.*

While working on these findings, the author realizes that Question 1 is in fact closely related to the following notion of *cyclical involutivity*, which, to the best of the author's knowledge, has not been introduced or investigated. As a result, we are led to provide the following definition.

Definition 1.6 (Cyclical involutivity). *Let $N \in \mathbb{N}$, $N \geq 2$, $c = c_N$. We shall say that a subset of functions $\Omega \subseteq \mathcal{A}(\mathcal{H})$ is N -cyclically involutive if for any*

$f_1, f_2, \dots, f_N \in \Omega$ that satisfies

$$(1.5) \quad f_i(x_i) = \left(\bigoplus_{j \neq i} f_j \right)^c(x_i) \text{ for every } i = 2, \dots, N,$$

then (f_1, \dots, f_N) is a c -conjugate tuple, that is, f_1 also satisfies

$$(1.6) \quad f_1(x_1) = \left(\bigoplus_{j \neq 1} f_j \right)^c(x_1).$$

Ω is called *cyclically involutive* if it is N -cyclically involutive for every $N \geq 2$.

Every $\mathcal{A}(\mathcal{H})$ is 2-cyclically involutive, which is equivalent to the following cornerstone statement by Fenchel and Moreau (see [8, Theorem 13.37])

$$(1.7) \quad f^{**} = f \text{ for every } f \in \mathcal{A}(\mathcal{H}).$$

It is natural to wonder whether $\mathcal{A}(\mathcal{H})$ is N -cyclically involutive for each $N \geq 3$. Our next result shows that it is also affirmative if $\mathcal{H} = \mathbb{R}$.

Theorem 1.7. *$\mathcal{A}(\mathbb{R})$ is cyclically involutive.*

See the proof of Theorem 3.7, in which we prove Theorems 1.5 and 1.7 simultaneously using an induction on N , demonstrating the close relationship between cyclical involutivity and maximal monotonicity.

Now for $\mathcal{H} = \mathbb{R}^n$, we readily observe Theorems 1.2 and 1.4 combine to imply:

Corollary 1.8. *The class of essentially smooth functions in $\mathcal{A}(\mathbb{R}^n)$ is cyclically involutive.*

Is $\mathcal{A}(\mathbb{R}^n)$ itself cyclically involutive as well? Somewhat surprisingly, it turns out not to be true in general, as the following counterexample indicates.

Proposition 1.9. *There exists $f, g, h \in \mathcal{A}(\mathbb{R}^2)$ such that $f = (g \oplus h)^c$, $g = (h \oplus f)^c$, but $h \neq (f \oplus g)^c$.*

See Example 5.1 for more details. This makes Question 1 obscure. Nevertheless, we can still hope that, if f, g, h are assumed to be c -conjugate, $\Gamma_{\{f, g, h\}}$ might satisfy (1.3). This sounds plausible in view of Theorem 1.4 where only one of the c -conjugate functions needs to be essentially smooth, which appears to be a fairly weak, and, seemingly redundant assumption when compared to the case $N = 2$. This hope, however, is dashed by the following counterexample.

Proposition 1.10. *Let $\lambda > 0$, and $u = (1, 0) \in \mathbb{R}^2$, $v = (\frac{1}{2}, \frac{\sqrt{3}}{2}) \in \mathbb{R}^2$. There exists a c -conjugate triple $f, g, h \in \mathcal{A}(\mathbb{R}^2)$ for which $\Gamma = \Gamma_{\{f, g, h\}}$ satisfies*

$$S(\Gamma) = \mathbb{R}^2 \setminus \text{int } \mathbf{H}_\lambda$$

where \mathbf{H}_λ is the convex hull of its six vertices $\pm 2\lambda u$, $\pm 2\lambda v$, and $\pm 2\lambda(v - u)$.

As a result, the regularity assumption in Theorem 1.4 is not redundant. More detailed statement and related examples can be found in Section 4.

In summary, we provide a fairly complete answer to Question 1 by demonstrating the significant difference between the cases $N = 2$ and $N \geq 3$, and also, between $\mathcal{H} = \mathbb{R}$ and $\mathcal{H} = \mathbb{R}^n$. While Question 1 holds true for $N = 2$ and $\mathcal{A}(\mathcal{H})$ is 2-cyclically involutive shown by Fenchel, Moreau, Minty and Rockafellar, we show both statements fail in general when $N \geq 3$. Nevertheless, Theorems 1.5, 1.7 show that the results are still affirmative in full generality for any $N \geq 3$ if $\mathcal{H} = \mathbb{R}$. Furthermore, Theorems 1.4, 1.8 show that the results are also affirmative within the class of essentially smooth convex functions when $\mathcal{H} = \mathbb{R}^n$. As a result, we believe that identifying other significant subsets of $\mathcal{A}(\mathcal{H})$ that are cyclically involutive and understanding their relationship with maximal monotonicity is an interesting question for future research.

1.1. Connection with theory of multi-marginal optimal transport.

Let $(X_1, \mu_1), \dots, (X_N, \mu_N)$ be Borel probability spaces, and $X := X_1 \times \dots \times X_N$. Denote $\Pi(X)$ by the set of all Borel probability measures π on X whose marginals are the μ_i 's [39, 41]. Given a cost function $c : X \rightarrow \mathbb{R}$, the optimal transport problem refers to the following optimization problem:

$$(1.8) \quad P_c := \min_{\pi \in \Pi(X)} \int_X c(x) d\pi(x).$$

To distinguish it from the two-marginal case, the problem is commonly referred to as multi-marginal optimal transport problem when $N \geq 3$. In this problem, the optimal transport cost P_c , as well as the geometry and structure of optimal transport plans – the solutions to (1.8) – are sought.

Because (1.8) is an infinite-dimensional linear programming problem, it has a dual problem whose formulation turns out to have the following form:

$$(1.9) \quad D_c := \max_{\substack{f_i \in L_1(\mu_i), \\ \sum_{1 \leq i \leq N} f_i(x_i) \leq c(\mathbf{x})}} \sum_{1 \leq i \leq N} \int_{X_i} f_i(x_i) d\mu_i(x_i).$$

Kellerer's [20] generalization of the Kantorovich duality states that, under mild assumptions on the marginals μ_1, \dots, μ_N and cost function c , it holds

$$(1.10) \quad P_c = D_c.$$

This has the important implication that every optimal transport π solving (1.8) is concentrated on the contact set

$$(1.11) \quad \Gamma = \left\{ \mathbf{x} \in X \mid \sum_{1 \leq i \leq N} f_i(x_i) = c(\mathbf{x}) \right\}$$

where (f_1, \dots, f_N) is a solution to the dual problem (1.9). This provides a crucial information for investigating the geometry of optimal transport plans.

The interaction between the optimal transport and its dual problems is what makes the theory surprisingly powerful for many applications in fields such as analysis, geometry, PDEs, probability, statistics, economics, data sciences, and many researchers have helped to advance the field [17, 19, 27, 32, 33, 39, 41]. Regarding the geometry of optimal transport for $N = 2$, arguably one of the most well-known and widely applied result is the Brenier's theorem [12]: given marginals $\mu_1, \mu_2 \in \mathcal{P}_2(\mathbb{R}^n)$ and the cost function $c(x_1, x_2) = |x_1 - x_2|^2$, there exists a convex function φ such that for any solution π to (1.8), it holds

$$(1.12) \quad y \in \partial\varphi(x) \text{ } \pi\text{-}a.e. (x, y), \text{ and moreover, } y = \nabla\varphi(x) \text{ if } \mu_1 \text{ has density.}$$

Because the geometry of the subdifferential $\partial\varphi$ is well understood by studies in convex analysis, Brenier's theorem could yield important further results. Likewise, a better understanding of multi-conjugate convex analysis should also have a significant impact on the theory of multi-marginal optimal transport, their geometry, and applications. This is one of the motivations of this paper.

Recent advances in the theory of multi-marginal optimal transport and its geometrical structures have been rapid and fruitful, yielding numerous new

research directions and open problems [1, 5–7, 13, 14, 16–18, 21–23, 25, 26, 28–31]. In light of two-marginal optimal transport theory, Brenier’s theorem and their consequences, it appears clear that understanding the geometry of the contact set (1.11) is crucial, much of which falls within the scope of the multi-conjugate convex analysis. In this regard, the author hopes that this paper will contribute to a better understanding of the geometry of various multi-marginal optimal transport problems.

1.2. Organization of the paper. This paper is organized as follows. In Section 2, we prove Theorem 1.4. In Section 3, we prove Theorems 1.5 and 1.7. In Section 4, we explain Proposition 1.10 and provide additional examples to demonstrate the difference between $\mathcal{H} = \mathbb{R}$ and $\mathcal{H} = \mathbb{R}^n$. Finally, in Section 5, we revisit cyclical involutivity and maximal monotonicity in the $N = 3$ case in the context of duality, as well as provide details for Proposition 1.9.

2. EXTENSION OF THEOREM 1.3: PROOF OF THEOREM 1.4

First, as in [5], we need the following fact.
 [40, Corollary 2.3]. *Let $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ be proper and lower-semicontinuous. If f^* is essentially smooth, then f is convex.*

We also need the following lemma whose proof is given in [8, Proposition 14.19] for the case $N = 1$. Extension for arbitrary $N \in \mathbb{N}$ appears to be useful.

Lemma 2.1. *For $g, f_1, f_2, \dots, f_N \in \mathcal{A}(\mathcal{H})$, we have the following identity*

(2.1)

$$\sup_{\substack{x_i \in \text{dom } f_i \\ i=1, \dots, N}} \left(g(x + x_1 + \dots + x_N) - \sum_{i=1}^N f_i(x_i) \right) = \left(g^* - \sum_{i=1}^N f_i^* \right)^* (x) \text{ for all } x \in \mathcal{H},$$

where $g^* - \sum_{i=1}^N f_i^* : \mathcal{H} \rightarrow [-\infty, +\infty]$ is defined as (note $-\infty$ can be assumed)

$$\left(g^* - \sum_{i=1}^N f_i^* \right)(y) := \begin{cases} (g^* - \sum_{i=1}^N f_i^*)(y) & \text{if } y \in \text{dom } g^*, \\ +\infty & \text{if } y \notin \text{dom } g^*. \end{cases}$$

Proof. Recalling $S(\mathbf{x}) := x_1 + \cdots + x_N$, we compute as follows:

$$\begin{aligned}
\left(g^* - \sum_{i=1}^N f_i^*\right)^*(x) &= \sup_{y \in \text{dom } g^*} x \cdot y - \left(g^* - \sum_{i=1}^N f_i^*\right)(y) \\
&= \sup_{y \in \text{dom } g^*} x \cdot y - g^*(y) + \sum_{i=1}^N \sup_{x_i \in \text{dom } f_i} y \cdot x_i - f_i(x_i) \\
&= \sup_{y \in \text{dom } g^*} x \cdot y - g^*(y) + \sup_{\substack{x_i \in \text{dom } f_i \\ i=1, \dots, N}} y \cdot S(\mathbf{x}) - \sum_{i=1}^N f_i(x_i) \\
&= \sup_{\substack{x_i \in \text{dom } f_i \\ i=1, \dots, N}} \sup_{y \in \text{dom } g^*} y \cdot (x + S(\mathbf{x})) - g^*(y) - \sum_{i=1}^N f_i(x_i) \\
&= \sup_{\substack{x_i \in \text{dom } f_i \\ i=1, \dots, N}} g(x + S(\mathbf{x})) - \sum_{i=1}^N f_i(x_i).
\end{aligned}$$

This proves the lemma. □

We can now prove Theorem 1.4 using Lemma 2.1 and the above fact, by closely following the proof of Theorem 1.3 given in [5].

Proof of Theorem 1.4. Recalling $f_1 = (\oplus_{i=2}^N f_i)^c$, we compute

$$\begin{aligned}
(f_1 + q)(x_1) &= \sup_{x_2, \dots, x_N \in \mathbb{R}^n} c(\mathbf{x}) + q(x_1) - \sum_{i=2}^N f_i(x_i) \\
&= \sup_{x_2, \dots, x_N} x_2 \cdot (x_1 + x_3 + \dots + x_N) - f_2(x_2) + \sum_{\substack{1 \leq j < k \leq N \\ j \neq 2, k \neq 2}} x_j \cdot x_k + q(x_1) - \sum_{i=3}^N f_i(x_i) \\
&= \sup_{x_3, \dots, x_N} f_2^*(x_1 + x_3 + \dots + x_N) + q(x_1 + x_3 + \dots + x_N) - \sum_{i=3}^N (f_i + q)(x_i) \\
&= \left((f_2^* + q)^* - \sum_{i=3}^N (f_i + q)^* \right)^*(x_1) \\
&= \left(e_{f_2} - \sum_{i=3}^N e_{f_i^*} \right)^*(x_1) = \left(q - \sum_{i=2}^N e_{f_i^*} \right)^*(x_1)
\end{aligned}$$

where the last two equalities are due to Lemma 2.1 and Moreau's decomposition ((v)) for $N = 2$. Now since $f_1 + q$ is essentially smooth, [40, Corollary 2.3] implies $q - \sum_{i=2}^N e_{f_i^*}$ is convex. And $e_{f_k^*}$, which is a Moreau envelope of a function in $\mathcal{A}(\mathbb{R}^n)$, is continuous in \mathbb{R}^n . Consequently,

$$e_{f_1^*} = (f_1 + q)^* = (q - \sum_{i=2}^N e_{f_i^*})^{**} = q - \sum_{i=2}^N e_{f_i^*},$$

that is, $\sum_{i=1}^N e_{f_i^*} = q$, which is the Moreau decomposition ((v)). \square

3. ONE-DIMENSIONAL DOMAIN: PROOF OF THEOREMS 1.5 AND 1.7

We begin with a lemma about strong convexity and how it is inherited.

Lemma 3.1. *Let f, g, h be proper functions on a Hilbert space \mathcal{H} , satisfying*

$$f(x) = \sup_{y \in \text{dom } g} h(x + y) - g(y).$$

If h is lower-semicontinuous and λ -strongly convex, then so is f .

Proof. Let $k = h - \lambda q$, which belongs to $\mathcal{A}(\mathcal{H})$, thus $k = k^{**}$. We compute

$$\begin{aligned} f(x) &= \sup_{y \in \text{dom } g} h(x + y) - g(y) \\ &= \sup_{y \in \text{dom } g} \sup_{z \in \text{dom } k^*} \lambda q(x + y) + \langle x + y, z \rangle - k^*(z) - g(y) \\ &= \lambda q(x) + \sup_{z \in \text{dom } k^*} \left\{ \langle x, z \rangle - k^*(z) + \sup_{y \in \text{dom } g} \{ \langle y, \lambda x + z \rangle - (g - \lambda q)(y) \} \right\} \\ &= \lambda q(x) + \sup_{z \in \text{dom } k^*} \langle x, z \rangle - k^*(z) + (g - \lambda q)^*(\lambda x + z) \\ &=: \lambda q(x) + \xi(x). \end{aligned}$$

Observe ξ is convex lower-semicontinuous as a supremum of such functions. \square

Let Δ be the diagonal subspace of \mathcal{H}^N . The concept of a “directional convex envelope” is clearly relevant to the study of c -conjugate convex functions. We introduce the following definition as we are not aware of it appearing elsewhere.

Definition 3.2 (Δ -convex envelope). *Let $\mathbf{x} = (x_1, \dots, x_N) \in \mathcal{H}^N$, $S(\mathbf{x}) = \sum_{i=1}^N x_i$. Let $f : \mathcal{H}^N \rightarrow \mathbb{R} \cup \{+\infty\}$ be proper, satisfying $f(\mathbf{x}) \geq \langle S(\mathbf{x}), y \rangle + b$ for some $y \in \mathcal{H}$, $b \in \mathbb{R}$. Then g is called the Δ -convex envelope of f if g is the largest convex lower-semicontinuous function on \mathcal{H} satisfying $f(\mathbf{x}) \geq g(S(\mathbf{x}))$.*

Lemma 3.3. *Let f satisfy the condition in Definition 3.2. Then g is the Δ -convex envelope of f if and only if $g^*(y) = \sup_{\mathbf{x}} \langle S(\mathbf{x}), y \rangle - f(\mathbf{x})$.*

Proof. Let h be any element in $\mathcal{A}(\mathcal{H})$. The following equivalence

$$\begin{aligned} f(\mathbf{x}) &\geq h(S(\mathbf{x})) \quad \text{for every } \mathbf{x} \in \mathcal{H}^N \\ \iff f(\mathbf{x}) &\geq \langle S(\mathbf{x}), y \rangle - h^*(y) \quad \text{for every } \mathbf{x} \in \mathcal{H}^N, y \in \mathcal{H} \\ \iff h^*(y) &\geq \sup_{\mathbf{x}} \langle S(\mathbf{x}), y \rangle - f(\mathbf{x}) \quad \text{for every } y \in \mathcal{H} \end{aligned}$$

yields the lemma, since maximality of g corresponds to minimality of g^* . \square

Definition 3.4. *For proper functions $f, g, h : \mathcal{H} \rightarrow \mathbb{R} \cup \{+\infty\}$, we say that f and g are h -conjugate if the following holds:*

$$(3.1) \quad f(x) = \sup_{y \in \text{dom } g} h(x + y) - g(y), \quad g(y) = \sup_{x \in \text{dom } f} h(x + y) - f(x).$$

Proposition 3.5. *Assume that $f, g, h \in \mathcal{A}(\mathbb{R})$ and that f, g are h -conjugate. Assume further that f and h are continuous, and that h is λ -strongly convex for some $\lambda > 0$. Then h is the Δ -convex envelope of $f \oplus g$.*

Proof. By Lemma 3.1, f and g are λ -strongly convex. In particular, $\bigcup_{x \in \mathbb{R}} \partial f(x) = \bigcup_{y \in \mathbb{R}} \partial g(y) = \mathbb{R}$. Firstly, we claim that the following set \mathcal{I} is dense in \mathbb{R} :

$$(3.2) \quad \mathcal{I} = \{s \in \mathbb{R} \mid s = x + y \text{ such that } \partial f(x) \cap \partial g(y) \neq \emptyset, \text{ and} \\ \text{either } f \text{ is differentiable at } x \text{ or } g \text{ is differentiable at } y\}.$$

Let us prove the claim later. Let H denote the Δ -convex envelope of $f \oplus g$. Then $H \geq h$ since $f(x) + g(y) \geq h(x + y)$ by (3.1). The proposition asserts $H = h$. To prove this, we claim that it is sufficient to prove the following tightness assertion: For any $x_0, y_0 \in \mathbb{R}$ such that $\partial f(x_0) \cap \partial g(y_0) \neq \emptyset$ and either f is differentiable at x_0 or g is differentiable at y_0 , we have

$$(3.3) \quad f(x_0) + g(y_0) = h(x_0 + y_0).$$

The sufficiency is because (3.3) implies $H = h$ on \mathcal{I} , and thus for any $s \in \mathbb{R}$, by the first claim, there exists a sequence s_n in \mathcal{I} such that $\lim s_n = s$, and

$$H(s) \leq \liminf H(s_n) = \liminf h(s_n) = h(s)$$

as desired, thanks to the continuity of h .

Now to verify (3.3), by translation, we may assume without loss of generality that $x_0 = y_0 = 0$. Moreover we may assume that $0 \in \partial f(0) \cap \partial g(0)$. To see why this can be assumed, let $a \in \partial f(0) \cap \partial g(0)$. Consider $\tilde{f}(x) = f(x) - \langle a, x \rangle - f(0)$, $\tilde{g}(y) = g(y) - \langle a, y \rangle - g(0)$, and $\tilde{h}(z) = h(z) - \langle a, z \rangle - f(0) - g(0)$. Then f and g are h -conjugate if and only if \tilde{f} and \tilde{g} are \tilde{h} -conjugate. And since $\min \tilde{f} = \tilde{f}(0) = 0$ and $\min \tilde{g} = \tilde{g}(0) = 0$, (3.3) holds if and only if $\tilde{h}(0) = 0$. Our discussion so far indicates it is sufficient to prove the claim (3.3) under the assumption $x_0 = y_0 = 0$, f, g are h -conjugate, $f(0) = \min f = g(0) = \min g = 0$, and either f or g is differentiable at 0; and the goal is to prove $h(0) = 0$.

Now to derive a contradiction, suppose $h(0) < 0$, so that $m = \min h < 0$. Assume f is differentiable at 0 (the proof will be the same in the case g is differentiable at 0, by switching the role of f and g). Let $K = \{x \mid h(x) \leq m/2\}$. Since h is strongly convex, there exists $\delta > 0$ such that

$$(3.4) \quad x \in \mathbb{R} \setminus K \text{ and } z \in \partial h(x) \text{ implies } |z| \geq \delta.$$

By (3.1), given $\epsilon > 0$, there exists y_ϵ such that $-\epsilon < h(y_\epsilon) - g(y_\epsilon) \leq 0 = f(0)$. Now $f(x) \geq h(x + y_\epsilon) - g(y_\epsilon)$ for all x and $\nabla f(0) = 0$ imply that for all sufficiently small ϵ , we must have $y_\epsilon \in K$ by (3.4). However, we then have

$$-\epsilon < h(y_\epsilon) - g(y_\epsilon) \leq h(y_\epsilon) \leq m/2,$$

a contradiction for small ϵ , proving the tightness assertion.

It remains to prove that \mathcal{I} is dense in \mathbb{R} . For any $s \in \mathbb{R}$, recall that there exists $x, y \in \mathbb{R}$ such that $s \in \partial f(x) \cap \partial g(y)$. By translation and subtracting affine functions as before, we may assume $0 \in \partial f(0) \cap \partial g(0)$. Then notice the desired denseness will follow if we can show that for any $r > 0$, there exists $x, y \in \mathbb{R}$ such that $|x| < r$, $|y| < r$, $\partial f(x) \cap \partial g(y) \neq \emptyset$, and either f is differentiable at x or g is differentiable at y .

Now to prove the claim, assume that neither f nor g is differentiable at 0, since otherwise there is nothing to prove. $\partial f(0)$ is a compact interval, say $[a, b]$, since f is continuous. And $W := \partial g((-r, r))$ is an open interval since g is strongly convex, thus g^* is differentiable and $\partial g^* = (\partial g)^{-1}$ is continuous.

Suppose $b \in W$. Then for any $\epsilon > 0$, there exists $x \in [0, \epsilon)$ such that f is differentiable at x and $\nabla f(x) \in [b, b + \epsilon)$ since f is differentiable a.e.. Thus $\nabla f(x) \in W$ for small ϵ , and this implies $\nabla f(x) \in \partial g(y)$ for some $y \in (-r, r)$,

proving the claim. Likewise, the claim holds in the case $a \in W$. Finally, if $\{a, b\} \cap W = \emptyset$, then $W \subseteq (a, b)$, yielding that g is Lipschitz and differentiable a.e. in $(-r, r)$. Hence there exists $y \in (-r, r)$ such that $\nabla g(y) \in \partial f(0)$. This proves the desired denseness of \mathcal{I} in \mathbb{R} , hence the proposition. \square

Remark 3.6. *The above proof shows that Proposition 3.5 will continue to hold for functions f, g, h defined on an arbitrary Hilbert space \mathcal{H} if the corresponding set \mathcal{I} is dense in \mathcal{H} given the mutual conjugacy (3.1).*

Now we combine Theorems 1.5 and 1.7 into the following theorem.

Theorem 3.7. *Let $\mathcal{H} = \mathbb{R}$, and let $c : \mathbb{R}^N \rightarrow \mathbb{R}$ be given by (1.4). Suppose $f_i \in \mathcal{A}(\mathbb{R})$, $i = 1, \dots, N$, satisfy*

$$(3.5) \quad f_i(x_i) = \left(\bigoplus_{j \neq i} f_j \right)^c(x_i) \quad \text{for every } i = 2, \dots, N.$$

Then (f_1, \dots, f_N) is a c -conjugate tuple, that is, f_1 also satisfies

$$(3.6) \quad f_1(x_1) = \left(\bigoplus_{j \neq 1} f_j \right)^c(x_1).$$

In this case, the contact set $\Gamma = \Gamma_{\{f_i\}_{i=1}^N}$ satisfies (1.3), and thus, the assertions (i)–(vii) in Theorem 1.2 hold true if $\mathcal{H} = \mathbb{R}$.

Proof. If $N = 2$, (3.6) is equivalent to the fact $f^{**} = f$ by Fenchel and Moreau, and (1.3) is also shown by Rockafellar and Minty. We will proceed by an induction on $N \geq 3$, thus when $\mathcal{H} = \mathbb{R}$, firstly we will extend these results (3.6), (1.3) for $N = 3$. However, since the proof presented below will be valid for an arbitrary Hilbert space \mathcal{H} , in the sequel, we will denote \mathcal{H} (rather than \mathbb{R}) by the underlying space, though we will eventually assume $\mathcal{H} = \mathbb{R}$.

Step 1: $N = 3$ case. To begin, let us write $(f, g, h) = (f_1, f_2, f_3)$. We have

$$f(x) + g(y) + h(z) \geq \langle x, y \rangle + \langle y, z \rangle + \langle z, x \rangle,$$

hence

$$(3.7) \quad \varphi(x, y) := f(x) + g(y) - \langle x, y \rangle \geq h^*(x + y).$$

We will show h^* is the Δ -convex envelope of φ . Notice (3.7) is equivalent to

$$(3.8) \quad F(x) + G(y) \geq H(x + y)$$

where $F = f + q$, $G = g + q$, $H = h^* + q$, and we recall $q(s) = \frac{1}{2}|s|^2$. Observe that the conjugacy assumption (3.5), which reads

$$f(x) = \sup_y \{h^*(x + y) + \langle x, y \rangle - g(y)\}, \quad g(y) = \sup_x \{h^*(x + y) + \langle x, y \rangle - f(x)\}$$

implies that F and G are also H -conjugate (see (3.1)). We claim that H is the Δ -convex envelope of $F \oplus G$. Observe that this implies (3.6) for $N = 3$, because if H is the Δ -convex envelope of $F \oplus G$, then h^* must be the Δ -convex envelope of φ due to the equivalence between (3.7) and (3.8). But this precisely means that $h = (f \oplus g)^c$ by Lemma 3.3, as desired.

Then as argued in the proof of Proposition 3.5, it is sufficient to prove the claim under the assumption that F and G are H -conjugate, $F(0) = 0 = \min F$, $G(0) = 0 = \min G$, and the goal is to show $H(0) = 0 = \min H$.

To this end, for each $R > 0$, define

$$\begin{aligned} G_R(y) &= G(y) \quad \text{if } |y| \leq R, \quad G_R(y) = +\infty \quad \text{if } |y| > R, \\ h_R^*(x) &= \sup_{|y| \leq R} \langle x, y \rangle - h(y), \quad H_R = h_R^* + q, \\ F_R(x) &= \sup_y \{H_R(x + y) - G_R(y)\}, \\ F_R^H(y) &= \sup_x \{H_R(x + y) - F_R(x)\}, \\ K_R(y) &= \sup_x \{H_R(x + y) - F(x)\}. \end{aligned}$$

Assume R is large enough so that $\min G_R = \min G$ and h_R^* is proper. We have

$$(3.9) \quad h_R^* \text{ has Lipschitz constant at most } R,$$

$$(3.10) \quad F_R \text{ is locally Lipschitz and monotone increasing to } F \text{ as } R \rightarrow \infty,$$

$$(3.11) \quad F_R^H \text{ converges pointwise to } G.$$

(3.10) is because H_R and $-G_R$ monotonically increase in R , and F_R is locally Lipschitz because the supremum defining F_R is taken over $|y| \leq R$ only. And (3.11) is because $G_R \geq F_R^H \geq K_R$, G_R decreases to G , and K_R increases to G

in R . Now since F_R and F_R^H are H_R -conjugate, by Proposition 3.5, we have

$$(3.12) \quad H_R(x+y) \text{ is the } \Delta\text{-convex envelope of } F_R(x) + F_R^H(y).$$

Recall that our goal is to show $\min H = \min F + \min G$. It is clear that $\min H \leq \min F + \min G$. To show the reverse, since $H_R \leq H$ and $\min H_R = \min F_R + \min F_R^H$ by (3.12), and also $G_R \geq F_R^H \geq K_R$, it is enough to show

$$(3.13) \quad \min F_R \nearrow \min F \quad \text{and} \quad \min K_R \nearrow \min G \quad \text{as } R \rightarrow \infty.$$

The fact that $\min F = F(0) = 0$ and that F is of the form $F = f + q$ implies $F \geq q$, thus $F^* \leq q$. Since F_R is increasing to F , F_R^* is decreasing in R and is bounded below by F^* . Let F_∞ denote the limit of F_R^* . We claim $F_\infty = F^*$. To see this, first notice F_∞ is convex as a limit of convex functions. Secondly we have F_∞ is continuous, because $F^* \leq F_\infty \leq F_R^*$ and F_R is 1-strongly convex by Lemma 3.1, thus $q - F_R^*$ is continuous and convex. This implies F_∞ is bounded on every bounded subset of \mathcal{H} , thus is locally Lipschitz, hence continuous on \mathcal{H} . This yields $F_\infty = (F_\infty)^{**} = F^*$ as claimed. This implies in particular,

$$\min F = -F^*(0) = -F_\infty(0) = -\lim_{R \rightarrow \infty} F_R^*(0) = \lim_{R \rightarrow \infty} \min F_R.$$

Similarly, $\min K_R \nearrow \min G$. This proves $\min H = H(0) = 0$, and thus (3.6).

Now to prove (1.3), fix any $s \in \mathcal{H}$. By (1.3) holding for $N = 2$, there exists $z \in \mathcal{H}$ such that $h(z) + h^*(s - z) = \langle z, s - z \rangle$. This yields $z \in \partial h^*(s - z)$, implying $s \in \partial H(s - z)$. Since F, G, H are strongly convex, there exist unique $x, y, u \in \mathcal{H}$ such that $s \in \partial F(x) \cap \partial G(y) \cap \partial H(u)$. Our previous proof yields $F(x) + G(y) = H(x + y)$ and $s \in \partial H(x + y)$. Then the uniqueness of u implies $s - z = x + y$, that is, $s = x + y + z$. Finally,

$$\begin{aligned} F(x) + G(y) &= H(x + y) \\ \iff f(x) + g(y) &= h^*(x + y) + \langle x, y \rangle \\ \iff f(x) + g(y) &= h^*(s - z) + \langle x, y \rangle \\ \iff f(x) + g(y) &= \langle z, s - z \rangle - h(z) + \langle x, y \rangle \\ \iff f(x) + g(y) + h(z) &= \langle x, y \rangle + \langle y, z \rangle + \langle z, x \rangle. \end{aligned}$$

This proves the maximality (1.3), hence the theorem for $N = 3$.

Step 2: induction on N . From now on, we extend the proof for $N \geq 4$. We proceed by an induction on N . Suppose the theorem holds for $N - 1$. Define

$$\begin{aligned}\tilde{\mathbf{x}} &= (x_3, \dots, x_N), \quad S(\tilde{\mathbf{x}}) = \sum_{i=3}^N x_i, \quad c(\tilde{\mathbf{x}}) = \sum_{3 \leq i < j \leq N} \langle x_i, x_j \rangle, \\ \psi(\tilde{\mathbf{x}}) &= \sum_{i=3}^N f_i(x_i) - c(\tilde{\mathbf{x}}), \quad \varphi(x_1, x_2) = f_1(x_1) + f_2(x_2) - \langle x_1, x_2 \rangle, \\ g &= (f_1 \oplus f_2)^c, \text{ i.e., } g(y) = \sup_{x_1, x_2} \{ \langle y, x_1 + x_2 \rangle - \varphi(x_1, x_2) \}.\end{aligned}$$

From the inequality $\sum_{i=1}^N f_i(x_i) \geq c(\mathbf{x})$, we have

$$(3.14) \quad \psi(\tilde{\mathbf{x}}) \geq g(S(\tilde{\mathbf{x}})) = \sup_{x_1, x_2} \{ \langle S(\tilde{\mathbf{x}}), x_1 + x_2 \rangle - \varphi(x_1, x_2) \}.$$

Now comes the crux of the observation: (3.14), the induction hypothesis (on the cyclical involutivity), and the conjugacy (3.5) (i.e., each of the f_3, \dots, f_N is the smallest convex function satisfying (3.14) given others) combine to imply

$$(f_3, \dots, f_N, g^*) \text{ are } c(\tilde{\mathbf{x}}, y) \text{ - conjugate, where } c(\tilde{\mathbf{x}}, y) = c(\tilde{\mathbf{x}}) + \langle S(\tilde{\mathbf{x}}), y \rangle.$$

In other words, $g(S(\tilde{\mathbf{x}}))$ is the Δ -convex envelope of $\psi(\tilde{\mathbf{x}})$, by Lemma 3.3.

This in turn implies $f_2 = (f_1 \oplus g)^c$ due to the following calculation:

$$\begin{aligned}f_2(x_2) &= \left(\bigoplus_{j \neq 2} f_j \right)^c(x_2) \\ &= \sup_{x_1, \tilde{\mathbf{x}}} \{ \langle x_1, x_2 \rangle + \langle x_1 + x_2, S(\tilde{\mathbf{x}}) \rangle - f_1(x_1) - \psi(\tilde{\mathbf{x}}) \} \\ &= \sup_{x_1} \{ \langle x_1, x_2 \rangle - f_1(x_1) + \sup_{\tilde{\mathbf{x}}} \{ \langle x_1 + x_2, S(\tilde{\mathbf{x}}) \rangle - \psi(\tilde{\mathbf{x}}) \} \} \\ &= \sup_{x_1, y} \{ \langle x_1, x_2 \rangle - f_1(x_1) + \langle x_1 + x_2, y \rangle - g(y) \} \\ &= \sup_{x_1, y} \{ \langle x_2, x_1 + y \rangle - (f_1(x_1) + g(y) - \langle x_1, y \rangle) \} \\ &= (f_1 \oplus g)^c(x_2)\end{aligned}$$

where the fourth equality is because g is the Δ -convex envelope of ψ . The induction hypothesis (or the theorem we established for $N = 3$) now implies

$$f_1 = (f_2 \oplus g)^c = \left(\bigoplus_{j \neq 1} f_j \right)^c(x_1)$$

where the second equality is by an analogous calculation given above. This completes the proof of the cyclical involutivity (3.6).

Finally, we establish the maximality (1.3). Recall (3.14), that is

$$\psi(\tilde{\mathbf{x}}) \geq g(S(\tilde{\mathbf{x}})) \geq \langle y, S(\tilde{\mathbf{x}}) \rangle - g^*(y) \quad \text{for every } x_3, \dots, x_N, y.$$

Fix any $s \in \mathcal{H}$. By the conjugacy of (f_3, \dots, f_N, g^*) and the induction hypothesis on the maximality, there exists $\tilde{\mathbf{x}}^s = (\tilde{x}_3^s, \dots, \tilde{x}_N^s)$ such that

$$(3.15) \quad \psi(\tilde{\mathbf{x}}^s) = g(S(\tilde{\mathbf{x}}^s)) = \langle s - S(\tilde{\mathbf{x}}^s), S(\tilde{\mathbf{x}}^s) \rangle - g^*(s - S(\tilde{\mathbf{x}}^s)).$$

Similarly, the conjugacy of (f_1, f_2, g) yields

$$\varphi(x_1, x_2) \geq g^*(x_1 + x_2) \geq \langle z, x_1 + x_2 \rangle - g(z) \quad \text{for every } x_1, x_2, z,$$

and for the same s , there exists $x_1^s, x_2^s \in \mathcal{H}$ such that

$$(3.16) \quad \varphi(x_1^s, x_2^s) = g^*(x_1^s + x_2^s) = \langle s - x_1^s - x_2^s, x_1^s + x_2^s \rangle - g(s - x_1^s - x_2^s).$$

However, the pair $u, v \in \mathcal{H}$ that satisfies $u + v = s$ and $g(u) + g^*(v) = \langle u, v \rangle$ is unique. Hence (3.15), (3.16) implies $S(\tilde{\mathbf{x}}^s) = s - x_1^s - x_2^s$, or $s = \sum_{i=1}^N x_i^s$. From this identity, by adding the identities (3.15), (3.16), we obtain

$$\begin{aligned} \varphi(x_1^s, x_2^s) + \psi(\tilde{\mathbf{x}}^s) &= \langle S(\tilde{\mathbf{x}}^s), x_1^s + x_2^s \rangle \\ \iff (x_1^s, \dots, x_N^s) &\in \Gamma = \left\{ \mathbf{x} \mid \sum_{j=1}^N f_j(x_j) = c(\mathbf{x}) \right\}. \end{aligned}$$

This completes the proof of the theorem. \square

Remark 3.8. *The proof shows that Theorem 3.7 holds for any Hilbert space \mathcal{H} and for all $N \geq 3$ as soon as it holds for $N = 3$. However, the case $N = 3$ necessitates the restriction $\mathcal{H} = \mathbb{R}$ for the theorem to hold unless some regularity assumption is imposed on the conjugate convex functions. In view of Remark 3.6, this implies the set \mathcal{I} is not dense in \mathcal{H} in general when \mathcal{H} is multi-dimensional. In the following section, we provide examples for illustration.*

4. FAILURE ON MULTIDIMENSIONAL DOMAIN: EXAMPLES ON THE PLANE

In the sequel, let $e_1 = (1, 0)$, $e_2 = (0, 1)$ denote the standard basis of \mathbb{R}^2 . Firstly, we provide details for Proposition 1.10 in the following example.

Example 4.1. Let $\lambda > 0$, and $u = (1, 0) \in \mathbb{R}^2$, $v = (\frac{1}{2}, \frac{\sqrt{3}}{2}) \in \mathbb{R}^2$. There exists a c -conjugate triple $f, g, h \in \mathcal{A}(\mathbb{R}^2)$ for which $\Gamma = \Gamma_{\{f, g, h\}}$ satisfies

$$(4.1) \quad S(\Gamma) = \mathbb{R}^2 \setminus \text{int } \mathbf{H}_\lambda$$

where \mathbf{H}_λ is the convex hull of its six vertices $\pm 2\lambda u$, $\pm 2\lambda v$, and $\pm 2\lambda(v - u)$. An example of such a c -conjugate triple is as follows:

$$\begin{aligned} f(x) &= \begin{cases} 0 & \text{on } I_1 := \{x = au \mid a \in [-\lambda, \lambda]\}, \\ \infty & \text{else,} \end{cases} \\ g(y) &= \begin{cases} 0 & \text{on } I_2 := \{y = bv \mid b \in [-\lambda, \lambda]\}, \\ \infty & \text{else,} \end{cases} \\ h(z) &= \max \left(\lambda|u \cdot z + \lambda u \cdot v| + \lambda v \cdot z, \lambda|u \cdot z - \lambda u \cdot v| - \lambda v \cdot z \right). \end{aligned}$$

Proof. Step 1: $h = (f \oplus g)^c$. We firstly show $h = (f \oplus g)^c$. This follows from the following straightforward calculation:

$$\begin{aligned} (f \oplus g)^c(z) &= \sup_{x, y \in \mathbb{R}^2} x \cdot y + y \cdot z + z \cdot x - f(x) - g(y) \\ &= \sup_{|a| \leq \lambda, |b| \leq \lambda} (au + bv) \cdot z + ab(u \cdot v) \\ &= \sup_{|b| \leq \lambda} \sup_{|a| \leq \lambda} a(u \cdot z + b(u \cdot v)) + b(v \cdot z) \\ &= \sup_{|b| \leq \lambda} \lambda|u \cdot z + b(u \cdot v)| + b(v \cdot z) \\ &= \max \left(\lambda|u \cdot z + \lambda u \cdot v| + \lambda v \cdot z, \lambda|u \cdot z - \lambda u \cdot v| - \lambda v \cdot z \right) \end{aligned}$$

where the last equality is because the function $b \mapsto \lambda|u \cdot z + b(u \cdot v)| + b(v \cdot z)$ is convex and thus its maximum is attained at the boundary $b = \lambda$ or $b = -\lambda$.

Step 2: geometry of h and h^* . We investigate the geometry of h and thereby derive h^* . Recall $u = e_1$, $v = \frac{1}{2}e_1 + \frac{\sqrt{3}}{2}e_2$. Thus, for $z = (z_1, z_2) \in \mathbb{R}^2$,

$$h(z) = \max \left(\lambda \left| z_1 + \frac{1}{2}\lambda \right| + \frac{1}{2}\lambda z_1 + \frac{\sqrt{3}}{2}\lambda z_2, \lambda \left| z_1 - \frac{1}{2}\lambda \right| - \frac{1}{2}\lambda z_1 - \frac{\sqrt{3}}{2}\lambda z_2 \right).$$

The solution of the equation

$$\left| z_1 + \frac{1}{2}\lambda \right| + \frac{1}{2}z_1 + \frac{\sqrt{3}}{2}z_2 = \left| z_1 - \frac{1}{2}\lambda \right| - \frac{1}{2}z_1 - \frac{\sqrt{3}}{2}z_2$$

is given by

$$\begin{aligned} z_2 &= \frac{1}{\sqrt{3}}(|z_1 - \tfrac{1}{2}\lambda| - |z_1 + \tfrac{1}{2}\lambda| - z_1) \\ &= \begin{cases} -\sqrt{3}z_1 & \text{if } z_1 \in [-\tfrac{1}{2}\lambda, \tfrac{1}{2}\lambda], \\ -\frac{1}{\sqrt{3}}z_1 - \frac{1}{\sqrt{3}}\lambda & \text{if } z_1 \in [\tfrac{1}{2}\lambda, +\infty), \\ -\frac{1}{\sqrt{3}}z_1 + \frac{1}{\sqrt{3}}\lambda & \text{if } z_1 \in (-\infty, -\tfrac{1}{2}\lambda]. \end{cases} \end{aligned}$$

This, and the presence of the terms $|z_1 + \frac{1}{2}\lambda|$ and $|z_1 - \frac{1}{2}\lambda|$ imply that h is a piecewise affine convex function on the following four closed convex regions

$$\begin{aligned} R_1 &= \{z_1 \geq \tfrac{1}{2}\lambda\} \cap \{z_2 \leq -\tfrac{1}{\sqrt{3}}z_1 - \tfrac{1}{\sqrt{3}}\lambda\}, \\ R_2 &= \{z_1 \leq -\tfrac{1}{2}\lambda\} \cap \{z_2 \geq -\tfrac{1}{\sqrt{3}}z_1 + \tfrac{1}{\sqrt{3}}\lambda\}, \\ R_3 &= \{z_2 \geq -\sqrt{3}z_1\} \setminus (\text{int}R_1 \cup \text{int}R_2), \\ R_4 &= \{z_2 \leq -\sqrt{3}z_1\} \setminus (\text{int}R_1 \cup \text{int}R_2), \end{aligned}$$

where $\text{int}R$ denotes the interior of R , and h is defined on each region as

$$(4.2) \quad h(z) = \begin{cases} \frac{1}{2}\lambda z_1 - \frac{\sqrt{3}}{2}\lambda z_2 - \frac{1}{2}\lambda^2 & \text{in } R_1, \\ -\frac{1}{2}\lambda z_1 + \frac{\sqrt{3}}{2}\lambda z_2 - \frac{1}{2}\lambda^2 & \text{in } R_2, \\ \frac{3}{2}\lambda z_1 + \frac{\sqrt{3}}{2}\lambda z_2 + \frac{1}{2}\lambda^2 & \text{in } R_3, \\ -\frac{3}{2}\lambda z_1 - \frac{\sqrt{3}}{2}\lambda z_2 + \frac{1}{2}\lambda^2 & \text{in } R_4. \end{cases}$$

In particular, $\min h = h(0) = \frac{1}{2}\lambda^2$. Let $w = v - u = -\frac{1}{2}e_1 + \frac{\sqrt{3}}{2}e_2$, and let $D_\lambda \subseteq \mathbb{R}^2$ denote the convex hull of its four vertices $\pm\lambda w, \pm\lambda(u+v)$. Observe (4.2) readily implies that its convex conjugate is the following:

$$(4.3) \quad h^*(z^*) = \begin{cases} \lambda^2(t - \frac{1}{2}) & \text{if } z^* = \pm t\lambda w + s\lambda(u+v) \text{ for } t \in [0, 1], s \in [t-1, 1-t] \\ +\infty & \text{else, i.e., if } z^* \notin D_\lambda. \end{cases}$$

Step 3: $g = (h \oplus f)^c$ and $f = (h \oplus g)^c$. Now we show $g = (h \oplus f)^c$. By symmetry, $f = (h \oplus g)^c$ will then follow verbatim and we omit. We compute

$$\begin{aligned}
 (h \oplus f)^c(y) &= \sup_{x, z \in \mathbb{R}^2} x \cdot y + y \cdot z + z \cdot x - f(x) - h(z) \\
 &= \sup_{z \in \mathbb{R}^2} \sup_{a \in [-\lambda, \lambda]} a(y_1 + z_1) + y \cdot z - h(z) \\
 &= \sup_{z \in \mathbb{R}^2} y \cdot z - (h(z) - \lambda|z_1 + y_1|) \\
 &= (\xi_{y_1})^*(y)
 \end{aligned}$$

where $y = (y_1, y_2)$, $z = (z_1, z_2)$ and $\xi_{y_1}(z) := h(z) - \lambda|z_1 + y_1|$. We need to compute $(\xi_{y_1})^*$, the convex conjugate of ξ_{y_1} for each y_1 , and evaluate at y . First, since the coefficient of z_2 in (4.2) is within $[-\frac{\sqrt{3}\lambda}{2}, \frac{\sqrt{3}\lambda}{2}]$, we readily get

$$(\xi_{y_1})^*(y) = +\infty \text{ if } |y_2| > \frac{\sqrt{3}\lambda}{2}.$$

As a result, we will assume $y_2 \in [-\frac{\sqrt{3}\lambda}{2}, \frac{\sqrt{3}\lambda}{2}]$ from now on. We claim that $(\xi_{y_1})^*(y) = +\infty$ if y is not parallel to v . To see this, we will show that ξ_{y_1} is constant on the half-infinite lines $L_1 := R_1 \cap R_3$ and $L_2 := R_2 \cap R_4$ respectively. Notice the claim then follows from this constancy and the fact that v is perpendicular to the lines L_1, L_2 . Now it is clear that ξ_{y_1} is constant on L_1 , since for $z \in L_1$, we have $z_2 = -\frac{1}{\sqrt{3}}z_1 - \frac{1}{\sqrt{3}}\lambda$, yielding $h(z) = \frac{\lambda}{2}z_1 - \frac{\sqrt{3}\lambda}{2}z_2 - \frac{\lambda^2}{2} = \lambda z_1$. Similarly, $h(z) = -\lambda z_1$ on L_2 , proving the claim.

The remaining case for calculating $(\xi_{y_1})^*(y)$ is when y is parallel to v , that is, $y_2 = \sqrt{3}y_1$ and $y_1 \in [-\frac{\lambda}{2}, \frac{\lambda}{2}]$. We need to show $(\xi_{y_1})^*(y) = 0$, which will follow if we can show that the function $l_y(z) := y \cdot z$ satisfies $l_y \leq \xi_{y_1}$ in \mathbb{R}^2 with the inequality being saturated at some point in \mathbb{R}^2 . In fact, we claim

$$\begin{aligned}
 l_y &= \xi_{y_1} \text{ on } L_1 \cup L_2, \text{ and } l_y \leq \xi_{y_1} \text{ on } L_3 \cup L_4 \cup L_5 \cup L_6, \text{ where} \\
 L_3 &= R_1 \cap R_4, L_4 = R_2 \cap R_3, L_5 = R_3 \cap R_4, L_6 = \{z \mid z_1 = -y_1\}.
 \end{aligned}$$

Notice that since ξ_{y_1} is piecewise affine, the claim implies $l_y \leq \xi_{y_1}$ as desired.

To see $l_y = \xi_{y_1}$ on L_1 , since l_y is constant on L_1 , it is enough to show $l_y(-\lambda w) = \xi_{y_1}(-\lambda w)$. But $\xi_{y_1}(-\lambda w) = h(-\lambda w) - \lambda|y_1 - \lambda w_1| = \frac{\lambda^2}{2} - \lambda(y_1 + \frac{\lambda}{2}) = -\lambda y_1 = \lambda(\frac{1}{2}, -\frac{\sqrt{3}}{2}) \cdot (y_1, \sqrt{3}y_1) = -\lambda w \cdot y$, as desired. Similarly, $l_y = \xi_{y_1}$ on L_2 . Then $l_y \leq \xi_{y_1}$ on L_4 is immediate from the fact that L_4 is vertical, and the coefficient of z_2 in (4.2) is $\frac{\sqrt{3}\lambda}{2}$ which is no less than y_2 , meaning that ξ_{y_1}

grows no slower than l_y along L_4 . Similarly $l_y \leq \xi_{y_1}$ on L_3 . Then $l_y \leq \xi_{y_1}$ on L_5 follows from the fact that ξ_{y_1} is concave on L_5 with $l_y = \xi_{y_1}$ at the boundary points of L_5 , i.e., at λw and $-\lambda w$. From this, the dominance $l_y \leq \xi_{y_1}$ on L_6 can also be seen from the growth of h in z_2 direction, along with the fact $l_y \leq \xi_{y_1}$ at the point $L_5 \cap L_6$ just established. This proves the conjugacy $g = (h \oplus f)^c$.

Step 4: verification of Γ . We want to characterize Γ induced by the c -conjugate triple (f, g, h) . Recall that $f(x)$ and $g(y)$ are finite only for $x = au, y = bv$ with $a, b \in [-\lambda, \lambda]$, so we assume this henceforth. The inequality

$$f(x) + g(y) + h(z) \geq x \cdot y + y \cdot z + z \cdot x$$

then becomes

$$(4.4) \quad h(z) \geq z \cdot (x + y) + x \cdot y.$$

Notice this inequality can only become equality for (x, y) that satisfies:

$$(4.5) \quad h^*(x + y) = -x \cdot y.$$

That is, only for those (x, y) satisfying (4.5) can there be z satisfying equality in (4.4), i.e., $(x, y, z) \in \Gamma$. Thus we want to solve (4.5). Recall (4.3) that $h^*(z^*)$ is constant (and equal to $\lambda^2(t - \frac{1}{2})$) for $z^* = \pm t\lambda w + s\lambda(u + v)$, $t \in [0, 1]$, $s \in [t - 1, 1 - t]$, where $w = v - u$. In view of (4.5), let us assume $x + y = t\lambda(v - u) + s\lambda(u + v)$. Notice this implies $x = (s - t)\lambda u$, $y = (s + t)\lambda v$, since x, y are parallel to u, v respectively. In this case, (4.5) yields

$$\begin{aligned} \lambda^2(t - \tfrac{1}{2}) &= -\tfrac{1}{2}\lambda^2(s^2 - t^2) \\ \iff s^2 &= (t - 1)^2 \\ \iff s &= t - 1 \text{ or } 1 - t. \end{aligned}$$

In view of (4.3) and the definition of the region D_λ , this precisely means

$$(4.6) \quad \{x + y \mid h^*(x + y) = -x \cdot y, x = au, y = bv, -\lambda \leq a, b \leq \lambda\} = \partial D_\lambda$$

where ∂D_λ is the boundary of D_λ . Given (x, y) such that $x + y \in \partial D_\lambda$, finding $\Gamma_{x,y} := \{z \mid (x, y, z) \in \Gamma\}$ yielding equality in (4.4) is now straightforward from the description of h in (4.2). For example, for $x = \lambda u, y = \lambda v$, it is clear that $\Gamma_{x,y}$ is precisely R_3 , since the slope of h is $x + y = \lambda(u + v)$ on R_3 . Similarly,

for $x = -\lambda u, y = \lambda v$, we find $\Gamma_{x,y} = R_2$. For $x = t\lambda u, y = \lambda v$ with $t \in (-1, 1)$, we find $\Gamma_{x,y} = R_2 \cap R_3 = L_4$, and so on. Gathering $x + y + \Gamma_{x,y}$ for every $x + y \in \partial D$, we conclude that $S(\Gamma)$ is precisely as described in (4.1). \square

The oblique direction of u, v (i.e., $0 < u \cdot v < 1$), as well as finite-length but nonzero support of f and g (i.e., $0 < \lambda < \infty$), appear to be essential in constructing a counterexample presented in Example 4.1. In the following examples, we illustrate these observations.

Example 4.2 (Perpendicular u, v yields $S(\Gamma) = \mathbb{R}^2$). *Let $u = e_1, v = e_2$ and $\lambda \in [0, \infty]$ in Example 4.1 (note that we allow $\lambda = 0$ or ∞), so that*

$$\begin{aligned} f(x) &= \begin{cases} 0 & \text{on } I_1 = \{x = au \mid a \in [-\lambda, \lambda]\}, \\ \infty & \text{else,} \end{cases} \\ g(y) &= \begin{cases} 0 & \text{on } I_2 = \{y = bv \mid b \in [-\lambda, \lambda]\}, \\ \infty & \text{else,} \end{cases} \\ h(z) &= (f \oplus g)^c(z) \\ &= \sup_{a,b \in [-\lambda, \lambda]} (au + bv) \cdot z \\ &= \begin{cases} \lambda(|z_1| + |z_2|) & \text{if } \lambda \in [0, \infty), \\ 0 & \text{if } z = 0, \infty \text{ else, if } \lambda = \infty. \end{cases} \end{aligned}$$

(f, g, h) is a c -conjugate triple as easily verified. If $\lambda = 0$, then $(0, 0, z) \in \Gamma$ for any $z \in \mathbb{R}^2$, yielding $S(\Gamma) = \mathbb{R}^2$. If $\lambda = \infty$, then $(au, bv, 0) \in \Gamma$ for any $a, b \in \mathbb{R}$, again yielding $S(\Gamma) = \mathbb{R}^2$. Thus we henceforth assume $\lambda \in (0, \infty)$. We have

$$h^*(z^*) = \begin{cases} 0 & \text{if } z^* = (z_1^*, z_2^*), -\lambda \leq z_1^*, z_2^* \leq \lambda, \\ \infty & \text{else.} \end{cases}$$

Then the pair of $(x, y) \in I_1 \times I_2$ satisfying (4.5) is equal to $I_1 \times I_2$, since $x \cdot y = 0$. Thus the sum set, i.e., the set of $x + y$, becomes

$$(4.7) \quad \{x + y \mid h^*(x + y) = -x \cdot y, x \in I_1, y \in I_2\} =: D$$

where $D = I_1 + I_2$ is the convex hull of its four vertices $\pm\lambda(u+v), \pm\lambda(v-u)$. Notice the difference between (4.6) in Step 4 of Example 4.1, where the sum set is equal to the boundary of D , and not all of D .

Now for (x, y) with $x + y \in \text{int}D$, clearly $\Gamma_{x,y} = \{z \mid (x, y, z) \in \Gamma\} = \{0\}$. For each (x, y) such that $x + y \in \partial D$, verifying $\Gamma_{x,y}$ is again straightforward from the definition of h . For example, it is easy to see that $\Gamma_{\lambda u, \lambda v} = \{z = (z_1, z_2) \in \mathbb{R}^2 \mid z_1 \geq 0, z_2 \geq 0\}$, $\Gamma_{-\lambda u, \lambda v} = \{z = (z_1, z_2) \in \mathbb{R}^2 \mid z_1 \leq 0, z_2 \geq 0\}$, and $\Gamma_{t\lambda u, \lambda v} = \{z = (z_1, z_2) \in \mathbb{R}^2 \mid z_1 = 0, z_2 \geq 0\}$ for any $t \in (-1, 1)$, and so on. Gathering $x + y + \Gamma_{x,y}$ for every $x + y \in D$, we verify $S(\Gamma) = \mathbb{R}^2$, that is, Γ is maximally monotone. We thus conclude that the triple (f, g, h) does not provide a counterexample to Question 1 when u and v are perpendicular.

Example 4.3 (Infinite support of f, g with $u \cdot v \neq 0$ yields $h \equiv +\infty$). Let u, v be non-perpendicular unit vectors in \mathbb{R}^2 , i.e., assume $u \cdot v \in (0, 1]$. Define

$$f(x) = \begin{cases} 0 & \text{on } I_1 = \{x = au \mid a \in \mathbb{R}\}, \\ \infty & \text{else,} \end{cases}$$

$$g(y) = \begin{cases} 0 & \text{on } I_2 = \{y = bv \mid b \in \mathbb{R}\}, \\ \infty & \text{else.} \end{cases}$$

In this case, we claim that $h := (f \oplus g)^c$ is not proper but $h \equiv +\infty$. Because of this, the triple (f, g, h) does not provide a counterexample to Question 1.

The claim is straightforward from the following calculation:

$$\begin{aligned} (f \oplus g)^c(z) &= \sup_{x, y \in \mathbb{R}^2} x \cdot y + y \cdot z + z \cdot x - f(x) - g(y) \\ &= \sup_{a \in \mathbb{R}, b \in \mathbb{R}} (au + bv) \cdot z + ab(u \cdot v) \\ &\geq \sup_{a \in \mathbb{R}} a(u + v) \cdot z + a^2(u \cdot v) \\ &= \infty \end{aligned}$$

for any z , since $u \cdot v > 0$.

5. DUAL PERSPECTIVE OF CYCLICAL CONJUGATION AND MAXIMALITY

In this section, we illustrate cyclical involutivity and maximal monotonicity in the $N = 3$ case in the context of duality. For $f, g, h \in \mathcal{A}(\mathcal{H})$, we recall the

following inequality

$$(5.1) \quad f(x) + g(y) + h(z) \geq \langle x, y \rangle + \langle y, z \rangle + \langle z, x \rangle, \quad x, y, z \in \mathcal{H}$$

is equivalent to

$$(5.2) \quad F(x) + G(y) \geq H(x + y)$$

where $F = f + q$, $G = g + q$, $H = h^* + q$, which in turn yields the equivalence

$$(5.3) \quad \begin{aligned} f &= (g \oplus h)^c \text{ and } g = (h \oplus f)^c \\ &\iff F(x) = \sup_{y \in \mathcal{H}} H(x + y) - G(y) \text{ and } G(y) = \sup_{x \in \mathcal{H}} H(x + y) - F(x) \\ &\iff F = (H^* - G^*)^* \text{ and } G = (H^* - F^*)^* \text{ by Lemma 2.1} \end{aligned}$$

$$(5.4) \quad \iff U = (W - V)^{**} \text{ and } V = (W - U)^{**}$$

where $U = F^*$, $V = G^*$, $W = H^*$. This naturally leads us to consider the following class of convex functions (see [8, Propositions 12.30, 14.2])

$$\begin{aligned} \mathcal{A}_1(\mathcal{H}) &:= \{F \in \mathcal{A}(\mathcal{H}) \mid F \text{ is 1-strongly convex}\}, \\ \mathcal{A}_1^*(\mathcal{H}) &:= \{U \in \mathcal{A}(\mathcal{H}) \mid U = F^* \text{ for some } F \in \mathcal{A}_1(\mathcal{H})\} \\ &= \{U \in \mathcal{A}(\mathcal{H}) \mid U = f \square q \text{ for some } f \in \mathcal{A}(\mathcal{H})\} \\ &= \{U \in \mathcal{A}(\mathcal{H}) \mid q - U \text{ is continuous and convex}\}. \end{aligned}$$

We see that, given (5.3), the question of 3-cyclical involutivity, that is, whether h is equal to $(f \oplus g)^c$ or not, can be recast as the following dual problem:

Is $W := h \square q$ the smallest (pointwise in \mathcal{H}) function in $\mathcal{A}_1^*(\mathcal{H})$ satisfying (5.4)?

Note that $W := U + V$ is obviously the smallest convex function satisfying (5.4), but $U + V$ may not belong to the class $\mathcal{A}_1^*(\mathcal{H})$ in general. This makes the question of finding the smallest W in $\mathcal{A}_1^*(\mathcal{H})$ nontrivial. Indeed, we show below how the cyclical involution can fail only under the assumption (5.3).

Now we turn to the maximality question (1.3) in the context of duality. Assume $f, g, h \in \mathcal{A}(\mathcal{H})$ satisfies (5.1). The equivalence between ((v)) and ((vii)) in Theorem 1.2 is then recast, via Moreau decomposition, as follows:

$$(5.5) \quad \Gamma = \Gamma_{\{f, g, h\}} \text{ satisfies (1.3) if and only if } W = U + V.$$

Now assume $f, g \in \mathcal{A}(\mathcal{H})$, and set $h := (f \oplus g)^c$. Observe that (5.5) then yields the following equivalence:

$$(5.6) \quad \Gamma = \Gamma_{\{f, g, h\}} \text{ satisfies (1.3) if and only if } U + V \in \mathcal{A}_1^*(\mathcal{H}).$$

This is because if $W := U + V$ is in $\mathcal{A}_1^*(\mathcal{H})$, then $W^* - q$ is convex, thus the corresponding triple $f := U^* - q$, $g := V^* - q$ and $h := (W^* - q)^*$ satisfies (1.3) and c -conjugate, by the equivalence between ((v)) and ((vii)) in Theorem 1.2.

Let us explore the above discussion through the examples from the previous section. In Example 4.1, the triple (f, g, h) is c -conjugate, which yields $W = h \square q$ is indeed the smallest element in $\mathcal{A}_1^*(\mathcal{H})$ satisfying (5.4). However, $W(0) = -\min W^* > 0 = U(0) + V(0)$, causing the equation $W = U + V$ to fail. We deduce Γ does not satisfy (1.3), without having to precisely compute $S(\Gamma)$.

On the other hand, in Example 4.2, we have

$$U(x) = (f + q)^*(x_1, x_2) = \begin{cases} \frac{1}{2}|x_1|^2 & \text{for } x_1 \in [-\lambda, \lambda], \\ \lambda x_1 - \frac{1}{2}\lambda^2 & \text{for } x_1 \geq \lambda, \\ -\lambda x_1 - \frac{1}{2}\lambda^2 & \text{for } x_1 \leq -\lambda, \end{cases}$$

and $V(x_1, x_2) = U(x_2, x_1)$. It is easy to see that $U + V$ belongs to $\mathcal{A}_1^*(\mathcal{H})$, and hence by (5.6), we conclude that the triple (f, g, h) does satisfy (1.3).

Finally, we conclude this paper by detailing Proposition 1.9.

Example 5.1. *We will construct $f, g, h \in \mathcal{A}(\mathbb{R}^2)$ such that $f = (g \oplus h)^c$, $g = (h \oplus f)^c$, but $h \neq (f \oplus g)^c$. We denote $x = (x_1, x_2) \in \mathbb{R}^2$, $y = (y_1, y_2) \in \mathbb{R}^2$. Let $a \vee b := \max\{a, b\}$. Recall $\{e_1, e_2\}$ denote the standard basis of \mathbb{R}^2 . Define*

$$\begin{aligned} H_1(x) &= |x_1| \vee |x_2| + q(x), \\ G_0(y) &= \begin{cases} H_1(y) & \text{if } y = e_1 \text{ or } y = -e_1, \\ +\infty & \text{else,} \end{cases} \\ F_1(x) &= \sup_{y \in \mathbb{R}^2} H_1(x + y) - G_0(y), \\ G_1(y) &= \sup_{x \in \mathbb{R}^2} H_1(x + y) - F_1(x). \end{aligned}$$

Then F_1, G_1 are H_1 -conjugate. And by definition of F_1 , we have

$$F_1(0) = \min F_1 = 0, \text{ and } \frac{\partial F_1}{\partial x_2}(0) = 0,$$

that is, F_1 is smooth at its minimum (origin) in the x_2 -direction. Next, notice $G_1 = G_0$ at $y = \pm e_1$, and by symmetry of the construction, we have $G_1(0) = \min G_1$. We claim $G_1(0) > 0$. This can be easily seen from the inequality

$$F_1(x) \geq H_1(x) - G_1(0) \text{ for all } x \in \mathbb{R}^2,$$

and the fact that $F_1(0) = H_1(0) = 0$, and at the origin $x = 0$, F_1 is smooth in x_2 -direction but H_1 is singular. This proves the claim. Let $m := G_1(0) > 0$, and redefine

$$H = H_1 - m, \quad F = F_1, \quad G = G_1 - m,$$

so that we have

$$(5.7) \quad F(0) = \min F = G(0) = \min G = 0, \quad H(0) = \min H < 0, \text{ and}$$

$$(5.8) \quad F, G \text{ are } H\text{-conjugate.}$$

Now we define $f, g, h \in \mathcal{A}(\mathbb{R}^2)$ by $f = F - q$, $g = G - q$, and $h = (H - q)^*$. Then as discussed before, (5.8) implies that $f = (g \oplus h)^c$ and $g = (h \oplus f)^c$. We need to show $h \neq (f \oplus g)^c$. To show this, rather than finding precise formulas for h and $(f \oplus g)^c$, we derive a contradiction. Recall that the equality $h = (f \oplus g)^c$ implies $h^* + q$ is the largest 1-strongly convex lower-semicontinuous function satisfying (5.2). We claim that this is false with $h = (H - q)^*$.

Set $\tilde{H} := H \vee 0$. Notice that (5.7) then readily implies F, G are \tilde{H} -conjugate as well. But \tilde{H} is not 1-strongly convex yet. Note that for any $K \in \mathcal{A}(\mathbb{R}^2)$ satisfying $H \leq K \leq \tilde{H}$, we have that F, G are K -conjugate. Hence the claim will follow if we can find a 1-strongly convex function K satisfying:

$$(5.9) \quad H \leq K \leq \tilde{H}, \text{ and } H(0) < K(0).$$

But the definitions $H(x) = |x_1| \vee |x_2| + q(x) - m$ and $\tilde{H} = H \vee 0$ readily imply that for all sufficiently small $\epsilon > 0$, the following function

$$K_\epsilon := H \vee (q - m + \epsilon)$$

is a 1-strongly convex function satisfying (5.9). This proves $h \neq (f \oplus g)^c$.

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MAXIMALITY AND INVOLUTIVITY OF MULTI-CONJUGATE CONVEX FUNCTIONS31

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