Model-Free Reinforcement Learning for Static Point Source Localization in a 3D Simulation.*

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Abstract—The development of effective source localization techniques has broad reaching implications across multiple domains and environments. Whether it be natural resource detection, environmental monitoring and conservation, search and rescue, navigation or endless additional applications it is an interesting and complex problem that can be solved by the implementation of machine learning algorithms. The contribution of this work aims to implement an RL method that balances the trade-off between exploration and exploitation to efficiently locate and navigate toward the "source" in a relatively large static environment

Index Terms—reinforcement learning, q-learning, source localization.

I. INTRODUCTION

The development of effective source localization techniques has broad reaching implications across multiple domains and environments. Whether it be natural resource detection, environmental monitoring and conservation, search and rescue, navigation or endless additional applications it is an interesting and complex problem that can be solved by the implementation of machine learning algorithms.

Demonstrated methods of source localization such as local search and optimization problems guided by chemotaxis are not efficient for large search environments or remote isolated sources due to their affinity for local minima and maxima. The contribution of this work aims to implement an RL method that balances the trade-off between exploration and exploitation to efficiently locate and navigate toward the "source" in a relatively large static environment

II. RELATED WORKS

What papers can we reference?

III. METHODS

A python interface was implemented to simulate an agent and a three-dimensional environment. A uniform concentration gradient

Explain data, pollution? units?

was applied around a source point which the agents goal was to locate. The agent was trained using Direct Utility Estimation

Identify applicable funding agency here. If none, delete this.

Cite this: 21.2.1 Direct utility estimation, Artificial Intelligence A Modern Approach Third Edition, pg 833

Missing figure add figures in experiments

Fig. 1. Example of a figure caption.

V. CONCLUSION

VI. FUTURE WORK

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| What papers can we reference? | 1 | | | | |
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- There is no period after the "et" in the Latin abbreviation "et al.".
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TABLE I TABLE TYPE STYLES

| | Table | Table Column Head | | | |
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| | Head | Table column subhead | Subhead | Subhead | |
| | copy | More table copy ^a | | | |
| ^a Sample of a Table footnote. | | | | | |

Figure Labels: Use 8 point Times New Roman for Figure labels. Use words rather than symbols or abbreviations when

Fig. 2. Example of a figure caption.

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ACKNOWLEDGMENT

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