

$$A_0 = \int \vec{x} \times \vec{u} dV$$

$$= \underbrace{-\frac{1}{2} \int r^2 \vec{\omega} dV - \frac{1}{2} \int r^2 (\hat{n} \times \vec{u}) dS}_{\parallel \text{Lamb (1932)} \leftarrow \text{Angular impulse}}$$

$$= \underbrace{\frac{1}{3} \int \vec{x} \times (\vec{x} \times \vec{\omega}) dV}_{\text{Batchelor (1967)} \leftarrow \text{Angular impulse}} + \underbrace{\frac{1}{6} \int r^2 \vec{x} (\vec{\omega} \cdot \hat{n}) dS}_A - \underbrace{\frac{1}{2} \int r^2 (\hat{n} \times \vec{u}) dS}_B$$

Useful identity: $\int \hat{n} \times \vec{u} dS = \int \vec{\omega} dV = \int \vec{x} (\vec{\omega} \cdot \hat{n}) dS$

In case of a spherical boundary ($r^2 = \text{const.}$),

$$\therefore A_0 = \frac{1}{3} \int_V \vec{x} \times (\vec{x} \times \vec{\omega}) dV - \frac{1}{3} r^2 \int \vec{x} (\vec{\omega} \cdot \hat{n}) dS$$

" If V contains **all** vorticity, $\vec{\omega} \cdot \hat{n} = 0$ (on surface),

$$\underbrace{\vec{A}_0 = \int_V \vec{x} \times \vec{u} dV}_{\text{Angular momentum}} = \underbrace{\frac{1}{3} \int_V \vec{x} \times (\vec{x} \times \vec{\omega}) dV}_{\text{Batchelor (1967)}} = - \underbrace{\frac{1}{2} \int_V r^2 \vec{\omega} dV}_{\text{Lamb (1932)}}$$

"these terms vanish at infinity" Saffman

- this isn't obvious as $u \sim \frac{|z|}{r^3}$; $\omega \sim \frac{1}{r^4}$!

- Only way this works is by requiring

$$\text{AND } \begin{cases} \textcircled{1} \vec{\omega} \cdot \hat{n} = 0 \\ \textcircled{2} (\hat{n} \times \vec{u}) = 0 \text{ or } u \sim \frac{1}{r^2} \end{cases}$$

- For a spherical boundary and incompressibility,

$$\underbrace{\quad}_B = -\frac{1}{2} \int r^2 (\hat{n} \times \vec{u}) dS = -\frac{1}{2} \int r^2 \vec{x} (\vec{\omega} \cdot \hat{n}) dS = \int \hat{n} \times \vec{u} dS = \int \vec{\omega} dV = \int \vec{x} (\vec{\omega} \cdot \hat{n}) dS$$

$$\Rightarrow \underbrace{\quad}_A + \underbrace{\quad}_B = -\frac{1}{3} \int r^2 \vec{x} (\vec{\omega} \cdot \hat{n}) dS$$