

## **EECE 5610: Homework #3**

Due on October 11, 2022 at 11:45 am

Homework should be submitted via Canvas before the beginning of the class. Late submission is not accepted.

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**Problem 1****Problem 2.7-1**

- (a) Find  $e(0)$ ,  $e(1)$ , and  $e(10)$  for

$$E(z) = \frac{0.1}{z(z - 0.9)}$$

using the inversion formula.

- (b) Check the value of  $e(0)$  using the initial-value property.

- (c) Check the values calculated in part (a) using partial fractions.

- (d) Find  $e(k)$  for  $k = 0, 1, 2, 3, 4$  if  $\mathcal{Z}[e(k)]$  is given by

$$E(z) = \frac{1.98z}{(z^2 - 0.9z + 0.9)(z - 0.8)(z^2 - 1.2z + 0.27)}$$

- (e) A continuous time function  $e(t)$ , when sampled at a rate of 10 Hz ( $T = 0.1s$ ), has the following  $z$ -transform  $E(z) = \frac{2z}{z-0.8}$ . Find function  $e(t)$ .

- (f) Repeat part (e) for  $E(z) = \frac{2z}{z+0.8}$ .

- (g) From parts (e) and (f), what is the effect on the inverse  $z$ -transform of changing the sign on a real pole?

**Problem 2**

Consider the system described by

Problem 2.10-2

$$x(k+1) = \begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} x(k) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(k),$$

$$y(k) = \begin{bmatrix} -2 & 1 \end{bmatrix} x(k).$$

- (a) Find the transfer function  $Y(z)/U(z)$ .
- (b) Using any similarity transformation, find a different state model for this system.
- (c) Find the transfer function of the system from the transformed state equations.

**Problem 3**

Problem 2.6-6

Given the MATLAB program

```
1 - clear all;
2 - s1 = 0;
3 - e = 0;    %input signal e(0)
4 - for k = 0:10
5 -     s2 = e - s1;
6 -     m = 0.5*s2 - s1; % output signal m(k)
7 -     s1 = s2;
8 -     [k,m,s1]
9 -     e = e + 1;    %input signal e(k)
10 - end
```

that solves the difference equation of a digital controller.

- (a) Find the transfer function of the controller from input  $e(\cdot)$  to output  $m(\cdot)$ .
- (b) Find the  $z$ -transform of the controller input  $\{e(k)\}_{k=0}^{\infty}$ .
- (c) Use the results of parts (a) and (b) to find the inverse  $z$ -transform of the controller output.
- (d) Run the program to check the results of part (c). Please attach your MATLAB code/result (from the command window) to your report.

**Problem 4**

Problem 3.7-7 of the textbook (page 113).