## Solution

**⊔\**\/#6

Solution 1:

(a) 
$$1+KG(z)H=0=z^2-1.8187z+0.8187+0.001311Kz+0.001226K$$

:. char.eq.: 
$$Q(z) = z^2 - (1.8187 - 0.001311K)z + 0.8187 + 0.001226K = 0$$

(b) 
$$z = \frac{1 + \frac{T}{2}w}{1 - \frac{T}{2}w} = \frac{1 + 0.05w}{1 - 0.05w} = \frac{20 + w}{20 - w}$$

$$\therefore Q(w) = (20 + w)^2 - (1.8187 - 0.001311K)(400 - w^2) + (0.8187 + 0.001226K)(20 - w)^2 = 0$$

$$\therefore (3.6374 - 0.000085K)w^2 + (7.252 - 0.04904K)w + 1.0148K = 0$$

$$w^2 | 3.6374 - 0.000085K \quad 1.0148K \Rightarrow K < 42,793$$

\ for stability, 0 < K < 147.9

(c) 
$$Q(1) > 0 \Rightarrow 1 - 1.8187 + 0.001311K + 0.8187 + 0.001226K > 0$$

$$\therefore K > 0$$

$$(1)^2 Q(-1) > 0 \Rightarrow 1 + 1.8187 - 0.001311K + 0.8187 + 0.001226K > 0$$

$$\therefore K < 42,793$$

$$|a_0| < a_2 \Rightarrow 0.8187 + 0.001226K < 1, : K < 147.9$$

For Stability: 0 < K < 147.9

(d) 
$$K = 147.9$$
 From (a): char. eq.  $z^2 - 1.6248z + 1 = 0$ 

zeros: 
$$z = 1 \angle \pm 35.67^{\circ} = 1 \angle \pm 0.6225$$
 rad.

From (b): char. eq. 
$$3.6148w^2 + 150.09 = 0$$

$$W = \pm j6.437$$

(e) 
$$z - plane : 1\angle \omega T = 1\angle 0.6225$$
  $\therefore w = \frac{0.6225}{0.1} = 6.225 \text{ rad/s}$   
 $w$ -plane:  $\omega_w = 6.437$ 

(f) 
$$(7-10) \omega_w = \frac{2}{T} \tan\left(\frac{\omega T}{2}\right) = \frac{2}{0.1} \tan\left(\frac{0.6225}{2}\right) = 6.433$$

## MATLAB:

$$K = 147.9;$$
  
 $q = [1(-1.8187 + 0.001311*K) (0.8187 + 0.001226*K)]$   
roots(q)

(a) 
$$1 + KG(z)H = 0 = z^2 - 1.7408z + 0.7408 + 0.009072Kz +$$

:. char. eq.:  $z^2 + (0.009072K - 1.7408)z + 0.7408 + 0.008208K = 0$ 

(b) 
$$z = \frac{1 \pm \frac{T}{2}w}{1 - \frac{T}{2}w} = \frac{1 + 0.025w}{1 - 0.025w} = \frac{40 + w}{40 - w}$$
 yields

$$(40+w)^2 + (0.009072K - 1.7408(1600 - w^2) + (0.7408 + 0.008208K)(40 - w)^2 = 0$$

$$\therefore (3.4816 - 0.000864K)w^2 + (20.736 - 0.65664K)w + 27.65K = 0$$

$$\begin{vmatrix} w^2 \\ w^1 \end{vmatrix} 3.4816 - 0.000864K & 27.65K \Rightarrow K < 4,029.6 \\ w^1 & 20.736 - 0.65664K & \Rightarrow K < 31.58 \\ w^0 & 27.65K & \Rightarrow K > 0$$

\ for stability: 0 < K < 31.58

(c) 
$$Q(1) > 0 \Rightarrow 1 + 0.009072K - 1.7408 + 0.7408 + 0.008208K > 0 \Rightarrow K > 0$$

$$(-1)^2 Q(-1) > 0 \Rightarrow 1 - 0.009072K + 1.7408 + 0.7408 + 0.008208K > 0 \Rightarrow K < 4029.6$$

$$\left|a_0\right| < a_2 \Longrightarrow 0.7408 + 0.008208K < 1 \qquad \Longrightarrow K < 31.58$$

\ for stability: 0 < K < 31.58

(d) 
$$K = 31.58$$
, from (a):  $z^2 - 1.4543z + 1 = 0$ 

$$\therefore z = 1 \angle \pm 43.36^{\circ} = 1 \angle \pm 0.7567 \text{ rad}$$

from (b): 
$$3.4543W^2 + 873.2 = 0 \Rightarrow w = \pm j15.90 = \pm j\omega_w$$

(e) 
$$z$$
-plane:  $1\angle \omega T = 1\angle 0.7567 \Rightarrow \omega = 0.7567/0.05 = 15.13 \text{ rad/s}$ 

*w-plane* : 
$$\omega_{w} = 15.90$$

(f) 
$$(7-10) \ \omega_w = \frac{2}{T} \tan\left(\frac{\omega T}{2}\right) = 40 \tan\left(\frac{0.7567}{2}\right) = 15.90$$

MATLAB:

$$K = 31.58;$$

$$q = [1(.009072*K-1.7408) (0.7408+0.008208*K)]$$

roots(q)