

HW #3

Solution 1:

$$(a) \ e(k) = \sum_{\text{residues}} \frac{0.1z^{k-1}}{z(z-0.9)} = \sum_{\text{residues}} \frac{0.1z^{k-2}}{z-0.9}$$

$$k=0: \text{fcn} = \frac{0.1}{z^2(z-0.9)}, \quad \therefore \text{residue}\big|_{z=0.9} = \frac{0.1}{(0.9)^2} = 0.1235$$

$$\text{residue}\big|_{z=0} = \frac{d}{dz} \left[\frac{0.1}{z-0.9} \right]_{z=0} = \frac{-0.1(1)}{(z-0.9)^2} \bigg|_{z=0} = \frac{-0.1}{(0.9)^2} = -0.1235$$

$$\therefore e(0) = 0$$

$$k=1: e(1) = \frac{0.1}{z-0.9} \bigg|_{z=0} + \frac{0.1}{z} \bigg|_{z=0.9} = 0$$

$$k=10: e(10) = 0.1(0.9)^8$$

$$(b) \ e(0) = \lim_{z \rightarrow \infty} E(z) = \lim_{z \rightarrow \infty} \frac{0.1}{z(z-0.9)} = 0$$

$$(c) \ \frac{E(z)}{z} = \frac{0.1}{z^2(z-0.9)} = \frac{k_1}{z^2} + \frac{k_2}{z} + \frac{k_3}{z-0.9}$$

$$k_1 = \frac{-0.1}{0.9} = -\frac{1}{9}; \quad k_3 = \frac{0.1}{(0.9)^2} = \frac{1}{8.1}$$

$$k_2 = \frac{d}{dz} \left[\frac{0.1}{z-0.9} \right]_{z=0} = \frac{-1}{8.1}, \text{ from (a)}$$

$$\therefore e(k) = \frac{-1}{8.1} \delta(k) - \frac{1}{9} \delta(k-1) + \frac{1}{8.1} (0.9)^k$$

$$x(0) = -\frac{1}{8.1} + 0 + \frac{1}{8.1} = 0; \quad x(1) = -0 - \frac{1}{9} + \frac{0.9}{8.1} = 0$$

$$x(10) = -0 - 0 + \frac{0.1}{(0.9)^2} (0.9)^{10} = 0.1(0.9)^8$$

$$(d) \quad E(z) = \frac{1.98z}{z^5 + \dots} = 1.98z^{-4} + (\cdot)z^{-5} + (\cdot)z^{-6} + \dots$$

$$\therefore e(0) = e(1) = e(2) = e(3) = 0; \quad e(4) = 1.98$$

$$(e) \quad E(z) = \frac{2z}{z-0.8} = \frac{2z}{z-\epsilon^{-aT}} \quad \therefore \epsilon^{-aT} = 0.8 \Rightarrow aT = 0.2231$$

$$\therefore a = \frac{0.2231}{0.1} = 2.231, \quad \therefore e(t) = 2\epsilon^{-2.231t} u(t)$$

$$(f) \quad E(z) = \frac{2z}{z-(-0.8)}; \quad \therefore \epsilon^{-aT} \epsilon^{j\pi} = -0.8 \Rightarrow aT = 2.231$$

$$\therefore e(t) = 2e^{-2.231t} \cos 10\pi t \quad \text{where } \frac{\omega_s}{2} = 10\pi$$

$$(g) \quad (e) \quad e(k) = (0.8)^k; \quad (f) \quad e(k) = (-0.8)^k$$

$$\therefore \text{sign alternates on } e(k).$$

Solution 2:

$$(a) \quad z\mathbf{I} - \mathbf{A} = \begin{bmatrix} z & -1 \\ 0 & z-3 \end{bmatrix}; \quad \Delta = |z\mathbf{I} - \mathbf{A}| = z(z-3) = \Delta$$

$$\frac{Y(z)}{U(z)} = \mathbf{C}[z\mathbf{I} - \mathbf{A}]^{-1}\mathbf{B} = \frac{1}{\Delta} \begin{bmatrix} -2 & 1 \end{bmatrix} \begin{bmatrix} z-3 & 1 \\ 0 & z \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{\Delta} \begin{bmatrix} -2z+6 & z-2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{-z+4}{z(z-3)}$$

$$(b) \quad \mathbf{P} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}; \quad \mathbf{P}^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$\begin{aligned} \mathbf{A}_w &= \mathbf{P}^{-1} \mathbf{A} \mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 3 & 3 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 2 \\ 1 & 1 \end{bmatrix} \end{aligned}$$

$$\mathbf{B}_w = \mathbf{P}^{-1} \mathbf{B} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\mathbf{C}_w = \mathbf{C} \mathbf{P} = \begin{bmatrix} -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 3 \end{bmatrix}$$

$$\therefore \mathbf{w}(k+1) = \begin{bmatrix} 2 & 2 \\ 1 & 1 \end{bmatrix} \mathbf{w}(k) + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \mathbf{u}(k)$$

$$\mathbf{y}(k) = \begin{bmatrix} -1 & 3 \end{bmatrix} \mathbf{w}(k)$$

$$(c) \quad z\mathbf{I} - \mathbf{A}_w = \begin{bmatrix} z-2 & -2 \\ -1 & z-1 \end{bmatrix}; \quad \Delta = |z\mathbf{I} - \mathbf{A}_w| = z^2 - 3z + 2 - 2 = z(z-3)$$

$$\frac{Y(z)}{U(z)} = \mathbf{C}_w [z\mathbf{I} - \mathbf{A}_w]^{-1} \mathbf{B}_w = \frac{1}{\Delta} \begin{bmatrix} -1 & 3 \end{bmatrix} \begin{bmatrix} z-1 & 2 \\ 1 & z-2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{\Delta} \begin{bmatrix} -1 & 3 \end{bmatrix} \begin{bmatrix} z-1 \\ 1 \end{bmatrix} = \frac{-z+4}{z(z-3)}$$

Note that solution of part (b) could be different depending on how you choose your coordinate transform however you should get the same result for part (c)

Solution 3:

(a) From the code, we can get the difference equations as follows:

$$s_2(k) = e(k) - s_1(k), \quad (1)$$

$$m(k) = \frac{1}{2}s_2(k) - s_1(k), \quad (2)$$

and

$$s_1(k+1) = s_2(k). \quad (3)$$

Using (1) and (3), we get

$$s_1(k+1) = e(k) - s_1(k) \rightarrow e(k) = s_1(k+1) + s_1(k). \quad (4)$$

Using (1) and (2), we have

$$m(k) = \frac{1}{2}(e(k) - s_1(k)) - s_1(k) = \frac{1}{2}e(k) - \frac{3}{2}s_1(k). \quad (5)$$

Let's substitute $k = k+1$ in (5):

$$m(k+1) = \frac{1}{2}e(k+1) - \frac{3}{2}s_1(k+1). \quad (6)$$

Then, adding the both sides of (6) to the both sides of (5), we get

$$\begin{aligned} m(k+1) + m(k) &= \frac{1}{2}e(k+1) - \frac{3}{2}s_1(k+1) + \frac{1}{2}e(k) - \frac{3}{2}s_1(k) \\ &= \frac{1}{2}(e(k+1) + e(k)) - \frac{3}{2}(s_1(k+1) + s_1(k)). \end{aligned}$$

Now based on this equation and (4), it follows that

$$m(k+1) + m(k) = \frac{1}{2}(e(k+1) + e(k)) - \frac{3}{2}e(k) = \frac{1}{2}e(k+1) - e(k). \quad (7)$$

Using the z -transform, we get

$$\begin{aligned} M(z) &= \frac{1}{2}E(z) - z^{-1}E(z) - z^{-1}M(z) \\ \frac{M(z)}{E(z)} &= \frac{0.5z - 1}{z + 1} \end{aligned}$$

(b)

$$e(k+1) = e(k) + 1 = e(k-1) + 1 + 1 = \dots = e(0) + k + 1 = k + 1$$

$$e(k) = k \rightarrow E(z) = \sum_{k=0}^{\infty} kz^{-k} = \frac{z}{(z-1)^2}$$

(c) Using partial fraction formula, we get

$$\begin{aligned} M(z) &= \frac{0.5z - 1}{z + 1} \frac{z}{(z-1)^2} = \frac{(0.5z - 1)z}{(z+1)(z-1)^2} \\ \frac{M(z)}{z} &= \frac{A}{z+1} + \frac{B}{z-1} + \frac{C}{(z-1)^2} \end{aligned}$$

Solving for A :

$$A = \frac{0.5z - 1}{(z-1)^2} \Big|_{z=-1} = -\frac{3}{8}$$

Solving for B :

$$B = \frac{1}{(2-1)!} \frac{d}{dz} \frac{0.5z - 1}{z + 1} \Big|_{z=1} = \frac{3}{8}$$

Solving for C :

$$C = \left. \frac{0.5z - 1}{z + 1} \right|_{z=1} = \frac{1}{4}$$

Using A , B , and C , we have

$$\begin{aligned} \frac{M(z)}{z} &= \frac{-3}{8(z+1)} + \frac{3}{8(z-1)} + \frac{-1}{4(z-1)^2} \\ M(z) &= \frac{-0.375z}{z+1} + \frac{0.375z}{z-1} + \frac{-0.25z}{(z-1)^2} \end{aligned}$$

Then, applying the inverse z -transform it follows that

$$m(k) = -0.375(-1)^k - 0.25(k) + 0.375$$

Checking some results based on the result of the Matlab code:

$$m(10) = -0.375(-1)^{10} - 0.25(10) + 0.375 = -2.5.$$

```
>> hw3
```

```
ans =
```

```
0    0    0
```

```
ans =
```

```
1.0000    0.5000    1.0000
```

```
ans =
```

```
2.0000   -0.5000    1.0000
```

```
ans =
```

```
3     0     2
```

```
ans =
```

```
4    -1     2
```

```
ans =
```

```
5.0000   -0.5000    3.0000
```

```
ans =
```

```
6.0000   -1.5000    3.0000
```

```
ans =
```

```
7    -1     4
```

```
ans =
```

```
8    -2     4
```

```
ans =
```

```
9.0000   -1.5000    5.0000
```

```
ans =
```

```
10.0000   -2.5000    5.0000
```

```
>>
```

Solution 4:

x 2 pi are
missing in all
G_h0

$$(a) \quad \frac{1}{T} G_{h0}(j2) = \frac{\sin\left(\pi \frac{2\pi(2)}{2\pi(12)}\right)}{2\pi/12} e^{-j\pi/6} = \frac{0.50 \angle -30^\circ}{0.5236} = 0.9549 \angle -30^\circ$$

$$(b) \quad \frac{1}{T} G_{h0}(j10) = \frac{\sin\left(\pi \frac{10}{12}\right)}{10\pi/12} e^{-j^{10}\pi/12} = \frac{0.50 \angle -150^\circ}{2.618} = 0.1910 \angle -150^\circ$$

$$(c) (a) \quad \frac{1}{T} |G_{h1}(j\omega)| = \left[1 + \left(\frac{2\pi\omega}{\omega_s} \right)^2 \right]^{1/2} \left[\frac{1}{T} G_{h0}(j\omega) \right]^2$$

$$\frac{1}{T} |G_{h1}(j2z)| = \left[1 + \left(\frac{2\pi}{6} \right)^2 \right]^{1/2} (0.9549)^2 = 1.3203$$

$$\angle G_{h1}(j2) = \tan^{-1}\left(\frac{2\pi}{6}\right) - \left(\frac{2\pi}{6}\right) = 46.32^\circ - 60^\circ = -13.7^\circ$$

$$(b) \quad \frac{1}{T} |G_{h1}(j10)| = \left[1 + \left(\frac{20\pi}{12} \right)^2 \right]^{1/2} [0.1910]^2 = 0.194$$

$$\angle G_{h1}(j10) = \tan^{-1}\left(\frac{20\pi}{12}\right) - \left(\frac{20\pi}{12}\right) = 79.2^\circ - 300^\circ = -220.18^\circ$$

(d) The components at $\omega = 10$ are approximately equal.

The component at $\omega = 2$ for the 1st order hold is approximately 30% too large, which that for the zero-order-hold is approximately 10% too small. \therefore the zero-order hold is better in this case.