# **EECE 5610 Digital Control Systems**

### Lecture 7

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• Ideal sampler:

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Consider 
$$E^*(s) = \sum_{0}^{\infty} e(kT)e^{-kTs}$$

$$\iiint_{\infty} y^{-1}$$

$$e^{*(t)} = \stackrel{\sim}{z} e(kT) \stackrel{\sim}{z} \left[e^{kT_{s}}\right] = \stackrel{\sim}{z} e(kT) \delta(t-kT) = \stackrel{\sim}{z} e(t) \delta(t-kT)$$

$$= e(t) \stackrel{\sim}{z} \delta(t-kT)$$

• Ideal sampler:

Consider 
$$E(s) = \sum_{0}^{\infty} e(kT)e^{-kTs}$$

$$\iiint_{\infty} y^{-1}$$

$$e^{k}(t) = \sum_{0}^{\infty} e^{-kT_{0}} \int_{0}^{1} \left[e^{-kT_{0}}\right] = \sum_{0}^{\infty} e^{-kT_{0}} \int_{0}^{1} \left$$

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$$\delta_{T} = \sum_{0}^{\infty} \delta(t - kT)$$
 (a train of impulses)

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$$e(t) \xrightarrow{\times} e^{*}(t) = e(t) \xrightarrow{\delta_{T}(t)} e^{*}(t)$$

Let: 
$$\delta_T = \sum_{0}^{\infty} \delta(t-kT)$$
 (a train of impulses)

The action of the ideal sampler can be tought off as modulating a train of impulses with the input signal 
$$e(t)$$

$$e(t) = e(t) = e(t) = e(t)$$

$$e(6) \int_{0}^{\infty} \frac{e(kT)}{kT} dk$$

In the future we will think of E'(s) as the output of an ideal sampler.

• As mentioned before neither the ideal sampler nor the [1-e<sup>TS</sup>] block by themselves model the operation of a physical device. However, their combination does give the correct mathematical description of the sample & hold operation.

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  - · 9: Why do we go through all this trouble?
  - A: We want to get a T.F model of the hold operation and an input-output model of the sample and hold suitable for using in combination with linear systems analysis tools, such as the we'll see later

    2-transform

    R

    E(Z)

    SAMPLE

    ZOH

    PLANT

    Where G3(Z) = Z (3-e<sup>3</sup>). Plant

Example: 
$$e(t) = v(t)$$

$$e^* ?$$

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$$e^* ?$$

$$e(nT) = u(nT) = 1$$
 =  $e^*(t) = \sum_{n=0}^{\infty} e(nT) \delta(t-nT) = \sum_{n=0}^{\infty} \delta(t-nT)$ 

Example: 
$$e(t) = v(t)$$
 $e^*$ ?

$$e(nT) = u(nT) = 1$$
 =  $e^*(t) = \sum_{n=0}^{\infty} e(nT) \delta(t-nT) = \sum_{n=0}^{\infty} \delta(t-nT)$ 

$$E'(s) = \sum_{0}^{\infty} e^{-nTs} = \frac{1}{1-e^{Ts}} \quad \left( \text{Roc: } |e^{-Ts}| \right)$$

Example: 
$$e(t) = u(t)$$

$$e^*?$$

$$e(nT) = u(nT) = 3$$
 =  $e^*(t) = \sum_{n=0}^{\infty} e(nT) \delta(t-nT) = \sum_{n=0}^{\infty} \delta(t-nT)$ 

$$E'(s) = \sum_{0}^{\infty} e^{-nTs} = \frac{1}{1-e^{Ts}} \quad \left( \text{Roc: } |e^{-Ts}| \right)$$

(Note that the expression for E(8) resembles that of E(2), in fact, they are identical if we define  $z=e^{sT}$ . This is no accident, more on this later

· How do we compute E(s)? (we'd like to have a closed form like in the example, rather than the intinite series)

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**Facts:** 

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#### **Facts:**

(a) 
$$E(s) = \sum_{x \in S} \left[ \text{residues of } \left\{ E(\lambda) \frac{1}{1 - e^{T(x-\lambda)}} \right\} \text{ at poles of } E(\lambda) \right]$$
  
(b)  $E(s) = \sum_{x \in S} \left[ \sum_{x \in S} E(s + \ln w_s) + e(0)^{\frac{1}{2}} \right] \text{ where } w_s = 2\pi \frac{\pi}{T}$   
= sampling frequency

· How do we compute E(s)? (we'd like to have a closed form like in the example, rather than the intinite series)

**Facts:** 

(a) 
$$E(s) = \sum_{s=1}^{\infty} \left[ \text{residues of } \left\{ E(\lambda) \frac{1}{1 - e^{T(s-\lambda)}} \right\} \text{ at poles of } E(\lambda) \right]$$
  
(b)  $E(s) = \frac{1}{T} \left[ \sum_{s=0}^{+\infty} E(s+ \ln w_s) + e(0)^{\frac{1}{2}} \right]$  where  $w_s = 2\pi T$   
 $= sampling frequency$ 

Which one is useful to find E\*(s)?

· How do we compute E(s)? (we'd like to have a closed form like in the example, rather than the infinite series)

**Facts:** 

(a) 
$$E(s) = Z$$
 [ residues of  $g(s) = Z(s) = Z(s)$ ] at poles of  $g(s) = Z(s)$ ]

(b)  $E(s) = Z(s) = Z(s) = Z(s) = Z(s)$ 

$$= \sum_{t=0}^{+\infty} E(s+Jnw_s) + e(s) + e(s) = 2IT$$

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Which one is useful to find E\*(s)?

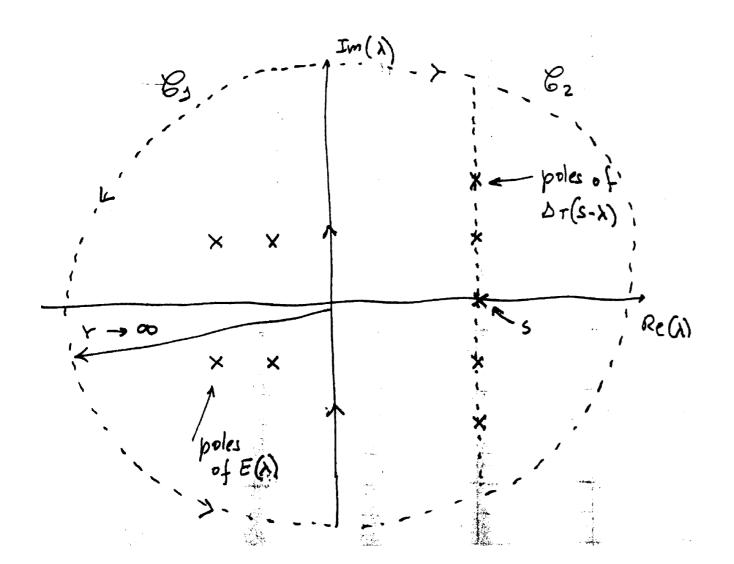
Which one is useful to determine properties of E\*(s)?

The proof uses again Cauchy's theorem. Sketch of the proof:  $e^{*}(t) = e(t) \delta_{T}(t) \qquad \text{where} \qquad \delta_{T}(t) = \sum_{n=0}^{\infty} \delta(t-nT)$   $E^{*}(s) = \frac{1}{2\pi J} \int E(\lambda) \Delta_{T}(s-\lambda) d\lambda \qquad \qquad \Delta_{T}(s) = \delta \left[ \delta_{T}(t) \right]$ 

The proof uses again Cauchy's theorem. Sketch of the proof:  $e^*(t) = e(t) \delta_T(t)$  where  $\delta_T(t) = \sum_{n=0}^{\infty} \delta(t-nT)$  $E^{*}(s) = \frac{1}{2\pi J} \begin{cases} c+5\infty \\ E(\lambda) \Delta_{T}(s-\lambda) d\lambda \end{cases} \qquad \Delta_{T}(s) = \mathcal{L}\left[\delta_{T}(t)\right]$ (Here we used the fact that product in time to convolucion in domain s ("frequency") domain)
where c must be chosen such that all poles of E(A) are to the left and all poles of DT are to the right The proof uses again Couchy's theorem. Sketch of the proof:  $e^*(t) = e(t) S_T(t)$  where  $S_T(t) = \sum_{n=0}^{\infty} S(t-nT)$  $E^{*}(s) = \frac{1}{2\pi J} \int_{C^{*}J^{\infty}}^{C^{*}J^{\infty}} E(\lambda) \Delta_{T}(s-\lambda) d\lambda \qquad \Delta_{T}(s) = \mathcal{L}\left[\delta_{T}(t)\right]$ 

(Here we used the fact that product in time to convolucion in domain s ("frequency") domain) where c must be chosen such that all poles of E(x) are to the left and all poles of DT are to the right

Note that  $\Delta_{T}(s) = \mathcal{L}\left[S_{T}(t)\right] = \sum_{0}^{\infty} e^{-nTs} = \frac{1}{1 - e^{sT}}$  = poles at  $e^{-Ts} = 1$   $\Rightarrow s = \pm \int_{\overline{ST}}^{2\overline{1}T} = \int_{\overline{ST}}^{\overline{T}} s^{n}$ So that  $\Delta_{\tau}(s)$  has an <u>infinite</u> number of poles, all on the ju axis, spaced  $w_s$ 



 $\Delta_{\tau}(\hat{s})$  poles at  $s = \pm \ln w_s$  $\Delta_{\tau}(s - \lambda)$  poles at  $\lambda = s \pm \ln w_s$ 

Closing the contour with  $G_2$  (a semicircle in the LHP with radius  $r \to \infty$ )
yields the first equality. If, on the other hand, we close the
contour with  $G_2$  (semicircle in RHP,  $r \to \infty$ ) we obtain the second formula

Example 1 = e(1) = v(1)

$$\longrightarrow E(\lambda) = \frac{1}{\lambda}; \quad E(\lambda) = \frac{1}{1 - e^{T(J-\lambda)}} = \frac{1}{\lambda (1 - e^{T(J-\lambda)})}$$

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$$\sum_{\text{poles}} \text{Res} = \sum_{\text{l}=0}^{\text{l}} \#$$
 $\lambda = 0$ 
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**Hint:** 

(a) 
$$E(s) = \sum_{x \in S} \left[ \text{ residues of } \left\{ E(\lambda) \frac{1}{1 - e^{T(s - \lambda)}} \right\} \text{ at poles of } E(\lambda) \right]$$

(b)  $E(s) = \frac{1}{T} \left[ \sum_{x \in S} E(s + \ln w_s) + e(0)^{\frac{1}{T}} \right] \text{ where } w_s = 2\pi$ 

$$= \text{ sampling frequency}$$

Res 
$$(z_i) = \frac{1}{(n-1)!} \frac{d^{n-1}}{dz^{n-1}} \left[ (z-z_i)^n F(z) \right]_{z=z_i}^{l} = z_i$$

Singularity of ord

Res  $(z_i) = (z-z_i) F(z) \Big|_{z=z_i}^{l}$  for singularities of order 1

Example 2: Suppose that  $f(t) = 1 - e^{-t}$ 

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$$\rightarrow F(s) = \sum_{k=0}^{\infty} (3 - e^{-kT}) e^{-kTS}$$

$$k=0$$

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$$= \sum_{k=0}^{\infty} e^{-kTs} \sum_{k=0}^{\infty} e^{-k(s+k)T} = \boxed{\frac{1}{1 - e^{-Ts}} - \frac{1}{1 - e^{(s+k)T}}}$$

Alternatively: 
$$F(s) = \frac{1}{s} \frac{1}{(s+1)} = \frac{1}{s(s+1)}$$
, poles at  $s = 0$ ,  $s = -1$ 

$$\geq \text{Res} \left\{ F(\lambda) \frac{1}{1 - e^{T(s-\lambda)}} \right\} = \sum_{\lambda=-1}^{\infty} \text{Res} \frac{1}{\lambda(\lambda+1)} \cdot \frac{1}{(1 - e^{T(s-\lambda)})} = \frac{1}{1 - e^{T(s-\lambda)}} + \frac{1}{1 - e^{T(s-\lambda)}}$$
(same as before)

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$$f(t) = 1 - e^{-t}$$

$$F(s) = \sum_{k=0}^{\infty} (1-e^{-kT}) e^{-kTS}$$

$$= \sum_{k=0}^{\infty} e^{-kTS} \sum_{k=0}^{\infty} e^{-k(S+k)T} = \boxed{\frac{1}{1-e^{-T}S} - \frac{1}{1-e^{(S+k)T}}}$$

Alternatively: 
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$$\sum_{\lambda=0}^{\infty} \text{Res} \left\{ F(\lambda) \frac{1}{1 - e^{T(s-\lambda)}} \right\} = \sum_{\lambda=-1}^{\infty} \frac{1}{\lambda(\lambda+1)} \cdot \frac{1}{(1 - e^{T(s-\lambda)})} = \frac{1}{1 - e^{Ts}} = \frac{1}{1 - e^{T(s+1)}} #$$

$$\left( \text{same as before} \right) ?$$

## Example 3:

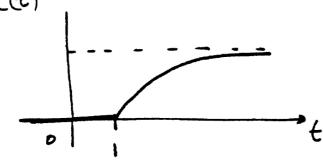
A function with a time-dalay. This example will become relevant later on when we will look into the effects of sampling:

T=1/2

# Example 3:

A function with a time-dalay. This example will become relevant later on when we will look into the effects of sampling:

Let 
$$e(t) = [1 - e^{-(t-1)}] v(t-1)$$
 (i.e.  $e(t) = (1 - e^{-t})$  delayed by  $1 = (1 - e^{-t})$  second)



$$e(k) = \left(1 - e^{(0.5k-1)}\right)$$
  $k \ge 2$ ;  $e(k) = 0$   $k = 0$ ,  $1 = 1/2$ 

#### Example 3:

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 (1.e

(1.e: 
$$e(t) = (1-e^t)$$
 delayed  
by 1 second)

Starting Summation from k = 2 because first 2 terms are zero due to step delay

$$e(k)=0$$
  $k=0, 1$   $T=1/2$ 

From the definition we have:

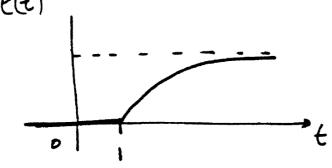
$$E(s) = \sum e(k)e^{-kTs} = \sum (1 - e^{(0.5k-1)})e^{-kTs} = \frac{2^{Ts}}{1 - e^{-Ts}} - e^{\frac{1}{2}} = \frac{2^{(0.5+1s)}}{1 - e^{-(0.5+Ts)}}$$

$$= \frac{e^{-5}}{1 - e^{-0.5}s} - e^{\frac{3}{2}}e^{\frac{1}{2}}e^{-\frac{5}{2}} = \frac{(1 - e^{-0.5})e^{-1.5s}}{(1 - e^{-0.5})(1 - e^{-0.5}(s+1))} #$$

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$$e(k) = \left[1 - e^{(0.5k-1)}\right] \quad k > 2; \quad e(k) = 0 \quad k = 0, 1$$

#### Example 3:

A function with a time-dalay. This example will become relevant later on when we will look into the effects of sampling:

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$$e(k) = [1 - e^{(0.5k-1)}]$$
  $k > 2;$   $e(k) = 0$   $k = 0, 1$ 

Now let's try our residues formula:

$$E(s) = \frac{e^{-s}}{s(s+1)} = E(s) = E(s) = \frac{E(s)}{\lambda} = \frac{1}{1 - e^{\tau(s-\lambda)}} = \frac{1}{\lambda = 1}$$

$$= \frac{1}{1 - \bar{e}^{TS}} + \frac{e^{1}}{(-1)} \cdot \frac{1}{1 - \bar{e}^{T(S+1)}} = \sqrt{\frac{1}{1 - \bar{e}^{0.5(S+1)}}} + \frac{e^{1}}{1 - \bar{e}^{0.5(S+1)}}$$

Surprise! we got different answers

P: What went wrong here?

Surprise! we got different answers

P: What went wrong here? -> Cauchy's Integral does not work well with time-delays!!

A: A techical point: the "proof" of the residues formula is not valid for systems baving time delays

The reason is that e<sup>st</sup> to on the infinite portion of the contour Bs and thus we can't close the contour and compute the susing residues

Solution (a) don't use the residues formula for systems with delays

Not too convenient. It defeats the whole purpose

of introducing the \* transform!

### Solution

(a) don't use the residues formula for systems with delays Not too convenient. It defeats the whole purpose of introducing the \* transform!

(b) Modify the formula:

It can be shown that if the delay is an integer number of periods then?

$$E^*(s) = \left[e^{-kT_S}E_{r}(s)\right]^* = e^{-kT_S} \sum_{\substack{a \neq poles \\ of E_{d}}} \left\{ \text{Res } E_{s}(\lambda) \frac{1}{1 - e^{T(s-\lambda)}} \right\}$$
hon delayed
signal

Applying this modified formula to our earlier example we get

$$E_{1}(s) = \frac{1}{s(s+1)}$$

$$\frac{\lambda=0}{\lambda=-1} \quad \frac{\lambda(\lambda+1)}{\lambda(\lambda+1)} \left(\frac{1-e^{T(s-\lambda)}}{1-e^{T(s+1)}}\right)$$

$$= \frac{1}{(3-e^{Ts})} - \frac{1}{(3-e^{T(s+1)})}$$

Applying this modified formula to our earlier example we get

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$$\frac{\lambda=0}{\lambda=-1} \quad \frac{\lambda(\lambda+1)}{\lambda(\lambda+1)} \left(\frac{1-e^{T(s-\lambda)}}{1-e^{T(s+1)}}\right)$$

$$= \frac{1}{(1-e^{T(s)})} - \frac{1}{(1-e^{T(s+1)})}$$

$$= e^{-2Ts} \left[ \frac{1}{1 - e^{-0.5s}} - \frac{1}{1 - e^{-0.5(s+1)}} \right] = e^{-s} \left[ \frac{1}{1 - e^{-0.5(s+1)}} \right]$$

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$$\frac{\lambda=0}{\lambda=-1} \quad \frac{\lambda(\lambda+1)}{\lambda(\lambda+1)} \left(\frac{1-e^{T(s-\lambda)}}{1-e^{T(s+1)}}\right)$$

$$= \frac{1}{(1-e^{Ts})} - \frac{1}{(1-e^{T(s+1)})}$$

$$\Rightarrow E(s) = e^{-2Ts} \left[ \frac{1}{1 - e^{-0.5s}} - \frac{1}{1 - e^{-0.5(s+1)}} \right] = e^{-s} \left[ \frac{1}{1 - e^{-0.5(s+1)}} - \frac{1}{1 - e^{-0.5(s+1)}} \right]$$

which coincides with our earlier result

proof:  

$$E(s) = \sum_{0}^{\infty} e(kT) e^{-skT}$$

$$E(s) = \sum_{0}^{\infty} e(kT) e^{-skT} = \sum_{0}^{\infty} e(kT) e^{-skT} - \int_{0}^{k2T-T} e^{-skT} = E(s)$$

$$= \sum_{0}^{\infty} e(kT) e^{-skT} = \sum_{0}^{\infty} e(kT) e^{-skT} = E(s)$$

proof:  

$$E(s) = Ze(kT) e^{-skT}$$

$$E(s) = Ze(kT) e^{-k[s+J2I]T} = Ze(kT) e^{-skT} - Jk^{2II} = E(s) \#$$

$$E(s+Jw_s) = Ze(kT) e^{-k[s+J2I]T} = Ze(kT) e^{-skT} = E(s) \#$$

Example: assume that E(s) has a pole at s=0 =0 E(s) poles at  $s_m = \pm \int n w_s$   $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}$ 

Example: assume that E(i) has a pole at s=0 =0 E(s) poles at  $s_m = \pm \int n \omega_s$   $\begin{array}{c} J\omega_s \\ 2J\omega_s \\ \end{array}$   $\begin{array}{c} J\omega_s \\ \end{array}$   $\begin{array}{c} J\omega_s \\ \end{array}$   $\begin{array}{c} Z\omega_s \\ \end{array}$   $\begin{array}{c} Z\omega_s \\ \end{array}$   $\begin{array}{c} Re(s) \\ \end{array}$   $\begin{array}{c} Re(s) \\ \end{array}$   $\begin{array}{c} Primary \\ \end{array}$   $\begin{array}{c} Strip: -\omega_s \\ \end{array}$   $\begin{array}{c} \omega_s \\ \end{array}$ 

proof: 
$$E'(s) = \frac{1}{T} \sum_{N=-\infty}^{N=+\infty} E(s+J_{N}w_{s}) = \frac{1}{T} \left[ E(s) + E(s+J_{N}w_{s}) + \cdots \right]$$

Example: assume that E(x) has a pole at x = 0 =0 E(x) poles at x = 0 = x = 0 y = 0

proof: 
$$E(s) = \frac{1}{T} \sum_{n=-\infty}^{n=+\infty} E(s+j_n w_s) = \frac{1}{T} \left[ E(s) + E(s+j_w_s) + \cdots \right]$$

If E(1) has a pole at  $s=s_1$ , the first term contributes a pole at  $s=s_1$ -jus  $s=s_1$ -jus  $s=s_1$ -jus

Example 2: Recall that we have shown that:

$$F(S) = \frac{1}{S} \cdot \frac{1}{(S+1)}$$

$$F(S) = \frac{1}{1 - e^{-ST}} - \frac{1}{1 - e^{-T(SH)}}$$

$$poles at S=0$$

$$poles at S=\frac{1}{T}$$

$$S=-1 + T n 2T$$

· Spectrum of a Sampled Signal

· Spectrum of a Sampled Signal

e(t) e\*(t)

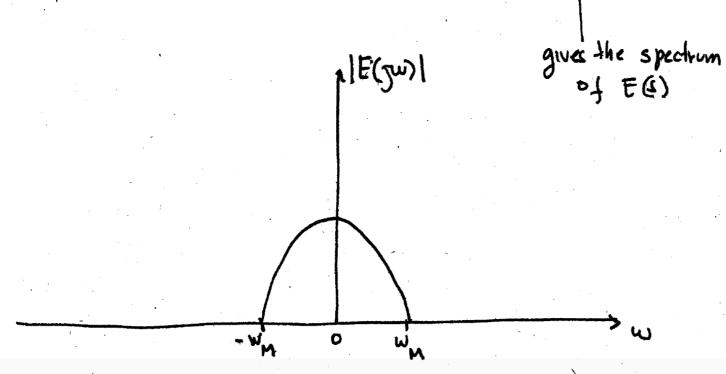
# Sampled

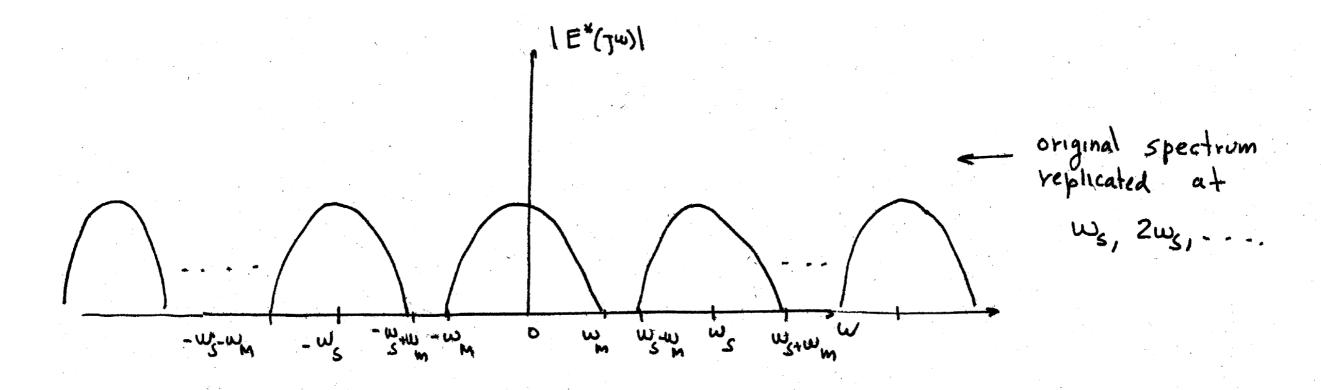
$$e(t)$$
  $e^{*}(t)$ 

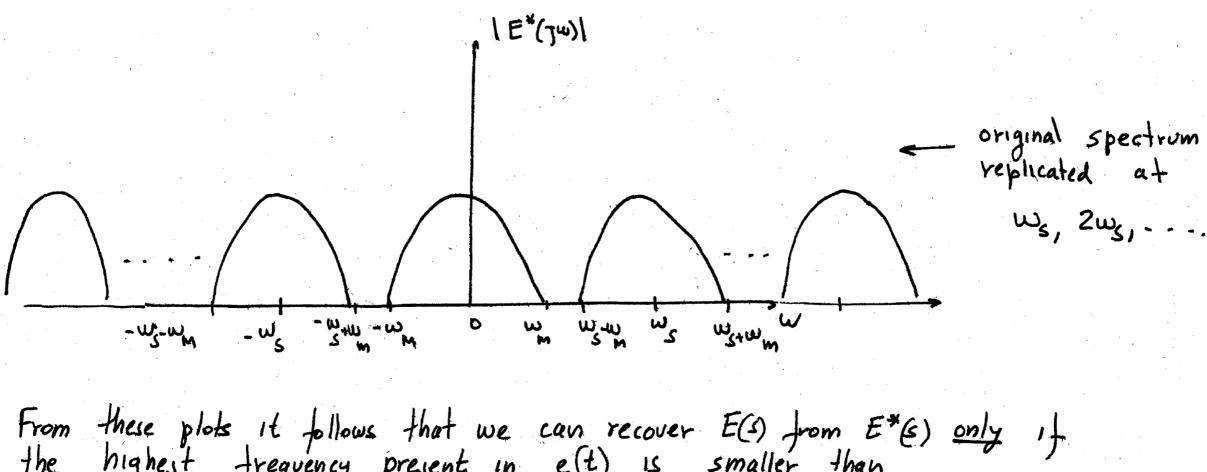
We'd like to relate the spectrum (i.e. fourier transform) of e(t) and e\*(t). This will become relevant when we discuss how to reconstruct (if possible) e(t)

Let 
$$e^*(t) = \sum_{k=-\infty}^{k=+\infty} e(t) \delta(t-kT)$$

$$e^{*}(t) = Z e(t) \delta(t-kT)$$
 $u = -\infty$ 
 $e^{*}(t) = Z e(t) \delta(t-kT)$ 
 $u = -\infty$ 
 $v \neq E, shifted binus$ 
 $v \neq E(s+jnws) = \frac{1}{T} \left[ E(s) + E(s+jws) + \cdots \right]$ 
 $v \neq E, shifted binus$ 
 $v \neq E(s+jnws) + \cdots = E(s+jnws) + E(s+jnws) + E(s+jnws) + E$ 

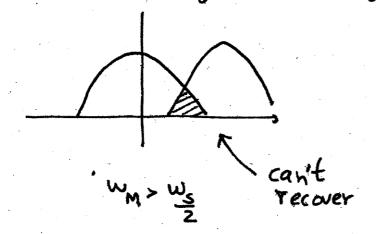


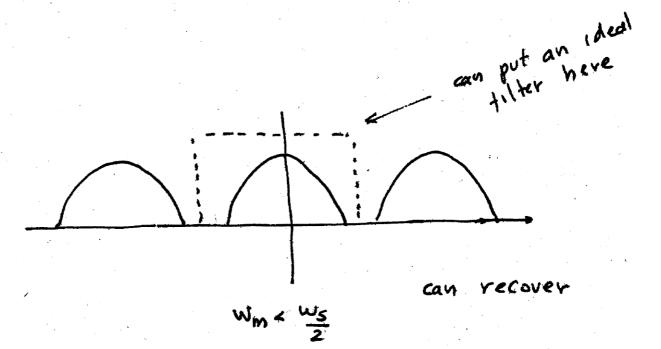


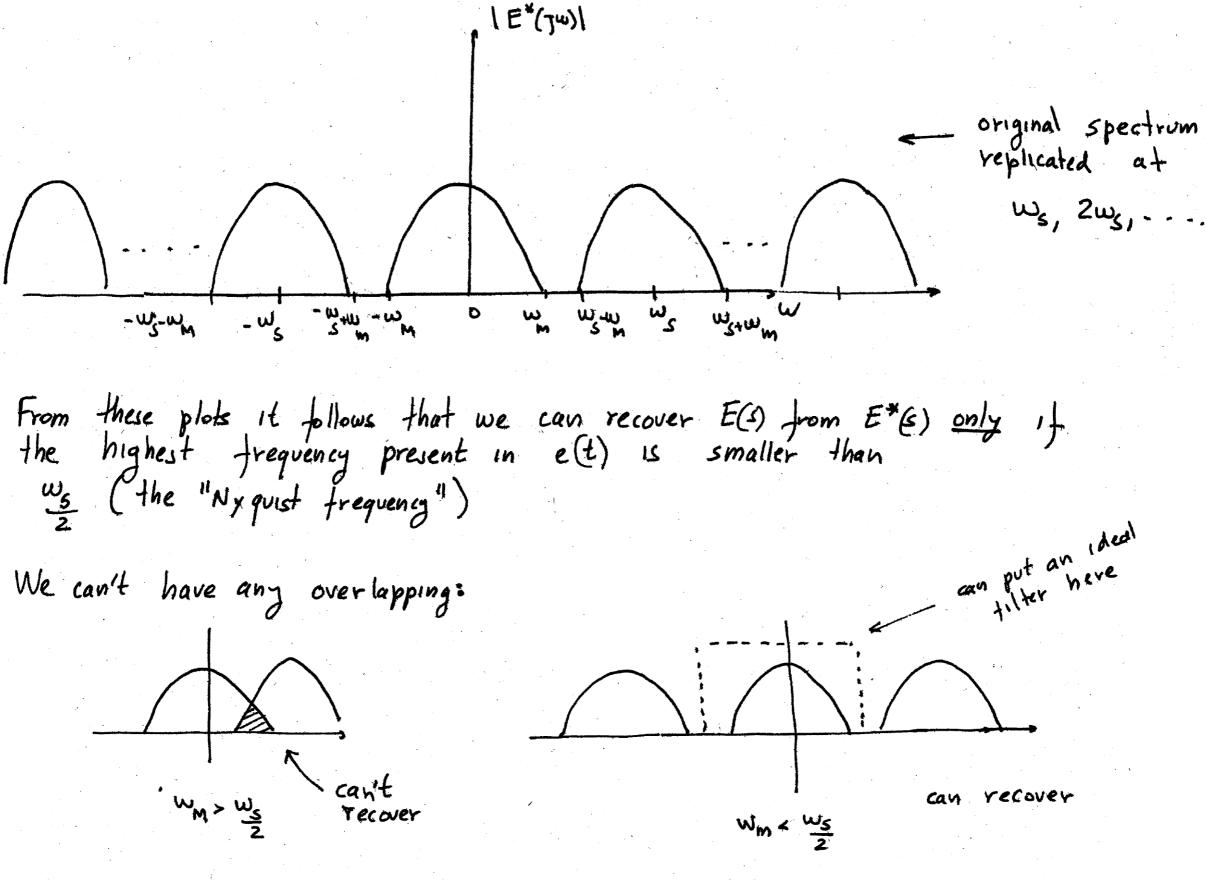


From these plots it follows that we can recover E(3) from  $E^*(6)$  only if the highest frequency present in e(t) is smaller than  $w_5$  (the "Nx quist frequency")

We can't have any overlapping:







Shannon's Sampling Theorem. the celebrated

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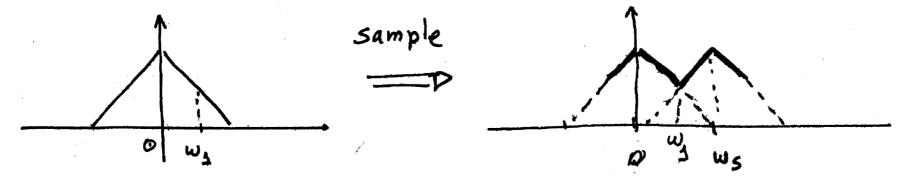
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## This is the celebrated Shannon's Sampling Theorem:

• A function eft) which contains no frequency component higher than fo is uniquely determined by the values of e(t) at any set of sampling points spaced  $T = \frac{1}{2} \int_{0}^{2} dt$ 

If e(t) has components above the Nyquist frequency we have the following situation:



In the sampled signal the contributions from the frequencies  $\omega_1$  and  $\omega_2 = \omega_1 - \omega_2$ both show up at  $\omega_3$ . This phenomenon is called <u>aliasing</u>

Implications:

2 sinusoids of different frequencies appear at the same place when sampled = D can't tell them appart

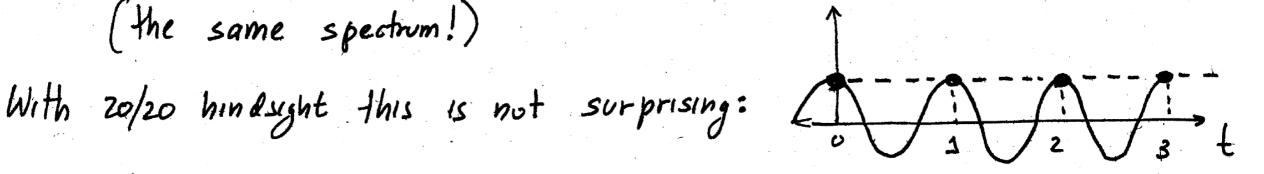
Example:

$$f_2(t) = 1$$

$$f_2(t) = \cos 2\pi t$$

If sampled at  $f_s = 1$  Hz both yield:  $\frac{1}{-2}$   $\frac{1}{-1}$   $\frac{1}{2}$ 

(the same spectrum!)



Related phenomenon: <u>Hidden</u> oscillations:

We can have a signal that does not show up at all when sampled

