Digital Control Systems Homework #2

Problem 1

Find the z-transforms of the number sequences generated by sampling the following time functions every T seconds, beginning at t = 0. Express these transforms in closed form.

(a)
$$e(t) = \exp(-at)$$

From this expression, since we are sampling every T seconds we can replace the term t with t = kT and we can include a *unit step* function into the expression since we are concerned with beginning from t = 0 onward:

$$e(t) = e(kT) = e^{-akT}u(k)$$

Expressing this in closed form, we get:

$$Z\{e(kT)\} = \sum_{k=0}^{\infty} e(kT)z^{-k}$$
$$= \sum_{k=0}^{\infty} e^{-akT}z^{-k}$$
$$= \sum_{k=0}^{\infty} (e^{-aT}z^{-1})^k$$

$$E(z) = \frac{1}{1 - e^{-aT}z^{-1}} \text{ or } \frac{z}{z - e^{-aT}}, \quad \text{for } |e^{-aT}z^{-1}| < 1$$

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% Prove with MATLAB
syms a k t T
et = exp(-a*t)
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$$et = e^{-at}$$

$$ekT = e^{-Tak}$$

$$\frac{z}{z - e^{-Ta}}$$

Ez =

(a)
$$e(t) = \exp(-t + T)u(t - T)$$

$$e(t) = e^{-t+T}u(t-T)$$

Replace the term t with the sampling interval $t \rightarrow kT$

$$e(kT) = e^{-kT+T}u(kT - T) = e^{-(k-1)T}u((k-1)T)$$

Using the z-transform property for a Time-Shift:

$$z\{e(k-n)u(k-n)\} = z^{-n}E(z)$$

which illustrates that the original *z*-transform of e(k) is multiplied by a factor of z^{-n} depending on the shift term. The closed-form expression results in:

$$z\{e^{-(k-1)T}u((k-1)T)\} = z^{-1}E(z) = z^{-1}\left[\frac{z}{z-e^{-T}}\right] = \frac{1}{z-e^{-T}}, \quad \text{for } |e^{-T}z^{-1}| < 1$$

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% Prove with MATLAB
syms z k t T
et = exp(-t)
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 $et = e^{-t}$

 $ekT = e^{-Tk}$

Ez =

$$\frac{z}{z - e^{-T}}$$

$$Ez = (z^{-1}) * Ez$$

Ez =

$$\frac{1}{z - e^{-T}}$$

(a)
$$e(t) = \exp(-t + 5T)u(t - 5T)$$

This expression follows the same operations as the previous question, but has a larger delay. Following the same steps previously, we get:

$$e(t) = e^{-t + 5T}u(t - 5T)$$

Replace the term t with the sampling interval $t \rightarrow kT$

$$e(kT) = e^{-kT+5T}u(kT-5T) = e^{-(k-5)T}u((k-5)T)$$

Again, using the *z*-transform property for a Time-Shift yields:

$$z\{e^{-(k-5)T}u((k-5)T)\} = z^{-5}E(z) = z^{-5}\left[\frac{z}{z-e^{-T}}\right] = \frac{1}{z^4(z-e^{-T})}, \quad \text{for } |e^{-T}z^{-1}| < 1$$

% Prove with MATLAB
syms k t T

$$et = exp(-t)$$

$$et = e^{-t}$$

$$ekT = e^{-Tk}$$

Ez =

$$\frac{z}{z - e^{-T}}$$

$$Ez = (z^{-5}) * Ez$$

Ez =

$$\frac{1}{z^4 (z - e^{-T})}$$

Problem 2

A function e(t) is sampled, and the resultant sequence has the z-transform

$$E(z) = \frac{z - b}{z^3 - cz^2 + d}$$

Find the *z*-transform of $\exp(akT)e(kT)$

This problem is asking us to solve for the z-transform of $\exp(akT)e(kT)$, which involves using the z-transform property of Complex Translation, that is:

$$\begin{split} z\{\varepsilon^{akT}e(kT)\} &= e(0) + \varepsilon^{aT}e(T)z^{-1} + \varepsilon^{2aT}e(2T)z^{-2} + \dots \\ &= e(0) + e(T)(z\varepsilon^{-aT})^{-1} + e(2T)(z\varepsilon^{-aT})^{-2} + \dots \end{split}$$

or

$$z\{\varepsilon^{akT}e(kT)\} = E(z)_{z \leftarrow z\varepsilon^{-aT}} = E(z\varepsilon^{-aT})$$

Thus, we can solve this problem using this property, which essentially states that we replace all terms of z in E(z) with the term ze^{-aT}

$$E(z)\Big|_{z \leftarrow z\varepsilon^{-aT}} = \frac{z - b}{z^3 - cz^2 + d}\Big|_{z \leftarrow z\varepsilon^{-aT}} = \frac{z\varepsilon^{-aT} - b}{z^3\varepsilon^{-aT} - cz^2\varepsilon^{-aT} + d}$$

Thus, using the property of Complex Translation and E(z), we can solve for $\exp(akT)e(kT)$

syms a b c d T z % Use property of Complex Translation to replace values of z for ze^-aT
$$Ez = (z-b)/(z^3 - c*z^2 + d)$$

$$-\frac{b-z}{z^3-c\,z^2+d}$$

$$Ez = subs(Ez,z,z*exp(-a*T))$$

Ez =

$$-\frac{b-z e^{-T a}}{e^{-3 T a} z^3 - c e^{-2 T a} z^2 + d}$$

Problem 3

For the number sequence $\{e(k)\}$,

$$E(z) = \frac{z}{(z-1)^2}$$

(a) Apply the final-value theorem to E(z)

The final-value theorem states that $\lim_{k\to\infty} e(k) = \lim_{z\to 1} (z-1)E(z)$ if $e(\infty)$ exists. When examining E(z), we use the transform pair to find the inverse transform is equal to:

 $z^{-1}\{E(z)\}=\frac{z}{(z-1)^2}=k$ then, finding $e(\infty)$ in our case is rather simple since this sequence linearly increases in values, so:

 $\lim_{k\to\infty}e(k)=\infty$, which it's limit is unbounded.

Thus, we cannot use the final-value theorem because all the poles of E(z) are not inside the unit circle.

Double-checking in the z-Domain, we find:

$$\lim_{k \to \infty} e(k) = \lim_{z \to 1} (z - 1)E(z)$$

$$= \lim_{z \to 1} (z - 1) \frac{z}{(z - 1)^2}$$

$$= \lim_{z \to 1} \frac{z}{(z - 1)}$$

$$= \lim_{z \to 1} \frac{1}{(1 - 1)} = \frac{1}{0} = \text{indeterminate}$$

syms k z
$$Ez1 = z/(z-1)^2$$

Ez1 =

$$\frac{z}{(z-1)^2}$$

ek1 = iztrans(Ez1,k)

ek1 = k

ek_final_value = subs(ek1,k,Inf)

ek final value = ∞

(b) Find the *z*-transform of $e(k) = k(-1)^k$

For this problem, we can use the transform pair:

$$ka^k \leftrightarrow \frac{az}{(z-a)^2}$$

In our case, a = -1, which results in the z-transform:

$$z\{e(k)\} = z\{k(-1)^k\} = -\frac{z}{(z+1)^2}$$

Thus,

$$E(z) = -\frac{z}{(z+1)^2}$$

% Prove using MATLAB
syms k z
ek2 = k*(-1)^k

$$\mathsf{ek2} = (-1)^k \, k$$

Ez2 = ztrans(ek2)

Ez2 =

$$-\frac{z}{(z+1)^2}$$

(c) Explain how parts(a) and (b) are related

From part (a), we showed that the final-value theorem for E(z) was unbounded.

So, now we check if $e(\infty)$ exists for part (b)

 $\lim_{k\to\infty} e(k) = k(-1)^k \to \lim_{k\to\infty} \infty (-1)^\infty \text{ which results in an unbounded result}$

So, here for the case of part (b), the value of $e(\infty)$ is unbounded as well, which means that it doesn't exist either

So, we conclude that both parts (a) and (b) are related due to both of their time-domai signals at $e(\infty)$ not existing when taking their corresponding limits. This means that we cannot take the final-value theorem approach for these sequences because all of their poles for E(z) are not within the unit circle. In fact, part

(a) has double poles at $z = 1$ and part (b) has double poles at $z = -1$, which is exactly on the unit circle and explains our findings.