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蒙特卡羅方法之罕見事件及其應用於電路模擬  
Rare Events in Monte Carlo Methods  
with Applications to Circuit Simulation

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## **Abstract**

The simulation of rare events in Monte Carlo is of practical importance across many disciplines including circuit simulation, finance, and metrology to name a few. To make inferences about the behavior of distributions in systems which have a likelihood of 1 in billions, simulation by traditional Monte Carlo becomes impractical. Intuitively, Monte Carlo samples which are likely (i.e. samples drawn from regions of higher probability density) have little influence on the tail distribution which is associated with rare events. This work provides a novel methodology to directly sample rare events in input multivariate random vector space as a means to efficiently learn about the distribution tail in the output space. In addition, the true form of the Monte Carlo simulation is modeled by first linear and then quadratic forms. A systematic procedure is developed which traces the flow from the linear or quadratic modeling to the computation of distribution statistics such as moments and quantiles directly from the modeling form itself. Next, a general moment calculation method is derived based on the distribution quantiles where no underlying linear or quadratic model is assumed. Finally, each of the proposed methods is grounded in practical circuit simulation examples. Overall, the thesis provides several new methods and approaches to tackle some challenging problems in Monte Carlo simulation, probability distribution modeling, and statistical analysis.



## Acknowledgements

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studies at NTU in Taipei during the early years of the PhD studies. Without the guidance and support of these folks, the thesis would not have been possible.

Though the thesis scope does not directly include machine learning, the inspiration behind the developed algorithms is certainly related to ML. I was fortunate enough to be exposed to memorable experiences in machine learning relatively early in my academic career with an automated VLSI design course taught by Sung-Kyu Lim at Georgia Tech as an undergraduate and later in a machine learning course taught by Andrew Ng at Stanford as a graduate student. It was not until my PhD studies were underway at National Taiwan University, though, that I was able to delve deeper into machine learning and become more proficient. Taking courses from Chih-Jen Lin, Hsuan-Tien Lin, and Shou-De Lin at NTU provided an excellent grounding in all things machine learning from Support Vector Machines and Convex Optimization to Probabilistic Graphical Models and Low Rank Approximation. Beyond the coursework, there were also international competitions such as the KDDCup where the theory could be immediately put to practice and these exercises led to many successful results[42, 30, 6]. Special thanks to Shou-De Lin for playing an important role in the early stages of my PhD research. In those first few years I attempted a range of pure machine learning topics and though the final thesis topic ultimately departed from this earlier work, from a learning perspective the time with Shou-De was invaluable and also fruitful[27].

When I initially decided to pursue the PhD degree in Taiwan as a non-native Chinese speaker, I knew there would be some interesting challenges both in and out of the classroom. Now that I find myself near the other end of this goal, I have

a small army of Chinese language teachers I wish to thank. To my first Chinese language teacher Xiao-Liang Li at Georgia Tech, who helped spark my passion for the Chinese language, and to my many teachers at the Mandarin Training Center at National Taiwan Normal University and at the International Chinese Language Program at National Taiwan University, I owe a great debt. At ICLP, I would especially like to thank Li-Yuan Chen, Zhou Chang-Zhen, Mei-Yuan Fan, Xin-Chun Chen, Rou-Yu Shen, Zhi-Cheng Xu, and Jing-Jing Chai.

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# **Chapter 1**

## **Introduction**

### **1.1 Problem Statement**

The problems addressed by this thesis are as follows:

1. How to investigate rare Monte Carlo events given a limited simulation budget?
2. How to model and characterize quadratic forms of multivariate standard normal random variables?
3. How to calculate mean, standard deviation, skewness and kurtosis efficiently from quantile information alone?

### **1.2 Motivation and Scope**

Stochastic process variation plays an ever increasing role in the reliability of semiconductor circuit as scaling descends further into the nanoscale regime advanced by the

two plus year transistor count doubling cadence in dense integrated circuits[33, 5]. Process variation accounts for the naturally occurring variation during the semiconductor manufacturing process such as gate length or width, fin height, and oxide thickness[31]. Also important are sources of systematic variation such as random dopant fluctuation (RDF), random polysilicon crystal orientation, and other like physical effects[15]. The effect of such variation are intensified by transistor scaling due to the fact that the variation impact is roughly inversely proportional to the square root of the transistor area[38].

In this context, two central questions often posed by circuit designers are :

1. Given a percentile of component yield, what is the measure value at the yield boundary? (the “quantile question”)
2. Given a measure specification limit, what percentage of components satisfy that criterion? (the “yield question”)

As these questions must be answered iteratively during the design process by Monte Carlo methods, providing accurate answers is an important part of the circuit design flow. Highly replicated systems and systems that are difficult or impossible to replace such as space applications require extremely low failure rates. The automotive industry, driven by stringent safety standards of ISO 26262[23], also requires the hardware and hardware development systems to meet stringent high-sigma requirements. The high sigma circuit simulation which is needed for these applications can easily become a bottleneck in the circuit design process due to the high number of simulation samples required.

With the high replication of cell instances for circuits such as static random access memories(SRAMs) and flip-flops, the occurrence of extremely rare events becomes more likely. For a cell which is replicated 10 million times (for example, in a 10-Mb SRAM array), each manufactured instance is slightly different due to manufacturing variation though they are identical by design. Because there is a built in design margin, most of the cell instances will meet specifications despite this variation. If the desired chip yield is 99%, the cell yield requirement would be 99.999998995%, which is roughly 6-sigma. In order to simulate just 5 failing samples at such a yield rate, a Monte Carlo simulation of 4.48 billion samples would be required. If one such simulation takes just 1 second, then 51.9 days would be required on 1000 cores to complete the full simulation. As is evident, it is difficult to accurately determine yield rates under such conditions in a reasonable amount of time. This thesis explores several methods to simulate rare samples, including a novel method called In-Order Multivariate Sampling.

Another area of research covered in the thesis is the modeling of vectors of standard normal random numbers. Such vectors are used extensively in semiconductor simulation systems to model process and physical variation, as mentioned. While linear forms of multivariate standard normals are well understood and often used, the quadratic form is used much less frequently with known treatment in computational finance[19] not yet becoming widespread in circuit simulation. The thesis aims to bridge this gap by integrating and extending relevant techniques into a coherent flow for quadratic form utilization in the circuit simulation domain. The flow includes the fitting of the quadratic form via sparse orthogonal polynomial mod-

els through the extraction of statistical properties such as moments and quantiles directly from the quadratic form without sampling.

The calculation of moments is a common task when studying complex systems. When the linear or quadratic form is available, the moments can be directly calculated from the model as discussed. In the case when sample data is given, then the moments can be calculated from the sample data in the standard way. However, if the CDF of the given probability function is theoretically derived, only the information of a QQ plot is provided, or the sample data is otherwise unavailable, can quantiles be used to calculate moments? The thesis provides an answer to this question in the affirmative with a novel method for moment calculation given quantile information only.

In the thesis, the topics outlined above are first studied from a theoretical perspective and with the results of simplified examples to build intuition. These findings are then grounded in actual circuit simulation results which show the applicability of the methods to real world problems.

### 1.3 Thesis Organization

In Chapter 2, a foundation is established which covers random variable expectation, moments, quantiles, probability distributions, and other topics. The main theme of the thesis centers on the statistics and sampling of random variables, so this chapter lays the groundwork for subsequent chapters.

In Chapter 3, we propose a new algorithm In-Order Multivariate Sampling (IMS)

to efficiently study rare events in Monte Carlo simulation associated with distribution tails. Both the “yield question” and the “quantile question” discussed in the previous section are intrinsically linked to the tail distribution of the circuit measures which represent rare events. The IMS method is first motivated by describing the details and challenges of Monte Carlo simulation at higher sigma.

In Chapter 4, the linear representation of the true Monte Carlo function which was analyzed in Chapter 3 is extended to the quadratic domain. A flow for modeling and characterizing quadratic forms of multivariate normal distributions is presented and reviewed. The results of the characterization flow include the computation of moments, cumulants, and quantiles.

In Chapter 5, a method for calculating moments from quantile information is presented. The method is compared against the sample moment method for several common probability distributions.

In Chapter 6, applications to circuit simulation are presented which tie together and reveal the practical value of methods developed in earlier chapters.

In Chapter 7, the contributions of the thesis are outlined and future work is proposed.

# Chapter 2

## Background : Random Variables and their Statistics

This chapter aims to provide an introduction to probability distributions and their statistics which will provide a foundation for the rest of the thesis.

### 2.1 Notation

Table 2.1: Symbol Definitions

Notation	Meaning
$\mathbb{E}[X]$	the expectation of a random variable $X$
$\mathbb{N}$	the set of natural numbers $\{1, 2, 3, \dots\}$
$Pr[E]$	probability of event $E$

Table 2.2: Variable Notation

Notation	Deterministic Variable	Random Variable
$\mathbf{X}$	-	collection of multivariate random vectors
$\mathbf{x}$	constant vector	multivariate random vector
$X$	constant matrix	random scalar
$x$	constant scalar	-

## 2.2 Random Variable Probability Distribution

A continuous random variable  $X$  has a probability density function (or PDF) given by  $f_X$  if

$$\Pr[a \leq X \leq b] = \int_a^b f_X(x) \, dx \quad (2.1)$$

where  $\Pr[\cdot]$  denotes event probability. The PDF has the property that it is non-negative for all  $x$  and the integral under its curve is 1. As an example, the probability density plot for the standard normal distribution (discussed later in Section 2.11.1) is shown in Figure 2.1.

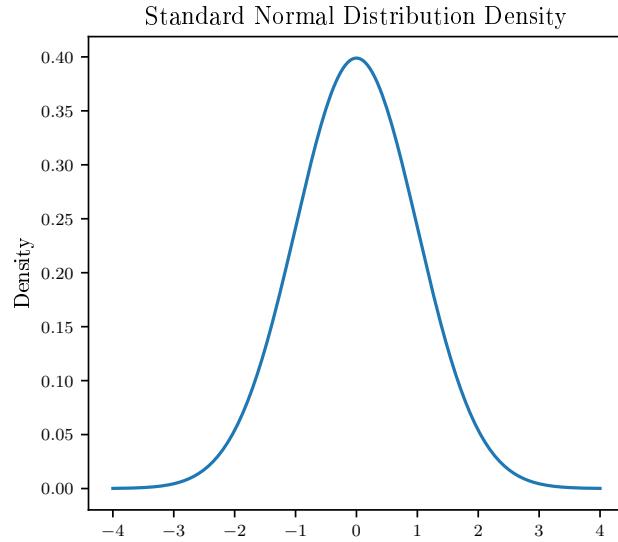


Figure 2.1: Standard Normal Distribution Density

The cumulative probability distribution (or CDF) of  $X$  is given by

$$F_X(x) = \Pr[X \leq x] = \int_{-\infty}^x f_X(t) dt. \quad (2.2)$$

thus if at  $x$  the density  $f_X$  is continuous, then

$$f_X(x) = \frac{d}{dx} F_X(x). \quad (2.3)$$

$F_X(x)$  is a weakly monotonically increasing function of  $X$  with  $0 \geq F(x) \geq 1$  for all  $x$  and  $F(-\infty) = 0$ ,  $F(\infty) = 1$ . The CDF plot for the standard normal distribution is shown in Figure 2.2.

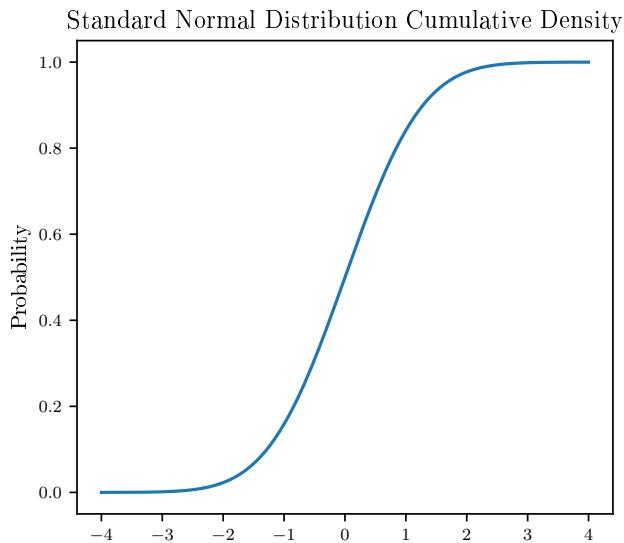


Figure 2.2: Standard Normal Distribution Cumulative Density

## 2.3 Expectations

### 2.3.1 Univariate Expectation

The expectation of a random variable  $X$  is denoted as  $\mathbb{E}(X)$  and given for discrete  $X$  by

$$\mathbb{E}(X) = \sum_x f(x) \quad (2.4)$$

and for continuous  $X$  by

$$\mathbb{E}(X) = \int_{-\infty}^{\infty} xf(x) dx \quad (2.5)$$

where  $f(x)$  is the PDF of  $X$ .

The expectation of a function  $g(X)$  can be inferred from the probability distribution of  $X$  and the function for discrete  $X$  by

$$\mathbb{E}[g(X)] = \sum_x g(x)f(x) \quad (2.6)$$

and for continuous  $X$  by

$$\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x)f(x) dx . \quad (2.7)$$

### 2.3.2 Multivariate Expectation

Extending the expectations in the previous section to the multivariate case, the expectation of a multivariate random vector  $\mathbf{X}$  is given by

$$\mathbb{E}(\mathbf{X}) = \begin{bmatrix} \mathbb{E}(X_1) \\ \mathbb{E}(X_2) \\ \vdots \\ \mathbb{E}(X_n) \end{bmatrix} = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_n \end{bmatrix} . \quad (2.8)$$

Given a function  $g : \mathbb{R}^n \rightarrow \mathbb{R}$ , for discrete  $\mathbf{X}$  the expectation may be written as

$$\mathbb{E}[g(\mathbf{X})] = \sum_{\mathbf{x}} g(\mathbf{x})f(\mathbf{x}) \quad (2.9)$$

or for continuous  $\mathbf{X}$  the expectation is given by

$$\begin{aligned}\mathbb{E}[g(\mathbf{X})] &= \int_{\mathbb{R}^n} g(\mathbf{x})f(\mathbf{x}) d\mathbf{x} \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} g(x_1, x_2, \dots, x_n) f(x_1, x_2, \dots, x_n) dx_1 dx_2 \cdots dx_n.\end{aligned}\tag{2.10}$$

## 2.4 Moments

Moments, used extensively in physics and mathematics, provide quantitative measures of the shapes of functions. Within the realm of physics, the function may represent a physical density where the zeroth moment is the total mass, the first moment divided by the zeroth moment is the center of mass, and the second moment is the rotational inertia. In a statistical context, probability density functions are considered. In this case, the total probability (always exactly one) is the zeroth moment, the first moment is the mean, the second central moment is the variance, the third standardized moment is the skewness, and the fourth standardized moment is the kurtosis. It can be shown that on bounded intervals, the total set of all moments uniquely determine the distribution[17, 39], however in practice the first four moments are the most widely used.

Moment computation on discrete distributions can be expensive if the dataset size is large. While streaming moment computation is possible in some cases, it is useful to have alternative moment computation methods. Cases where streaming moment computation may not be practical include when streams are no longer available or when the moment family does not support online calculation, such as

L-moments. In this chapter, both standard and L-moments (also known as linear moment) will be described. We will derive methods for calculating moments of both types from quantile information with some important assumptions.

### 2.4.1 Standard Moments

Standard moments are commonly defined in three ways : raw, central, and normalized. The  $n$ th raw moment is given by

$$\mu'_n = \mathbb{E}[\mathbf{X}^n] = \int_{-\infty}^{\infty} x^n f(x) dx . \quad (2.11)$$

The  $n$ th central moments are given by

$$\mu_n = \mathbb{E}[(\mathbf{X} - \mu)^n] = \int_{-\infty}^{\infty} (x - \mu)^n f(x) dx, \mu = \mathbb{E}[\mathbf{X}] . \quad (2.12)$$

The  $n$ th normalized (also known as standardized) moment is the  $n$ th central moment divided by  $\sigma^n$  (where  $\sigma$  is the standard deviation) as given by

$$\frac{\mu_n}{\sigma^n} = \frac{\mathbb{E}[(\mathbf{X} - \mu)^n]}{\sigma^n} . \quad (2.13)$$

The named properties of distributions including the mean, standard deviation, skewness and kurtosis can also be defined in terms of the raw, central, and normalized moments as follows :

$$\mu = \mu'_0 \quad (\text{mean}) \quad (2.14)$$

$$\sigma = \sqrt{\mu_1} \quad (\text{standard deviation}) \quad (2.15)$$

$$\gamma = \frac{\mu_2}{\sigma^2} \quad (\text{skewness}) \quad (2.16)$$

$$\kappa = \frac{\mu_3}{\sigma^3} \quad (\text{kurtosis}) . \quad (2.17)$$

## 2.5 Order statistics

The  $k$ th order statistic of a size  $n$  sample from  $\mathbf{x}$ , denoted  $X_{(k)}$ , is the  $k$ th smallest of  $X_1, X_2, \dots, X_n$  iid random variables. Thus  $X_{(1)}$  and  $X_{(n)}$  are the smallest and largest  $X$ , respectively. Meaning that

$$X_{(1)} = \min(X_1, X_2, \dots, X_n) \quad (2.18)$$

$$X_{(n)} = \max(X_1, X_2, \dots, X_n) . \quad (2.19)$$

## 2.6 Expectation of Gaps between Order Statistics

The general formula for the average distance between the  $k$ th and  $(k+1)$ th order statistic of a sample drawn from a random distributed variable  $x$  with cumulative probability density function  $F(x)$  of size  $n$  is given by

$$\frac{n}{(n-k)!k!} \int_{-\infty}^{\infty} F(x)^{n-k} (1-F(x))^k dx . \quad (2.20)$$

This formulation by Karl Pearson[37] was a generalized solution to a problem earlier posed by Galton[11].

### 2.6.1 L-Moments

Introduced by Hosking in 1990, L-moments are so named as they are the construction of linear combinations of order statistics[20, 21] and are measures of the location, scale, and shape of probability distributions or data samples. L-moments are generally known to be more robust than classical moments as they are less sensitive to outliers and often yield more efficient parameter estimates than the maximum likelihood estimates[41]. Data drawn from a wide variety of probability distributions can be effectively characterized by L-moments and unlike product moments, the sampling properties for L-moments statistics are nearly unbiased, even in small samples, and are near normally distributed.

L-moments have various theoretical advantages over the classical moments. For example, for L-moments of a probability distribution to be meaningful, it is only required that the distribution have finite mean, whereas no higher-order moments need be finite. Similarly, in order for the standard errors of L-moments to be finite, only the distribution is required to have finite variance and no higher-order moments need be finite. L-moments also give asymptotic approximations to sampling distributions better than classical moments and provide better identification of the

parent distribution which generated a particular data sample.

First 4 L-moments are defined as follows :

$$\lambda_1 = \mathbb{E}[\mathbf{X}] \quad (2.21)$$

$$\lambda_2 = (\mathbb{E}[\mathbf{X}_{2:2}] - \mathbb{E}[\mathbf{X}_{1:2}])/2 \quad (2.22)$$

$$\lambda_3 = (\mathbb{E}[\mathbf{X}_{3:3}] - 2\mathbb{E}[\mathbf{X}_{2:3}] + \mathbb{E}[\mathbf{X}_{1:3}])/3 \quad (2.23)$$

$$\lambda_4 = (\mathbb{E}[\mathbf{X}_{4:4}] - 3\mathbb{E}[\mathbf{X}_{3:4}] + 3\mathbb{E}[\mathbf{X}_{2:4}] - \mathbb{E}[\mathbf{X}_{1:4}])/4 \quad (2.24)$$

where  $\mathbf{X}_{k:n}$  denotes the  $k$ th order statistic in a independent sample of size  $n$  from the distribution of  $\mathbf{X}$ .

The named properties of L-moments include Mean, L-Cv, L-Skewness, and L-Kurtosis, are defined as follows :

$$\mu_L = \lambda_1 \quad (\text{mean}) \quad (2.25)$$

$$\sigma_L = \lambda_2 \lambda_1 \quad (\text{L-Cv}) \quad (2.26)$$

$$\gamma_L = \frac{\lambda_3}{\lambda_2} \quad (\text{L-skewness}) \quad (2.27)$$

$$\kappa_L = \frac{\lambda_4}{\lambda_2} \quad (\text{L-kurtosis}) . \quad (2.28)$$

In Hosking's work, the continuous L-moments are defined in terms of the CDF as follows

$$\lambda_1 = \int_0^1 x(F) dF = \int_{-\infty}^{\infty} xf(x) dx \quad (2.29)$$

$$\lambda_2 = \int_0^1 x(F)(2F - 1) dF = \int_{-\infty}^{\infty} x(2F(x) - 1) f(x) dx \quad (2.30)$$

$$\lambda_3 = \int_0^1 x(F)(6F^2 - 6F + 1) dF \quad (2.31)$$

$$\lambda_4 = \int_0^1 x(F)(20F^3 - 30F^2 + 12F - 1) dF . \quad (2.32)$$

In terms of the independent random variable  $x$ , these can be redefined as follows

$$\lambda_1 = \int_{-\infty}^{\infty} xf(x) dx \quad (2.33)$$

$$\lambda_2 = \int_{-\infty}^{\infty} x(2F(x) - 1) f(x) dx \quad (2.34)$$

$$\lambda_3 = \int_{-\infty}^{\infty} x(6F(x)^2 - 6F(x) + 1) f(x) dx \quad (2.35)$$

$$\lambda_4 = \int_{-\infty}^{\infty} x(20F(x)^3 - 30F(x)^2 + 12F(x) - 1) f(x) dx . \quad (2.36)$$

The sample L-moments  $L_i$ , estimates of  $\lambda_i$ , can be computed as follows

$$L_1 = \frac{1}{n} \sum_{j=1}^n x_j \quad (2.37)$$

$$L_2 = \frac{1}{n} \sum_{j=2}^n x_j \frac{j-1}{n-1} \quad (2.38)$$

$$L_3 = \frac{1}{n} \sum_{j=3}^n x_j \frac{(j-1)(j-2)}{(n-1)(n-2)} \quad (2.39)$$

$$L_4 = \frac{1}{n} \sum_{j=4}^n x_j \frac{(j-1)(j-2)(j-3)}{(n-1)(n-2)(n-3)} . \quad (2.40)$$

## 2.7 Sample Quantiles

There are many different definitions for the sample quantiles in use in the literature and across software packages[22]. In this thesis, the definition provided by Hazen[18] is used as follows:

$$p_k = \frac{k - \frac{1}{2}}{n} \quad (2.41)$$

where  $p_k$  is the quantile value such that  $(\Phi^{-1}(p_k), X_{(k)})$  for  $1 \leq k \leq n$  comprise the points drawn on a standard QQ plot.

## 2.8 Confidence Intervals for Binomial Proportions

The two-sided Clopper-Pearson interval[7, 40] is an inversion of the equal-tailed binomial test for a proportion  $p$ . Hence for a confidence level  $\alpha$ , the interval contains all values of  $p$  which are not rejected by the test. The lower and upper limits of the interval, denoted  $p_L$  and  $p_U$  respectively, can be computed in terms of the beta distribution:

$$p_L = \beta(\alpha/2, k, n - k + 1) \quad (2.42)$$

$$p_U = \beta(1 - \alpha/2, k + 1, n - k) . \quad (2.43)$$

Applying this confidence interval to the uniform sample distribution of the same size of the sample set drawn from any distribution  $X$  allows for the construction of

confidence intervals around the order statistics of sample of  $X$ , which will be shown in the next section.

## 2.9 QQ Plots

Another useful representation of the cumulative distribution function is the Quantile-Quantile (or QQ) plot. The QQ plot shows the data quantile versus a reference distribution quantile, usually the standard normal distribution quantile. For this reason, normally distributed data appears as a straight line on a QQ plot, see Figure 2.3. Because the standard normal quantile axis is linear in sigma, there is an emphasis on the data quantile tails and a de-emphasis on the region far from the tails.

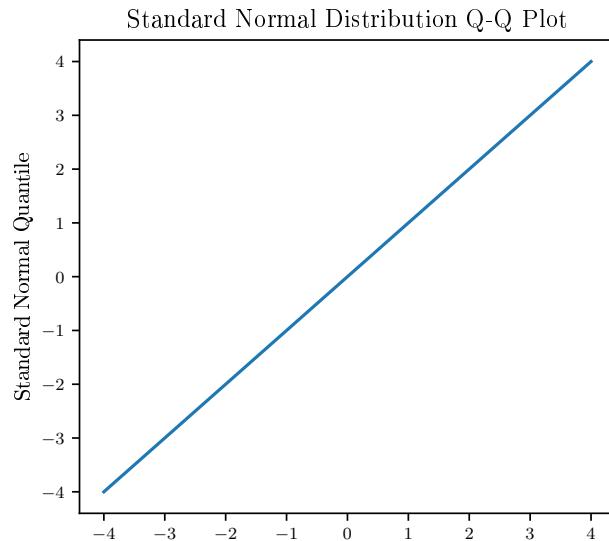


Figure 2.3: Standard Normal Distribution Q-Q Plot

It is also useful to show an axis opposite the standard normal axis which shows the probability as shown in Figure 2.4. Since the standard normal quantile axis is linear, the probability axis has a probit scale. From another perspective, the QQ plot is the CDF plot with a probit probability scale replacing the linear probability scale.

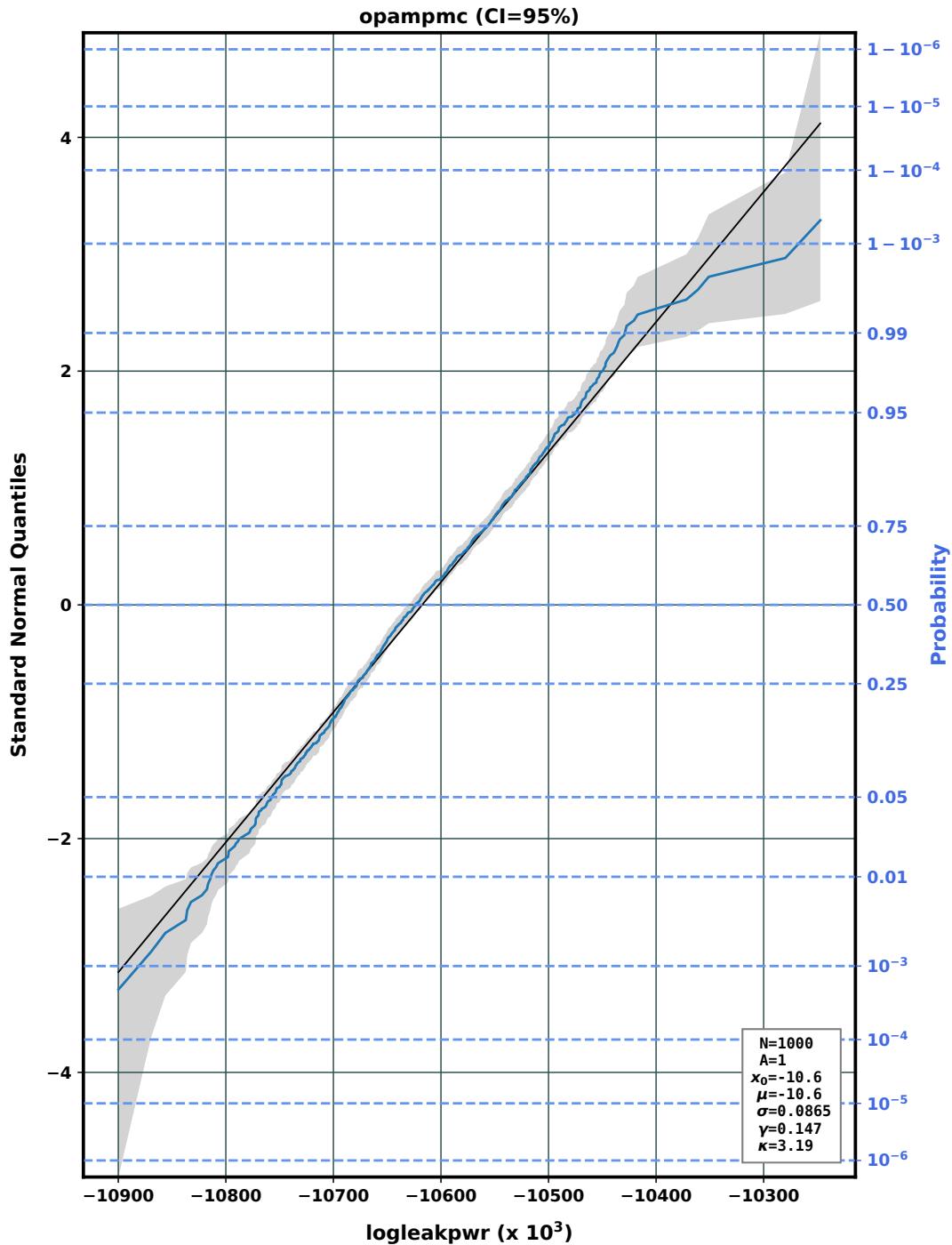


Figure 2.4: Example Production QQ Plot

According to style, the data quantile may appear on either the X or Y axis. Our convention is to use the X axis for the data quantile as it is then directly comparable to the corresponding probability density function plot, in which the data quantile also appears on the X axis. If  $n$  samples are drawn from an arbitrary random distribution, the confidence interval of the  $k$ th order statistic is described in Section 2.8 which is shown in the gray shaded region around the blue QQ curve in Figure 2.4.

## 2.10 Error Function

Because the error function is linked strongly to the normal distribution and the normal distribution will be used in the formulation of quantile based moment calculation in Chapter 5, a brief review of the error function is provided in this section. The error function, denoted by  $\text{erf}(\cdot)$  is a non-elementary function utilized by the cumulative distribution function of the normal distribution given by

$$\Phi = \frac{1}{2} \left[ 1 + \text{erf} \left( \frac{x - \mu}{\sigma\sqrt{2}} \right) \right]. \quad (2.44)$$

Though the concept of the error function were known since at latest 1808 when Adrain and Gauss independently developed the formula for the normal distribution, it was J. W. L. Glaisher who first proposed the name for the error function. In 1871 he wrote, “As it is necessary that the function should have a name, and as I do not know that any has been suggested, I propose to call it the Error-function, on account of its earliest and still most important use being in connexion[sic] with the

theory of Probability and notably the theory of Errors...”[12]. The error function, in its standardized form, is defined as

$$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt . \quad (2.45)$$

In Glashier’s work, many of the properties of the error function such as first order derivatives and integrals of it and related functions were provided. Much more has been described of the error function since this time and higher order derivatives as well as some higher order integrals are available in common mathematical texts[1, 14]. For example, the  $k$ th order derivative of the error function is given in closed form by

$$\text{erf}^{(k)}(x) = \frac{2(-1)^{k-1}}{\sqrt{\pi}} H_{k-1}(x) e^{-x^2} = \frac{2}{\sqrt{\pi}} \frac{d^{k-1}}{dx^{k-1}} \left( e^{-x^2} \right), k \in \mathbb{N} \quad (2.46)$$

where  $H_k(x)$  is a Hermite polynomial. On the other hand, no general formulae are readily available for integrals of the error function above the third order. A proposal for a general formula for the integral of powers of the error function is given in Appendix A.

## 2.11 Selected Probability Distributions

The probability distributions discussed in this section are either utilized in subsequent theory discussion and/or are utilized as the basis for theoretical examples in following chapters. In particular, the normal and chi-square distributions will later be discussed in the context of formulating a novel sampling method. The normal

distribution will then again be used in the proposal of a method of moment calculation using quantile information. The beta distribution will be utilized in its relation to the margin distribution of the multivariate standard normal distribution conditioned on origin distance. The remaining distributions outlined in this section are used for empirical experiments, where differing moment computation methods are compared across selected probability distributions.

### 2.11.1 Normal distribution

The process variation in modern semiconductor device models are exclusively based on the normal distribution (also known as the Gaussian distribution). For this reason, the normal distribution will be the probability distribution of focus for much of the thesis, though other distributions will be used and introduced for machine learning or for describing certain statistical relationships with respect to the normal.

The normal distribution has a cumulative distribution function given by

$$\Phi(x) = \frac{1}{2} \left[ 1 + \operatorname{erf} \left( \frac{x - \mu}{\sigma\sqrt{2}} \right) \right] \quad (2.47)$$

where  $\mu$  is the mean,  $\sigma$  is the standard deviation, and  $\operatorname{erf}(\cdot)$  is the error function, studied in more detail in Section 2.10. The probability density function of the normal distribution is given by

$$\phi(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} . \quad (2.48)$$

The density and QQ plots of the normal distribution are shown in Figure 2.5.

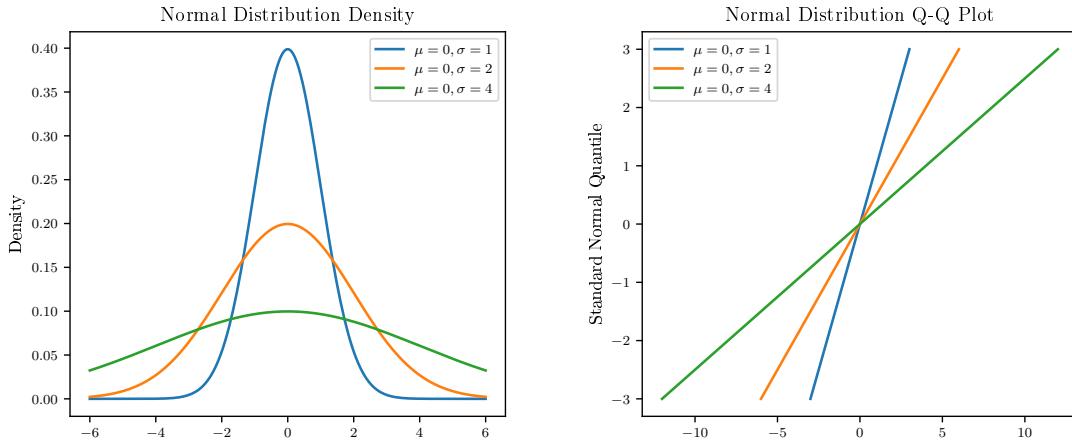


Figure 2.5: Normal Distribution Density and QQ Plot

### 2.11.2 Chi-squared distribution

This chi-square distribution is important as it is the sum of squares of normal variates. Its probability density function is given by

$$f(x) = \frac{1}{2^{k/2}\Gamma(k/2)} x^{k/2-1} e^{-x/2}. \quad (2.49)$$

The cumulative density function is given by

$$F(x) = \frac{1}{\Gamma(k/2)} \gamma\left(\frac{k}{2}, \frac{x}{2}\right) \quad (2.50)$$

where  $\gamma(s, t)$  is the lower incomplete gamma function given by

$$\gamma(s, x) = \int_0^x t^{s-1} e^{-t} dt. \quad (2.51)$$

The density and QQ plots of the chi-square distribution are shown in Figure 2.6.

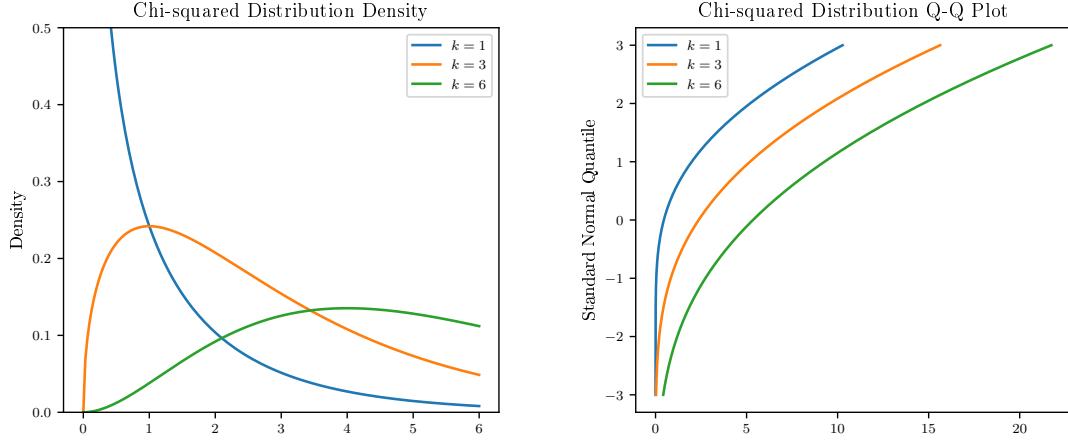


Figure 2.6: Chi-square Distribution Density and QQ Plot

### 2.11.3 Beta distribution

The probability density function is given by

$$f(x) = \frac{x^{\alpha-1}(1-x)^{\beta-1}}{B(\alpha, \beta)} \quad (2.52)$$

where

$$B(\alpha, \beta) = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha + \beta)} \quad (2.53)$$

$$\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt. \quad (2.54)$$

The cumulative density function is given by the regularized incomplete beta function  $I_x$  as

$$F(x) = I_x(\alpha, \beta) = \frac{B(x; \alpha, \beta)}{B(\alpha, \beta)} \quad (2.55)$$

where  $B(x; a, b)$  is the incomplete beta function given by

$$B(x; a, b) = \int_0^x t^{a-1} (1-t)^{b-1} dt. \quad (2.56)$$

The density and QQ plots of the beta distribution are shown in Figure 2.7.

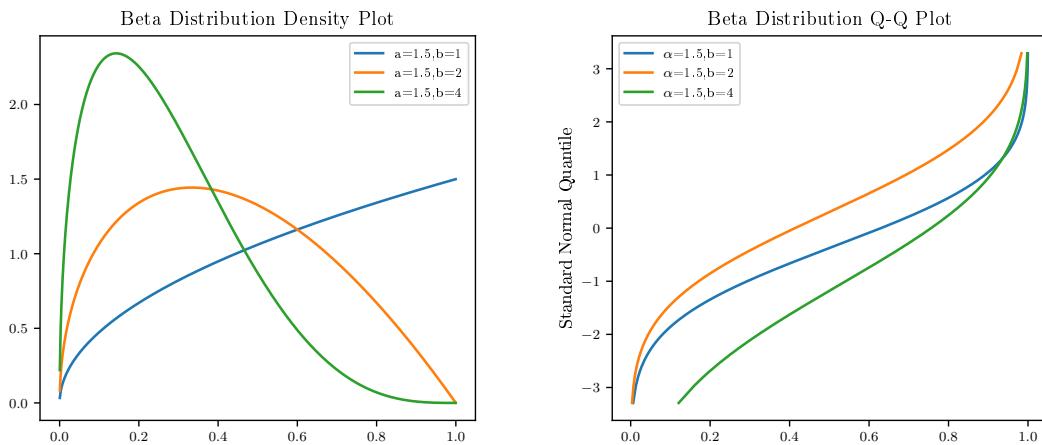


Figure 2.7: Beta Distribution Density and QQ Plot

#### 2.11.4 Log-normal distribution

The log-normal distribution is used quite extensively across many fields[2, 28, 32], having probability density function given by

$$f(x) = \frac{1}{x\sigma\sqrt{2\pi}} \exp\left(-\frac{(\ln x - \mu)^2}{2\sigma^2}\right). \quad (2.57)$$

The cumulative density function is given by

$$F(x) = \frac{1}{2} + \frac{1}{2} \operatorname{erf} \left[ \frac{\ln x - \mu}{\sqrt{2}\sigma} \right]. \quad (2.58)$$

The density and QQ plots of the log-normal distribution are shown in Figure 2.8.

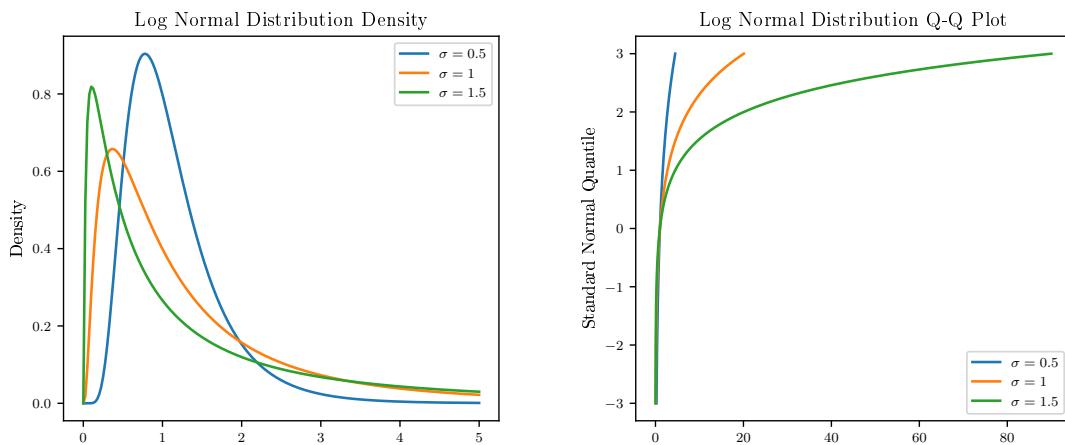


Figure 2.8: Log-normal Distribution Density and QQ Plot

### 2.11.5 Skew Normal distribution

The skew normal distribution[3] has the probability density function given by

$$f(x) = \frac{2}{\omega\sqrt{2\pi}} e^{-\frac{(x-\xi)^2}{2\omega^2}} \int_{-\infty}^{\alpha(\frac{x-\xi}{\omega})} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt \quad (2.59)$$

The cumulative density function is given by

$$F(x) = \Phi\left(\frac{x - \xi}{\omega}\right) - 2T\left(\frac{x - \xi}{\omega}, \alpha\right) \quad (2.60)$$

where  $T(h, a)$  is the Owen's T function[35]. The density and QQ plots of the skew normal distribution are shown in Figure 2.9.

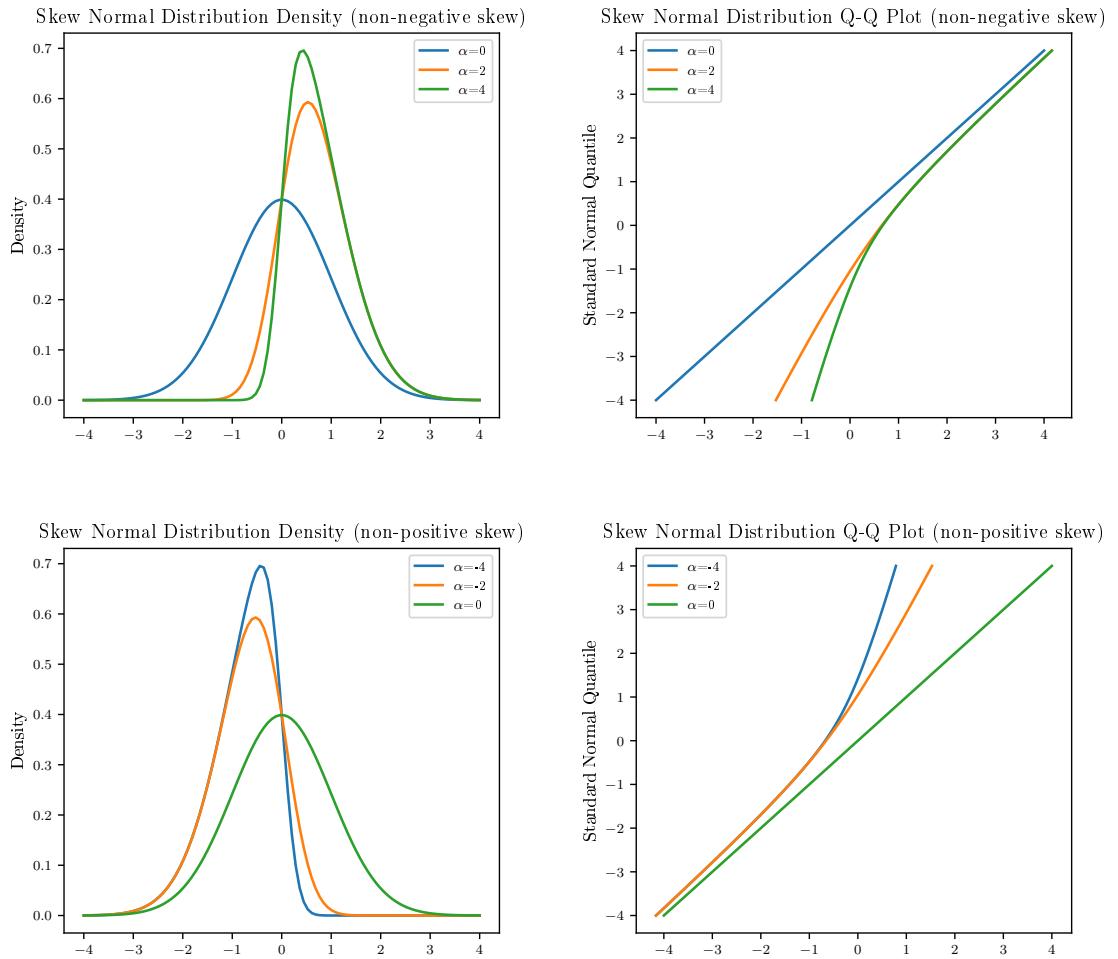


Figure 2.9: Skew Normal Distribution Density and QQ Plot with  $\xi = 0$  and  $\omega = 1$

### 2.11.6 Weibull distribution

The probability density function is given by

$$f(x) = \begin{cases} \frac{k}{\lambda} \left(\frac{x}{\lambda}\right)^{k-1} e^{-(x/\lambda)^k} & x \geq 0 \\ 0 & x < 0 \end{cases}. \quad (2.61)$$

The cumulative density function is given by

$$F(x) = \begin{cases} 1 - e^{-(x/\lambda)^k} & x \geq 0 \\ 0 & x < 0 \end{cases}. \quad (2.62)$$

The density and QQ plots of the Weibull distribution are shown in Figure 2.10.

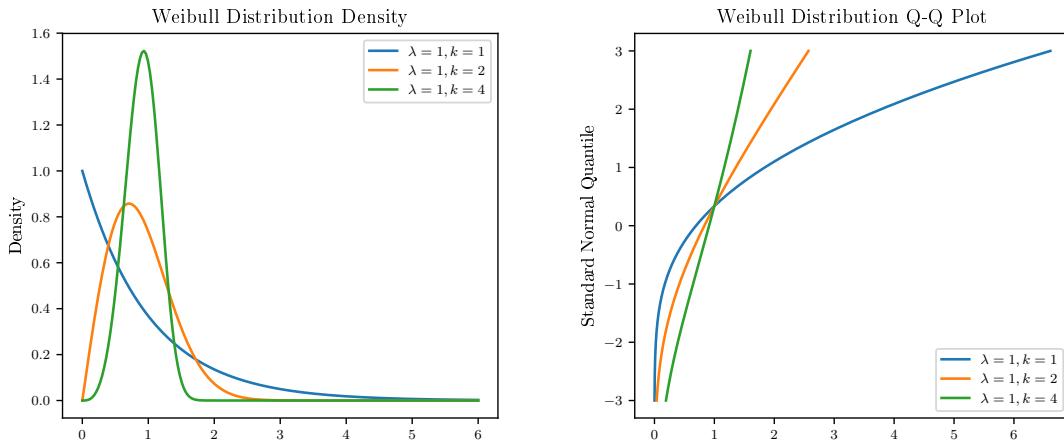


Figure 2.10: Weibull Distribution Density and QQ Plot

### 2.11.7 Student's t distribution

The probability density function is given by

$$f(x) = \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}. \quad (2.63)$$

The cumulative density function is given by

$$F(x) = \frac{1}{2} + x\Gamma\left(\frac{\nu+1}{2}\right) \frac{{}_2F_1\left(\frac{1}{2}, \frac{\nu+1}{2}; \frac{3}{2}; -\frac{x^2}{\nu}\right)}{\sqrt{\pi\nu}\Gamma\left(\frac{\nu}{2}\right)} \quad (2.64)$$

where  ${}_2F_1$  is the hypergeometric function.

The density and QQ plots of the Student's t distribution are shown in Figure 2.11.

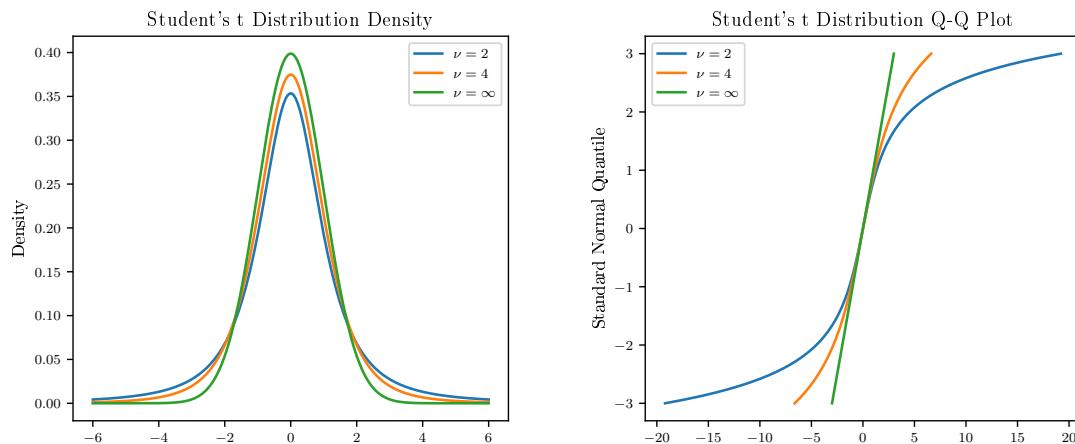


Figure 2.11: Student's t Distribution Density and QQ Plot

# Chapter 3

## Monte Carlo Sampling Techniques

### 3.1 Monte Carlo Simulation

A simple random sample is meant to be an unbiased representation of a group. Specifically, a simple random sample is a subset of a statistical population in which each member of the subset has an equal probability of being chosen. The process of choosing simple random samples is called Simple Random Sampling (SRS). For nearly all Monte Carlo simulation performed in the realm of circuit simulation, SRS is employed based on the multivariate standard normal distribution. Simple Random Sampling with  $N(0,1)$ , which denotes a normal distribution with mean 0 and variance 1, produces a majority of samples near the origin as shown in Figure 3.1.

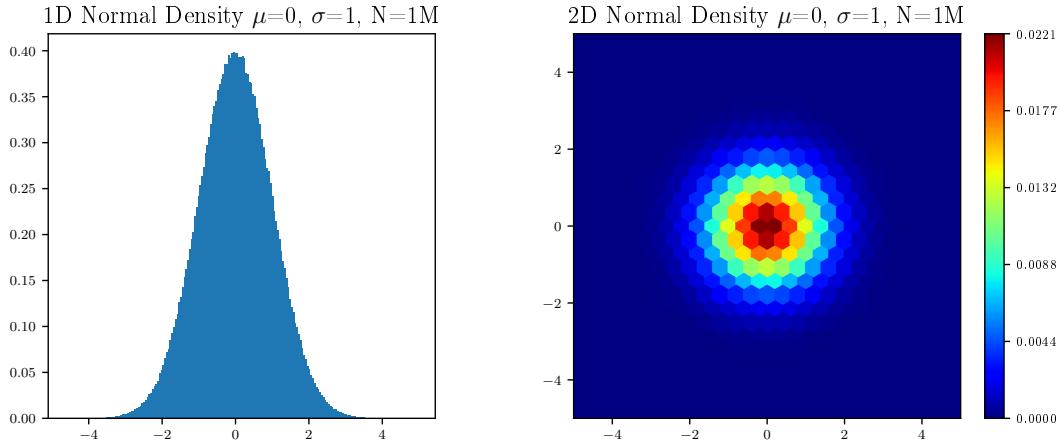


Figure 3.1: One and two dimensional density plots of 1M normal samples with mean=0 and standard deviation=1

The right plot of Figure 3.1 is called a hexbin plot. Hexbin plots are useful for providing a graphical representation of the 2D densities or 2D histograms. This hexbin plot shows the density of the bivariate standard normal distribution, where each axis represents one dimension of that distribution.

## 3.2 Motivation for Rare Sample Simulation

For arbitrary functions of normal random variables, it does not follow that rare samples in the input space tend to correspond with rare samples in the output space. As a counter example, consider the function  $Y = X^2$  where  $X \sim N(0, 1)$ . The smallest values of  $Y$  (left tail of its distribution) occur when  $X$  is near zero where the PDF of  $X$  is most dense.

However, for monotone functions of normal random variables, there is a correspondence between rare samples in the input and rare samples in the output. Specifically, for a non-decreasing monotone function  $g(x)$  it is true that

$$x \leq x' \Rightarrow g(x) \leq g(x')$$

while for a non-increasing monotone function  $h(x)$  it can also be said that

$$x \geq x' \Rightarrow h(x) \geq h(x') .$$

To extend this notion to higher dimension multivariate functions, let  $\preceq$  be the element-wise inequality on  $\mathbb{R}^n$  ( $x \preceq y$  if and only if  $x_i \leq y_i \forall i$ ). Using this notation, a function  $g : \mathbb{R}^n \mapsto \mathbb{R}$  is monotone with respect to this partial ordering if

$$x \preceq y \Rightarrow f(x) \leq f(y) .$$

This is equivalent to requiring

$$f(x) \leq f(x + \gamma e_i) \quad \forall x \in \mathbb{R}^n, \gamma \geq 0, \text{ and } i \in \{1, 2, \dots, n\},$$

where  $\{e_1, \dots, e_n\}$  is the standard basis for  $\mathbb{R}^n$ .

In this case, the rare samples in the input space correspond to rare samples in the output space. Measures used in circuit simulation often satisfy this multivariate monotonicity property, as shown later in Section 6.2. If not only the monotone property holds, but we also assume linearity (which is a reasonable approximation in many cases) then additional properties of the distribution can be derived as shown in the following section.

### 3.3 Linear Forms of Standard Normal Random Vectors

In the previous section, motivation for rare sample simulation was provided based on the commonality of monotonic behavior of the circuit response. As a special case of a linear response, the nature of the posterior functional probability density given distance of the multivariate normal input can be described exactly.

Let  $Z$  be a sample from an uncorrelated multivariate normal distribution

$$Z \sim N(0, I_d) .$$

The sum of squares of the elements of  $Z$  are distributed according to the  $\chi^2$  distribution

$$X = \sum_{i=1}^d Z_i^2 \implies X \sim \chi_d^2 .$$

Define the linear map  $Y$  of  $Z$  with vector  $w$  and constant  $\mu$  as

$$Y = Zw + \mu .$$

If a beta-distributed random variable  $B$  is defined as

$$B \sim \beta\left(\frac{d-1}{2}, \frac{d-1}{2}\right)$$

then the marginal distribution  $Y$  given a fixed value  $x$  for  $X$  is given by

$$(Y|X = x) = x\|w\|_2 \left( B - \frac{1}{2} \right) + \|\mu\|_2 .$$

### 3.3.1 Empirical Verification

In these experiments, 10M samples are drawn from a multivariate normal distributions of dimension  $d$ , for  $d \in [2, 3, 4, 5, 50, 500]$  and the samples are then multiplied by the simple linear map  $I_d$

$$Y = ZI_d, Z \sim N(0, I_d) .$$

From Section 3.3, the normalizing factor  $m$  was calculated as

$$m = 2\sqrt{d}F_{\chi^2}^{-1}\left(\frac{1}{2}, d\right) .$$

In Figure 3.2, the red curves show the probability density functions of  $\beta(\frac{d-1}{2}, \frac{d-1}{2})$ , while the blue histograms of  $\hat{B}$  represent empirical samples

$$\hat{B} = \frac{Y + m}{2m} .$$

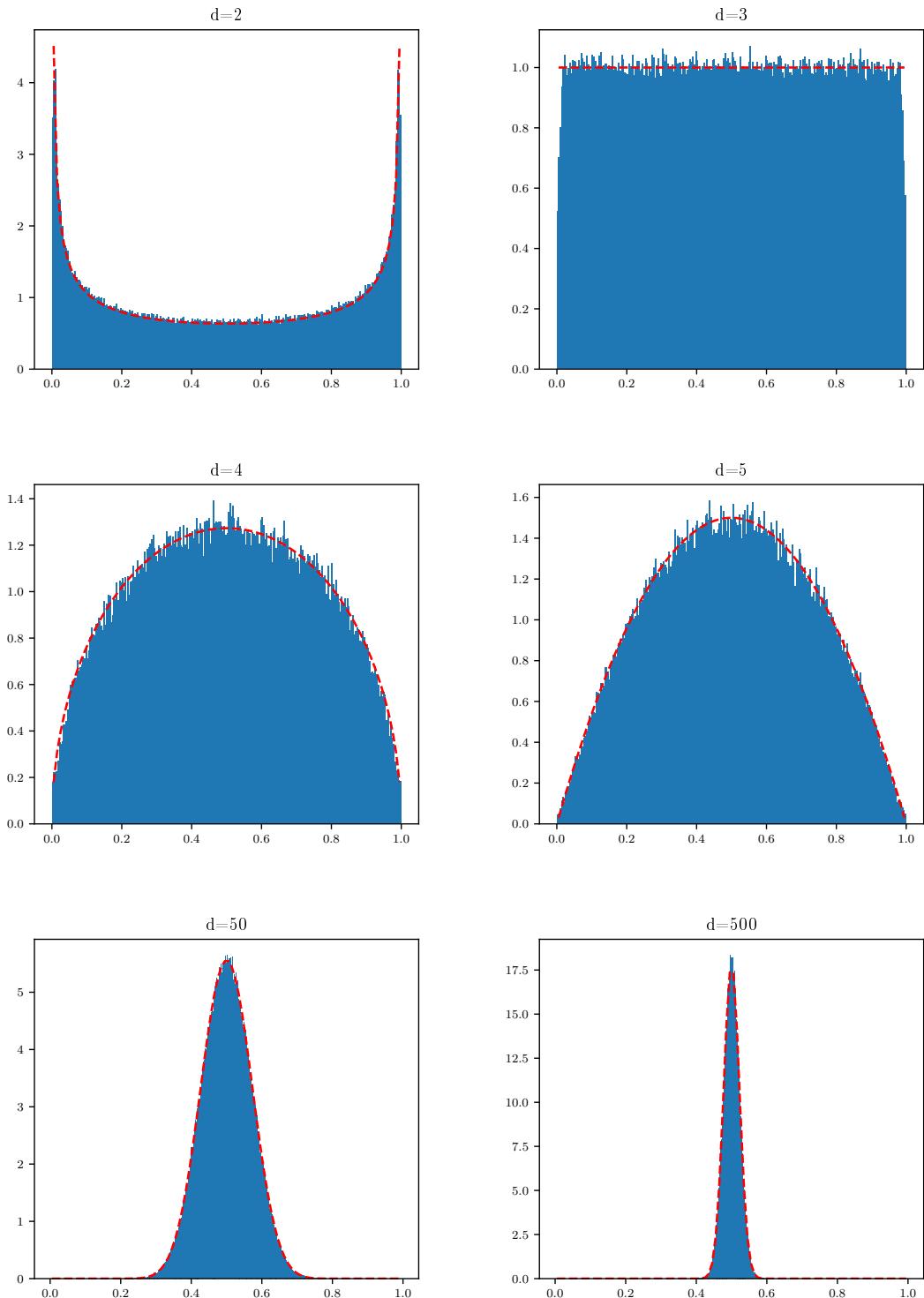


Figure 3.2: Multivariate Normal Conditioned on Vector Norm

### 3.4 Statistics of the Linear Form

It is well known that a linear form of independent normal random variables is normally distributed. Consider a linear form of  $n$  independent standard normal random variables as follows:

$$\mathbf{y} = \sum_{i=1}^n a_i \mathbf{x}_i \quad (3.1)$$

where  $a_1, a_2, \dots, a_n$  are constants. If the means and variances of  $\mathbf{x}_i$  are given by  $\mu_i$  and  $\sigma_i^2$ , respectively then the mean and variance of  $\mathbf{y}$  are given by

$$\mu_{\mathbf{y}} = \sum_{i=1}^n a_i \mu_i , \quad (3.2)$$

$$\sigma_{\mathbf{y}}^2 = \sum_{i=1}^n a_i^2 \sigma_i^2 . \quad (3.3)$$

Further, if each  $\mathbf{x}_i$  is standard normal ( $\mu_i = 0$  and  $\sigma_i = 1 \forall i$ ), then the mean and variance of  $\mathbf{y}$  is given by

$$\mu_{\mathbf{y}} = 0 , \quad (3.4)$$

$$\sigma_{\mathbf{y}}^2 = \sum_{i=1}^n a_i^2 . \quad (3.5)$$

### 3.5 Monte Carlo Sampling for Machine Learning

Samples drawn from  $N(0, k)$  with  $k > 1$  are shifted further from the origin, however the sample distribution is still concentrated at the origin as shown in Figure 3.3.

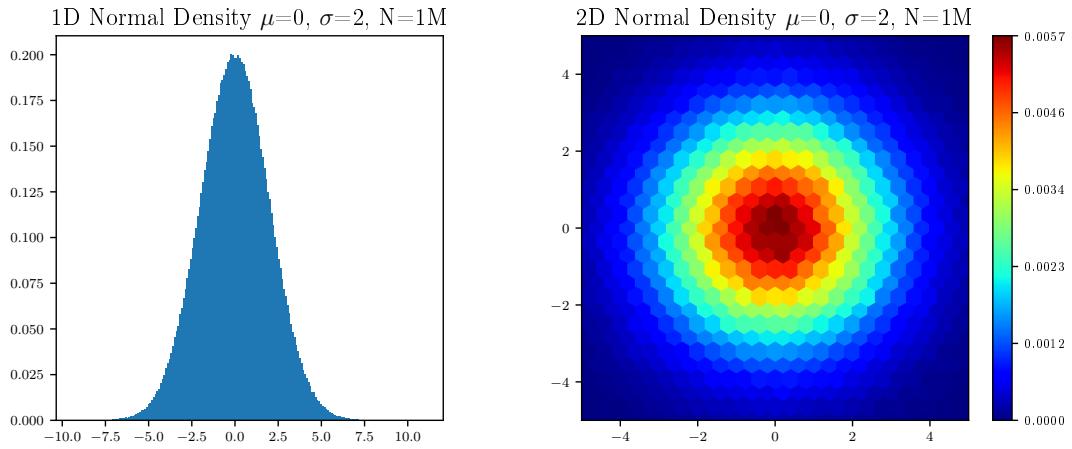


Figure 3.3: One and two dimensional density plots of 1M normal samples with mean=0 and standard deviation=2

Using a uniform distribution, as shown in Figure 3.4,

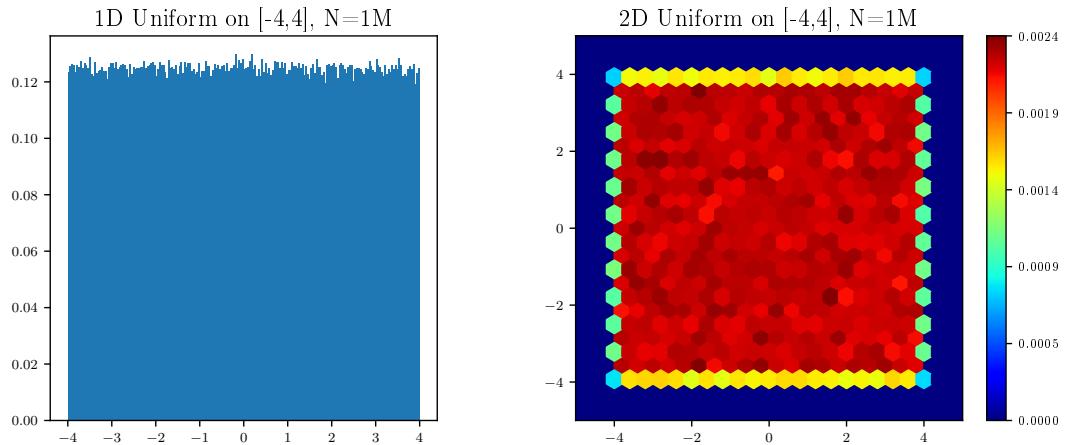


Figure 3.4: One and two dimensional density plots of 1M uniform samples on the interval  $[-4,4]$

Figure 3.5 shows the 2D projection of the 5D multivariate standard normal and uniform distributions, respectively. Because these distributions are joint normal and joint uniform, respectively, these figures closely resemble the 2D densities of Figures 3.1 and 3.4.

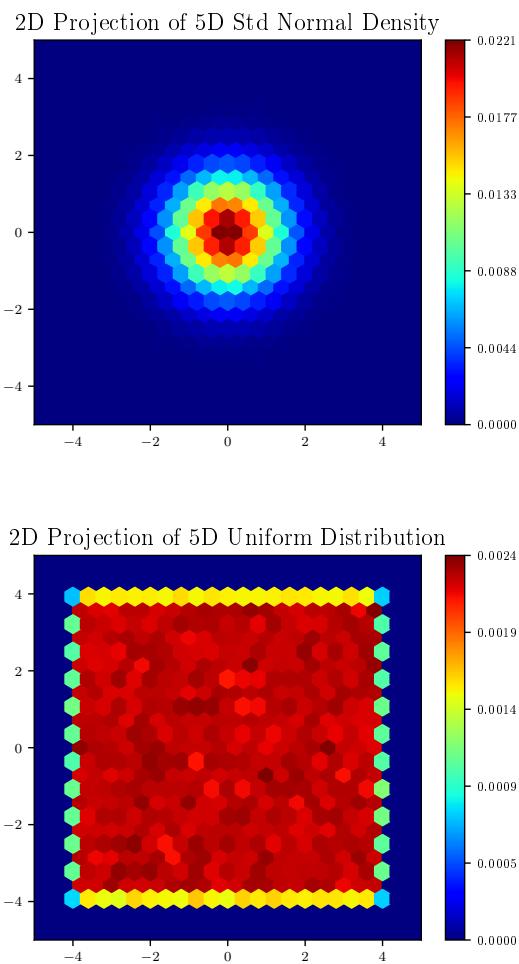


Figure 3.5: 2D Projections of 5D standard normal and uniform distributions

### 3.5.1 Uniform Sampling in High Dimensions

Drawing from the uniform distribution on the interval  $[-5,5]$  in a high dimension  $d$  can also be thought of as drawing from a uniform hypercubical volumetric probability density distribution of dimensions  $10^d$  centered at the origin. This uniform distribution, when sampled in high dimensions, draws samples which are often too improbable for practical statistical purpose (though importantly, they still may be useful for certain machine learning applications). To see the statistical challenges in sampling from the uniform in high dimensions for probability distributions of the multivariate normal, suppose samples are drawn in 300 dimensional space from both the uniform on  $[-5,5]$  and normal distribution with 1D density projections shown in Figure 3.6.

Figures 3.7 and 3.8 illustrate the distance from the origin and effective sigma value for normal and uniform distributions sampled in this 300 dimensional space, respectively. Note that the majority of the probability density exceeds 30 sigma for the uniform distribution in blue found in Figure 3.8. For reference, a 30 sigma events occur at a probability level of 1 in  $2 \times 10^{197}$ . In comparison, the estimated number of elementary particles in the known universe is  $10^{86}$ . For most practical purposes, such low probability events need not be considered and this is certainly true for circuit simulation where typically 6-7 sigma or perhaps even 8 sigma is considered the upper end of high sigma simulation.

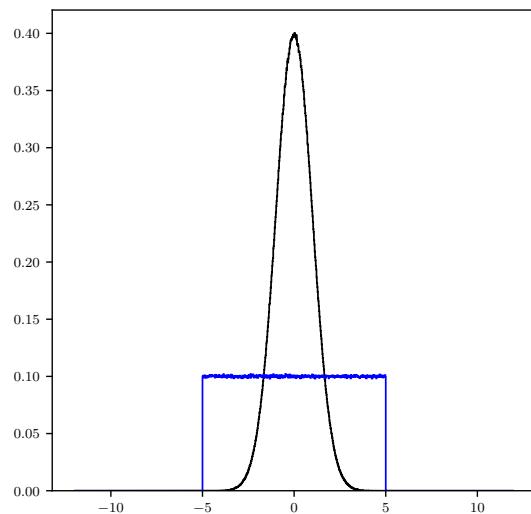


Figure 3.6: One dimensional projections of the normal and uniform distributions drawn from a 300 dimensional space

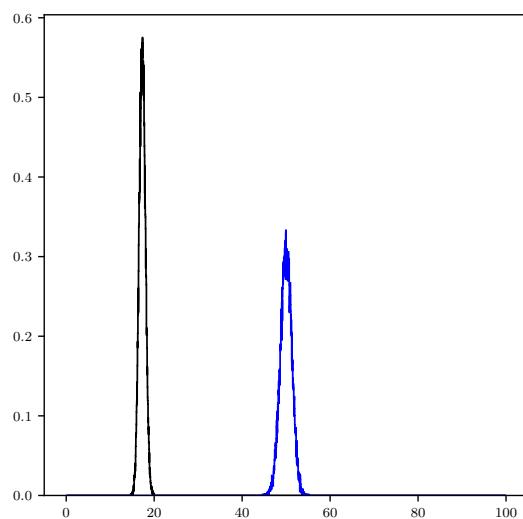


Figure 3.7: The distance from the origin of the normal and uniform distributions drawn from a 300 dimensional space

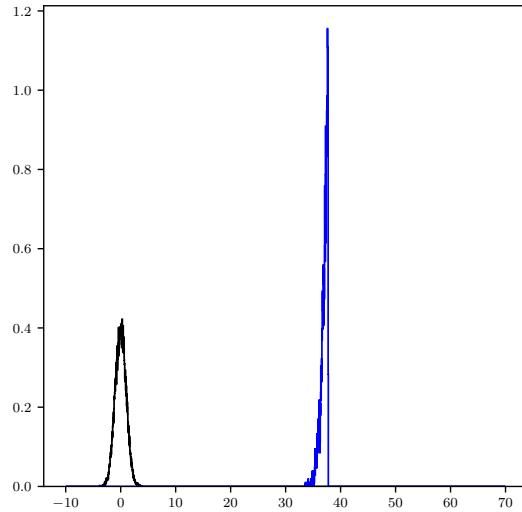


Figure 3.8: The effective value of sigma of the normal and uniform distributions drawn from a 300 dimensional space

### 3.5.2 Hyperspherical Uniform Volumetric Sampling

To avoid the issue of drawing highly improbable samples, samples can be drawn[16] uniformly from the volume of a hypersphere with radius  $r$ . In one and two dimensions, as shown in Figure 3.9, this equates to drawing from a uniform interval  $[-r, r]$  and from the area contained within the circle of radius  $r$ , respectively. In 3 or more dimensions, samples are drawn uniformly from the volume enclosed in the sphere or hypersphere, respectively. Algorithm 1 shows the steps of drawing samples from a hypersphere of dimension  $d$  uniformly.

An improvement of Algorithm 1 is given by Algorithm 2, where one fewer random

---

**Algorithm 1** Hyperspherical Uniform Volumetric Sampling Steps (d+1 RVs per sample)

---

1. Draw  $N$  joint standard normal random vectors each of length  $d$ , call each vector  $\mathbf{x}_i$
  2. For each vector  $\mathbf{x}_i$ , let  $s_i$  be the square of its distance from the origin
  3. Draw  $N$  uniform random variables on  $(0, 1)$ , call values  $u_i$
  4. Hyperspherical Uniform Volumetric samples  $\mathbf{Z}$  are given by  $\mathbf{z}_i = \mathbf{x}_i u_i^{\frac{1}{d}} / \sqrt{s_i}$
- 

variable is required per sample. This is because  $s_i$  can be utilized not only for normalization as in Algorithm 1, but its value can be again leveraged as a new random variable from which  $u_i$  can be calculated (by  $F_{\chi^2}$ , i.e. the CDF of the chi-squared distribution) rather than drawn independently.

---

**Algorithm 2** Volumetric Uniform Sampling Steps (Revised, d RVs per sample)

---

1. Draw  $N$  joint standard normal random vectors each of length  $d$ , call each vector  $\mathbf{x}_i$
  2. For each vector  $\mathbf{x}_i$ , let  $s_i$  be the square of its distance from the origin
  3. Calculate  $\mathbf{u}$  by  $u_i = \gamma(\frac{d}{2}, \frac{s_i}{2})/\Gamma(\frac{d}{2}) = F_{\chi^2}(s_i, d)$
  4. Volumetric uniform samples  $\mathbf{Z}$  are given by  $\mathbf{z}_i = \mathbf{x}_i u_i^{\frac{1}{d}} / \sqrt{s_i}$
-

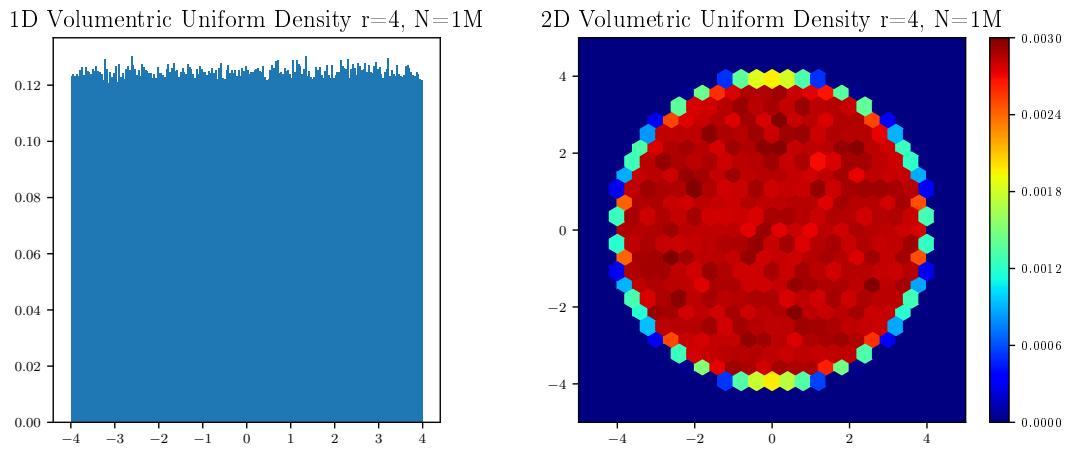


Figure 3.9: One and two dimensional density plots of 1M uniform samples on the interval  $[-4,4]$

Scatter plots of the four distributions discussed are shown in Figure 3.10.

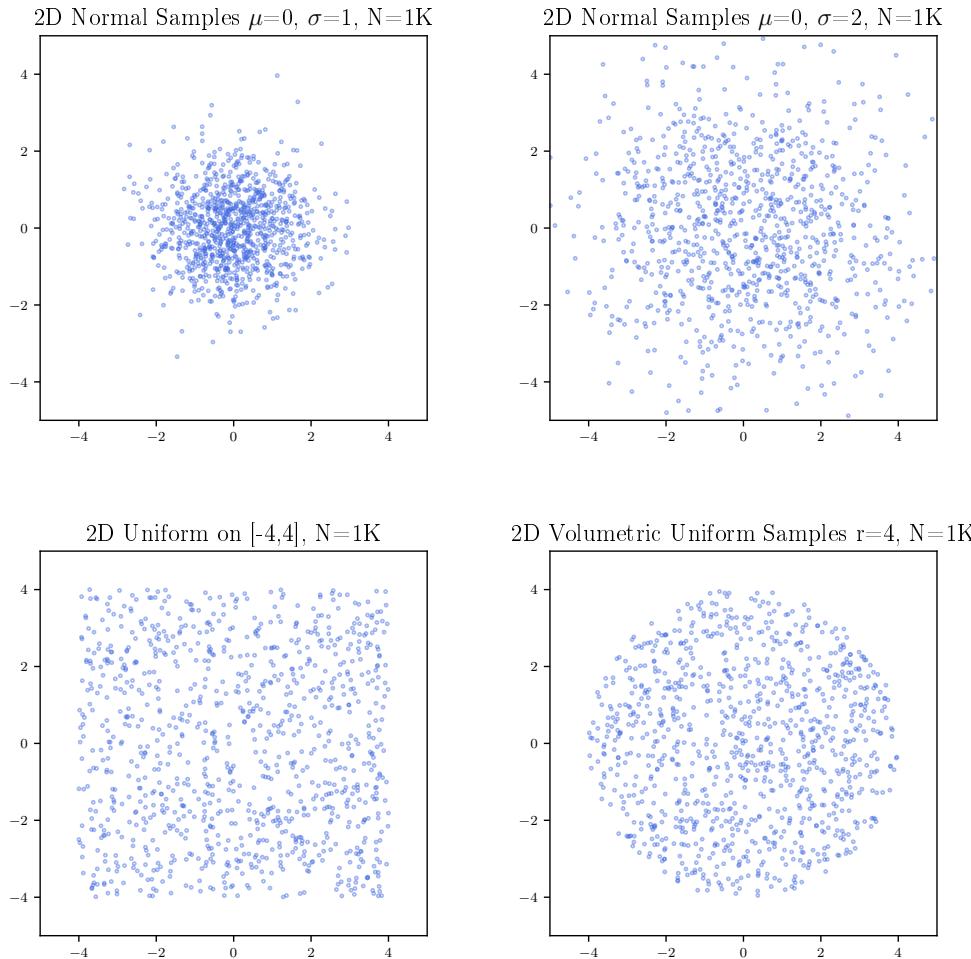


Figure 3.10: Two dimensional scatter plots of 1K samples of normal, uniform, and Hyperspherical Uniform Volumetric samples

## 3.6 Rejection Sampling

Rejection sampling is a method to simulate random samples from a target distribution which is unknown or difficult from which to sample by using random samples

from a similar, more convenient distribution. A random subset of the generated samples are rejected while the rest are accepted, by the so-called accept-reject criteria. Often the end goal is for the accepted samples to be distributed as if they were from the target distribution.

The canonical example of rejection sampling is to estimate the value of  $\pi$ . This is done by sampling uniformly on the unit square, accepting the values which meet the criteria  $x^2 + y^2 \leq 1$ . Then, noting that the ratio of the area of the circle to the square is  $\pi/4$ , the value of  $\pi$  is estimated by 4 times the number of accepted samples divided by the total samples. A similar method can be used to estimate closed integrals of arbitrary functions. While the accept-reject criteria may be easy to evaluate, the analytic integral may be difficult or impossible to compute directly.

For standard area/volume estimation, the rejection criteria is fixed. However, there are important situations where the rejection criteria is dependent on the samples drawn. Consider the acceptance criteria that accepts exactly the  $k$  largest samples from a random subset of size  $n$ . This problem is similar to the scenario of interest in many engineering problems.

Figure 3.11 shows the example of rejection sampling in 2 dimensions. The lower and upper left plots show the 3K standard normal samples and their corresponding origin distances. In the upper left plot, the origin distances are sorted and all but the furthest 300 samples are rejected, yielding the plot in the lower right.

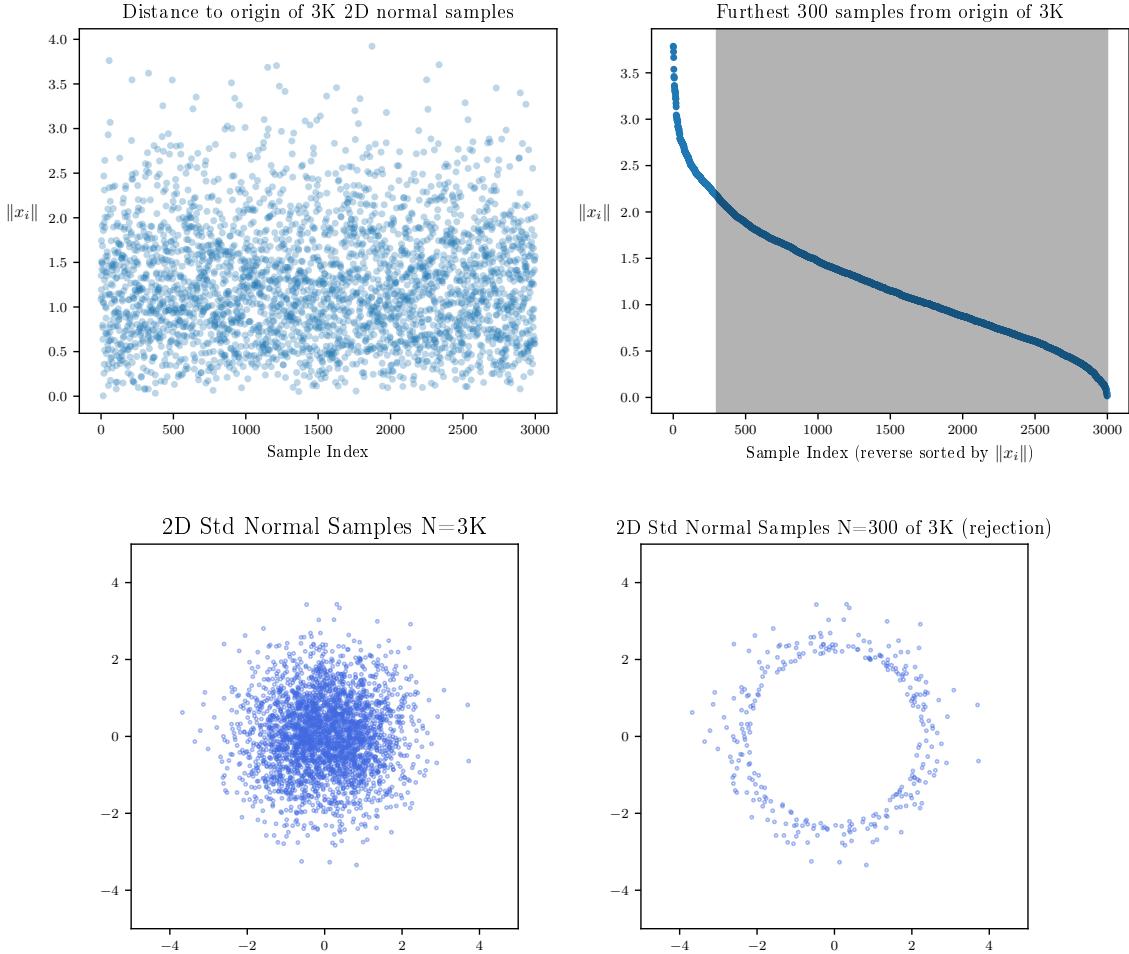


Figure 3.11: Distance to Origin of 2D Normal Samples Unordered and Ordered by Distance to Origin

In such a scenario, rejection sampling does not scale well with sample size since the acceptance probability is inversely proportion to the sample size. For example, suppose  $10^{14}$  samples (roughly 7 sigma) are to be simulated with a simulation budget of  $10^6$  simulations. Take a simple 6 transistor circuit where each transistor is

described by 7 random numbers (42 total). Assume, on average, the generation of a normal random number takes 5ns (a very competitive generation rate). In total, 5.8 hours would be required on 1000 cores assuming perfect scaling just to generate  $10^{14}$  random numbers to perform Rejection Sampling. In Section 3.9, we propose a new method called In-Order Multivariate Sampling which can directly generate tail samples efficiently. We will first lay the groundwork in the next two sections.

### 3.7 Generating List of Random Numbers in Sorted Order

The most direct way to create a list of  $n$  sorted uniform random numbers is by generating  $n$  uniform random numbers and sorting the list, as shown in Algorithm 3. The function `random()` used here and in subsequent algorithms returns an independent random number from the uniform distribution on [0,1].

---

#### **Algorithm 3** Generate Sorted Uniform Random Numbers by Sorting

---

```

1: procedure SORTEDUNIFORMBYSORTING
2:   for  $k \leftarrow 1, n$  do
3:      $x[k] \leftarrow \text{random}()$ 
4:    $x \leftarrow \text{sort}(x)$ 
```

---

The approach of Algorithm 3 requires a sort, which (see Knuth[26]) in linear space is of complexity  $\mathcal{O}(n \log n)$ . Direct sorting may be avoided by employing more sophisticated approaches which leverage probability theory[25]. Such approaches are possible due to the fact that the gaps between samples drawn from a uniform probability distribution are themselves distributed exponentially. More specifically,

the order statistics of a random sample of size  $n$  from the uniform distribution on  $[0,1]$  can be computed by

$$y_k = \sum_{j=1}^k x_j \Big/ \sum_{j=1}^{n+1} x_j \quad (3.6)$$

for  $k \in 1, \dots, n$  and  $x_j$  independent exponentially distributed random variables of any fixed mean[24]. This property is utilized in Algorithm 4 whose output is a list of  $n$  sorted random numbers independently drawn from  $U[0,1]$ .

---

**Algorithm 4** Generate Sorted Uniform Random Numbers in Two Passes

---

```

1: procedure SORTEDUNIFORMTWO PASS
2:    $s \leftarrow 0$ 
3:   for  $k \leftarrow 1, n$  do
4:      $s \leftarrow s - \log(\text{random}())$ 
5:      $x[k] \leftarrow s$ 
6:    $s \leftarrow s - \log(\text{random}())$ 
7:   for  $k \leftarrow 1, n$  do
8:      $x[k] \leftarrow x[k]/s$ 
```

---

While Algorithm 4 is a great improvement in efficiency over Algorithm 3, it does require two passes to produce the sorted random list. Friedman[10] showed that this can be further improved into a one-pass approach as shown in Algorithm 5.

---

**Algorithm 5** Generate Sorted Uniform Random Numbers in One Pass, Version 1

---

```

1: procedure SORTEDUNIFORMONE PASS V1
2:    $c \leftarrow 1$ 
3:   for  $k \leftarrow n, 1$  do
4:      $c \leftarrow c * \text{pow}(\text{random}(), 1/k)$ 
5:      $x[k] \leftarrow c$ 
```

---

Bentley and Saxe[4] of Carnegie-Mellon University proposed an alternative more

numerically robust computation given by Algorithm 6, which replaces the call to `pow()` with calls to `log()` and `exp()`.

---

**Algorithm 6** Generate Sorted Uniform Random Numbers in One Pass, Version 2

---

```

1: procedure SORTEDUNIFORMONEPASSV2
2:    $c \leftarrow 0$ 
3:   for  $k \leftarrow n, 1$  do
4:      $c \leftarrow c * \log(\text{random})/k$ 
5:      $x[k] \leftarrow \exp(c)$             $\triangleright$  for streaming computation, omit store to  $x[k]$ 
```

---

When the value of  $n$  is large (for example, in the billions), it may not be desirable to store all  $n$  numbers in array  $x$  as shown. Algorithm 6 can easily be converted into a streaming sorted random number generator by omitting the storage step in Line 5.

### 3.8 Inverse Transform Sampling

In Section 3.7, a method of producing lists of random numbers from the uniform distribution on  $[0,1]$  was presented. Not specific to sorted lists, a value  $x$  for a random variable  $X$  with non-uniform distribution may also be generated using inverse transform sampling.

**Lemma 1** (Inverse Transform Sampling). *If  $U$  is a uniform random variable on  $[0,1]$  then  $X$  as defined below has a distribution function  $F_X$ .*

$$X = F_X^{-1}(U) \tag{3.7}$$

$$\begin{aligned} \textit{Proof. } \Pr(F^{-1}(U) \leq x) &= \Pr(\inf\{x : F(x) = U\} \leq x) && (\text{definition of } F^{-1}) \\ &= \Pr(U \leq F(x)) && (\text{application of } F \text{ to each side}) \end{aligned}$$

$$= F(x) \quad (\text{definition of CDF of } U)$$

□

Using Algorithm 6 together with Lemma 1, lists of sorted random numbers can be obtained for a wide range of continuous probability distributions. In Section 3.9 this idea will be extended from univariate to multivariate random numbers.

### 3.9 In-order Multivariate Sampling

In Section 3.7, it was shown that sorted lists of uniform random numbers can be efficiently generated. Then in Section 3.8, this idea was extended to the sorted lists of arbitrarily distributed random numbers via the inverse transform sampling method. In this section, this idea is extended further to multivariate standard normal random vectors.

It is well known that the sum of squares of  $k$  standard normal distributed random variables follows a chi-square distribution with  $k$  degrees of freedom[36]. In other words, the square of the distance from the origin of a  $k$ -dimensional standard normal random vector is distributed as the  $k$  degrees of freedom chi-square. Given a random variable  $Y \sim U(0, 1)$ , inverse transform sampling can be used to find  $X \sim F_{\chi^2}^{-1}(k, Y) = F_{\chi^2}(k, X)$ . Now the distance to the origin of the  $k$ -dimensional standard normal random vector is distributed as  $\sqrt{X}$ . The values in each of the  $k$  dimensions need only satisfy the requirement that the sum of their squares equal  $X$ . Utilizing the method of Lemma 1, a point on the surface of the hypersphere of radius  $\sqrt{X}$  can be sampled to yield the desired  $k$ -dimensional standard normal random

vector[34]. In Algorithm 7, these ideas are synthesized into a program which gives lists of multivariate standard normal random vectors which are sorted according to distance from origin.

---

**Algorithm 7** In-order Multivariate Normal Sampling Steps (Original,  $d+1$  RVs per sample)

---

1. Draw  $N$  joint standard normal random vectors each of length  $d$ , call each vector  $\mathbf{x}_i$
  2. For each vector  $\mathbf{x}_i$ , let  $s_i$  be the square of its distance from the origin
  3. Draw  $N$  uniform random variables on  $(0, 1)$ , call values  $u_i$
  4. Update  $t = t - \log(u_i)/(N - i)$ ; with  $t = 0$  initially
  5. In-order Multivariate Normal samples  $\mathbf{Z}$  are given by  $\mathbf{z}_i = \mathbf{x}_i \sqrt{F_{\chi^2}^{-1}(e^t, d)/s_i}$
- 

Algorithm 8 (an alternative form of Algorithm 7) requires one fewer random variables per sample. This is possible because the required uniformly distributed variables can be calculated with the CDF of the chi-square distribution with  $s_i$  in  $d$  degree of freedom instead of drawn independently.

---

**Algorithm 8** In-order Multivariate Normal Sampling Steps (Revised,  $d$  RVs per sample)

---

1. Draw  $N$  joint standard normal random vectors each of length  $d$ , call each vector  $\mathbf{x}_i$
  2. For each vector  $\mathbf{x}_i$ , let  $s_i$  be the square of its distance from the origin
  3. Calculate  $\mathbf{u}$  by  $u_i = \gamma(\frac{d}{2}, \frac{s_i}{2})/\Gamma(\frac{d}{2}) = F_{\chi^2}(s_i, d)$
  4. Update  $t = t - \log(u_i)/(N - i)$ ; with  $t = 0$  initially
  5. In-order Multivariate Normal samples  $\mathbf{Z}$  are given by  $\mathbf{z}_i = \mathbf{x}_i \sqrt{F_{\chi^2}^{-1}(e^t, d)/s_i}$
- 

Figure 3.12 shows the furthest 1K samples out of 1K, 100K, 100M, and 100B samples, respectively. Note that in the first instance of drawing 1K samples of 1K

samples, this sample distribution is the same as standard Monte Carlo. In the latter three instances, the drawn distribution is distributed as if by standard Monte Carlo with rejection sampling, however the samples are drawn sequentially. As the total virtual sample size increases, the first 1K samples drawn become located further and further from the origin.

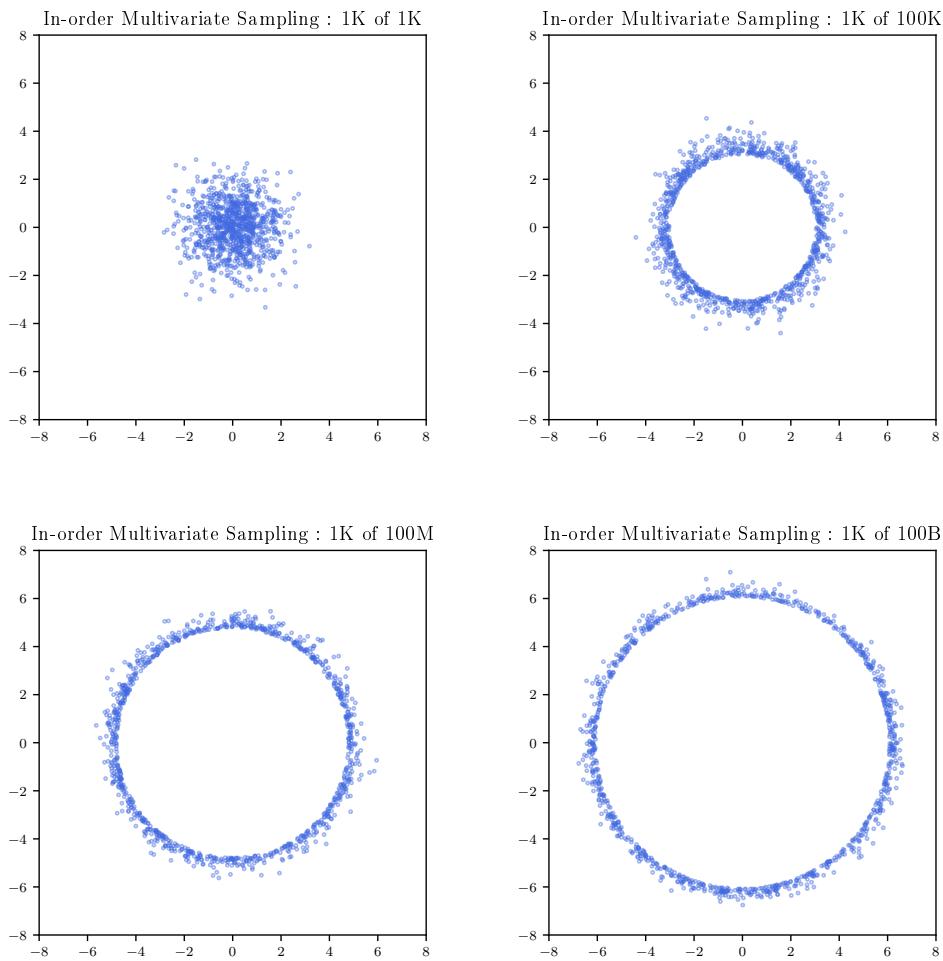


Figure 3.12: In-order Multivariate Sampling

Such sampling can be done in higher dimensions, as shown in Figure 3.13. Unlike Figure 3.12 which is distributed in just two dimensions, Figure 3.13 shows a two dimensional projection of the 5D In-Order Multivariate Sampling distribution.

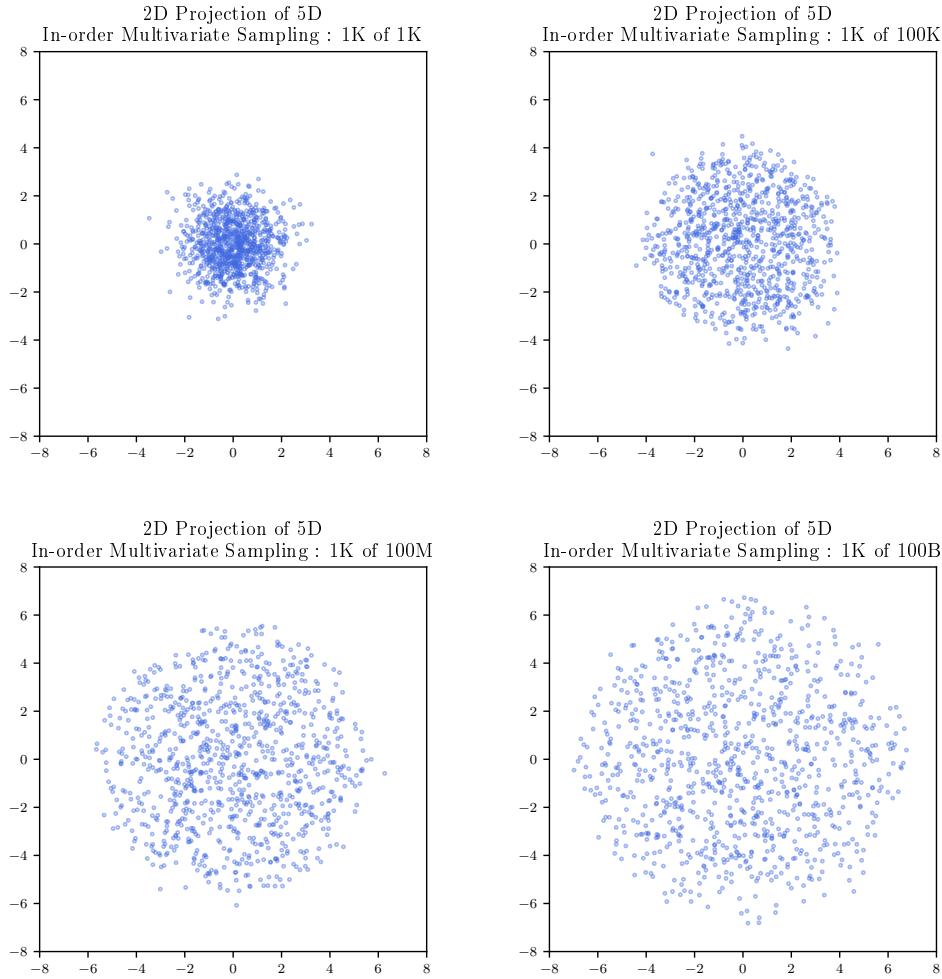


Figure 3.13: In-order Multivariate Sampling

The radius of the hypersphere is related to the dimension and probability in terms of  $\sigma$ . The hyperspherical iso-density contours of the  $d$ -dimensional standard

multivariate normal have radius  $r$  given by

$$r = \sqrt{F_{\chi^2}^{-1}(P; d)} \quad (3.8)$$

where  $P$  is the probability that a random sample is drawn from the interior of that hypersphere. In terms of In-order Multivariate Sampling, this can be restated as follows

$$r = \sqrt{F_{\chi^2}^{-1}(1 - (n - 0.5)/N; d)} \quad (3.9)$$

where  $N$  is the total sample size of the distribution from which  $n$  samples furthest from the origin are collected.

### **Example : Radius Calculation**

For a standard normal random vector in 42 dimensions, at  $5\sigma$ , 99.99997% of samples are expected to be contained within a hypersphere centered at the origin with a radius given by

$$r = \sqrt{F_{\chi^2}^{-1}(\Phi(5); 42)} = 10.23268 \quad (3.10)$$

which can be computed in the R language by : `sqrt(qchisq(pnorm(5), 42))` .

### **Example : $\sigma$ Calculation**

If the failure point closest to the origin lies at a distance 10.23268 from the origin in 42 dimensions, then the  $\sigma$  value associated with the joint probability contained

within that hyperspheric surface is given by

$$\sigma = \Phi^{-1}(F_{\chi^2}(r^2, d)) = \Phi^{-1}(F_{\chi^2}(10.23268^2, 42)) = 5 \quad (3.11)$$

which can be computed in the R language by : `qnorm(pchisq(10.23268^2, 42))` .

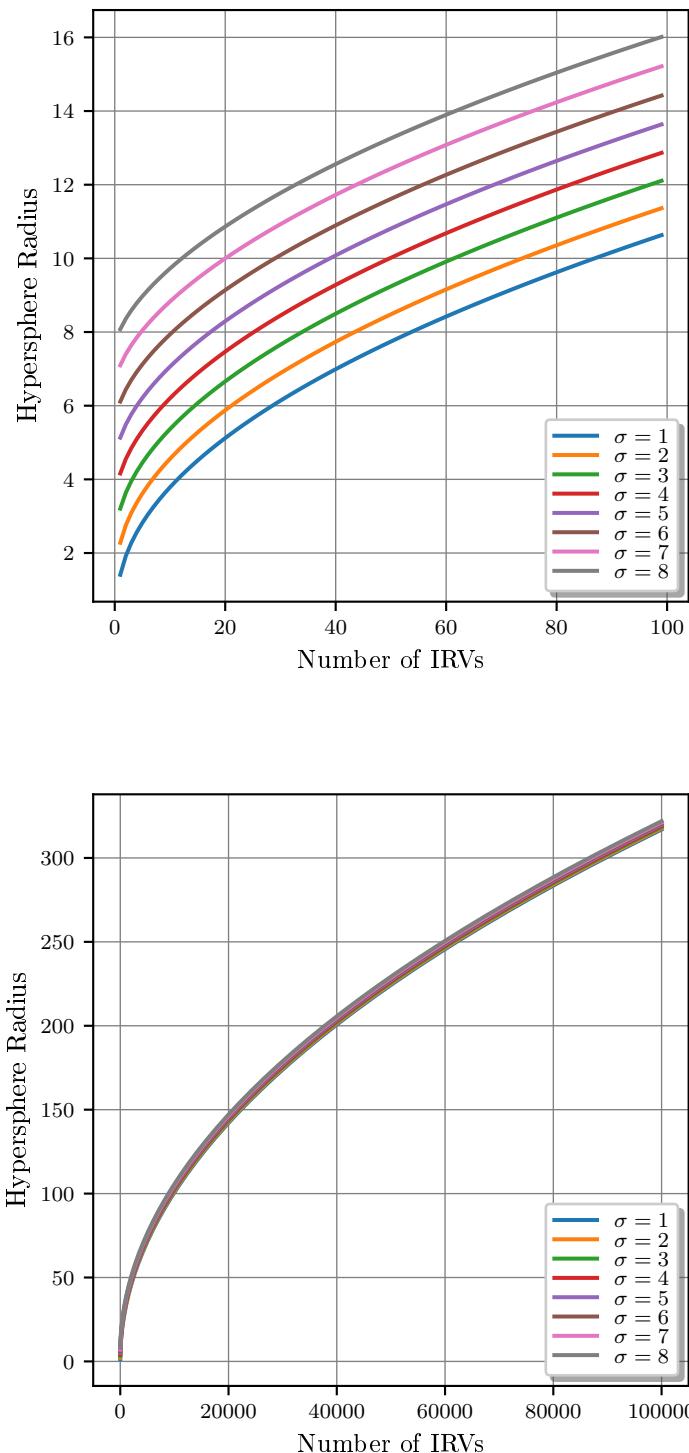


Figure 3.14: Hypersphere Radius as a function of the number of IRVs and probability in terms of  $\sigma$

## 3.10 Extensions

It is possible to extend the Hyperspherical Uniform Volumetric Sampling (HUVS) and In-order Multivariate Sampling (IMS) methods for sampling outlined in this chapter in a variety of ways. Examples of three such extensions are outlined in this section : correlated sampling, Hyperspherical Non-uniform Volumetric Sampling (HNVS), and directional sampling. The HNVS method is an extension of the HUVS method only, whereas correlated sampling and directional sampling can be applied both to HUVS and IMS. It should be noted that these extensions are not revisited elsewhere in the thesis. They are provided to give evidence for the flexibility of the established methods to cater to differing situational requirements.

### 3.10.1 Correlated Sampling

In this section, we will show how Hyperspherical Uniform Volumetric Sampling (HUVS) and In-order Multivariate Sampling (IMS) methods can be extended to incorporate correlated sampling. The multivariate standard normal distribution can be thought of as a hyperspherical distribution as the boundary of equally probable density contours form hyperspheres in  $d$  dimensions. Given non-equal variance among these elements, the hypersphere becomes a hyperellipse. Further, if there exists a covariance among the elements that is non-zero, then the hyperellipse becomes a rotated hyperellipse. A covariance matrix  $\Sigma$  represent such conditions, with variances on the diagonal and covariances off the diagonal. The covariance matrix can be factored uniquely as the product of two upper triangular matrices as follows

$$\boldsymbol{\Sigma} = \mathbf{U}^T \mathbf{U} . \quad (3.12)$$

The matrix  $\mathbf{U}$  is the Cholesky matrix, though it is often written[13] instead as a lower diagonal matrix  $\mathbf{L}$  defined by

$$\boldsymbol{\Sigma} = \mathbf{L} \mathbf{L}^T . \quad (3.13)$$

The Cholesky matrix transforms uncorrelated variables into variables whose variances and covariances are given by  $\boldsymbol{\Sigma}$ . In particular, the Cholesky transformation in Equation 3.14 maps the multivariate standard normal distribution  $\mathbf{X}$  into the multivariate normal distribution with covariance matrix  $\boldsymbol{\Sigma}$  centered at the origin, denoted  $\mathbf{Y} = N_d(\mathbf{0}, \boldsymbol{\Sigma})$ .

$$\mathbf{Y} = \mathbf{L} \mathbf{X} . \quad (3.14)$$

In the following example, let  $\boldsymbol{\Sigma}$  take the following value

$$\boldsymbol{\Sigma} = \begin{bmatrix} 3.25 & 3.5 \\ 3.5 & 5 \end{bmatrix} . \quad (3.15)$$

The lower Cholesky matrix  $\mathbf{L}$  is then computed as

$$\mathbf{L} = \begin{bmatrix} 1.80277564 & 0 \\ 1.94145069 & 1.10940039 \end{bmatrix} . \quad (3.16)$$

Using the  $\mathbf{L}$  in Equation 3.16 as a mapping of the input distribution by Equation 3.14 yields a correlated distributions as shown in Figure 3.15

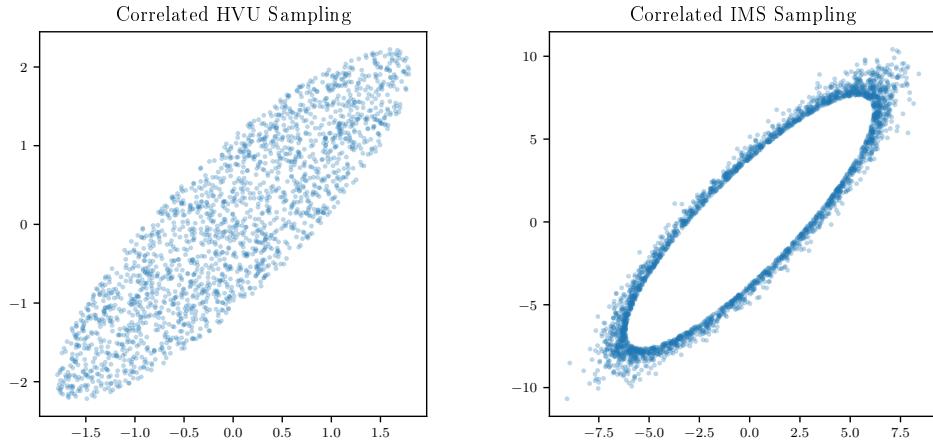


Figure 3.15: Correlated sampling with Hyperspherical Uniform Volumetric Sampling and In-order Multivariate Sampling

### 3.10.2 Hyperspherical Non-Uniform Volumetric Sampling

Algorithm 2 provided a method to generate a volumetric uniform samples within the surface of hyperspheres. This sample distribution can be generalized to include a radient density parameter  $r$  as in Algorithm 9. An outline of the behavior, in relation to the value of  $r$ , of samples drawn from the non-uniform distribution is shown in Table 3.1.

---

**Algorithm 9** Volumetric Non-uniform Sampling Steps with radial density parameter  $r$

---

1. Draw  $N$  joint standard normal random vectors each of length  $d$ , call each vector  $\mathbf{x}_i$
  2. For each vector  $\mathbf{x}_i$ , let  $s_i$  be the square of its distance from the origin
  3. Calculate  $\mathbf{u}$  by  $u_i = \gamma(\frac{d}{2}, \frac{s_i}{2})/\Gamma(\frac{d}{2}) = F_{\chi^2}(s_i, d)$
  4. Volumetric uniform samples  $\mathbf{Z}$  are given by  $\mathbf{z}_i = \mathbf{x}_i u_i^{\frac{r}{d}} / \sqrt{s_i}$
- 

Table 3.1: The effect of non-uniform distribution radial density parameter  $r$  on resulting sample distribution

Condition	Description
$r < 0$	samples distributed beyond hyperspheric surface
$r = 0$	samples distributed on hyperspheric surface only
$0 < r < 1$	samples distributed with lower probability density near origin
$r = 1$	samples distributed with uniform density within hypersphere
$r > 1$	samples distributed with higher probability density near origin

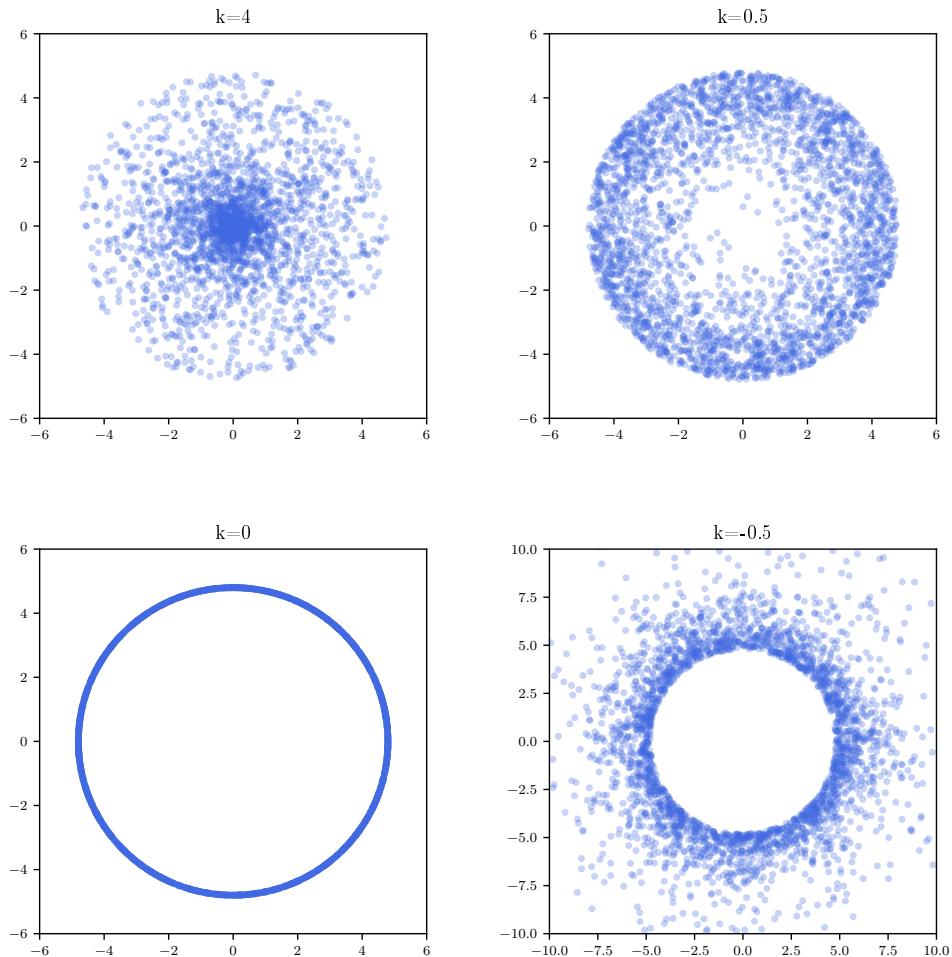


Figure 3.16: Hyperspherical Non-uniform Volumetric Sampling distributions for  $k=4, 0.5, 0, -0.5$

### 3.10.3 Directional Sampling

Named after Richard von Mises, the von Mises distribution[9] (also known as the circular normal distribution or Tikhonov distribution) is a probability distribution

used in directional statistics on the circle and has a probability density function given by

$$f(x \mid \mu, \kappa) = \frac{e^{\kappa \cos(x-\mu)}}{2\pi I_0(\kappa)} \quad (3.17)$$

where  $I_0(\kappa)$  is the order 0 modified Bessel function,  $\mu$  is the location parameter which indicated the angular direction, and  $\kappa$  is the concentration parameter. When  $\kappa$  is zero, the distribution is uniform on the circle whereas when  $\kappa$  is large the samples are highly clustered on the circle about the angle  $\mu$ .

Moving to higher dimensions, the Fisher distribution (named for Ronald Fisher) extends the von Mises distribution to the sphere and the von Mises—Fisher distribution generalizes this further to the  $(d-1)$ -dimensional sphere in  $\mathbb{R}^d$ . The probability density function of the von Mises—Fisher distribution for the random  $d$ -dimensional unit vector  $\mathbf{x}$  is given by:

$$f_p(\mathbf{x}; \boldsymbol{\mu}, \kappa) = c_d(\kappa) \exp(\kappa \boldsymbol{\mu}^T \mathbf{x}) \quad (3.18)$$

where  $\kappa \geq 0, d \geq 2, \|\boldsymbol{\mu}\| = 1$  and the normalization constant  $c_d(\kappa)$  is given by

$$c_d(\kappa) = \frac{\kappa^{d/2-1}}{(2\pi)^{d/2} I_{d/2-1}(\kappa)}. \quad (3.19)$$

where  $I_v$  denotes the modified Bessel function of the first kind of order  $v$ .

For visualization purposes, the samples drawn from the von-Mises Fisher distribution in two dimensions (on the unit circle) with constant  $\boldsymbol{\mu} = (\sqrt{2}/2, \sqrt{2}/2)$  and  $\kappa = 1, 2, 5, 15$  is shown in Figure 3.17. The angular densities of these samples is

shown in Figure 3.18, which clearly illustrates the high density of sample angles at  $\pi/4$ , which corresponds to the specified location parameter of  $\mu = (\sqrt{2}/2, \sqrt{2}/2)$ .

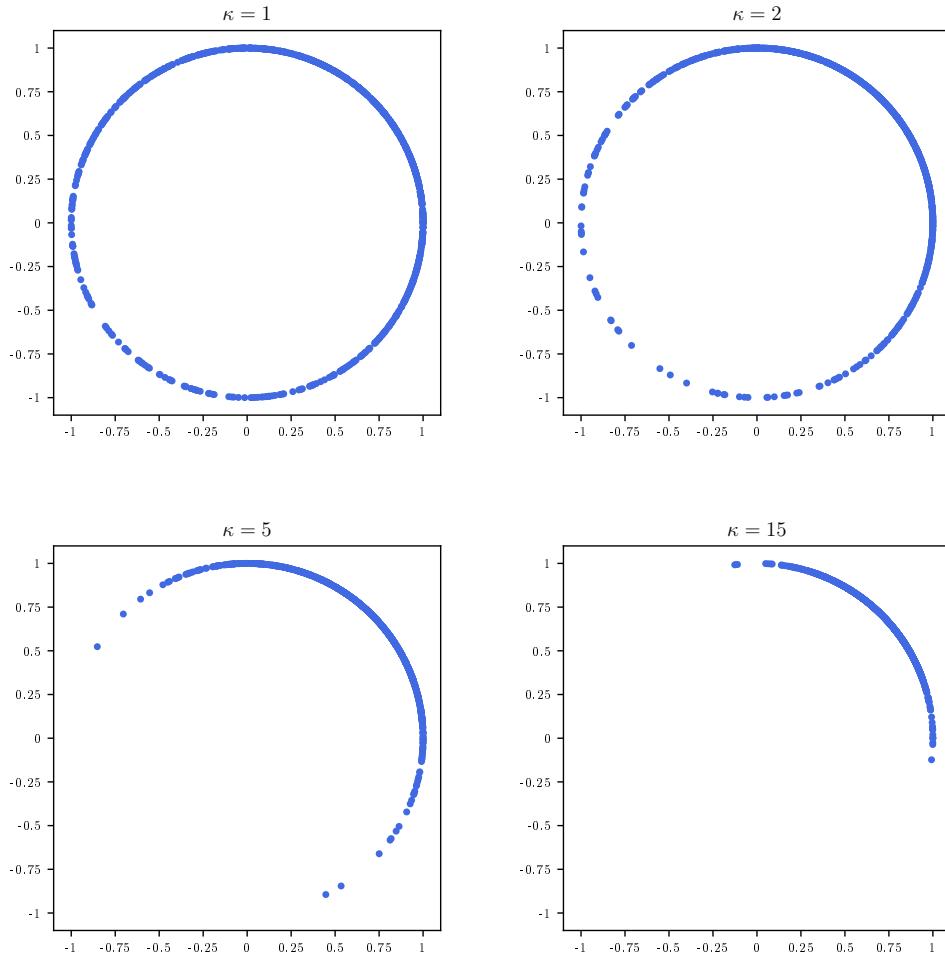


Figure 3.17: Samples from the von Mises-Fisher Distribution on the unit circle for  $\kappa = 1, 2, 5, 15$  in direction  $\mu = (\sqrt{2}/2, \sqrt{2}/2)$

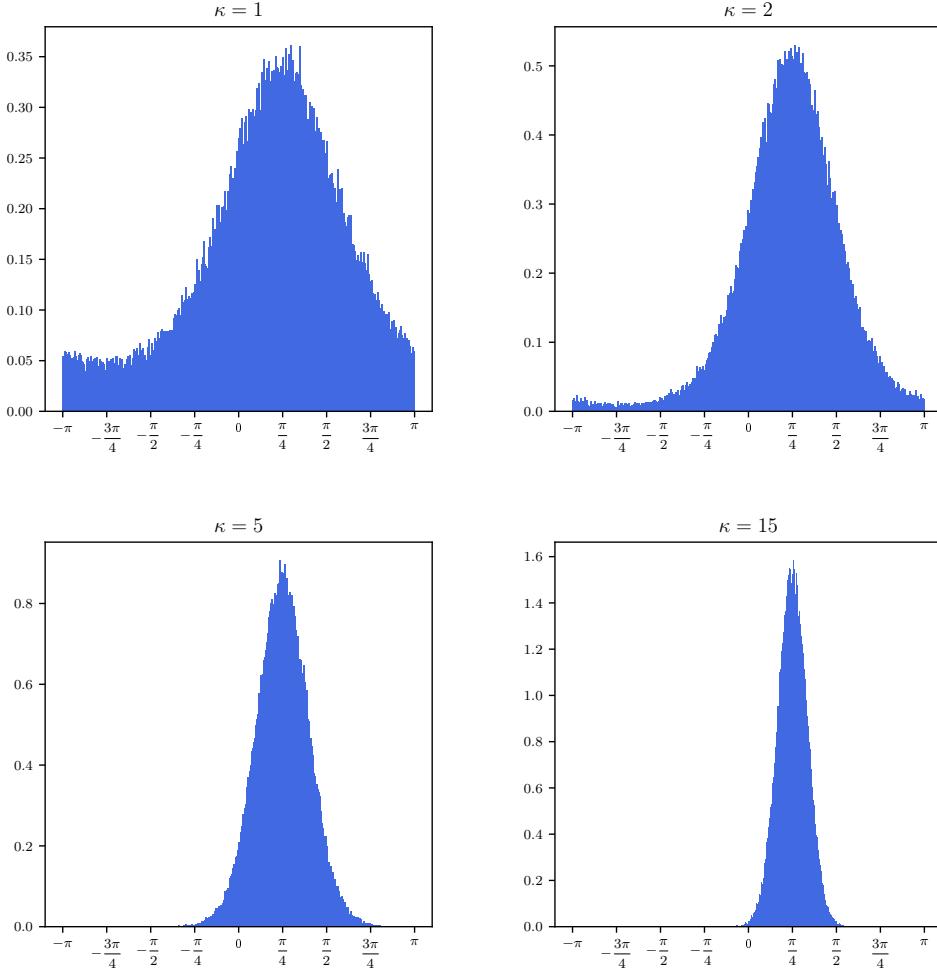


Figure 3.18: Samples from the von Mises-Fisher Distribution on the unit circle for  $\kappa = 1, 2, 5, 15$  in direction  $\mu = (\sqrt{2}/2, \sqrt{2}/2)$

It has been shown that the von Mises-Fisher distribution may be applied to the Hyperspherical Uniform Volumetric Sampling in the case where the radius density parameter is set to zero to achieve samples on the hyperspheric surface only. This same technique may be applied to arbitrary Hyperspherical Uniform Volumetric

Sampling and In-order Multivariate Sampling methods as well to achieve directional versions of these sampling methods.

### 3.11 Discussion

In this chapter, concepts related to Monte Carlo sampling have been reviewed. Simple random sampling from the normal, i.e. drawing samples from the standard normal distribution in our case, was shown to be an inefficient method to learn about the output distribution tails. Next, sampling from a normal distribution with standard deviation greater than unity instead allowed for faster exploration of tail samples, though a majority of samples still were located in close proximity to the origin. Sampling from the uniform distribution was then presented and details about statistical practicality of drawn samples in higher dimensions was discussed. The inefficiency of rejection sampling to learn about distribution tails was explored and motivated the development a more advanced sampling method.

A novel method for In-order Multivariate Sampling (IMS) was proposed to efficiently explore tail samples from a multivariate normal distribution. An alternative IMS algortihm was given the relationship as well as several examples to illustrate the power and theoretical foundation of the method. In-Order Multivariate Sampling is revisited again in Chapter 6 with circuit examples.

Finally. these methods were extended in three ways : correlated sampling, Hyperspherical Non-uniform Volumetric Sampling, and directional sampling. The extensions provide several ideas for leveraging the established sampling methods to

apply to a wider domain of practical problems.

# Chapter 4

## Quadratic Forms of the Multivariate Standard Normal

In the last chapter, a first order Taylor series expansion (the linear form) of the true MC mapping of the multivariate standard normal was studied. This effort is taken one step further to consider the second order Taylor series expansion, the quadratic form.

Given a set of data, a procedure is established to model the data by a sparsified quadratic polynomial leveraging Legendre polynomials. Once the quadratic form is available, it is transformed into a linear form of normal and/or chi-square random variables. Subsequently, the raw and central moments as well as the cumulants are computed. Finally, using the Cornish-Fisher expansion, the distribution quantiles are estimated.

## 4.1 Quadratic Forms

As was seen in the previous chapter, linear forms of multivariate standard normals have moments and quantiles which are easily computable. Although the computations are more complex, assuming the vector of independent random variables are joint normal, the moments and quantiles of the quadratic form can be directly computed from the form itself[29]. In particular, a quadratic form of a multivariate standard normal vector has the following properties:

1. Can be expressed as a linear form of independent chi-square and normal random variables
2. Has moments which can be calculated in closed form.
3. Has quantile estimates which can be estimated in closed form.

## 4.2 Quadratic Modeling with Monomial Polynomials

The problem of finding a polynomial  $P_n(x)$  of degree at most  $n$  which models a function  $g(x)$  which is continuous on  $[a, b]$  such that the integral of the square of the error is minimized can be written as

$$\min_{\mathbf{w}} \int_a^b [g(x) - P_n(x)]^2 dx \quad (4.1)$$

where  $P_n(x)$  is given by

$$P_n(x) = w_0 + w_1x + w_2x^2 + \cdots + w_nx^n . \quad (4.2)$$

To perform the same minimization using a set of  $m$  discrete data points  $(x_i, y_i), i = 1, 2, \dots, m$ , the  $P_n(x)$  of Equation 4.2 the new objective becomes

$$\min_{\mathbf{w}} \sum_1^m (y_i - w_0 - w_1x_i - w_2x_i^2 - \cdots - w_nx_i^n)^2 dx \quad (4.3)$$

provided that  $n < m$ .

While solutions to the problems outlined in this section, they are seldom used in practice due to the problem of ill-conditioning. The specific causes are beyond the scope of the thesis, however this computation can be made computationally effective by using a special type of polynomials, called orthogonal polynomials, of which the Legendre polynomials are an important class.

### 4.3 Quadratic Modeling with Legendre Polynomials

Legendre polynomials form an orthogonal polynomial basis over the interval  $[-1,1]$ , thus the  $n$ th-order Legendre polynomial has the property

$$\int_{-1}^1 P_n(x)P_m(x) dx = 0 \quad \text{if } n \neq m \quad (4.4)$$

where  $P_n(x)$  denote the Legendre polynomials and are given by Equations 4.6-4.11 and plotted in Figure 4.1 for  $x \in [-1, 1]$  and  $n = 0, 1, 2, \dots, 5$ .

$$P_0(x) = 1 \quad (4.5)$$

$$P_1(x) = x \quad (4.6)$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1) \quad (4.7)$$

$$P_3(x) = \frac{1}{2}(5x^2 - 3x) \quad (4.8)$$

$$P_4(x) = \frac{1}{8}(35x^4 - 30x^2 + 3) \quad (4.9)$$

$$P_5(x) = \frac{1}{8}(63x^5 - 30x^3 + 3) \quad (4.10)$$

$$P_n(x) = \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k}^2 (x-1)^{n-k} (x+1)^k. \quad (4.11)$$

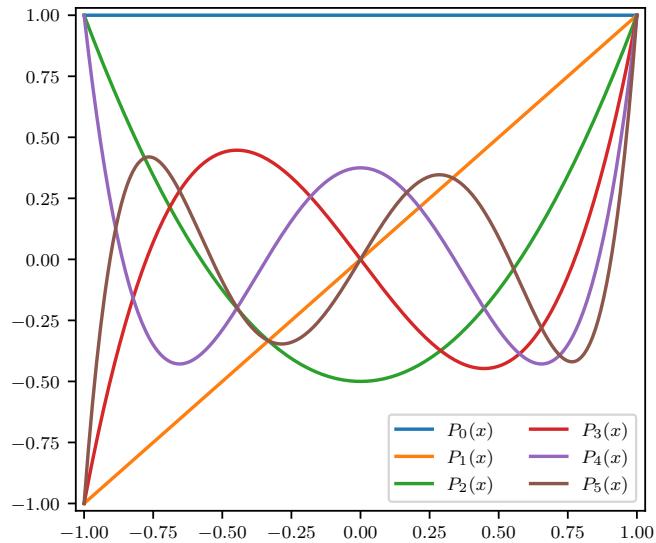


Figure 4.1: Plots of the first six Legendre polynomials

Using Legendre polynomials to model unknown functions is more computation-

ally effective as mentioned in the previous section and useful in that small perturbations in the input sample data result in small coefficient updates. Partial fits are also possible with series truncation. In 1 dimension, Legendre polynomials of order  $0 \dots n$  form a 1D orthogonal basis on  $-1 \leq x \leq 1$  in the degree  $n$  univariate polynomial space. To approximate sample data from an unknown function by a  $n$ th order Legendre polynomial, the  $n + 1$  coefficients  $a_k$  are used as follows

$$L_n(x) = \sum_{k=0}^n a_k P_k(x) . \quad (4.12)$$

In higher dimensions, the tensor product of the span of the Legendre polynomial basis functions are considered

$$\mathbf{L}_n^d = L_{n,1} \otimes L_{n,2} \otimes L_{n,3} \cdots \otimes L_{n,d} . \quad (4.13)$$

This may be solved as in the 1D case, but in  $d$  dimensions the number of Legendre coefficients becomes  $(n_1 + 1) \times (n_2 + 1) \times (n_3 + 1) \times \cdots \times (n_d + 1)$  in  $d$  dimensions, when  $n_k = n \forall k$  then the number of fitting coefficients number  $(n + 1)^d$ .

Since the quadratic form is being considered, a  $d$ -order tensor space of order up to 2 Legendre polynomials with  $k = 3^d$  fitting terms, which can be expressed as  $c$  and  $w_1 \dots w_{k-1}$ . Utilizing LASSO, a sparse quadratic fit is produced by finding  $c$  and  $\mathbf{w}$ .

$$\arg \min_{c, \mathbf{w}} \left\{ \frac{1}{N} \|y - c\mathbf{1}_N - X\mathbf{w}\|_2^2 \right\} \text{ subject to } \|\mathbf{w}\|_1 \leq \lambda \quad (4.14)$$

Finally, the solved coefficients of  $c$  and  $\mathbf{w}$  can be remapped to  $a$ ,  $\mathbf{b}$ , and  $\mathbf{C}$

which represent the constant, linear and quadratic terms of the quadratic form, respectively. The dependent random variable  $y$  may now be expressed in terms of the vector of independent random variables  $\mathbf{x} \sim N_d(\mathbf{0}, \mathbf{I})$  as follows

$$y = \mathbf{x}^\top \mathbf{C} \mathbf{x} + \mathbf{b} \mathbf{x} + a . \quad (4.15)$$

## 4.4 Linearization via Eigenvector Decomposition

The quadratic form modeled in the previous section can be expressed as a linear form of normal and chi-square variables. The linearized form has a very similar structure given by

$$y = \tilde{\mathbf{x}}^\top \tilde{\mathbf{C}} \tilde{\mathbf{x}} + \tilde{\mathbf{b}} \tilde{\mathbf{x}} + \tilde{a} \quad (4.16)$$

where a matrix  $\mathbf{U}$ , comprised of the orthonormal eigenvectors of  $\mathbf{C}$ , is used to compute  $\tilde{\mathbf{x}}$ ,  $\tilde{\mathbf{C}}$ ,  $\tilde{\mathbf{b}}$  and  $\tilde{a}$  as follows

$$\tilde{\mathbf{x}} = \mathbf{U} \mathbf{x} \quad (4.17)$$

$$\tilde{\mathbf{C}} = \mathbf{U} \mathbf{C} \mathbf{U}^\top = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_d \end{bmatrix} \quad (4.18)$$

$$\tilde{\mathbf{b}} = \mathbf{b} \mathbf{U}^\top \quad (4.19)$$

$$\tilde{a} = a . \quad (4.20)$$

Since  $\tilde{\mathbf{C}}$  has no off-diagonal elements, the matrix algebra can be rewritten in summation form as

$$y = \sum_{i=1}^d \tilde{\mathbf{C}}_{i,i} \tilde{\mathbf{x}}_i^2 + \tilde{\mathbf{b}}_i \tilde{\mathbf{x}}_i + \tilde{a} . \quad (4.21)$$

In these terms, the dependence of  $y$  upon  $\tilde{\mathbf{x}}$  can be express in four ways :

1.  $\tilde{\mathbf{C}}_{i,i} = 0$  and  $\tilde{\mathbf{b}}_i = 0$  : No dependence
2.  $\tilde{\mathbf{C}}_{i,i} = 0$  and  $\tilde{\mathbf{b}}_i \neq 0$  : Linear dependence
3.  $\tilde{\mathbf{C}}_{i,i} \neq 0$  and  $\tilde{\mathbf{b}}_i = 0$  : Central quadratic dependence
4.  $\tilde{\mathbf{C}}_{i,i} \neq 0$  and  $\tilde{\mathbf{b}}_i \neq 0$  : Non-central quadratic dependence

## 4.5 Raw Moments

Derivation details of the calculation of raw moments by the quadratic form and its linearization is covered by Mathai and Provost[29]. The raw moments are given by

$$\mathbb{E}[\mathbf{y}^r] = \sum_{r_1=0}^{r-1} \binom{r-1}{r_1} g^{(r-1-r_1)} \sum_{r_2=0}^{r_1-1} \binom{r_1-1}{r_2} g^{(r_1-1-r_2)} \dots \quad (4.22)$$

$$(4.23)$$

where  $g^{(k)}$  is defined by

$$g^{(k)} = \begin{cases} \tilde{a} + \frac{1}{2} \sum_{j=1}^p (2\lambda_j) & k = 0 \\ \frac{k!}{2} \sum_{j=1}^p (2\lambda_j)^{k+1} + \frac{(k+1)!}{2} \sum_{j=1}^p \tilde{\mathbf{b}_j}^2 (2\lambda_j)^{k-1} & k \geq 1 \end{cases}. \quad (4.24)$$

## 4.6 Central Moments

From the raw moments, the central moments can be calculated as follows:

$$\mu_n = \mathbb{E}[(\mathbf{y} - \mathbb{E}[\mathbf{y}])^n] = \sum_{j=0}^m \binom{n}{j} (-1)^{n-j} \mu'_j \mu^{m-j} \quad (4.25)$$

$$\mu'_m = \mathbb{E}[\mathbf{y}^m] \quad (4.26)$$

$$\mu_1 = 0 \quad (4.27)$$

$$\mu_2 = \mu'_2 - \mu^2 \quad (4.28)$$

$$\mu_3 = \mu'_3 - 3\mu\mu'_2 + 2\mu^3 \quad (4.29)$$

$$\mu_4 = \mu'_4 - 4\mu\mu'_3 + 6\mu^2\mu'_2 - 3\mu^4 \quad (4.30)$$

$$\mu_5 = \mu'_5 - 5\mu\mu'_4 + 10\mu^2\mu'_3 - 10\mu^3\mu'_2 + 4\mu^5. \quad (4.31)$$

## 4.7 Cumulants

The cumulants,  $\kappa_j$ , can be expressed in terms of the central moments  $\mu_j$ .

$$\kappa_1 = \mu \quad (4.32)$$

$$\kappa_2 = \mu_2 \quad (4.33)$$

$$\kappa_3 = \mu_3 \quad (4.34)$$

$$\kappa_4 = \mu_4 - 3\mu_2^2 \quad (4.35)$$

$$\kappa_5 = \mu_5 - 10\mu_2\mu_3 . \quad (4.36)$$

## 4.8 Quantiles

By the Cornish-Fisher expansion[8], the probability distribution quantiles can calculated based on the cumulants.

$$\begin{aligned} F_y^{-1}(q) \approx & \Phi^{-1}(q) + \frac{\Phi^{-1}(q)^2 - 1}{6}\kappa_3 + \frac{\Phi^{-1}(q)^3 - 3\Phi^{-1}(q)}{24}\kappa_4 \\ & - \frac{2\Phi^{-1}(q)^3 - 5\Phi^{-1}(q)}{36}\kappa_3^2 + \frac{\Phi^{-1}(q)^4 - 6\Phi^{-1}(q)^2 + 3}{120}\kappa_5 \\ & - \frac{\Phi^{-1}(q)^4 - 5\Phi^{-1}(q)^2 + 2}{24}\kappa_3\kappa_4 + \frac{12\Phi^{-1}(q)^4 - 53\Phi^{-1}(q)^2 + 17}{324}\kappa_3^3 \end{aligned} \quad (4.37)$$

where  $\Phi^{-1}(q)$  is the quantile function of the standard normal distribution.

The expansion is performed using the normalized  $\kappa^*$  rather than  $\kappa$  as the expansion requires standard normality. This yields the quantile of  $y^*$  which is subsequently un-normalized. The relationships between these terms is given by

$$y^* = \frac{y - \mu}{\sigma} \quad (4.38)$$

$$\mu_j^* = \frac{\mu_j}{\sigma^j} \quad (4.39)$$

$$\sigma = \sqrt{\mu_2} . \quad (4.40)$$

## 4.9 Toy Example

In this section, the Booth function is used to illustrate the quadratic modeling and the extraction of distribution properties directly from the quadratic model as described earlier in this chapter. The Booth function is given in both standard quadratic form as well as in matrix form as follows:

$$y = 5x_0^2 + 5x_1^2 + 8x_0x_1 - 34x_0 - 38x_1 + 74$$

$$\begin{aligned} y &= \mathbf{x}' \mathbf{C} \mathbf{x} + \mathbf{b}' \mathbf{x} + a \\ \mathbf{C} &= \begin{bmatrix} 5 & 4 \\ 4 & 5 \end{bmatrix} \\ \mathbf{b} &= \begin{bmatrix} -34 & -38 \end{bmatrix} \\ a &= 74 . \end{aligned}$$

Now define the rows of square matrix  $\mathbf{U}$  comprised of the orthonormal eigenvectors of  $\mathbf{C}$  as follows

$$\mathbf{U} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} .$$

Completing the transformation, it can be written as

$$\begin{aligned} y &= \tilde{\mathbf{x}}' \tilde{\mathbf{C}} \tilde{\mathbf{x}} + \tilde{\mathbf{b}}' \tilde{\mathbf{x}} + \tilde{a} \\ \tilde{\mathbf{x}} &= \mathbf{U} \mathbf{x} \\ \tilde{\mathbf{C}} &= \mathbf{U} \mathbf{C} \mathbf{U}' = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 9 & 0 \\ 0 & 1 \end{bmatrix} \\ \tilde{\mathbf{b}} &= \mathbf{b} \mathbf{U}' = \begin{bmatrix} -36\sqrt{2} & -2\sqrt{2} \end{bmatrix} \\ \tilde{a} &= a = 74 \end{aligned}$$

$$\begin{aligned} y &= 9\tilde{x}_0^2 + \tilde{x}_1^2 - 36\sqrt{2}\tilde{x}_0 - 2\sqrt{2}\tilde{x}_1 + 74 \\ &= 9(\tilde{x}_0 - 2\sqrt{2})^2 + (\tilde{x}_1 - \sqrt{2})^2 . \end{aligned}$$

Now  $y$  can be expressed as a linear combination of two independent chi-squared random variables

$$(\tilde{x}_0 - 2\sqrt{2})^2 \sim \chi^2(1, 8)$$

$$(\tilde{x}_1 - \sqrt{2})^2 \sim \chi^2(1, 2) .$$

The analytic raw moments, calculated by Equation 4.22, are compared with the sample raw moments in Table 4.1. The correspondence between the analytic and

sample raw moments is good, with the error of the analytic moments versus the sample moments within 0.3%.

Table 4.1: Sample versus analytic raw moments : Booth function

r	Analytic	Sample	Rel. Error
1	84.000	84.002	0.003%
2	9810	9821	0.111%
3	1432512	1435297	0.194%
4	248515452	249157550	0.258%
5	49659227280	49807988025	0.300%

Using the raw moments, the central moments are then computed by Equations 4.25-4.31. A comparison between the analytic central moments and sample central moments is given in Table 4.2. The agreement between the analytic and sample central moments is also good, with a maximum relative error of 0.2%.

Table 4.2: Sample versus analytic central moments : Booth function

r	Analytic	Sample	Rel. Error
1	0	0	0.000%
2	2765	2764	-0.026%
3	145901	145855	-0.031%
4	33329811	33302404	-0.082%
5	4965361922	4955431600	-0.200%

The normalized central moments and cumulants, computed by Equations 4.40 and 4.33-4.36 respectively, are reported in Table 4.3. These quantities are subsequently used in order to calculate analytic quantile information.

Table 4.3: Normalized central moments and cumulants : Booth function

$j$	$\mu_j^*$	$\kappa_j^*$
1	0	0
2	1	1
3	1.0037	1.0037
4	4.3605	1.3605
5	12.3548	2.3181

Lastly, the quantiles are computed analytically by the Cornish-Fisher expansion given by Equation 4.38. A comparison between the analytic and sample values is given in Table 4.4. The correspondence between the two quantile calculation methods is very close, with the largest relative error being less than 0.1% up to a quantile of 0.999999.

Table 4.4: Sample versus analytic quantiles : Booth function

Quantile	Analytic	Sample	Rel. Error
0.5	75.06	75.02	-0.047%
0.75	113.54	113.52	-0.023%
0.95	183.31	183.23	-0.039%
0.99	242.47	242.29	-0.075%
0.999	318.73	318.51	-0.068%
0.9999	389.30	389.19	-0.028%
0.99999	456.22	456.49	0.059%
0.999999	520.50	520.16	-0.065%
0.9999999	582.74	596.61	2.380%

## 4.10 Quadratic Modeling Examples

In the previous section, the modeling of the Booth function was used as a vehicle for demonstrating the extraction of probability distribution statistics such as moments, cumulants, and quantiles from the quadratic form directly. In the last section, in order to outline the ideas clearly, the quadratic form of the model for the Booth function was given as an input. In this section, the more general case is considered where only sample data from an unknown function is provided. Several different types of functions are considered, both univariate and multivariate. In each case, the analytic quantiles of the linear and quadratic models are compared to the quantiles

of the sample data. For reference, the linear and quadratic model equations are also provided.

#### 4.10.1 Univariate Linear

Table 4.5: Univariate Linear Example True and Modeled Forms

True Form	$2X + 1$
Modeled Linear Form	$2X + 1$
Modeled Quadratic Form	$1.9956X + 0.999$

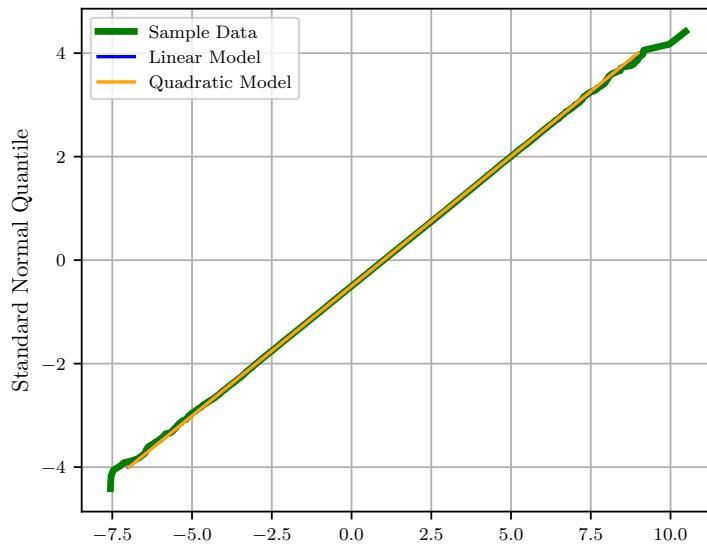


Figure 4.2: Sample data of univariate linear form compared with analytic quantiles of modeled linear and quadratic forms

### 4.10.2 Univariate Quadratic

Table 4.6: Univariate Quadratic Example True and Modeled Forms

True Form	$2X^2 - 3X + 7$
Modeled Linear Form	$-2.9937X + 8.9999$
Modeled Quadratic Form	$1.9156X^2 - 2.9599X + 7.075$

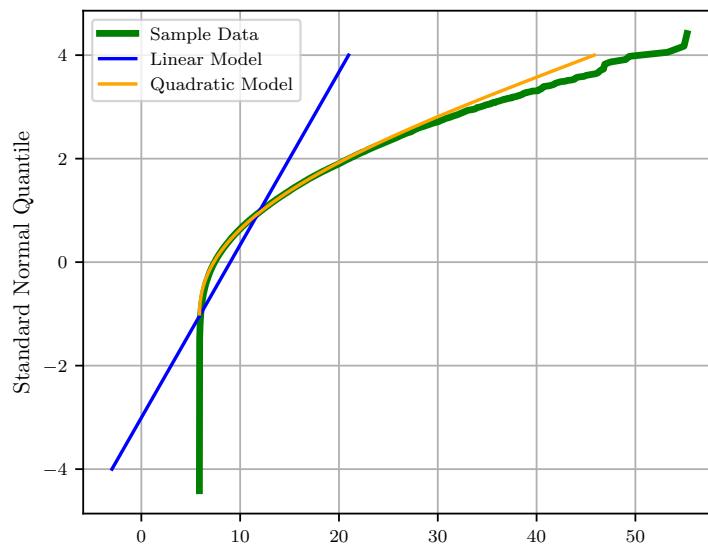


Figure 4.3: Sample data of univariate quadratic form compared with analytic quantiles of modeled linear and quadratic forms

### 4.10.3 Multivariate Quartic

Table 4.7: Multivariate Quartic Example True and Modeled Forms

True Form	$\begin{aligned} & \text{Himmelblau's function : } (X_0^2 + X_1 - 11)^2 + (X_0 + X_1^2 - 7)^2 \\ &= X_0^4 + 2X_1X_0^2 - 21X_0^2 + 2X_1^2X_0 - 14X_0 + X_1^4 \\ &\quad - 13X_1^2 - 22X_1 + 170 \end{aligned}$
Modeled Linear Form	$-12.083X_0 - 19.966X_1 + 142.05$
Modeled Quadratic Form	$-14.305X_0 - 6.4260X_1^2 - 11.379X_0 - 19.398X_1 + 162.62$

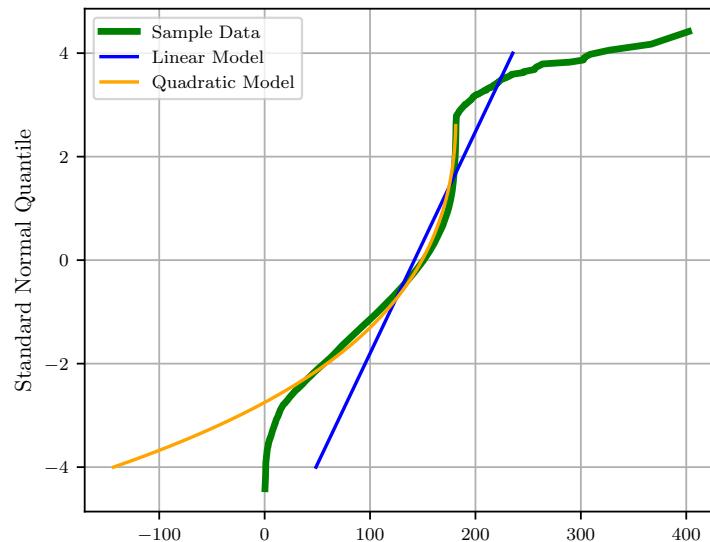


Figure 4.4: Sample data of multivariate quartic form compared with analytic quantiles of modeled linear and quadratic forms

#### 4.10.4 Multivariate Exponential and Quadratic

Table 4.8: Multivariate Exponential and Quadratic Example True and Modeled Forms

True Form	$e^{X_0} + 8X_1^2 - 17X_0$
Modeled Linear Form	$-15.339X_0 - 0.022676X_1 + 9.6711$
Modeled Quadratic Form	$0.70111X_0^2 + 7.8921X_1^2 - 5.3091X_0 + 1.0426$

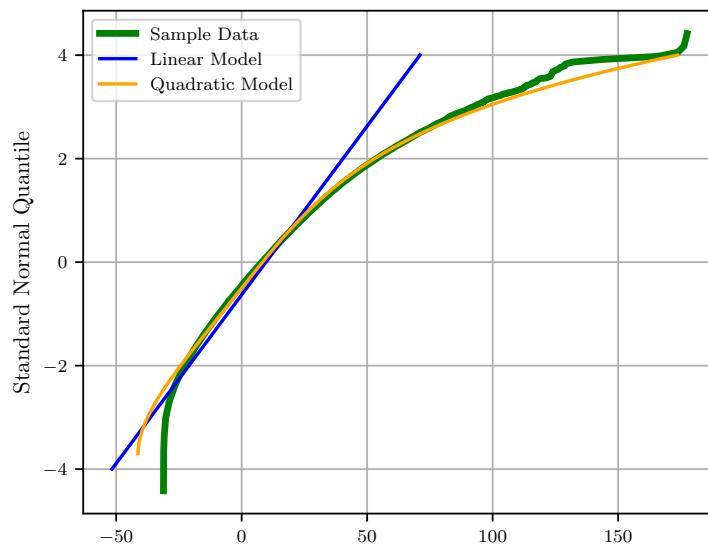


Figure 4.5: Sample data of multivariate exponential and quadratic form compared with analytic quantiles of modeled linear and quadratic forms

#### 4.10.5 Quadratic Modeling Example Observations

Linear and quadratic forms of multivariate standard normal vectors are useful to capture the first and second order terms of a Taylor series expansion. From the examples given in this section, it is clear that the quadratic form is not well suited to model the distribution of black box forms far from the origin which vary significantly from linear or quadratic. The consistency of the quantiles of the quadratic form near the origin could be useful for modeling high dimensional systems for lower sigma as the Taylor expansion is done about the origin. As shown in this chapter, the quantiles (and other statistics such as moments and cumulants) of the quadratic form may be determined analytically, making the quadratic form a useful modeling tool.

### 4.11 Discussion

In this chapter, a complete flow for modeling an unknown function by a quadratic form was outlined. Distribution parameters were then computed not by sampling, but analytically from the quadratic form itself.

A multidimensional Legendre polynomial of order two is used to model the unknown form of the standard multivariate normals as a quadratic form. Next, the quadratic form is broken down by eigenvalue decomposition to reveal an underlying linear equation which is a combination of normal and chi-squared distributed vectors of random variables. Given this new equivalent formulation, raw moments are calculated whereupon central moments are derived. Once the raw and central

moments are available, the cumulants may then be subsequently computed. Normalized quantiles are calculated by the Cornish-Fisher expansion given the normalized cumulants. A final reverse normalization of the normalized quantiles then provides the quantiles of the quadratic model fit to the unknown form.

The procedure outlined above can be useful to provide rough distribution properties where extensive sampling is expensive or impractical. Abstractly, the quadratic form represents the second order Taylor series expansion of the unknown form.

The main contribution in this chapter is the outline of a coherent flow which starts from raw data and ends with extracted statistical information from a sparse quadratic form including moments, cumulants, and quantiles.

# Chapter 5

## Quantile-Based Moments

### 5.1 Computing Moments from Quantile Information

The  $r$ th raw moment of probability distribution of random variable  $\mathbf{X}$  is given by

$$\mathbb{E}[\mathbf{X}^r] = \int_{-\infty}^{\infty} x^r f(x) dx \quad (5.1)$$

where  $f$  is the probability density function (PDF) of  $\mathbf{X}$ .

Analogously, moments can also be written in terms of the cumulative density function (CDF) as follows

$$\mathbb{E}[\mathbf{X}^r] = -r \int_{-\infty}^0 x^{r-1} F(x) dx + r \int_0^{\infty} x^{r-1} (1 - F(x)) dx . \quad (5.2)$$

Now, assuming  $\mathbf{X}$  is piece-wise normally distributed in  $n$  samples,  $\mathbb{E}[\mathbf{X}]$  can be approximated by

$$\mathbb{E}[\mathbf{X}^r] \approx r \sum_{i=1}^{n-1} g_r(x_{(i)}, x_{(i+1)} | \mu_i, \sigma_i) + c \quad (5.3)$$

$$g_r(x_{(i)}, x_{(i+1)} | \mu_i, \sigma_i) = \begin{cases} - \int_{x_{(i)}}^{x_{(i+1)}} x^{r-1} \Phi(x | \mu_i, \sigma_i^2) dx & \text{if } 0 \leq x_{(i)} \leq x_{(i+1)} \\ - \int_0^{x_{(i)}} x^{r-1} \Phi(x | \mu_i, \sigma_i^2) dx & \text{if } x_{(i)} \leq 0 \leq x_{(i+1)} \\ + \int_0^{x_{(i+1)}} x^{r-1} (1 - \Phi(x | \mu_i, \sigma_i^2)) dx \\ \int_{x_{(i)}}^{x_{(i+1)}} x^{r-1} (1 - \Phi(x | \mu_i, \sigma_i^2)) dx & \text{if } x_{(i)} \leq x_{(i+1)} \leq 0 \end{cases} \quad (5.4)$$

By subtracting out the minimum value  $x_{(1)}$ , the discrete distribution becomes non-negative allowing for the significant simplification as follows

$$\mathbb{E}[\mathbf{X}^r] = r \sum_{i=1}^{n-1} \int_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} x^{r-1} [1 - F(x)] dx + x_{(1)} \delta_{i-1}. \quad (5.5)$$

Now, assuming  $\mathbf{X}$  is piece-wise normally distributed in  $n$  samples, the  $r$ th order expectation  $\mathbb{E}[\mathbf{X}^r]$  can be written as

$$\mathbb{E}[\mathbf{X}^r] = r \sum_{i=1}^{n-1} \int_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} x^{r-1} \left[ 1 - \Phi\left(\frac{x - \mu_i}{\sigma_i}\right) \right] dx + x_{(1)} \delta_{i-1} \quad (5.6)$$

where  $\Phi$  is the standard normal CDF and  $x_{(i)}$  is the  $i$ th order statistic. The moments can now be computed in closed form for all  $r$ . Results for  $r \in \{1, 2, 3, 4\}$  are given as follows.

$$\mathbb{E}[\mathbf{X}] = \frac{1}{2} \sum_{i=1}^{n-1} \left[ x - \sigma_i \sqrt{\frac{2}{\pi}} e^{-\frac{(x-\mu_i)^2}{2\sigma_i^2}} + (\mu_i - x) \operatorname{erf}\left(\frac{x-\mu_i}{\sigma_i \sqrt{2}}\right) \right] \Big|_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} + x_{(1)} \quad (5.7)$$

$$\begin{aligned} \mathbb{E}[\mathbf{X}^2] &= \frac{1}{2} \sum_{i=1}^{n-1} \left[ x^2 - \sigma_i (\mu_i + x) \sqrt{\frac{2}{\pi}} e^{-\frac{(x-\mu_i)^2}{2\sigma_i^2}} \right. \\ &\quad \left. + (\mu_i^2 + \sigma_i^2 - x^2) \operatorname{erf}\left(\frac{x-\mu_i}{\sigma_i \sqrt{2}}\right) \right] \Big|_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} \end{aligned} \quad (5.8)$$

$$\begin{aligned} \mathbb{E}[\mathbf{X}^3] &= \frac{1}{2} \sum_{i=1}^{n-1} \left[ x^3 - \sigma_i (\mu_i^2 + 2\sigma_i^2 + \mu_i x + x^2) \sqrt{\frac{2}{\pi}} e^{-\frac{(x-\mu_i)^2}{2\sigma_i^2}} \right. \\ &\quad \left. + (\mu_i^3 + 3\mu_i \sigma_i^2 - x^3) \operatorname{erf}\left(\frac{x-\mu_i}{\sigma_i \sqrt{2}}\right) \right] \Big|_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} \end{aligned} \quad (5.9)$$

$$\begin{aligned} \mathbb{E}[\mathbf{X}^4] &= \frac{1}{2} \sum_{i=1}^{n-1} \left[ x^4 - \sigma_i (\mu_i^3 + 5\mu_i \sigma_i^2 + \mu_i^2 x + 3\sigma_i^2 x + \mu_i x^2 + x^3) \sqrt{\frac{2}{\pi}} e^{-\frac{(x-\mu_i)^2}{2\sigma_i^2}} \right. \\ &\quad \left. + (\mu_i^4 + 6\mu_i^2 \sigma_i^2 + 3\sigma_i^4 - x^4) \operatorname{erf}\left(\frac{x-\mu_i}{\sigma_i \sqrt{2}}\right) \right] \Big|_{x_{(i)} - x_{(1)}}^{x_{(i+1)} - x_{(1)}} \end{aligned} \quad (5.10)$$

The mean, standard deviation, skewness and kurtosis can then be computed from these expectations with

$$\mu = \mathbb{E}[\mathbf{X}] \quad (\text{mean}) \quad (5.11)$$

$$\sigma = \sqrt{\mathbb{E}[\mathbf{X}^2] - \mathbb{E}[\mathbf{X}]^2} \quad (\text{standard deviation}) \quad (5.12)$$

$$\gamma = \frac{2\mathbb{E}[\mathbf{X}]^3 - 3\mathbb{E}[\mathbf{X}]\mathbb{E}[\mathbf{X}^2] + \mathbb{E}[\mathbf{X}^3]}{\sigma^3} \quad (\text{skewness}) \quad (5.13)$$

$$\kappa = \frac{-3\mathbb{E}[\mathbf{X}]^4 + 6\mathbb{E}[\mathbf{X}^2]\mathbb{E}[\mathbf{X}]^2 - 4\mathbb{E}[\mathbf{X}]\mathbb{E}[\mathbf{X}^3] + \mathbb{E}[\mathbf{X}^4]}{\sigma^4} \quad (\text{kurtosis}) . \quad (5.14)$$

## 5.2 Experiments

In order to test the quantile based moment calculation method developed in the previous section, it is compared against the sample based moment computation for a wide range of probability distributions. For each probability distribution setting, 10K trials of 10K samples are simulated and the sample and quantile based moment calculations methods are compared.

Tables 5.1, 5.2, 5.3, and 5.4 provide the mean, standard deviation, skewness, and kurtosis comparisons, respectively. Further details about the statistic distribution for selected probability distributions across trials are given in Figures 5.1-5.8. Where a red line appears on the plot, it indicates the given population statistic.

Table 5.1: Sample vs. Quantile Based Moment Computation : Mean

Prob Distribution	(Population)	Sample	Quantile	Abs. Error
Normal ( $\mu = 1$ )	0.000e+00	-7.185e-05	-6.890e-05	2.952e-06
Normal ( $\mu = 2$ )	0.000e+00	4.203e-04	4.189e-04	1.403e-06
Normal ( $\mu = 4$ )	0.000e+00	-1.319e-03	-1.321e-03	1.873e-06
Log Normal ( $s = 0.5$ )	1.133e+00	1.133e+00	1.133e+00	9.428e-06
Log Normal ( $s = 1$ )	1.649e+00	1.648e+00	1.648e+00	1.231e-04
Log Normal ( $s = 1.5$ )	3.080e+00	3.078e+00	3.076e+00	1.222e-03
Skew Normal ( $\alpha = -4$ )	-7.741e-01	-7.742e-01	-7.742e-01	3.456e-06
Skew Normal ( $\alpha = -2$ )	-7.136e-01	-7.137e-01	-7.137e-01	3.971e-06
Skew Normal ( $\alpha = 0$ )	0.000e+00	-5.397e-05	-5.317e-05	8.020e-07
Skew Normal ( $\alpha = 2$ )	7.136e-01	7.136e-01	7.136e-01	3.616e-06
Skew Normal ( $\alpha = 4$ )	7.741e-01	7.741e-01	7.741e-01	3.247e-06
Weibull ( $\lambda = 1, k = 1$ )	1.000e+00	9.998e-01	9.998e-01	1.150e-05
Weibull ( $\lambda = 1, k = 2$ )	8.862e-01	8.861e-01	8.861e-01	2.446e-06
Weibull ( $\lambda = 1, k = 4$ )	9.064e-01	9.064e-01	9.064e-01	9.057e-08
Beta ( $a = 1.5, b = 1$ )	6.000e-01	5.999e-01	5.999e-01	3.571e-08
Beta ( $a = 1.5, b = 2$ )	4.286e-01	4.286e-01	4.286e-01	2.837e-08
Beta ( $a = 1.5, b = 4$ )	2.727e-01	2.727e-01	2.727e-01	3.987e-07
Student's t ( $\nu = 2$ )	0.000e+00	-1.987e-04	-1.214e-04	7.733e-05
Student's t ( $\nu = 4$ )	0.000e+00	-1.498e-04	-1.737e-04	2.391e-05
Student's t ( $\nu = \infty$ )	0.000e+00	-1.871e-05	-1.901e-05	3.011e-07
Chi-square ( $k = 1$ )	1.000e+00	1.000e+00	1.000e+00	2.909e-05
Chi-square ( $k = 3$ )	3.000e+00	3.000e+00	3.000e+00	2.961e-05
Chi-square ( $k = 6$ )	1.600e+01	1.600e+01	1.600e+01	1.528e-05

Table 5.2: Sample vs. Quantile Based Moment Computation : Standard Deviation

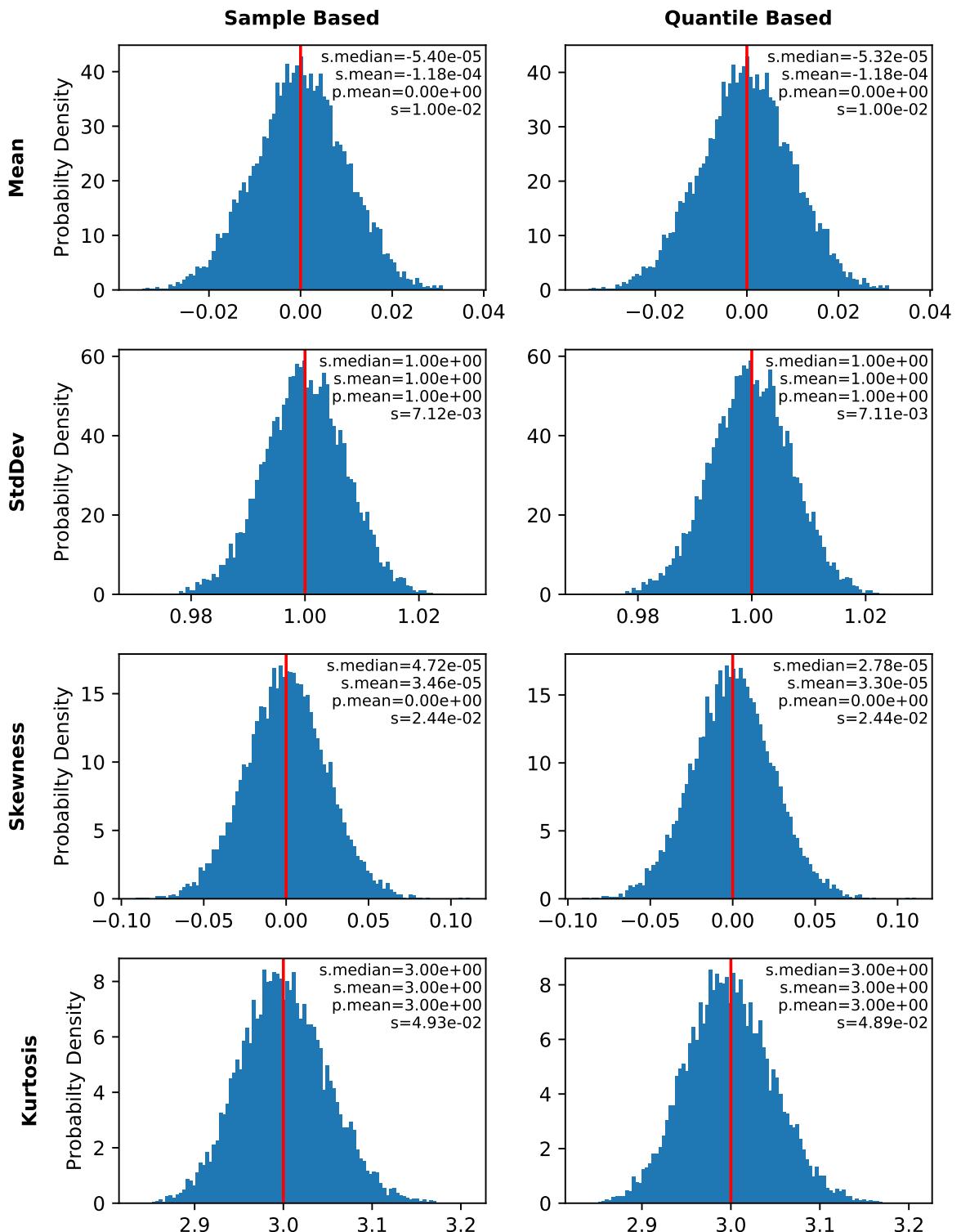
Prob Distribution	(Population)	Sample	Quantile	Abs. Error
Normal ( $\mu = 1$ )	1.000e+00	9.999e-01	9.998e-01	7.887e-05
Normal ( $\mu = 2$ )	2.000e+00	2.000e+00	2.000e+00	1.475e-04
Normal ( $\mu = 4$ )	4.000e+00	4.000e+00	3.999e+00	3.110e-04
Log Normal ( $s = 0.5$ )	6.039e-01	6.036e-01	6.035e-01	1.565e-04
Log Normal ( $s = 1$ )	2.161e+00	2.147e+00	2.144e+00	3.415e-03
Log Normal ( $s = 1.5$ )	8.974e+00	8.408e+00	8.356e+00	5.197e-02
Skew Normal ( $\alpha = -4$ )	6.331e-01	6.332e-01	6.331e-01	5.355e-05
Skew Normal ( $\alpha = -2$ )	7.005e-01	7.005e-01	7.004e-01	6.386e-05
Skew Normal ( $\alpha = 0$ )	1.000e+00	1.000e+00	9.999e-01	7.908e-05
Skew Normal ( $\alpha = 2$ )	7.005e-01	7.005e-01	7.005e-01	6.246e-05
Skew Normal ( $\alpha = 4$ )	6.331e-01	6.331e-01	6.330e-01	5.593e-05
Weibull ( $\lambda = 1, k = 1$ )	1.000e+00	9.997e-01	9.996e-01	1.648e-04
Weibull ( $\lambda = 1, k = 2$ )	4.633e-01	4.632e-01	4.632e-01	3.560e-05
Weibull ( $\lambda = 1, k = 4$ )	2.543e-01	2.542e-01	2.542e-01	1.587e-05
Beta ( $a = 1.5, b = 1$ )	2.619e-01	2.619e-01	2.619e-01	1.319e-05
Beta ( $a = 1.5, b = 2$ )	2.333e-01	2.333e-01	2.333e-01	1.187e-05
Beta ( $a = 1.5, b = 4$ )	1.747e-01	1.747e-01	1.747e-01	1.025e-05
Student's t ( $\nu = 2$ )	inf	3.111e+00	3.077e+00	3.419e-02
Student's t ( $\nu = 4$ )	1.414e+00	1.410e+00	1.409e+00	1.273e-03
Student's t ( $\nu = \infty$ )	1.000e+00	1.000e+00	9.999e-01	9.277e-05
Chi-square ( $k = 1$ )	1.414e+00	1.414e+00	1.414e+00	3.504e-04
Chi-square ( $k = 3$ )	2.449e+00	2.449e+00	2.449e+00	3.625e-04
Chi-square ( $k = 6$ )	5.657e+00	5.656e+00	5.656e+00	5.113e-04

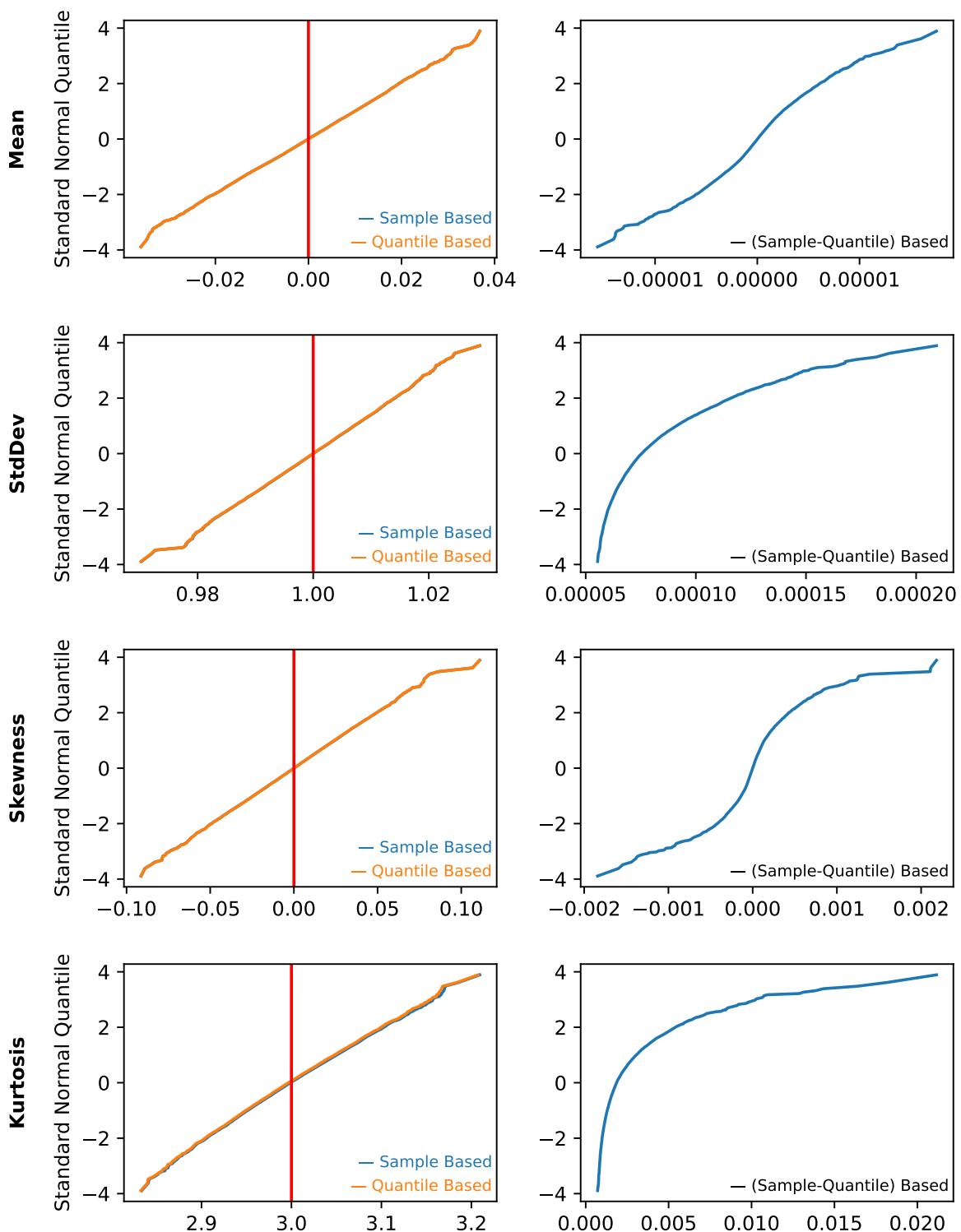
Table 5.3: Sample vs. Quantile Based Moment Computation : Skewness

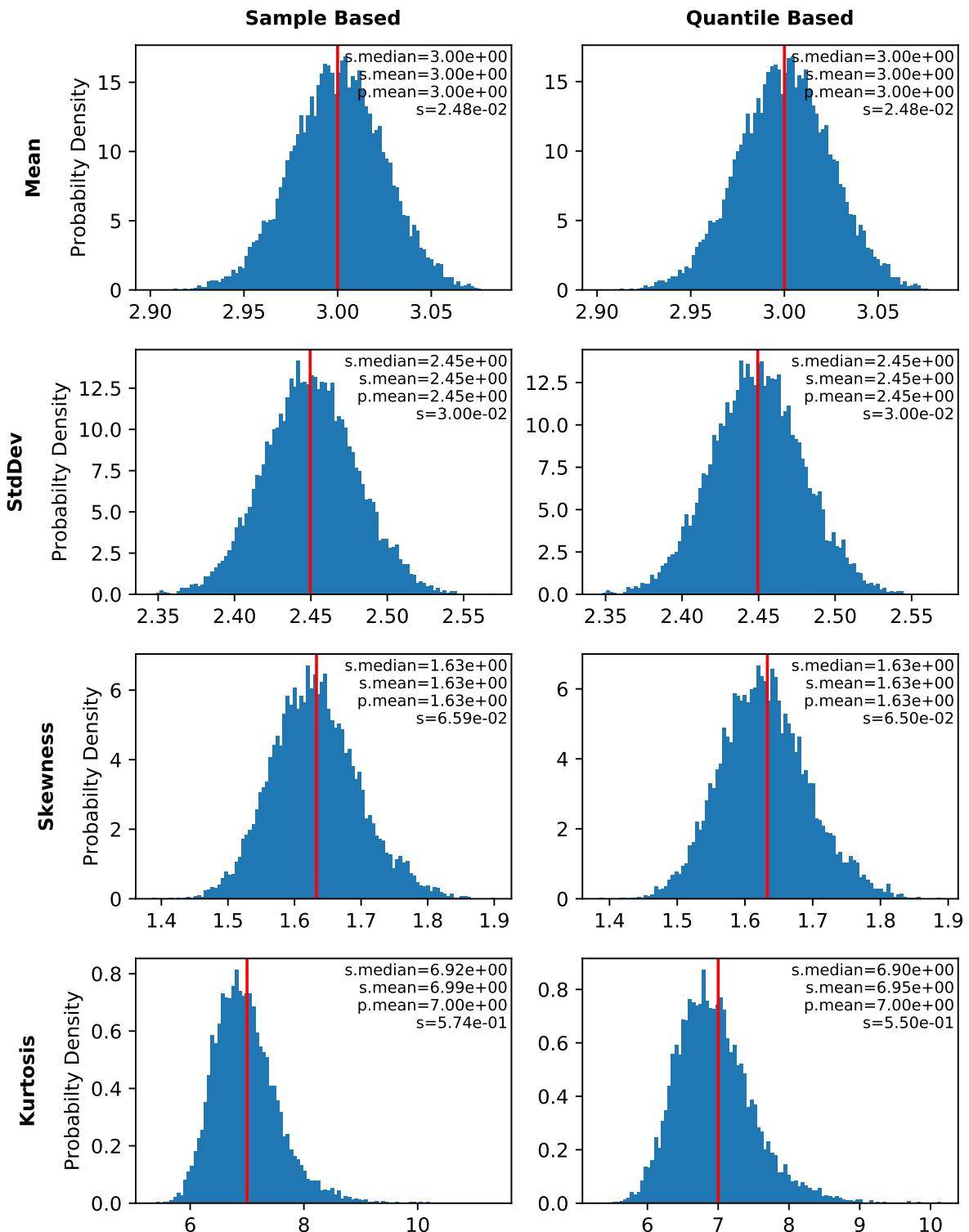
Prob Distribution	(Population)	Sample	Quantile	Abs. Error
Normal ( $\mu = 1$ )	0.000e+00	1.967e-04	2.062e-04	9.429e-06
Normal ( $\mu = 2$ )	0.000e+00	2.818e-04	2.962e-04	1.436e-05
Normal ( $\mu = 4$ )	0.000e+00	-1.267e-04	-1.390e-04	1.229e-05
Log Normal ( $s = 0.5$ )	1.750e+00	1.731e+00	1.727e+00	4.295e-03
Log Normal ( $s = 1$ )	6.185e+00	5.332e+00	5.271e+00	6.109e-02
Log Normal ( $s = 1.5$ )	3.347e+01	1.360e+01	1.322e+01	3.798e-01
Skew Normal ( $\alpha = -4$ )	-7.844e-01	-7.840e-01	-7.835e-01	4.858e-04
Skew Normal ( $\alpha = -2$ )	-4.538e-01	-4.536e-01	-4.533e-01	2.781e-04
Skew Normal ( $\alpha = 0$ )	0.000e+00	4.725e-05	2.779e-05	1.945e-05
Skew Normal ( $\alpha = 2$ )	4.538e-01	4.536e-01	4.532e-01	3.334e-04
Skew Normal ( $\alpha = 4$ )	7.844e-01	7.833e-01	7.828e-01	4.895e-04
Weibull ( $\lambda = 1, k = 1$ )	2.000e+00	1.991e+00	1.988e+00	2.866e-03
Weibull ( $\lambda = 1, k = 2$ )	6.311e-01	6.306e-01	6.302e-01	3.924e-04
Weibull ( $\lambda = 1, k = 4$ )	-8.724e-02	-8.730e-02	-8.734e-02	4.415e-05
Beta ( $a = 1.5, b = 1$ )	-3.395e-01	-3.391e-01	-3.390e-01	5.217e-05
Beta ( $a = 1.5, b = 2$ )	2.227e-01	2.225e-01	2.224e-01	3.692e-05
Beta ( $a = 1.5, b = 4$ )	6.939e-01	6.941e-01	6.939e-01	1.579e-04
Student's t ( $\nu = 2$ )	undefined	-9.000e-02	-1.033e-01	1.329e-02
Student's t ( $\nu = 4$ )	0.000e+00	2.850e-03	3.402e-03	5.519e-04
Student's t ( $\nu = \infty$ )	0.000e+00	2.066e-05	2.680e-05	6.143e-06
Chi-square ( $k = 1$ )	2.828e+00	2.811e+00	2.806e+00	5.238e-03
Chi-square ( $k = 3$ )	1.633e+00	1.628e+00	1.626e+00	2.253e-03
Chi-square ( $k = 6$ )	7.071e-01	7.055e-01	7.048e-01	7.431e-04

Table 5.4: Sample vs. Quantile Based Moment Computation : Kurtosis

Prob Distribution	(Population)	Sample	Quantile	Abs. Error
Normal ( $\mu = 1$ )	3.000e+00	2.999e+00	2.997e+00	2.064e-03
Normal ( $\mu = 2$ )	3.000e+00	2.999e+00	2.996e+00	2.159e-03
Normal ( $\mu = 4$ )	3.000e+00	2.999e+00	2.997e+00	2.307e-03
Log Normal ( $s = 0.5$ )	8.898e+00	8.501e+00	8.441e+00	5.982e-02
Log Normal ( $s = 1$ )	1.139e+02	5.795e+01	5.610e+01	1.858e+00
Log Normal ( $s = 1.5$ )	1.008e+04	3.270e+02	3.070e+02	2.003e+01
Skew Normal ( $\alpha = -4$ )	3.633e+00	3.628e+00	3.624e+00	3.943e-03
Skew Normal ( $\alpha = -2$ )	3.305e+00	3.302e+00	3.299e+00	2.941e-03
Skew Normal ( $\alpha = 0$ )	3.000e+00	2.999e+00	2.997e+00	2.178e-03
Skew Normal ( $\alpha = 2$ )	3.305e+00	3.302e+00	3.299e+00	3.113e-03
Skew Normal ( $\alpha = 4$ )	3.633e+00	3.627e+00	3.623e+00	3.954e-03
Weibull ( $\lambda = 1, k = 1$ )	9.000e+00	8.846e+00	8.808e+00	3.835e-02
Weibull ( $\lambda = 1, k = 2$ )	3.245e+00	3.240e+00	3.237e+00	2.942e-03
Weibull ( $\lambda = 1, k = 4$ )	2.748e+00	2.749e+00	2.748e+00	1.011e-03
Beta ( $a = 1.5, b = 1$ )	2.051e+00	2.050e+00	2.050e+00	1.293e-04
Beta ( $a = 1.5, b = 2$ )	2.140e+00	2.140e+00	2.140e+00	1.849e-04
Beta ( $a = 1.5, b = 4$ )	2.931e+00	2.930e+00	2.929e+00	9.399e-04
Student's t ( $\nu = 2$ )	undefined	3.613e+02	3.213e+02	3.998e+01
Student's t ( $\nu = 4$ )	undefined	1.129e+01	1.093e+01	3.625e-01
Student's t ( $\nu = \infty$ )	3.000e+00	2.999e+00	2.997e+00	1.966e-03
Chi-square ( $k = 1$ )	1.500e+01	1.461e+01	1.451e+01	9.566e-02
Chi-square ( $k = 3$ )	7.000e+00	6.921e+00	6.896e+00	2.450e-02
Chi-square ( $k = 6$ )	3.750e+00	3.736e+00	3.730e+00	6.080e-03

Figure 5.1: Moment Trials Density : Normal ( $\mu = 1$ )

Figure 5.2: Moment Trials QQ Plot and Delta QQ Plot : Normal ( $\mu = 1$ )

Figure 5.3: Moment Trials Density : Chi-square ( $k = 3$ )

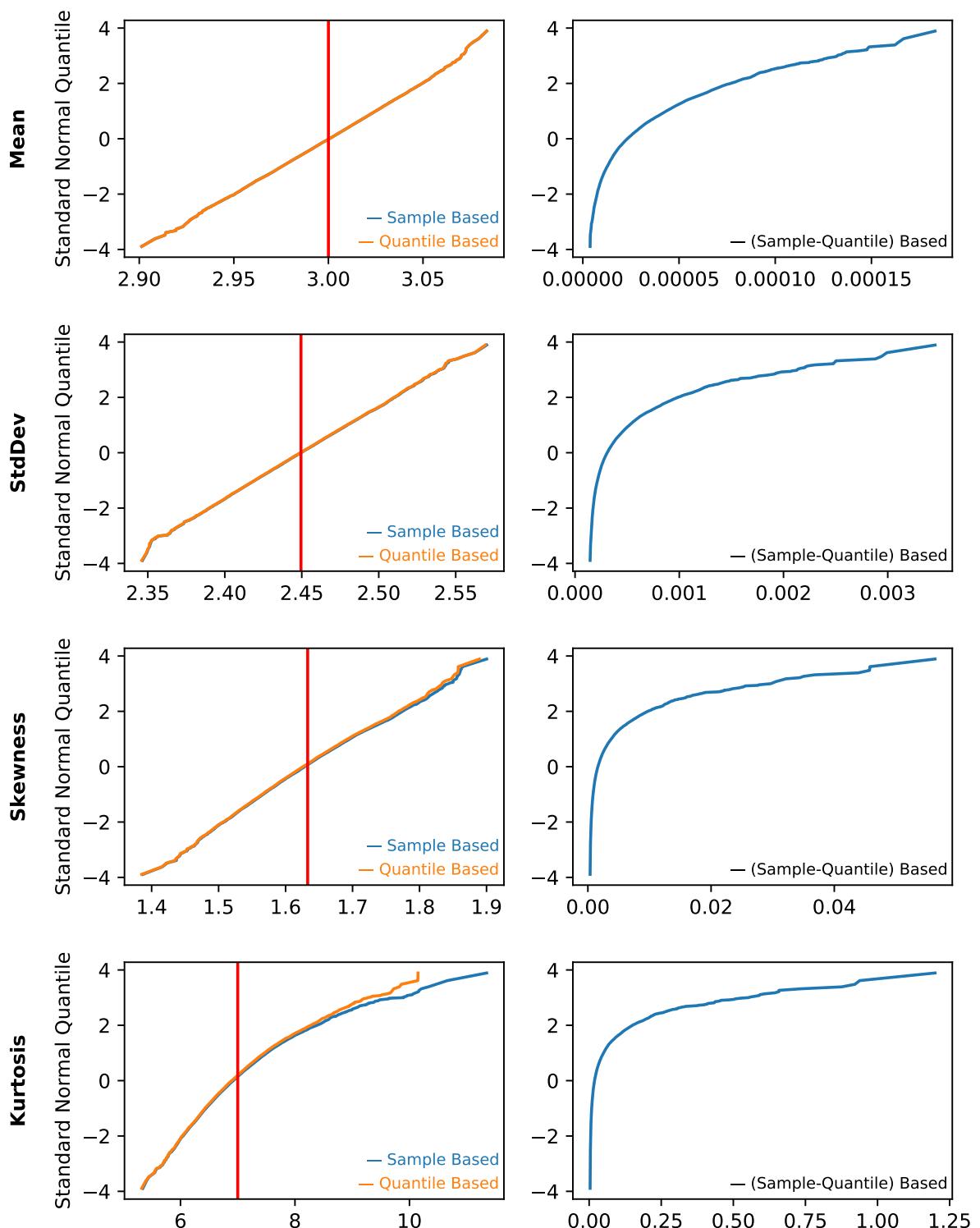
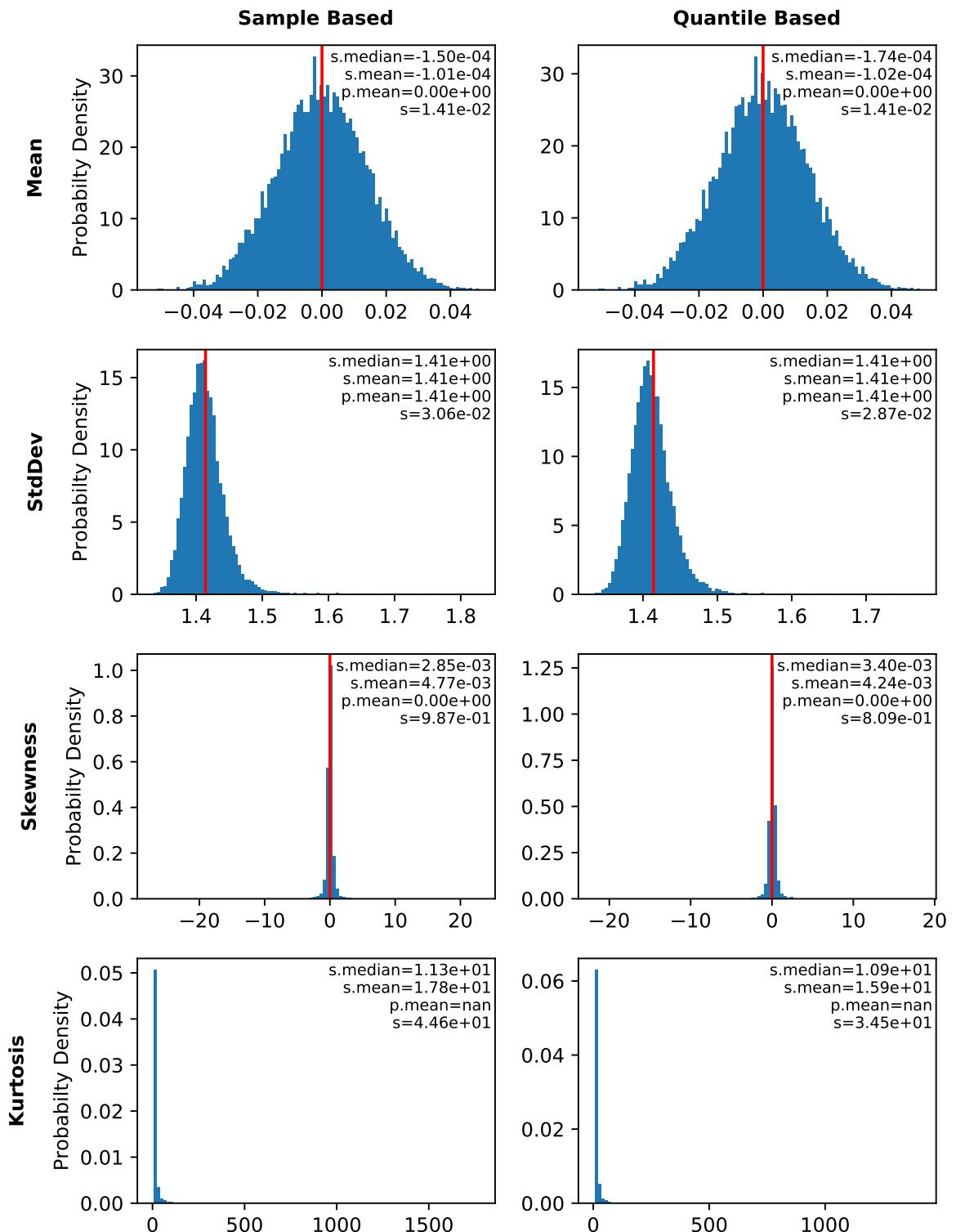
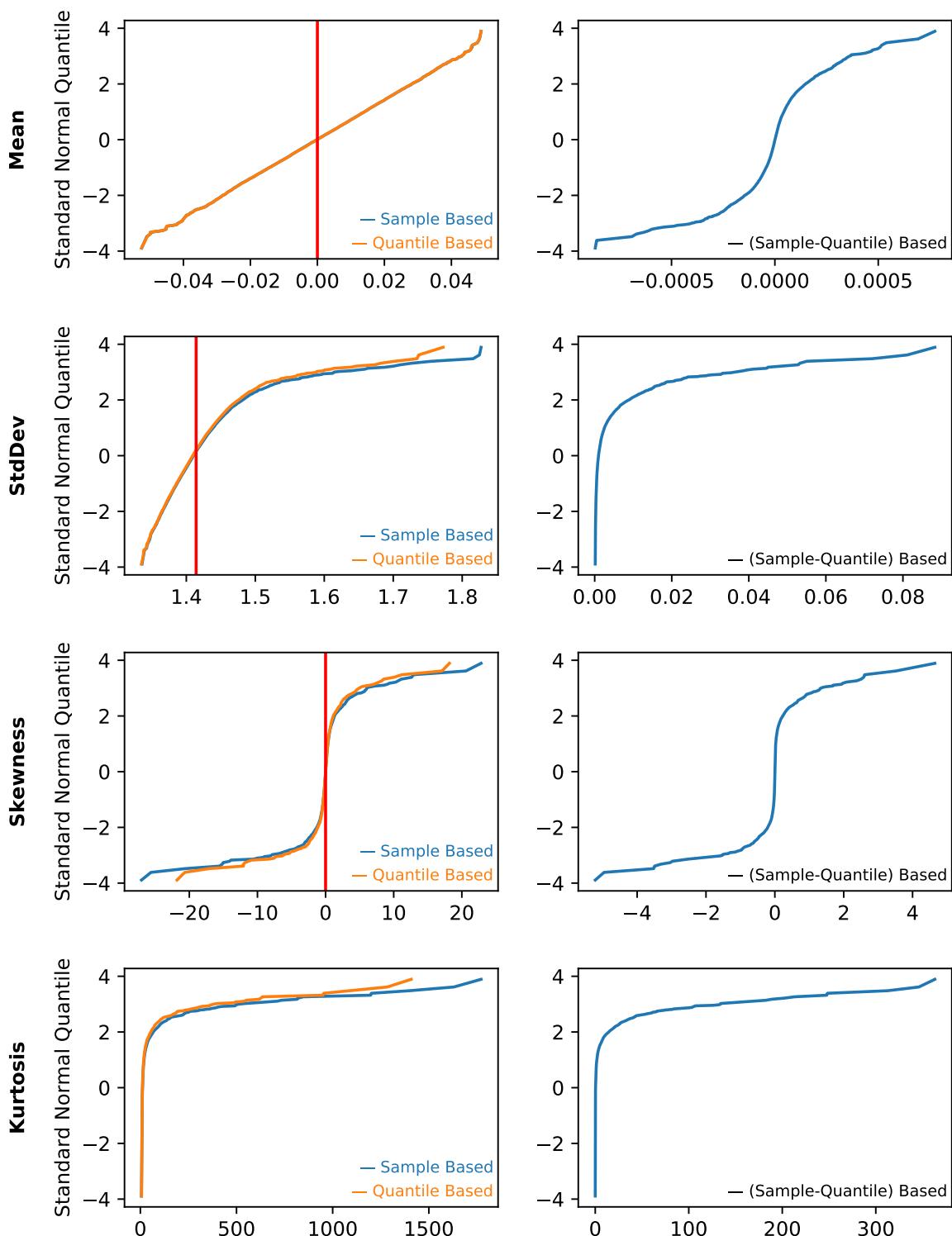
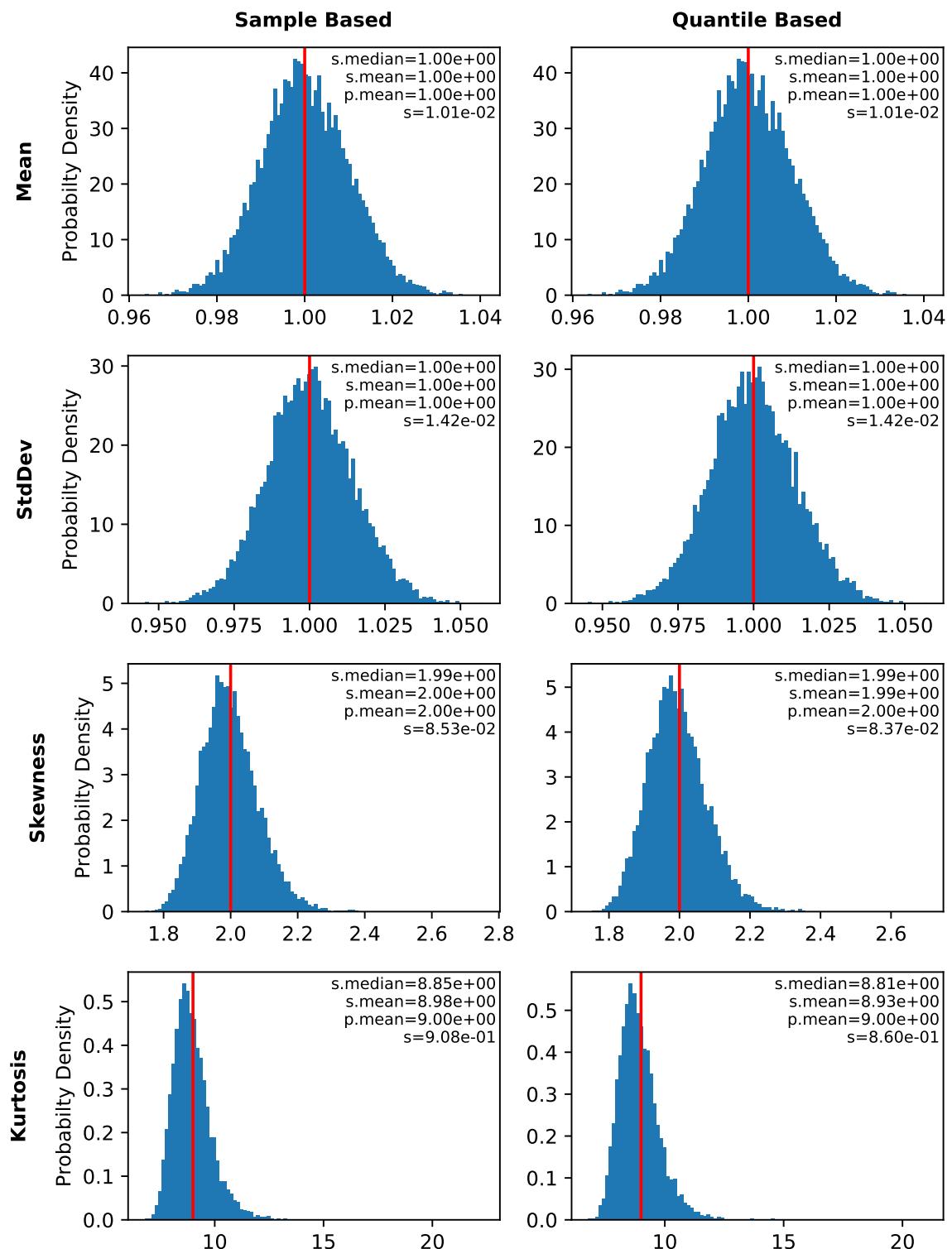


Figure 5.4: Moment Trials QQ Plot and Delta QQ Plot : Chi-square ( $k = 3$ )

Figure 5.5: Moment Trials Density : Student's t ( $\nu = 4$ )

Figure 5.6: Moment Trials QQ Plot and Delta QQ Plot : Student's t ( $\nu = 4$ )

Figure 5.7: Moment Trials Density : Weibull ( $\lambda = 1, k = 1$ )

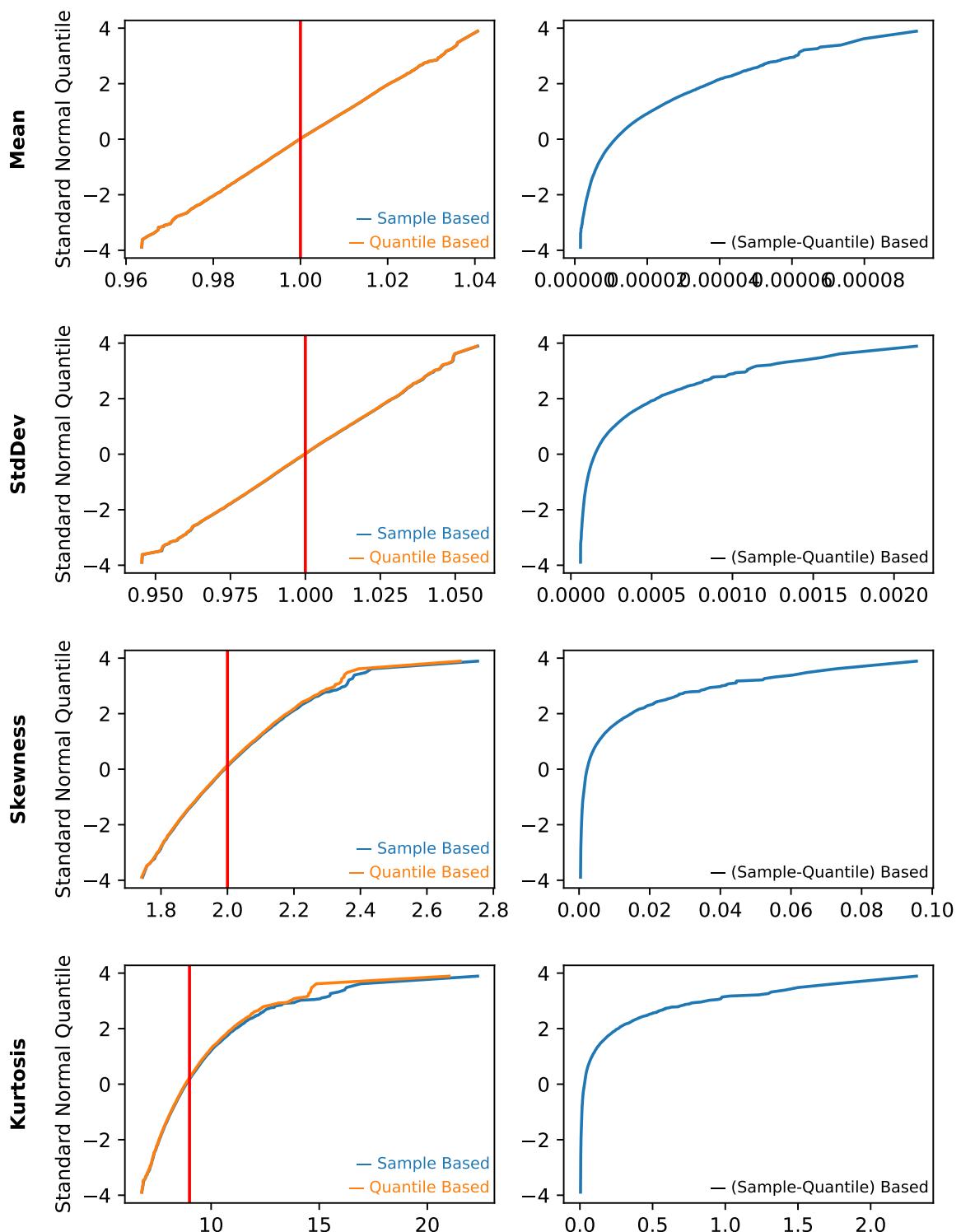


Figure 5.8: Moment Trials QQ Plot and Delta QQ Plot : Weibull ( $\lambda = 1, k = 1$ )

### **5.3 Discussion**

Quantile based moment calculation, developed in this chapter, is a useful method to approximate sample moments. While the technique is inherently predicated upon the local normality assumption, it is shown to work well for a wide variety of random variable distributions. As is evident from the experimental results, the accuracy of quantile based moment calculations is greater for lower order moments than higher order moments with respect to the sample moment reference. The even order moments appear to have a small positive bias, though this is an artifact of the even order exponents in the quantile based moment calculation. As approximation to the sample moments, the quantile based moments provide an alternative method of moment calculation when the full sample set is not available.

# Chapter 6

## Applications

This chapter deals with applications of the previously defined methods in the realm of Electronic Design Automation (EDA). Specifically, we consider SPICE circuit simulation. Circuit designers are interested in distribution properties of circuit measurements, as they are directly related to the predicted yield or circuit performance.

For an SRAM bit cell designer, the distribution of read current and noise margin will be very important. For a standard cell logic designer, the distribution of delay and slope will be very important.

In the following sections, the methods of In-order Multivariate Sampling and quantile-based moment calculation are applied to these problems. For In-order Multivariate Sampling, it is shown that the number of Monte Carlo samples required to accurately characterize the tail behavior is greatly reduced compared to simple random sampling. The quantile-based moment calculations are also provided and compared against standard calculation methods.

## 6.1 Circuits

In this chapter, the following circuits described in Table 6.1 are used for testing the proposed algorithms in Chapters 3-5.

Table 6.1: Circuit Characteristics

Index	Circuit	Node	FET	Res	Cap
1	Inverter	7nm	6	151	259
2	AOI	16nm	80	1064	2600
3	Clock Gate	16nm	122	1879	3578
4	Operational Amplifier	0.2 μm	8	4	3

## 6.2 Monotonicity Verification

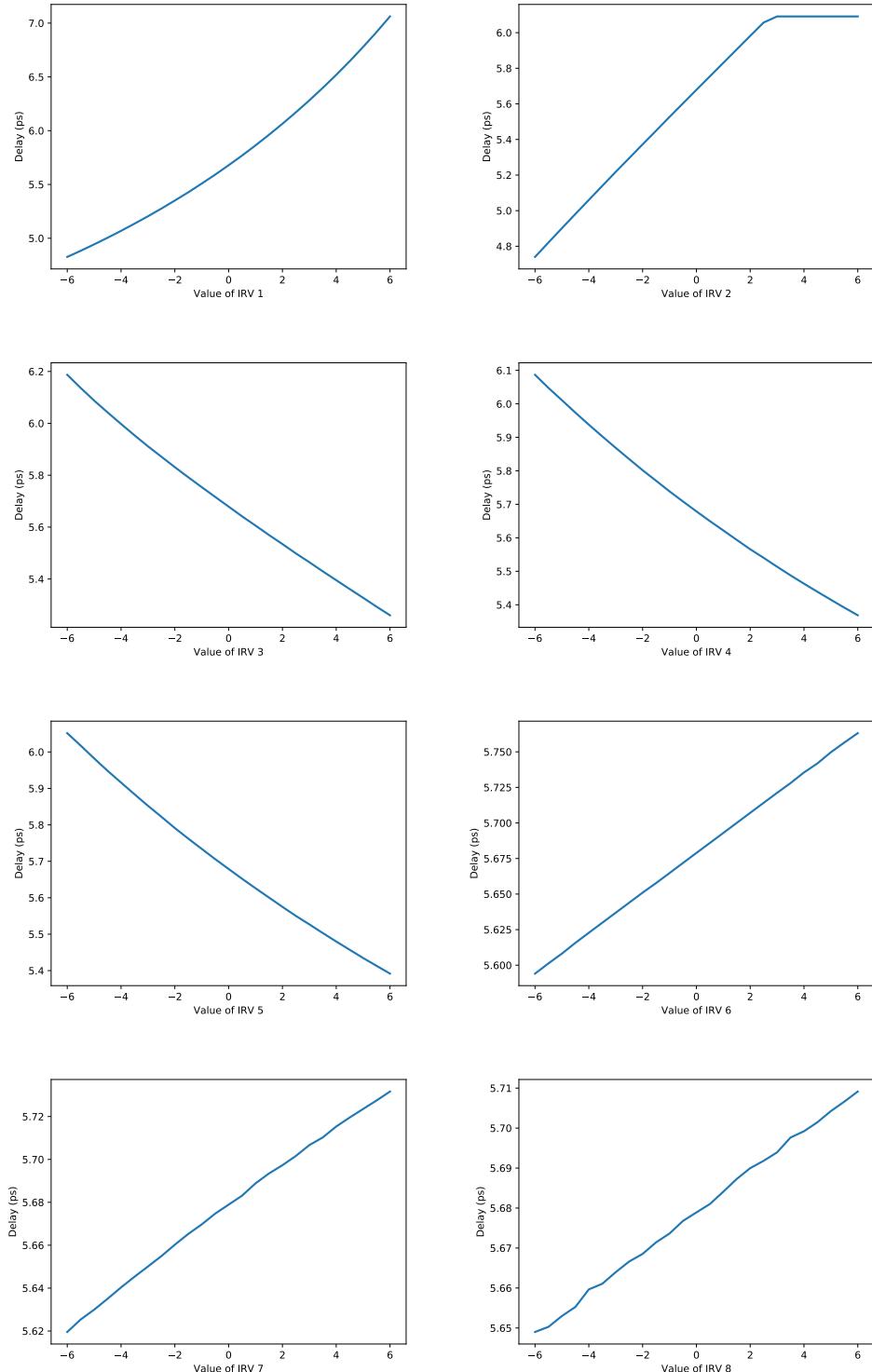


Figure 6.1: Monotonicity plots of delay measurement of an inverter circuit in 16nm technology

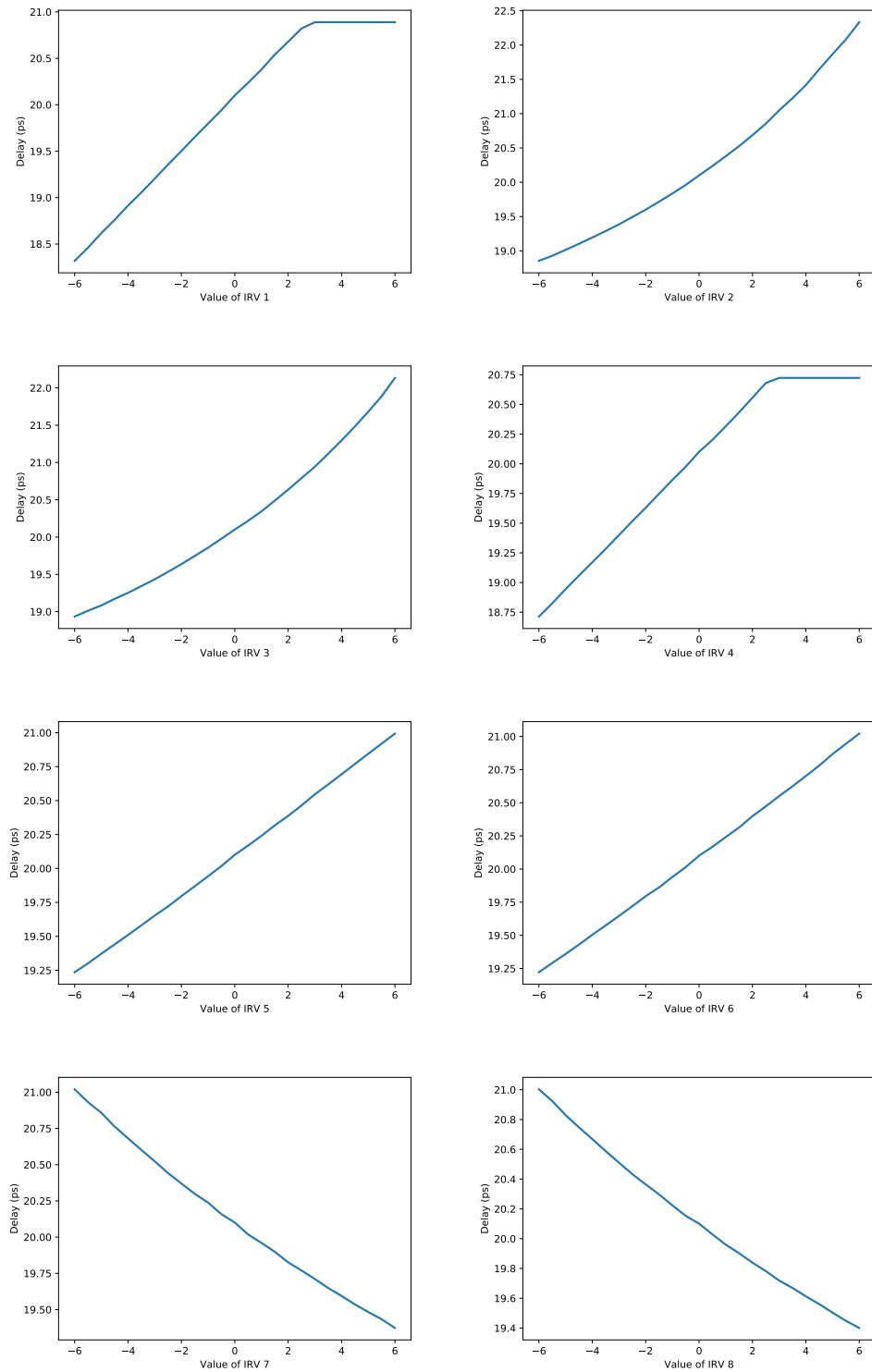


Figure 6.2: Monotonicity plots of delay measurement of a MAJ circuit in 16nm technology

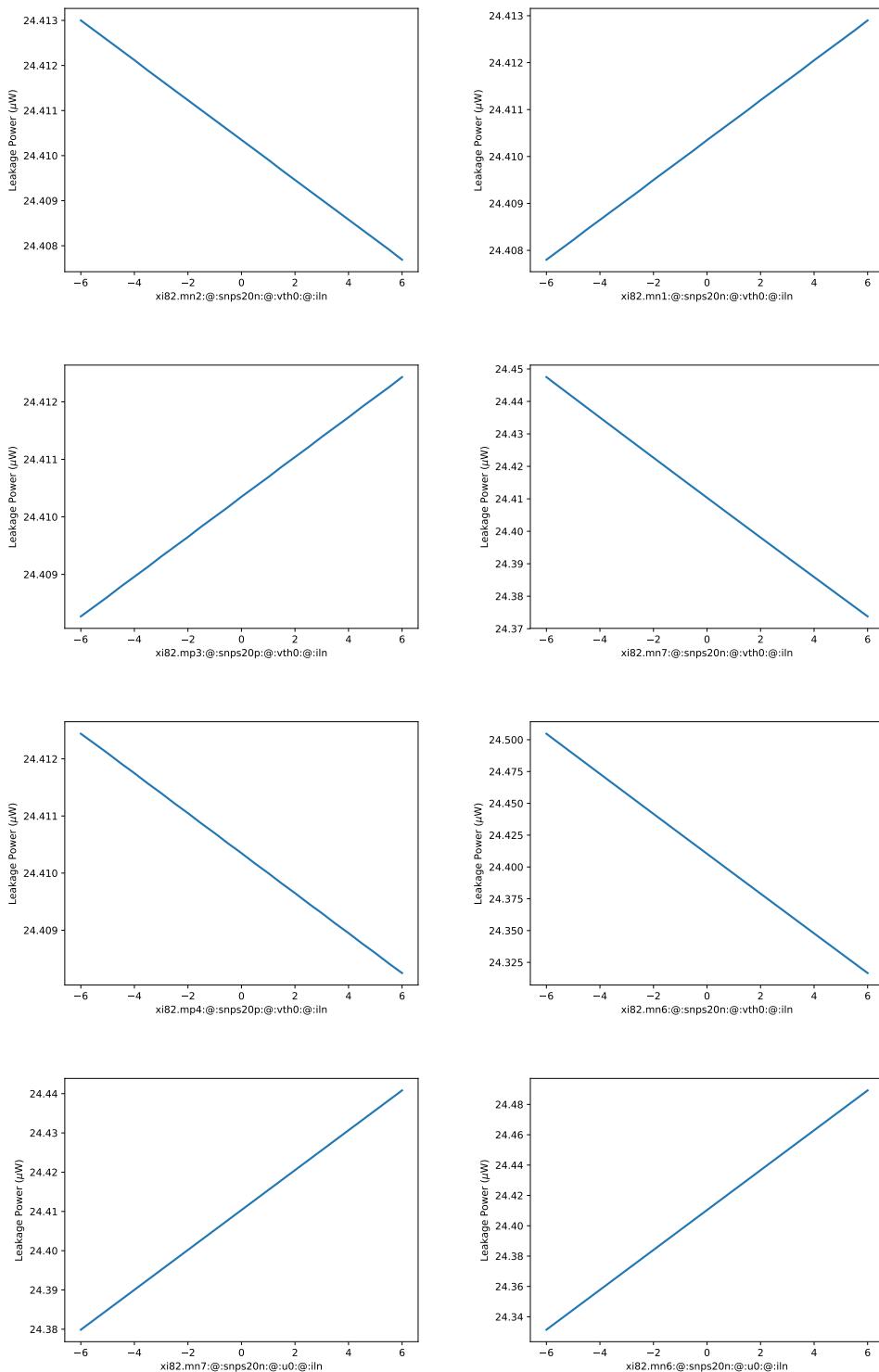


Figure 6.3: Monotonicity plots of delay measurement of a operational amplifier circuit in  $0.2 \mu\text{m}$  technology

### 6.3 In-Order Multivariate Sampling Experiments

In Chapter 3, it was shown that, assuming a linear model for the output response, there is a direct theoretical justification that rare samples in the output space correspond to rare samples in the inputs space. It was further argued that this principle also holds when the output response is monotonic.

In this experiment, we investigate the idea that rare inputs correspond well to rare output responses in the context of circuit simulation. Figures 6.4 - 6.6 show an overlay of the measure value distribution and sample count. The multivariate standard normal input distance from the origin, which is directly related to the input probability density, is recorded on the X axis. The colored lines represent the measure value at a given percentile and is shown on the left-Y axis. The black bell curve corresponds to sample count which is shown on the right-Y axis.

The results confirm that rare samples for the input space do indeed correspond to rare samples in the output space for real circuits. More specifically, when measuring delay for the inverter circuit at in Figure 6.4, delay measurements near the tail of the distribution tend to occur at input samples (drawn from a multivariate normal distribution) which lie further from the origin.

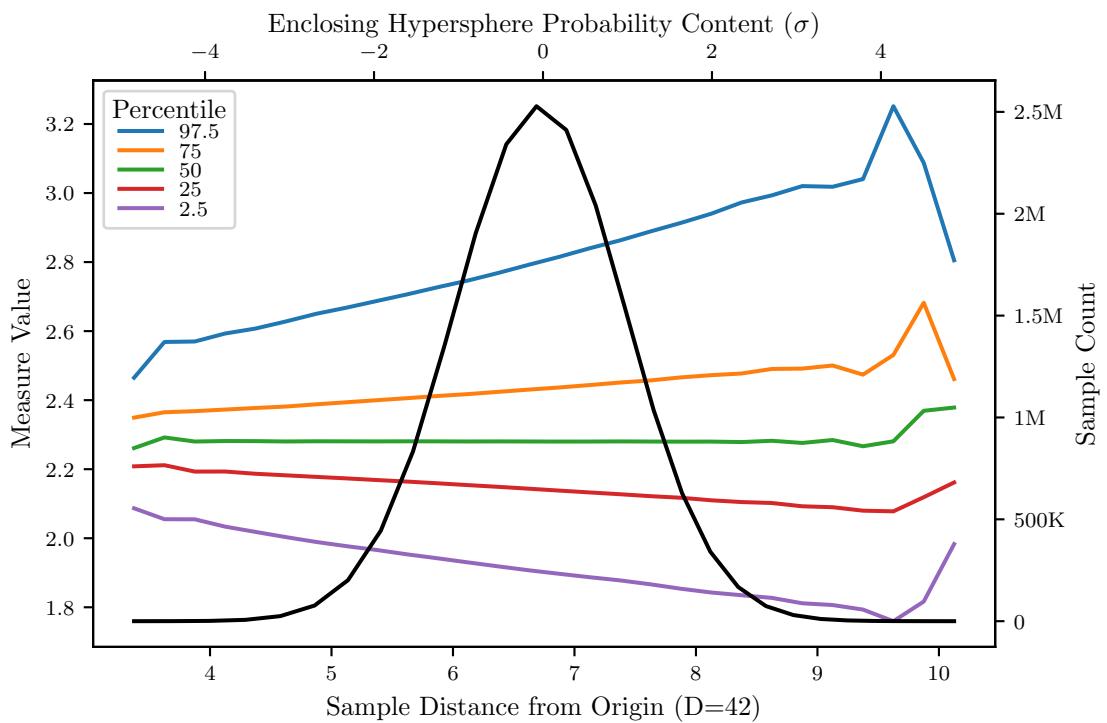


Figure 6.4: Origin Distance versus Measure Percentile : 7nm Inverter Delay

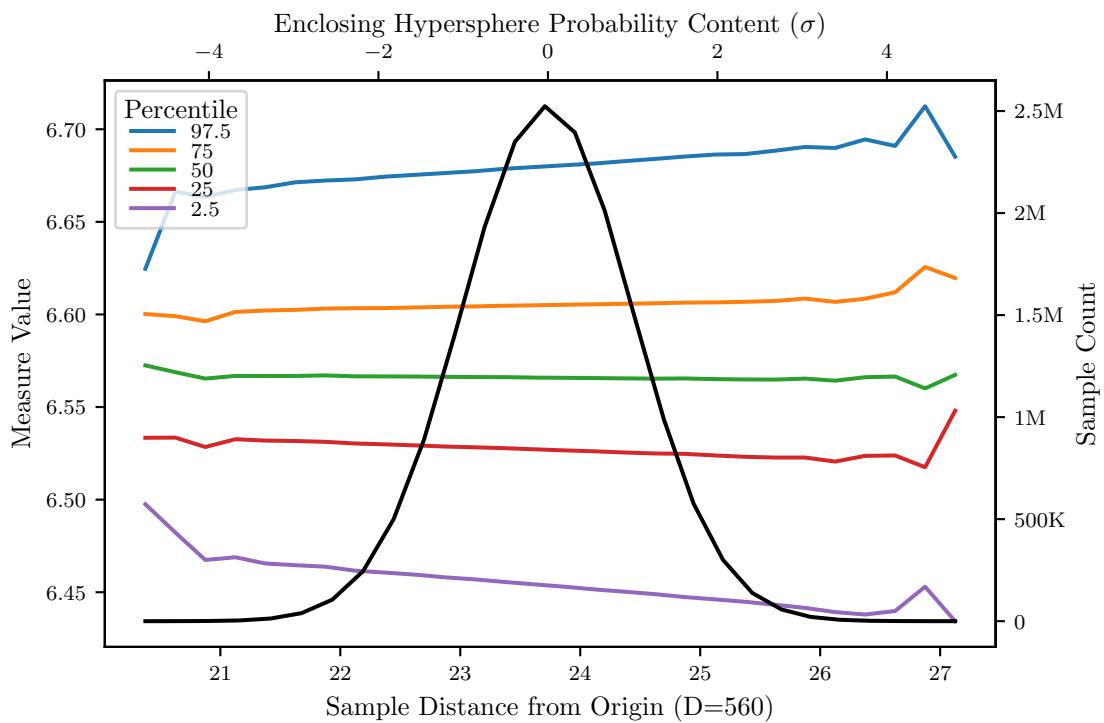


Figure 6.5: Origin Distance versus Measure Percentile : 16nm AOI Delay

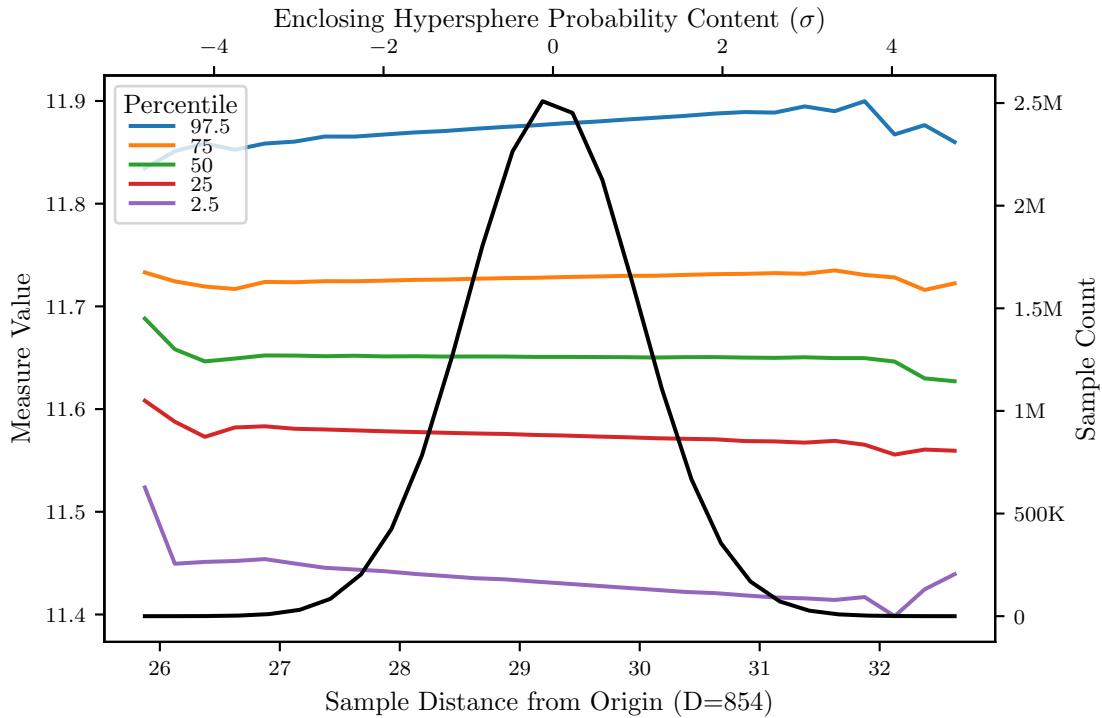


Figure 6.6: Origin Distance versus Measure Percentile : 16nm CKGTPLT Measure

## 6.4 Linear and Quadratic Modeling with Direct Model-Based Quantile Computation

In this section, we demonstrate the ability to compute quantiles directly from quadratic models for circuit measures. The flow follows that developed in Chapter 4, including quadratic model extraction via sparse Legendre polynomials through quantile estimation via Cornish-Fisher expansion. Figure 6.7 represents the distribution of leakage power of an operational amplifier. The quadratic model is better

able to capture the distribution than the linear. From this example, we find along with previous study of quadratic modeling in Chapter 4, the quadratic form can provide good approximations for certain classes of maps of the multivariate normal distribution, but is not a universal method.

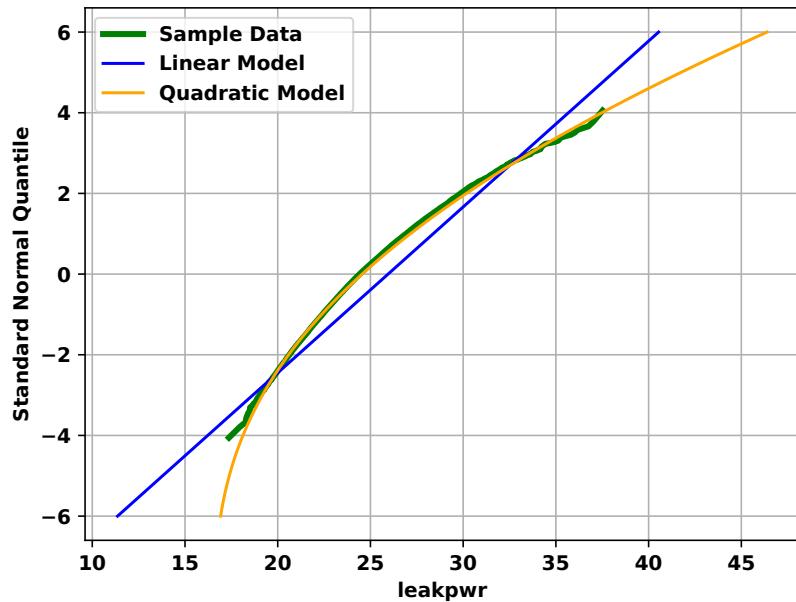


Figure 6.7: QQ plots of MC sample data versus quantiles of linear and quadratic models extracted directly : operational amplifier in 0.2  $\mu\text{m}$  technology

## 6.5 Quantile-Based Moment Experiments

Note that while the full dataset has 18M samples, the quantile information consist of just 3K samples. This is a significant compression, making computation of moments from quantile information fast despite their rather complicated formulation.

The QQ plots of delay measurements for a 7nm inverter circuit is shown in Figure 6.8 and a comparison of the sample and quantile moments is given in Table 6.2

Table 6.2: Comparison of sample and quantile-based moments for a 7nm inverter circuit

	Sample Moments		Quantile Moments		Error	
	meas_1	meas_2	meas_1	meas_2	meas_1	meas_2
<b>Mean</b>	2.2973	6.6810	2.2941	6.6734	0.136%	0.113%
<b>StdDev</b>	0.2213	0.5531	0.2213	0.5532	0.004%	0.004%
<b>Skewness</b>	0.5451	0.4579	0.5460	0.4589	0.165%	0.198%
<b>Kurtosis</b>	3.6750	3.4591	3.6769	3.4608	0.051%	0.049%

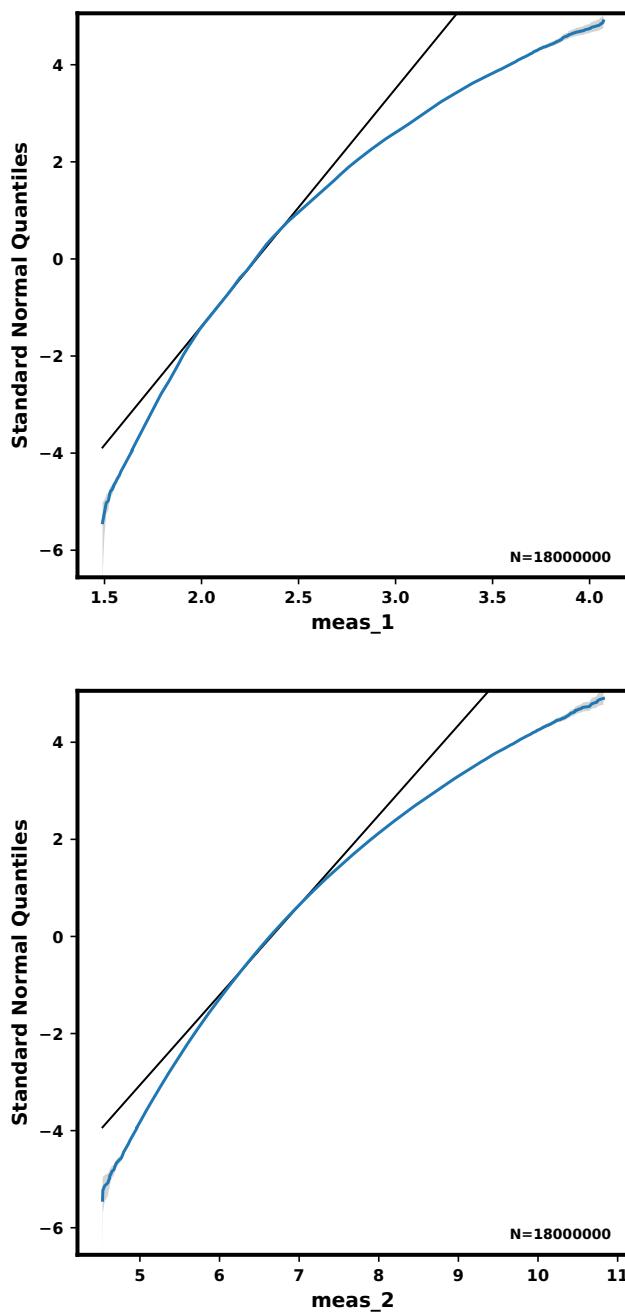


Figure 6.8: QQ plots of two delay measurements of an inverter circuit in 7nm technology

## 6.6 Discussion

In this chapter, concrete circuit simulation domain examples were provided to reinforce and verify the algorithms proposed in Chapters 3-5. In Section 6.2, it was shown that for many important circuit problems, the black box form presenting the response to process variation is monotone. This monotone property provides the opportunity to perform Monte Carlo sampling in a highly efficient manner using In-order Multivariate Sampling. It was then shown that the probability of finding a sample in the tail region tapers off considerably as distance from the origin of the multivariate standard normal MC sample point diminishes. Because of this, combined with the fact that a majority of simple random MC samples are near the origin, directly implies that little sampling is required to find the tail samples of the distribution.

It was then shown the the quantiles of linear and quadratic forms can be computed directly and reliably from the quadratic model itself with no model sampling. While this approach is very convenient, the accuracy of the computed quantiles is naturally limited by the fitting error between the true black box circuit simulation model and the linear or quadratic model. For many circuit measures where the fitting was reasonably good, the agreement between the true model and approximation model was acceptable.

Verification of the quantile-based moment calculation was also carried out for practical circuit examples and the results showed good agreement with that of the sample-based approach. Because the technique does not assume any underlying

distribution, the method can be used to calculate moments from any available CDF or QQ plot in any context.

# Chapter 7

## Conclusions

### 7.1 Thesis Contributions

A summary of the thesis contributions are summarized as follows:

- In-order Multivariate Sampling (IMS)
  - Formulation of a novel method to draw samples from the multivariate standard normal distribution in pre-sorted order
  - Extensions to IMS : mixture with volumetric sampling, directional via von Mises-Fisher distribution, correlated variables
- Flow of Statistical Analysis of Quadratic Forms
  - Fit quadratic models to data using sparse Legendre polynomials
  - Represent the quadratic form as a sum of normal and chi-square distributions

- Calculation of raw/central moments and cumulants
- Estimation of quadratic model quantiles via Cornish Fisher expansion
- Moment Calculation from Quantile Information by Analytic Integration of CDF
  - An analysis of the integrals of higher orders of the error function, proposing a novel closed form solution to those integrals in terms of a newly defined function  $S_t(x) = \int e^{-2x^2} \operatorname{erf}^t(x) dx$
  - A novel method for calculation of classical moments via quantile information

## 7.2 Future Work

Possible areas of future work include the following:

- Numerical approximation to  $S_t(x)$  of Appendix A
- Extension of In-order multivariate sampling to distributions other than the multivariate standard normal

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# Appendices

# **Appendix A**

## **Integral of High Order Error Function**

Integrals of the error function are well known up to third order, with higher order solutions not available in closed form. In this section, a novel and general representation of the integrals of the high order error function is provided. Numerical approximation to the new closed form solution is left as an exercise to the reader.

The integrals up to third order are given by[1] :

$$\int \operatorname{erf}(x) dx = x \operatorname{erf}(x) + \frac{1}{\sqrt{\pi}} e^{-x^2} \quad (\text{A.1})$$

$$\int \operatorname{erf}^2(x) dx = x \operatorname{erf}^2(x) + \frac{2}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}(x) - \sqrt{\frac{2}{\pi}} \operatorname{erf}\left(\sqrt{2}x\right) \quad (\text{A.2})$$

$$\begin{aligned} \int \operatorname{erf}^3(x) dx &= x \operatorname{erf}^3(x) + \frac{3}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}^2(x) - 12 \sqrt{\frac{2}{\pi}} T\left(2x, \frac{1}{\sqrt{2}}\right) \\ &\quad + 3 \sqrt{\frac{2}{\pi}} \end{aligned} \quad (\text{A.3})$$

where  $T$  is Owen's T function[35], named after statistician Donald Bruce Owen, defined by

$$T(h, a) = \frac{1}{2\pi} \int_0^a \frac{e^{-\frac{1}{2}h^2(1+x^2)}}{1+x^2} dx, (-\infty < h, a < +\infty). \quad (\text{A.4})$$

To aid in numerical solution, an alternative formulation of  $T(h, a)$  is often used in terms of an integral over an area of the standardized bivariate normal distribution with zero correlation defined by

$$T(h, a) = \frac{-1}{2\pi} \int_0^h \int_0^{ax} e^{-\frac{1}{2}(x^2+y^2)} dy dx + \frac{\arctan(a)}{2\pi} \quad (\text{A.5})$$

While integrals of the error function of fourth order and beyond do not have a standard closed form solution, a clear pattern emerges when the error function integrals are instead redefined in the following way.

$$\int \operatorname{erf}(x) dx = x \operatorname{erf}(x) + \frac{1}{\sqrt{\pi}} e^{-x^2} \quad (\text{A.6})$$

$$\int \operatorname{erf}^2(x) dx = x \operatorname{erf}^2(x) + \frac{2}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}(x) - \frac{4}{\pi} \int e^{-2x^2} dx \quad (\text{A.7})$$

$$\int \operatorname{erf}^3(x) dx = x \operatorname{erf}^3(x) + \frac{3}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}^2(x) - \frac{12}{\pi} \int e^{-2x^2} \operatorname{erf}(x) dx \quad (\text{A.8})$$

$$\int \operatorname{erf}^4(x) dx = x \operatorname{erf}^4(x) + \frac{4}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}^3(x) - \frac{24}{\pi} \int e^{-2x^2} \operatorname{erf}^2(x) dx \quad (\text{A.9})$$

$$\begin{aligned} \int \operatorname{erf}^k(x) dx &= x \operatorname{erf}^k(x) + \frac{k}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}^{k-1}(x) \\ &\quad - \frac{2k(k-1)}{\pi} \int e^{-2x^2} \operatorname{erf}^{k-2}(x) dx, k \in \mathbb{N} \end{aligned} \quad (\text{A.10})$$

Define a function  $S_t(x)$  as follows:

$$S_t(x) = \int e^{-2x^2} \operatorname{erf}^t(x) dx \quad (\text{A.11})$$

Now integrals of the error function of any positive integer order can be universally defined in closed form in terms of  $S_t(x)$  by

$$\int \operatorname{erf}^k(x) dx = x \operatorname{erf}^k(x) + \frac{k}{\sqrt{\pi}} e^{-x^2} \operatorname{erf}^{k-1}(x) - \frac{2k(k-1)}{\pi} S_{k-2}(x), k \in \mathbb{N} \quad (\text{A.12})$$

While more general than Owen's T function, the numerical approximation of  $S_t(x)$  for  $t > 1$  is left an exercise and is beyond the scope of this thesis.

# Appendix B

## Operational Amplifier Netlist Listing

```
** Copyright (C) 2005 Synopsys, Inc. All rights reserved
** Test circuit for Monte Carlo analysis
** Classic 7-transistor opamp
** global and local variations
**
.GLOBAL gnda vdda
.PARAM vdd=2.5 vin=vdd/2 k=2

.subckt opamp gnda inn inp out vdda nmosbulk pmosbulk
mn1 net031 inn net044 nmosbulk snps20N L='k*0.5u' W='k*3.5u' M=4
mn2 net18 inp net044 nmosbulk snps20N L='k*0.5u' W='k*3.5u' M=4
mp3 net031 net031 vdda pmosbulk snps20P L='k*0.5u' W='k*4.5u' M=4
mp4 net18 net031 vdda pmosbulk snps20P L='k*0.5u' W='k*4.5u' M=4
mp5 out net18 vdda pmosbulk snps20P L=400e-9 W=10e-6 M=3
mn8 net0148 net0148 gnda nmosbulk snps20N L=3e-6 W=18e-6 M=5
mn7 net044 net0148 gnda nmosbulk snps20N L=3e-6 W=18e-6 M=2
mn6 out net0148 gnda nmosbulk snps20N L=3e-6 W=18e-6 M=12
ccomp out net058 900e-15
rcomp net18 net058 7e3
r0 net0148 vdda 1e6
```

---

```

.ends opamp

c0 in_neg 0 1m
c1 out 0 5e-12
r1 0 out 1e6
r0 in_neg out 10e6
xi82 gnda in_neg in_pos out vdda gnda vdda opamp
v2 0 gnda DC=0
v1 in_pos 0 DC=vin AC 1
v0 vdda 0 DC=vdd

* model for tsmc 0.2u technology
* from NCSU CDK tsmc20P and tsmc20N
.MODEL snps20p PMOS (
+VERSION = 3.1
+XJ      = 1E-7
+K1      = 0.5955538
+K3B     = 10.7990376
+DVTOW   = 0
+DVTO    = 0.3622323
+U0      = 119.2085214
+UC      = -1E-10
+AGS     = 0.4199318
+KETA    = 0.0126497
+RDSW   = 201.0196067
+WR      = 1
+XL      = -2E-8
+DWB     = 5.977646E-9
+CIT     = 0
+CDSCB   = 0
+DSUB    = 0.940025
+PDIBLC2 = 0.0195957
+PSCBE1  = 2.224265E9
+DELTA   = 0.01
+PRT     = 0
+KT1L    = 0
+UB1     = -7.61E-18
+WL      = 0
+WWN    = 1
+LLN    = 1
+LWL    = 0
TNOM    = 27
NCH     = 4.1589E17
K2       = 0.0265154
W0       = 1E-6
DVT1W   = 0
DVT1    = 0.2560341
UA       = 1.656038E-9
VSAT    = 1.840486E5
B0       = 9.960505E-7
A1       = 0.4537105
PRWG    = 0.5
WINT    = 0
XW       = -1E-8
VOFF    = -0.1035186
CDSC    = 2.4E-4
ETAO    = 0.0079869
PCLM    = 1.9711817
PDIBLCB = -1E-3
PSCBE2  = 6.4242E-10
RSH     = 7.6
UTE     = -1.5
KT2     = 0.022
UC1     = -5.6E-11
WLN     = 1
WWL     = 0
LW      = 0
CAPMOD  = 2
TOX     = 4.1E-9
VTH0    = -0.4215645
K3      = 0
NLX     = 7.393151E-8
DVT2W   = 0
DVT2    = 0.1
UB      = 1E-21
AO      = 1.7659056
B1      = 3.37199E-6
A2      = 0.3
PRWB    = -0.5
LINT    = 2.42201E-8
DWG     = -2.790988E-8
NFACTOR = 1.8044589
CDSCD   = 0
ETAB    = -0.115204
PDIBLC1 = 0
DROUT   = 5.830459E-4
PVAG    = 10.2269693
MOBMOD  = 1
KT1     = -0.11
UA1     = 4.31E-9
AT      = 3.3E4
WW      = 0
LL      = 0
LWN     = 1
XPART   = 0.5
LEVEL   = 49

```

```

+CGDO      = 6.52E-10      CGSO      = 6.52E-10      CGBO      = 1E-12
+CJ        = 1.156829E-3    PB         = 0.8604313    MJ         = 0.4161985
+CJSW      = 1.800318E-10   PBSW      = 0.6161205    MJSW      = 0.2735145
+CJSWG     = 4.22E-10      PBSWG     = 0.6161205    MJSWG     = 0.2735145
+CF        = 0             PVTH0     = 1.121114E-3   PRDSW     = 12.2644118
+PK2       = 1.671328E-3   WKETA     = 2.478808E-3   LKETA     = -2.85111E-3
+PU0       = -1.8187729    PUA        = -7.23748E-11  PUB        = 1E-21
+PVSAT     = -50           PETAO     = 1E-4          PKETA     = 2.650105E-3   )
) 

.MODEL snps20n NMOS (
+VERSION = 3.1
+XJ      = 1E-7
+K1      = 0.5935169
+K3B     = 3.1905105
+DVTOW   = 0
+DVTO    = 1.7203781
+UO      = 269.0634518
+UC      = 2.224818E-11
+AGS     = 0.4169677
+KETA    = -7.704208E-3
+RDSW   = 105
+WR      = 1
+XL      = -2E-8
+DWB     = 1.217904E-8
+CIT     = 0
+CDSCB   = 0
+DSUB   = 0.0110906
+PDIBLC2 = 3.755701E-3
+PSCBE1  = 5.995957E10
+DELTA   = 0.01
+PRT     = 0
+KT1L    = 0
+UB1     = -7.61E-18
+WL      = 0
+WWN    = 1
+LLN    = 1
+LWL     = 0
+CGDO   = 7.45E-10
+CJ      = 9.725136E-4
+CJSW   = 2.269386E-10
+CJSWG  = 3.3E-10
TNOM      = 27
NCH       = 2.3549E17
K2        = 2.38533E-3
W0        = 1E-7
DVT1W    = 0
DVT1     = 0.4308344
UA        = -1.188565E-9
VSAT     = 9.67502E4
B0        = -1.063955E-8
A1        = 7.99632E-4
PRWG     = 0.5
WINT     = 2.025957E-9
XW        = -1E-8
VOFF     = -0.0901723
CDSC     = 2.4E-4
ETA0     = 1.448044E-3
PCLM     = 1.0622551
PDIBLC  = -0.1
PSCBE2  = 5.686023E-8
RSH      = 6.7
UTE      = -1.5
KT2      = 0.022
UC1      = -5.6E-11
WLN      = 1
WWL      = 0
LW       = 0
CAPMOD   = 2
CGSO     = 7.45E-10
PB        = 0.7292509
PBSW     = 0.6351005
PBSWG   = 0.6351005
LEVEL    = 49
TOX      = 4.1E-9
VTH0    = 0.3796589
K3       = 1E-3
NLX      = 1.786849E-7
DVT2W   = 0
DVT2    = 0.0467521
UB       = 1.930877E-18
A0       = 2
B1       = -1E-7
A2       = 0.999873
PRWB    = -0.2
LINT     = 1.028309E-8
DWG      = -6.4982E-10
NFACTOR  = 2.3820479
CDSCD   = 0
ETAB     = -2.754731E-4
PDIBLC1 = 0.3172281
DROUT   = 0.783102
PVAG     = 0.3568363
MOBMOD   = 1
KT1      = -0.11
UA1      = 4.31E-9
AT       = 3.3E4
WW       = 0
LL       = 0
LWN      = 1
XPART   = 0.5
CGBO     = 1E-12
MJ       = 0.3610145
MJSW    = 0.1
MJSWG   = 0.1
)

```

```

+CF      = 0          PVTH0   = -2.139932E-3    PRDSW   = -1.2311975
+PK2     = 1.860342E-3 WKETA   = 1.76355E-3     LKETA   = -5.667186E-3
+PU0     = -0.2295277 PUA     = -2.87112E-11   PUB     = 0
+PVSAT   = 1.427606E3 PETAO   = 1E-4           PKETA   = -1.196986E-3   )

.variation
.global_variation
  nmos snps20N vth0=0.07 u0=10 %
  pmos snps20P vth0=0.08 u0=8 %
.end_global_variation
.local_variation
  nmos snps20N vth0='1.234e-9/sqrt(get_E(W)*get_E(L)*get_E(M))'
+
  u0='2.345e-6/sqrt(get_E(W)*get_E(L)*get_E(M))' %
  pmos snps20P vth0='1.234e-9/sqrt(get_E(W)*get_E(L)*get_E(M))'
+
  u0='2.345e-6/sqrt(get_E(W)*get_E(L)*get_E(M))' %
.element_variation
  R r=10 %
.end_element_variation
.end_local_variation
.end_variation

.dc k start=1 stop=4 step=1 monte=1000

.meas DC systoffset1 find V(in_pos,in_neg) at=1
.meas DC systoffset2 find V(in_pos,in_neg) at=2
.meas DC systoffset3 find V(in_pos,in_neg) at=3
.meas DC systoffset4 find V(in_pos,in_neg) at=4
.meas DC leakpwr PARAM='-I(v0)*V(vdda)',
.meas DC logleakpwr PARAM='log(-I(v0)*V(vdda))'

.TEMP 25
.option nomod dcon=1
.option post $sampling_method=ofat
.END

```