Algorithm 1: Temporal Metric Distillation (TMD)

- 1: **input:** dataset \mathcal{D} , learning rate η
- 2: initialize representations ϕ , ψ , policy π
- 3: while training do
- 4: sample $\mathcal{B} = \{s_i, a_i, s_i', g_i\}_{i=1}^N \sim \mathcal{D}$
- 5: $\overline{\psi} \leftarrow \psi$
- 6: $(\phi, \psi) \leftarrow (\phi, \psi) \eta \nabla_{\phi, \psi} \mathcal{L}_{TMD}(\phi, \psi; \overline{\psi}, \mathcal{B})$

 $\triangleright Eq.$ (26)

 $\triangleright Eq.$ (27)

- 7: $\pi \leftarrow \pi \eta \nabla_{\pi} \mathcal{L}_{\pi}(\phi, \psi, \pi; \mathcal{B})$
- 8: return π