

Relative variance

N = 500

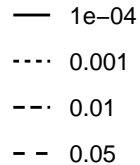
N = 1000

N = 2000

N = 4000

N = 8000

System noise



1 2 3 4 5 1 2 3 4 5 1 2 3 4 5 1 2 3 4 5 1 2 3 4 5

GPS error (m)