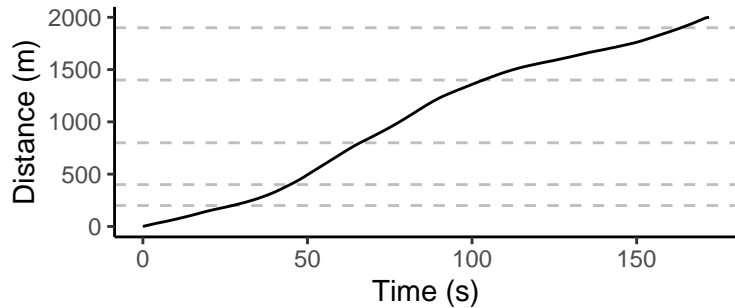
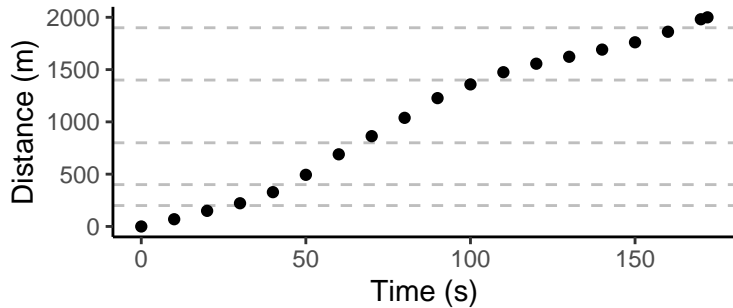


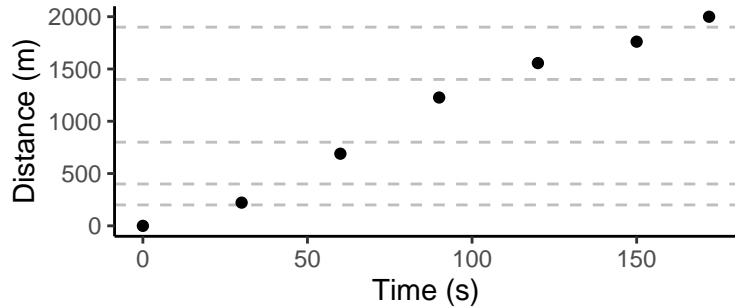
Simulated vehicle trajectory



10~s sampling



30~s sampling



Observations at nodes

