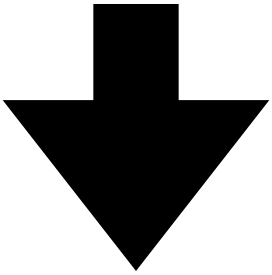
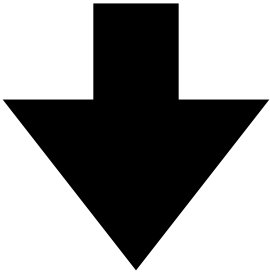


position

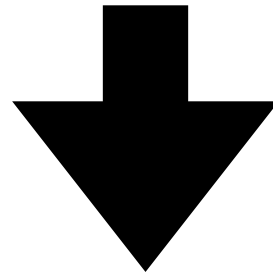
state



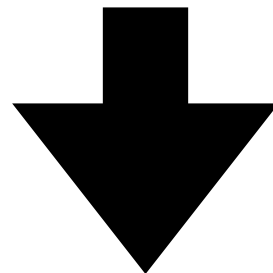
distance + speed



position



state



distance + speed

