

# EN.600.475 Machine Learning

# Regression

Raman Arora Lecture 3 February 6, 2017

- Supervised Learning
- Linear regression

#### Formal setup

- ullet Input data space  ${\mathcal X}$
- ullet Output (label, target) space  ${\cal Y}$
- ullet Unknown function  $f:\mathcal{X} o\mathcal{Y}$
- We are given a set of labeled examples  $(\mathbf{x}_i, y_i)$ , i = 1, ..., N, with  $\mathbf{x}_i \in \mathcal{X}$ ,  $y_i \in \mathcal{Y}$ .
- Goal: any for future  $\mathbf{x}$ , accurately predict y in other words: learn a mapping  $f: \mathcal{X} \to \mathcal{Y}$



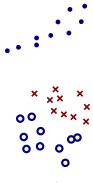


#### Types of supervised problems

- ullet Goal: learn  $f:\mathcal{X} o\mathcal{Y}$
- ullet We will consider two sorts of f, based on nature of  ${\mathcal Y}$ :

regression: 
$$\mathcal{Y} = \mathbb{R}$$

classification: 
$$\mathcal{Y} = \{1, \dots, C\}$$



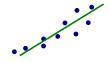


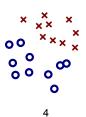
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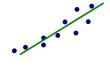


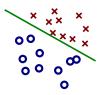
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classification: 
$$\mathcal{Y} = \{1, \dots, C\}$$
  
learn a separator between classes





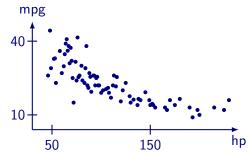




#### Regression

• We are given a set of N observations  $(\mathbf{x}_i, y_i)$ ,  $i = 1, \dots, N$ , with  $y_i \in \mathbb{R}$ .

 $\bullet \ \, {\sf Example:} \ \, {\sf predict} \ \, {\sf car} \ \, {\sf MPG} \ \, y \\ {\sf from \ engine} \ \, {\sf horsepower} \ \, x \\$ 



• Does it make sense to use learning here?

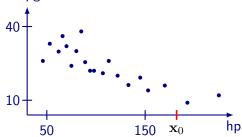


## Attempt 1: rote learning

ullet Memorize the observed  $(\mathbf{x},y)$  pairs

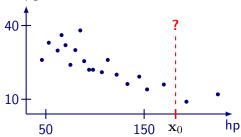
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- $\bullet$  What do we do when a new  ${\bf x}$  comes along? mpg



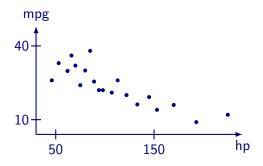
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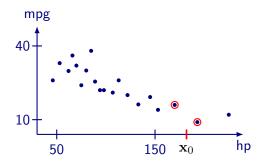
• Is this really learning?

#### Attempt 2: lazy learning



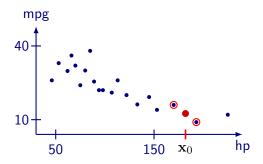
- Memorize the observed values
- For a new  $\mathbf{x}_0$ , find two nearest neighbors, that is, two observed  $\mathbf{x}_i$  closest to it, and predict  $\widehat{y}(\mathbf{x}_0)$  as the average of the nearest neighbors'  $y_i$ s

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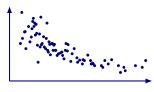
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- This is k-nearest neighbors regression (k=2)

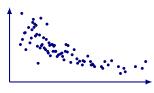




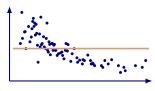
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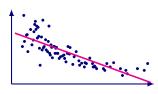
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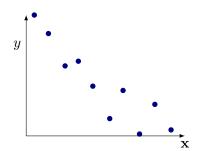
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- Simplest model class: constant functions
- Second simplest: linear functions

- We want to fit a linear function to an observed set of points  $X = [x_1, \dots, x_N]$  with associated labels  $Y = [y_1, \dots, y_N]$ .
  - Once we fit the function, we want to use it to predict the y for new x.

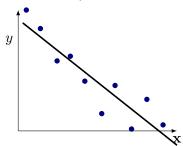
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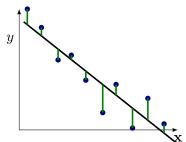
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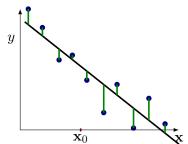


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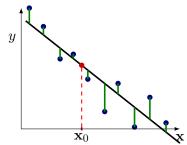
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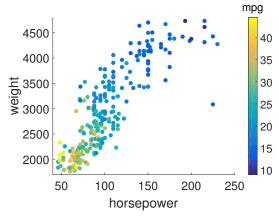


distances along y, not orthogonal to line! The fitted line is used as a predictor; it

summarizes the information x provides about y, according to the model

#### Multiple input variables

- ullet Can consider additional features; e.g.,  $x_1$  horsepower and  $x_2$  vehicle weight.
- We now have mapping from  $\mathbf{x} = (x_1, x_2) \in \mathbb{R}^2$  to y



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colorbar: one possible way to convey multi-dimensional plots

