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```
from flask import Flask, Response
import cv2
import numpy as np
from naoqi import ALProxy
import vision definitions
app = Flask(__name___)
# NAO robot IP and Port
NAO_IP = "192.168.86.95" # Replace 'your_nao_ip' with your NAO
NAO_PORT = 9559 # Default port
# Create a proxy to ALVideoDevice on the robot
try:
    video_service = ALProxy("ALVideoDevice", NAO_IP, NAO_PORT)
except Exception as e:
    print("Could not create proxy to ALVideoDevice: {}".format(
    exit(1)
# Subscribe to the camera feed
resolution = vision definitions.kVGA # 640x480
colorSpace = vision_definitions.kRGBColorSpace
fps = 20
camera_index = 0 # 0 for the top camera, 1 for the bottom came;
try:
    video client = video service.subscribeCamera(
        "python_client", camera_index, resolution, colorSpace, i
except Exception as e:
```

```
print("Could not subscribe to camera: {}".format(e))
    exit(1)
def gen frames():
    while True:
        # Obtain an image from the robot's camera
        nao image = video service.getImageRemote(video client)
        if nao_image is None:
            continue
        # Get the image size and pixel array.
        image_width = nao_image[0]
        image_height = nao_image[1]
        array = nao image[6]
        image_string = bytes(bytearray(array))
        # Convert the string to an image
        img = np.frombuffer(image_string, dtype=np.uint8)
        img = img.reshape((image_height, image_width, 3))
        # Encode the frame in JPEG format
        (flag, encodedImage) = cv2.imencode(".jpg", img)
        if not flag:
            continue
        # Yield the encoded image in byte format
        yield (b'--frame\r\n'
               b'Content-Type: image/jpeg\r\n\r\n' +
               encodedImage.tobytes() + b'\r\n')
@app.route('/video_feed')
def video_feed():
    # Return the response generated along with the specific med:
    # type (mime type).
```

```
return Response(gen_frames(), mimetype='multipart/x-mixed-return return 
if name__ == '__main__':
             app.run(host='0.0.0.0', port=5000)
NAO Config
from naogi import ALProxy
import vision definitions
IP = "192.168.86.95" # Replace with your NAO robot's IP address
PORT = 9559 # Default port for NAOqi
# Create a proxy to ALVideoDevice
video_service = ALProxy("ALVideoDevice", IP, PORT)
# Subscribe to the camera feed
resolution = vision definitions.kVGA # 640x480
colorSpace = vision definitions.kRGBColorSpace
fps = 20
camera_index = 0 # 0 for the top camera, 1 for the bottom came;
video_client = video_service.subscribeCamera(
             "python client", camera index, resolution, colorSpace, fps)
# Now video_service.getImageRemote(video_client) can be used to
Live Stream on Website
<!DOCTYPE html>
<html lang="en">
<head>
             <meta charset="UTF-8">
             <title>NAO Robot Live Feed</title>
</head>
```

```
<body>
            <h1>NAO Robot Live Stream</h1>
            <img src="http://10.211.55.7:5000/video_feed" alt="Live Street"</pre>
</body>
</html>
Livestream Application
import SwiftUI
import AVKit
// Define a UIViewRepresentable struct to wrap the LivestreamVie
struct LivestreamViewControllerPreview: UIViewRepresentable {
            func makeUIView(context: Context) -> UIView {
                         // Create an instance of your LivestreamViewController
                         let viewController = LivestreamViewController()
                         // Add the view controller's view to a UIView
                         let view = UIView()
                        view.addSubview(viewController.view)
                        // Set autoresizing mask to make the view resize with it
                         viewController.view.translatesAutoresizingMaskIntoConsti
                         // Add constraints with margins for iPhone
                         NSLayoutConstraint.activate([
                                     viewController.view.leadingAnchor.constraint(equalTo
                                     viewController.view.trailingAnchor.constraint(equal
                                     viewController.view.topAnchor.constraint(equalTo: viewController.view.topAnchor.constraint(
                                     viewController.view.bottomAnchor.constraint(equalTo
                         1)
                         return view
            }
```

```
func updateUIView(_ uiView: UIView, context: Context) {
     // Update the view if needed
  }
}

// Preview Provider
struct LivestreamViewControllerPreview_Previews: PreviewProvider
    static var previews: some View {
        LivestreamViewControllerPreview()
    }
}
```

```
LiveStream Application
// LivestreamViewController.swift
import UIKit
import AVFoundation
class LivestreamViewController: UIViewController {
    var player: AVPlayer!
    override func viewDidLoad() {
        super.viewDidLoad()
        // URL of the livestream
        guard let url = URL(string: "http://10.211.55.7:5000/vic
            fatalError("Invalid URL")
        }
        // Create AVPlayerItem
        let playerItem = AVPlayerItem(url: url)
```

```
// Initialize AVPlayer with the player item
player = AVPlayer(playerItem: playerItem)

// Create AVPlayerLayer to display video
let playerLayer = AVPlayerLayer(player: player)
playerLayer.frame = view.bounds

// Add AVPlayerLayer to the view's layer
view.layer.addSublayer(playerLayer)

// Start video playback
player.play()
}
```