

# Calculus II

## Lecture 20

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<https://github.com/tmilev/freecalc>

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# Outline

- 1 Modeling with Differential Equations
  - Models of Population Growth
  - A Model for the Motion of a Spring
  - General Differential Equations

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  - Direction Fields
- 3 Separable Equations
  - Orthogonal Trajectories
  - Mixing Problems

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  - A Model for the Motion of a Spring
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- 2 Direction Fields and Euler's Method
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- 3 Separable Equations
  - Orthogonal Trajectories
  - Mixing Problems
- 4 Models for Population Growth
  - The Law of Natural Growth
  - The Logistic Model

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# Modeling with Differential Equations

- When modeling real-world problems, we often have a relationship between an unknown function and some of its derivatives.
- Such a relationship is called a differential equation.
- It is not always possible to find an explicit solution to a differential equation, but sometimes a graphical or approximate answer can be good enough for applications.

# Models of Population Growth

- One model for population growth assumes that the population grows at a rate proportional to its size.
- In other words, if a certain number of bacteria produce a certain number of offspring in a certain time, then ten times that many bacteria produce ten times that many offspring in the same time.
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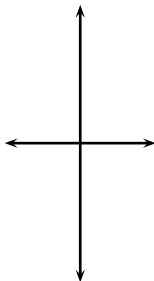
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- The rate of growth is  $dP/dt$ .
- Then “rate of growth proportional to population size” means

$$\frac{dP}{dt} = kP$$

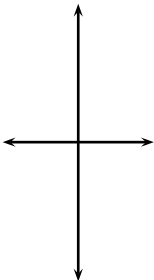
where  $k$  is the proportionality constant.

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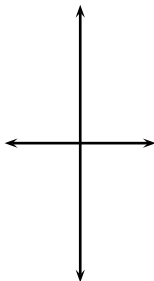
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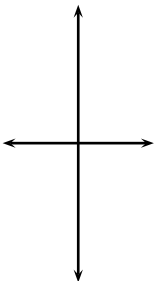
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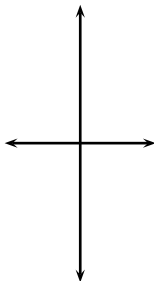
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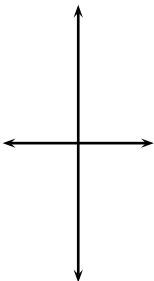


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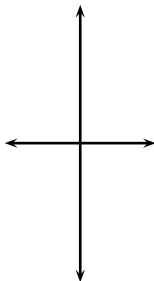
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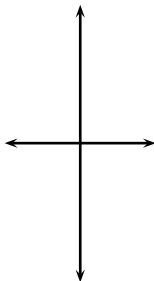
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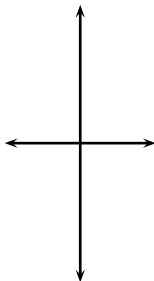
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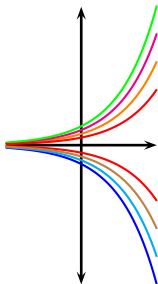


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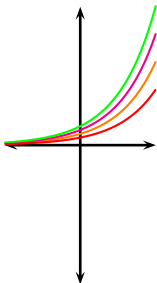


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- Therefore any function of the form  $P(t) = Ce^{kt}$  satisfies the equation. We will see later that there is no other solution.
- Letting  $C$  vary over the real numbers gives a family of solutions.
- Since populations are non-negative, only solutions with  $C > 0$  are relevant.

- This model works well under ideal conditions.
- In real life, most populations are constrained by the environment, the amount of food, etc.
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- To take this into account, make two assumptions:
  - $\frac{dP}{dt} \approx kP$  if  $P$  is small (Initially, the growth rate is proportional to  $P$ ).
  - $\frac{dP}{dt} < 0$  if  $P > K$  ( $P$  decreases if it ever exceeds  $K$ ).



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- Here is an expression that takes both assumptions into account:

$$\frac{dP}{dt} = kP \left( 1 - \frac{P}{K} \right)$$

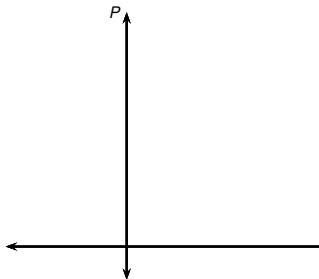
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- This is called the logistic differential equation.

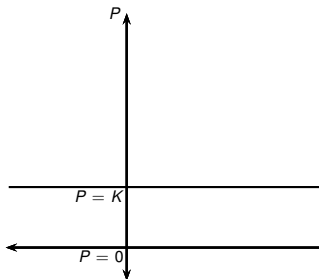
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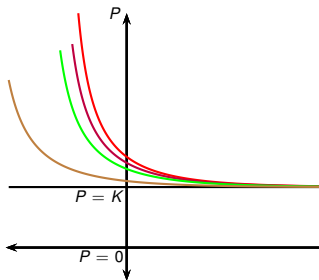
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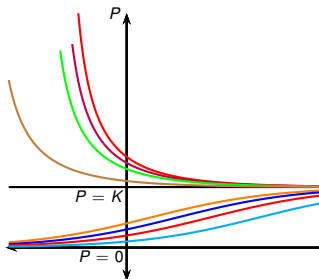
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- If  $P > K$ , then  $1 - P/K < 0$ , so  $dP/dt < 0$ , and  $P$  decreases.



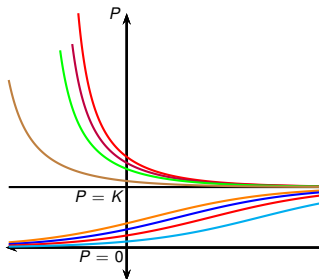
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- As  $P \rightarrow K$ ,  $1 - P/K \rightarrow 0$ , so  $dP/dt \rightarrow 0$  and  $P$  levels off.



# A Model for the Motion of a Spring

- Suppose we have an object with mass  $m$  attached to a spring.
- Hooke's Law: if the spring is stretched or compressed  $x$  units from its natural length, then it exerts a force that is proportional to  $x$ .
- Force equals mass times acceleration.
- Acceleration is the second derivative of displacement with respect to time.

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- Sine and cosine functions are solutions.

# General Differential Equations

## Definition (Differential Equation)

A differential equation is an equation that contains an unknown function and some of its derivatives.

## Definition (Order of a Differential Equation)

The order of a differential equation is the highest derivative that appears in it.

## Definition (Solution)

A function  $f$  is called a solution of a differential equation if the equation is satisfied when  $f$  and its derivatives are plugged in.

## Definition (To Solve a Differential Equation)

When we are asked to solve a differential equation we are expected to find all possible solutions.

## Example

Show that every member of the family of functions

$$y = \frac{1 + ce^t}{1 - ce^t}$$

is a solution of the differential equation  $y' = \frac{1}{2}(y^2 - 1)$ .

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- Often we don't want to find all solutions (the general solution).
- Instead, we only want to find a single solution that satisfies some additional requirement.
- Often that requirement has the form  $y(t_0) = y_0$ .
- This is called an initial condition.
- This type of problem is called an initial value problem.

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$$\begin{aligned} 2 &= \frac{1 + ce^0}{1 - ce^0} = \frac{1 + c}{1 - c} \\ 2(1 - c) &= 1 + c \end{aligned}$$

## Example

Find a solution of the differential equation  $y' = \frac{1}{2}(y^2 - 1)$  that satisfies the initial condition  $y(0) = 2$ .

Substitute  $t = 0$  and  $y = 2$  into the formula

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$$\begin{aligned} 2 &= \frac{1 + ce^0}{1 - ce^0} = \frac{1 + c}{1 - c} \\ 2(1 - c) &= 1 + c \\ 2 - 2c &= 1 + c \end{aligned}$$

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Therefore the solution to the initial-value problem is

$$y = \frac{1 + \frac{1}{3}e^t}{1 - \frac{1}{3}e^t} = \frac{3 + e^t}{3 - e^t}.$$

# Direction Fields and Euler's Method

- Often we don't know how to find explicit solutions to a differential equation.
- Nevertheless, we can learn a lot about the solutions using:
  - A graphical approach (direction fields)
  - A numerical approach (Euler's method)

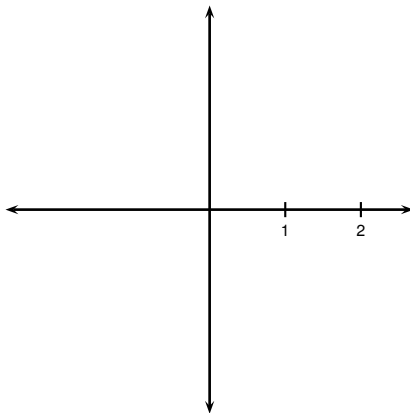
# Direction Fields and Euler's Method

- Often we don't know how to find explicit solutions to a differential equation.
- Nevertheless, we can learn a lot about the solutions using:
  - A graphical approach (direction fields)
  - A numerical approach (Euler's method)
- Today we will discuss direction fields, but not Euler's method.



# Direction Fields

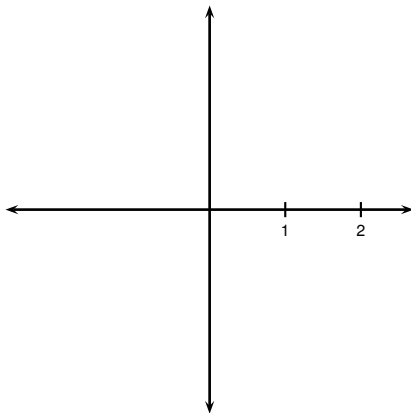
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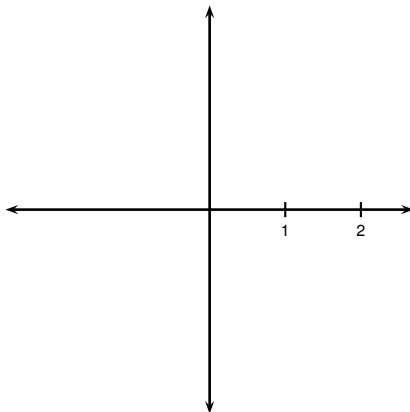
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   |      |
| $(-1, 0)$  |      |
| $(0, 1)$   |      |
| $(0, -1)$  |      |
| $(0, 0)$   |      |
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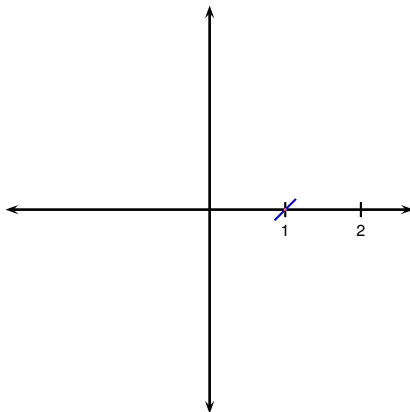
| Point    | $y'$ |
|----------|------|
| (1, 0)   |      |
| (-1, 0)  |      |
| (0, 1)   |      |
| (0, -1)  |      |
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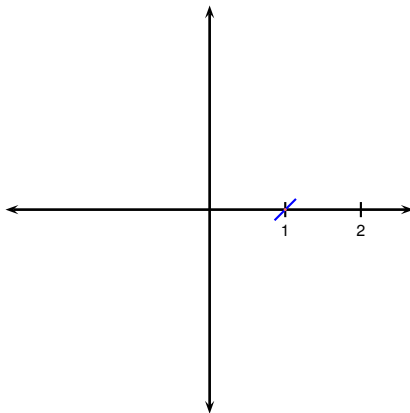
| Point    | $y'$ |
|----------|------|
| (1, 0)   | 1    |
| (-1, 0)  |      |
| (0, 1)   |      |
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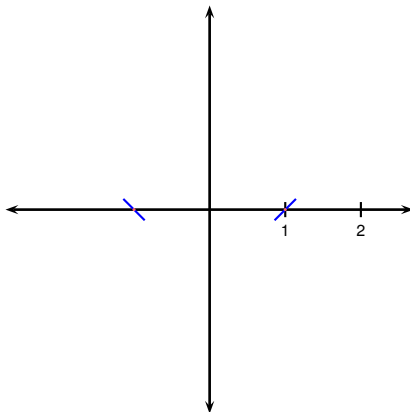
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  |      |
| $(0, 1)$   |      |
| $(0, -1)$  |      |
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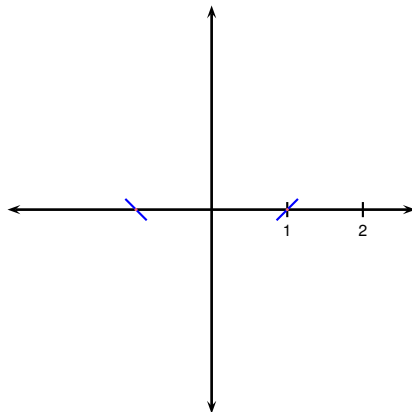
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
| $(0, 1)$   |      |
| $(0, -1)$  |      |
| $(0, 0)$   |      |
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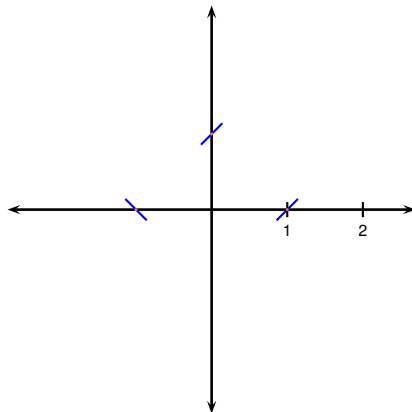
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
| $(0, 1)$   |      |
| $(0, -1)$  |      |
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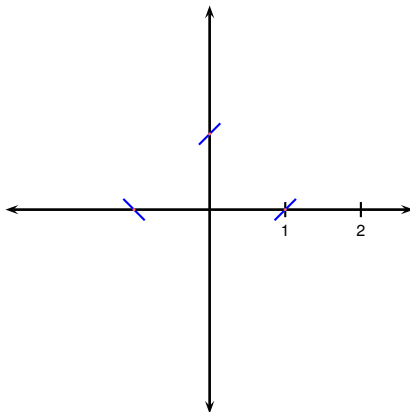




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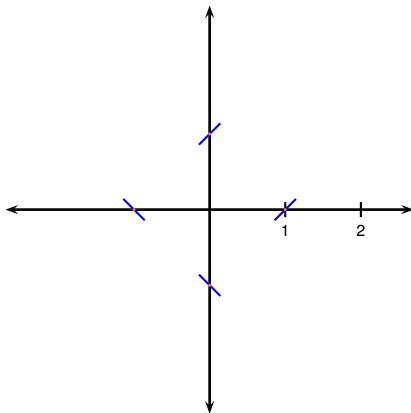
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
| $(0, 1)$   | 1    |
| $(0, -1)$  |      |
| $(0, 0)$   |      |
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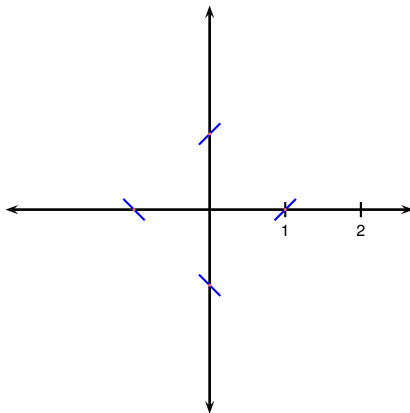
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
| $(0, 1)$   | 1    |
| $(0, -1)$  | -1   |
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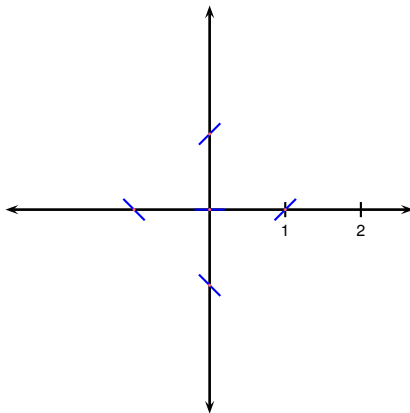
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
| $(0, 1)$   | 1    |
| $(0, -1)$  | -1   |
| $(0, 0)$   |      |
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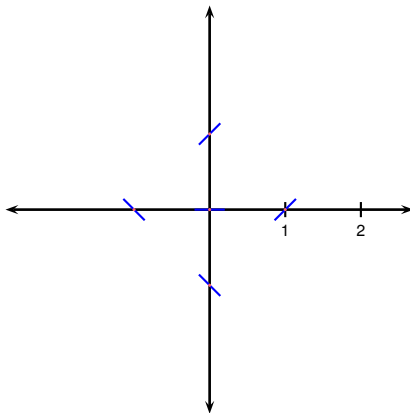
| Point      | $y'$ |
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| $(1, 0)$   | 1    |
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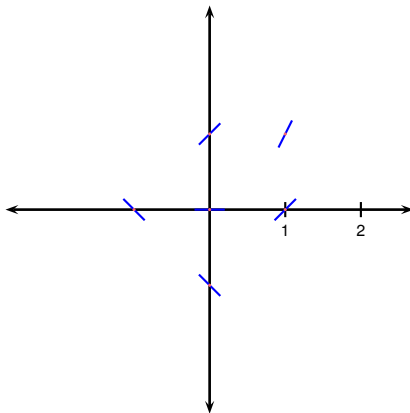
| Point      | $y'$ |
|------------|------|
| $(1, 0)$   | 1    |
| $(-1, 0)$  | -1   |
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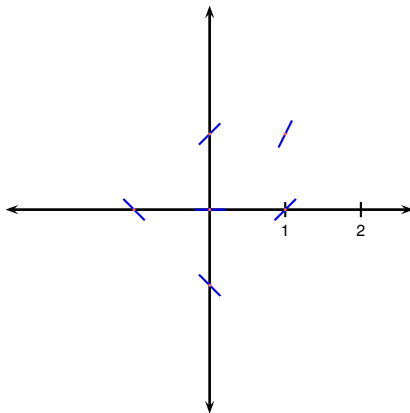
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|------------|------|
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| $(-1, 0)$  | -1   |
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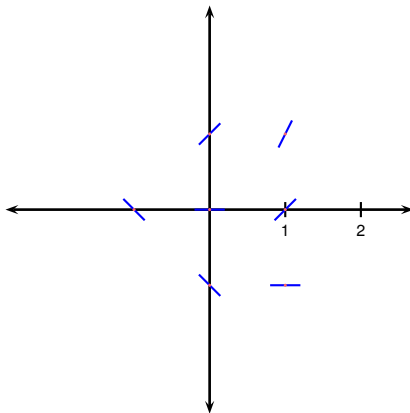
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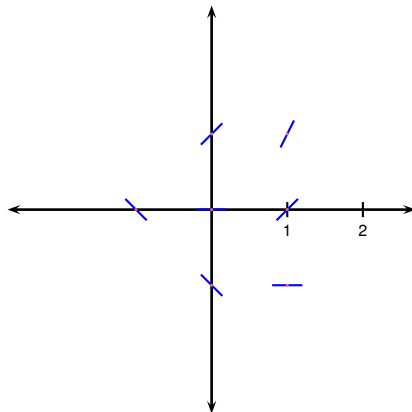




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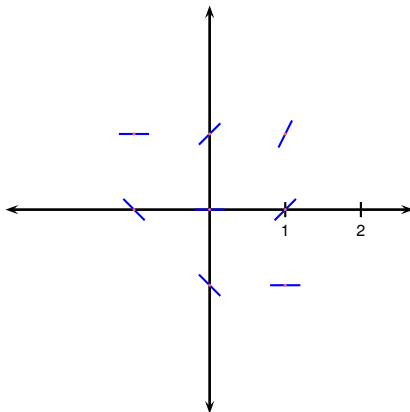
| Point      | $y'$ |
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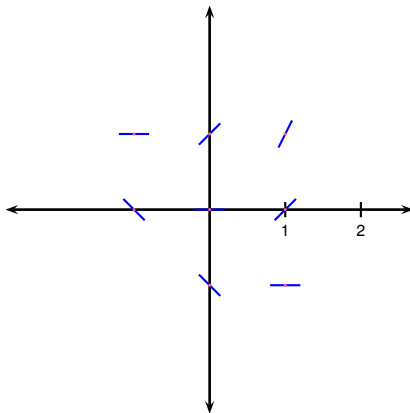
| Point      | $y'$ |
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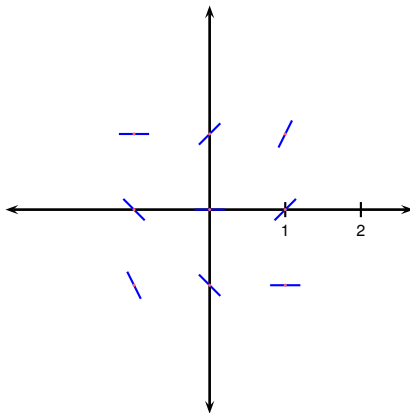
| Point      | $y'$ |
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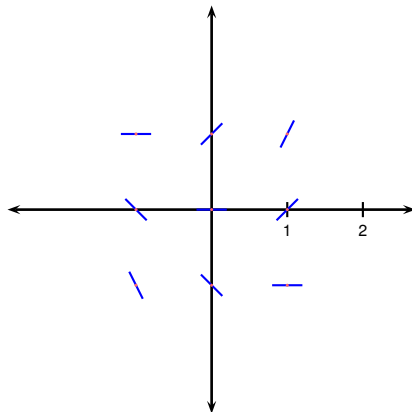
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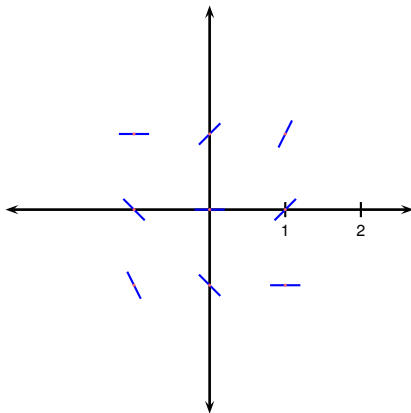
| Point      | $y'$ |
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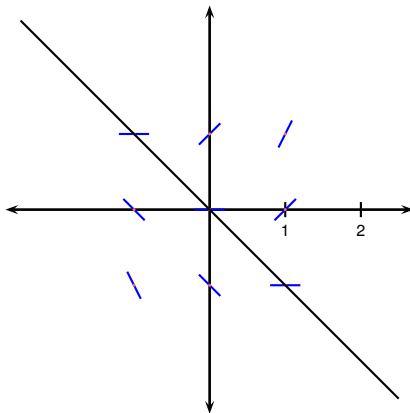


| Line                   | $y'$ |
|------------------------|------|
| $y = -x$               |      |
| $y = -x + \frac{1}{2}$ |      |
| $y = -x + 1$           |      |
| $y = -x - \frac{1}{2}$ |      |
| $y = -x - 1$           |      |

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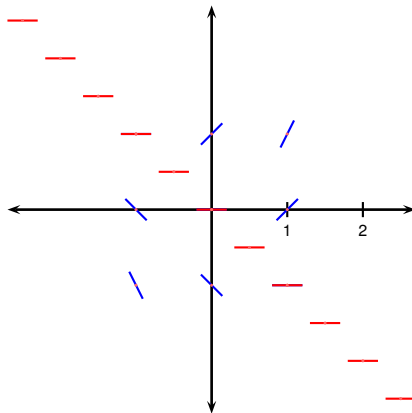


| Line                   | $y'$ |
|------------------------|------|
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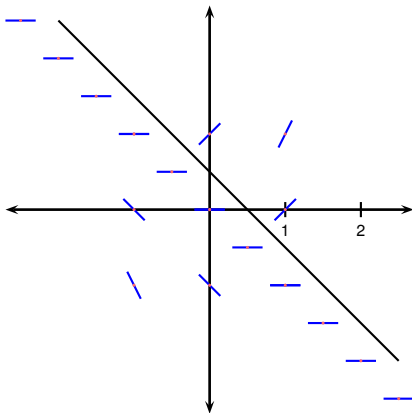
| Line                   | $y'$ |
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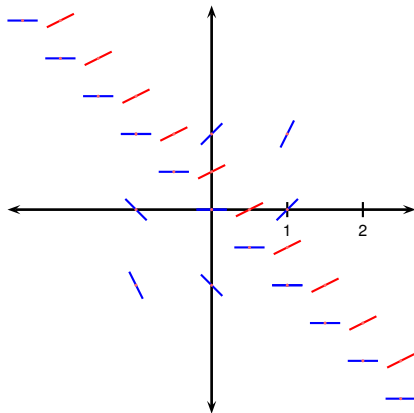


| Line                   | $y'$ |
|------------------------|------|
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| $y = -x + \frac{1}{2}$ |      |
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| $(0, 0)$   | 0    |
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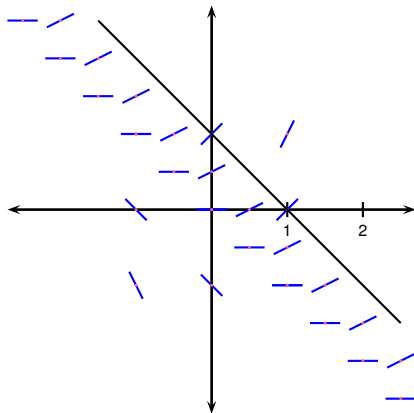


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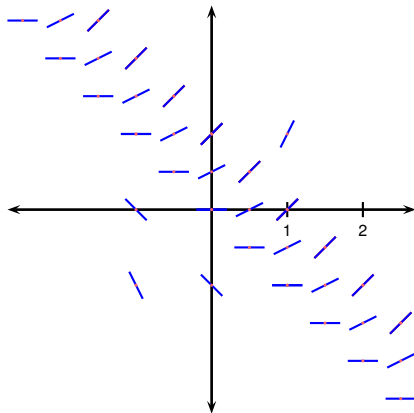


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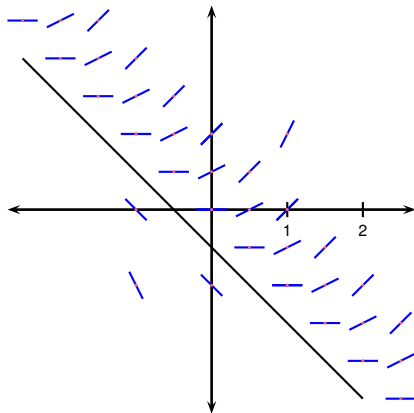


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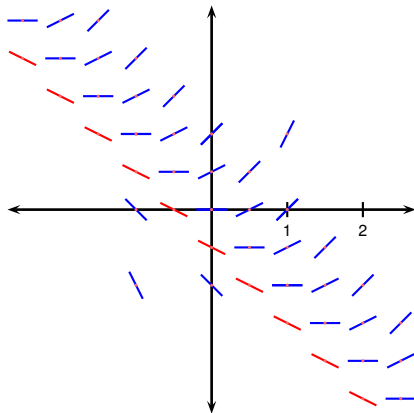


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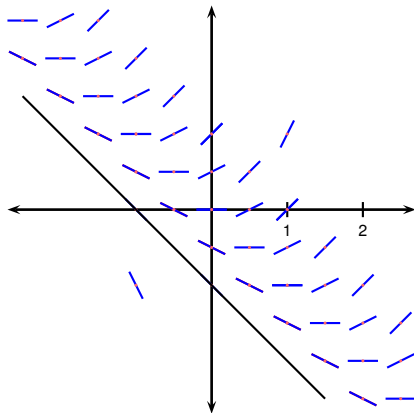


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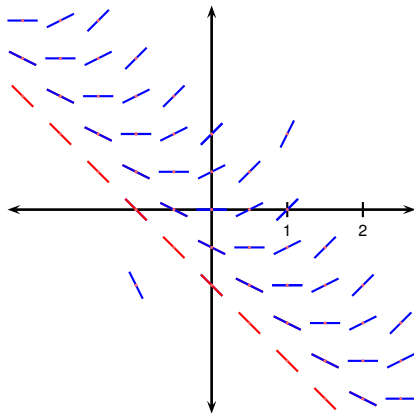


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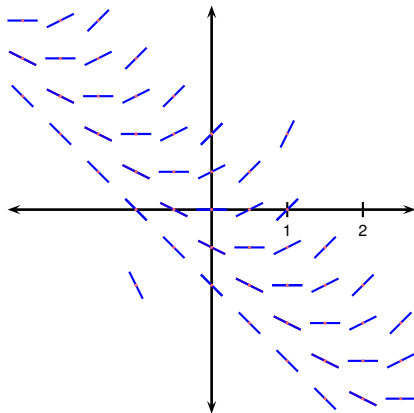
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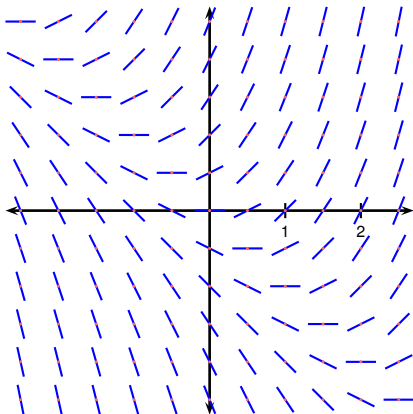


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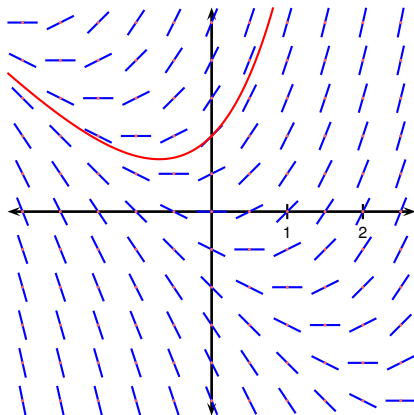


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# Separable Equations

In this section, we will discuss a type of differential equation, called a separable equation, for which it is possible to find an explicit solution.

## Definition (Separable Equation)

A separable equation is a first-order equation in which the expression for  $dy/dx$  can be factored as a function of  $x$  times a function of  $y$ . In other words,

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Let  $f(y) = 1/h(y)$ . Then

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- To solve, write this in differential form:

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- Sometimes we might be able to solve explicitly for  $y$  in terms of  $x$ .

Why does this process yield a function that satisfies the original differential equation? Suppose that  $\int h(y)dy = \int g(x)dx$ . Then we will use the Chain Rule to show that  $y$  satisfies the original equation.

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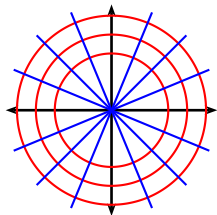
The function  $y = 0$  satisfies the equation. General solution:

$$y = A e^{x^3/3}.$$

# Orthogonal Trajectories

## Definition (Orthogonal Trajectory)

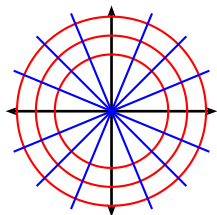
An orthogonal trajectory to a family of curves is a curve that intersects each curve of the family orthogonally (that is, at right angles).



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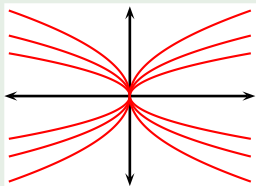
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Each member of the family  $y = mx$  of straight lines passing through the origin is an orthogonal trajectory to the family  $x^2 + y^2 = r^2$  of circles centered at the origin.

## Example

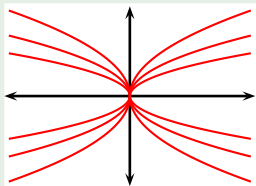
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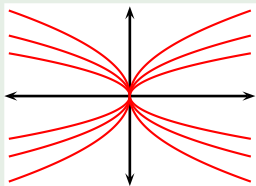


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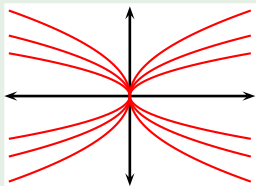
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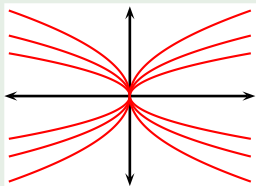
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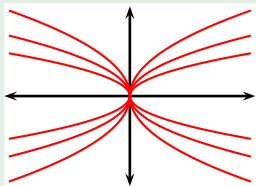
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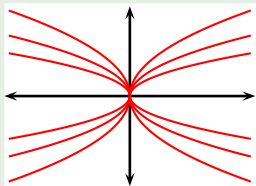
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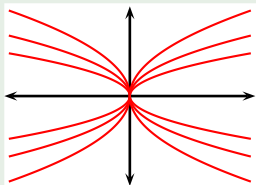
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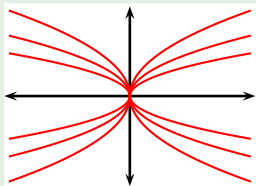
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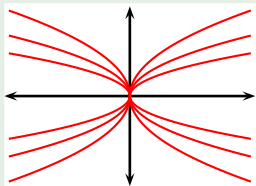
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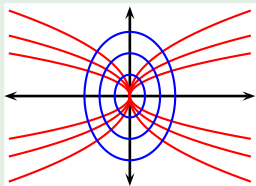
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The ellipses  $x^2 + \frac{y^2}{2} = C$  are all orthogonal trajectories to  $x = ky^2$ .

# Mixing Problems

- Typical mixing problems involve:
- A tank of fixed capacity.
- A completely mixed solution of some substance in the tank.
- A solution of a certain concentration enters the tank at a fixed rate.
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- The mixture leaves at the other end at a fixed rate (possibly a different rate).
- Let  $y(t)$  denote the amount of substance in the tank at time  $t$ .
- Then  $y'(t)$  denotes the rate at which the substance is being added minus the rate at which it is being removed.
- This often gives a differential equation.



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$$y(30) = 150 - 130e^{-30/200} \approx 38.1 \text{ kg}$$

# The Law of Natural Growth

- Recall that differential equations could be used to model population growth.
- The Law of Natural Growth works in ideal cases, where populations are unconstrained by lack of food, or the environment.
- Let  $P(t)$  be the population at time  $t$ .
- Then the Law of Natural Growth says:

$$\frac{dP}{dt} = kP$$

- The constant  $k$  is sometimes called the relative growth rate.



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- Let  $A = \pm e^C$ . Then the solution is  $P = Ae^{kt}$ .

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This is a separable equation, so we can solve it.

$$\begin{aligned}\int \frac{dP}{P} &= \int k dt \\ \ln |P| &= kt + C \\ |P| &= e^C e^{kt} \\ P &= \pm e^C e^{kt}\end{aligned}$$

- Let  $A = \pm e^C$ . Then the solution is  $P = Ae^{kt}$ .
- $A = \pm e^C$  can be any positive or negative number.

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This is a separable equation, so we can solve it.

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The solution to the initial value problem

$$\begin{aligned}\frac{dP}{dt} &= kP, & P(0) &= P_0 \\ \text{is} & & P(t) &= P_0 e^{kt}.\end{aligned}$$

# The Logistic Model

- The Logistic Model works in cases when the population is constrained by its environment.
- Let  $P(t)$  be the population at time  $t$ .
- Then the Logistic Equation is:

$$\frac{dP}{dt} = kP \left( 1 - \frac{P}{K} \right)$$

- The constant  $K$  is called the carrying capacity. It represents how many individuals the environment can sustain in the long run.

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$$P = \frac{K}{1 + Ae^{-kt}}$$

Plug in  $P(0) = P_0$ :

$$\frac{K - P_0}{P_0} = Ae^{-k \cdot 0} = A.$$

The solution to the initial value problem

$$\frac{dP}{dt} = kP \left( 1 - \frac{P}{K} \right), \quad P(0) = P_0$$

is

$$P = \frac{K}{1 + Ae^{-kt}}, \quad A = \frac{K - P_0}{P_0}.$$

## Example

Write the solution of the initial value problem

$$\frac{dP}{dt} = 0.08P \left( 1 - \frac{P}{1000} \right), \quad P(0) = 100$$

and use it to find when the population reaches 900.



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$$\begin{aligned} \text{Set } P(t) = 900 : \quad & \frac{1000}{1 + 9e^{-0.08t}} = 900 \\ & 1 + 9e^{-0.08t} = 1000/900 \end{aligned}$$



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