

Calculus III

Lecture 5

Todor Milev

<https://github.com/tmilev/freecalc>

2020

Outline

1 Polar Coordinates

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- 1 Polar Coordinates
- 2 Cylindrical Coordinates

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- 1 Polar Coordinates
- 2 Cylindrical Coordinates
- 3 Spherical Coordinates

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- 1 Polar Coordinates
- 2 Cylindrical Coordinates
- 3 Spherical Coordinates
- 4 Curvilinear boxes

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- Should the link be outdated/moved, search for “freecalc project”.
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Polar Coordinates

- The polar coordinate system is an alternative to the Cartesian coordinate system.

Polar Coordinates

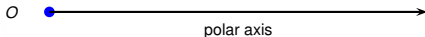
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- Choose a point in the plane called O (the origin).



O •

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- Draw a ray starting at O . The ray is called the polar axis. This ray is usually drawn horizontally to the right.

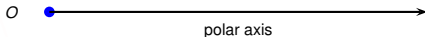


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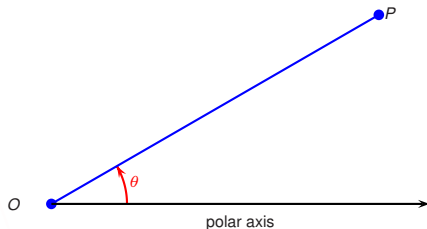
• P

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Polar Coordinates

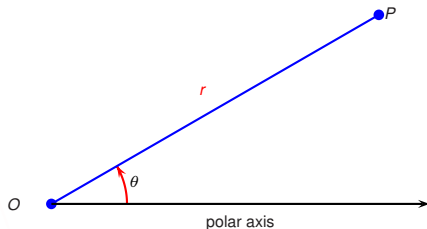
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- Let θ denote the angle between the polar axis and the line OP .

Polar Coordinates

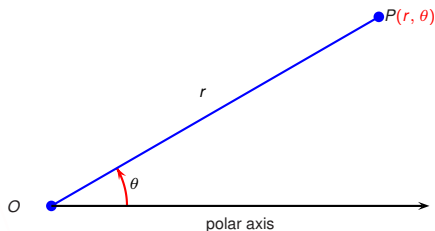
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- Let r denote the length of the segment OP .

Polar Coordinates

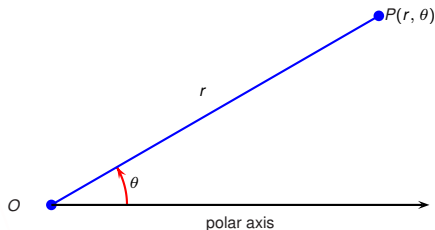
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- Let P be a point in the plane.
- Let θ denote the angle between the polar axis and the line OP .
- Let r denote the length of the segment OP .
- Then P is represented by the ordered pair (r, θ) .

Polar Coordinates

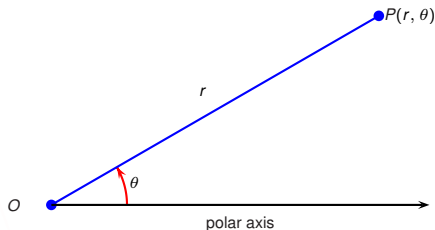
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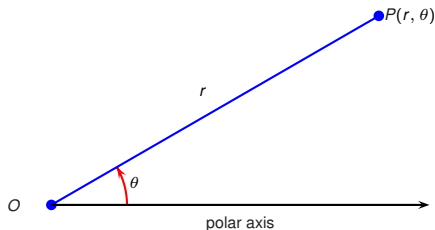
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Polar Coordinates

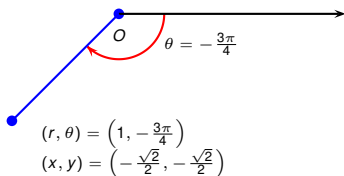
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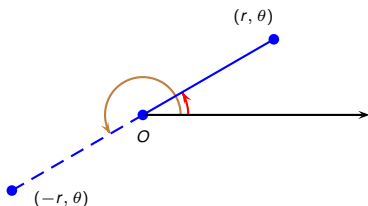
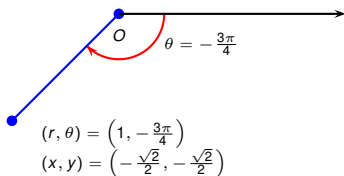
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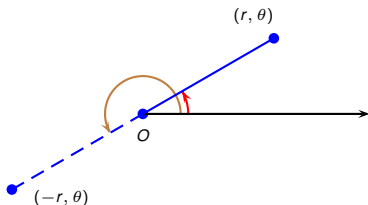
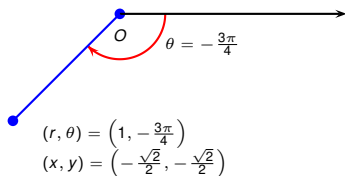
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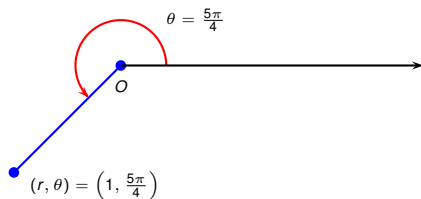


- 1 Positive angles θ are measured in the counterclockwise direction from O . Negative angles are measured in the clockwise direction.
- 2 Points with polar coordinates $(-r, \theta)$ and (r, θ) lie on the same line through O and at the same distance from O , but on opposite sides.

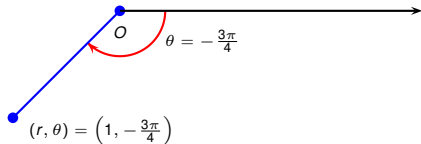
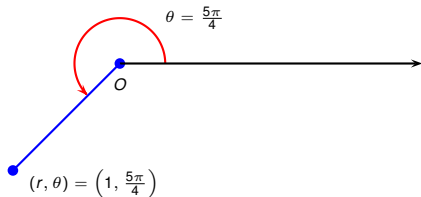
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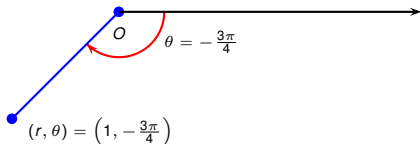
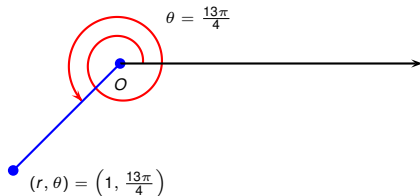
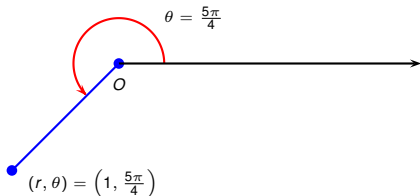
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- 3 If $r = 0$, then $(0, \theta)$ represents O for all values of θ .



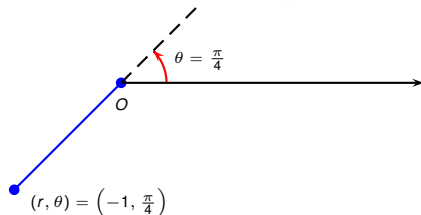
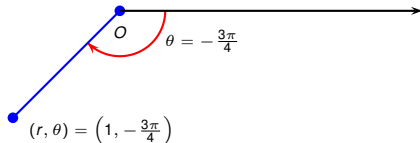
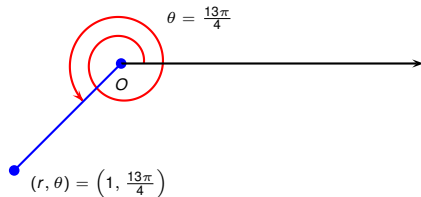
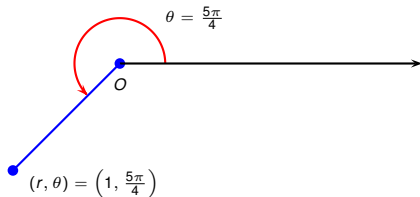
- There are many ways to represent the same point.



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- There are many ways to represent the same point.
- We could use a negative θ .
- We could go around more than once.
- We could use a negative r .**

- Let P_1 be point with polar coordinates (r_1, θ_1) .
- Let P_2 be point with polar coordinates (r_2, θ_2) .

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Observation

P_1 coincides with P_2 if one of the three mutually exclusive possibilities holds:

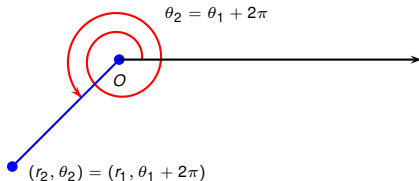
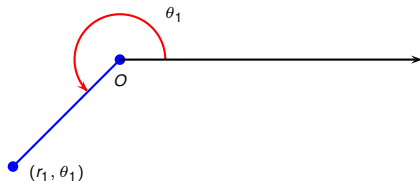
- $r_1 = r_2 \neq 0$ and $\theta_2 = \theta_1 + 2k\pi, k \in \mathbb{Z}$,
- $r_1 = -r_2 \neq 0$ and $\theta_2 = \theta_1 + (2k + 1)\pi, k \in \mathbb{Z}$,
- $r_1 = r_2 = 0$ and θ is arbitrary.

- Let P_1 be point with polar coordinates (r_1, θ_1) .
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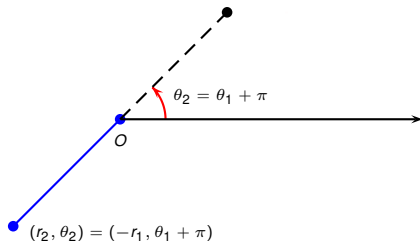
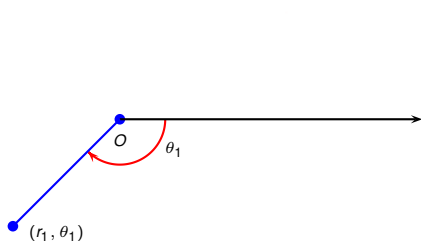


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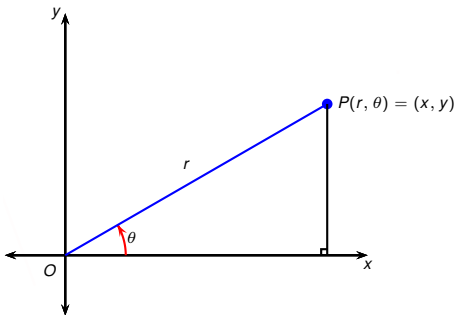
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- How do we go from polar coordinates to Cartesian coordinates?



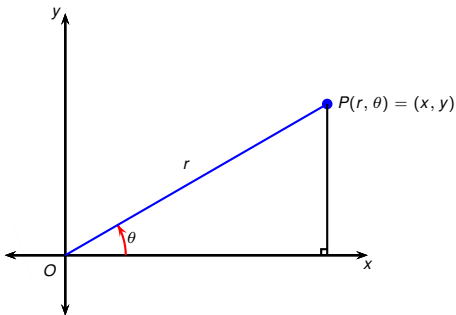
$$x =$$

$$y =$$

$$r =$$

$$\theta =$$

- How do we go from polar coordinates to Cartesian coordinates?
- Suppose a point has polar coordinates (r, θ) and Cartesian coordinates (x, y) .



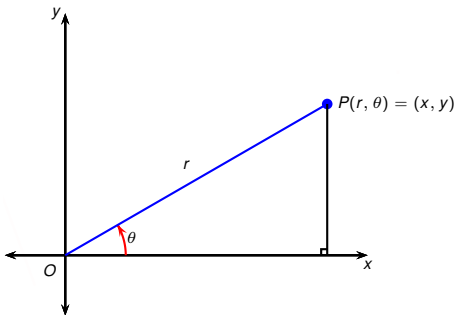
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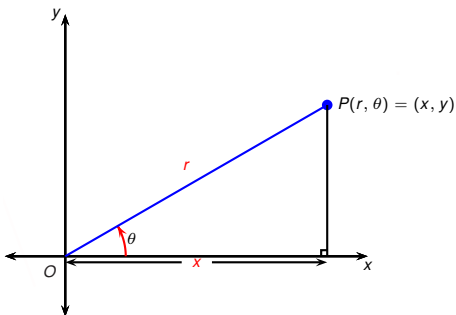
$$\cos \theta =$$

$$\sin \theta =$$

$$r =$$

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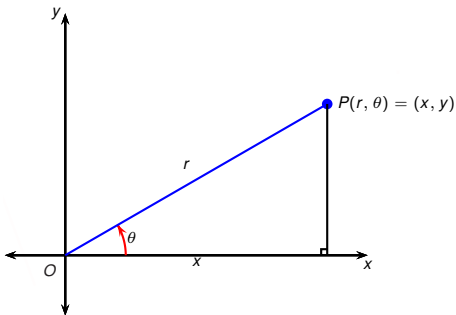
$$\cos \theta = \frac{x}{r}$$

$$\sin \theta =$$

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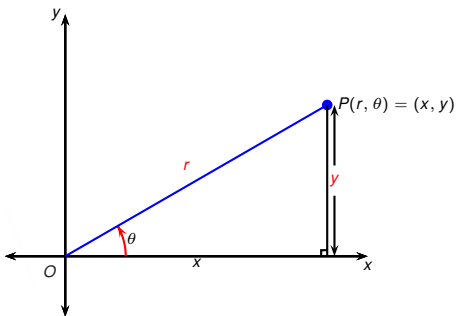
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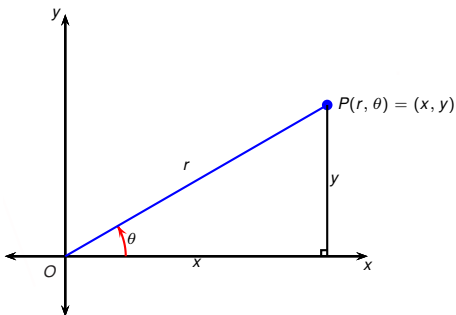
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$$x = r \cos \theta$$

$$y = r \sin \theta$$

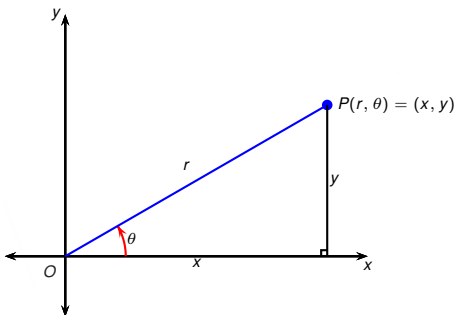
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- How do we go from polar coordinates to Cartesian coordinates?
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- How do we go from Cartesian coordinates to polar coordinates?



$$x = r \cos \theta$$

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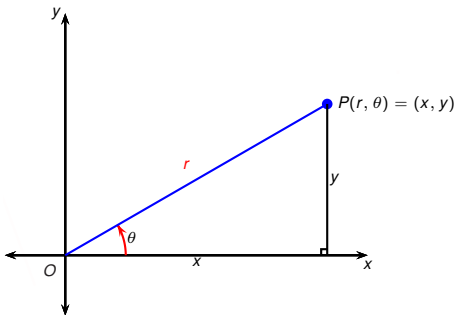
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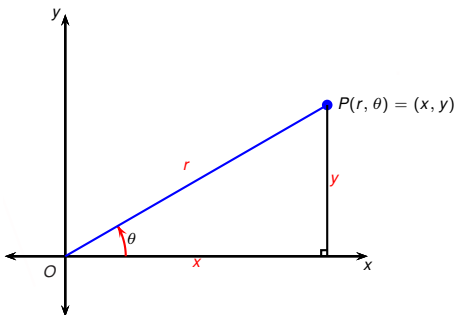
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$$r^2 =$$

$$r =$$

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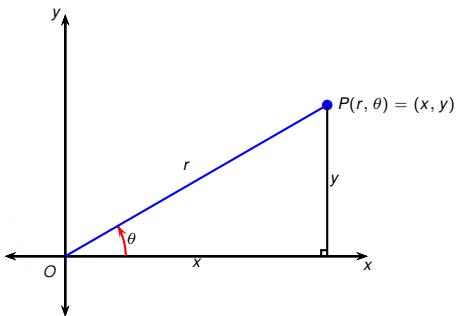
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$$r^2 = x^2 + y^2$$

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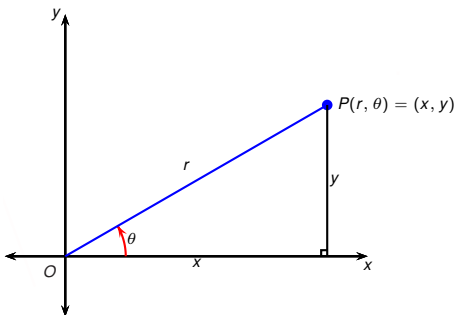
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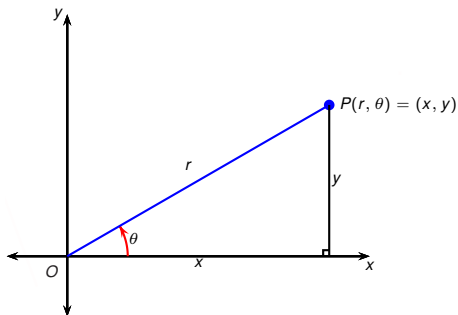
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$$\cos \theta = \frac{x}{r}$$

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$$r^2 = x^2 + y^2$$

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \arcsin\left(\frac{y}{r}\right) \quad \text{if } x > 0$$

$$= \arccos\left(\frac{x}{r}\right) \quad \text{if } y > 0$$

$$= \arctan\left(\frac{y}{x}\right) \quad \text{if } x > 0$$

Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

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$$y = r \sin \theta =$$

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$$x = r \cos \theta = \quad \cos$$

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Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

$$x = r \cos \theta = 2 \cos \frac{\pi}{3}$$

$$y = r \sin \theta =$$

Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

$$x = r \cos \theta = 2 \cos \frac{\pi}{3} = 2 \left(\right)$$

$$y = r \sin \theta =$$

Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

$$x = r \cos \theta = 2 \cos \frac{\pi}{3} = 2 \left(\frac{1}{2} \right)$$

$$y = r \sin \theta =$$

Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

$$x = r \cos \theta = 2 \cos \frac{\pi}{3} = 2 \left(\frac{1}{2} \right) = 1$$

$$y = r \sin \theta =$$

Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

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Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

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Example

Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

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Example

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Example

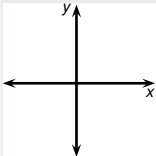
Convert the point $(2, \frac{\pi}{3})$ from polar to Cartesian coordinates.

$$x = r \cos \theta = 2 \cos \frac{\pi}{3} = 2 \left(\frac{1}{2} \right) = 1$$

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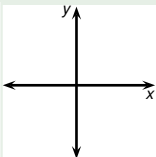
Therefore the point with polar coordinates $(2, \frac{\pi}{3})$ has Cartesian coordinates $(1, \sqrt{3})$.

Example



Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

Example

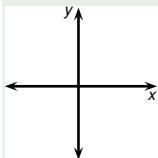


Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

$$r = \pm \sqrt{x^2 + y^2}$$

$$\tan \theta = \frac{y}{x}$$

Example



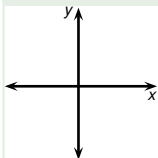
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.

$$r = \pm \sqrt{x^2 + y^2}$$

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Example



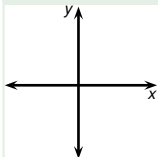
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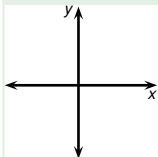
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

$$\tan \theta = \frac{y}{x}$$

Example



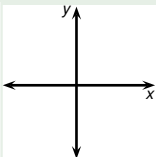
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

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$$\begin{aligned} \tan \theta &= \frac{y}{x} \\ &= -1 \end{aligned}$$

Example



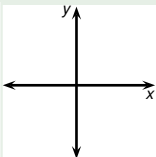
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.
- $\tan \theta = -1$ for $\theta = \frac{3\pi}{4}, \frac{7\pi}{4}$, and many other angles.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

$$\begin{aligned} \tan \theta &= \frac{y}{x} \\ &= -1 \end{aligned}$$

Example



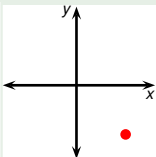
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.
- $\tan \theta = -1$ for $\theta = \frac{3\pi}{4}, \frac{7\pi}{4}$, and many other angles.
- $(1, -1)$ is in the fourth quadrant.

$$\begin{aligned}
 r &= \sqrt{x^2 + y^2} \\
 &= \sqrt{1^2 + (-1)^2} \\
 &= \sqrt{2}
 \end{aligned}$$

$$\begin{aligned}
 \tan \theta &= \frac{y}{x} \\
 &= -1
 \end{aligned}$$

Example



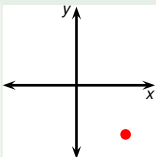
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Example



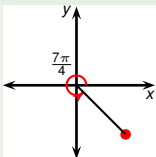
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.
- $\tan \theta = -1$ for $\theta = \frac{3\pi}{4}, \frac{7\pi}{4}$, and many other angles.
- $(1, -1)$ is in the fourth quadrant.
- Of the two values above, only $\theta =$ gives a point in the fourth quadrant.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

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Example



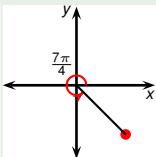
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- $(1, -1)$ is in the fourth quadrant.
- Of the two values above, only $\theta = \frac{7\pi}{4}$ gives a point in the fourth quadrant.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

$$\begin{aligned} \tan \theta &= \frac{y}{x} \\ &= -1 \end{aligned}$$

Example



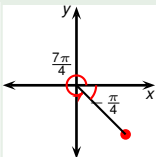
Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

- Suppose r is positive.
- $\tan \theta = -1$ for $\theta = \frac{3\pi}{4}, \frac{7\pi}{4}$, and many other angles.
- $(1, -1)$ is in the fourth quadrant.
- Of the two values above, only $\theta = \frac{7\pi}{4}$ gives a point in the fourth quadrant.
- \Rightarrow one representation of $(1, -1)$ in polar coordinates is $(\sqrt{2}, \frac{7\pi}{4})$.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

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Example



Represent the point with Cartesian coordinates $(1, -1)$ in terms of polar coordinates.

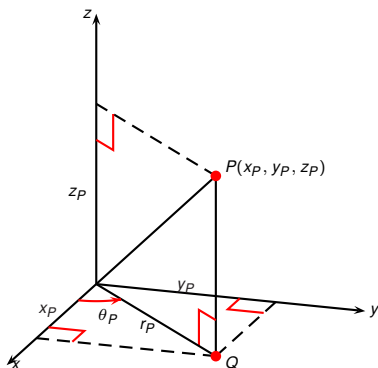
- Suppose r is positive.
- $\tan \theta = -1$ for $\theta = \frac{3\pi}{4}, \frac{7\pi}{4}$, and many other angles.
- $(1, -1)$ is in the fourth quadrant.
- Of the two values above, only $\theta = \frac{7\pi}{4}$ gives a point in the fourth quadrant.
- \Rightarrow one representation of $(1, -1)$ in polar coordinates is $(\sqrt{2}, \frac{7\pi}{4})$.
- $(\sqrt{2}, -\frac{\pi}{4})$ is another.

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ &= \sqrt{1^2 + (-1)^2} \\ &= \sqrt{2} \end{aligned}$$

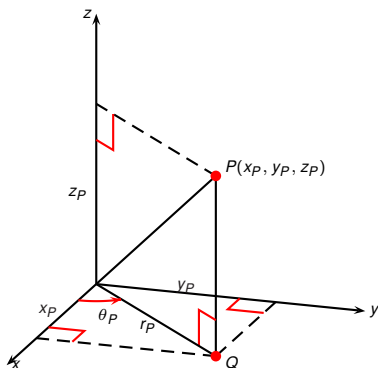
$$\begin{aligned} \tan \theta &= \frac{y}{x} \\ &= -1 \end{aligned}$$

Cylindrical coordinates

- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .

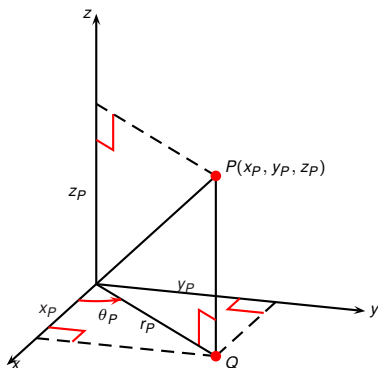


Cylindrical coordinates



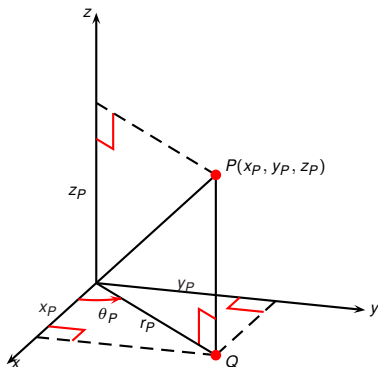
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative cylindrical coordinates (r_P, θ_P, z_P) .

Cylindrical coordinates



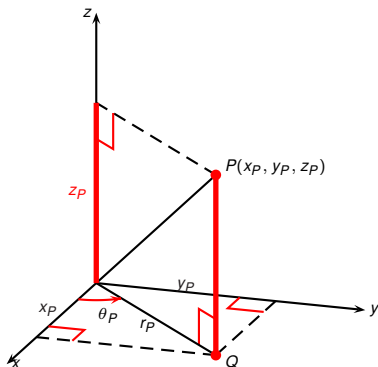
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Cylindrical coordinates



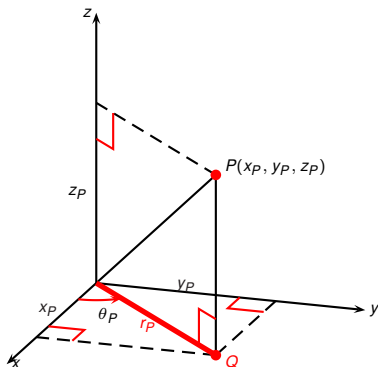
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- Cylindrical coordinates are obtained by “adding a z -coordinate” to the (2-dimensional) polar coordinates.
- More precisely, to P we assign triple (r_P, θ_P, z_P) , where:

Cylindrical coordinates



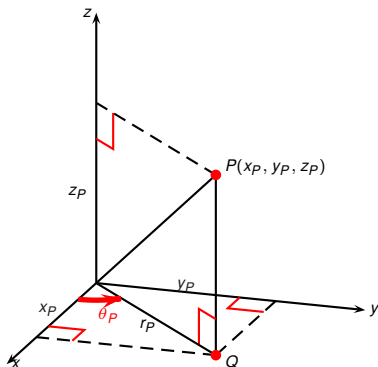
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 - z_P equals the z-coordinate of P ,
 - r_P is the distance $|OQ|$, where Q is the projection of P in the xy -plane and O -origin,

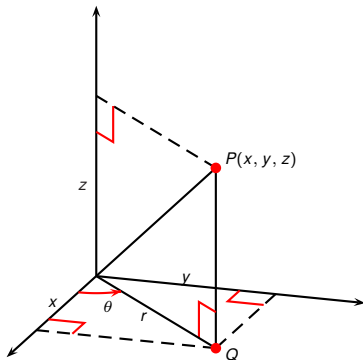
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 - r_P is the distance $|OQ|$, where Q is the projection of P in the xy -plane and O -origin,
 - θ_P is an angle between the x -axis and OQ .

Cylindrical to and from cartesian coordinates

To transform cylindrical to rectangular coordinates:



To transform rectangular to cylindrical:

$$r =$$

$$\cos \theta =$$

$$\sin \theta =$$

$$\theta =$$

$$z_{\text{cylindrical}} =$$

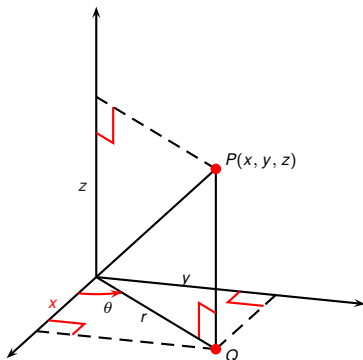
Cylindrical to and from cartesian coordinates

To transform cylindrical to rectangular coordinates:

$$x =$$

$$y =$$

$$z_{\text{rectangular}} =$$



To transform rectangular to cylindrical:

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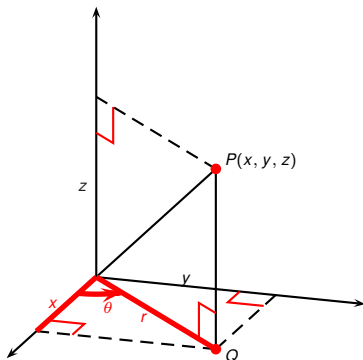
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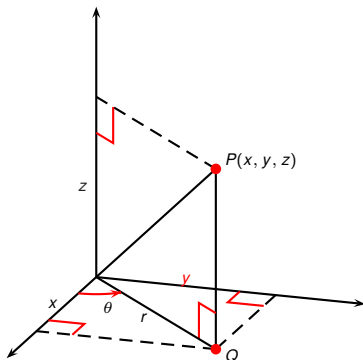
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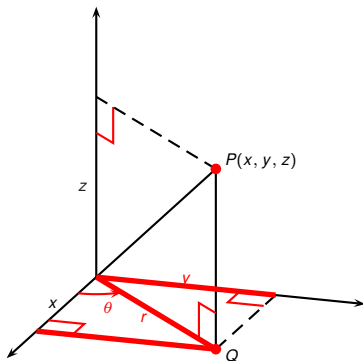
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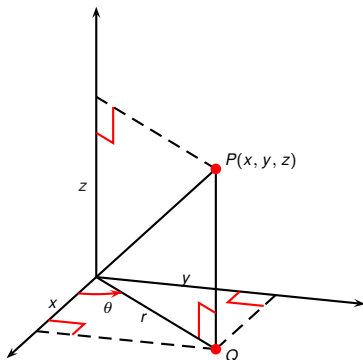
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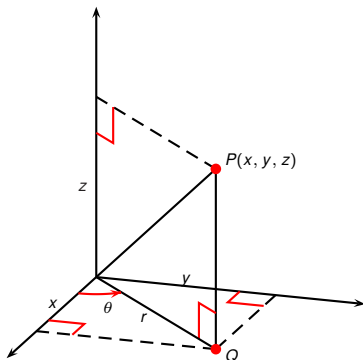
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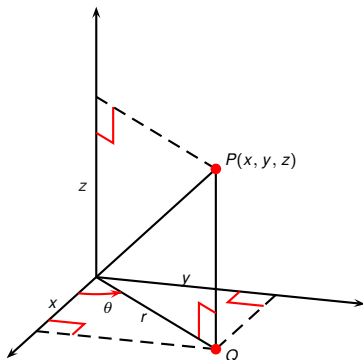
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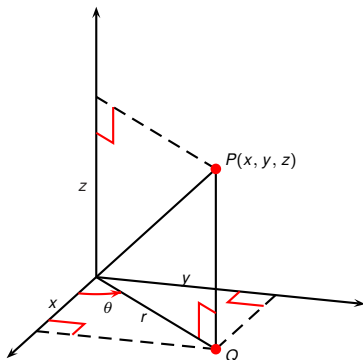
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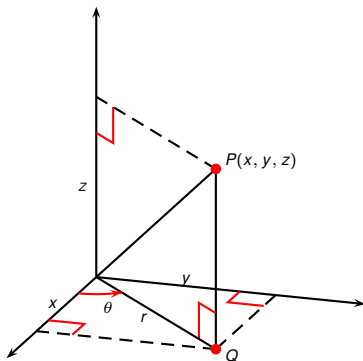
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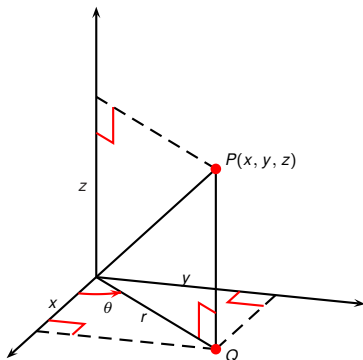
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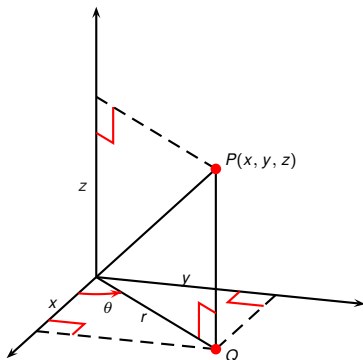
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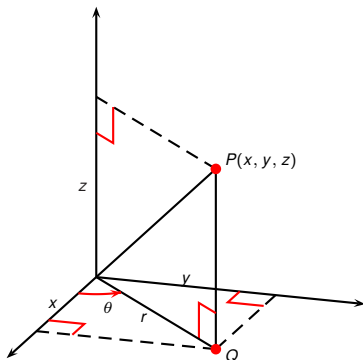
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$$\cos \theta = \frac{x}{r}$$

$$\sin \theta = \frac{y}{r}$$

$$\begin{aligned} \theta &= \arcsin\left(\frac{y}{r}\right) && \text{if } x > 0 \\ &= \arccos\left(\frac{x}{r}\right) && \text{if } y > 0 \\ &= \arctan\left(\frac{y}{x}\right) && \text{if } x > 0 \end{aligned}$$

$$z_{\text{cylindrical}} =$$

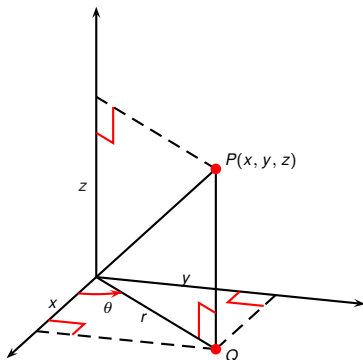
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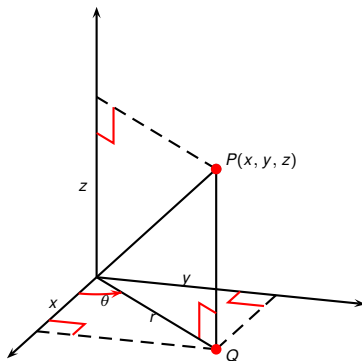
$$\theta = \arcsin\left(\frac{y}{r}\right) \quad \text{if } x > 0$$

$$= \arccos\left(\frac{x}{r}\right) \quad \text{if } y > 0$$

$$= \arctan\left(\frac{y}{x}\right) \quad \text{if } x > 0$$

$$z_{\text{cylindrical}} = z_{\text{rectangular}}$$

Constant Coordinate Sets



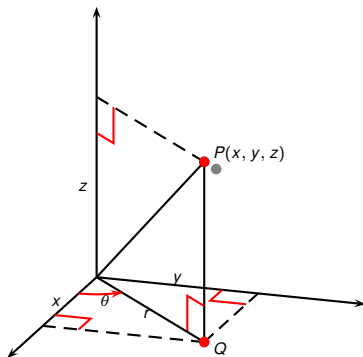
What curve is traced when:

- keep θ, z constant, let r vary:
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



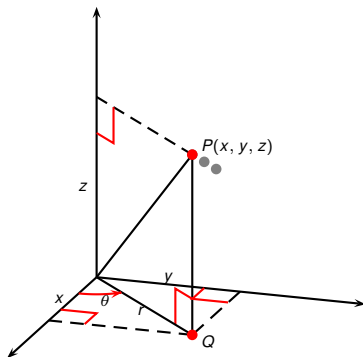
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Constant Coordinate Sets



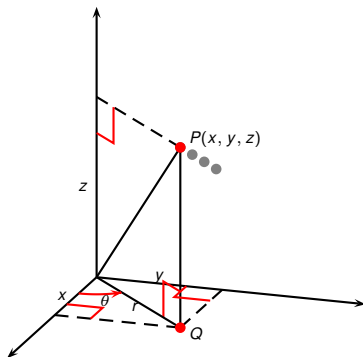
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- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



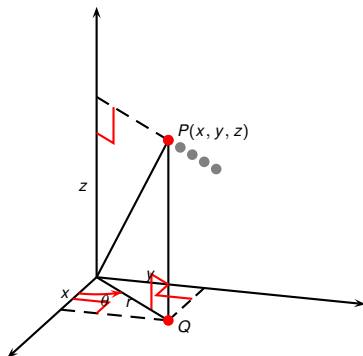
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Constant Coordinate Sets



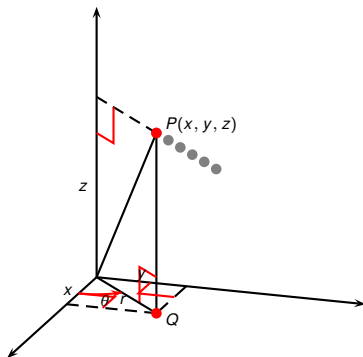
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Constant Coordinate Sets



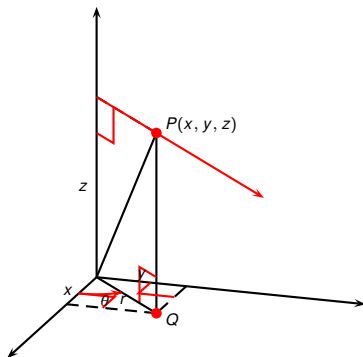
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- keep z constant, let r, θ vary:

Constant Coordinate Sets



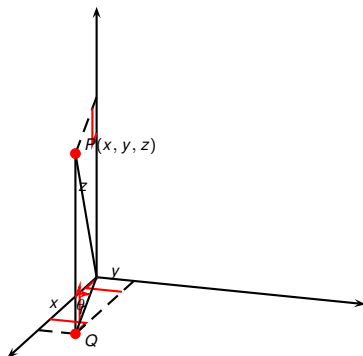
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



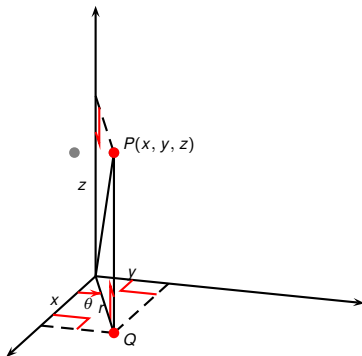
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



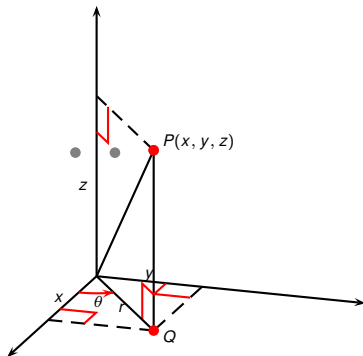
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



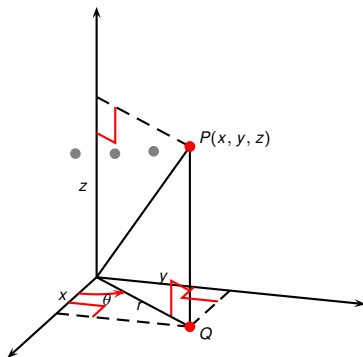
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



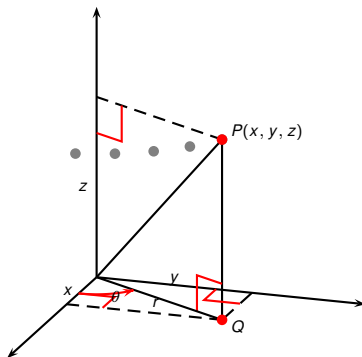
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



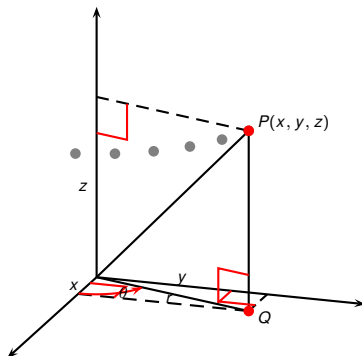
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary:
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



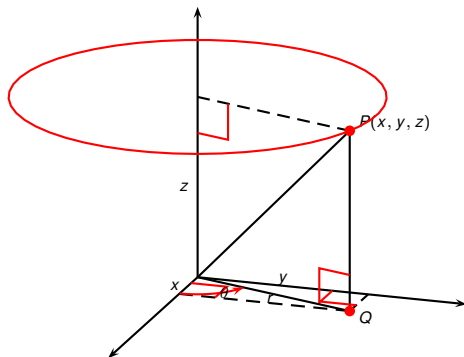
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- **keep r, z constant, let θ vary:**
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



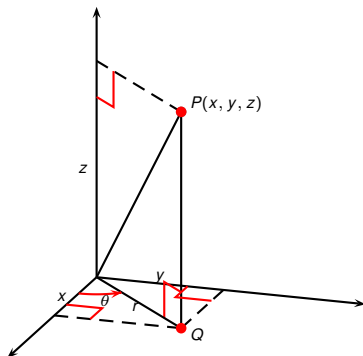
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- **keep r, z constant, let θ vary: horizontal circle;**
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



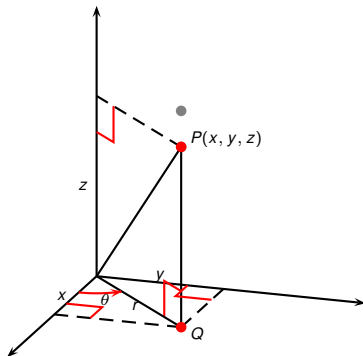
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



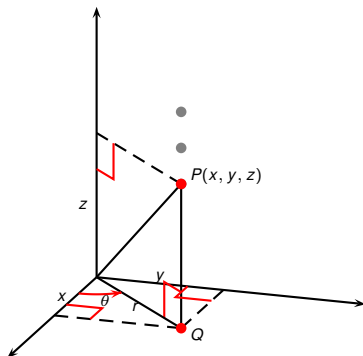
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



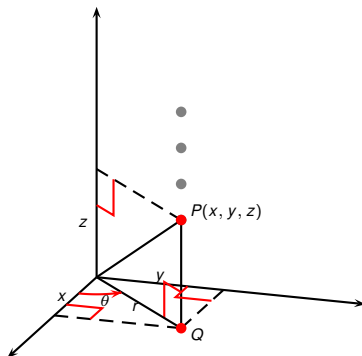
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



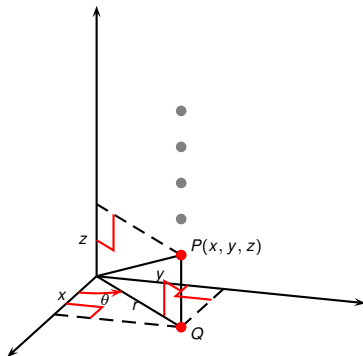
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- **keep r, θ constant, let z vary:**

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



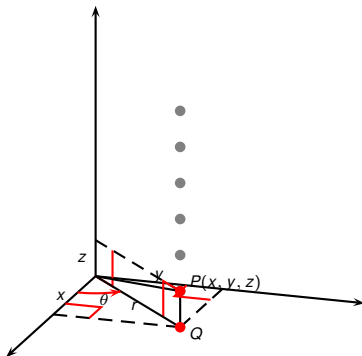
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



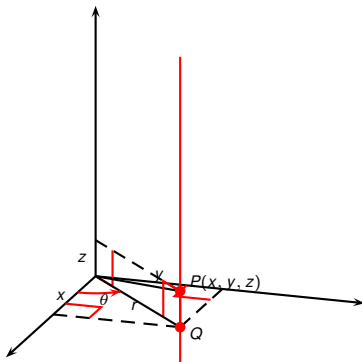
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary:

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



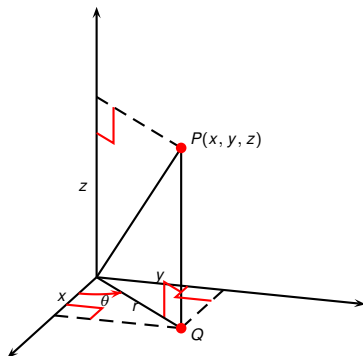
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



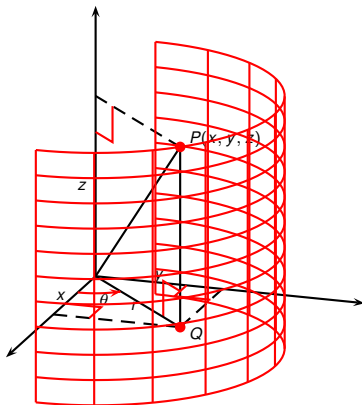
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary:
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



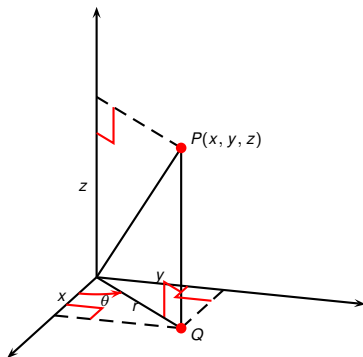
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary: vertical cylinder;
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



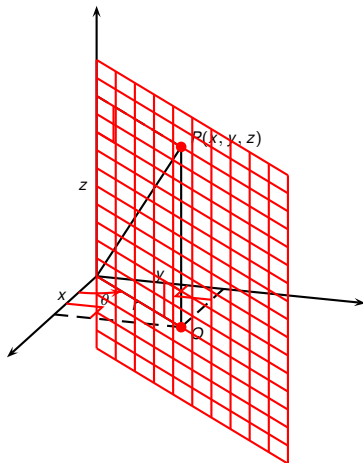
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary: vertical cylinder;
- keep θ constant, let r, z vary:
- keep z constant, let r, θ vary:

Constant Coordinate Sets



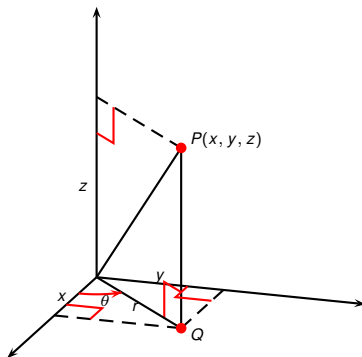
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary: vertical cylinder;
- keep θ constant, let r, z vary: vertical half plane;
- keep z constant, let r, θ vary:

Constant Coordinate Sets



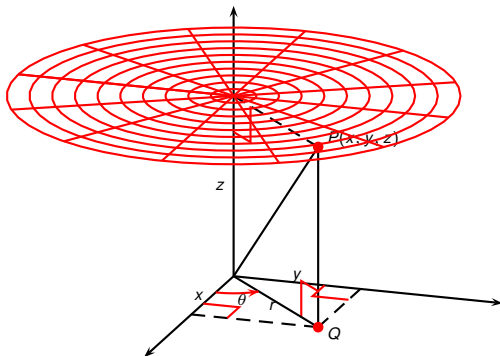
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

- keep r constant, let θ, z vary: vertical cylinder;
- keep θ constant, let r, z vary: vertical half plane;
- keep z constant, let r, θ vary:

Constant Coordinate Sets



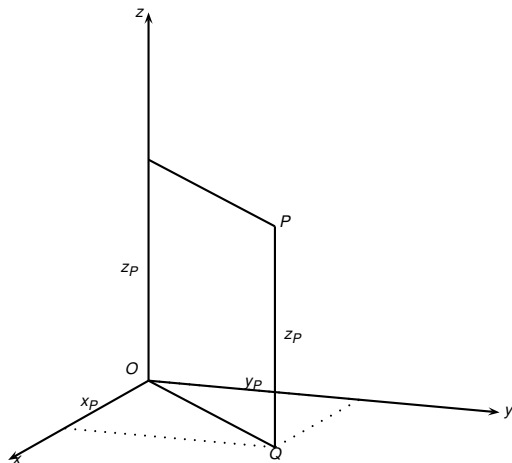
What curve is traced when:

- keep θ, z constant, let r vary: horizontal ray;
- keep r, z constant, let θ vary: horizontal circle;
- keep r, θ constant, let z vary: vertical line.

What surface is traced when:

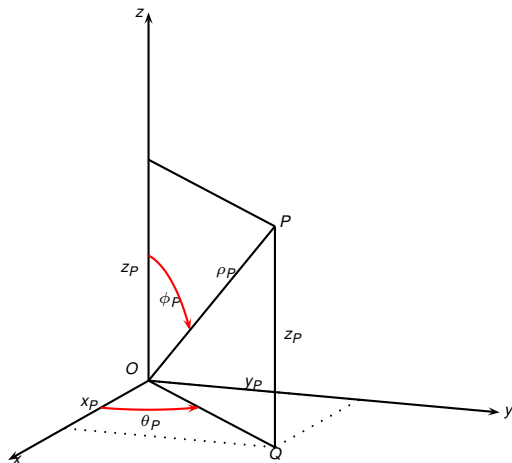
- keep r constant, let θ, z vary: vertical cylinder;
- keep θ constant, let r, z vary: vertical half plane;
- keep z constant, let r, θ vary: horizontal plane.

Spherical Coordinates



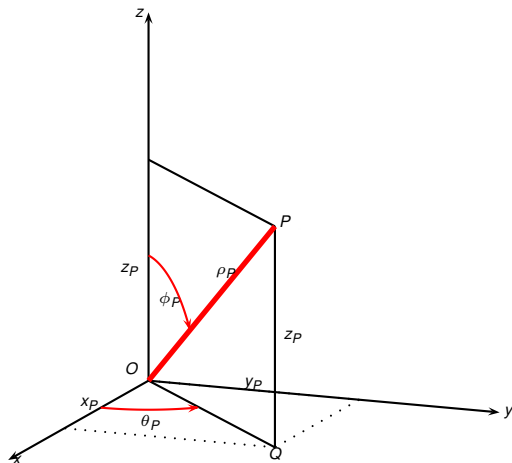
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .

Spherical Coordinates



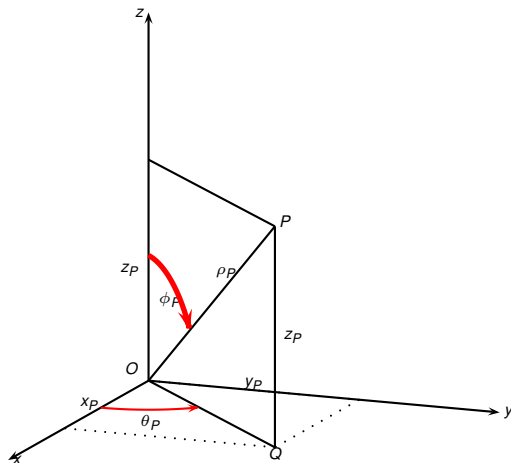
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .

Spherical Coordinates



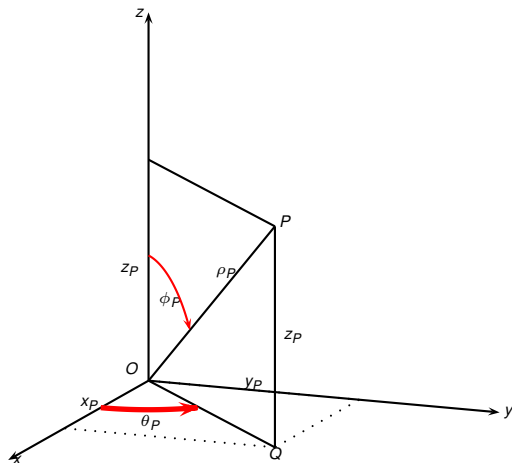
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .

Spherical Coordinates



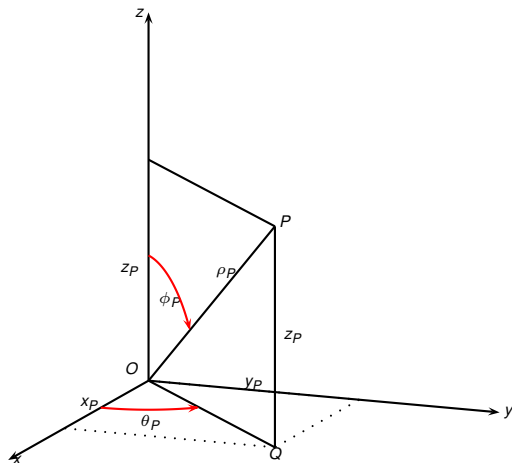
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Spherical Coordinates



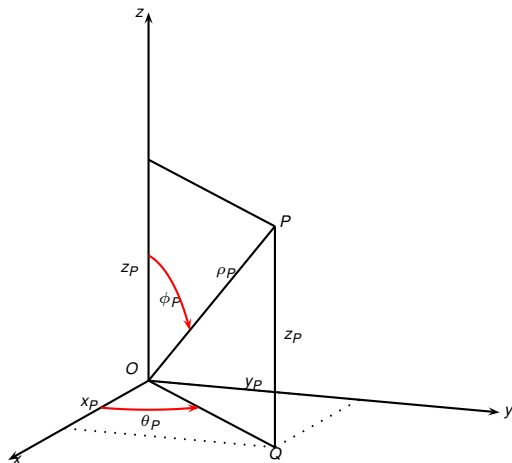
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .

Spherical Coordinates



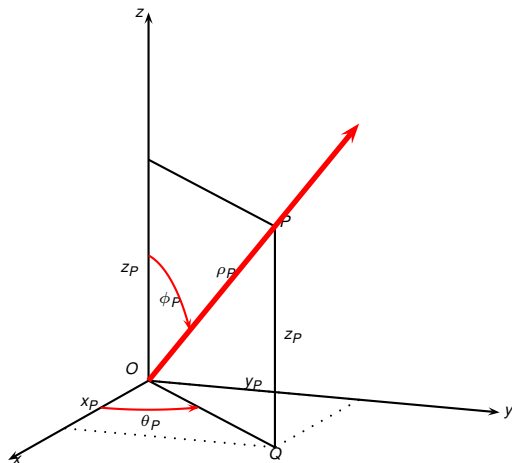
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ :
 - ϕ :
 - θ :

Spherical Coordinates



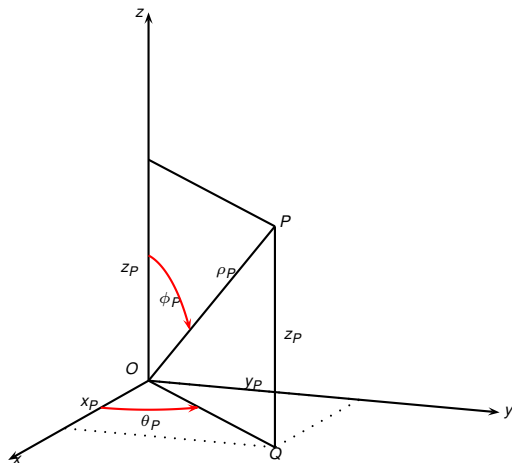
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ :
 - ϕ :
 - θ :

Spherical Coordinates



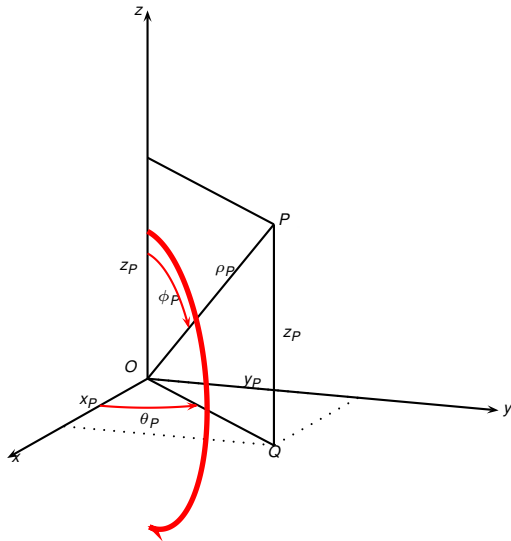
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ : $[0, \infty)$;
 - ϕ :
 - θ :

Spherical Coordinates



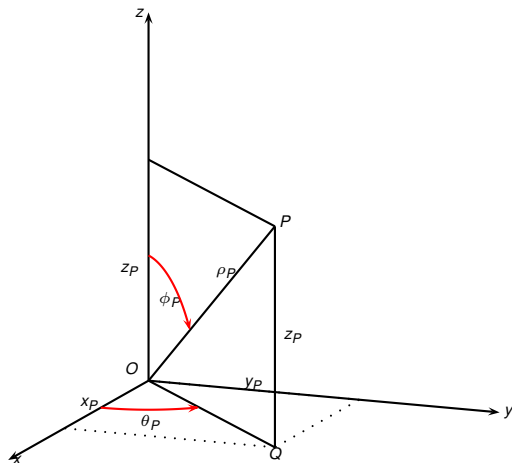
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ : $[0, \infty)$;
 - ϕ :
 - θ :

Spherical Coordinates



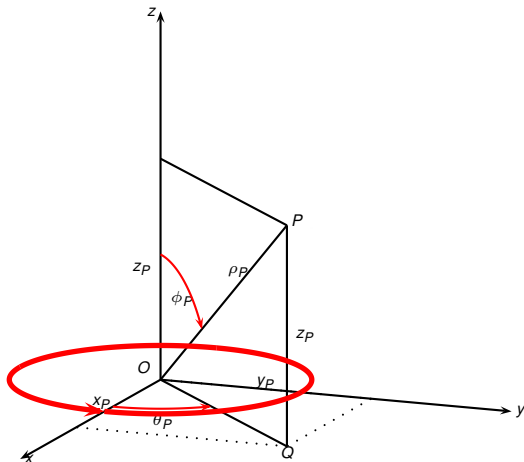
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ : $[0, \infty)$;
 - ϕ : $[0, \pi]$;
 - θ :

Spherical Coordinates



- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ : $[0, \infty)$;
 - ϕ : $[0, \pi]$;
 - θ :

Spherical Coordinates



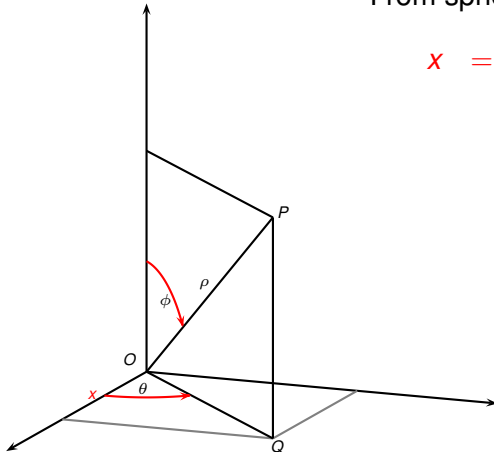
- In Cartesian coordinates, a point P is given by triple (x_P, y_P, z_P) .
- We introduce alternative spherical coordinates $(\rho_P, \phi_P, \theta_P)$.
 - ρ_P : distance $|OP|$;
 - ϕ_P : angle Oz to OP ;
 - θ_P : angle Ox to OP_{xy} .
- Coordinates range:
 - ρ : $[0, \infty)$;
 - ϕ : $[0, \pi]$;
 - θ : $[0, 2\pi)$.

Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

$x =$

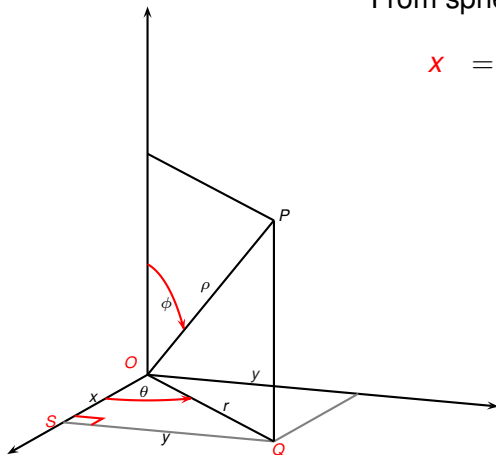
|



Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

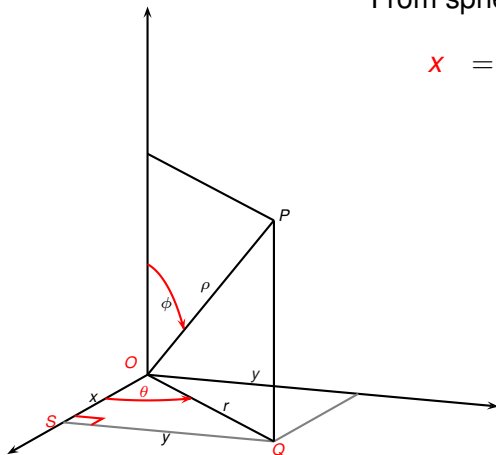
$$x = \quad \quad \quad | \text{ use } \triangle SQO$$



Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

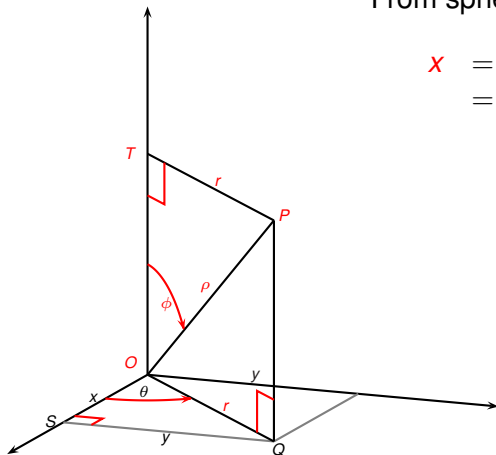
$$x = r \cos \theta \quad | \text{ use } \triangle SQO$$



Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

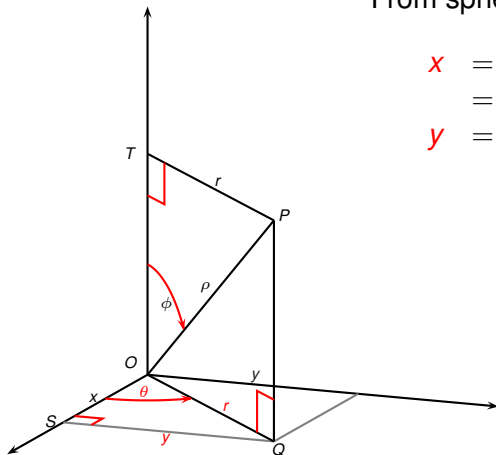
$$\begin{aligned}
 x &= r \cos \theta & \left| \begin{array}{l} \text{use } \triangle SQO \\ \text{use } \triangle OPT \end{array} \right. \\
 &= \rho \sin \phi \cos \theta
 \end{aligned}$$



Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

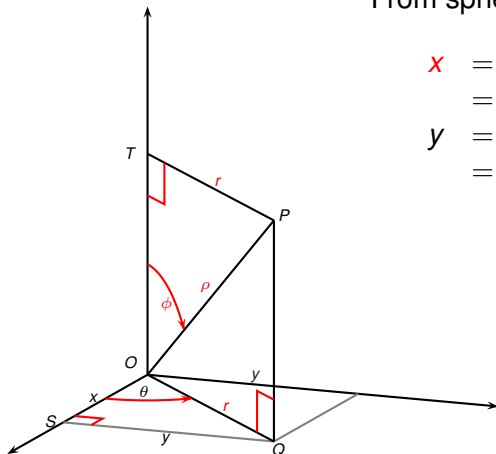
$$\begin{aligned}
 x &= r \cos \theta & \left| \begin{array}{l} \text{use } \triangle SQO \\ \text{use } \triangle OPT \end{array} \right. \\
 &= \rho \sin \phi \cos \theta \\
 y &= r \sin \theta
 \end{aligned}$$



Transition Spherical - Rectangular coordinates

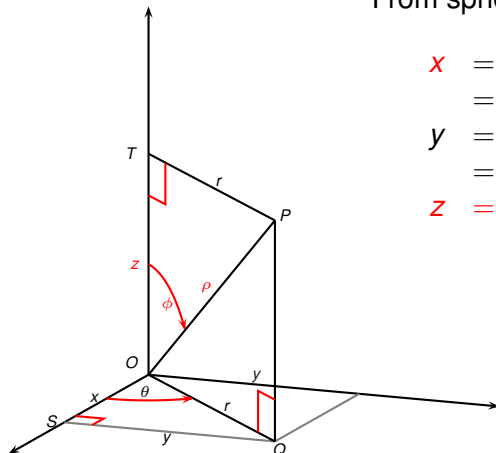
From spherical to rectangular coords:

$$\begin{aligned}
 x &= r \cos \theta & \left| \begin{array}{l} \text{use } \triangle SQO \\ \text{use } \triangle OPT \end{array} \right. \\
 &= \rho \sin \phi \cos \theta \\
 y &= r \sin \theta \\
 &= \rho \sin \phi \sin \theta
 \end{aligned}$$



Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

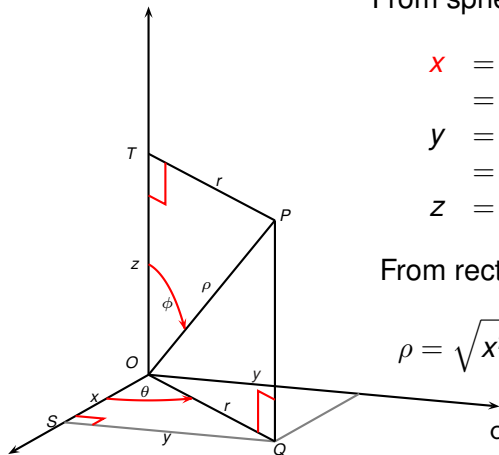


$$\begin{aligned}
 x &= r \cos \theta & \left| \begin{array}{l} \text{use } \triangle SQO \\ \text{use } \triangle OPT \end{array} \right. \\
 &= \rho \sin \phi \cos \theta \\
 y &= r \sin \theta \\
 &= \rho \sin \phi \sin \theta \\
 z &= \rho \cos \phi
 \end{aligned}$$

Transition Spherical - Rectangular coordinates

From spherical to rectangular coords:

$$\begin{aligned}
 x &= r \cos \theta & \left| \begin{array}{l} \text{use } \triangle S Q O \\ \text{use } \triangle O P T \end{array} \right. \\
 &= \rho \sin \phi \cos \theta \\
 y &= r \sin \theta \\
 &= \rho \sin \phi \sin \theta \\
 z &= \rho \cos \phi
 \end{aligned}$$



From rectangular to spherical coords:

$$\rho = \sqrt{x^2 + y^2 + z^2} \quad , \quad r = \sqrt{x^2 + y^2}$$

$$\cos \phi = \frac{z}{\rho} \quad , \quad \sin \phi = \frac{r}{\rho}$$

$$\cos \theta = \frac{x}{r} \quad , \quad \sin \theta = \frac{y}{r}$$

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary:
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary: ray through the origin;
- keep ρ, ϕ constant, let θ vary:
- keep ρ, θ constant, let ϕ vary:

Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary: ray through the origin;
- keep ρ, ϕ constant, let θ vary:
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- keep θ, ϕ constant, let ρ vary: ray through the origin;
- keep ρ, ϕ constant, let θ vary: circle parallel to the xy -plane, “parallel”;
- keep ρ, θ constant, let ϕ vary:

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Constant Coordinate Sets

What curve is traced when:

- keep θ, ϕ constant, let ρ vary: ray through the origin;
- keep ρ, ϕ constant, let θ vary: circle parallel to the xy -plane, “parallel”;
- keep ρ, θ constant, let ϕ vary: circle passing through z axis, “meridian”.

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary:
- keep θ constant, let ρ, ϕ vary:
- keep ρ constant, let ϕ, θ vary:

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary: cone;
- keep θ constant, let ρ, ϕ vary:
- keep ρ constant, let ϕ, θ vary:

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary: cone;
- keep θ constant, let ρ, ϕ vary:
- keep ρ constant, let ϕ, θ vary:

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary: cone;
- keep θ constant, let ρ, ϕ vary: vertical half plane;
- keep ρ constant, let ϕ, θ vary:

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary: cone;
- keep θ constant, let ρ, ϕ vary: vertical half plane;
- keep ρ constant, let ϕ, θ vary:

Constant Coordinate Sets

What surface is traced when:

- keep ϕ constant, let θ, ρ vary: cone;
- keep θ constant, let ρ, ϕ vary: vertical half plane;
- keep ρ constant, let ϕ, θ vary: sphere.

Polar curvilinear “boxes”

Polar “wedge”:

$$C = \{P(r, \theta) \mid r_0 \leq r \leq r_0 + \Delta r, \theta_0 \leq \theta \leq \theta_0 + \Delta \theta\} .$$

Shape?

Polar curvilinear “boxes”

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$$C = \{P(r, \theta) \mid r_0 \leq r \leq r_0 + \Delta r, \theta_0 \leq \theta \leq \theta_0 + \Delta \theta\} .$$

Shape? Area = ...?

Cylindrical curvilinear “boxes”

Cylindrical “box”:

$$X = \{P(r, \theta, z) \mid 0 \leq r \leq r_0, 0 \leq \theta \leq \theta_0, 0 \leq z \leq z_0\}$$

Cylindrical curvilinear “boxes”

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Shape ?

Cylindrical curvilinear “boxes”

Cylindrical “box”:

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Shape ? Volume = ...?

Spherical curvilinear “boxes”

- Cut off a rectangular box B in the ρ, ϕ, θ -coordinates. $B :=$

$$\left\{ (\rho, \phi, \theta) \mid \begin{array}{l} \rho_{min} \leq \rho \leq \rho_{max} \\ \phi_{min} \leq \phi \leq \phi_{max} \\ \theta_{min} \leq \theta \leq \theta_{max} \end{array} \right\}$$

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- As (ρ, ϕ, θ) traverse B , the point $P(\rho, \phi, \theta)$ traverses curvilinear “box” Y :

$$Y = \{P(\rho, \phi, \theta) \mid (\rho, \phi, \theta) \in B\}.$$

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- What is the shape of that curvilinear box?

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- What is the shape of that curvilinear box?
- What is the volume?