Calculus III Lecture 10

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https://github.com/tmilev/freecalc

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Multivariable Chain Rule

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Directional Derivatives via the Chain Rule

- Multivariable Chain Rule
- Directional Derivatives via the Chain Rule
- Gradient

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- Directional Derivatives via the Chain Rule
- Gradient
- Differential Operators
 - Differential Operators Variable Changes

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Multivariable Chain Rule Motivation

Recall:

- f, differentiable function,
- $\mathbf{u} = (u_1, u_2, u_3)$, unit vector,
- $P(x_0, y_0, z_0)$, point.

What is the rate of change of f at P in the direction \mathbf{u} ?

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$$(D_{\mathbf{u}}f)(P) = \frac{d}{dt}\Big|_{t=0} f(x_0 + tu_1, y_0 + tu_2, z_0 + tu_3)$$

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More general, if

- \bullet w = w(x, y, z);
 - x = x(t), y = y(t), z = z(t),

and all the functions are differentiable, how do we compute $\frac{dw}{dt}$?

Differentials

$$dw = w_x(x, y, z) \frac{dx}{dx} + w_y(x, y, z) \frac{dy}{dy} + w_z(x, y, z) \frac{dz}{dz}$$

and

$$dx = x'(t)dt$$
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Therefore

$$\frac{d}{dt}(w(x(t),y(t),z(t))) = \frac{\partial w}{\partial x}(x,y,z)\frac{dx}{dt} + \frac{\partial w}{\partial y}(x,y,z)\frac{dy}{dt} + \frac{\partial w}{\partial z}(x,y,z)\frac{dz}{dt}$$

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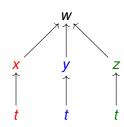
Derivative of composition of functions ⇒ Chain Rule

Algebra of Chain rule - Tree Diagrams

- \bullet W = W(X, Y, Z);
- x = x(t), y = y(t), z = z(t),

$$\frac{dw}{dt}(t) = \frac{\partial w}{\partial x}(x, y, z)\frac{dx}{dt}(t) + \frac{\partial w}{\partial y}(x, y, z)\frac{dy}{dt}(t) + \frac{\partial w}{\partial z}(x, y, z)\frac{dz}{dt}(t)$$

Alternative way of arranging terms - tree diagram:



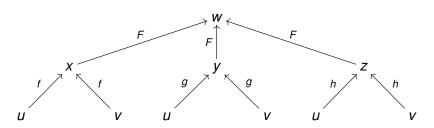
More General Chain Rule

More general formula:

- w = F(x, y, z);
- x = f(u, v), y = g(u, v), z = h(u, v).w = F(f(u, v), g(u, v), h(u, v)) = G(u, v).

To compute $\frac{\partial w}{\partial u} = \frac{\partial G}{\partial u}$:

• arrange variables in a tree diagram:



Example: powerexponential

Let $f(x) = x^x$. Compute f'(x).

- Calculus I method: logarithmic differentiation or $x^x = e^{x \ln x}$.
- Calculus III method: chain rule.

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Let $f(x) = x^x$. Compute f'(x).

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- Calculus III method: chain rule.

Let
$$w = w(u, v) = u^{v}$$
 and $u = u(x) = x$, $v = v(x) = x$.

Then
$$f(x) = w(u(x), v(x))$$
 and

Directional Derivatives via the Chain Rule

- Let f differentiable function,
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What is the rate of change of f at P in the direction \mathbf{u} ? Answer was studied: directional derivative.

Directional Derivatives via the Chain Rule

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$$(D_{\mathbf{u}}f)_{(x,y,z)=(x_0,y_0,z_0)}=\frac{\mathsf{d}}{\mathsf{d}t}_{|t=0}f(x_0+tu_1,y_0+tu_2,z_0+tu_3)$$

$$(D_{\mathbf{u}}f)(x_0,y_0,z_0)=\frac{\mathsf{d}}{\mathsf{d}t}_{|t=0}f(x_0+tu_1,y_0+tu_2,z_0+tu_3)$$

$$(D_{\mathbf{u}}f)(x_0,y_0,z_0) = \frac{d}{dt}_{|t=0}f(x_0+tu_1,y_0+tu_2,z_0+tu_3)$$
Let $w = f(x,y,z)$ and $\begin{vmatrix} x & = x_0+tu_1 \\ y & = y_0+tu_2 \\ z & = z_0+tu_3 \end{vmatrix}$.

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$$= \left(\frac{\partial f}{\partial x} \frac{\mathsf{d}x}{\mathsf{d}t} + \frac{\partial f}{\partial y} \frac{\mathsf{d}y}{\mathsf{d}t} + \frac{\partial f}{\partial z} \frac{\mathsf{d}z}{\mathsf{d}t} \right)_{|t=0}$$

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Definition (∇f ("nabla of f"))

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right).$$

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Definition (∇f ("nabla of f"))

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right).$$

Find the directional derivative of $f(x, y, z) = \ln(x^2 + 2y^2 - z^2)$ at P(2, 1, -1) in the direction $\mathbf{v} = (-1, 2, 1)$.

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$$\mathbf{u} = \frac{1}{|\mathbf{v}|}\mathbf{v} = \frac{1}{\sqrt{6}}(-1, 2, 1)$$
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The partial derivatives are

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} = \frac{\partial f}{\partial z} = 0$$

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The partial derivatives are

$$\frac{\partial f}{\partial x} = \frac{2x}{x^2 + 2y^2 - z^2}$$

$$\frac{\partial f}{\partial y} = \frac{4y}{x^2 + 2y^2 - z^2}$$

$$\frac{\partial f}{\partial z} = \frac{-2z}{x^2 + 2y^2 - z^2}$$

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 $(D_{\mathbf{u}}f)(2,1,-1) > 0$ implies that if we start at (2,1,-1) and move in the direction \mathbf{u} , then f is increasing.

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Definition

The *gradient vector* of f at P is the unique vector that has

- magnitude equal to the maximal rate of increase of f at P.
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$$(D_{\mathbf{u}}f)=(\nabla f)\cdot\mathbf{u}$$

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- If $|\nabla f| \neq 0$, then $(D_{\mathbf{u}}f)$ is maximal when $\cos \alpha = 1$, i.e., $\alpha = 0$.
- Therefore the maximum of $D_{\mathbf{u}}f$ is achieved for $\mathbf{u} = \frac{\nabla f}{|\nabla f|}$.

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- The increase of f in unit direction \mathbf{u} is $D_{\mathbf{u}}f$. We have: $(D_{\mathbf{u}}f) = (\nabla f) \cdot \mathbf{u} = |\nabla f| \cdot |\mathbf{u}| \cos \alpha = |\nabla f| \cos \alpha$, where α is the angle between ∇f and \mathbf{u} .
- If $|\nabla f| \neq 0$, then $(D_{\mathbf{u}}f)$ is maximal when $\cos \alpha = 1$, i.e., $\alpha = 0$.
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$$(\nabla_{\gamma'(t_0)}f)(\gamma(t_0)) = \frac{\mathsf{d}}{\mathsf{d}t}_{|t=t_0}f(\gamma(t)) = (\nabla f)_{\gamma(t_0)} \cdot \gamma'(t_0) .$$

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If **u** is a unit vector, $\gamma(t_0) = P$ and $\gamma'(t_0) = \mathbf{u}$, then:

$$(D_{\mathbf{u}}f)(P) = (\nabla f)_P \cdot \mathbf{u} = (\nabla f)_{\gamma(t_0)} \cdot \gamma'(t_0) = \frac{\mathsf{d}}{\mathsf{d}t}_{t=t_0} f(\gamma(t)) \ .$$

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 \mathbf{e}_r and \mathbf{e}_θ perpendicular unit vectors \Longrightarrow

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To compute $(D_{\mathbf{e}_r}f)(P)$ we use the line through $P(r_0, \theta_0)$ with direction \mathbf{e}_r , which in polar coordinates is given by $(r, \theta) = (t, \theta_0)$. Therefore

$$a = (D_{\mathbf{e}_r} f)(P) = \left. \frac{d}{dt} \right|_{t=r_0} f(t, \theta_0) = \frac{\partial f}{\partial r}(P) \ .$$

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To compute $(D_{\mathbf{e}_{\theta}}f)(P)$ we use the circle centered at the origin and passing through $P(r_0, \theta_0)$. The polar parametrization of this circle that has *unit* tangent at P is given by $(r, \theta) = (r_0, \frac{1}{r_0}t)$. Therefore

$$b = (D_{\mathbf{e}_{\theta}}f)(P) = \left. \frac{d}{dt} \right|_{t=\theta_0} f\left(r_0, \frac{1}{r_0}t\right) = \frac{1}{r_0} \frac{\partial f}{\partial \theta}(P) \ .$$

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From the previous computations:

$$(\nabla f)_P = \frac{\partial f}{\partial r}(P)\mathbf{e}_r + \frac{1}{r_0}\frac{\partial f}{\partial \theta}(P)\mathbf{e}_\theta ,$$

or

$$abla = \mathbf{e}_r \frac{\partial}{\partial r} + \mathbf{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} .$$

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Problem: Let X be a vector field of the form

$$\mathbf{X} = h(r)\mathbf{r}$$

for some continuous function h. Show that **X** is a *gradient field*: there exists a smooth function f such that $\mathbf{X} = \nabla f$.

Gravity and Gradient

- Let an object move along surface z = f(x, y).
- Let gravity **G** be constant, G = -mg k.
- Normal to surface:

$$\mathbf{n} = (-f_x(x_0, y_0), -f_y(x_0, y_0), 1) = -\nabla f + \mathbf{k}$$

Let F be the component of G effectively acting on the object.
 Object is restricted to the surface ⇒ F is the component of G tangent to the surface.

$$\begin{array}{rcl} \mathbf{F} & = & \mathrm{orth}_{n}\mathbf{G} = -mg \ \mathrm{orth}_{n}\mathbf{k} \\ \mathrm{orth}_{n}\mathbf{k} & = & \mathbf{k} - \mathrm{proj}_{n}\mathbf{k} = \mathbf{k} - \frac{\mathbf{k} \cdot \mathbf{n}}{|\mathbf{n}|^{2}} \mathbf{n} = \mathbf{k} - \frac{1}{|\mathbf{n}|^{2}} (-\nabla f + \mathbf{k}) \end{array}$$

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Gravity pulls object in the direction of fastest descent.

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Definition (Smooth finite order differential operators)

A differential operator over D is a map from $\mathcal{C}^{\infty}(D)$ to $\mathcal{C}^{\infty}(D)$ obtained by sums of operators $\frac{\partial^n}{\partial x^n} \frac{\partial^m}{\partial y^m}$ with coefficients in $\mathcal{C}^{\infty}(D)$.

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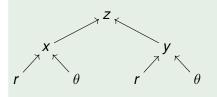
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- Analogous definitions exist for functions in n variables.

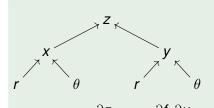


Let $x = r \cos \theta$, $y = r \sin \theta$ and z = f(x, y).

- Compute $\frac{\partial z}{\partial r}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator $\frac{\partial}{\partial r}$ via $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial v}$.

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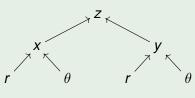
Example (Derivatives in polar coordinates)



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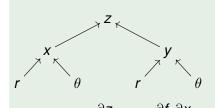
Todor Miley Lecture 10 2020



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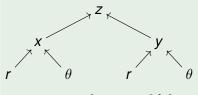
$$\frac{\partial z}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} = \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$$



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Recall that
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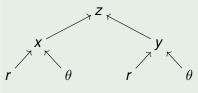


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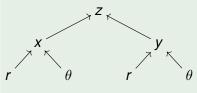
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$$\frac{\partial \mathbf{z}}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} = \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$$
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The above is true for all differentiable z = f(x, y),

Recall that
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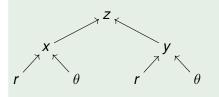
- Compute $\frac{\partial z}{\partial r}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator $\frac{\partial}{\partial r}$ via $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$.

$$\frac{\partial z}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} = \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$$
$$= \cos \theta \frac{\partial z}{\partial x} + \sin \theta \frac{\partial z}{\partial y} .$$

The above is true for all differentiable z = f(x, y), therefore

$$\frac{\partial}{\partial r} = \cos\theta \frac{\partial}{\partial x} + \sin\theta \frac{\partial}{\partial y} \quad .$$

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Let $x = r \cos \theta$, $y = r \sin \theta$ and z = f(x, y).

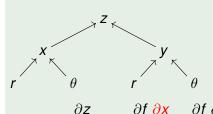
- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator $\frac{\partial}{\partial \theta}$ via $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$.



$$\frac{\partial z}{\partial \theta} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta}$$

Let
$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = f(x, y)$.

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator $\frac{\partial}{\partial \theta}$ via $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$.



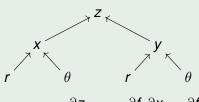
Let
$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = f(x, y)$.

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial v}$.
- Express the differential operator

$$r \qquad \theta \qquad \frac{\partial x}{\partial \theta} \text{ via } \frac{\partial}{\partial x} \text{ and } \frac{\partial}{\partial y}.$$

$$= \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = \frac{\partial f}{\partial x} (-r \sin \theta) + \frac{\partial f}{\partial y} r \cos \theta$$

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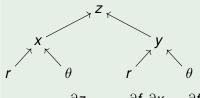


Let
$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = f(x, y)$.

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator $\frac{\partial}{\partial \theta}$ via $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$.

$$\frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = \frac{\partial f}{\partial x} (-r \sin \theta) + \frac{\partial f}{\partial y} r \cos \theta$$

Recall that
$$\frac{\partial z}{\partial x} = \left(\frac{\partial f}{\partial x}\right)(x, y)$$
 and $\frac{\partial z}{\partial y} = \left(\frac{\partial f}{\partial y}\right)(x, y)$.



Let
$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = f(x, y)$.

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial y}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator

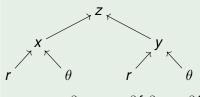
$$r \qquad \theta \qquad \text{Express the differential of } \frac{\partial}{\partial \theta} \text{ via } \frac{\partial}{\partial x} \text{ and } \frac{\partial}{\partial y}.$$

$$F = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = \frac{\partial f}{\partial x} (-r \sin \theta) + \frac{\partial f}{\partial y} r \cos \theta$$

$$= -r \sin \theta \frac{\partial z}{\partial x} + r \cos \theta \frac{\partial z}{\partial y} .$$

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Recall that
$$\frac{\partial z}{\partial x} = \left(\frac{\partial f}{\partial x}\right)(x,y)$$
 and $\frac{\partial z}{\partial y} = \left(\frac{\partial f}{\partial y}\right)(x,y)$.



Let $x = r \cos \theta$, $y = r \sin \theta$ and z = f(x, y).

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial y}$ and $\frac{\partial z}{\partial y}$.
- Express the differential operator

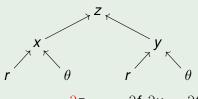
$$\frac{\partial z}{\partial \theta} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = \frac{\partial f}{\partial x} (-r \sin \theta) + \frac{\partial f}{\partial y} r \cos \theta$$

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The above is true for all differentiable z = f(x, y),

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Recall that
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 and $\frac{\partial z}{\partial y} = \left(\frac{\partial f}{\partial y}\right)(x,y)$.



Let
$$x = r \cos \theta$$
, $y = r \sin \theta$ and $z = f(x, y)$.

- Compute $\frac{\partial z}{\partial \theta}$ via $\frac{\partial z}{\partial y}$ and $\frac{\partial z}{\partial y}$.

$$\theta \qquad r \qquad \theta \qquad \text{Express the differential operator}$$

$$\frac{\partial z}{\partial \theta} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = \frac{\partial f}{\partial x} (-r \sin \theta) + \frac{\partial f}{\partial y} r \cos \theta$$

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The above is true for all differentiable z = f(x, y), therefore

$$\frac{\partial}{\partial \theta} = -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y} \quad .$$

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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. We computed previously that

$$\begin{array}{rcl} \frac{\partial}{\partial r} & = & \cos\theta \frac{\partial}{\partial x} + & \sin\theta \frac{\partial}{\partial y} \\ \frac{\partial}{\partial \theta} & = & -r\sin\theta \frac{\partial}{\partial x} + r\cos\theta \frac{\partial}{\partial y} \end{array}.$$

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This is a linear system in $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$.

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This is a linear system in $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$. To solve the system, eliminate $\frac{\partial}{\partial x}$ by multiplying the first equality by $r \sin \theta$, the second by $\cos \theta$ and adding the two.

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. We computed previously that

$$\frac{\partial}{\partial r} = \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y} \frac{\partial}{\partial \theta} = -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y}.$$

This is a linear system in $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$. To solve the system, eliminate $\frac{\partial}{\partial x}$ by multiplying the first equality by $r \sin \theta$, the second by $\cos \theta$ and adding the two. Similarly eliminate $\frac{\partial}{\partial y}$ by multiplying the first equality by $-r \cos \theta$ and the second by $\sin \theta$ and adding the two.

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. We computed previously that

$$\frac{\partial}{\partial r} = \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y} \frac{\partial}{\partial \theta} = -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y}.$$

This is a linear system in $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$. To solve the system, eliminate $\frac{\partial}{\partial x}$ by multiplying the first equality by $r\sin\theta$, the second by $\cos\theta$ and adding the two. Similarly eliminate $\frac{\partial}{\partial y}$ by multiplying the first equality by $-r\cos\theta$ and the second by $\sin\theta$ and adding the two. Finally:

$$\begin{array}{rcl} \frac{\partial}{\partial x} & = & \cos\theta \frac{\partial}{\partial r} - \frac{1}{r}\sin\theta \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial y} & = & \sin\theta \frac{\partial}{\partial r} + \frac{1}{r}\cos\theta \frac{\partial}{\partial \theta} \end{array}$$

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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

Recall that

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

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$$\tan \theta = \frac{r \sin \theta}{r \cos \theta}$$

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

Recall that

$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x}$$

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

Recall that

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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. Suppose $\theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Recall that

$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x}
 \theta = \arctan \left(\frac{y}{x}\right)$$

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. Suppose $\theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Recall that

$$\begin{array}{rcl} \tan \theta & = & \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x} \\ \theta & = & \arctan \left(\frac{y}{x}\right) \\ r & = & \sqrt{x^2 + y^2} \end{array}$$

Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

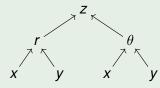
Suppose
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$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x}$$

$$\theta = \arctan \left(\frac{y}{x}\right)$$

$$r = \sqrt{x^2 + y^2}$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x}$$



Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

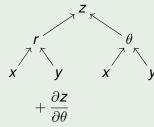
Suppose $\theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Recall that

$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{X}$$

$$\theta = \arctan \left(\frac{y}{X}\right)$$

$$r = \sqrt{X^2 + y^2}$$

$$\frac{\partial z}{\partial X} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial X} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial X} = \frac{\partial z}{\partial r}$$
?



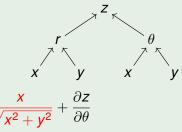
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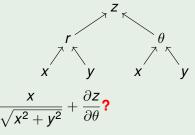
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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

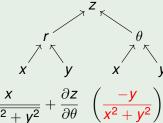
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$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x} \qquad r \qquad \theta$$

$$\theta = \arctan \left(\frac{y}{x}\right)$$

$$r = \sqrt{x^2 + y^2} \qquad x \qquad y \qquad x \qquad y$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial z}{\partial r} \qquad \frac{x}{\sqrt{x^2 + y^2}} + \frac{\partial z}{\partial \theta} \qquad \left(\frac{-y}{x^2 + y^2}\right)$$



Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. Suppose $\theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Recall that

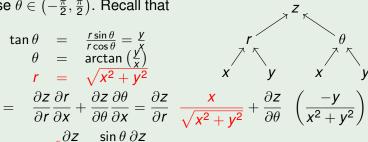
$$\tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x}$$

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$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial z}{\partial r}$$

$$= \cos \theta \frac{\partial z}{\partial r} - \frac{\sin \theta}{r} \frac{\partial z}{\partial \theta}$$



Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

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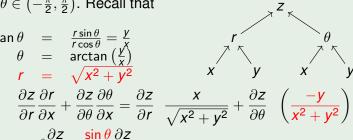
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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$.

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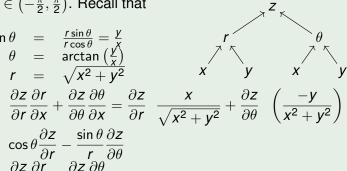
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$$= \cos \theta \frac{\partial z}{\partial r} - \frac{\sin \theta}{r} \frac{\partial z}{\partial \theta}$$

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Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. Suppose $\theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Recall that

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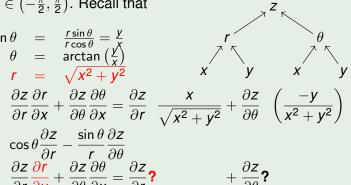
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$$= \cos \theta \frac{\partial z}{\partial r} - \frac{\sin \theta}{r} \frac{\partial z}{\partial \theta}$$

$$= \frac{\partial z}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial z}{\partial r}?$$



Express $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ via $\frac{\partial}{\partial r}$ and $\frac{\partial}{\partial \theta}$, where $x = r \cos \theta$, $y = r \sin \theta$. Suppose $\theta \in (-\frac{\pi}{2}, \frac{\pi}{2})$. Recall that

$$tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{y}{x} \qquad r$$

$$\theta = \arctan\left(\frac{y}{x}\right)$$

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$$= \frac{\partial z}{\partial y} = \frac{\partial z}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial z}{\partial \theta} \frac{\partial \theta}{\partial x} = \frac{\partial z}{\partial r} \qquad \frac{y}{\sqrt{x^2 + y^2}} + \frac{\partial z}{\partial \theta}?$$

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?

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$$= \cos \theta \frac{\partial z}{\partial r} - \frac{\sin \theta}{r} \frac{\partial z}{\partial \theta}$$

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The above hold for all z,

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The above hold for all z, therefore

$$\begin{array}{rcl} \frac{\partial}{\partial x} & = & \cos\theta \frac{\partial}{\partial r} - \frac{1}{r}\sin\theta \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial v} & = & \sin\theta \frac{\partial}{\partial r} + \frac{1}{r}\cos\theta \frac{\partial}{\partial \theta} \end{array}$$

The Laplace Operator

Definition

The *n*-variable Laplace operator is the differential operator:

$$\Delta = \sum_{j=1}^{n} \frac{\partial^{2}}{\partial x_{j}^{2}} = \frac{\partial^{2}}{\partial x_{1}^{2}} + \dots + \frac{\partial^{2}}{\partial x_{n}^{2}} .$$

In paticular the two-variable Laplace operator is:

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

The Laplace operator is named after Pierre Laplace (1749-1827).

Example

Express the Laplace operator $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$ in polar coordinates.

$$\Delta = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} .$$

Harmonic Functions

Recall that
$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

Definition (Harmonic function definition)

Functions f such that $\Delta f = 0$ are called *harmonic* functions.

Example

The function $f(x, y) = \ln(x^2 + y^2)$ is a harmonic function.

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The function $f(x,y) = \ln(x^2 + y^2)$ is a harmonic function. Rewrite in polar coordinates: $f(x,y) = g(r,\theta) = \ln(r^2) = 2 \ln r$. Then

$$\Delta g = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial g}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 g}{\partial \theta^2} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial (2 \ln r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 (2 \ln r)}{\partial \theta^2}$$

$$= \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \frac{2}{r} \right) = \frac{1}{r} \frac{\partial}{\partial r} (2) = 0 .$$

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<u>Fact</u>: The only harmonic functions independent of θ are of the form $g(r,\theta) = c_1 \ln r + c_2$.