

Calculus III

Lecture 17

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<https://github.com/tmilev/freecalc>

2020

Outline

- 1 Line integrals
 - Line Integral from Vector Field
 - Differential 1-forms

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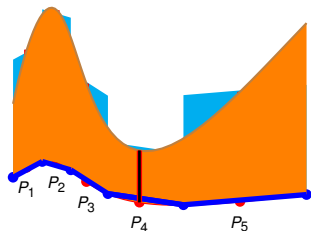
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Overview of Integrals Covered so Far

- We have so far studied integrals over:
 - intervals on a line;
 - planar regions in the plane;
 - solid regions in space.
- All studied integrals were over regions that have the same dimension as their ambient space.
- Can we make sense of an integral over region that has lower dimension than the ambient space?
- We can for arbitrary k -dimensional surface in n dimensional space. We will only consider the examples of
 - a curve (1D region) embedded in a plane (2D)
 - a curve (1D region) embedded in space (3D)
 - a surface (2D region) embedded in space (3D).

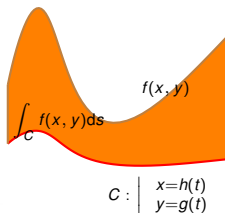
Riemann Sums for Line Integrals



- Let C be a piecewise smooth curve (endpoints included) in space.
- Let f be a scalar or vector-valued function defined on C .
- We aim to define the integral of f on C with respect to arclength.
- Divide C into pieces D_1, \dots, D_N with non-overlapping interiors;
- Pick a sample point P_k in each D_k .
- The accumulation on D_k is approximated by $f(P_k) \cdot \text{length}(D_k)$.
- The integral (total accum.): approximated by the Riemann sum

$$\sum_{k=1}^N f(P_k) \cdot \text{length}(D_k)$$

Definition of Line Integral



Definition

Suppose the limit

$$\lim_{\max_k (\text{segment length}) \rightarrow 0} \sum_{k=1}^N f(P_k) \cdot \text{length}(D_k)$$

exists and is finite. Then we call this limit the *line integral of f on C with respect to arclength*, and we denote it by

$$\int_C f(x, y) ds .$$

The line integral is guaranteed to exist if f is a continuous function or is bounded and continuous except at a finite number of points.

Parametrizations and Computations

Let $\mathbf{r}: [a, b] \rightarrow C$ be a regular, piecewise smooth parametrization of C . Then $\int_C f(x, y) ds$ is computed as follows.

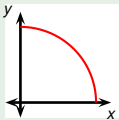
$$\begin{aligned} ds &= |\mathbf{r}'(t)| dt \\ \int_{(x,y) \in C} f(x, y) ds &= \int_a^b f(\mathbf{r}(t)) |\mathbf{r}'(t)| dt. \end{aligned}$$

The result is independent of the parametrization of C we use.

$$\mathbf{r}: [a, b] \rightarrow \mathbb{R}^2, \quad \mathbf{r}(t) = (x(t), y(t))$$

$$\begin{aligned} ds &= |\mathbf{r}'(t)| dt = \sqrt{(x'(t))^2 + (y'(t))^2} dt \\ \int_C f(x, y) ds &= \int_a^b f(x(t), y(t)) \sqrt{(x'(t))^2 + (y'(t))^2} dt. \end{aligned}$$

Example



Compute $\int_C x^2 y ds$, where C is the first quadrant part of the circle of radius 2 centered at origin and ds is the arclength form.

A parametrization of C can be given as

$$\mathbf{r}(t) = (x(t), y(t)) = (2 \cos t, 2 \sin t), \quad 0 \leq t \leq \frac{\pi}{2}.$$

$$ds = |\mathbf{r}'(t)| dt = |(-2 \sin t, 2 \cos t)| dt$$

$$= 2 \sqrt{(-\sin t)^2 + (\cos t)^2} dt = 2 dt$$

$$\begin{aligned} \int_C x^2 y ds &= \int_{t=0}^{t=\frac{\pi}{2}} (8 \cos^2 t \sin t) 2 dt \\ &= 16 \left[\frac{-\cos^3 t}{3} \right]_{t=0}^{t=\frac{\pi}{2}} = \frac{16}{3}. \end{aligned}$$

Line Integrals from Vector Fields

- Let C be piecewise smooth, *oriented* curve, parametrized via $\mathbf{r}(t)$.
- Let ds be the element of arclength.
- Let \mathbf{F} be a continuous vector defined on C .
- Let \mathbf{T} be unit tangent vector on C compatible with orientation.
- Let \mathbf{N} be unit vector perpendicular to \mathbf{T} (only for planar curves).

Definition

In any dimension, define the line integral of \mathbf{F} along C as

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \mathbf{F} \cdot \mathbf{T} ds, \text{ where } d\mathbf{r} = \mathbf{T} ds.$$

In dimension 2, define the line integral of \mathbf{F} across C as

$$\int_C \mathbf{F} \cdot \mathbf{N} ds = \int_C \mathbf{F} \cdot d\mathbf{n}, \text{ where } d\mathbf{n} = \mathbf{N} ds.$$

- Line integral = work done by force \mathbf{F} on particle moving along C .
- Line integral across C = flux across a membrane: $\mathbf{F} \cdot \mathbf{N}$ is the normal component of \mathbf{F} .

Line Integral Computations

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \mathbf{F} \cdot \mathbf{T} ds$$

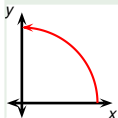
$\mathbf{r}: [a, b] \rightarrow C$: regular parametrization compatible with the orientation.
Recall that

$$\mathbf{T} = \frac{1}{|\mathbf{r}'(t)|} \mathbf{r}'(t), \quad ds = |\mathbf{r}'(t)| dt \Rightarrow \mathbf{T} ds = \mathbf{r}'(t) dt = d\mathbf{r}.$$

Let \mathbf{F} be given by $\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$. Then we can compute the line integral as follows.

$$\begin{aligned} \mathbf{r}'(t) &= (x'(t), y'(t)) = x'(t)\mathbf{i} + y'(t)\mathbf{j} \\ \mathbf{F} \cdot d\mathbf{r} &= \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = (P(x(t), y(t))x'(t) + Q(x(t), y(t))y'(t)) dt \\ \int_C \mathbf{F} \cdot d\mathbf{r} &= \int_{t=a}^{t=b} (P(x(t), y(t))x'(t) + Q(x(t), y(t))y'(t)) dt \end{aligned}$$

Example



Find the work done by the force $\mathbf{F} = (x, -y) = x\mathbf{i} - y\mathbf{j}$ on a particle moving from $(1, 0)$ to $(0, 1)$ along the quarter of the unit circle contained in the first quadrant.

A parametrization of C compatible with the given orientation is $\mathbf{r}(t) = (\cos t, \sin t) = (\cos t)\mathbf{i} + (\sin t)\mathbf{j}$, $t \in [0, \frac{\pi}{2}]$.

$$\begin{aligned}
 \mathbf{F} &= (\cos t)\mathbf{i} - (\sin t)\mathbf{j} \\
 \mathbf{r}'(t) &= -(\sin t)\mathbf{i} + (\cos t)\mathbf{j} \\
 \mathbf{F} \cdot \mathbf{r}'(t) &= -2 \sin t \cos t \\
 W &= \int_C \mathbf{F} \cdot d\mathbf{r} = \int_{t=0}^{t=\frac{\pi}{2}} \mathbf{F} \cdot \mathbf{r}'(t) dt \\
 &= \int_{t=0}^{t=\frac{\pi}{2}} -2 \sin t \cos t dt = \left[\cos^2 t \right]_{t=0}^{t=\frac{\pi}{2}} = -1.
 \end{aligned}$$

What if the parametrization is **not** compatible with the orientation?

Differential 1-Forms

Consider the expression $\mathbf{F} \cdot d\mathbf{r}$. Since $\mathbf{r} = x \mathbf{i} + y \mathbf{j}$, we have $d\mathbf{r} = dx \mathbf{i} + dy \mathbf{j}$. If $\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$, then

$$\mathbf{F} \cdot d\mathbf{r} = P(x, y)dx + Q(x, y)dy.$$

Definition (Differential 1-form)

An expression of the type

$\omega = P(x) dx$	(in 1D)
$\omega = P(x, y) dx + Q(x, y) dy$	(in 2D)
$\omega = P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$	(in 3D)

is called a *1-form*.

- $\int_C \mathbf{F} \cdot d\mathbf{r}$ is the integral of a 1-form over the oriented curve C .
- The definite integral $\int_a^b P(x) dx$ actually means
 - the integral of the 1-form $\omega = P(x) dx$
 - on the segment with endpoints a and b
 - oriented from a to b .

Integrals of 1-Forms

Let $\omega = P(x, y) dx + Q(x, y) dy$ be a 1-form, let C be an oriented curve. Let $\mathbf{r}: [a, b] \rightarrow C$, $\mathbf{r}(t) = (x(t), y(t))$ be an orientation-compatible parametrization. Consider

$$\int_C \omega = \int_C P(x, y) dx + Q(x, y) dy \quad .$$

We compute this integral as follows.

$$dx = x'(t) dt$$

$$dy = y'(t) dt$$

$$\begin{aligned} P(x, y) dx + Q(x, y) dy &= (P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t)) dt \\ \int_C P(x, y) dx + Q(x, y) dy &= \int_a^b (P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t)) dt \end{aligned}$$

If we **re-parametrize the curve**, the substitution rule and the multivariable chain rule imply that the integral doesn't change.

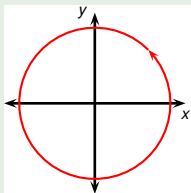
The Notation \oint : Closed Path Integrals

- Suppose that the curve image C , parametrized by $\mathbf{r}(t) : (x(t), y(t)), t \in [a, b]$ is a closed curve.
- That is, the **start point** and the **end point** coincide.
- In other words $(x(a), y(a)) = (x(b), y(b))$.
- Let ω be a 1-form.
- Then we sometimes use the notation

$$\oint_C \omega = \int_C \omega.$$

- The circle around the first integral simply indicates the path is closed.
- The notation is mostly useful when we are integrating an closed 1-form. (Definition of closed form is/will be studied separately).

Example



Let C be a circle of radius R centered at the origin, oriented counterclockwise. Compute the integral

$$\oint_C -\frac{y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy$$

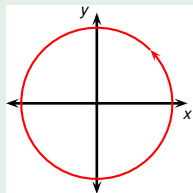
Parametrize: C :

$$\begin{aligned} x &= R \cos t \\ y &= R \sin t \\ dx &= (-R \sin t) dt \\ dy &= (R \cos t) dt \end{aligned} \quad , \quad 0 \leq t \leq 2\pi.$$

$$\begin{aligned} -\frac{y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy &= -\frac{R \sin t (-R \sin t dt)}{R^2} + \frac{R \cos t (R \cos t dt)}{R^2} \\ &= (\cos^2 t + \sin^2 t) dt = dt \end{aligned}$$

$$\oint_C -\frac{y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy = \int_0^{2\pi} dt = [t]_0^{2\pi} = 2\pi.$$

Example



Let C be a circle of radius R centered at the origin, oriented counterclockwise. Compute the integral

$$\oint_C \frac{x}{x^2 + y^2} dx + \frac{y}{x^2 + y^2} dy$$

Parametrize: C :

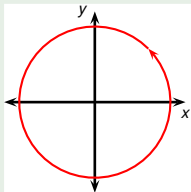
$$\begin{cases} x = R \cos t \\ y = R \sin t \\ dx = (-R \sin t) dt \\ dy = (R \cos t) dt \end{cases}, 0 \leq t \leq 2\pi.$$

$$\begin{aligned} \frac{x}{x^2 + y^2} dx + \frac{y}{x^2 + y^2} dy &= \frac{R \cos t (-R \sin t dt)}{R^2} + \frac{R \sin t (R \cos t dt)}{R^2} \\ &= 0 \end{aligned}$$

$$\oint_C \frac{x}{x^2 + y^2} dx - \frac{y}{x^2 + y^2} dx = 0.$$

1-Forms in Polar Coordinates

Example



Let C be a circle of radius R centered at the origin, oriented counterclockwise. Compute the integral

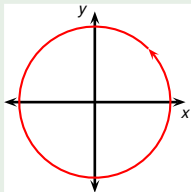
$$\oint_C -\frac{y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy$$

In polar coord.: $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \Rightarrow \begin{cases} dx = \cos \theta dr - r \sin \theta d\theta \\ dy = \sin \theta dr + r \cos \theta d\theta \end{cases}$

$$\begin{aligned} -\frac{y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy &= -\frac{r \sin \theta}{r^2} (\cos \theta dr - r \sin \theta d\theta) \\ &\quad + \frac{r \cos \theta}{r^2} (\sin \theta dr + r \cos \theta d\theta) \\ &= (\cos^2 \theta + \sin^2 \theta) d\theta \\ &= d\theta \end{aligned}$$

1-Forms in Polar Coordinates

Example



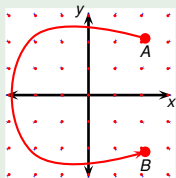
Let C be a circle of radius R centered at the origin, oriented counterclockwise. Compute the integral

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In polar coord.: $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \Rightarrow \begin{cases} dx = \cos \theta dr - r \sin \theta d\theta \\ dy = \sin \theta dr + r \cos \theta d\theta \end{cases}$

$$\begin{aligned} \frac{x}{x^2 + y^2} dx + \frac{y}{x^2 + y^2} dy &= \frac{r \cos \theta}{r^2} (\cos \theta dr - r \sin \theta d\theta) \\ &\quad + \frac{r \sin \theta}{r^2} (\sin \theta dr + r \cos \theta d\theta) \\ &= \frac{1}{r} (\cos^2 \theta + \sin^2 \theta) dr \\ &= \frac{1}{r} dr = d(\ln r) \end{aligned}$$

Example (Work Done by Point Mass Gravity Field)



Let \mathbf{F} be the vector field

$$\mathbf{F}(\mathbf{v}) = -\frac{1}{|\mathbf{v}|^3} \mathbf{v} ,$$

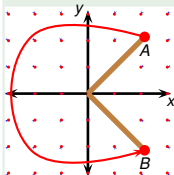
Let C be a smooth curve with endpoints A and B .

What is the work W done by the field \mathbf{F} on a particle moving from A to B along C ?

Let $\mathbf{r}: [a, b] \rightarrow C$ be a parametrization of C with $A = \mathbf{r}(a)$ and $B = \mathbf{r}(b)$.

$$W = \int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_a^b \left(-\frac{1}{|\mathbf{r}(t)|^3} \mathbf{r}(t) \cdot \mathbf{r}'(t) \right) dt .$$

Example (Work Done by Point Mass Gravity Field)



Let \mathbf{F} be the vector field

$$\mathbf{F}(\mathbf{v}) = -\frac{1}{|\mathbf{v}|^3} \mathbf{v},$$

Let C be a smooth curve with endpoints A and B .

What is the work W done by the field \mathbf{F} on a particle moving from A to B along C ?

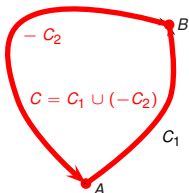
$$\mathbf{r}(t) \cdot \mathbf{r}'(t) = \frac{1}{2} \frac{d}{dt} (\mathbf{r}(t) \cdot \mathbf{r}(t)) = \frac{1}{2} \frac{d}{dt} |\mathbf{r}(t)|^2.$$

$$\text{Set } u = |\mathbf{r}(t)|^2 \Rightarrow \frac{1}{2} du = \mathbf{r}(t) \cdot \mathbf{r}'(t) dt.$$

$$\begin{aligned} W &= \int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_a^b \left(-\frac{1}{|\mathbf{r}(t)|^3} \mathbf{r}(t) \cdot \mathbf{r}'(t) \right) dt \\ &= \int_{u=|\mathbf{r}(a)|^2}^{u=|\mathbf{r}(b)|^2} \left(-\frac{1}{u^{\frac{3}{2}}} \right) \frac{1}{2} du = \left[u^{-\frac{1}{2}} \right]_{u=|\mathbf{r}(a)|^2}^{u=|\mathbf{r}(b)|^2} = \frac{1}{|\mathbf{r}(b)|} - \frac{1}{|\mathbf{r}(a)|} \end{aligned}$$

In this example, we established that the line integral depends only on the endpoints A and B but not on the connecting path.

Conservative Fields



Definition

A vector field \mathbf{F} is called *conservative* if for any two points A and B and any two paths C_1 and C_2 from A to B we have $\int_{C_1} \mathbf{F} \cdot d\mathbf{r} = \int_{C_2} \mathbf{F} \cdot d\mathbf{r}$.

Lemma (alternative definition)

A vector field \mathbf{F} is conservative if and only if every point A every path C starting and ending at A we have $\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$.

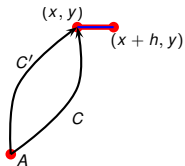
Proof.

The path $C = C_1 \cup (-C_2)$ starts and ends at A and therefore

$$0 = \oint_C \mathbf{F} \cdot d\mathbf{r} = \int_{C_1} \mathbf{F} \cdot d\mathbf{r} - \int_{C_2} \mathbf{F} \cdot d\mathbf{r} \Leftrightarrow \int_{C_1} \mathbf{F} \cdot d\mathbf{r} = \int_{C_2} \mathbf{F} \cdot d\mathbf{r}.$$



Conservative Field \Rightarrow Gradient Field



Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$ be a smooth conservative field. Fix pt. A inside the domain of \mathbf{F} . Define f by $f(B) = \int_C \mathbf{F} \cdot d\mathbf{r}$, where C is any piecewise smooth curve from A to B .

Theorem

$$\mathbf{F} = \nabla f.$$

Proof.

Let $h > 0$; for h small, the segment S from (x, y) to $(x+h, y)$ is in the domain of \mathbf{F} . S is given by $\mathbf{r}(t) = (x+t)\mathbf{i} + y\mathbf{j}$, $t \in [0, h]$. On S , $d\mathbf{r} = \mathbf{i}dt$.

$$\begin{aligned} \frac{\partial}{\partial x}(f) &= \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \left(\int_{C+S} \mathbf{F} \cdot d\mathbf{r} - \int_C \mathbf{F} \cdot d\mathbf{r} \right) \\ &= \lim_{h \rightarrow 0} \frac{1}{h} \int_S \mathbf{F} \cdot d\mathbf{r} \\ &= \lim_{h \rightarrow 0} \frac{1}{h} \int_{t=0}^{t=h} (P(x+t, y)\mathbf{i} + Q(x+t, y)\mathbf{j}) \cdot \mathbf{i}dt \\ &= \lim_{h \rightarrow 0} \frac{1}{h} \int_{t=0}^h P(x+t, y)dt = P(x, y), \end{aligned}$$

where the last equality is the single-variable Fundamental Theorem of Calculus. Similarly it follows that $\frac{\partial}{\partial y}(f) = Q(x, y)$. □

Gradient Field \Rightarrow Conservative Field

Theorem (Fundamental Theorem of Calculus for Line Integrals)

$\int_C (\nabla f) \cdot d\mathbf{r} = f(B) - f(A)$, for every smooth curve C from A to B .

Proof.

$$\begin{aligned}\int_C (\nabla f) \cdot d\mathbf{r} &= \int_C f_x dx + f_y dy = \int_C (f_x x'(t) + f_y y'(t)) dt \\ &= \int_a^b \frac{d}{dt} (f(\mathbf{r}(t))) dt = f(B) - f(A).\end{aligned}$$



Definition

If $\mathbf{F} = \nabla f$ then f is called *scalar potential* of \mathbf{F} ; \mathbf{F} is called *gradient field*.

Let $\mathbf{F} = \nabla f$ be gradient field. For a curve C joining points A and B

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (\nabla f) \cdot d\mathbf{r} = f(B) - f(A)$$

depends only on A and B , but not on $C \Rightarrow \mathbf{F}$ is conservative.

A Criterion for Conservative (Gradient) Fields

- Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$ be a smooth conservative (gradient) field.
- Then for some f , $\mathbf{F} = \nabla f$, hence

$$P = f_x, \quad Q = f_y.$$

- Since mixed partial derivatives are equal, it follows that

$$P_y = (f_x)_y = f_{xy} = f_{yx} = (f_y)_x = Q_x.$$

Proposition

If $\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$ is a gradient field, then $P_y = Q_x$.

- A similar consideration in 3 dimensions shows the following.

Proposition

If $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is a gradient field, then

$$P_y = Q_x, \quad P_z = R_x, \quad Q_z = R_y.$$

Simply Connected Regions

If $P_y(x, y) \neq Q_x(x, y)$, then \mathbf{F} is not a gradient field.

If $P_y(x, y) = Q_x(x, y)$, is \mathbf{F} necessarily a gradient field? No:

$$\mathbf{F} = -\frac{y}{x^2 + y^2} \mathbf{i} + \frac{x}{x^2 + y^2} \mathbf{j} = P \mathbf{i} + Q \mathbf{j}$$

$$P_y = \frac{y^2 - x^2}{(x^2 + y^2)^2} = Q_x$$

$$\oint_{C=\text{circ. around } (0,0)} \mathbf{F} \cdot d\mathbf{r} = \oint_C \left(-\frac{y}{x^2 + y^2} dy + \frac{x}{x^2 + y^2} dy \right) = 2\pi \neq 0.$$



simp. conn.



not simp. conn.

Definition

A domain D is called *simply connected* if every closed loop in D can be deformed ("lassoed") to a point inside D .

Theorem

Let $\mathbf{F} = P \mathbf{i} + Q \mathbf{j}$ and $P_y = Q_x$. Suppose \mathbf{F} is defined over a simply connected open set. Then \mathbf{F} is a gradient field.

Example

Show the field $\mathbf{F} = (3 + 2xy)\mathbf{i} + (x^2 - 3y^2)\mathbf{j}$ is gradient and find a scalar potential. Compute $\int_C \mathbf{F} \cdot d\mathbf{r}$, where C is any curve from $(1, 0)$ to $(0, 1)$.

$$P = 3 + 2xy$$

$$Q = x^2 - 3y^2$$

$$P_y = 2x = Q_x$$

\mathbb{R}^2 – simp. conn.
 \Rightarrow potential exists

$$\mathbf{F} = \nabla f = (f_x, f_y)$$

$$f_x = P = 3 + 2xy$$

$$f_y = Q = x^2 - 3y^2$$

$$f = \int P dx = 3x + x^2 y + C(y)$$

$C(y)$ depends on y

$$Q = f_y = x^2 + C'(y)$$

$$C'(y) = -3y^2$$

$$C(y) = \int C'(y) dy = \int (-3y^2) dy = -y^3 + K$$

$$f = 3x + x^2 y - y^3 + K$$

$$\int_C \mathbf{F} \cdot d\mathbf{r} = f(0, 1) - f(1, 0)$$

$$= (-1 + K) - (3 + K) = -4$$

Exact 1-Forms

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$ be a vector field and $\omega = \mathbf{F} \cdot d\mathbf{r} = Pdx + Qdy$ be the corresponding 1-form.

$$\begin{aligned}\mathbf{F} &= \nabla f && \Rightarrow \\ P &= f_x \\ Q &= f_y && \Rightarrow \\ Pdx + Qdy &= f_x dx + f_y dy && \Rightarrow \\ \omega &= df\end{aligned}$$

Definition

1-forms that are (total) differentials of functions are called *exact*.

\mathbf{F} is a gradient field \Rightarrow the 1-form $\omega = \mathbf{F} \cdot d\mathbf{r}$ is exact

Theorem (Net Change Theorem for Line Integrals)

If C is a curve from A and B , then $\int_C df = \int_C (\nabla f) \cdot d\mathbf{r} = f(B) - f(A)$.