Calculus III Lecture 20

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https://github.com/tmilev/freecalc

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Outline

Divergence Theorem

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Theorem (Divergence Theorem)

Let D be a compact set in space with boundary S a piecewise smooth parametrized surface, oriented by the outward normal, and let \mathbf{X} be a smooth vector field on D given by

$$X(x, y, z) = P(x, y, z)i + Q(x, y, z)j + R(x, y, z)k$$
.

Then

$$\iint_{S} \mathbf{X} \cdot d\mathbf{S} = \iiint_{D} \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV$$

Corollary (May serve as alternative definition of div)

$$\begin{aligned} (\operatorname{div} \mathbf{X})(p) &= \lim_{D \to \{p\}} \frac{1}{\operatorname{vol}(D)} \iint_{S} \mathbf{X} \cdot \mathrm{d}\mathbf{S} \\ &= \lim_{D \to \{p\}} \frac{1}{\operatorname{vol}(D)} \iiint_{D} \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) \mathrm{d}V \\ &= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}. \end{aligned}$$

Divergence Theorem

- Let $\mathbf{X} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$.
- Recall our notation

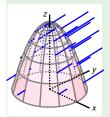
$$\operatorname{div} \mathbf{X} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = (\partial_x, \partial_y, \partial_z) \cdot (P, Q, R)$$
$$\operatorname{div} \mathbf{X} = \nabla \cdot \mathbf{X}.$$

Theorem (Divergence Theorem)

$$\iint_{S} \mathbf{X} \cdot d\mathbf{S} = \iiint_{D} \operatorname{div} \mathbf{X} \, dV$$

- If $(\text{div } \mathbf{X})(p) > 0$, then p acts as a source;
- If $(\text{div } \mathbf{X})(p) < 0$, then p acts as a sink;
- If div $X \equiv 0$ on some domain D, then X is incompressible on D.

Example



Let S be the part of the paraboloid $z=4-x^2-y^2$ above the xy-plane, oriented upward, and $\mathbf{X}=a\mathbf{i}+b\mathbf{j}+c\mathbf{k}$. Use the Divergence Theorem to compute $\iint_S \mathbf{X} \cdot d\mathbf{S}$.

The surface S does not enclose a region in space. However, we add the disk D of radius 2 centered at the origin in the plane z=0 to make it closed. R orients D with the downward normal, hence

The upward normal to D is \mathbf{k} , hence $\mathbf{X} \cdot d\mathbf{S} = \mathbf{X} \cdot \mathbf{k} dS = c dS$. Therefore

$$\iint_{S} \mathbf{X} \cdot d\mathbf{S} = \iint_{D} \mathbf{X} \cdot d\mathbf{S} = \iint_{D} c \, dS = c \cdot \operatorname{area}(D) = 4\pi c.$$

Balloon Pressure Equilibrium

 Let F be the total displacement force due pressure difference between interior and exterior of inflated balloon:

$$\mathbf{F} = \iint_{\mathcal{S}} \mathrm{d}\mathbf{F} = \iint_{\mathcal{S}} \rho \mathbf{N} \, \mathrm{d}\mathcal{S} = \iint_{\mathcal{S}} \rho \, \mathrm{d}\mathbf{S} \; .$$

• For every unit vector **u** we have

$$\mathbf{F} \cdot \mathbf{u} = \left(\iint_{\mathcal{S}} \rho \mathbf{N} \, \mathrm{d} \mathcal{S} \right) \cdot \mathbf{u} = \iint_{\mathcal{S}} \rho \, \mathbf{u} \cdot \mathbf{N} \, \mathrm{d} \mathcal{S} = \iiint_{D} \mathrm{div}(\rho \, \mathbf{u}) \mathrm{d} \mathcal{V} = 0$$

because $div(p\mathbf{u}) = 0$ since the vector field $\mathbf{X} = p\mathbf{u}$ is constant on D.

- Therefore $\mathbf{F} \cdot \mathbf{u} = 0$ for every unit vector \mathbf{u} ;
- Which implies $\mathbf{F} = \mathbf{0}$.

Archemedes' Law from the Divergence Theorem

A solid body is submerged into a tank containing a liquid of constant density ρ . What is the buoyant force?

- Body occupies a region D, exterior boundary S;
- Unit outward normal field N;
- Magnitude of pressure at depth a below the surface is p₀ + ρag, where
 - *g* is the magnitude of the gravitational acceleration.
 - p₀ is the pressure at surface of liquid
- Infinitesimal force acting on S is $d\mathbf{F} = -(p_0 + \rho ag) \mathbf{N} dS$,
- The total force is

$$extbf{\emph{F}} = \iint_{\mathcal{S}} \mathsf{dF} = \iint_{\mathcal{S}} -(p_0 +
ho ag) \, extbf{\emph{N}} \, \mathsf{dS} = \iint_{\mathcal{S}} -
ho ag \, extbf{\emph{N}} \, \mathsf{dS} = \iint_{\mathcal{S}}
ho gz \, extbf{\emph{N}}$$

• EC: Use the Divergence Theorem to show that $\mathbf{F} = \rho V g \mathbf{k}$ (V: volume of the region enclosed by S.)

Curl

Let $\mathbf{X} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ be a smooth vector field.

Definition (Curl, coordinate definition)

The *curl* of a vector field **X**, denoted by **curl X**, is defined by **curl X** = $(\partial_y R - \partial_z Q)$ **i** + $(\partial_z P - \partial_x R)$ **j** + $(\partial_x Q - \partial_y P)$ **k**.

$$\mathbf{curl} \, \mathbf{X} = \left| \begin{array}{ccc} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial_x & \partial_y & \partial_z \\ P & Q & R \end{array} \right| = \nabla \times \mathbf{X} \; .$$

• Just like div, **curl** can be equipped with a coordinate-free definition (in this case the above definition becomes a theorem).

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Induced Orientation on a Boundary Curve

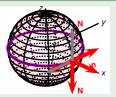
- Let S be smooth surface, oriented by unit normal vector n.
- Let *D* be region in *S*, bounded by a curve $C = \partial D$.
- Let N denote the unit vector field on C which is
 - tangent to S;
 - normal to C;
 - pointing outward of D.
- Let **T** be unit tangent vector to *C* (and hence tangent to *S*).
- Then **N** orients the tangents of *C* and thus *C* itself.

Definition

We say that **T** is *positively oriented* if the triple $\{n, N, T\}$ is positively oriented in space.

- Since T, n, N are pairwise orthogonal unit vectors, positive orientation is equivalent to $T = n \times N$.
- If we view the plane tangent to *S* from the tip of **n**, then {**N**, **T**} is positively oriented in that plane.

Example (Orientation of the equator of a sphere)



Let S be the unit sphere $x^2 + y^2 + z^2 = 1$ oriented by the outward normal \mathbf{n} , $D = S \cap \{z \ge 0\}$ be the upper hemisphere. Introduce an orientation on the boundary $C = \partial D$.

- At the point (1,0,0) the normal to the surface **n** equals **i**.
- Let **T** be a unit tangent to C at (1,0,0); then T = j or -j.
- Let N be unit vector perpendicular to n and T, pointing outwards from D ⇒ N equals -k.
- \Rightarrow positively oriented tangent to C is $\mathbf{T} = \mathbf{n} \times \mathbf{N} = \mathbf{i} \times (-\mathbf{k}) = \mathbf{j}$.
- A viewer, standing along n with feet on surface, and facing in the direction of the tangent, has the surface to the left.
- Change *D* to be lower hemisphere: we get N = k, $T = n \times N = -j$.
- A viewer, standing along n with feet on surface, facing in the direction of the tangent, has the surface again to the left.

- Let S be a smooth surface, oriented by the unit normal field n.
- Let D be a region on S, bounded by the piecewise smooth curve $C = \partial D$.
- Let C have unit tangent T positively oriented by n.
- Let X = Pi + Qj + Rk be a smooth vector field defined in a open set around S.
- Recall that $\operatorname{curl} X = (R_y Q_z) \mathbf{i} + (P_z R_x) \mathbf{j} + (Q_x P_y) \mathbf{k}$.
- Recall that $\mathbf{X} \cdot d\mathbf{r} = \mathbf{T} ds$ and $d\mathbf{S} = \mathbf{n} dS$.

Theorem (Stokes)

$$\oint_C \mathbf{X} \cdot d\mathbf{r} = \iint_D \mathbf{curl} \, \mathbf{X} \cdot d\mathbf{S}$$

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$$\oint_C \mathbf{X} \cdot d\mathbf{r} = \iint_D \mathbf{curl} \, \mathbf{X} \cdot d\mathbf{S} \quad .$$

Idea of proof:

- Use a parametrization of *S* to get integrals in the parameter plane.
- Apply Green's Theorem in the parameter plane.

We can use Stokes' theorem to:

- Evaluate line integrals by computing a surface integral, or
- Evaluate a surface integral by computing a line integral.

Example

Vector Potential

Given a smooth vector field X, one can ask:

- Is X the curl of a vector field?
- Any field G such that X = curl G is called a vector potential for X.
- If $\mathbf{X} = \nabla \times \mathbf{G}$ is a curl field, then div $\mathbf{X} = 0$.
- Two vector potentials differ by a gradient field.

Surface *D* the part of the paraboloid $z = 4 - x^2 - y^2$ above the xy-plane, oriented upward, $\mathbf{X} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$

$$\iint_D \mathbf{X} \cdot d\mathbf{S}$$

div $\mathbf{X} = \mathbf{0}$, hence \mathbf{X} may be the curl of a vector field $\mathbf{G} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$.

$$Q_x-P_y=c, \qquad P_z-R_x=b, \qquad R_y-Q_z=a\,.$$

One solution is Q = cx, P = bz, R = ay, hence $\mathbf{G} = bz\mathbf{i} + cx\mathbf{j} + ay\mathbf{k}$ is a vector potential for \mathbf{X} . Then $\mathbf{X} = \mathbf{curl}\,\mathbf{G}$ and therefore

$$\iint_{D} \mathbf{X} \cdot \mathrm{d}\mathbf{S} = \iint_{D} \mathbf{curl} \, \mathbf{G} \cdot \mathrm{d}\mathbf{S} = \oint_{C} \mathbf{G} \cdot \mathbf{dr} = \oint_{C} bz \, dx + cx \, dy + ay \, dz \; ,$$

where $C = \partial D$, the circle of radius 2 centered at the origin, oriented counterclockwise; $x = 2 \cos t$, $y = 2 \sin t$, z = 0, with $0 \le t \le 2\pi$ is an orientation-compatible parametrization of C

$$\oint_C \mathbf{G} \cdot \mathbf{dr} = \int_0^{2\pi} 2c \cos t \, (2 \cos t) \, dt = 4c \int_0^{2\pi} \cos^2 t \, dt = 4\pi \, c \, .$$

Div, Curl, Grad

$$\mathsf{div}(\boldsymbol{\mathsf{curl}}\,\boldsymbol{X}) = \nabla \cdot (\nabla \times \boldsymbol{X}) = 0$$
 .

B: ball centered at p, with boundary a sphere S centered at p.

$$\begin{split} &\iiint_{B} \operatorname{div}(\operatorname{\mathbf{curl}} \mathbf{X}) \, dV = \iint_{S = \partial B} \operatorname{\mathbf{curl}} \mathbf{X} \cdot \mathrm{d}\mathbf{S} = \oint_{\partial S} \mathbf{X} \cdot \mathrm{\mathbf{dr}} = 0 \;, \\ &\operatorname{div}(\operatorname{\mathbf{curl}} \mathbf{X})(p) = \lim_{B \to \{p\}} \frac{1}{\operatorname{vol}(B)} \iiint_{B} \operatorname{div}(\operatorname{\mathbf{curl}} \mathbf{X}) \, dV = 0 \;. \end{split}$$

$$\operatorname{curl}(\operatorname{grad} f) = \nabla \times (\nabla f) = \mathbf{0}$$
.

D: disk centered at p, in the plane normal to \mathbf{n} at p, and $C = \partial D$

$$\iint_{D} \mathbf{curl} \left(\mathbf{grad} f \right) \cdot \mathbf{n} \, dS = \iint_{D} \mathbf{curl} \left(\mathbf{grad} f \right) \cdot d\mathbf{S} = \oint_{C} \mathbf{grad} f \cdot d\mathbf{r} = 0 ,$$

$$\operatorname{curl} (\operatorname{grad} f)(p) \cdot \mathbf{n} = \lim_{D \to \{p\}} \frac{1}{\operatorname{area}(D)} \iint_D \operatorname{curl} (\operatorname{grad} f) \cdot \mathbf{n} \, \mathrm{d} S = 0$$
;

since this is valid for all unit vectors n we conclude that