## Tail Bounds

## 1 Markov/Chebyshev Bounds

### 1.1 Markov's Inequality

Recall Markov's Inequality: if X is a non-negative random variable, then

$$\Pr[X \ge t] \le \frac{\mathbb{E}[X]}{t}.$$

We'll use this to prove Adelman's Theorem (again). Choose as before the randomness vectors i.i.d. uniformly. Define the random variable  $X_i$  as the number of inputs in whose row we have not yet picked a 1 after i randomness strings have been chosen. Then  $X_0 \leq 2^n$  (all rows). Since the new string  $r_{i+1}$  has, for each remaining row, probability  $\geq 1/2$  of hitting that row,

$$\mathbb{E}[X_{i+1} \mid X_i] \le \frac{1}{2} X_i.$$

Then by the law of total expectation,

$$\begin{split} \mathbb{E}[X_i] &= \mathbb{E}[\mathbb{E}[X_i \mid X_{i-1}]] \\ &= \dots \\ &\leq 2^{-i}X_0 \\ &< 2^{n-i}. \end{split}$$

For  $i \geq n+1$ ,  $\mathbb{E}[X_i \leq 1/2]$ . Applying Markov's Inequality,

$$\begin{aligned} \Pr[\text{all rows have been hit}] &= 1 - \Pr[\text{at least one row remains}] \\ &= 1 - \Pr[X_i \geq 1] \\ &\geq 1 - \frac{\mathbb{E}[X_i]}{1} \\ &\geq 1 - 2^{n-i} \end{aligned}$$

This value decreases exponentially, and i = n + 1 gives probability  $\geq 1/2$ , which by the Probabilistic Method shows that there is a set of n + 1 randomness strings that cover all inputs.

### 1.2 Chebyshev's Inequality

Stronger tail bounds can be obtained if we know more about our random variable behavior. For a random variable X,

$$Var[X] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$
$$= \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$
$$\sigma_X = \sqrt{Var[X]}.$$

Then Chebyshev's Inequality is as follows: for every random variable X,

$$\Pr[|X - \mathbb{E}[X]| \ge t] \le \frac{Var[X]}{t^2}.$$

This is often useful if X is the sum of pairwise independent random variables, or if Var[X] is easy enough to analyze (and not too large).

Proof. Clearly

$$\Pr[|X - \mathbb{E}[X]| \ge t] = \Pr[(X - \mathbb{E}[X])^2 \ge t^2]$$

Let  $Y = (X - \mathbb{E}[X])^2$ . Then  $Y \ge 0$ . So by Markov's Inequality,

$$\begin{split} \Pr[Y \geq t^2] &\leq \frac{\mathbb{E}[Y]}{t^2} \\ &= \frac{\mathbb{E}[X - \mathbb{E}[X])^2]}{t^2} \\ &= \frac{Var[X]}{t^2}. \end{split}$$

# 2 Finding a Median

### 2.1 Randomized Algorithm

Given a set S, represented as an unsorted array, find a median x such that exactly half of the elements are  $\leq x$ . The standard algorithm uses a divide-and-conquer approach with a randomly chosen pivot to run in linear time. Here, we will use a very different sampling-based algorithm which illustrates that random samples are representative, and uses a typical tail bound-style analysis.

### Algorithm 1 Median-Finding Algorithm

- 1: Sample  $n^{3/4}$  elements from S, pairwise independently and uniformly at random with replacement. Call this set R.
- 2: Sort R in time  $\mathcal{O}(n^{3/4} \log n)$ .
- 3: Let  $\ell = n^{3/4}/2 \sqrt{n}$  and  $h = n^{3/4}/2 + \sqrt{n}$ . Let  $a = R_{(\ell)}$  and  $b = R_{(h)}$  in sorted order of R.
- 4: Compare all elements of S to a and b to determine

$$P = \{x \in S : a \le x \le b\}.$$

- 5: Use this comparison to find the positions of a and b in the sorted set S.
- 6: if n/2 is not between those positions, or  $|P| > 4n^{3/4} + 2$  then
- 7: Start over.
- 8: **else**
- 9: Sort P and determine the median from sorted P and the rank of a.
- 10: **end if**

This algorithm tries to ensure that the median is in P, and P is not too large. Note that the algorithm is always correct, but the runtime varies, so it is a Las Vegas algorithm.

### 2.2 Runtime Analysis

Lines 1, 2, and 9 run in time  $\mathcal{O}(n^{3/4}\log n)=o(n)$ . Lines 3 and 7 take time  $\mathcal{O}(1)$ . Line 4 makes 2n comparisons. So the total runtime is

$$(2n + o(n)) \cdot \#$$
 of restarts.

The # of restarts is a geometric random variable, so the expected number of restarts is the inverse of the success probability.

What could go wrong in one iteration of the algorithm?

- 1. a > median.
- 2. b < median.
- 3. P is too large (a too small and/or b too large).

Cases 1 and 2 are symmetric, so we will analyze cases 1 and 3.

#### 2.2.1 Case 1

Case 1 occurs when we undersample to the left of the median – that is, we had fewer than  $n^{3/4}/2 - \sqrt{n}$  samples to the left of the median. The expected number of samples to the left of the median is  $|R|/2 = n^{3/4}/2$ . This means the number of samples deviated by at least  $\sqrt{n}$  from its expectation.

Let X be the number of samples in R that are  $\leq$  median. Let  $X_i$  be the indicator random variable representing whether sample i is  $\leq$  median. Then  $X = \sum_i X_i$ , and

$$\mathbb{E}[X_i] = \Pr[X_i = 1] = 1/2,$$

so

$$\mathbb{E}[X] = |R|/2 = n^{3/4}/2.$$

Our goal is to bound  $\Pr[|X - n^{3/4}/2| < \sqrt{n}]$ . We'd like to apply Chebyshev, but we need the variance. Here,

$$Var[X] = \sum_{i} Var[X_i] + \sum_{i < j} Cov[X_i, X_j].$$

But all the covariance terms are 0 because of pairwise independence. Because the  $X_i$  are Bernoulli random variables,

$$Var[X] = \sum_{i} Var[X_i]$$

$$= \sum_{i} Pr[X_i = 1] \cdot Pr[X_i = 0]$$

$$= \sum_{i} \frac{1}{4}$$

$$= n^{3/4}/4.$$

Now we can apply Chebyshev:

$$\Pr[|X - n^{3/4}/2| \ge \sqrt{n}] \le \frac{n^{3/4}/4}{\sqrt{n}^2}$$
$$= n^{-1/4}/4.$$

#### 2.2.2 Case 3

We'd like to analyze the case when  $|P| \ge 4n^{3/4}$ , which occurs when a is too small and/or b is too large. For this to happen, we must have oversampled left of  $n/2 - 2n^{3/4}$  and/or oversampled right of  $n/2 + 2n^{3/4}$ . We'll analyze the first case in detail.

Assume we randomly picked more than  $n^{3/4}/2 - \sqrt{n}$  elements left of  $n/2 - 2n^{3/4}$ . Let X be the number of samples in R that are  $\leq n/2 - 2n^{3/4}$ . Then

$$\mathbb{E}[X] = n^{3/4} \cdot (1/2 - 2n^{-1/4})$$
$$= n^{3/4}/2 - 2\sqrt{n}.$$

Note that  $\mathbb{E}[X]$  is lesser than our assumption by  $\sqrt{n}$ . Also,

$$Var[X] = n^{3/4} \cdot (1/2 - 2n^{-1/4})(1/2 + 2n^{-1/4})$$
  
  $\leq n^{3/4}/4.$ 

Applying Chebyshev,

$$\begin{aligned} \Pr[a \text{ too small}] &\leq \Pr[|X - \mathbb{E}[X]| \geq \sqrt{n}] \\ &\leq \frac{n^{3/4}/4}{\sqrt{n^2}} \\ &= n^{-1/4}/4. \end{aligned}$$

#### 2.2.3 Summary

We showed that the failure probabilities for all four cases are  $n^{-1/4}/4$ . Using the union bound, the overall failure probability is at most  $n^{-1/4}$ . So the success probability of any one iteration is at most  $1 - n^{-1/4}$ . Thus, the expected number of restarts is at most

$$\frac{1}{1 - n^{-1/4}} \le 1 + 2n^{-1/4}$$
$$= 1 + o(1).$$

Putting it all together, the total amount of work in expectation is

$$2(1 + o(1))n + o(n) = 2n + o(n).$$

The best known deterministic algorithm takes 3n comparisons, with a lower bound of 2n for all deterministic algorithms.

# 3 Chernoff/Hoeffding Bounds

These are tail bounds that give stronger guarantees on random variables X that can be written as  $\sum_i X_i$  where each  $X_i$  is bounded, and all the  $X_i$  are mutually independent. This applies frequently in computer science-related scenarios. They are similar to a quantitative version of the "Law of Large Numbers": that the mean of enough i.i.d. samples converges to the population mean.

For Chernoff Bounds, assume we have  $X = \sum_i X_i$  with  $X_i$  Bernoulli and  $\Pr[X_i = 1] = p_i$ . Let  $\mu = \mathbb{E}[X] = \sum_i p_i$ .

Theorem 1. [Chernoff].

1. For any  $\delta > 0$ ,

$$\Pr[X > (1+\delta)\mu] < \left(\frac{e^{\delta}}{(1+\delta)^{(1+\delta)}}\right)^{\mu}.$$

2. For any  $0 < \delta < 1$ ,

$$\Pr[X < (1 - \delta)\mu] < (e^{-\delta^2/2})^{\mu}.$$

A special case is when  $p_i = p$ , so X is a sum of i.i.d random variables. Then  $\mu = np$ , so the bounds decrease exponentially in n.

For Hoeffding Bounds, assume we have  $X = \sum_i X_i$  with  $a_i \leq X_i \leq b_i$  for all i deterministically.

**Theorem 2.** [Hoeffding]. From survey on concentration inequalities by Mcdiarmid. For all  $\Delta \geq 0$ ,

$$\Pr[|X - \mathbb{E}[X]| \ge \Delta] \le 2 \exp\left(\frac{-2\Delta^2}{\sum_i (b_i - a_i)^2}\right).$$

The standard tail bounds are for independent random variables. Most have counterparts if the  $X_i$  are negatively correlated. The proof idea is that

$$\exp(\alpha \sum_{i} X_i) = \prod \exp(\alpha X_i),$$

and since the  $\exp(\alpha X_i)$  are independent, the expectation is the product of expectations, so we can apply Markov's Inequality.

The main workflow using these bounds is as follows:

- 1. Decompose random variable into sum of independent Bernoulli's.
- 2. Use linearity of expectation to find the mean.
- 3. Use Chernoff bounds to find concentration.
- 4. Take a union bound over failure cases.
- 5. Choose  $\delta$  big enough based on the result of the union bound.

Next class, we will see examples of this method.