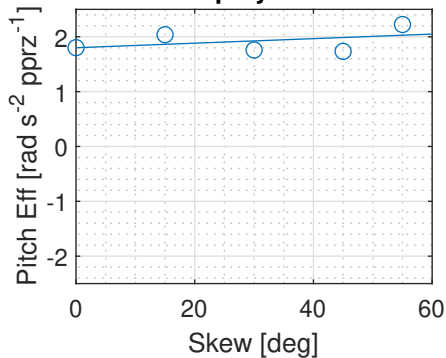


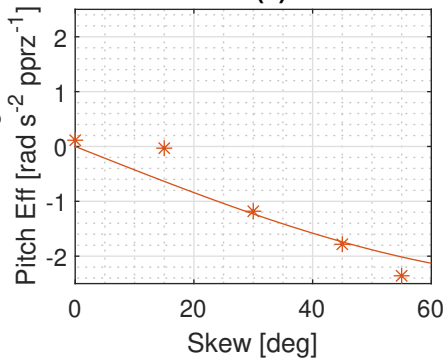
Motor Front 0

poly 1



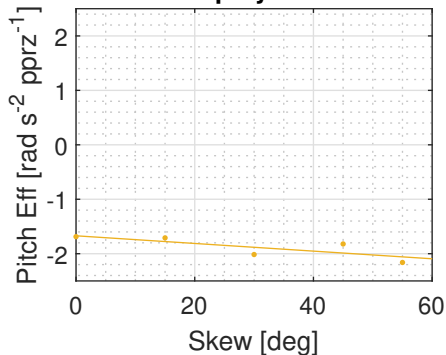
Motor Right 1

sin(x)



Motor Back 2

poly 1



Motor Left 4

sin(x)

