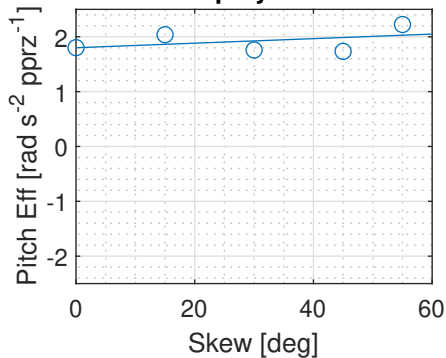


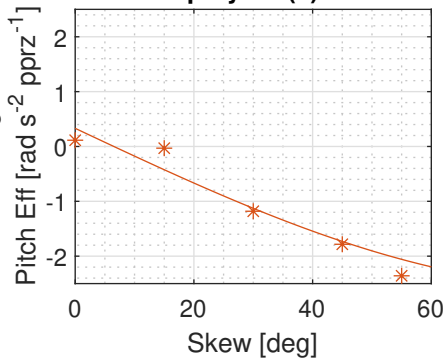
Motor Front 0

poly 1



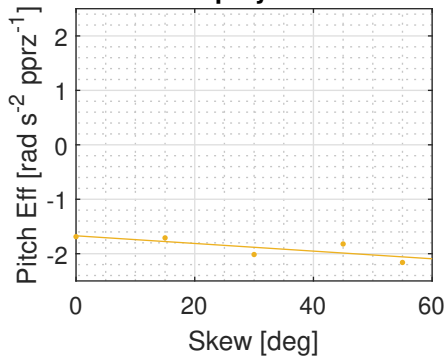
Motor Right 1

poly sin(x)



Motor Back 2

poly 1



Motor Left 4

poly sin(x)

