

# Sieving for shortest vectors in lattices using (angular) locality-sensitive hashing

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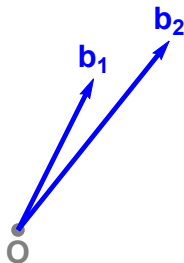
# Lattices

What is a lattice?



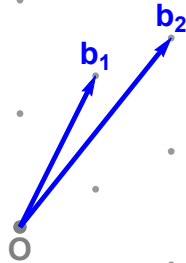
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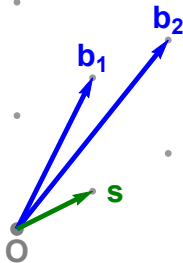
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# Lattices

## Shortest Vector Problem (SVP)



# Lattices

## Exact SVP algorithms

	Algorithm	$\log_2(\text{Time})$	$\log_2(\text{Space})$
Provable SVP	Enumeration [Poh81, Kan83, . . . , GNR10]	$\Omega(n \log n)$	$O(\log n)$
	AKS-sieve [AKS01, NV08, MV10, HPS11]	$3.398n$	$1.985n$
	ListSieve [MV10, MDB14]	$3.199n$	$1.327n$
	AKS-sieve-birthday [PS09, HPS11]	$2.648n$	$1.324n$
	ListSieve-birthday [PS09]	$2.465n$	$1.233n$
	Voronoi cell algorithm [MV10b]	$2.000n$	$1.000n$
	Discrete Gaussian sampling [ADRS15]	$1.000n$	$1.000n$
Heuristic SVP	Nguyen-Vidick sieve [NV08]	$0.415n$	$0.208n$
	GaussSieve [MV10, . . . , IKMT14, BNvdP14]	$0.415n?$	$0.208n$
	Two-level sieve [WLTB11]	$0.384n$	$0.256n$
	Three-level sieve [ZPH13]	$0.3778n$	$0.283n$
	Overlattice sieving [BGJ14]	$0.3774n$	$0.293n$

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	Hyperplane LSH [Laa15]	$0.337n$	$0.208n$

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	Hyperplane LSH [Laa15], [MLB15]	$0.337n$	$0.208n$
	May and Ozerov's NNS method [BGJ15]	$0.311n$	$0.208n$
	Spherical LSH [LdW15]	$0.298n$	$0.208n$
	Cross-polytope LSH [BL15]	$0.298n$	$0.208n$



# Nguyen-Vidick sieve

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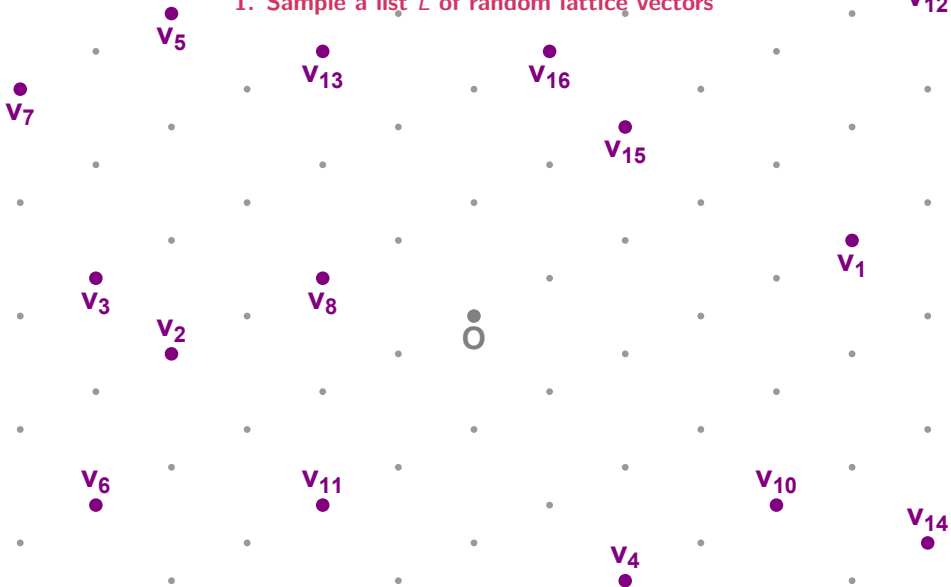
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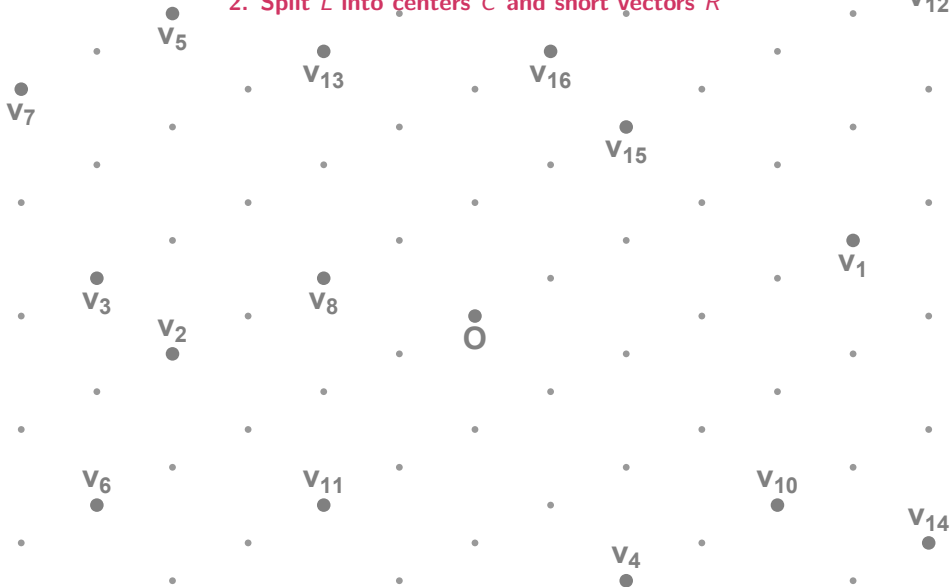
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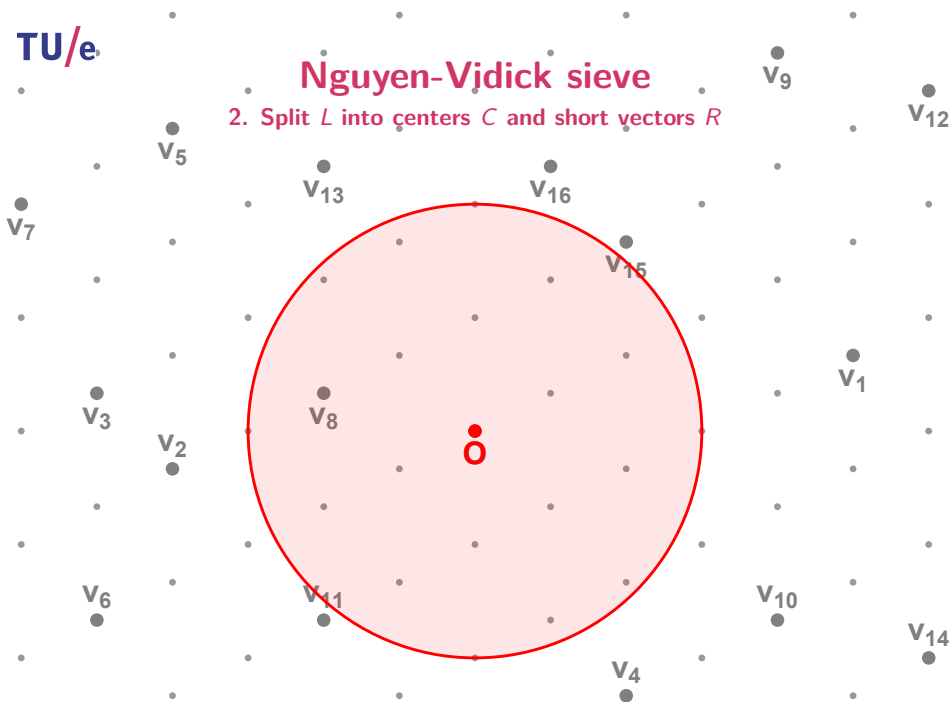
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2. Split  $L$  into centers  $C$  and short vectors  $R$



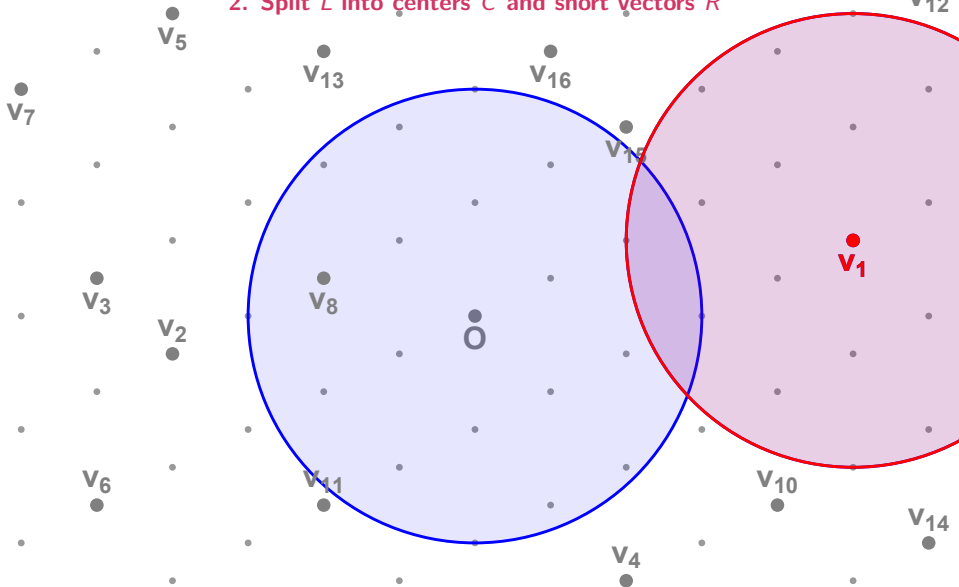
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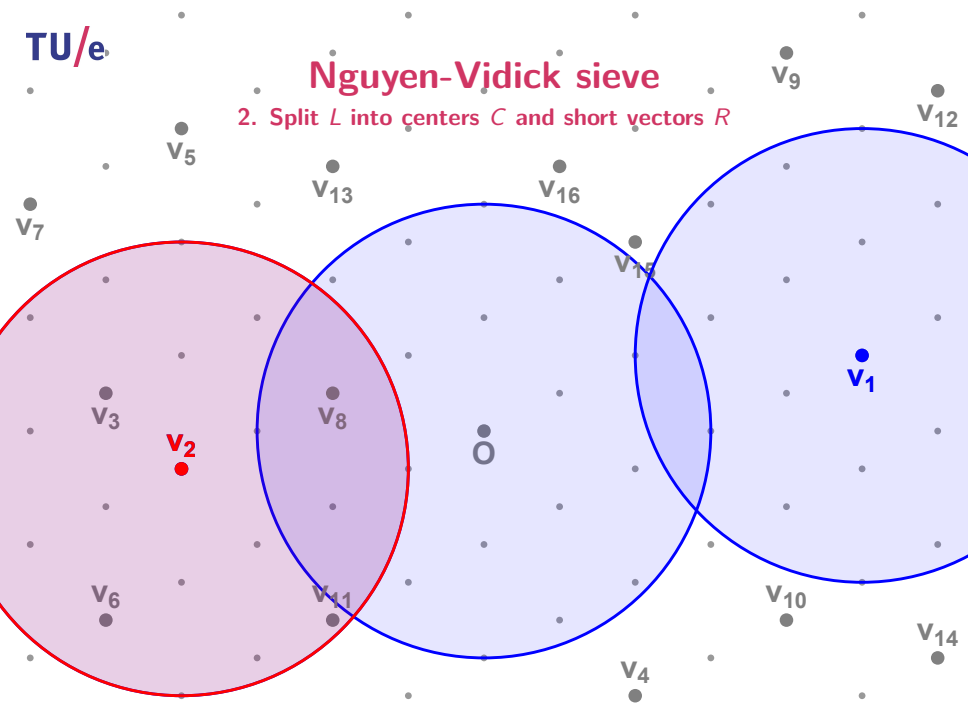
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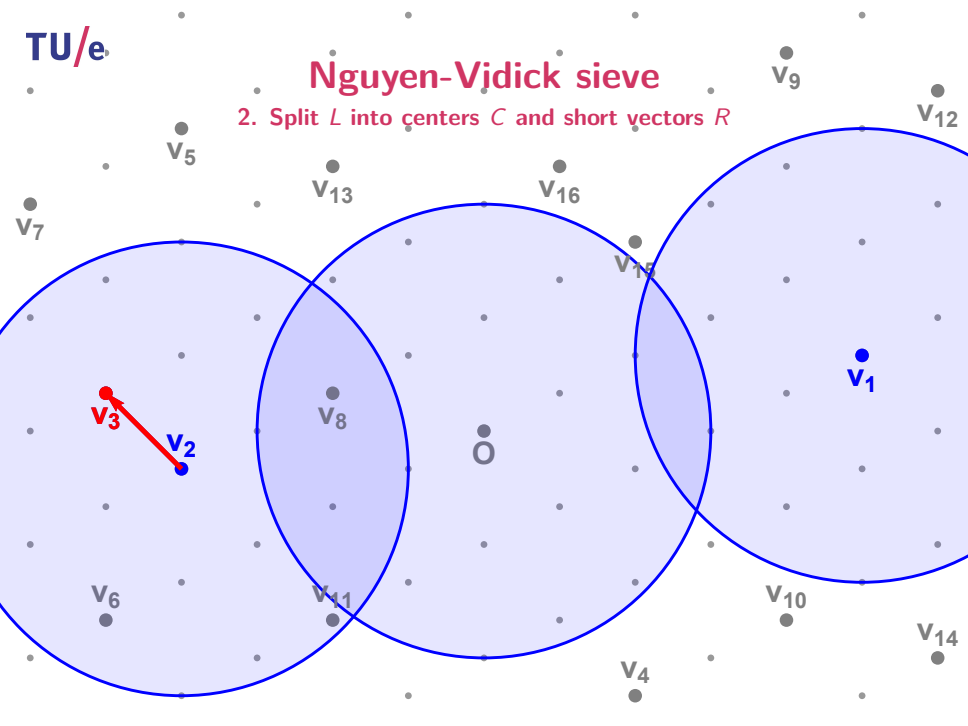
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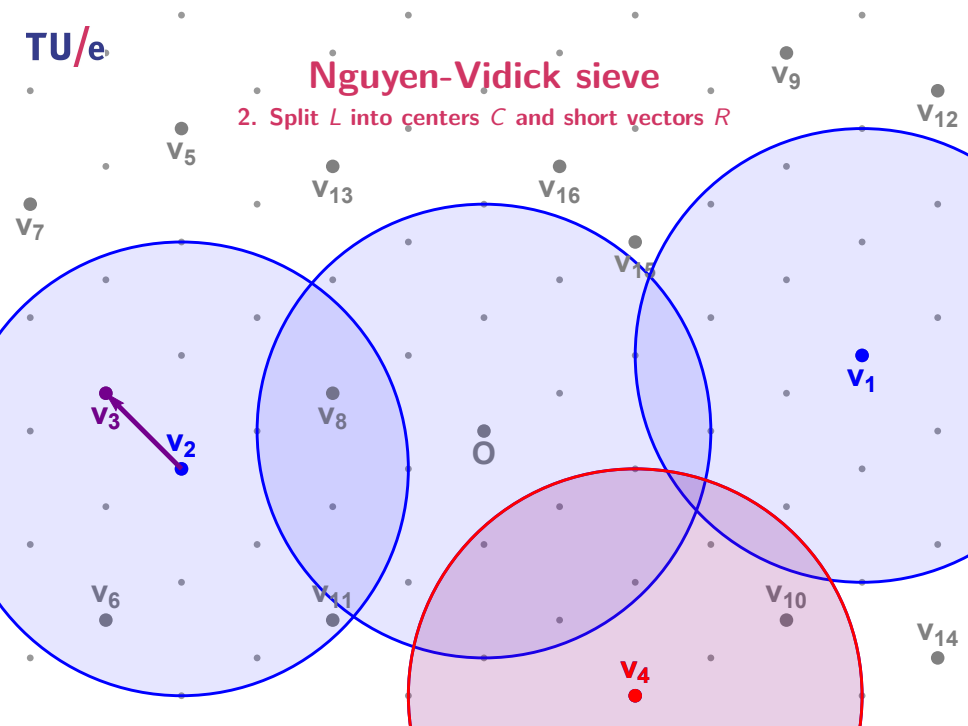
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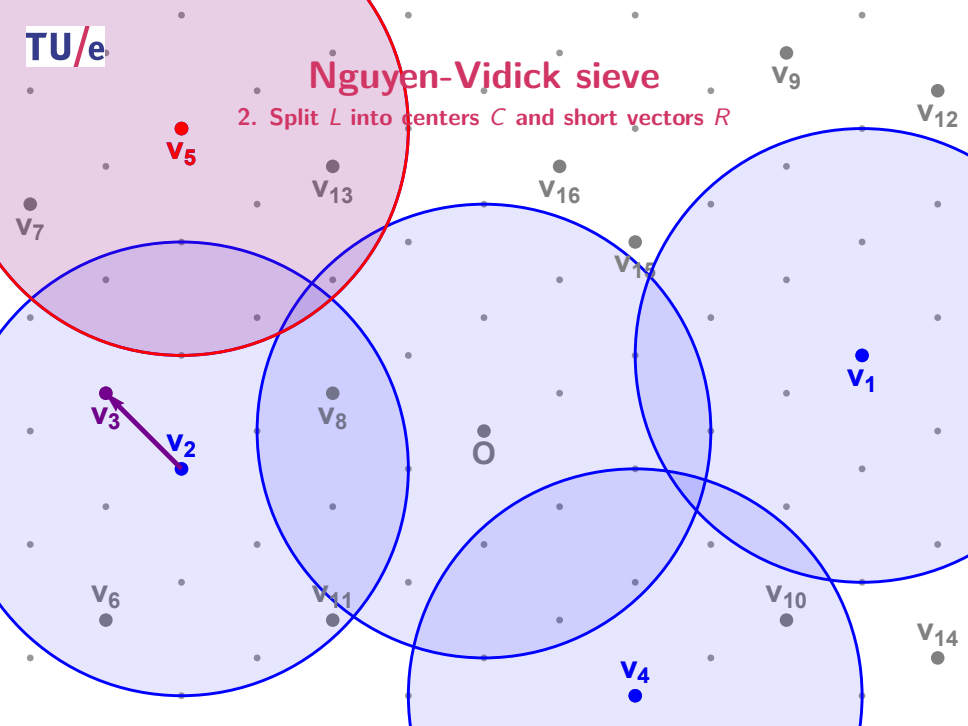
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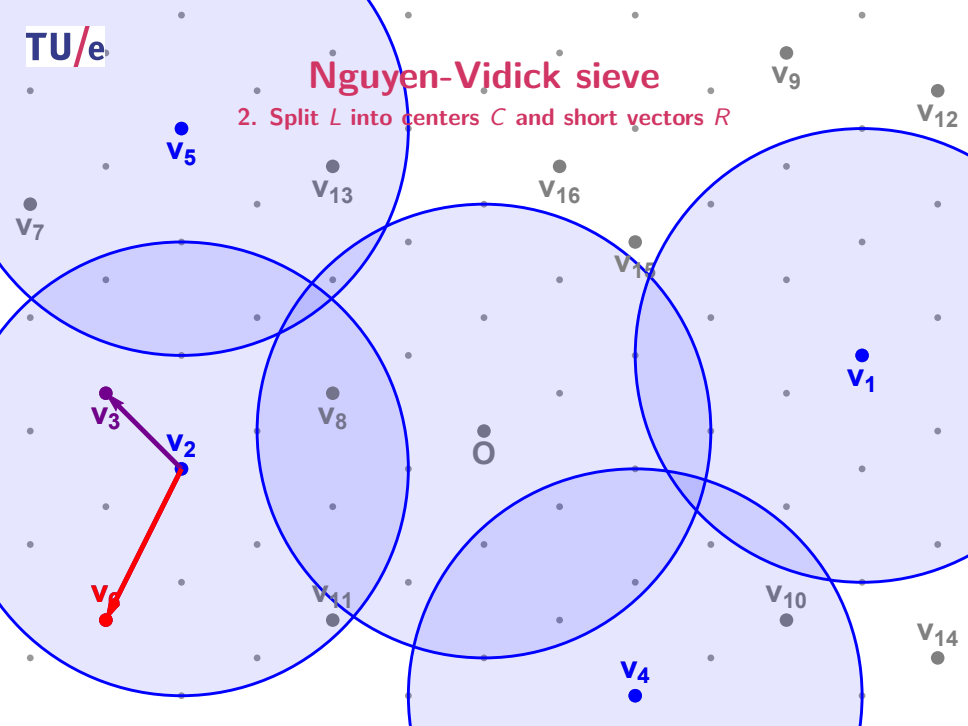
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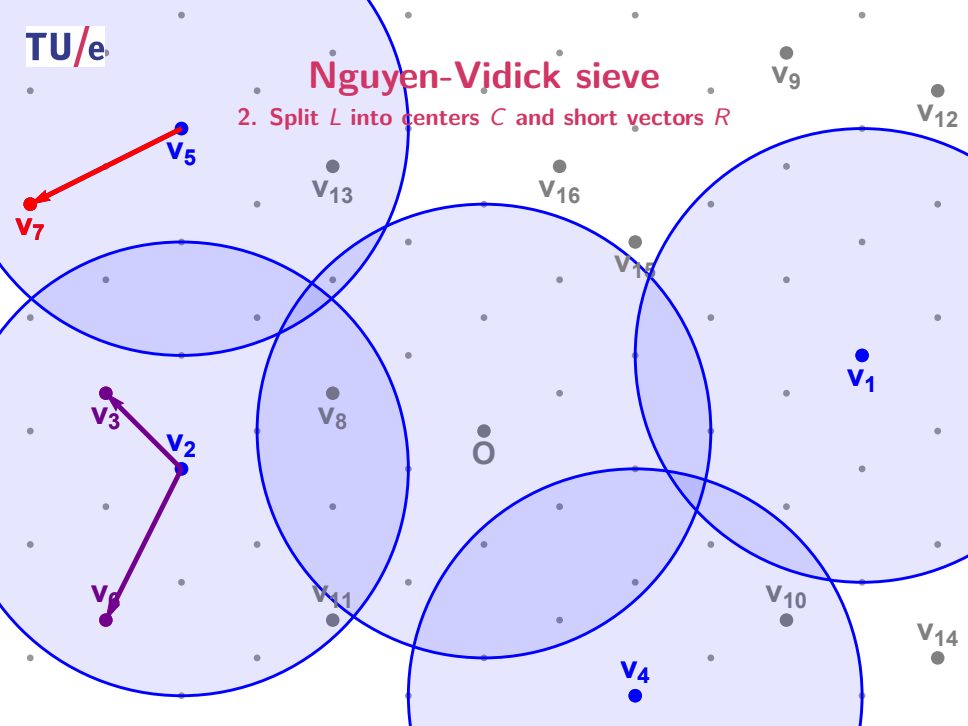
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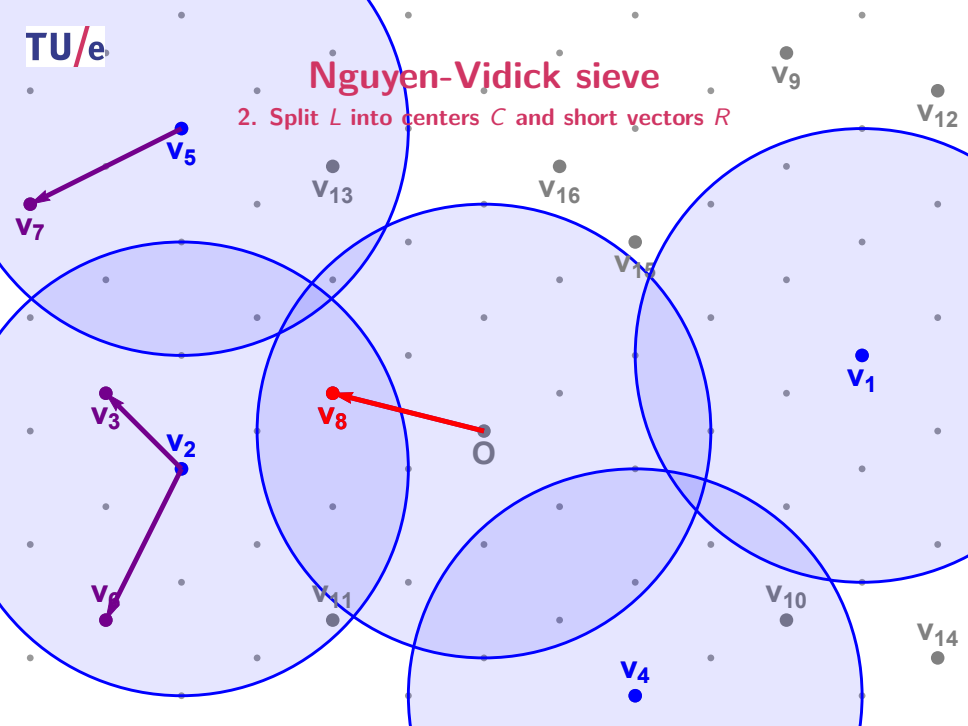
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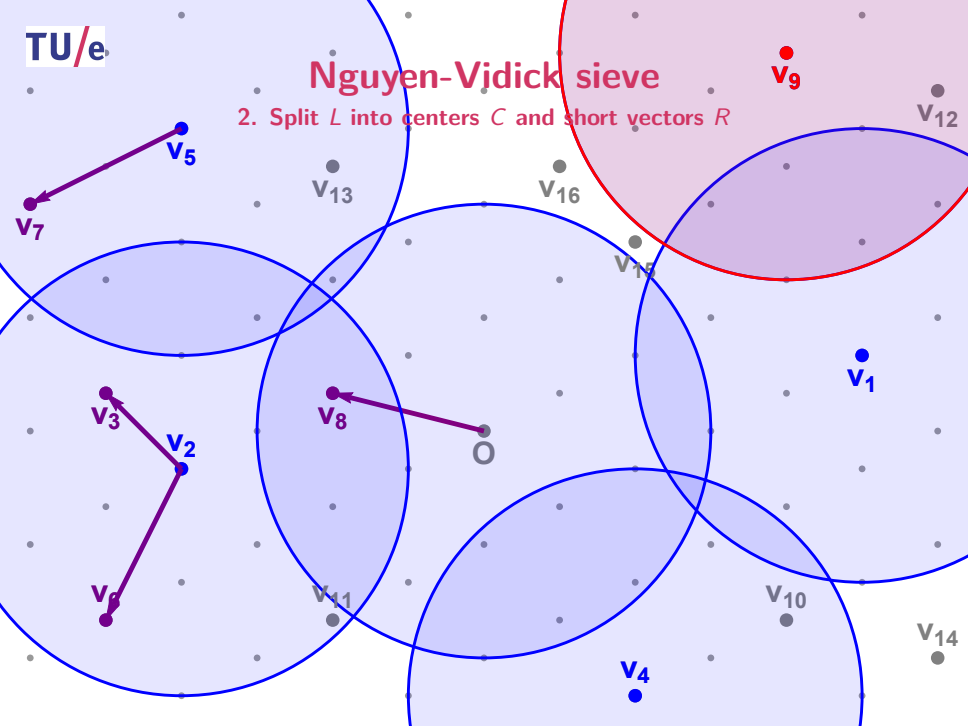
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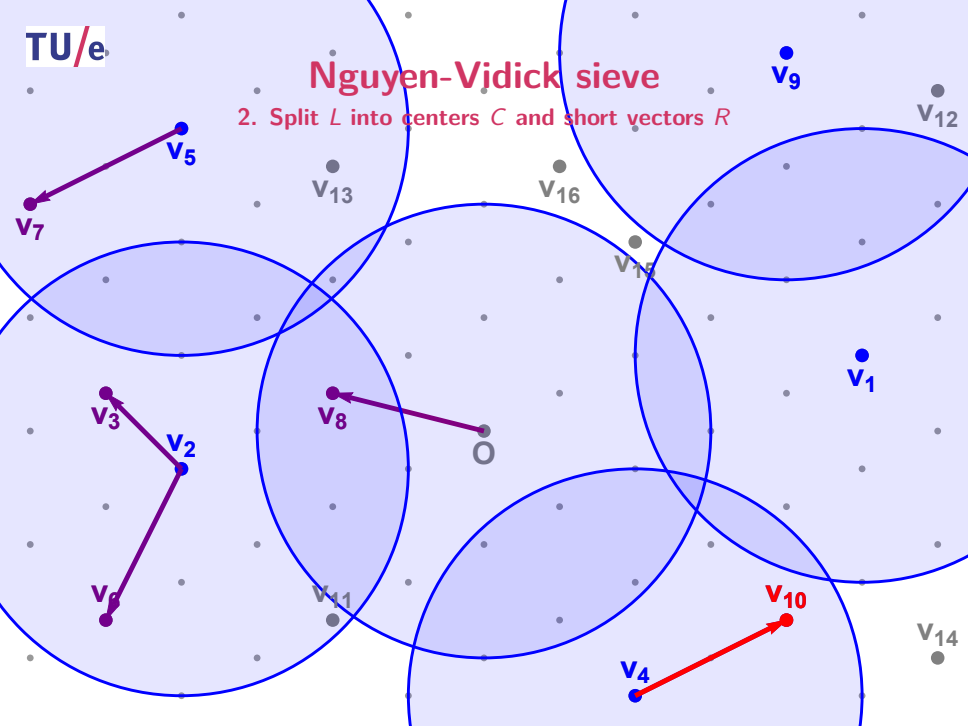
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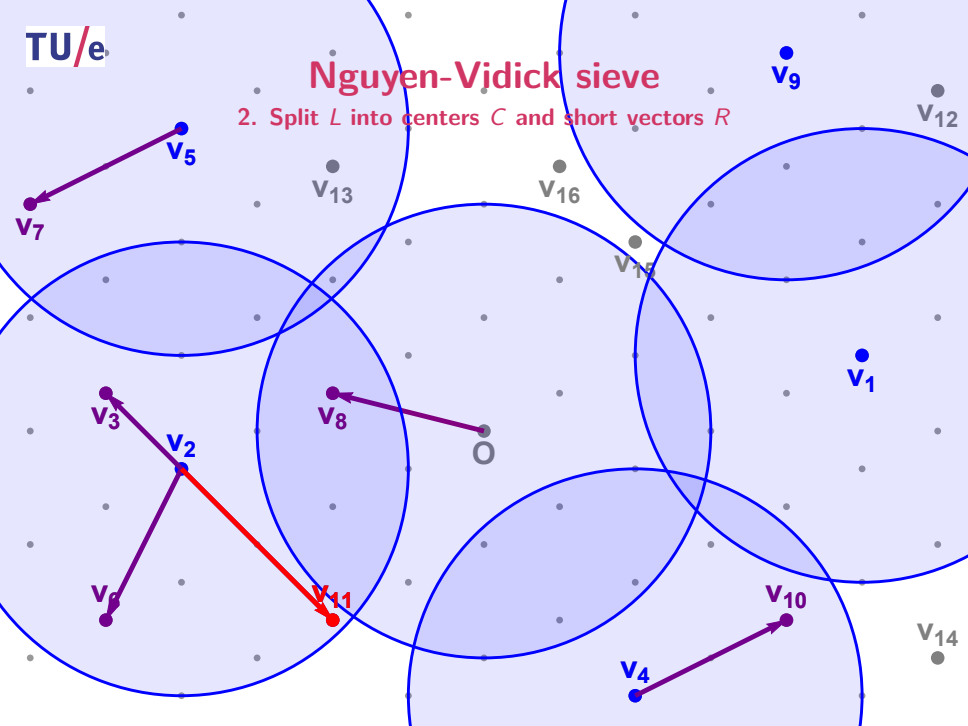
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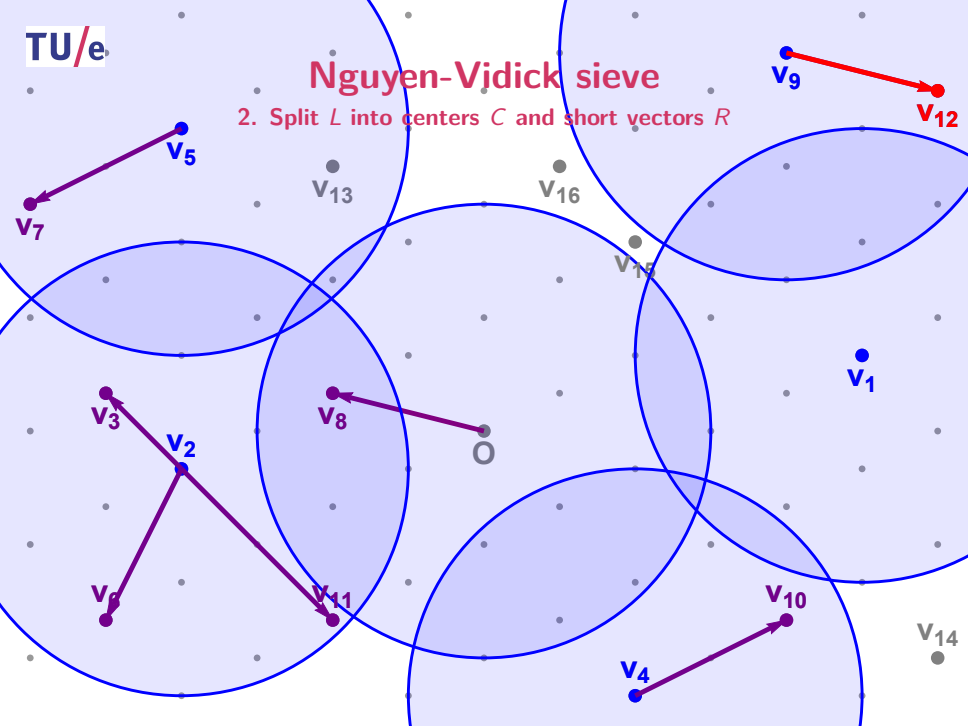
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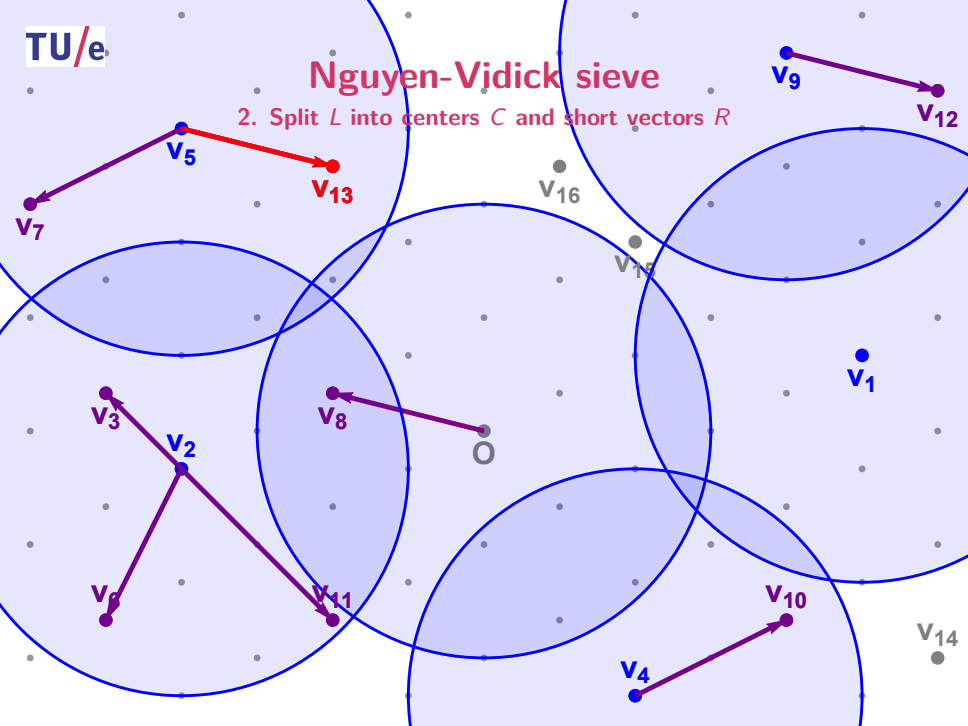
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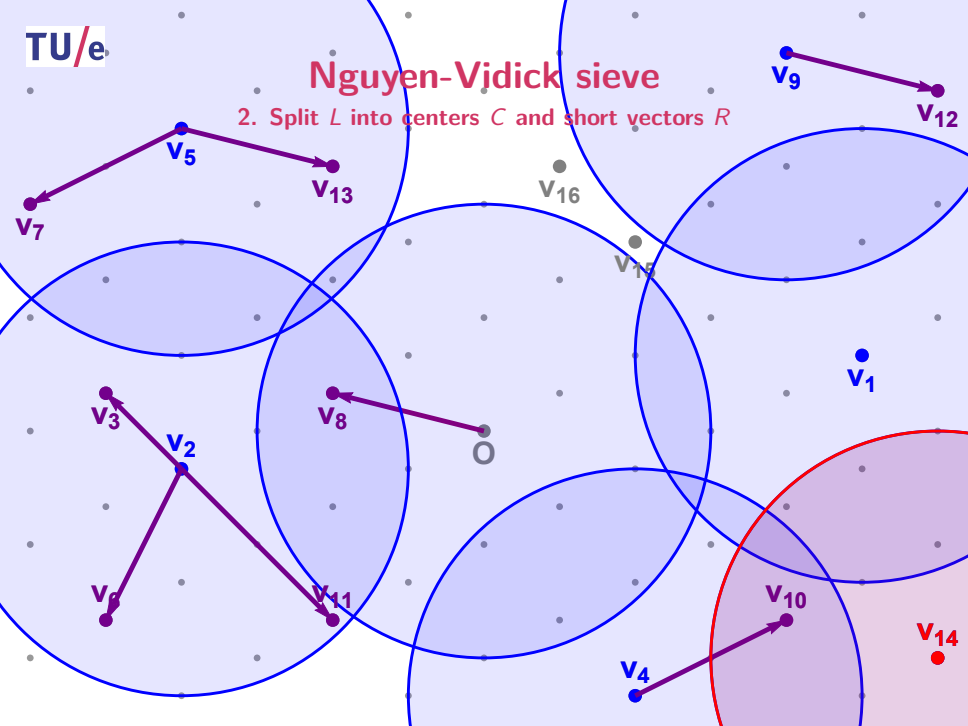
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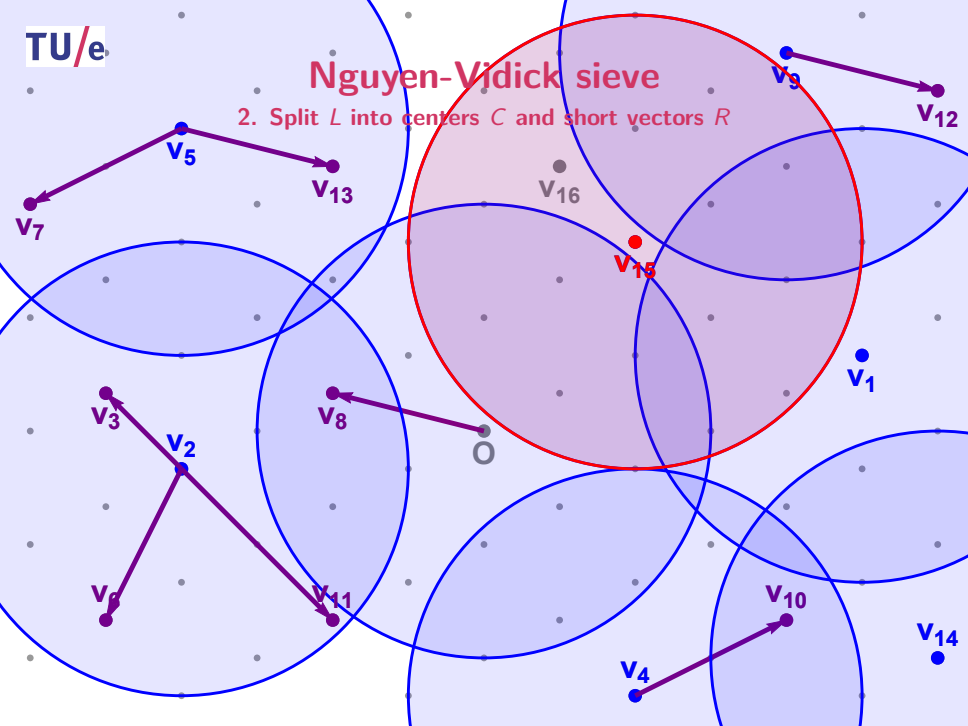
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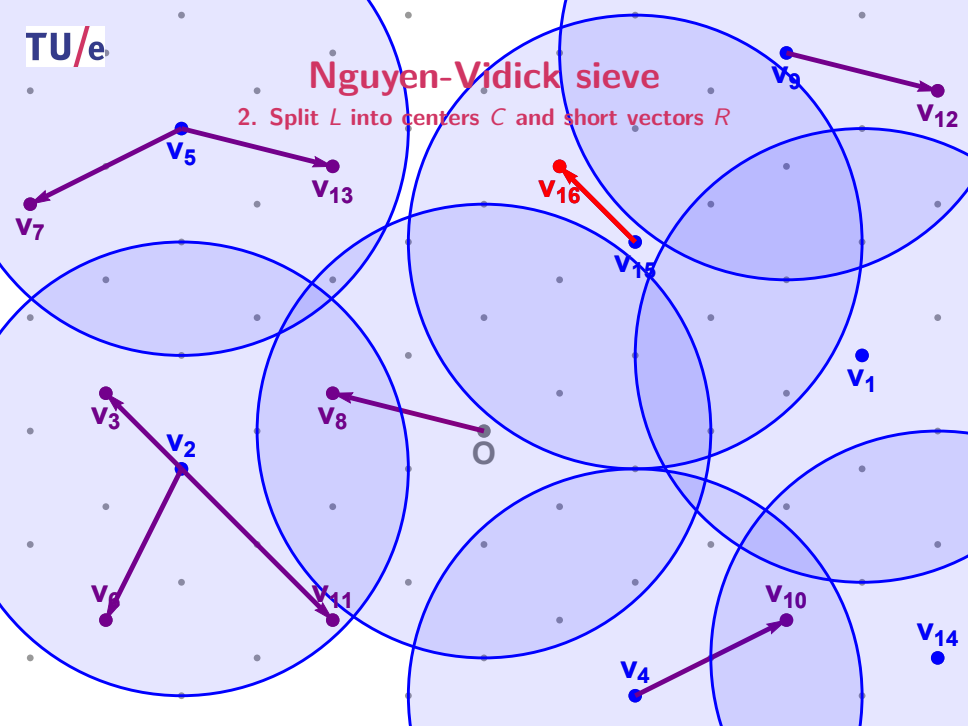
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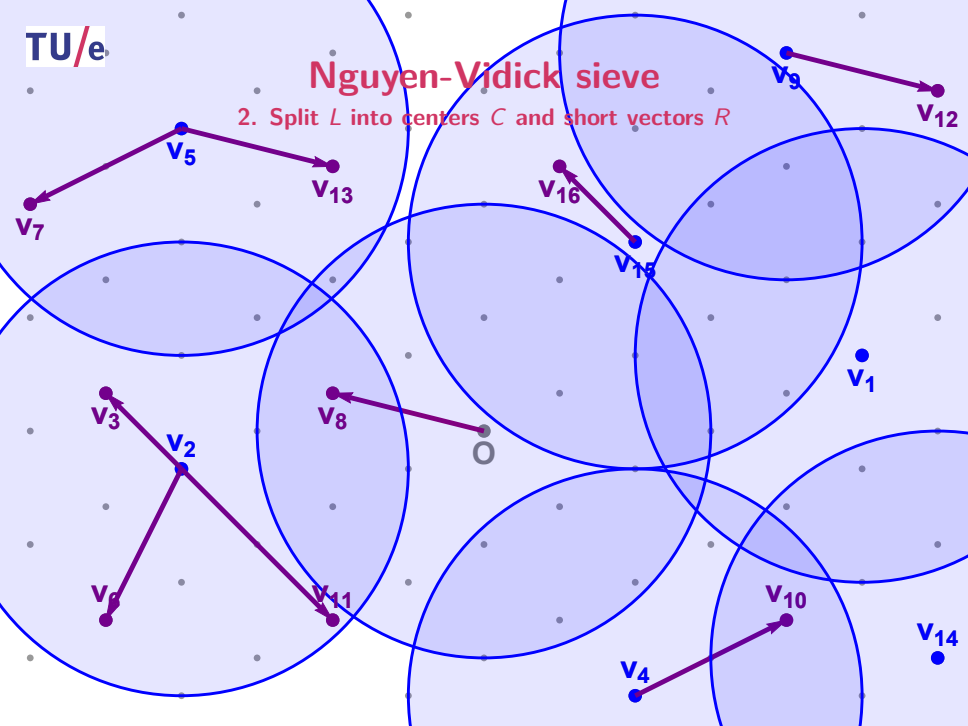
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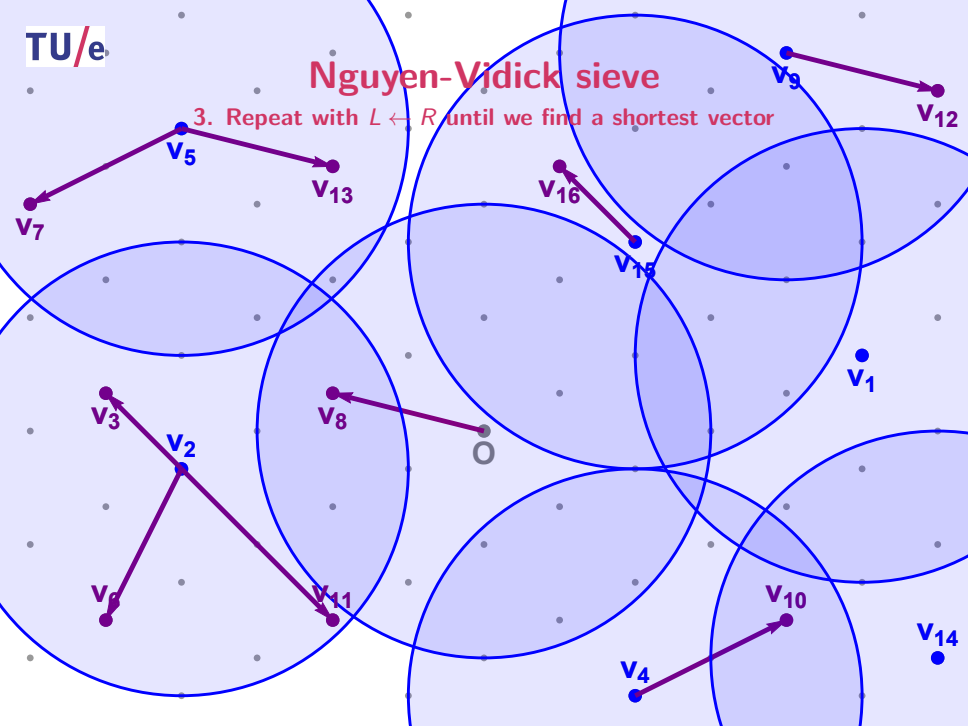
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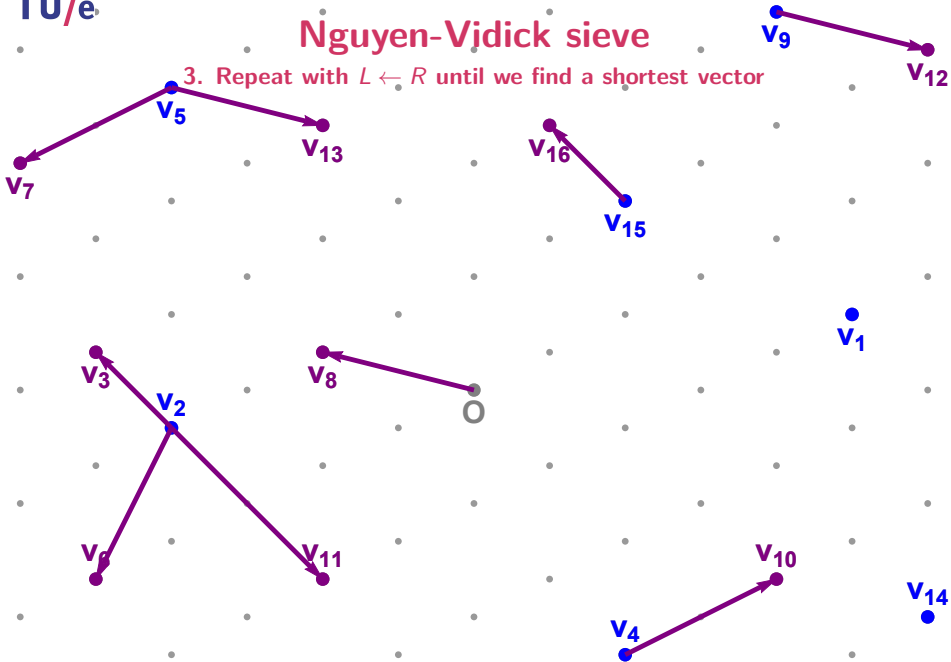
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3. Repeat with  $L \leftarrow R$  until we find a shortest vector



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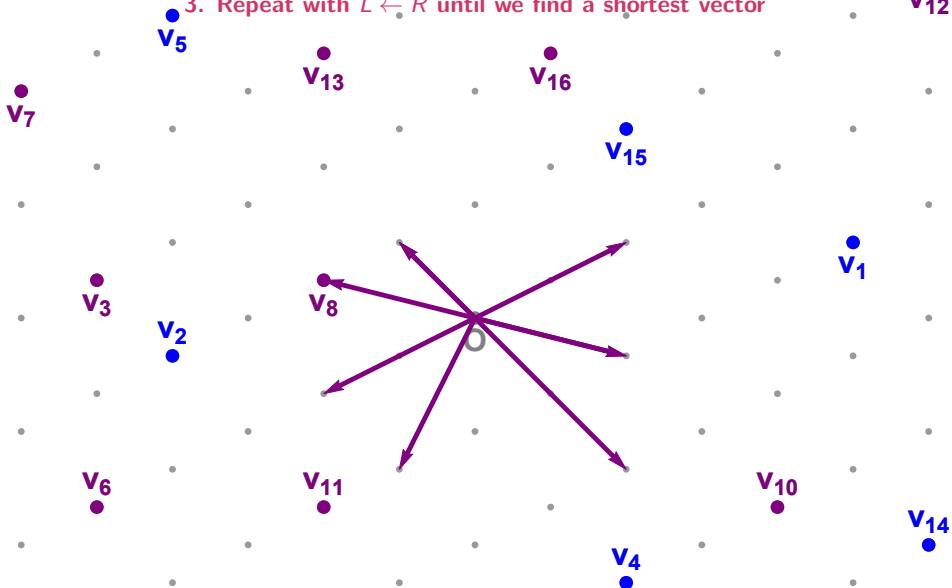
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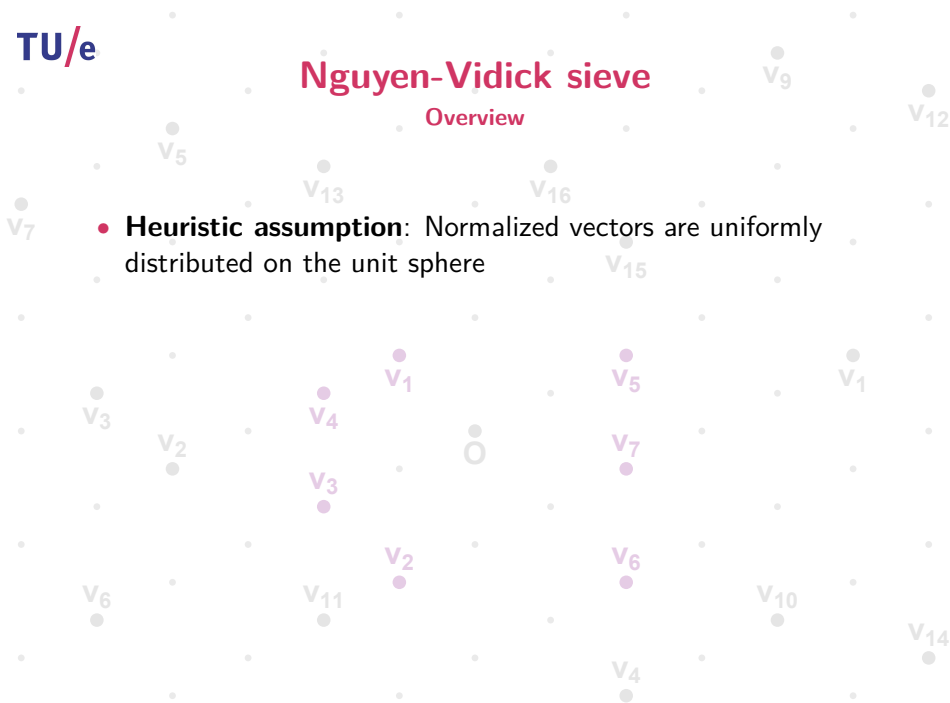
## Overview



# Nguyen-Vidick sieve

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- **Heuristic assumption:** Normalized vectors are uniformly distributed on the unit sphere



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- Space complexity:  $(\sqrt{4/3})^n \approx 2^{0.208n+o(n)}$  vectors
  - ▶ Each center covers  $(\sin \frac{\pi}{3})^{-n} = (\sqrt{3/4})^n$  of the space
  - ▶ Need  $(\sqrt{4/3})^{n+o(n)}$  vectors to cover all corners of  $\mathbb{R}^n$

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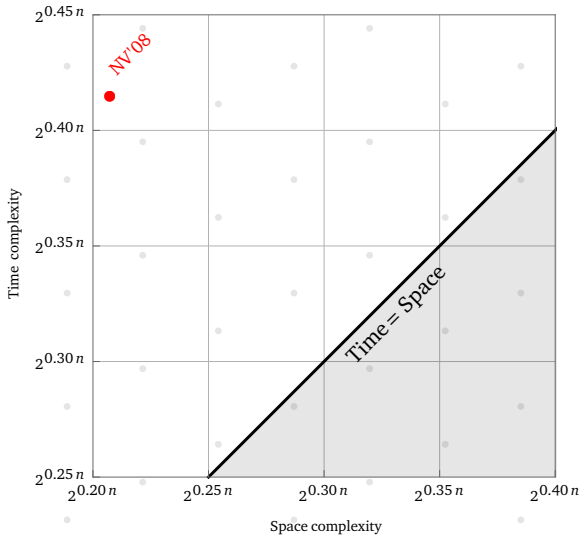
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Theorem (Nguyen and Vidick, J. Math. Crypt. '08)

The Nguyen-Vidick sieve heuristically solves SVP in time  $2^{0.415n+o(n)}$  and space  $2^{0.208n+o(n)}$ .

# Nguyen-Vidick sieve

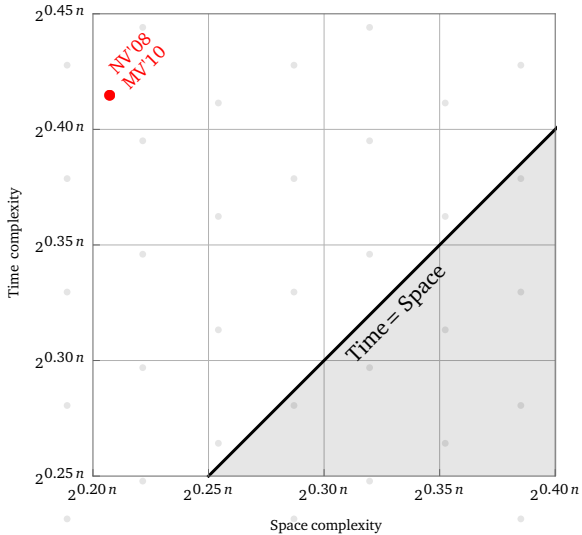
Space/time trade-off





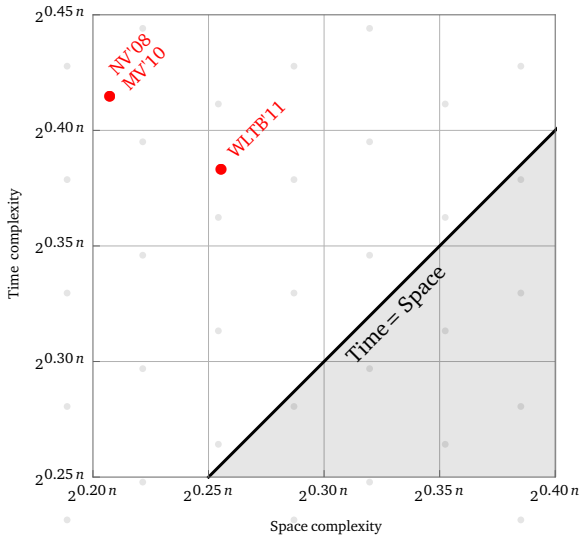
# GaussSieve

Space/time trade-off



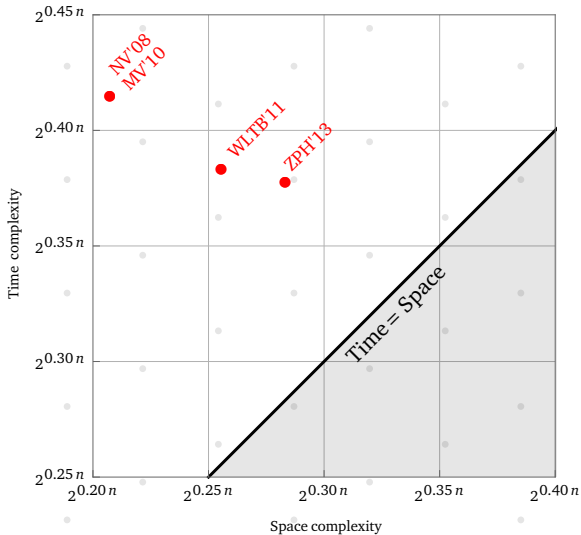
# Two-level sieve

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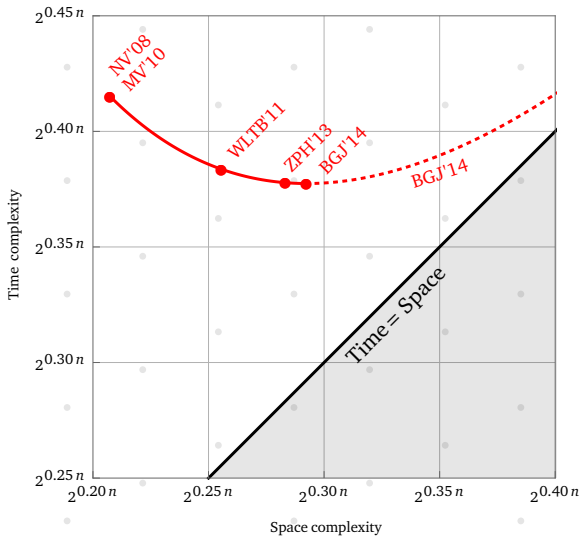
# Three-level sieve

Space/time trade-off



# Overlattice sieving

Space/time trade-off



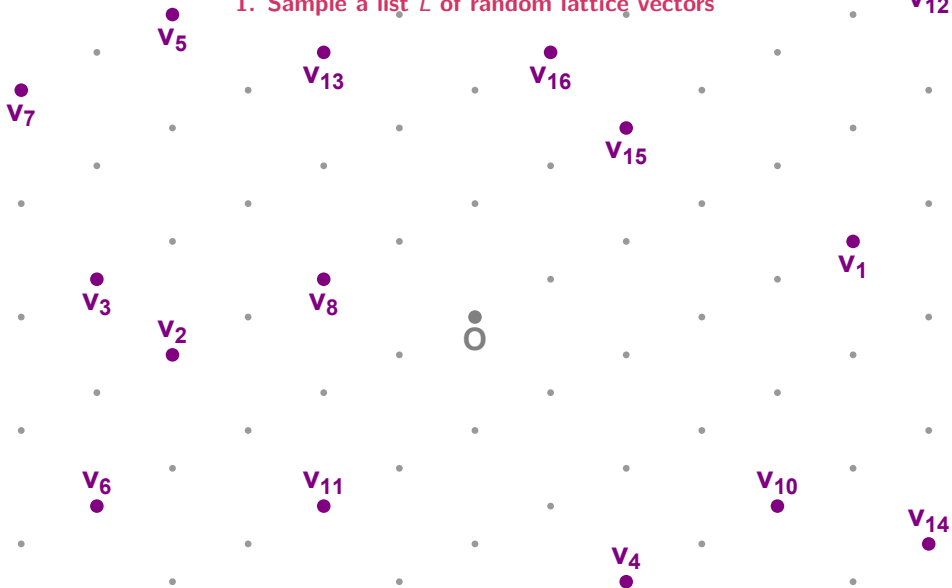
# Hyperplane LSH

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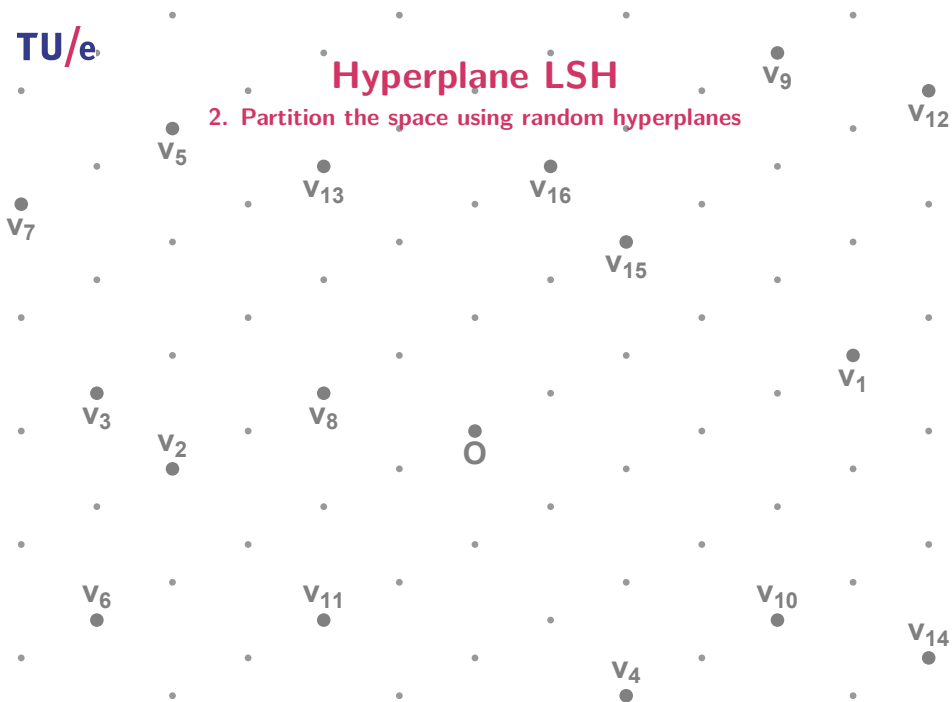
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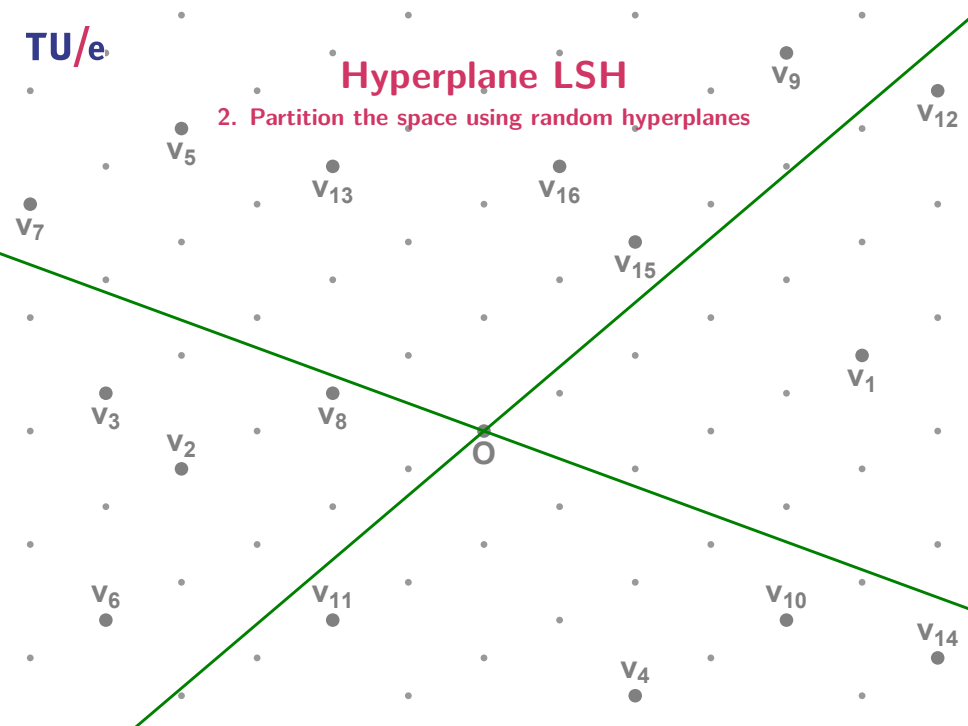
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## 2. Partition the space using random hyperplanes



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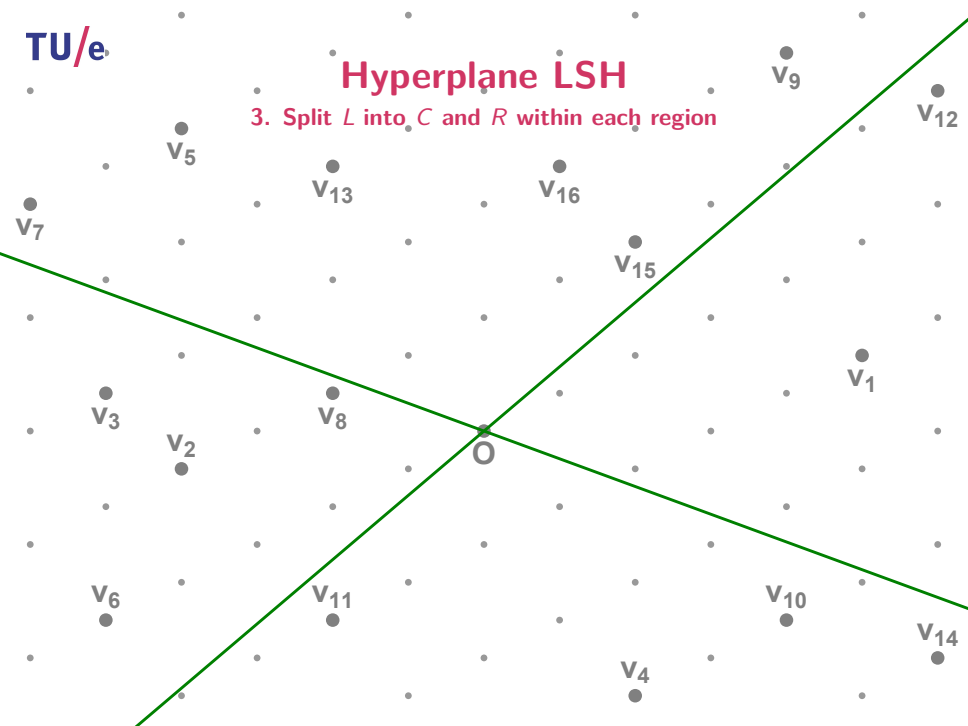
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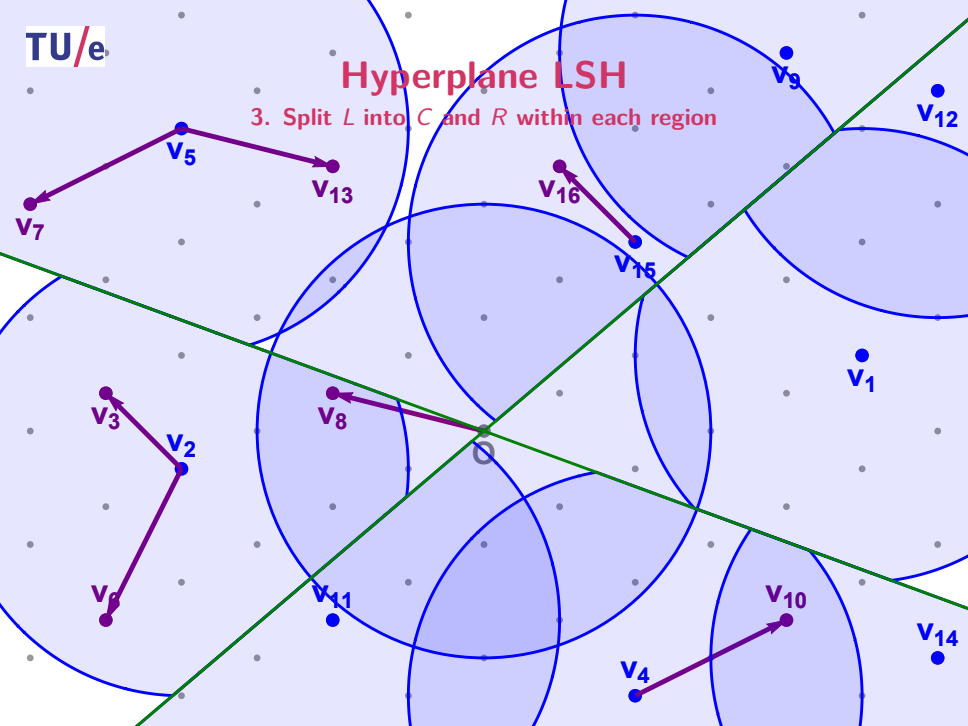
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## 3. Split $L$ into $C$ and $R$ within each region



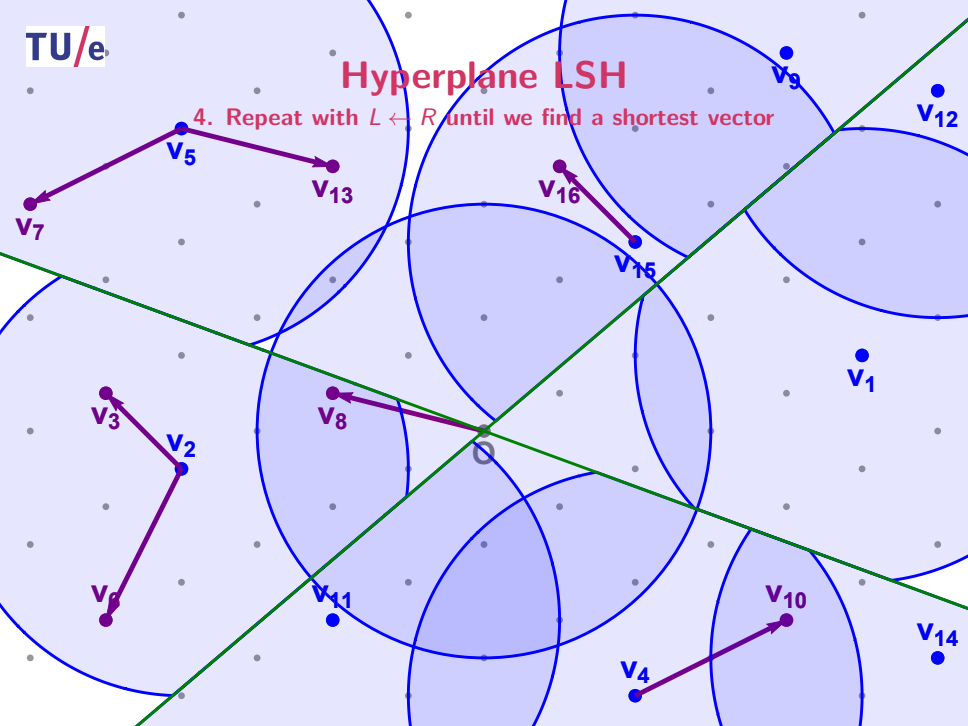
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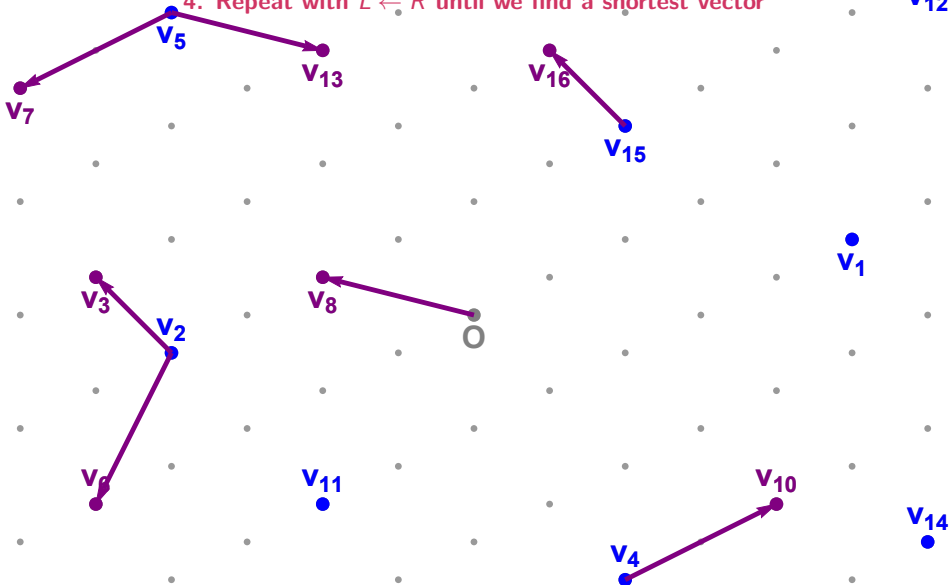
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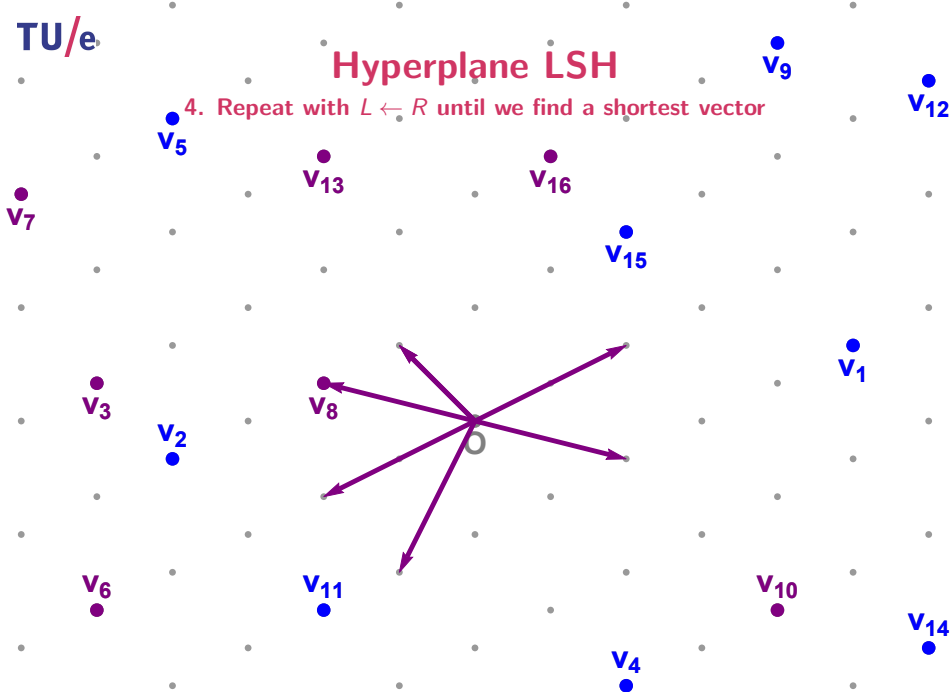
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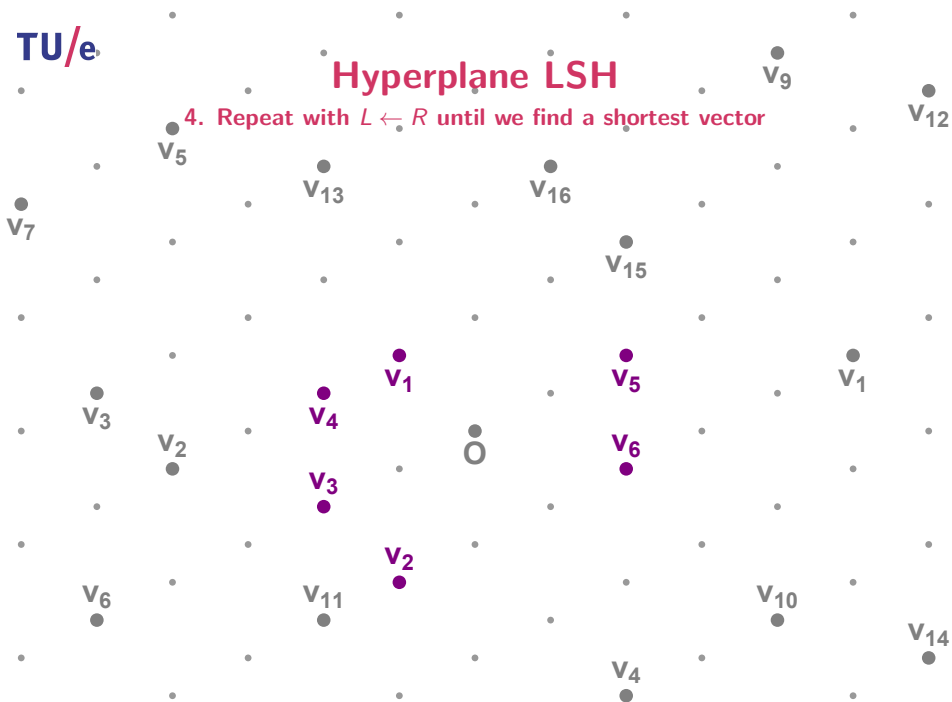
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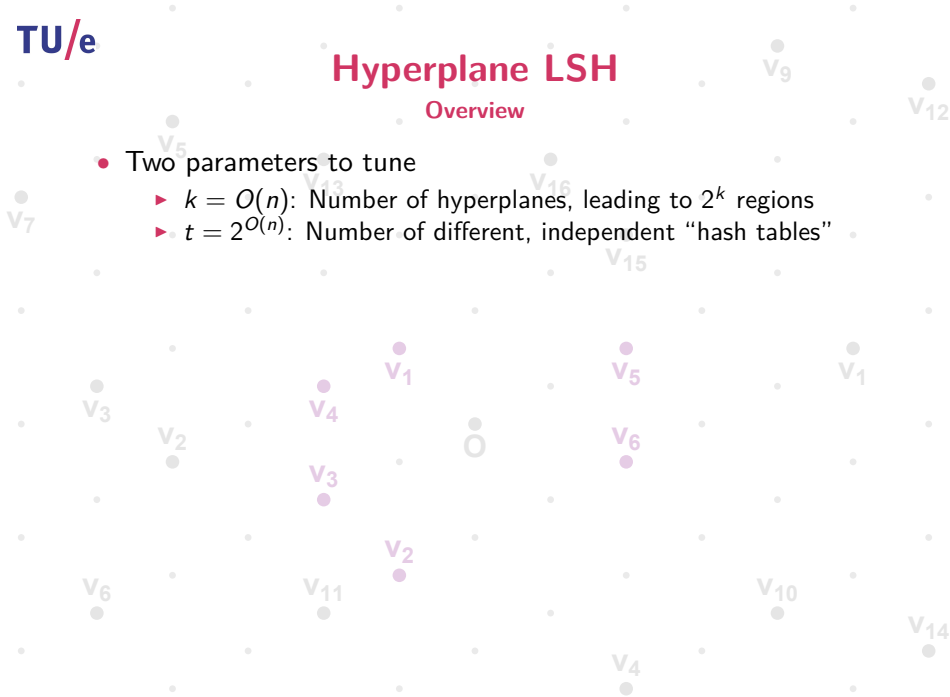
## Overview



# Hyperplane LSH

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- Two parameters to tune
  - ▶  $k = O(n)$ : Number of hyperplanes, leading to  $2^k$  regions
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- Space complexity:  $2^{0.337n+o(n)}$ 
  - ▶ Number of vectors:  $2^{0.208n+o(n)}$
  - ▶ Number of hash tables:  $2^{0.129n+o(n)}$
  - ▶ Each hash table contains all vectors

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  - ▶ Cost of computing hashes:  $2^{0.129n+o(n)}$
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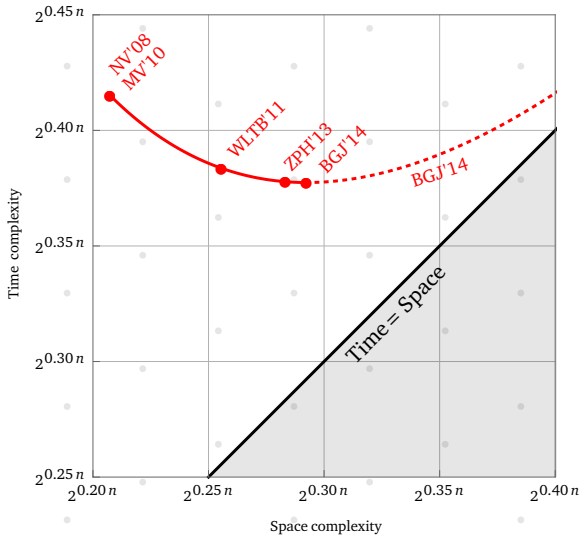
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## Theorem

Sieving with hyperplane LSH heuristically solves SVP in time and space  $2^{0.337n+o(n)}$ .

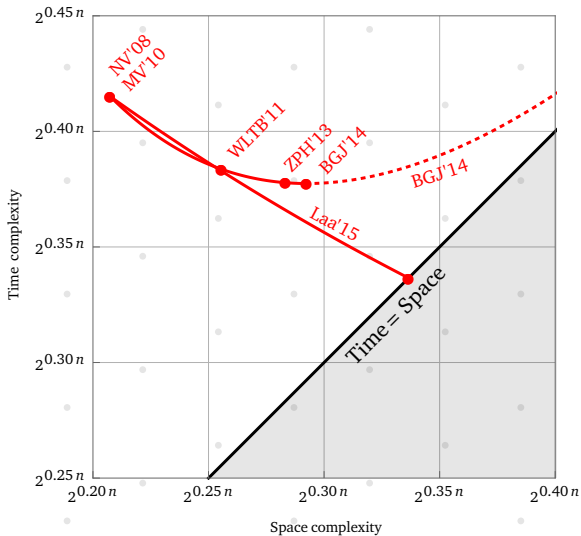
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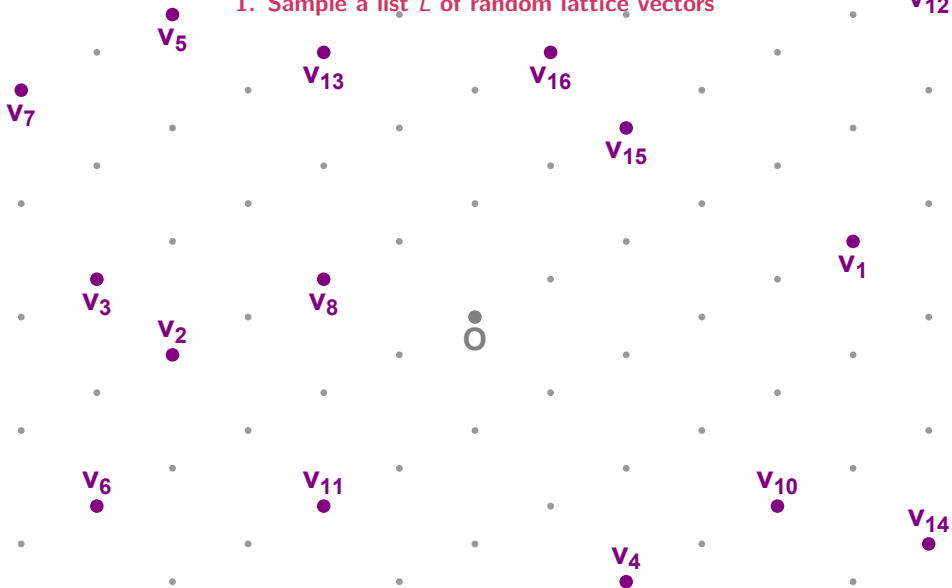
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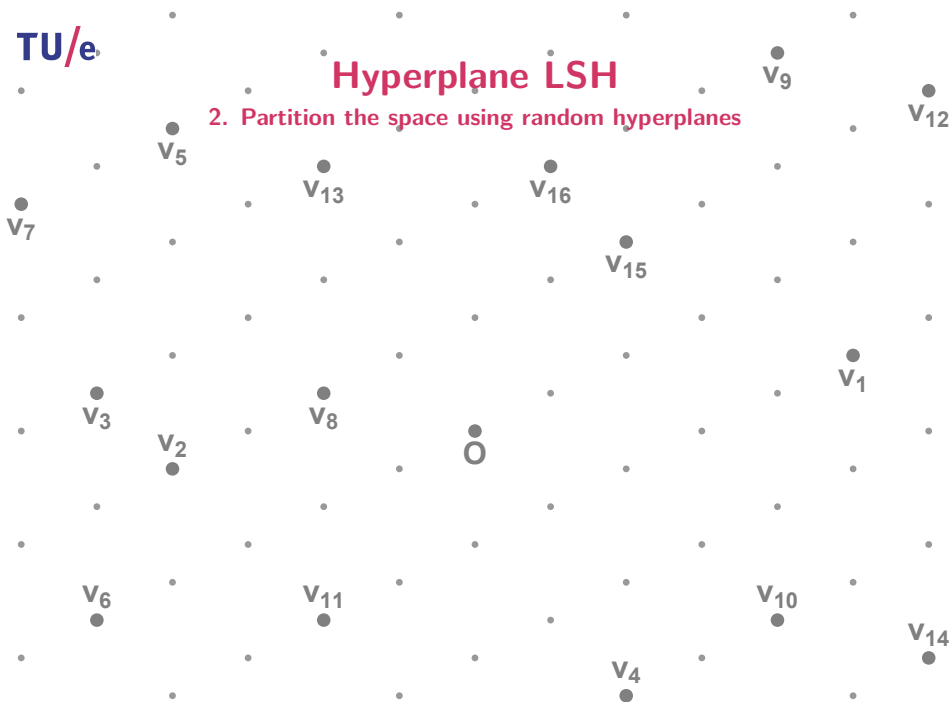
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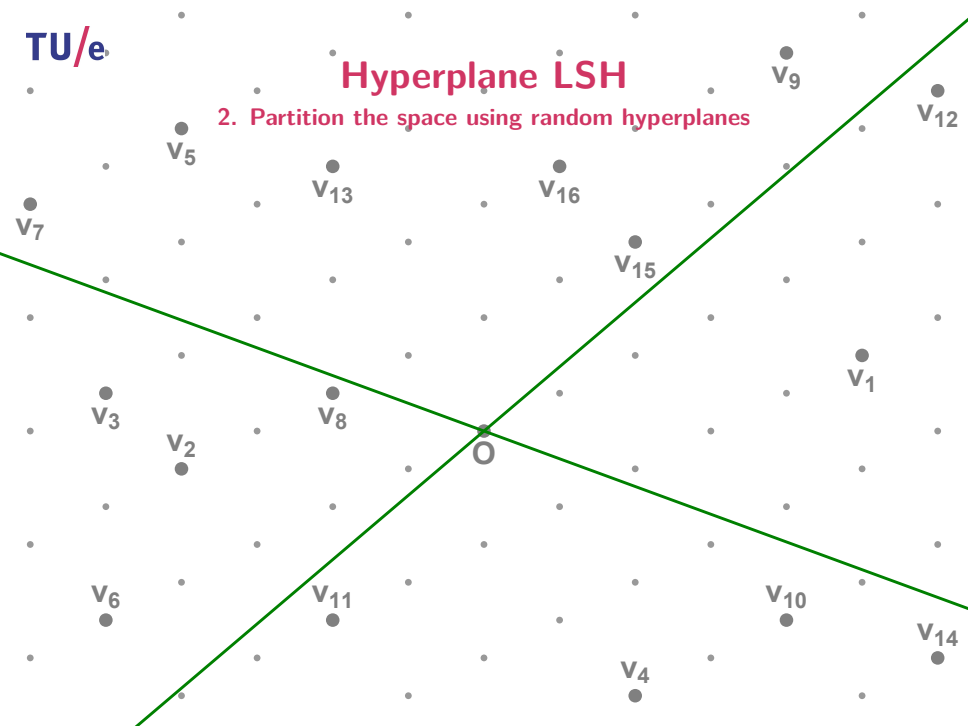
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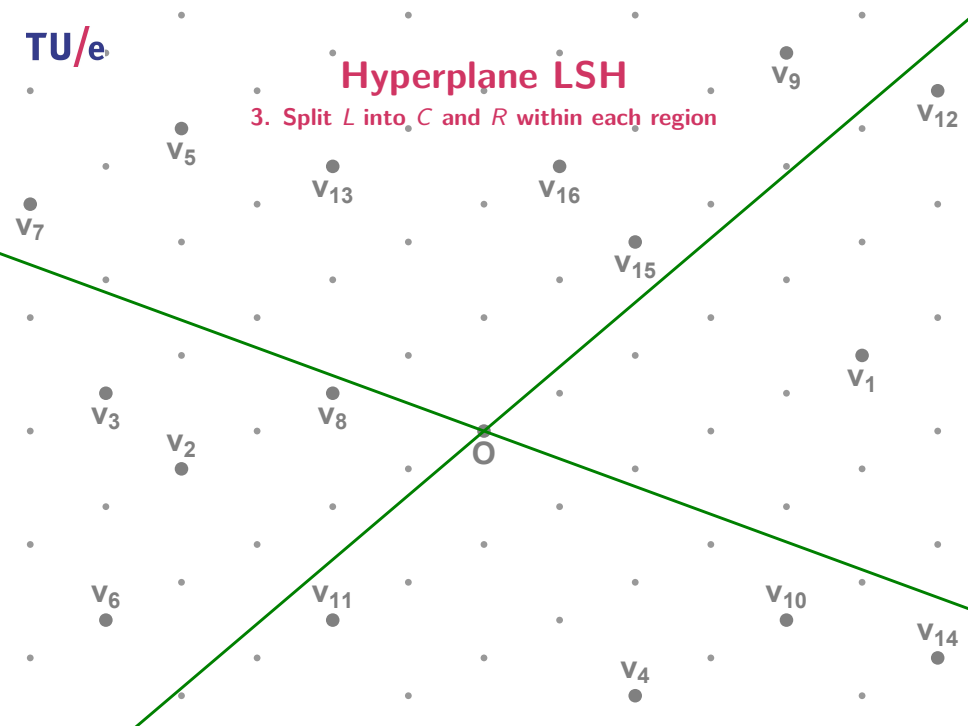
# Hyperplane LSH

## 2. Partition the space using random hyperplanes



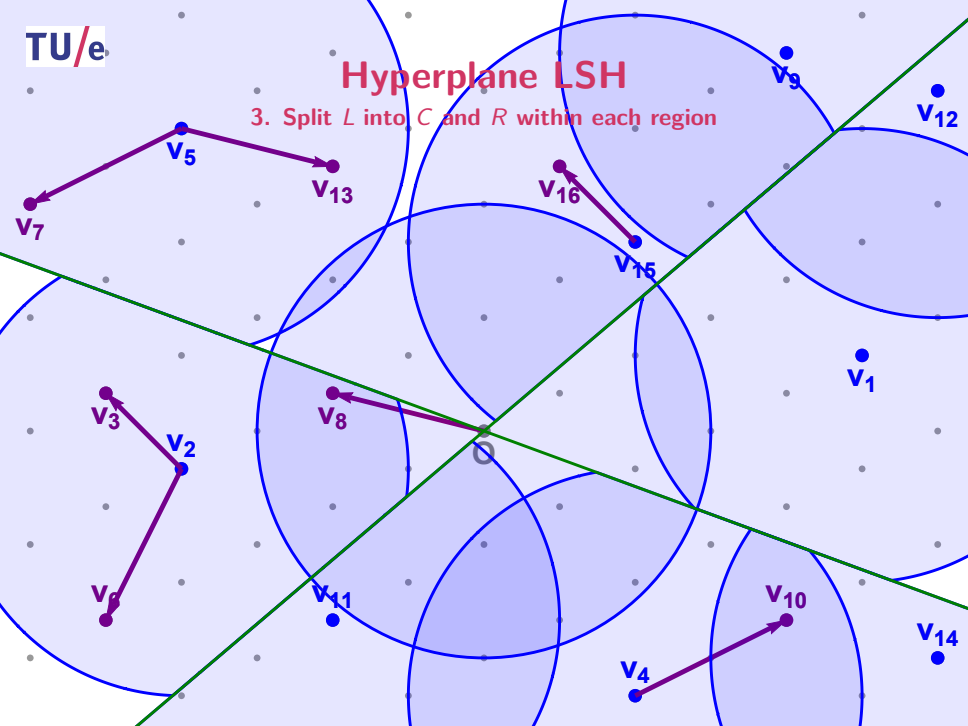
# Hyperplane LSH

3. Split  $L$  into  $C$  and  $R$  within each region



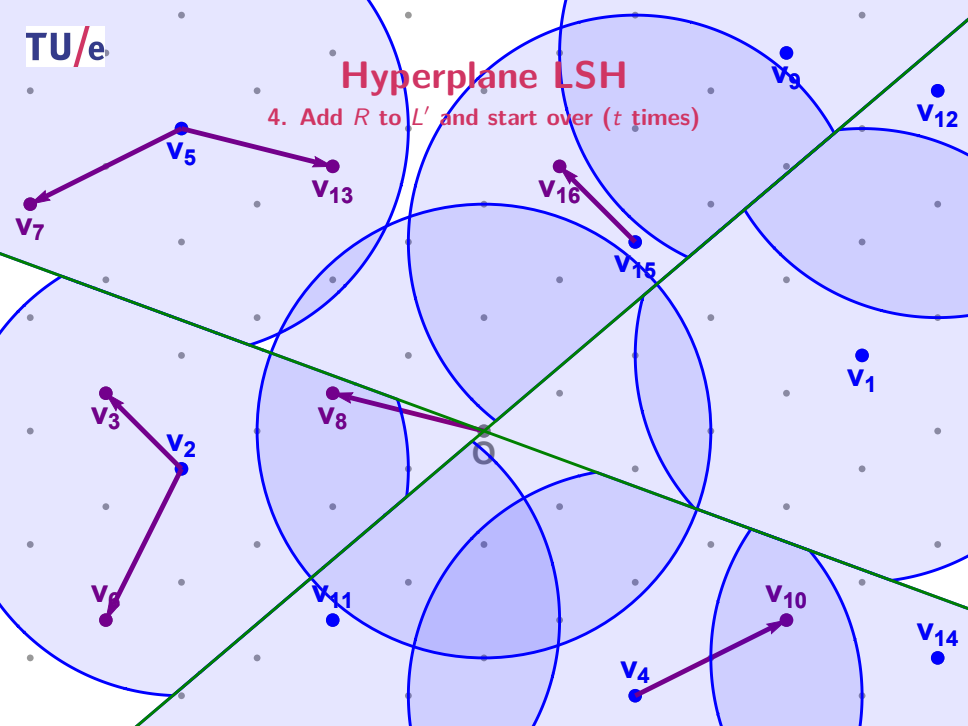
# Hyperplane LSH

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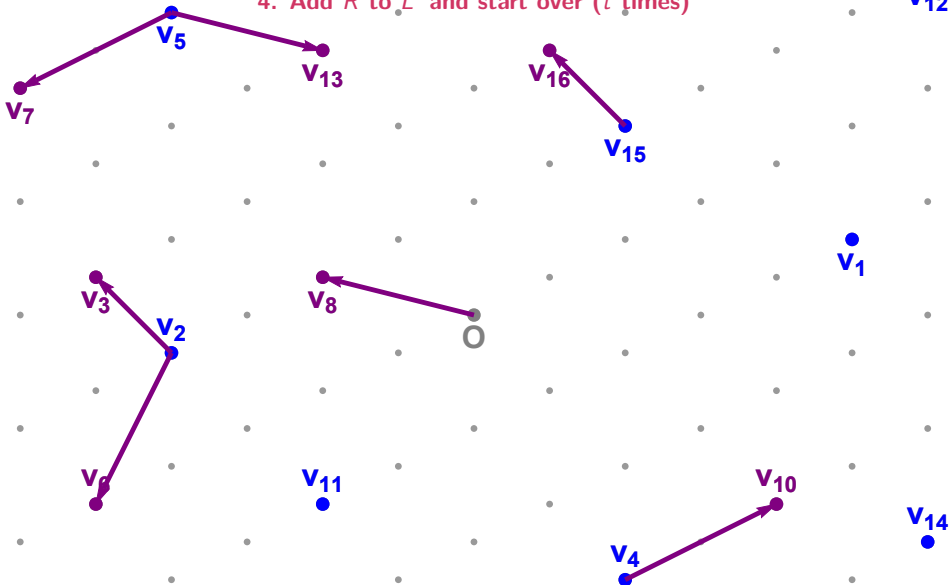


# Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)

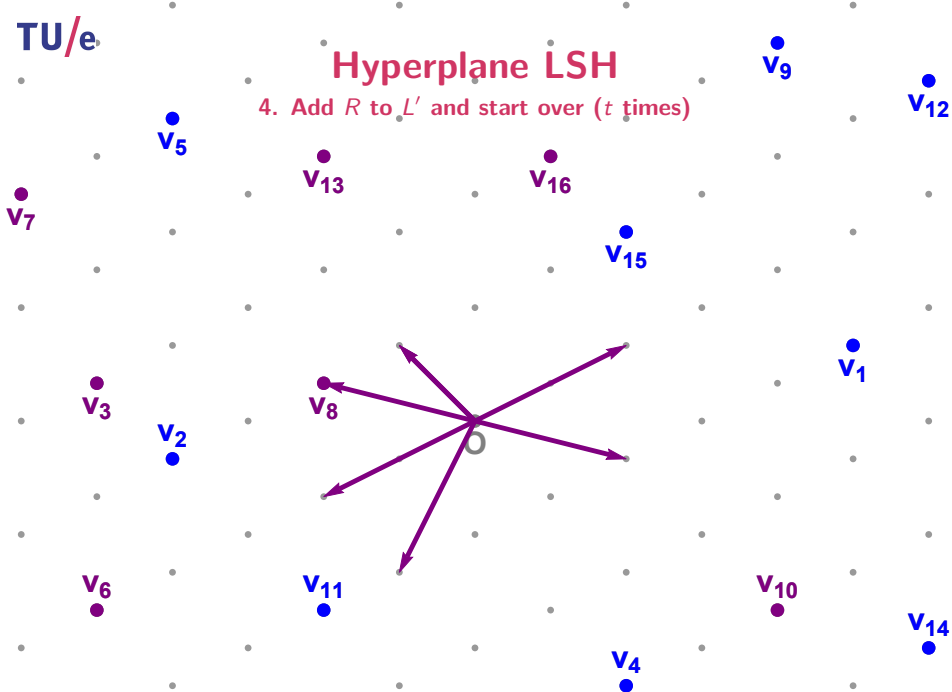


## Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)

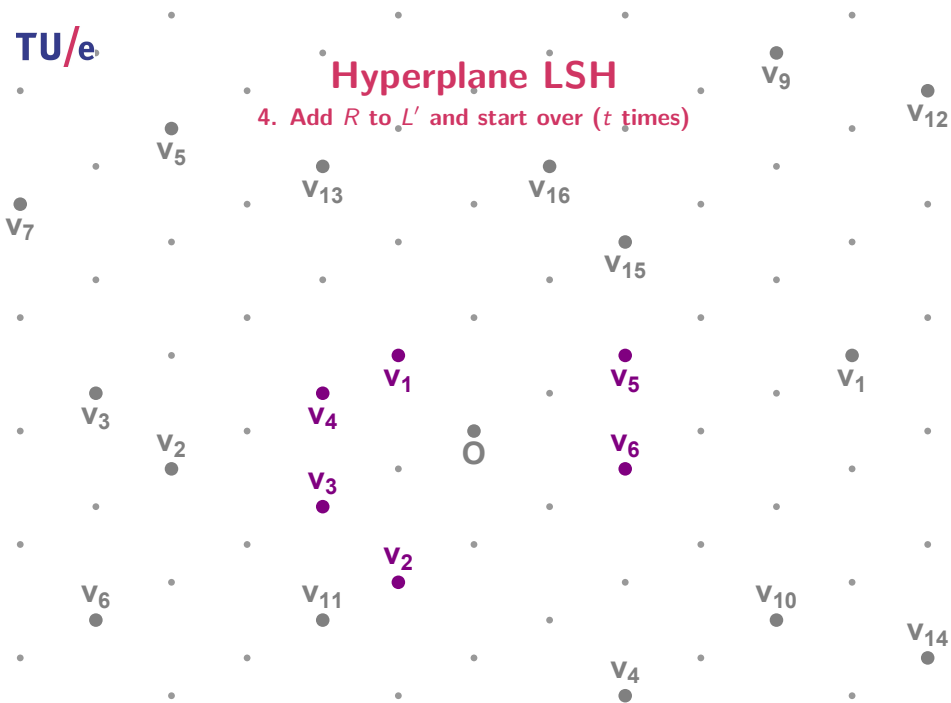
# Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)



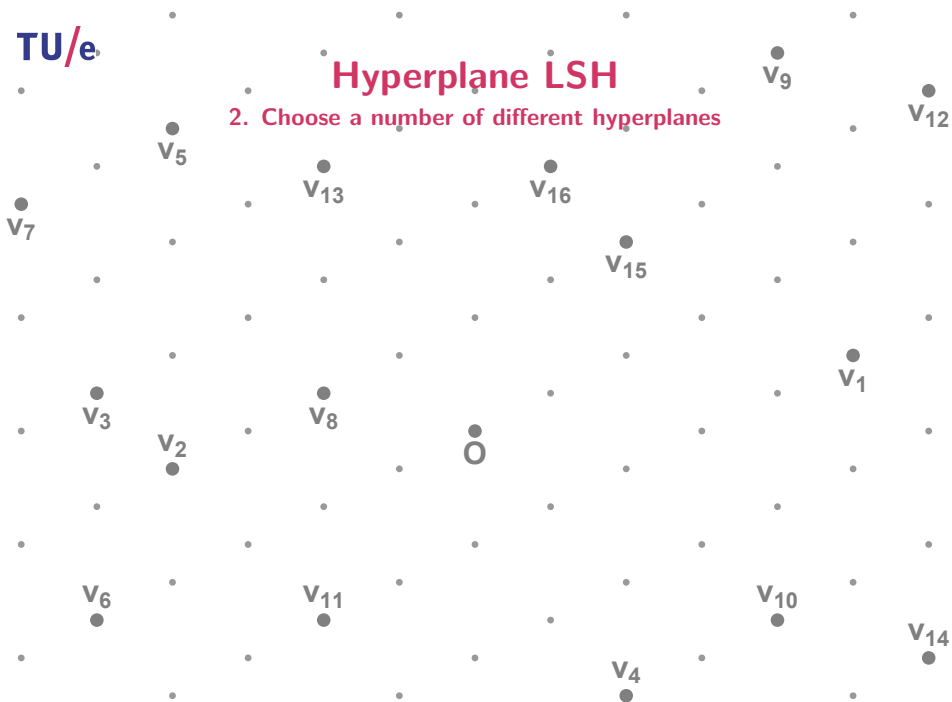
# Hyperplane LSH

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# Hyperplane LSH

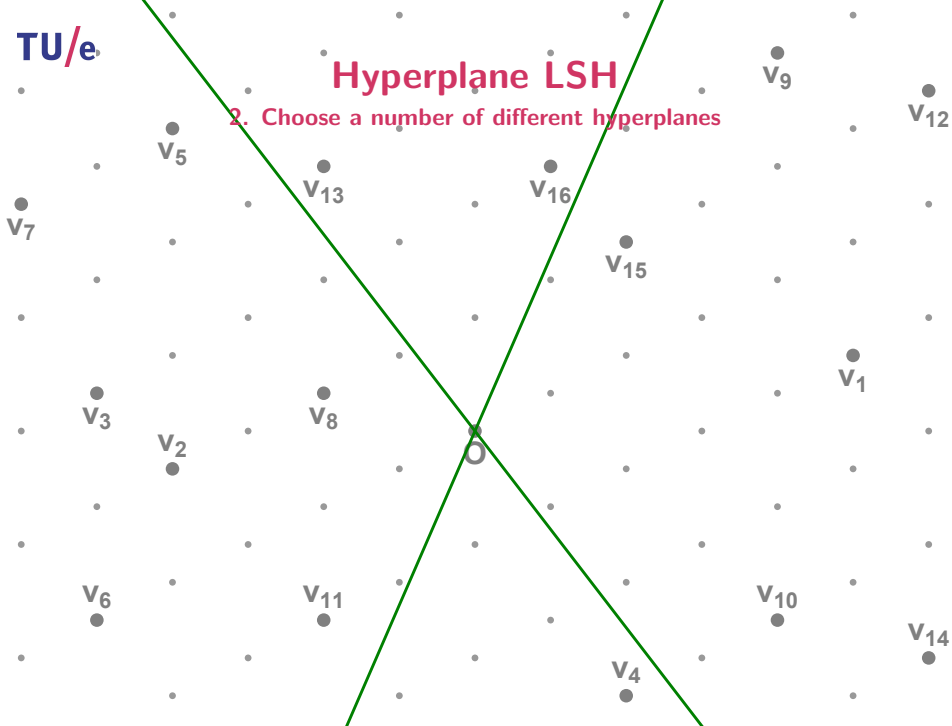
2. Choose a number of different hyperplanes





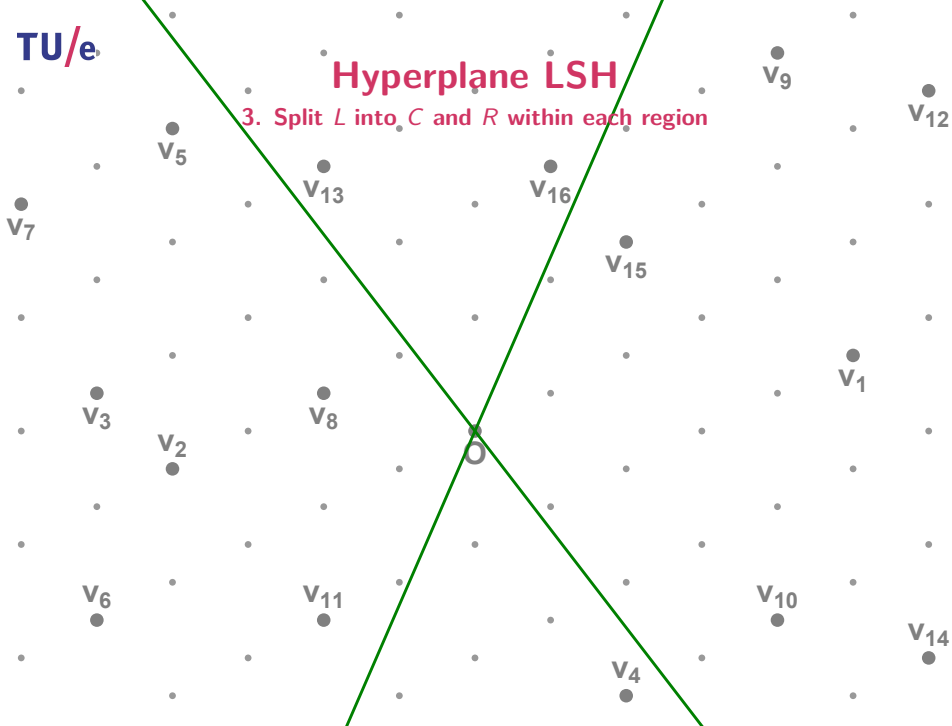
# Hyperplane LSH

2. Choose a number of different hyperplanes



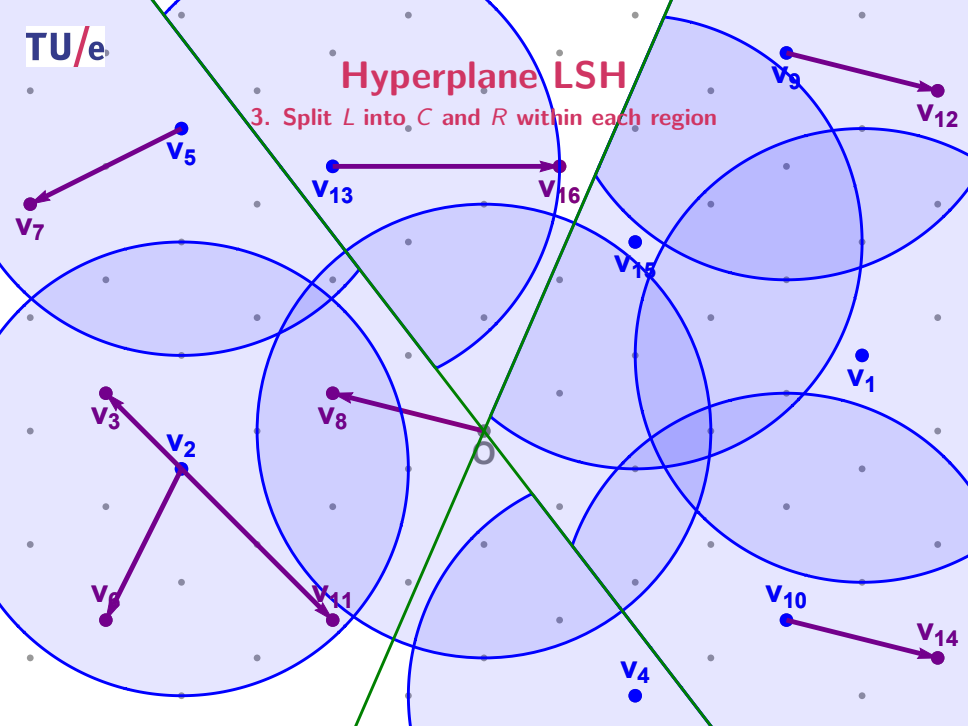
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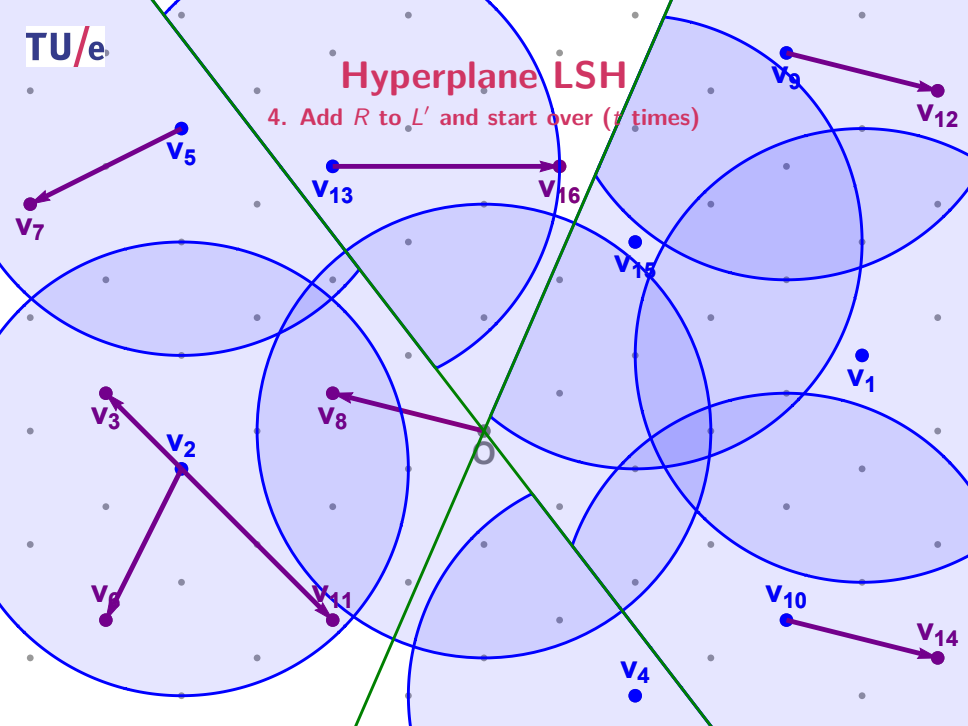
# Hyperplane LSH

3. Split  $L$  into  $C$  and  $R$  within each region



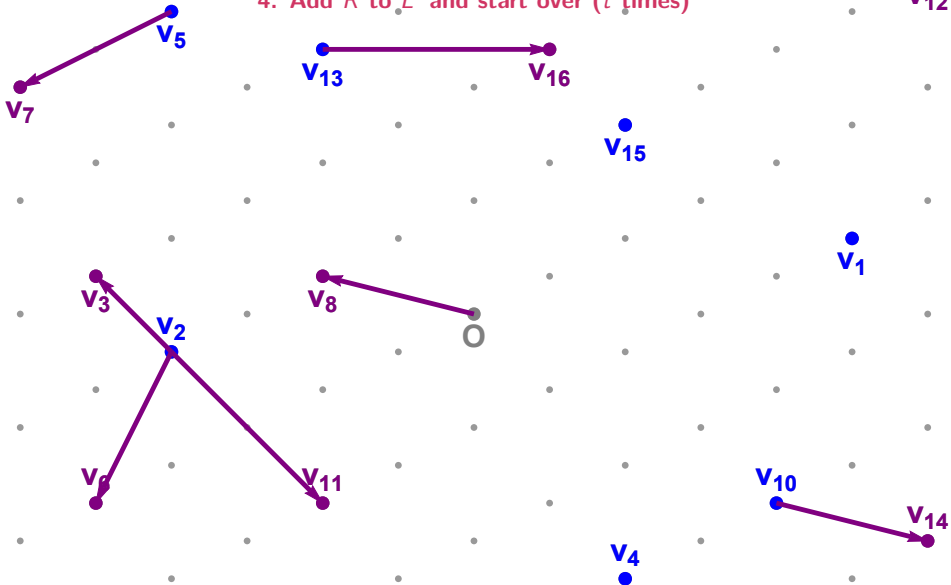
# Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)



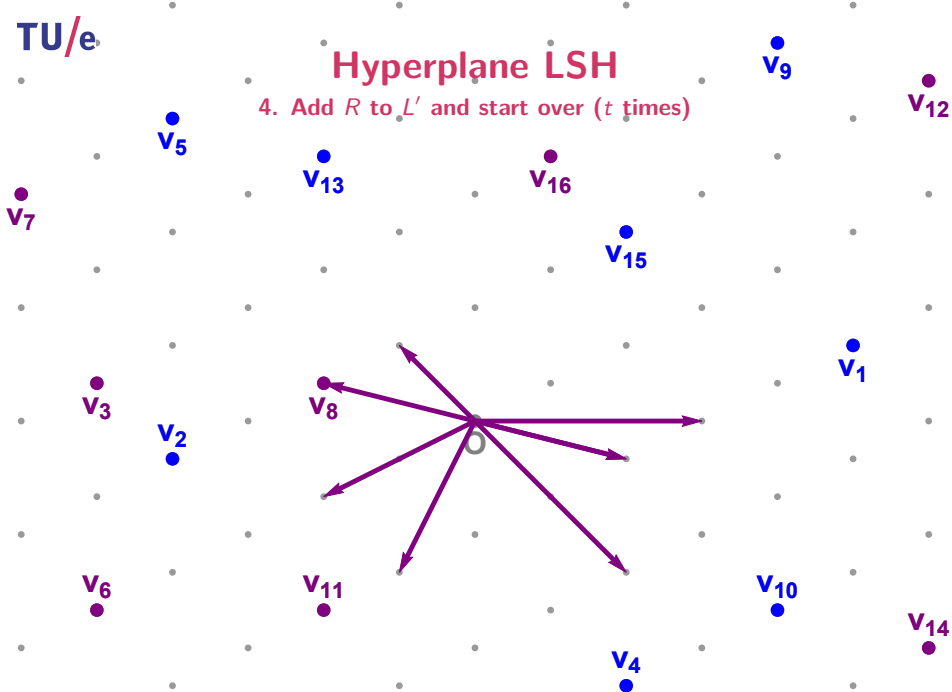
# Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)



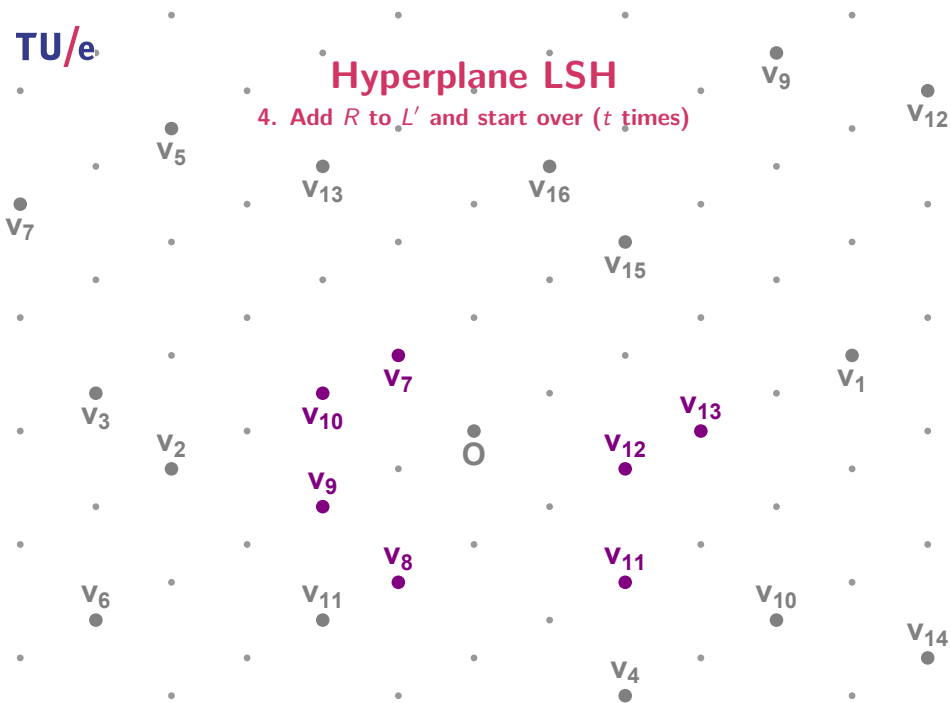
# Hyperplane LSH

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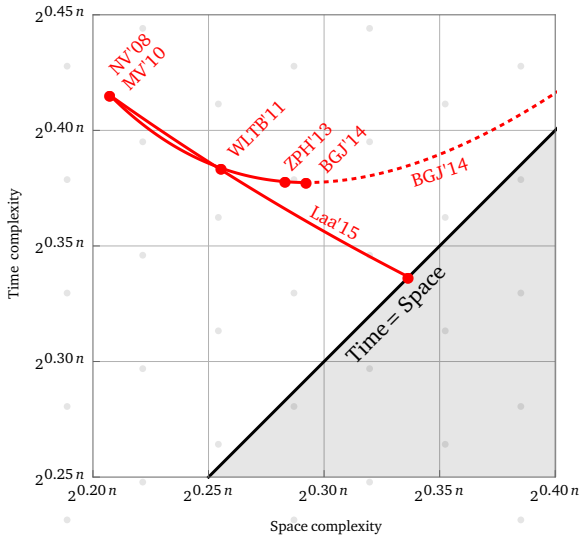
# Hyperplane LSH

4. Add  $R$  to  $L'$  and start over ( $t$  times)



# Hyperplane LSH

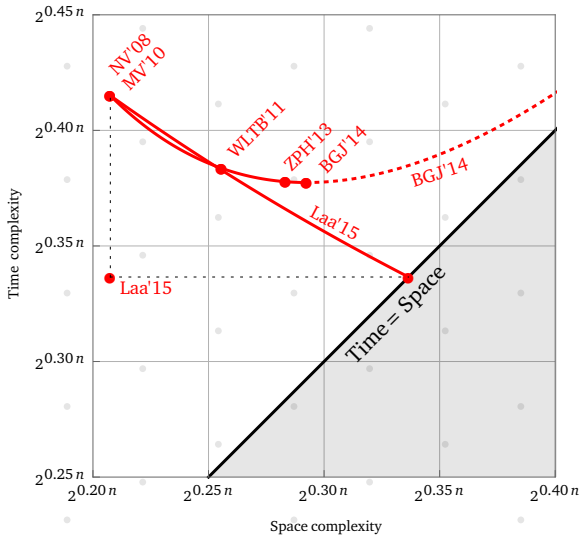
Space/time trade-off





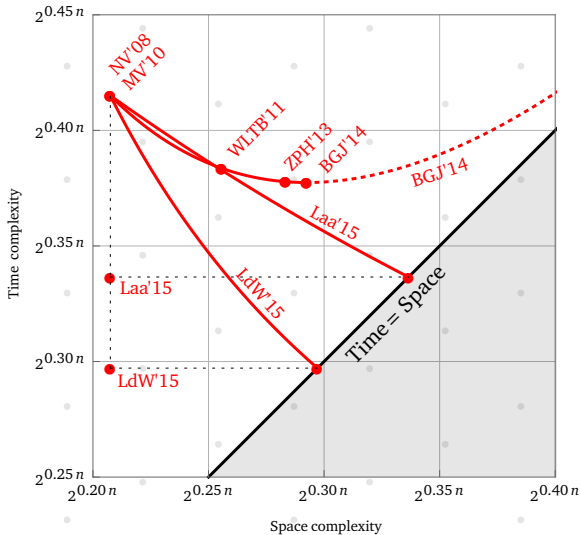
# Hyperplane LSH

Space/time trade-off



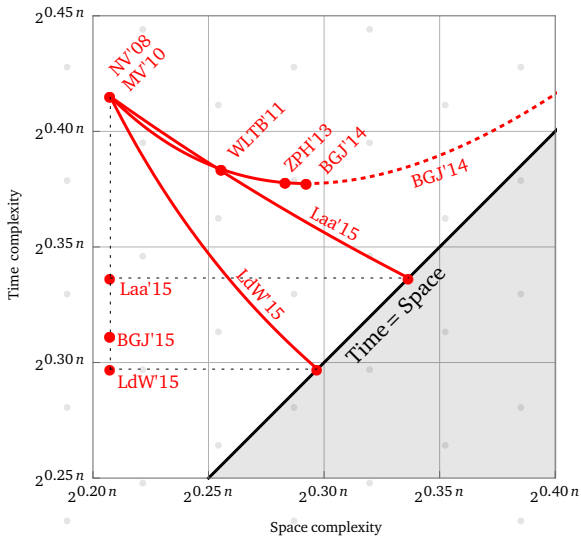
# Spherical LSH

Space/time trade-off



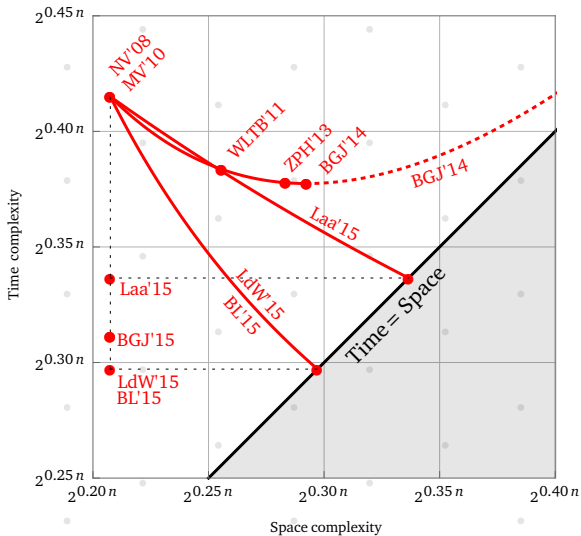
# May and Ozerov's NNS method

Space/time trade-off



# Cross-polytope LSH

Space/time trade-off



# Questions?

[vdP'12]

